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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	21
Program Memory Size	12KB (4K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 10x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24hj12gp202-e-ss

PIC24HJ12GP201/202

PIC24HJ12GP201/202 Product Families

The device names, pin counts, memory sizes and peripheral availability of each family are listed below, followed by their pinout diagrams.

TABLE 1: PIC24HJ12GP201/202 CONTROLLER FAMILIES

Device	Pins	Program Flash Memory (Kbyte)	RAM (Kbyte)	Remappable Peripherals							10-Bit/12-Bit ADC	I ² C™	I/O Pins (Max)	Packages
				Remappable Pins	16-bit Timer	Input Capture	Output Compare Std. PWM	UART	External Interrupts ⁽²⁾	SPI				
PIC24HJ12GP201	18	12	1	8	3 ⁽¹⁾	4	2	1	3	1	1 ADC, 6 ch	1	13	PDIP SOIC
PIC24HJ12GP202	28	12	1	16	3 ⁽¹⁾	4	2	1	3	1	1 ADC, 10 ch	1	21	SPDIP SOIC SSOP QFN

Note 1: Only two out of three timers are remappable.

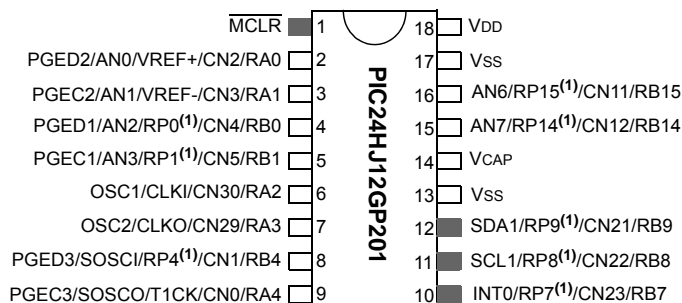
2: Only two out of three interrupts are remappable.

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Pin Diagrams

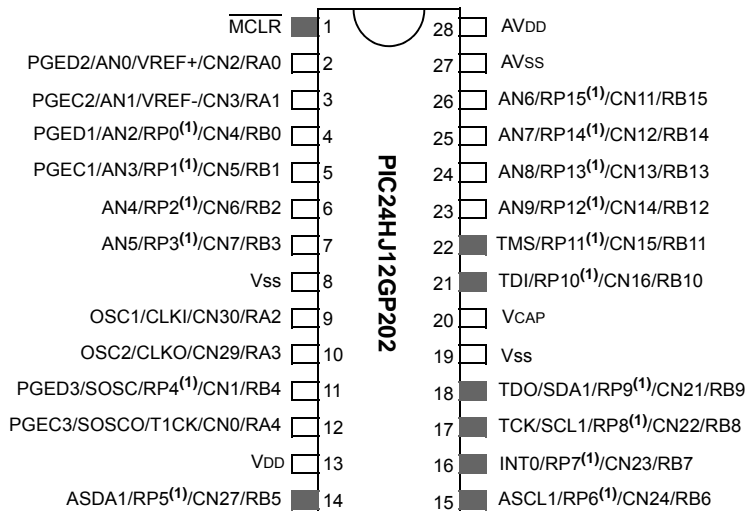
18-Pin PDIP, SOIC

■ = Pins are up to 5V tolerant



28-Pin SPDIP, SOIC, SSOP

■ = Pins are up to 5V tolerant



Note 1: The RPN pins can be used by any remappable peripheral. See Table 1 for the list of available peripherals.

TABLE 4-16: PORTA REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	02C0	—	—	—	—	—	—	—	—	—	—	—	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	001F
PORTA	02C2	—	—	—	—	—	—	—	—	—	—	—	RA4	RA3	RA2	RA1	RA0	xxxx
LATA	02C4	—	—	—	—	—	—	—	—	—	—	—	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
ODCA	02C6	—	—	—	—	—	—	—	—	—	—	—	ODCA4	ODCA3	ODCA2	ODCA1	ODCA0	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-17: PORTB REGISTER MAP FOR PIC24HJ12GP202

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	02CA	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	02CC	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	02CE	ODCB15	ODCB14	ODCB13	ODCB12	ODCB11	ODCB10	ODCB9	ODCB8	ODCB7	ODCB6	ODCB5	ODCB4	ODCB3	ODCB2	ODCB1	ODCB0	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-18: PORTB REGISTER MAP FOR PIC24HJ12GP201

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	—	—	—	—	TRISB9	TRISB8	TRISB7	—	—	TRISB4	—	—	TRISB1	TRISB0	C393
PORTB	02CA	RB15	RB14	—	—	—	—	RB9	RB8	RB7	—	—	RB4	—	—	RB1	RB0	xxxx
LATB	02CC	LATB15	LATB14	—	—	—	—	LATB9	LATB8	LATB7	—	—	LATB4	—	—	LATB1	LATB0	xxxx
ODCB	02CE	ODCB15	ODCB14	—	—	—	—	ODCB9	ODCB8	ODCB7	—	—	ODCB4	—	—	ODCB1	ODCB0	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

4.4.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The **TBLRDL** and **TBLWTL** instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The **TBLRDH** and **TBLWTH** instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two 16-bit-wide word address spaces, residing side by side, each with the same address range. **TBLRDL** and **TBLWTL** access the space that contains the least significant data word. **TBLRDH** and **TBLWTH** access the space that contains the upper data byte.

Two table instructions are provided to move byte- or word-sized (16-bit) data to and from program space. Both function as either byte or word operations.

- **TBLRDL** (Table Read Low): In Word mode, this instruction maps the lower word of the program space location ($P<15:0>$) to a data address ($D<15:0>$).

In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when Byte Select is '1'; the lower byte is selected when it is '0'.

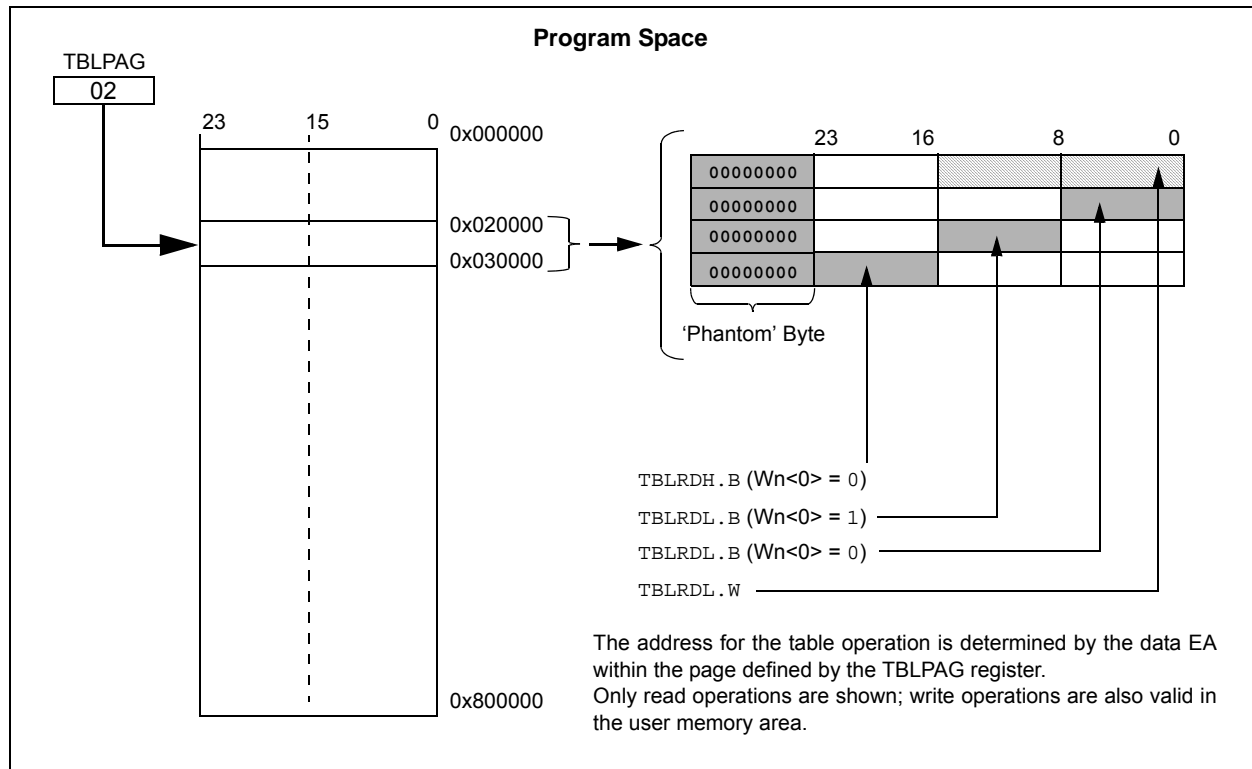
- **TBLRDH** (Table Read High): In Word mode, this instruction maps the entire upper word of a program address ($P<23:16>$) to a data address. Note that $D<15:8>$, the 'phantom byte', will always be '0'.

In Byte mode, this instruction maps the upper or lower byte of the program word to $D<7:0>$ of the data address, as in the **TBLRDL** instruction. Note that the data will always be '0' when the upper 'phantom' byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, **TBLWTH** and **TBLWTL**, are used to write individual bytes or words to a program space address. The details of their operation are explained in **Section 5.0 "Flash Program Memory"**.

For all table operations, the area of program memory space to be accessed is determined by the Table Page register (TBLPAG). TBLPAG covers the entire program memory space of the device, including user and configuration spaces. When $TBLPAG<7> = 0$, the table page is located in the user memory space. When $TBLPAG<7> = 1$, the page is located in configuration space.

FIGURE 4-6: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS



REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

- bit 1 **BOR:** Brown-out Reset Flag bit
 1 = A Brown-out Reset has occurred
 0 = A Brown-out Reset has not occurred
- bit 0 **POR:** Power-on Reset Flag bit
 1 = A Power-on Reset has occurred
 0 = A Power-on Reset has not occurred

- Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
- 2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

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REGISTER 7-1: SR: CPU STATUS REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	DC
bit 15							bit 8

R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 ⁽²⁾	IPL1 ⁽²⁾	IPL0 ⁽²⁾	RA	N	OV	Z	C
bit 7							bit 0

Legend:

C = Clear only bit	R = Readable bit	U = Unimplemented bit, read as '0'
S = Set only bit	W = Writable bit	-n = Value at POR
'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5 **IPL<2:0>**: CPU Interrupt Priority Level Status bits⁽¹⁾

- 111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
- 110 = CPU Interrupt Priority Level is 6 (14)
- 101 = CPU Interrupt Priority Level is 5 (13)
- 100 = CPU Interrupt Priority Level is 4 (12)
- 011 = CPU Interrupt Priority Level is 3 (11)
- 010 = CPU Interrupt Priority Level is 2 (10)
- 001 = CPU Interrupt Priority Level is 1 (9)
- 000 = CPU Interrupt Priority Level is 0 (8)

Note 1: For complete register details, see **Register 3-1: “SR: CPU Status Register”**.

- The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- The IPL<2:0> Status bits are read-only when NSTDIS (INTCON1<15>) = 1.

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REGISTER 8-2: CLKDIV: CLOCK DIVISOR REGISTER⁽²⁾

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
ROI	DOZE<2:0>			DOZEN ⁽¹⁾	FRCDIV<2:0>		
bit 15							bit 8

R/W-0	R/W-1	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PLLPOST<1:0>		—	PLLPRE<4:0>				
bit 7							bit 0

Legend:	y = Value set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **ROI:** Recover on Interrupt bit
1 = Interrupts will clear the DOZEN bit and the processor clock/peripheral clock ratio is set to 1:1
0 = Interrupts have no effect on the DOZEN bit
- bit 14-12 **DOZE<2:0>:** Processor Clock Reduction Select bits
111 = Fcy/128
110 = Fcy/64
101 = Fcy/32
100 = Fcy/16
011 = Fcy/8 (default)
010 = Fcy/4
001 = Fcy/2
000 = Fcy/1
- bit 11 **DOZEN:** DOZE Mode Enable bit⁽¹⁾
1 = DOZE<2:0> field specifies the ratio between the peripheral clocks and the processor clocks
0 = Processor clock/peripheral clock ratio forced to 1:1
- bit 10-8 **FRCDIV<2:0>:** Internal Fast RC Oscillator Postscaler bits
111 = FRC divide by 256
110 = FRC divide by 64
101 = FRC divide by 32
100 = FRC divide by 16
011 = FRC divide by 8
010 = FRC divide by 4
001 = FRC divide by 2
000 = FRC divide by 1 (default)
- bit 7-6 **PLLPOST<1:0>:** PLL VCO Output Divider Select bits (also denoted as 'N2', PLL postscaler)
00 = Output/2
01 = Output/4 (default)
10 = Reserved
11 = Output/8
- bit 5 **Unimplemented:** Read as '0'
- bit 4-0 **PLLPRE<4:0>:** PLL Phase Detector Input Divider bits (also denoted as 'N1', PLL prescaler)
00000 = Input/2 (default)
00001 = Input/3
.
.
.
11111 = Input/33

- Note 1:** This bit is cleared when the ROI bit is set and an interrupt occurs.
2: This register is reset only on a Power-on Reset (POR).

NOTES:

REGISTER 9-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
—	—	T3MD	T2MD	T1MD	—	—	—
bit 15				bit 8			

R/W-0	U-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0
I2C1MD	—	U1MD	—	SPI1MD	—	—	AD1MD ⁽¹⁾
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **T3MD:** Timer3 Module Disable bit
1 = Timer3 module is disabled
0 = Timer3 module is enabled
- bit 12 **T2MD:** Timer2 Module Disable bit
1 = Timer2 module is disabled
0 = Timer2 module is enabled
- bit 11 **T1MD:** Timer1 Module Disable bit
1 = Timer1 module is disabled
0 = Timer1 module is enabled
- bit 10-8 **Unimplemented:** Read as '0'
- bit 7 **I2C1MD:** I²C1 Module Disable bit
1 = I²C1 module is disabled
0 = I²C1 module is enabled
- bit 6 **Unimplemented:** Read as '0'
- bit 5 **U1MD:** UART1 Module Disable bit
1 = UART1 module is disabled
0 = UART1 module is enabled
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = SPI1 module is disabled
0 = SPI1 module is enabled
- bit 2-1 **Unimplemented:** Read as '0'
- bit 0 **AD1MD:** ADC1 Module Disable bit⁽¹⁾
1 = ADC1 module is disabled
0 = ADC1 module is enabled

Note 1: PCFGx bits have no effect if the ADC module is disabled by setting this bit. When the bit is set, all port pins that have been multiplexed with ANx will be in Digital mode.

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REGISTER 10-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T3CKR<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T2CKR<4:0>				
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **T3CKR<4:0>:** Assign Timer3 External Clock (T3CK) to the Corresponding RPN pin bits

11111 = Input tied to Vss

01111 = Input tied to RP15

•
•
•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **T2CKR<4:0>:** Assign Timer2 External Clock (T2CK) to the Corresponding RPN pin bits

11111 = Input tied to Vss

01111 = Input tied to RP15

•
•
•

00001 = Input tied to RP1

00000 = Input tied to RP0

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REGISTER 10-12: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP5R<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP4R<4:0>				
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-13 **Unimplemented:** Read as '0'
bit 12-8 **RP5R<4:0>:** Peripheral Output Function is Assigned to RP5 Output Pin bits (see Table 10-2 for peripheral function numbers)
bit 7-5 **Unimplemented:** Read as '0'
bit 4-0 **RP4R<4:0>:** Peripheral Output Function is Assigned to RP4 Output Pin bits (see Table 10-2 for peripheral function numbers)

REGISTER 10-13: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3

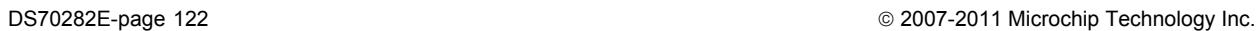
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP7R<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP6R<4:0>				
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-13 **Unimplemented:** Read as '0'
bit 12-8 **RP7R<4:0>:** Peripheral Output Function is Assigned to RP7 Output Pin bits (see Table 10-2 for peripheral function numbers)
bit 7-5 **Unimplemented:** Read as '0'
bit 4-0 **RP6R<4:0>:** Peripheral Output Function is Assigned to RP6 Output Pin bits (see Table 10-2 for peripheral function numbers)

[illegible]

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14.1 Output Compare Modes

Configure the Output Compare modes by setting the appropriate Output Compare Mode (OCM<2:0>) bits in the Output Compare Control (OCxCON<2:0>) register. Table 14-1 lists the different bit settings for the Output Compare modes. Figure 14-2 illustrates the output compare operation for various modes. The user

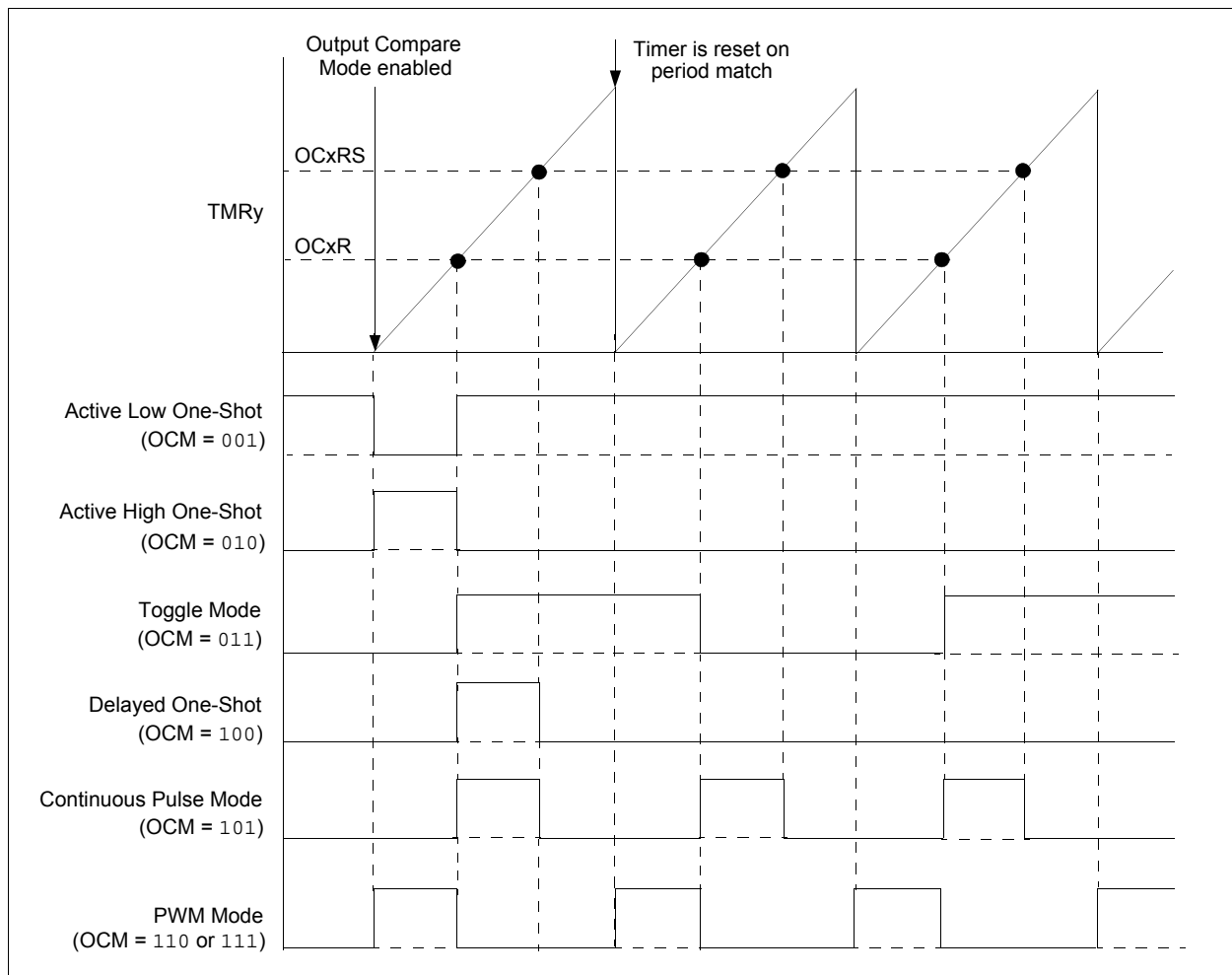
application must disable the associated timer when writing to the output compare control registers to avoid malfunctions.

Note: See **Section 13. “Output Compare”** in the *dsPIC33F/PIC24H Family Reference Manual* (DS70209) for OCxR and OCxRS register restrictions.

TABLE 14-1: OUTPUT COMPARE MODES

OCM<2:0>	Mode	OCx Pin Initial State	OCx Interrupt Generation
000	Module Disabled	Controlled by GPIO register	—
001	Active-Low One-Shot	0	OCx Rising edge
010	Active-High One-Shot	1	OCx Falling edge
011	Toggle Mode	Current output is maintained	OCx Rising and Falling edge
100	Delayed One-Shot	0	OCx Falling edge
101	Continuous Pulse mode	0	OCx Falling edge
110	PWM mode without fault protection	0, if OCxR is zero 1, if OCxR is non-zero	No interrupt
111	PWM mode with fault protection	0, if OCxR is zero 1, if OCxR is non-zero	OCFA Falling edge for OC1 to OC4

FIGURE 14-2: OUTPUT COMPARE OPERATION



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REGISTER 18-5: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB	—	—	CH0SB<4:0>				
bit 15							bit 8

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA	—	—	CH0SA<4:0>				
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **CH0NB:** Channel 0 Negative Input Select for Sample B bit

1 = Channel 0 negative input is AN1

0 = Channel 0 negative input is VREF-

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **CH0SB<4:0>:** Channel 0 Positive Input Select for Sample B bits

PIC24HJ12GP201 devices only:

00111 = Channel 0 positive input is AN7

00110 = Channel 0 positive input is AN6

00101 = Reserved

00100 = Reserved

00011 = Channel 0 positive input is AN3

00010 = Channel 0 positive input is AN2

00001 = Channel 0 positive input is AN1

00000 = Channel 0 positive input is AN0

PIC24HJ12GP202 devices only:

01001 = Channel 0 positive input is AN9

•

•

•

00010 = Channel 0 positive input is AN2

00001 = Channel 0 positive input is AN1

00000 = Channel 0 positive input is AN0

bit 7 **CH0NA:** Channel 0 Negative Input Select for Sample A bit

1 = Channel 0 negative input is AN1

0 = Channel 0 negative input is VREF-

bit 6-5 **Unimplemented:** Read as '0'

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NOTES:

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TABLE 22-7: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended		
Parameter No.	Typical ⁽¹⁾	Max	Units	Conditions	
Power-Down Current (IPD) ⁽²⁾					
DC60d	55	500	μA	-40°C	3.3V Base Power-Down Current ^(3,4)
DC60a	63	500	μA	+25°C	
DC60b	85	500	μA	+85°C	
DC60c	146	1000	μA	+125°C	
DC61d	8	13	μA	-40°C	3.3V Watchdog Timer Current: ΔI _{WDT} ^(3,5)
DC61a	10	15	μA	+25°C	
DC61b	12	20	μA	+85°C	
DC61c	13	25	μA	+125°C	

Note 1: Data in the Typical column is at 3.3V, 25°C unless otherwise stated.

2: Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to V_{SS}, WDT, etc., are all switched off, and VREGS (RCON<8>) = 1.

3: The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.

4: These currents are measured on the device containing the most memory in this family.

5: These parameters are characterized, but are not tested in manufacturing.

TABLE 22-8: DC CHARACTERISTICS: DOZE CURRENT (IDOZE)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended		
Parameter No.	Typical ⁽¹⁾	Max	Doze Ratio ⁽²⁾	Units	Conditions
DC73a	11	35	1:2	mA	-40°C 3.3V 40 MIPS
DC73f	11	30	1:64	mA	
DC73g	11	30	1:128	mA	
DC70a	11	50	1:2	mA	+25°C 3.3V 40 MIPS
DC70f	11	30	1:64	mA	
DC70g	11	30	1:128	mA	
DC71a	12	50	1:2	mA	+85°C 3.3V 40 MIPS
DC71f	12	30	1:64	mA	
DC71g	12	30	1:128	mA	
DC72a	12	50	1:2	mA	+125°C 3.3V 40 MIPS
DC72f	12	30	1:64	mA	
DC72g	12	30	1:128	mA	

Note 1: Data in the Typical column is at 3.3V, 25°C unless otherwise stated.

2: Parameters with DOZE ratios of 1:2 and 1:64 are characterized, but are not tested in manufacturing.

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TABLE 22-10: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
DO10 DO16	VOL	Output Low Voltage					
		I/O ports	—	—	0.4	V	IO _L = 2mA, V _{DD} = 3.3V
		OSC2/CLKO	—	—	0.4	V	IO _L = 2mA, V _{DD} = 3.3V
DO20 DO26	VOH	Output High Voltage					
		I/O ports	2.40	—	—	V	IO _H = -2.3 mA, V _{DD} = 3.3V
		OSC2/CLKO	2.41	—	—	V	IO _H = -1.3 mA, V _{DD} = 3.3V

TABLE 22-11: ELECTRICAL CHARACTERISTICS: BOR

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
BO10	VBOR	BOR Event on V _{DD} transition high-to-low	2.40	—	2.55	V	V _{DD}

Note 1: Parameters are for design guidance only and are not tested in manufacturing.

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22.2 AC Characteristics and Timing Parameters

The information contained in this section defines PIC24HJ12GP201/202 AC characteristics and timing parameters.

TABLE 22-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC

AC CHARACTERISTICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended Operating voltage V_{DD} range as described in Section 22.1 “DC Characteristics” .
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FIGURE 22-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

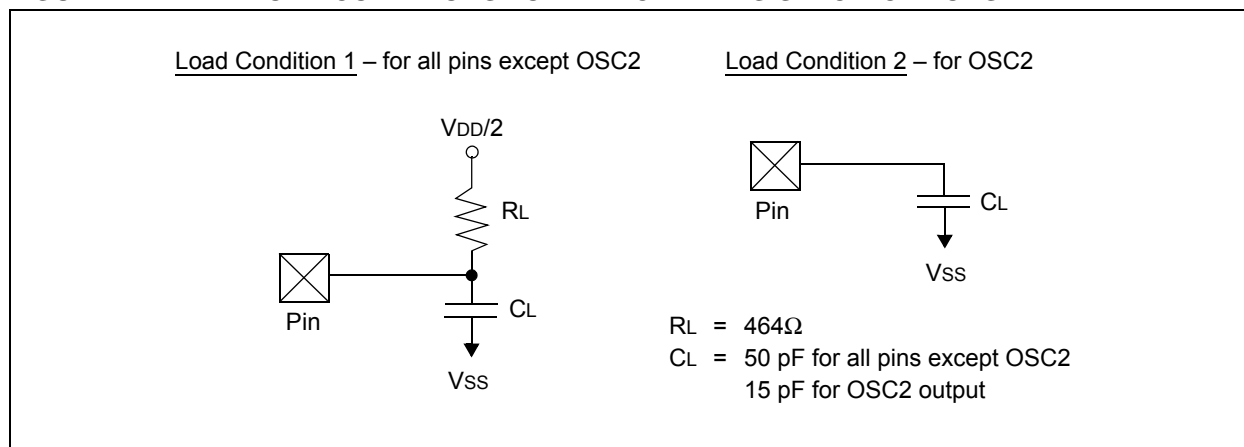


TABLE 22-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
DO50	Cosc2	OSC2/SOSC2 pin	—	—	15	pF	In XT and HS modes when external clock is used to drive OSC1
DO56	Cio	All I/O pins and OSC2	—	—	50	pF	EC mode
DO58	CB	SCLx, SDAx	—	—	400	pF	In I ² C™ mode

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FIGURE 22-5: TIMER1, 2, 3 AND 4 EXTERNAL CLOCK TIMING CHARACTERISTICS

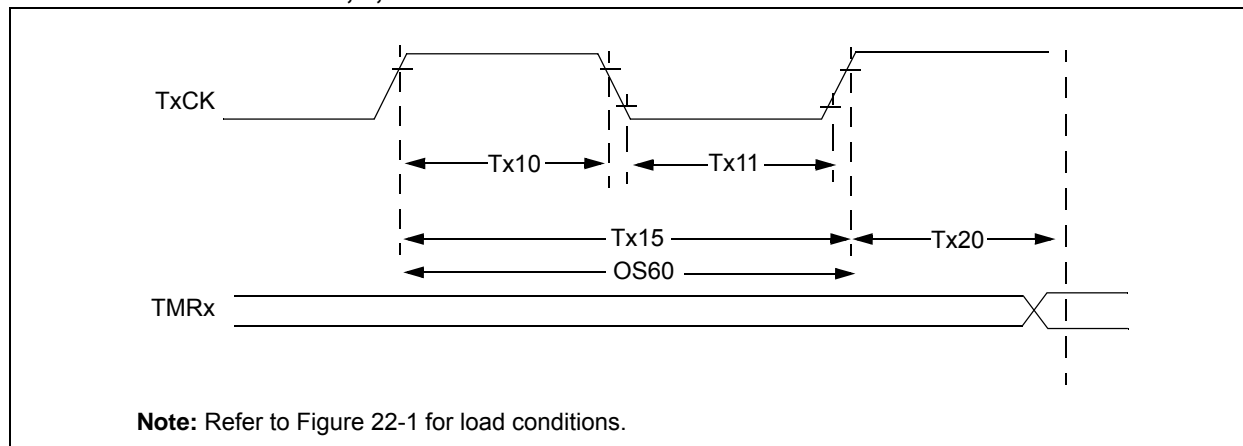


TABLE 22-22: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS⁽¹⁾

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic		Min	Typ	Max	Units	Conditions
TA10	T _{TxH}	TxCK High Time	Synchronous, no prescaler	T _{CY} + 20	—	—	ns	Must also meet parameter TA15. N = prescale value (1, 8, 64, 256)
			Synchronous, with prescaler	(T _{CY} + 20)/N	—	—	ns	
			Asynchronous	20	—	—	ns	
TA11	T _{TxL}	TxCK Low Time	Synchronous, no prescaler	(T _{CY} + 20)	—	—	ns	Must also meet parameter TA15. N = prescale value (1, 8, 64, 256)
			Synchronous, with prescaler	(T _{CY} + 20)/N	—	—	ns	
			Asynchronous	20	—	—	ns	
TA15	T _{TxP}	TxCK Input Period	Synchronous, no prescaler	2 T _{CY} + 40	—	—	ns	—
			Synchronous, with prescaler	Greater of: 40 ns or (2 T _{CY} + 40)/N	—	—	—	N = prescale value (1, 8, 64, 256)
			Asynchronous	40	—	—	ns	—
OS60	F _{t1}	SOSCI/T1CK Oscillator Input frequency Range (oscillator enabled by setting bit TCS (T1CON<1>))		DC	—	50	kHz	—
TA20	T _{CKEXTMRL}	Delay from External TxCK Clock Edge to Timer Increment		0.75 T _{CY} + 40		1.75 T _{CY} + 40	—	—

Note 1: Timer1 is a Type A.