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Details

Product Status	Obsolete
Core Processor	HC08
Core Size	8-Bit
Speed	8MHz
Connectivity	I ² C, IRSCI, SPI
Peripherals	LCD, LVD, POR, PWM
Number of I/O	40
Program Memory Size	24KB (24K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 6x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc68hc908lk24cpb

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Table 6-2. Opcode Map

	Bit Manipulation		Branch	Read-Modify-Write						Control		Register/Memory							
	DIR	DIR	REL	DIR	INH	INH	IX1	SP1	IX	INH	INH	IMM	DIR	EXT	IX2	SP2	IX1	SP1	IX
MSB LSB	0	1	2	3	4	5	6	9E6	7	8	9	A	B	C	D	9ED	E	9EE	F
0	BRSET0 3 DIR	BSET0 2 DIR	BRA 2 REL	NEG 2 DIR	NEGA 1 INH	NEGX 1 INH	NEG 2 IX1	NEG 3 SP1	NEG 1 IX	RTI 1 INH	BGE 2 REL	SUB 2 IMM	SUB 2 DIR	SUB 3 EXT	SUB 3 IX2	SUB 4 SP2	SUB 2 IX1	SUB 3 SP1	SUB 1 IX
1	BRCLR0 3 DIR	BCLR0 2 DIR	BRN 2 REL	CBEQ 3 DIR	CBEQA 3 IMM	CBEQX 3 IMM	CBEQ 3 IX1+	CBEQ 4 SP1	CBEQ 2 IX+	RTS 1 INH	BLT 2 REL	CMP 2 IMM	CMP 2 DIR	CMP 3 EXT	CMP 3 IX2	CMP 4 SP2	CMP 2 IX1	CMP 3 SP1	CMP 1 IX
2	BRSET1 3 DIR	BSET1 2 DIR	BHI 2 REL		MUL 1 INH	DIV 1 INH	NSA 1 INH		DAA 1 INH		BGT 2 REL	SBC 2 IMM	SBC 2 DIR	SBC 3 EXT	SBC 3 IX2	SBC 4 SP2	SBC 2 IX1	SBC 3 SP1	SBC 1 IX
3	BRCLR1 3 DIR	BCLR1 2 DIR	BLS 2 REL	COM 2 DIR	COMA 1 INH	COMX 1 INH	COM 2 IX1	COM 3 SP1	COM 1 IX	SWI 1 INH	BLE 2 REL	CPX 2 IMM	CPX 2 DIR	CPX 3 EXT	CPX 3 IX2	CPX 4 SP2	CPX 2 IX1	CPX 3 SP1	CPX 1 IX
4	BRSET2 3 DIR	BSET2 2 DIR	BCC 2 REL	LSR 2 DIR	LSRA 1 INH	LSRX 1 INH	LSR 2 IX1	LSR 3 SP1	LSR 1 IX	TAP 1 INH	TXS 1 INH	AND 2 IMM	AND 2 DIR	AND 3 EXT	AND 3 IX2	AND 4 SP2	AND 2 IX1	AND 3 SP1	AND 1 IX
5	BRCLR2 3 DIR	BCLR2 2 DIR	BCS 2 REL	STHX 2 DIR	LDHX 3 IMM	LDHX 2 DIR	CPHX 3 IMM		CPHX 2 DIR	TPA 1 INH	TSX 1 INH	BIT 2 IMM	BIT 2 DIR	BIT 3 EXT	BIT 3 IX2	BIT 4 SP2	BIT 2 IX1	BIT 3 SP1	BIT 1 IX
6	BRSET3 3 DIR	BSET3 2 DIR	BNE 2 REL	ROR 2 DIR	RORA 1 INH	RORX 1 INH	ROR 2 IX1	ROR 3 SP1	ROR 1 IX	PULA 1 INH		LDA 2 IMM	LDA 2 DIR	LDA 3 EXT	LDA 3 IX2	LDA 4 SP2	LDA 2 IX1	LDA 3 SP1	LDA 1 IX
7	BRCLR3 3 DIR	BCLR3 2 DIR	BEQ 2 REL	ASR 2 DIR	ASRA 1 INH	ASRX 1 INH	ASR 2 IX1	ASR 3 SP1	ASR 1 IX	PSHA 1 INH	TAX 1 INH	AIS 2 IMM	STA 2 DIR	STA 3 EXT	STA 3 IX2	STA 4 SP2	STA 2 IX1	STA 3 SP1	STA 1 IX
8	BRSET4 3 DIR	BSET4 2 DIR	BHCC 2 REL	LSL 2 DIR	LSLA 1 INH	LSLX 1 INH	LSL 2 IX1	LSL 3 SP1	LSL 1 IX	PULX 1 INH	CLC 1 INH	EOR 2 IMM	EOR 2 DIR	EOR 3 EXT	EOR 3 IX2	EOR 4 SP2	EOR 2 IX1	EOR 3 SP1	EOR 1 IX
9	BRCLR4 3 DIR	BCLR4 2 DIR	BHCS 2 REL	ROL 2 DIR	ROLA 1 INH	ROLX 1 INH	ROL 2 IX1	ROL 3 SP1	ROL 1 IX	PSHX 1 INH	SEC 1 INH	ADC 2 IMM	ADC 2 DIR	ADC 3 EXT	ADC 3 IX2	ADC 4 SP2	ADC 2 IX1	ADC 3 SP1	ADC 1 IX
A	BRSET5 3 DIR	BSET5 2 DIR	BPL 2 REL	DEC 2 DIR	DECA 1 INH	DECX 1 INH	DEC 2 IX1	DEC 3 SP1	DEC 1 IX	PULH 1 INH	CLI 1 INH	ORA 2 IMM	ORA 2 DIR	ORA 3 EXT	ORA 3 IX2	ORA 4 SP2	ORA 2 IX1	ORA 3 SP1	ORA 1 IX
B	BRCLR5 3 DIR	BCLR5 2 DIR	BMI 2 REL	DBNZ 3 DIR	DBNZA 2 INH	DBNZX 2 INH	DBNZ 3 IX1	DBNZ 4 SP1	DBNZ 2 IX	PSHH 1 INH	SEI 1 INH	ADD 2 IMM	ADD 2 DIR	ADD 3 EXT	ADD 3 IX2	ADD 4 SP2	ADD 2 IX1	ADD 3 SP1	ADD 1 IX
C	BRSET6 3 DIR	BSET6 2 DIR	BMC 2 REL	INC 2 DIR	INCA 1 INH	INCX 1 INH	INC 2 IX1	INC 3 SP1	INC 1 IX	CLRH 1 INH	RSP 1 INH		JMP 2 DIR	JMP 3 EXT	JMP 3 IX2		JMP 2 IX1		JMP 1 IX
D	BRCLR6 3 DIR	BCLR6 2 DIR	BMS 2 REL	TST 2 DIR	TSTA 1 INH	TSTX 1 INH	TST 2 IX1	TST 3 SP1	TST 1 IX		NOP 1 INH	BSR 2 REL	JSR 2 DIR	JSR 3 EXT	JSR 3 IX2		JSR 2 IX1		JSR 1 IX
E	BRSET7 3 DIR	BSET7 2 DIR	BIL 2 REL		MOV 3 DD	MOV 2 DIX+	MOV 3 IMD		MOV 2 IX+D	STOP 1 INH	*	LDX 2 IMM	LDX 2 DIR	LDX 3 EXT	LDX 3 IX2	LDX 4 SP2	LDX 2 IX1	LDX 3 SP1	LDX 1 IX
F	BRCLR7 3 DIR	BCLR7 2 DIR	BIH 2 REL	CLR 2 DIR	CLRA 1 INH	CLR 1 INH	CLR 2 IX1	CLR 3 SP1	CLR 1 IX	WAIT 1 INH	TXA 1 INH	AIX 2 IMM	STX 2 DIR	STX 3 EXT	STX 3 IX2	STX 4 SP2	STX 2 IX1	STX 3 SP1	STX 1 IX

INH Inherent
IMM Immediate
DIR Direct
EXT Extended
DD Direct-Direct
IX+D Indexed-Direct

REL Relative
IX Indexed, No Offset
IX1 Indexed, 8-Bit Offset
IX2 Indexed, 16-Bit Offset
IMD Immediate-Direct
DIX+ Direct-Indexed

SP1 Stack Pointer, 8-Bit Offset
SP2 Stack Pointer, 16-Bit Offset
IX+ Indexed, No Offset with Post Increment
IX1+ Indexed, 1-Byte Offset with Post Increment

Low Byte of Opcode in Hexadecimal

MSB LSB	0
0	BRSET0 3 DIR

High Byte of Opcode in Hexadecimal
Cycles
Opcode Mnemonic
Number of Bytes / Addressing Mode

*Pre-byte for stack pointer indexed instructions

7.5.1 Crystal Amplifier Input Pin (OSC1)

OSC1 pin is an input to the crystal oscillator amplifier. Schmitt trigger and glitch filter are implemented on this pin to improve EMC performance. See [Section 24. Electrical Specifications](#) for detail specification of the glitch filter.

7.5.2 Crystal Amplifier Output Pin (OSC2)

OSC2 pin is the output of the crystal oscillator inverting amplifier.

7.5.3 Oscillator Enable Signal (SIMOSCEN)

The SIMOSCEN signal from the system integration module (SIM) enables/disables the x-tal oscillator circuit.

7.5.4 Internal RC Clock (ICLK)

The ICLK clock is the output from the internal RC oscillator. This clock drives the SIM and COP modules.

7.5.5 CGM Oscillator Clock (CGMXCLK)

The CGMXCLK clock is the output from the x-tal oscillator. This clock drives to CGM, real time clock module, analog-to-digital converter, liquid crystal display driver module, and other MCU sub-systems.

7.5.6 CGM Reference Clock (CGMRCLK)

This is buffered signal of CGMXCLK, it is used by the CGM as the phase-locked-loop (PLL) reference clock.

7.6 Low Power Modes

The WAIT and STOP instructions put the MCU in low-power consumption standby modes.

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9.2 Introduction

This section describes the system integration module (SIM). Together with the CPU, the SIM controls all MCU activities. A block diagram of the SIM is shown in [Figure 9-1](#). [Table 9-1](#) is a summary of the SIM input/output (I/O) registers. The SIM is a system state controller that coordinates CPU and exception timing. The SIM is responsible for:

- Bus clock generation and control for CPU and peripherals:
 - Stop/wait/reset/break entry and recovery
 - Internal clock control
- Master reset control, including power-on reset (POR) and COP timeout
- Interrupt control:
 - Acknowledge timing
 - Arbitration control timing
 - Vector address generation
- CPU enable/disable timing
- Modular architecture expandable to 128 interrupt sources

[Table 9-1](#) shows the internal signal names used in this section.

System Integration Module (SIM)

Addr.	Register Name	Bit 7	6	5	4	3	2	1	Bit 0	
\$FE00	SIM Break Status Register (SBSR)	Read:	R	R	R	R	R	SBSW	R	
		Write:						Note		
		Reset:	0							
Note: Writing a 0 clears SBSW.										
\$FE01	SIM Reset Status Register (SRSR)	Read:	POR	PIN	COP	ILOP	ILAD	0	LVI	0
		Write:								
		POR:	1	0	0	0	0	0	0	0
\$FE03	SIM Break Flag Control Register (SBFCR)	Read:	BCFE	R	R	R	R	R	R	
		Write:								
		Reset:	0							
\$FE04	Interrupt Status Register 1 (INT1)	Read:	IF6	IF5	IF4	IF3	IF2	IF1	0	0
		Write:	R	R	R	R	R	R	R	R
		Reset:	0	0	0	0	0	0	0	0
\$FE05	Interrupt Status Register 2 (INT2)	Read:	IF14	IF13	IF12	IF11	IF10	IF9	IF8	IF7
		Write:	R	R	R	R	R	R	R	R
		Reset:	0	0	0	0	0	0	0	0
\$FE06	Interrupt Status Register 3 (INT3)	Read:	0	0	0	0	IF18	IF17	IF16	IF15
		Write:	R	R	R	R	R	R	R	R
		Reset:	0	0	0	0	0	0	0	0
= Unimplemented R = Reserved										

Figure 9-2. SIM I/O Register Summary

9.3 SIM Bus Clock Control and Generation

The bus clock generator provides system clock signals for the CPU and peripherals on the MCU. The system clocks are generated from an incoming clock, CGMOUT, as shown in [Figure 9-3](#). This clock can come from either the oscillator module or from the on-chip PLL. (See [Section 8. Clock Generator Module \(CGM\)](#).)

9.6.1.1 Hardware Interrupts

A hardware interrupt does not stop the current instruction. Processing of a hardware interrupt begins after completion of the current instruction. When the current instruction is complete, the SIM checks all pending hardware interrupts. If interrupts are not masked (I bit clear in the condition code register) and if the corresponding interrupt enable bit is set, the SIM proceeds with interrupt processing; otherwise, the next instruction is fetched and executed.

If more than one interrupt is pending at the end of an instruction execution, the highest priority interrupt is serviced first. **Figure 9-11** demonstrates what happens when two interrupts are pending. If an interrupt is pending upon exit from the original interrupt service routine, the pending interrupt is serviced before the LDA instruction is executed.

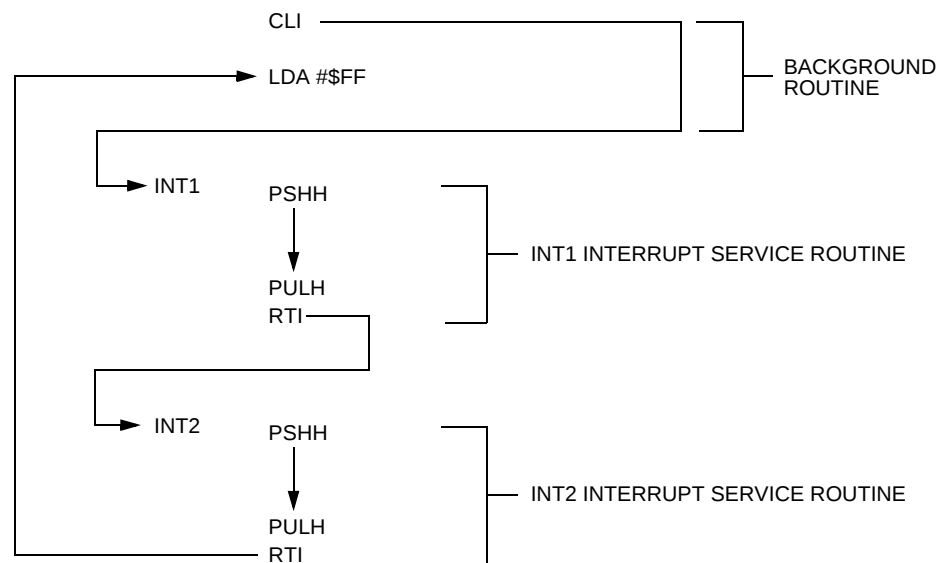


Figure 9-11. Interrupt Recognition Example

The LDA opcode is prefetched by both the INT1 and INT2 RTI instructions. However, in the case of the INT1 RTI prefetch, this is a redundant operation.

NOTE: *To maintain compatibility with the M6805 Family, the H register is not pushed on the stack during interrupt entry. If the interrupt service routine modifies the H register or uses the indexed addressing mode, software should save the H register and then restore it prior to exiting the routine.*

Table 10-5. WRITE (Write Memory) Command

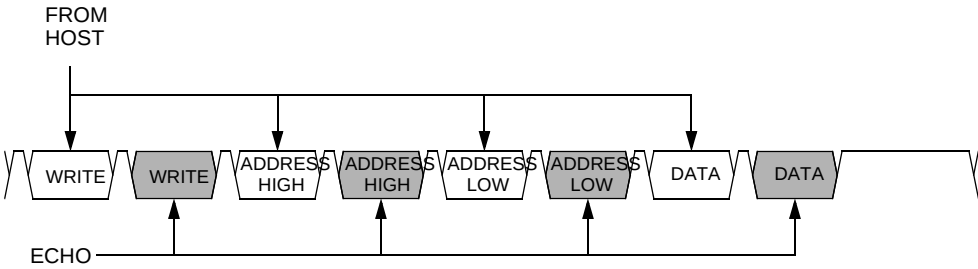
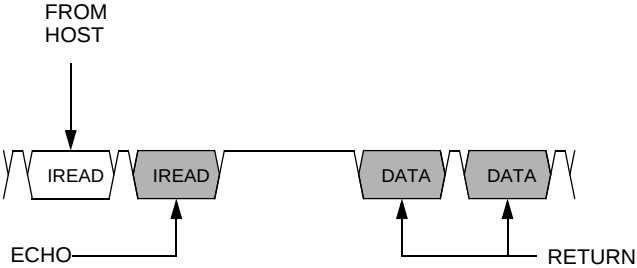
Description	Write byte to memory
Operand	2-byte address in high-byte:low-byte order; low byte followed by data byte
Data Returned	None
Opcode	\$49
Command Sequence 	

Table 10-6. IREAD (Indexed Read) Command

Description	Read next 2 bytes in memory from last address accessed
Operand	2-byte address in high byte:low byte order
Data Returned	Returns contents of next two addresses
Opcode	\$1A
Command Sequence 	

Upon power-on reset, if the received bytes of the security code do not match the data at locations \$FFF6–\$FFFD, the host fails to bypass the security feature. The MCU remains in monitor mode, but reading a FLASH location returns an invalid value and trying to execute code from FLASH causes an illegal address reset. After receiving the eight security bytes from the host, the MCU transmits a break character, signifying that it is ready to receive a command.

NOTE: *The MCU does not transmit a break character until after the host sends the eight security bits.*

To determine whether the security code entered is correct, check to see if bit 6 of RAM address \$40 is set. If it is, then the correct security code has been entered and FLASH can be accessed.

If the security sequence fails, the device should be reset by a power-on reset and brought up in monitor mode to attempt another entry. After failing the security sequence, the FLASH module can also be mass erased by executing an erase routine that was downloaded into internal RAM. The mass erase operation clears the security code locations so that all eight security bytes become \$FF (blank).

10.6 ROM-Resident Routines

Eight routines stored in the monitor ROM area (thus ROM-resident) are provided for FLASH memory manipulation. Six of the eight routines are intended to simplify FLASH program, erase, and load operations. The other two routines are intended to simplify the use of the FLASH memory as EEPROM. [Table 10-10](#) shows a summary of the ROM-resident routines.

Table 10-10. Summary of ROM-Resident Routines

Routine Name	Routine Description	Call Address	Stack Used (bytes)
PRGRNGE	Program a range of locations	\$FC06	14
ERARNGE	Erase a page or the entire array	\$FCBE	9
LDRNGE	Loads data from a range of locations	\$FF30	9
MON_PRGRNGE	Program a range of locations in monitor mode	\$FF28	16
MON_ERARNGE	Erase a page or the entire array in monitor mode	\$FF2C	11
MON_LDRNGE	Loads data from a range of locations in monitor mode	\$FF24	11
EE_WRITE	Emulated EEPROM write. Data size ranges from 2 to 15 bytes at a time.	\$FC00	17
EE_READ	Emulated EEPROM read. Data size ranges from 2 to 15 bytes at a time.	\$FC03	15

The routines are designed to be called as stand-alone subroutines in the user program or monitor mode. The parameters that are passed to a routine are in the form of a contiguous data block, stored in RAM. The index register (H:X) is loaded with the address of the first byte of the data block (acting as a pointer), and the subroutine is called (JSR). Using the start address as a pointer, multiple data blocks can be used, any area of RAM be used. A data block has the control and data bytes in a defined order, as shown in [Figure 10-9](#).

During the software execution, it does not consume any dedicated RAM location, the run-time heap will extend the system stack, all other RAM location will not be affected.

NOTE: *The EE_READ routine is unable to check for incorrect data blocks, such as the FLASH page boundary address and data size. It is the responsibility of the user to ensure the starting address indicated in the data block is at the FLASH page boundary and the data size is 2 to 15. If the FLASH page is programmed with a data array with a different size, the EE_READ call will be ignored.*

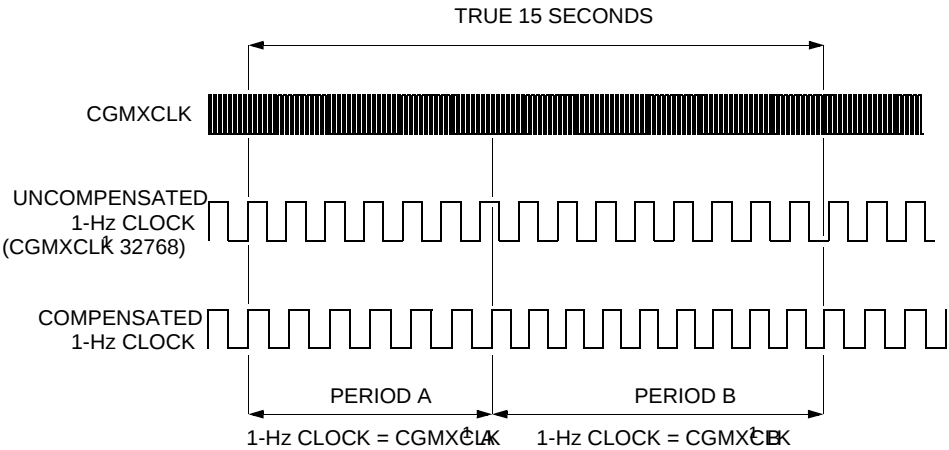


Figure 12-4. 1-Hz Clock Compensation

12.8 RTC Register and Bit Write Protection

A write-protect mechanism is implemented to prevent accidental writes to the RTC clock registers, calendar registers, and other control bits. The protected RTC registers and bits are listed in [Table 12-3](#).

Table 12-3. Write-Protected RTC Registers and Bits

Register	Bit
RTC Control Register 1	CAL
	AUTOCAL
	OUTF[1:0]
RTC Control Register 2	COMEN
	RTCE
Second Register	(All Bits)
Minute Register	(All Bits)
Hour Register	(All Bits)
Day-Of-Week Register	(All Bits)
Day Register	(All Bits)
Month Register	(All Bits)
Year Register	(All Bits)

The sub-module consists of two main blocks: the transmit encoder and the receive decoder. When transmitting data, the SCI data stream is encoded by the infrared sub-module. For every "0" bit, a narrow "low" pulse is transmitted; no pulse is transmitted for "1" bits. When receiving data, the infrared pulses should be detected using an infrared photo diode for conversion to CMOS voltage levels before connecting to the RxD pin for the infrared decoder. The SCI data stream is reconstructed by stretching the "0" pulses.

13.6.1 Infrared Transmit Encoder

The infrared transmit encoder converts the "0" bits in the serial data stream from the SCI module to narrow "low" pulses, to the TxD pin. The narrow pulse is sent with a duration of $1/32$, $1/16$, or $3/16$ of a data bit width. When two consecutive zeros are sent, the two consecutive narrow pulses will be separated by a time equal to a data bit width.

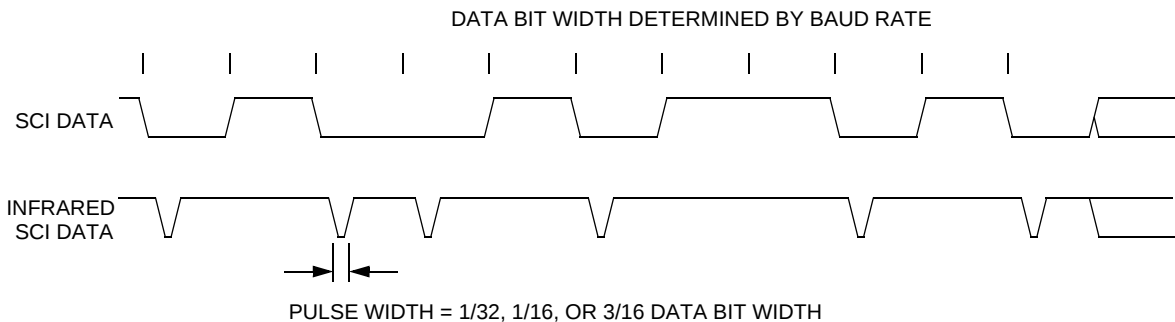


Figure 13-4. Infrared SCI Data Example

13.6.2 Infrared Receive Decoder

The infrared receive decoder converts low narrow pulses from the RxD pin to standard SCI data bits. The reference clock, SCI_R16XCLK, clocks a four bit internal counter which counts from 0 to 15. An incoming pulse starts the internal counter and a "0" is sent out to the IR_RxD output. Subsequent incoming pulses are ignored when the counter count is between 0 and 7; IR_RxD remains "0". Once the counter passes 7, an incoming pulse will reset the counter; IR_RxD remains "0". When the counter reaches 15, the IR_RxD output returns to "1", the counter stops and waits for further pulses. A pulse is interpreted as jitter if it arrives shortly after the counter reaches 15; IR_RxD remains "1".

slave. This happens because $\overline{SS}$ at logic 0 indicates the start of the transmission (MISO driven out with the value of MSB) for $CPHA = 0$. When $CPHA = 1$, a slave can be selected and then later unselected with no transmission occurring. Therefore, MODF does not occur since a transmission was never begun.

In a slave SPI ($MSTR = 0$), the MODF bit generates an SPI receiver/error CPU interrupt request if the ERRIE bit is set. The MODF bit does not clear the SPE bit or reset the SPI in any way. Software can abort the SPI transmission by clearing the SPE bit of the slave.

NOTE: A logic 1 voltage on the $\overline{SS}$ pin of a slave SPI puts the MISO pin in a high impedance state. Also, the slave SPI ignores all incoming SPSCCK clocks, even if it was already in the middle of a transmission.

To clear the MODF flag, read the SPSCR with the MODF bit set and then write to the SPCR register. This entire clearing mechanism must occur with no MODF condition existing or else the flag is not cleared.

14.9 Interrupts

Four SPI status flags can be enabled to generate CPU interrupt requests.

Table 14-2. SPI Interrupts

Flag	Request
SPTE Transmitter empty	SPI transmitter CPU interrupt request (DMAS = 0, SPTIE = 1, SPE = 1)
SPRF Receiver full	SPI receiver CPU interrupt request (DMAS = 0, SPRIE = 1)
OVRF Overflow	SPI receiver/error interrupt request (ERRIE = 1)
MODF Mode fault	SPI receiver/error interrupt request (ERRIE = 1)

Addr.	Register Name	Bit 7	6	5	4	3	2	1	Bit 0
\$003C	ADC Status and Control Register (ADSCR)	Read: COCO	AIEN	ADCO	ADCH4	ADCH3	ADCH2	ADCH1	ADCH0
		Write:							
		Reset: 0							
\$003D	ADC Data Register High (ADRH)	Read: ADx	ADx	ADx	ADx	ADx	ADx	ADx	ADx
		Write: R							
		Reset: 0							
\$003E	ADC Data Register Low (ADRL)	Read: ADx	ADx	ADx	ADx	ADx	ADx	ADx	ADx
		Write: R							
		Reset: 0							
\$003F	ADC Clock Register (ADCLK)	Read: ADIV2	ADIV1	ADIV0	ADICLK	MODE1	MODE0	0	0
		Write:							R
		Reset: 0							

= Unimplemented R = Reserved

Figure 16-1. ADC I/O Register Summary

16.4 Functional Descriptions

The ADC provides six pins for sampling external sources at pins PTA4/ADC0–PTA7/ADC3 and PTB6/ADC4–PTB7/ADC5. An analog multiplexer allows the single ADC converter to select one of ten ADC channels as ADC voltage in (V_{ADIN}). V_{ADIN} is converted by the successive approximation register-based analog-to-digital converter. When the conversion is completed, ADC places the result in the ADC data register, high and low byte (ADRH and ADRL), and sets a flag or generates an interrupt.

Figure 16-2 shows the structure of the ADC module.

16.4.1 ADC Port I/O Pins

PTA4–PTA7 and PTB6–PTB7 are general-purpose I/O pins that are shared with the ADC channels. The channel select bits, ADCH[4:0], define which ADC channel/port pin will be used as the input signal. The ADC overrides the port I/O logic by forcing that pin as input to the ADC. The remaining ADC channels/port pins are controlled by the port I/O

17.9.3 LCD Data Registers (LDAT1-LDAT17)

The seventeen (17) LCD data registers enable and disable the drive to the corresponding LCD segments.

Addr.	Register Name	Bit 7	6	5	4	3	2	1	Bit 0
\$0052	LCD Data Register 1 (LDAT1)	Read: F1B3	F1B2	F1B1	F1B0	F0B3	F0B2	F0B1	F0B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0053	LCD Data Register 2 (LDAT2)	Read: F3B3	F3B2	F3B1	F3B0	F2B3	F2B2	F2B1	F2B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0054	LCD Data Register 3 (LDAT3)	Read: F5B3	F5B2	F5B1	F5B0	F4B3	F4B2	F4B1	F4B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0055	LCD Data Register 4 (LDAT4)	Read: F7B3	F7B2	F7B1	F7B0	F6B3	F6B2	F6B1	F6B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0056	LCD Data Register 5 (LDAT5)	Read: F9B3	F9B2	F9B1	F9B0	F8B3	F8B2	F8B1	F8B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0057	LCD Data Register 6 (LDAT6)	Read: F11B3	F11B2	F11B1	F11B0	F10B3	F10B2	F10B1	F10B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0058	LCD Data Register 7 (LDAT7)	Read: F13B3	F13B2	F13B1	F13B0	F12B3	F12B2	F12B1	F12B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$0059	LCD Data Register 8 (LDAT8)	Read: F15B3	F15B2	F15B1	F15B0	F14B3	F14B2	F14B1	F14B0
		Write:							
		Reset:	U	U	U	U	U	U	U
\$005A	LCD Data Register 9 (LDAT9)	Read: F17B3	F17B2	F17B1	F17B0	F16B3	F16B2	F16B1	F16B0
		Write:							
		Reset:	U	U	U	U	U	U	U

U = Unaffected  = Unimplemented

Figure 17-18. LCD Data Registers 1–17 (LDAT1–LDAT17)

