Microchip Technology - PIC24EP512GU814-E/PH Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	CANbus, I²C, IrDA, LINbus, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	122
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 32x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-TQFP
Supplier Device Package	144-TQFP (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24ep512gu814-e-ph

3.8 Arithmetic Logic Unit (ALU)

The ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are two's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

Refer to the *"16-bit MCU and DSC Programmer's Reference Manual"* (DS70157) for information on the SR bits affected by each instruction.

The core CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

3.8.1 MULTIPLIER

Using the high-speed 17-bit x 17-bit multiplier, the ALU supports unsigned, signed, or mixed-sign operation in several MCU multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit signed x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

3.8.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. The 16-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.9 DSP Engine (dsPIC33EPXXX(GP/MC/MU)806/810/814 Devices Only)

The DSP engine consists of a high-speed 17-bit x 17-bit multiplier, a 40-bit barrel shifter and a 40-bit adder/subtracter (with two target accumulators, round and saturation logic).

The DSP engine can also perform inherent accumulator-to-accumulator operations that require no additional data. These instructions are: `ADD`, `SUB` and `NEG`.

The DSP engine has options selected through bits in the CPU Core Control register (CORCON), as listed below:

- Fractional or integer DSP multiply (IF)
- Signed, unsigned or mixed-sign DSP multiply (US)
- Conventional or convergent rounding (RND)
- Automatic saturation on/off for ACCA (SATA)
- Automatic saturation on/off for ACCB (SATB)
- Automatic saturation on/off for writes to data memory (SATDW)
- Accumulator Saturation mode selection (ACCSAT)

TABLE 3-2: DSP INSTRUCTIONS SUMMARY

Instruction	Algebraic Operation	ACC Write Back
CLR	$A = 0$	Yes
ED	$A = (x - y)^2$	No
EDAC	$A = A + (x - y)^2$	No
MAC	$A = A + (x \bullet y)$	Yes
MAC	$A = A + x^2$	No
MOVSAC	No change in A	Yes
MPY	$A = x \bullet y$	No
MPY	$A = x^2$	No
MPY.N	$A = -x \bullet y$	No
MSC	$A = A - x \bullet y$	Yes

TABLE 4-3: INTERRUPT CONTROLLER REGISTER MAP FOR dsPIC33EPXXXMU814 DEVICES ONLY (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IPC16	0860	—	CRCIP<2:0>			—	U2EIP<2:0>			—	U1EIP<2:0>			—	—	—	—	4440
IPC17	0862	—	C2TXIP<2:0>			—	C1TXIP<2:0>			—	DMA7IP<2:0>			—	DMA6IP<2:0>			4444
IPC18	0864	—	QEI2IP<2:0>			—	—	—	—	—	PSESMIP<2:0>			—	—	—	—	4040
IPC20	0868	—	U3TXIP<2:0>			—	U3RXIP<2:0>			—	U3EIP<2:0>			—	—	—	—	4440
IPC21	086A	—	U4EIP<2:0>			—	USB1IP<2:0>			—	—	—	—	—	—	—	—	4400
IPC22	086C	—	SPI3IP<2:0>			—	SPI3EIP<2:0>			—	U4TXIP<2:0>			—	U4RXIP<2:0>			4444
IPC23	086E	—	PWM2IP<2:0>			—	PWM1IP<2:0>			—	IC9IP<2:0>			—	OC9IP<2:0>			4444
IPC24	0870	—	PWM6IP<2:0>			—	PWM5IP<2:0>			—	PWM4IP<2:0>			—	PWM3IP<2:0>			4444
IPC25	0872	—	—	—	—	—	—	—	—	—	—	—	—	—	PWM7IP<2:0>			0004
IPC29	087A	—	DMA9IP<2:0>			—	DMA8IP<2:0>			—	—	—	—	—	—	—	—	4400
IPC30	087C	—	SPI4IP<2:0>			—	SPI4EIP<2:0>			—	DMA11IP<2:0>			—	DMA10IP<2:0>			4444
IPC31	087E	—	IC11IP<2:0>			—	OC11IP<2:0>			—	IC10IP<2:0>			—	OC10IP<2:0>			4444
IPC32	0880	—	DMA13IP<2:0>			—	DMA12IP<2:0>			—	IC12IP<2:0>			—	OC12IP<2:0>			4444
IPC33	0882	—	IC13IP<2:0>			—	OC13IP<2:0>			—	—	—	—	—	DMA14IP<2:0>			4404
IPC34	0884	—	IC15IP<2:0>			—	OC15IP<2:0>			—	IC14IP<2:0>			—	OC14IP<2:0>			4444
IPC35	0886	—	—	—	—	—	ICDIP<2:0>			—	IC16IP<2:0>			—	OC16IP<2:0>			0444
INTCON1	08C0	NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE	SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	—	0000
INTCON2	08C2	GIE	DISI	SWTRAP	—	—	—	—	—	—	—	—	INT4EP	INT3EP	INT2EP	INT1EP	INT0EP	8000
INTCON3	08C4	—	—	—	—	—	—	—	—	—	UAE	DAE	DOOVR	—	—	—	—	0000
INTCON4	08C6	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	SGHT	0000
INTTREG	08C8	—	—	—	—	ILR<3:0>				VECNUM<7:0>								0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-14: PWM GENERATOR 2 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PWMCON2	0C40	FLTSTAT	CLSTAT	TRGSTAT	FLTIEN	CLIEN	TRGIEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000
IOCON2	0C42	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000
FCLCON2	0C44	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000
PDC2	0C46	PDC2<15:0>																0000
PHASE2	0C48	PHASE2<15:0>																0000
DTR2	0C4A	—	—	DTR2<13:0>														0000
ALTDTR2	0C4C	—	—	ALTDTR2<13:0>														0000
SDC2	0C4E	SDC2<15:0>																0000
SPHASE2	0C50	SPHASE2<15:0>																0000
TRIG2	0C52	TRGCMP<15:0>																0000
TRGCON2	0C54	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>						0000
PWMCAP2	0C58	PWMCAP2<15:0>																0000
LEBCON2	0C5A	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000
LEBDLY2	0C5C	—	—	—	—	LEB<11:0>												0000
AUXCON2	0C5E	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-15: PWM GENERATOR 3 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PWMCON3	0C60	FLTSTAT	CLSTAT	TRGSTAT	FLTIEN	CLIEN	TRGIEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000
IOCON3	0C62	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000
FCLCON3	0C64	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000
PDC3	0C66	PDC3<15:0>																0000
PHASE3	0C68	PHASE3<15:0>																0000
DTR3	0C6A	—	—	DTR3<13:0>														0000
ALTDTR3	0C6C	—	—	ALTDTR3<13:0>														0000
SDC3	0C6E	SDC3<15:0>																0000
SPHASE3	0C70	SPHASE3<15:0>																0000
TRIG3	0C72	TRGCMP<15:0>																0000
TRGCON3	0C74	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>						0000
PWMCAP3	0C78	PWMCAP3<15:0>																0000
LEBCON3	0C7A	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000
LEBDLY3	0C7C	—	—	—	—	LEB<11:0>												0000
AUXCON3	0C7E	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-16: PWM GENERATOR 4 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PWMCON4	0C80	FLTSTAT	CLSTAT	TRGSTAT	FLTIEN	CLIEN	TRGIEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000
IOCON4	0C82	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000
FCLCON4	0C84	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000
PDC4	0C86	PDC4<15:0>																0000
PHASE4	0C88	PHASE4<15:0>																0000
DTR4	0C8A	—	—	DTR4<13:0>														0000
ALTDTR4	0C8C	—	—	ALTDTR4<13:0>														0000
SDC4	0C8E	SDC4<15:0>																0000
SPHASE4	0C90	SPHASE4<15:0>																0000
TRIG4	0C92	TRGCMP<15:0>																0000
TRGCON4	0C94	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>						0000
PWMCAP4	0C98	PWMCAP4<15:0>																0000
LEBCON4	0C9A	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000
LEBDLY4	0C9C	—	—	—	—	LEB<11:0>												0000
AUXCON4	0C9E	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-17: PWM GENERATOR 5 REGISTER MAP FOR dsPIC33EPXXX(MC/MU)810/814 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PWMCON5	0CA0	FLTSTAT	CLSTAT	TRGSTAT	FLTIEN	CLIEN	TRGIEN	ITB	MDCS	DTC<1:0>		DTCP	—	MTBS	CAM	XPRES	IUE	0000
IOCON5	0CA2	PENH	PENL	POLH	POLL	PMOD<1:0>		OVRENH	OVRENL	OVRDAT<1:0>		FLTDAT<1:0>		CLDAT<1:0>		SWAP	OSYNC	0000
FCLCON5	0CA4	IFLTMOD	CLSRC<4:0>					CLPOL	CLMOD	FLTSRC<4:0>					FLTPOL	FLTMOD<1:0>		0000
PDC5	0CA6	PDC5<15:0>																0000
PHASE5	0CA8	PHASE5<15:0>																0000
DTR5	0CAA	—	—	DTR5<13:0>														0000
ALTDTR5	0CAC	—	—	ALTDTR5<13:0>														0000
SDC5	0CAE	SDC5<15:0>																0000
SPHASE5	0CB0	SPHASE5<15:0>																0000
TRIG5	0CB2	TRGCMP<15:0>																0000
TRGCON5	0CB4	TRGDIV<3:0>				—	—	—	—	—	—	TRGSTRT<5:0>						0000
PWMCAP5	0CB8	PWM Capture<15:0>																0000
LEBCON5	0CBA	PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—	—	—	BCH	BCL	BPHH	BPHL	BPLH	BPLL	0000
LEBDLY5	0CBC	—	—	—	—	LEB<11:0>												0000
AUXCON5	0CBE	—	—	—	—	BLANKSEL<3:0>				—	—	CHOPSEL<3:0>				CHOPHEN	CHOPLEN	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-54: DMAC REGISTER MAP (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DMA4STAL	0B44	STA<15:0>																0000
DMA4STAH	0B46	—	—	—	—	—	—	—	—	STA<23:16>								0000
DMA4STBL	0B48	STB<15:0>																0000
DMA4STBH	0B4A	—	—	—	—	—	—	—	—	STB<23:16>								0000
DMA4PAD	0B4C	PAD<15:0>																0000
DMA4CNT	0B4E	—	—	CNT<13:0>														0000
DMA5CON	0B50	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000
DMA5REQ	0B52	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>								00FF
DMA5STAL	0B54	STA<15:0>																0000
DMA5STAH	0B56	—	—	—	—	—	—	—	—	STA<23:16>								0000
DMA5STBL	0B58	STB<15:0>																0000
DMA5STBH	0B5A	—	—	—	—	—	—	—	—	STB<23:16>								0000
DMA5PAD	0B5C	PAD<15:0>																0000
DMA5CNT	0B5E	—	—	CNT<13:0>														0000
DMA6CON	0B60	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000
DMA6REQ	0B62	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>								00FF
DMA6STAL	0B64	STA<15:0>																0000
DMA6STAH	0B66	—	—	—	—	—	—	—	—	STA<23:16>								0000
DMA6STBL	0B68	STB<15:0>																0000
DMA6STBH	0B6A	—	—	—	—	—	—	—	—	STB<23:16>								0000
DMA6PAD	0B6C	PAD<15:0>																0000
DMA6CNT	0B6E	—	—	CNT<13:0>														0000
DMA7CON	0B70	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000
DMA7REQ	0B72	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>								00FF
DMA7STAL	0B74	STA<15:0>																0000
DMA7STAH	0B76	—	—	—	—	—	—	—	—	STA<23:16>								0000
DMA7STBL	0B78	STB<15:0>																0000
DMA7STBH	0B7A	—	—	—	—	—	—	—	—	STB<23:16>								0000
DMA7PAD	0B7C	PAD<15:0>																0000
DMA7CNT	0B7E	—	—	CNT<13:0>														0000
DMA8CON	0B80	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000
DMA8REQ	0B82	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>								00FF
DMA8STAL	0B84	STA<15:0>																0000
DMA8STAH	0B86	—	—	—	—	—	—	—	—	STA<23:16>								0000
DMA8STBL	0B88	STB<15:0>																0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

8.1 DMA Resources

Many useful resources related to DMA are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310

8.1.1 KEY RESOURCES

- **Section 22. "Direct Memory Access (DMA)"** (DS70348) in the *"dsPIC33E/PIC24E Family Reference Manual"*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *"dsPIC33E/PIC24E Family Reference Manual"* Sections
- Development Tools

8.2 DMA Control Registers

Each DMAC Channel x (where x = 0 through 14) contains the following registers:

- 16-Bit DMA Channel Control register (DMAxCON)
- 16-Bit DMA Channel IRQ Select register (DMAxREQ)
- 32-Bit DMA RAM Primary Start Address register (DMAxSTA)
- 32-Bit DMA RAM Secondary Start Address register (DMAxSTB)
- 16-Bit DMA Peripheral Address register (DMAxPAD)
- 14-Bit DMA Transfer Count register (DMAxCNT)

Additional status registers (DMAPWC, DMARQC, DMAPPS, DMALCA and DSADR) are common to all DMAC channels. These status registers provide information on write and request collisions, as well as on last address and channel access information.

The DMA Interrupt Flags (DMAxIF) are located in an IFSx register in the interrupt controller. The corresponding interrupt enable control bits (DMAxIE) are located in an IECx register in the interrupt controller, and the corresponding interrupt priority control bits (DMAxIP) are located in an IPCx register in the interrupt controller.

REGISTER 9-2: CLKDIV: CLOCK DIVISOR REGISTER(2) (CONTINUED)

bit 4-0 **PLLPRE<4:0>:** PLL Phase Detector Input Divider Select bits (also denoted as 'N1', PLL prescaler)
11111 = Input divided by 33
•
•
•
00001 = Input divided by 3
00000 = Input divided by 2 (default)

Note 1: This bit is cleared when the ROI bit is set and an interrupt occurs.

2: This register resets only on a Power-on Reset (POR).

3: DOZE<2:0> bits can only be written to when the DOZEN bit is clear. If DOZEN = 1, any writes to DOZE<2:0> are ignored.

4: The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

14.1 Input Capture Resources

Many useful resources related to input capture are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en554310

14.1.1 KEY RESOURCES

- **Section 12. "Input Capture"** (DS70352) in the *"dsPIC33E/PIC24E Family Reference Manual"*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related *"dsPIC33E/PIC24E Family Reference Manual"* Sections
- Development Tools

REGISTER 16-19: IOCONx: PWMx I/O CONTROL REGISTER (CONTINUED)

bit 3-2 **CLDAT<1:0>:** Data for PWMxH and PWMxL Pins if CLMOD is Enabled bits

IFLTMOD (FCLCONx<15>) = 0: Normal Fault mode:
If current limit is active, PWMxH is driven to the state specified by CLDAT<1>.
If current limit is active, PWMxL is driven to the state specified by CLDAT<0>.

IFLTMOD (FCLCONx<15>) = 1: Independent Fault mode:
The CLDAT<1:0> bits are ignored.

bit 1 **SWAP:** Swap PWMxH and PWMxL Pins bit

1 = PWMxH output signal is connected to PWMxL pins; PWMxL output signal is connected to PWMxH pins
0 = PWMxH and PWMxL pins are mapped to their respective pins

bit 0 **OSYNC:** Output Override Synchronization bit

1 = Output overrides via the OVRDAT<1:0> bits are synchronized to the PWM time base
0 = Output overrides via the OVDDAT<1:0> bits occur on the next CPU clock boundary

Note 1: These bits should not be changed after the PWM module is enabled (PTEN = 1).

21.4 ECANx Control Registers

REGISTER 21-1: CxCTRL1: ECANx CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
—	—	CSIDL	ABAT	CANCKS	REQOP<2:0>		
bit 15							bit 8

R-1	R-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0
OPMODE<2:0>			—	CANCAP	—	—	WIN
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **CSIDL:** ECANx Stop in Idle Mode bit
1 = Discontinues module operation when device enters Idle mode
0 = Continues module operation in Idle mode

bit 12 **ABAT:** Abort All Pending Transmissions bit
1 = Signals all transmit buffers to abort transmission
0 = Module will clear this bit when all transmissions are aborted

bit 11 **CANCKS:** ECANx Module Clock (FCAN) Source Select bit
1 = FCAN is equal to twice FP
0 = FCAN is equal to FP

bit 10-8 **REQOP<2:0>:** Request Operation Mode bits
111 = Set Listen All Messages mode
110 = Reserved
101 = Reserved
100 = Set Configuration mode
011 = Set Listen Only Mode
010 = Set Loopback mode
001 = Set Disable mode
000 = Set Normal Operation mode

bit 7-5 **OPMODE<2:0>:** Operation Mode bits
111 = Module is in Listen All Messages mode
110 = Reserved
101 = Reserved
100 = Module is in Configuration mode
011 = Module is in Listen Only mode
010 = Module is in Loopback mode
001 = Module is in Disable mode
000 = Module is in Normal Operation mode

bit 4 **Unimplemented:** Read as '0'

bit 3 **CANCAP:** CAN Message Receive Timer Capture Event Enable bit
1 = Enables input capture based on CAN message receive
0 = Disables CAN capture

bit 2-1 **Unimplemented:** Read as '0'

bit 0 **WIN:** SFR Map Window Select bit
1 = Uses filter window
0 = Uses buffer window

REGISTER 22-29: UxFRML: USB FRAME NUMBER LOW REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	
bit 15							bit 8

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
FRM<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-0 **FRM<7:0>:** 11-Bit Frame Number Lower 8 bits
These register bits are updated with the current frame number whenever a SOF token is received.

REGISTER 23-1: ADxCON1: ADCx CONTROL REGISTER 1 (CONTINUED)

bit 7-5 **SSRC<2:0>:** Sample Clock Source Select bits

If SSRCG = 1:
111 = Reserved
110 = PWM Generator 7 primary trigger compare ends sampling and starts conversion(2)
101 = PWM Generator 6 primary trigger compare ends sampling and starts conversion(2)
100 = PWM Generator 5 primary trigger compare ends sampling and starts conversion(2)
011 = PWM Generator 4 primary trigger compare ends sampling and starts conversion(2)
010 = PWM Generator 3 primary trigger compare ends sampling and starts conversion(2)
001 = PWM Generator 2 primary trigger compare ends sampling and starts conversion(2)
000 = PWM Generator 1 primary trigger compare ends sampling and starts conversion(2)

If SSRCG = 0:
111 = Internal counter ends sampling and starts conversion (auto-convert)
110 = Reserved
101 = PWM secondary Special Event Trigger ends sampling and starts conversion(2)
100 = Timer5 compare ends sampling and starts conversion
011 = PWM primary Special Event Trigger ends sampling and starts conversion(2)
010 = Timer3 compare ends sampling and starts conversion
001 = Active transition on the INT0 pin ends sampling and starts conversion
000 = Clearing the Sample bit (SAMP) ends sampling and starts conversion (Manual mode)

bit 4 **SSRCG:** Sample Clock Source Group bit

(See bits<7-5> for details.)

bit 3 **SIMSAM:** Simultaneous Sample Select bit (only applicable when CHPS<1:0> = 01 or 1x)

When AD12B = 1, SIMSAM is: U-0, Unimplemented, Read as '0'
1 = Samples CH0, CH1, CH2, CH3 simultaneously (when CHPS<1:0> = 1x); or samples CH0 and CH1 simultaneously (when CHPS<1:0> = 01)
0 = Samples multiple channels individually in sequence

bit 2 **ASAM:** ADC Sample Auto-Start bit(3)

1 = Sampling begins immediately after the last conversion; SAMP bit is auto-set
0 = Sampling begins when the SAMP bit is set

bit 1 **SAMP:** ADC Sample Enable bit

1 = ADC S&H amplifiers are sampling
0 = ADC S&H amplifiers are holding
If ASAM = 0, software can write '1' to begin sampling. Automatically set by hardware if ASAM = 1.
If SSRC = 000, software can write '0' to end sampling and start conversion. If SSRC ≠ 000, automatically cleared by hardware to end sampling and start conversion.

bit 0 **DONE:** ADC Conversion Status bit(3)

1 = ADC conversion cycle is completed.
0 = ADC conversion has not started or is in progress
Automatically set by hardware when ADC conversion is complete. Software can write '0' to clear the DONE status (software not allowed to write '1'). Clearing this bit does NOT affect any operation in progress. Automatically cleared by hardware at the start of a new conversion.

Note 1: This bit is only available in the ADC1 module. In the ADC2 module, this bit is unimplemented and is read as '0'.

2: This setting is available in dsPIC33EPXXX(MC/MU)806/810/814 devices only.

3: Do not clear the DONE bit in software if ADC Sample Auto-Start is enabled (ASAM = 1).

REGISTER 24-2: DCICON2: DCI CONTROL REGISTER 2

U-0	U-0	U-0	U-0	R/W-0	R/W-0	U-0	R/W-0
r	r	r	r	BLEN<1:0>		r	COFSG3
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
COFSG<2:0>			r	WS<3:0>			
bit 7							bit 0

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Reserved:** Read as '0'

bit 11-10 **BLEN<1:0>:** Buffer Length Control bits
11 = Four data words will be buffered between interrupts
10 = Three data words will be buffered between interrupts
01 = Two data words will be buffered between interrupts
00 = One data word will be buffered between interrupts

bit 9 **Reserved:** Read as '0'

bit 8-5 **COFSG<3:0>:** Frame Sync Generator Control bits
1111 = Data frame has 16 words
•
•
•
0010 = Data frame has 3 words
0001 = Data frame has 2 words
0000 = Data frame has 1 word

bit 4 **Reserved:** Read as '0'

bit 3-0 **WS<3:0>:** DCI Data Word Size bits
1111 = Data word size is 16 bits
•
•
•
0100 = Data word size is 5 bits
0011 = Data word size is 4 bits
0010 = **Invalid Selection**. Do not use. Unexpected results may occur.
0001 = **Invalid Selection**. Do not use. Unexpected results may occur.
0000 = **Invalid Selection**. Do not use. Unexpected results may occur.

REGISTER 26-2: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL(1)	PMPTTL
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-2 **Unimplemented:** Read as '0'

bit 1 **RTSECSEL:** RTCC Seconds Clock Output Select bit(1)
1 = RTCC seconds clock is selected for the RTCC pin
0 = RTCC alarm pulse is selected for the RTCC pin

bit 0 Not used by the RTCC module.

Note 1: To enable the actual RTCC output, the RTCOE bit (RCFGCAL<10>) must be set.

TABLE 32-4: DC TEMPERATURE AND VOLTAGE SPECIFICATIONS

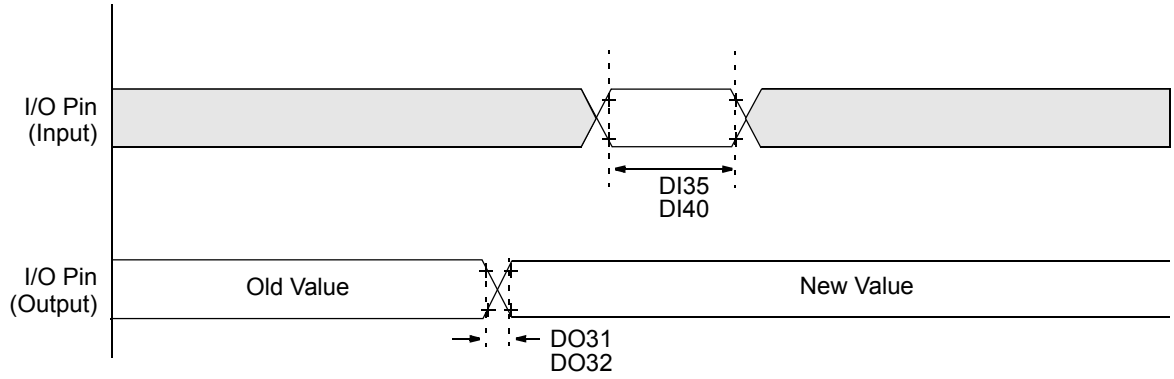
DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	**Symbol**	**Characteristic**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
Operating Voltage							
DC10	VDD	**Supply Voltage(3)**	3.0	—	3.6	V	
DC12	VDR	**RAM Data Retention Voltage(2)**	1.8	—	—	V	
DC16	VPOR	**VDD Start Voltage** to Ensure Internal Power-on Reset Signal	—	—	VSS	V	
DC17	SVDD	**VDD Rise Rate** to Ensure Internal Power-on Reset Signal	1.0	—	—	V/ms	0-3.0V in 3 ms

Note 1: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.

2: This is the limit to which VDD may be lowered without losing RAM data.

3: Device is functional at VBORMIN < VDD < VDDMIN. Analog modules: ADC, Comparator and DAC will have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 32-11 for the minimum and maximum BOR values.

FIGURE 32-3: I/O TIMING CHARACTERISTICS



Note: Refer to Figure 32-1 for load conditions.

TABLE 32-21: I/O TIMING REQUIREMENTS

AC CHARACTERISTICS		**Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)** Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param.	**Symbol**	**Characteristic**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
DO31	TIOR	Port Output Rise Time	—	5	10	ns	
DO32	TIOF	Port Output Fall Time	—	5	10	ns	
DI35	TINP	INTx Pin High or Low Time (input)	20	—	—	ns	
DI40	TRBP	CNx High or Low Time (input)	2	—	—	TCY	

Note 1: Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.

FIGURE 32-13: QEA/QEB INPUT CHARACTERISTICS (dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY)

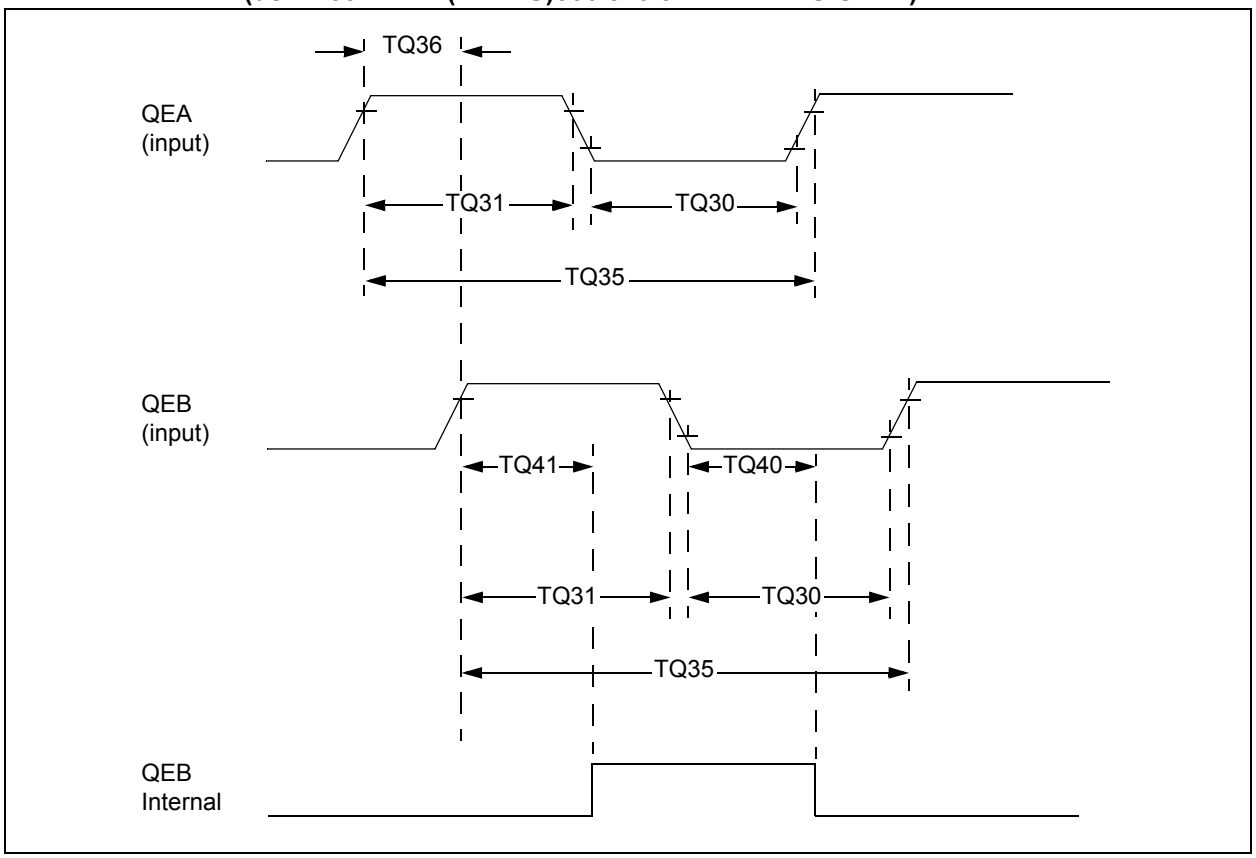


TABLE 32-31: QUADRATURE DECODER TIMING REQUIREMENTS (dsPIC33EPXXX(MC/MU)806/810/814 DEVICES ONLY)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param.	**Symbol**	**Characteristic(1)**	**Typ.(2)**	**Max.**	**Units**	**Conditions**
TQ30	TQUL	Quadrature Input Low Time	6 TCY	—	ns	
TQ31	TQUH	Quadrature Input High Time	6 TCY	—	ns	
TQ35	TQUIN	Quadrature Input Period	12 TCY	—	ns	
TQ36	TQUP	Quadrature Phase Period	3 TCY	—	ns	
TQ40	TQUFL	Filter Time to Recognize Low with Digital Filter	3 * N * TCY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)**
TQ41	TQUFH	Filter Time to Recognize High with Digital Filter	3 * N * TCY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)**

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: N = Index Channel Digital Filter Clock Divide Select bits. Refer to **Section 15. "Quadrature Encoder Interface (QEI)"** (DS70601) in the "*dsPIC33E/PIC24E Family Reference Manual*". Please see the Microchip web site for the latest family reference manual sections.

TABLE 32-49: I2Cx BUS DATA TIMING REQUIREMENTS (MASTER MODE)

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param.	**Symbol**	**Characteristic(4)**		**Min.(1)**	**Max.**	**Units**	**Conditions**
IM10	TLO:SCL	Clock Low Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	
			400 kHz mode	TCY/2 (BRG + 2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM11	THI:SCL	Clock High Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	
			400 kHz mode	TCY/2 (BRG + 2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM20	TF:SCL	SDAx and SCLx Fall Time	100 kHz mode	—	300	ns	CB is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 CB	300	ns	
			1 MHz mode(2)	—	100	ns	
IM21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	—	1000	ns	CB is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 CB	300	ns	
			1 MHz mode(2)	—	300	ns	
IM25	TSU:DAT	Data Input Setup Time	100 kHz mode	250	—	ns	
			400 kHz mode	100	—	ns	
			1 MHz mode(2)	40	—	ns	
IM26	THD:DAT	Data Input Hold Time	100 kHz mode	0	—	µs	
			400 kHz mode	0	0.9	µs	
			1 MHz mode(2)	0.2	—	µs	
IM30	TSU:STA	Start Condition Setup Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	Only relevant for Repeated Start condition
			400 kHz mode	TCY/2 (BRG + 2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM31	THD:STA	Start Condition Hold Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	After this period, the first clock pulse is generated
			400 kHz mode	TCY/2 (BRG +2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM33	TSU:STO	Stop Condition Setup Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	
			400 kHz mode	TCY/2 (BRG + 2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM34	THD:STO	Stop Condition Hold Time	100 kHz mode	TCY/2 (BRG + 2)	—	µs	
			400 kHz mode	TCY/2 (BRG + 2)	—	µs	
			1 MHz mode(2)	TCY/2 (BRG + 2)	—	µs	
IM40	TAA:SCL	Output Valid From Clock	100 kHz mode	—	3500	ns	
			400 kHz mode	—	1000	ns	
			1 MHz mode(2)	—	400	ns	
IM45	TBF:SDA	Bus Free Time	100 kHz mode	4.7	—	µs	Time the bus must be free before a new transmission can start
			400 kHz mode	1.3	—	µs	
			1 MHz mode(2)	0.5	—	µs	
IM50	CB	Bus Capacitive Loading		—	400	pF	
IM51	TPGD	Pulse Gobbler Delay		65	390	ns	See **Note 3**

Note 1: BRG is the value of the I^2C Baud Rate Generator. Refer to **Section 19. "Inter-Integrated Circuit (I^2C™)"** (DS70330) in the "*dsPIC33E/PIC24E Family Reference Manual*". Please see the Microchip web site for the latest family reference manual sections.

2: Maximum pin capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

3: Typical value for this parameter is 130 ns.

4: These parameters are characterized, but not tested in manufacturing.

33.0 DC AND AC DEVICE CHARACTERISTICS GRAPHS

Note: The graphs provided following this note are a statistical summary based on a limited number of samples and are provided for design guidance purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore, outside the warranted range.

FIGURE 33-1: VOH – 4x DRIVER PINS @ +85ºC

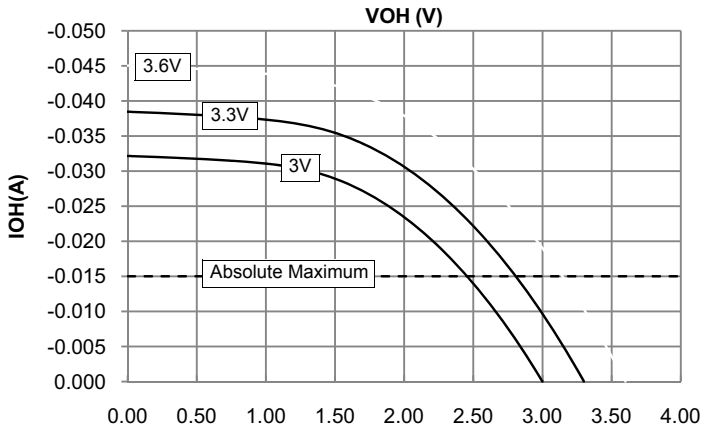


FIGURE 33-2: VOH – 8x DRIVER PINS @ +85ºC

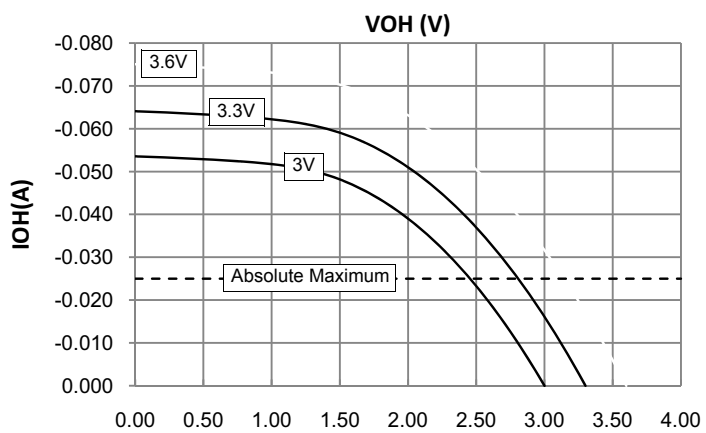


FIGURE 33-3: VOL – 4x DRIVER PINS @ +85ºC

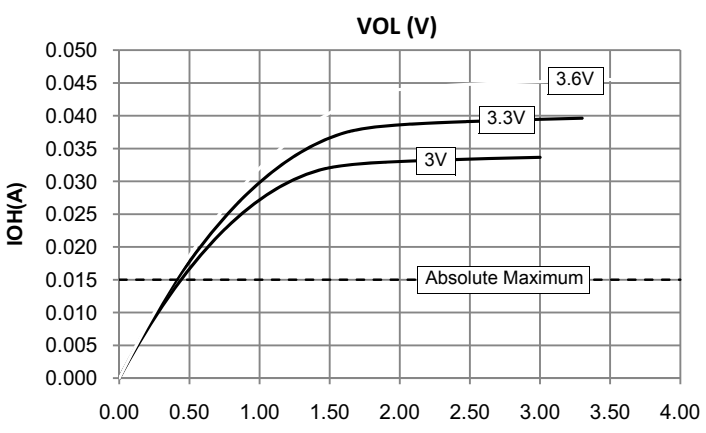
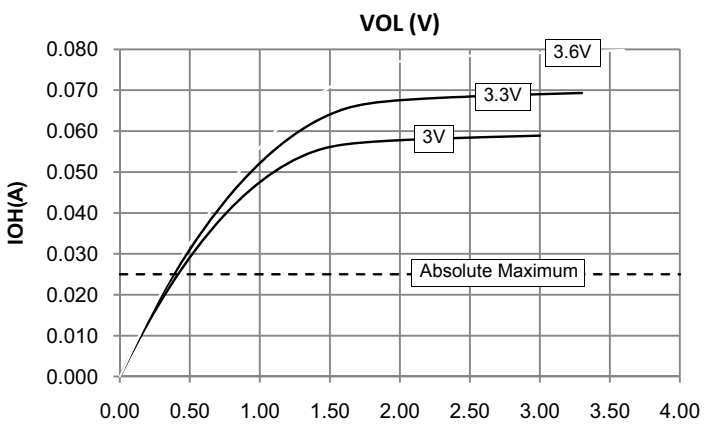


FIGURE 33-4: VOL – 8x DRIVER PINS @ +85ºC



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