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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Discontinued at Digi-Key
Core Processor	ARM® Cortex®-M4F
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I <sup>2</sup> C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, LCD, POR, PWM, WDT
Number of I/O	56
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.98V ~ 3.8V
Data Converters	A/D 8x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm32wg840f128-qfn64">https://www.e-xfl.com/product-detail/silicon-labs/efm32wg840f128-qfn64</a>

process and close to automatic transfers. Automatic recognition of slave addresses is provided in all energy modes.

### 2.1.11 Universal Synchronous/Asynchronous Receiver/Transmitter (USART)

The Universal Synchronous Asynchronous serial Receiver and Transmitter (USART) is a very flexible serial I/O module. It supports full duplex asynchronous UART communication as well as RS-485, SPI, MicroWire and 3-wire. It can also interface with ISO7816 SmartCards, IrDA and I2S devices.

### 2.1.12 Pre-Programmed UART Bootloader

The bootloader presented in application note AN0003 is pre-programmed in the device at factory. Auto-baud and destructive write are supported. The autobaud feature, interface and commands are described further in the application note.

### 2.1.13 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUART<sup>™</sup>, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

### 2.1.14 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output. TIMER0 also includes a Dead-Time Insertion module suitable for motor control applications.

### 2.1.15 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

### 2.1.16 Backup Real Time Counter (BURTC)

The Backup Real Time Counter (BURTC) contains a 32-bit counter and is clocked either by a 32.768 kHz crystal oscillator, a 32.768 kHz RC oscillator or a 1 kHz ULFRCO. The BURTC is available in all Energy Modes and it can also run in backup mode, making it operational even if the main power should drain out.

### 2.1.17 Low Energy Timer (LETIMER)

The unique LETIMER<sup>™</sup>, the Low Energy Timer, is a 16-bit timer that is available in energy mode EM2 in addition to EM1 and EM0. Because of this, it can be used for timing and output generation when most of the device is powered down, allowing simple tasks to be performed while the power consumption of the system is kept at an absolute minimum. The LETIMER can be used to output a variety of waveforms with minimal software intervention. It is also connected to the Real Time Counter (RTC), and can be configured to start counting on compare matches from the RTC.

### 2.1.18 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn\_S0IN pin as external clock source. The module may operate in energy mode EM0 – EM3.

### 2.1.19 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs can either be one of the selectable internal references or from external pins. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.20 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

### 2.1.21 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to one million samples per second. The integrated input mux can select inputs from 8 external pins and 6 internal signals.

### 2.1.22 Digital to Analog Converter (DAC)

The Digital to Analog Converter (DAC) can convert a digital value to an analog output voltage. The DAC is fully differential rail-to-rail, with 12-bit resolution. It has two single ended output buffers which can be combined into one differential output. The DAC may be used for a number of different applications such as sensor interfaces or sound output.

### 2.1.23 Operational Amplifier (OPAMP)

The EFM32WG840 features 3 Operational Amplifiers. The Operational Amplifier is a versatile general purpose amplifier with rail-to-rail differential input and rail-to-rail single ended output. The input can be set to pin, DAC or OPAMP, whereas the output can be pin, OPAMP or ADC. The current is programmable and the OPAMP has various internal configurations such as unity gain, programmable gain using internal resistors etc.

### 2.1.24 Low Energy Sensor Interface (LESENSE)

The Low Energy Sensor Interface (LESENSE<sup>™</sup>), is a highly configurable sensor interface with support for up to 16 individually configurable sensors. By controlling the analog comparators and DAC, LESENSE is capable of supporting a wide range of sensors and measurement schemes, and can for instance measure LC sensors, resistive sensors and capacitive sensors. LESENSE also includes a programmable FSM which enables simple processing of measurement results without CPU intervention. LESENSE is available in energy mode EM2, in addition to EM0 and EM1, making it ideal for sensor monitoring in applications with a strict energy budget.

### 2.1.25 Backup Power Domain

The backup power domain is a separate power domain containing a Backup Real Time Counter, BURTC, and a set of retention registers, available in all energy modes. This power domain can be configured to automatically change power source to a backup battery when the main power drains out. The backup power domain enables the EFM32WG840 to keep track of time and retain data, even if the main power source should drain out.

### 2.1.26 Advanced Encryption Standard Accelerator (AES)

The AES accelerator performs AES encryption and decryption with 128-bit or 256-bit keys. Encrypting or decrypting one 128-bit data block takes 52 HFCORECLK cycles with 128-bit keys and 75 HFCORECLK

cycles with 256-bit keys. The AES module is an AHB slave which enables efficient access to the data and key registers. All write accesses to the AES module must be 32-bit operations, i.e. 8- or 16-bit operations are not supported.

### 2.1.27 General Purpose Input/Output (GPIO)

In the EFM32WG840, there are 56 General Purpose Input/Output (GPIO) pins, which are divided into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 16 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

### 2.1.28 Liquid Crystal Display Driver (LCD)

The LCD driver is capable of driving a segmented LCD display with up to 8x20 segments. A voltage boost function enables it to provide the LCD display with higher voltage than the supply voltage for the device. In addition, an animation feature can run custom animations on the LCD display without any CPU intervention. The LCD driver can also remain active even in Energy Mode 2 and provides a Frame Counter interrupt that can wake-up the device on a regular basis for updating data.

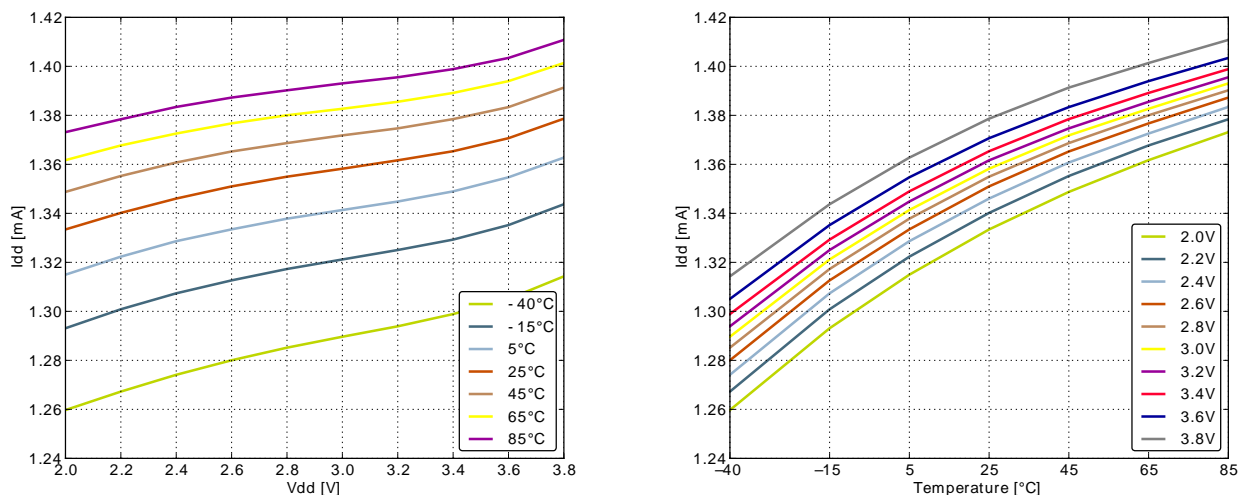
## 2.2 Configuration Summary

The features of the EFM32WG840 is a subset of the feature set described in the EFM32WG Reference Manual. Table 2.1 (p. 7) describes device specific implementation of the features.

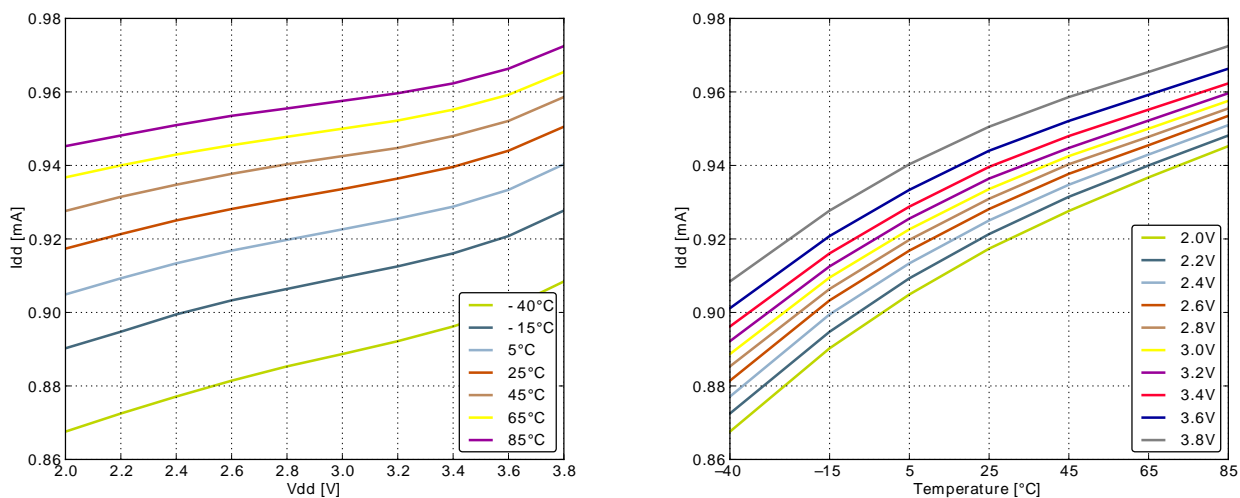
**Table 2.1. Configuration Summary**

Module	Configuration	Pin Connections
Cortex-M4	Full configuration	NA
DBG	Full configuration	DBG_SWCLK, DBG_SWDIO, DBG_SWO
MSC	Full configuration	NA
DMA	Full configuration	NA
RMU	Full configuration	NA
EMU	Full configuration	NA
CMU	Full configuration	CMU_OUT0, CMU_OUT1
WDOG	Full configuration	NA
PRS	Full configuration	NA
I2C0	Full configuration	I2C0_SDA, I2C0_SCL
I2C1	Full configuration	I2C1_SDA, I2C1_SCL
USART0	Full configuration with IrDA	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	Full configuration with I2S	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	Full configuration with I2S	US2_TX, US2_RX, US2_CLK, US2_CS
LEUART0	Full configuration	LEU0_TX, LEU0_RX
LEUART1	Full configuration	LEU1_TX, LEU1_RX

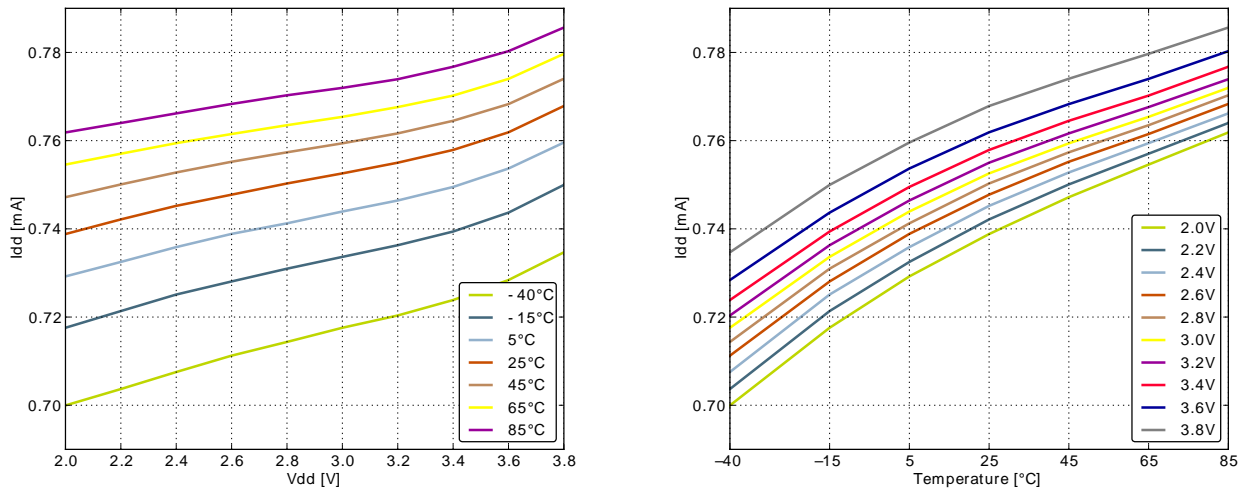
**Figure 3.3. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 21MHz**



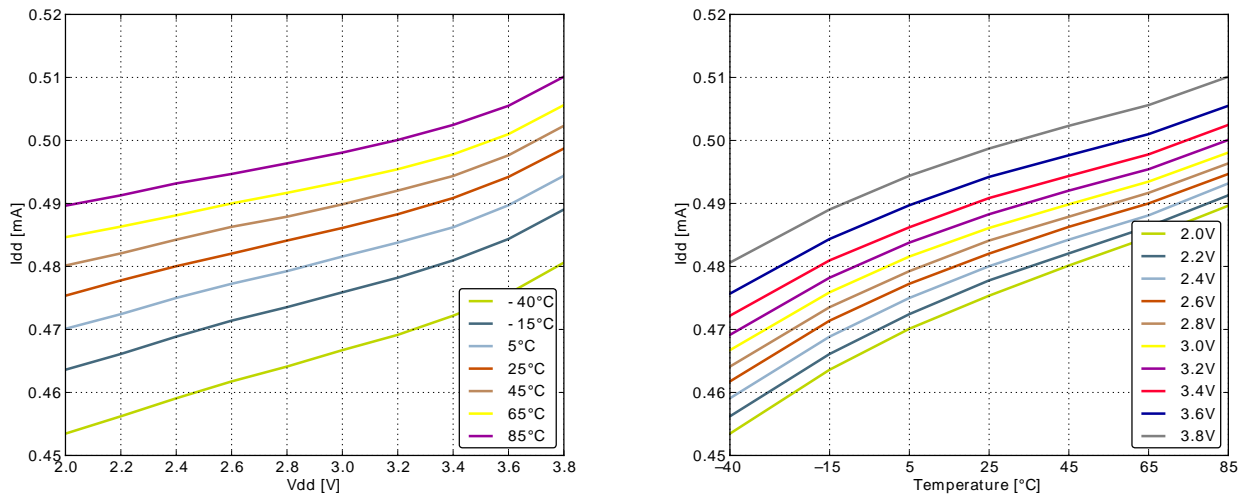
**Figure 3.4. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 14MHz**



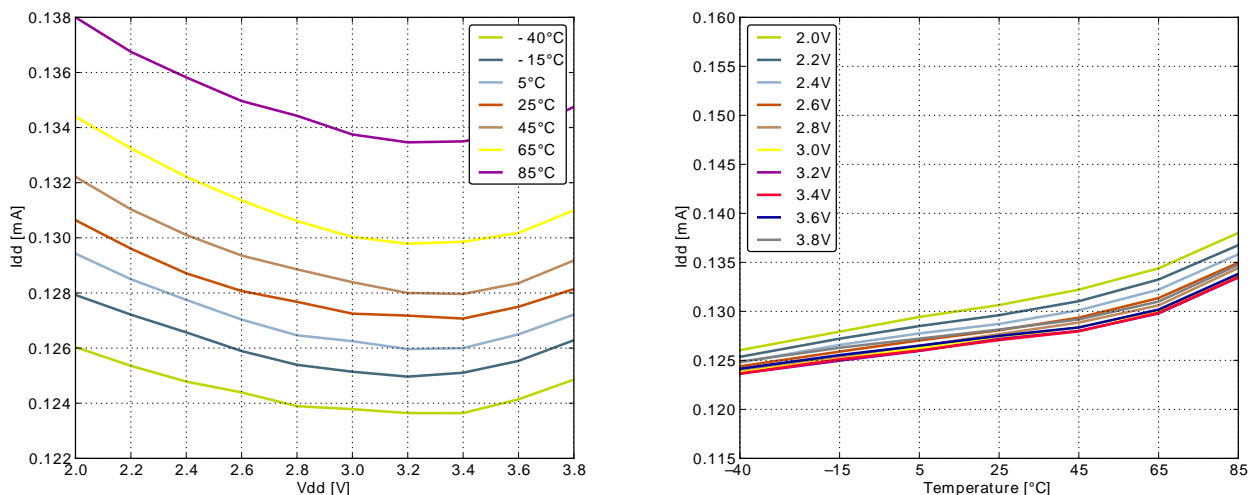
**Figure 3.5. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 11MHz**



**Figure 3.6. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 6.6MHz**

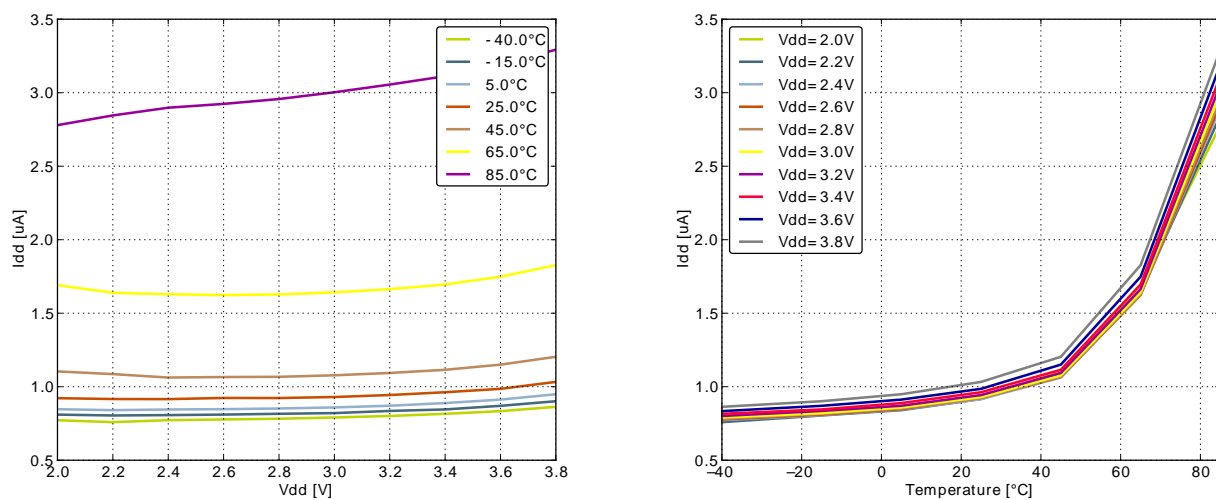


**Figure 3.7. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 1.2MHz**



### 3.4.2 EM2 Current Consumption

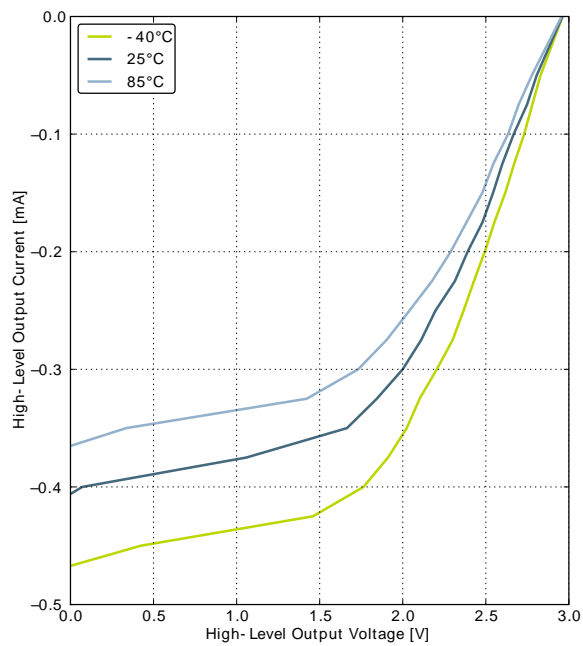
**Figure 3.8. EM2 current consumption. RTC<sup>1</sup> prescaled to 1kHz, 32.768 kHz LFRCO.**



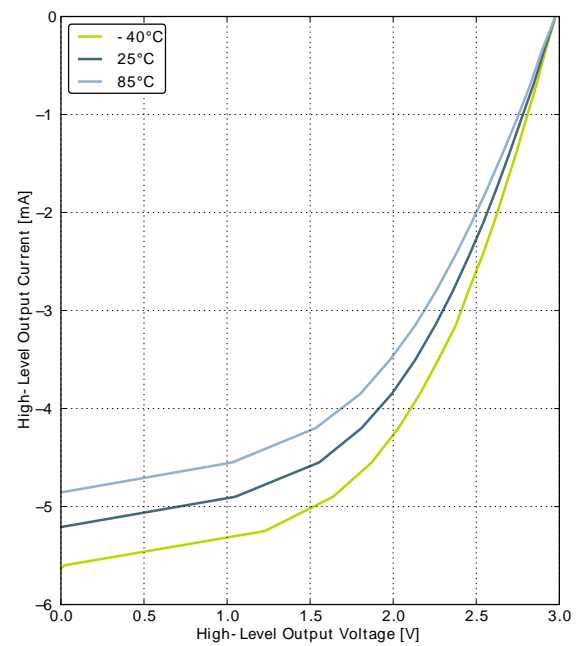
<sup>1</sup>Using backup RTC.

Symbol	Parameter	Condition	Min	Typ	Max	Unit
		Sinking 20 mA, $V_{DD}=3.0$ V, GPIO_Px_CTRL DRIVEMODE = HIGH			$0.25V_{DD}$	V
$I_{IOLEAK}$	Input leakage current	High Impedance IO connected to GROUND or Vdd		$\pm 0.1$	$\pm 100$	nA
$R_{PU}$	I/O pin pull-up resistor			40		kOhm
$R_{PD}$	I/O pin pull-down resistor			40		kOhm
$R_{IOESD}$	Internal ESD series resistor			200		Ohm
$t_{IOGLITCH}$	Pulse width of pulses to be removed by the glitch suppression filter		10		50	ns
$t_{IOOF}$	Output fall time	GPIO_Px_CTRL DRIVEMODE = LOWEST and load capacitance $C_L=12.5-25$ pF.	$20+0.1C_L$		250	ns
		GPIO_Px_CTRL DRIVEMODE = LOW and load capacitance $C_L=350-600$ pF	$20+0.1C_L$		250	ns
$V_{IOHYST}$	I/O pin hysteresis ( $V_{IOTHR+}$ - $V_{IOTHR-}$ )	$V_{DD} = 1.98 - 3.8$ V	$0.10V_{DD}$			V

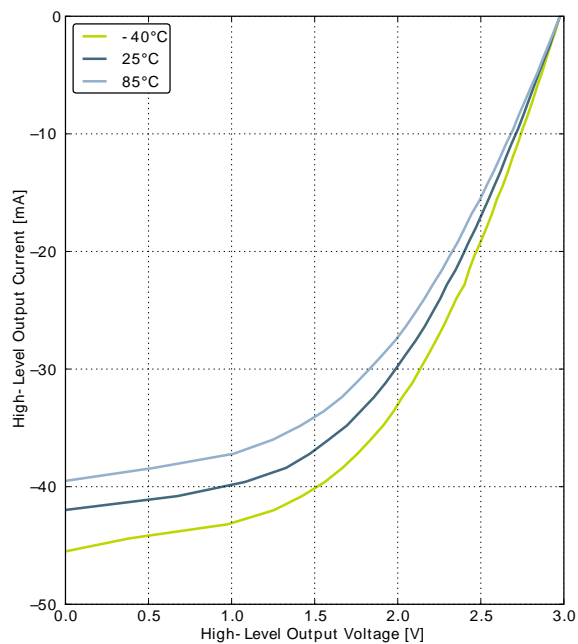


**Figure 3.14. Typical High-Level Output Current, 3V Supply Voltage**

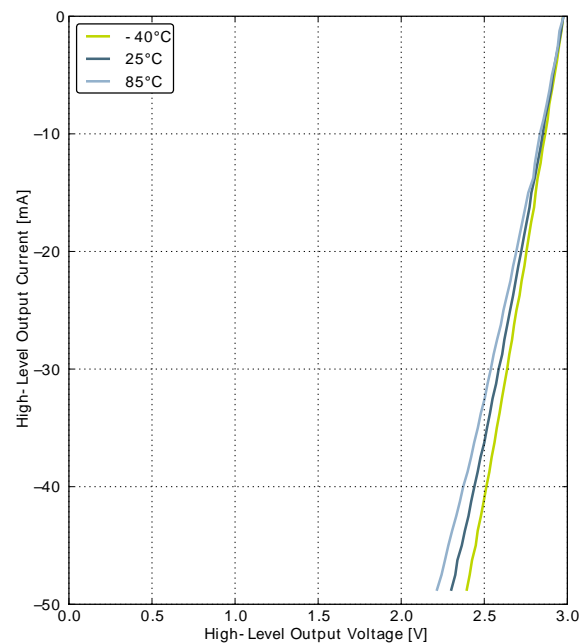
GPIO\_Px\_CTRL DRIVEMODE = LOWEST



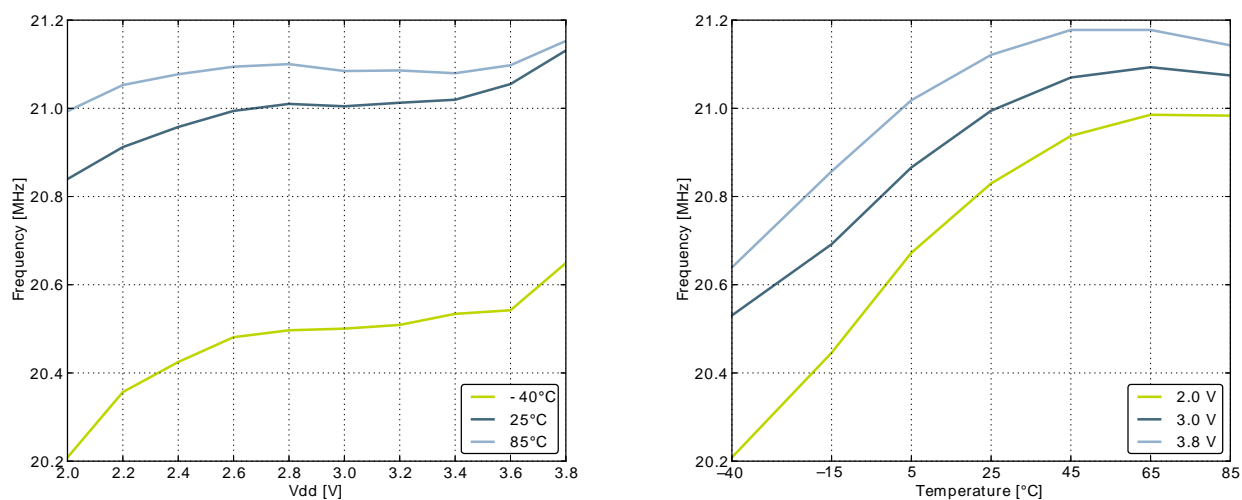
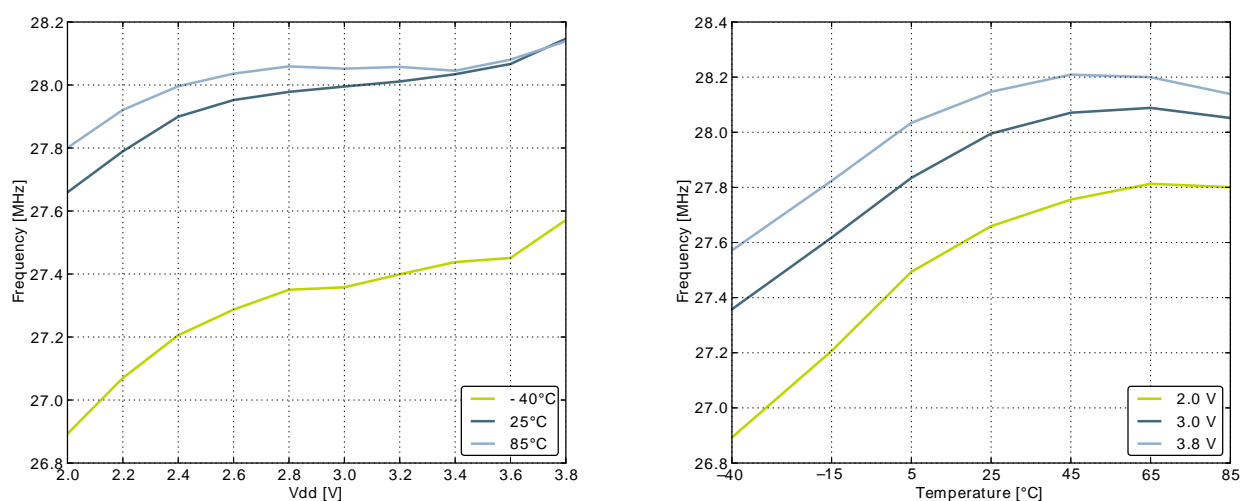
GPIO\_Px\_CTRL DRIVEMODE = LOW



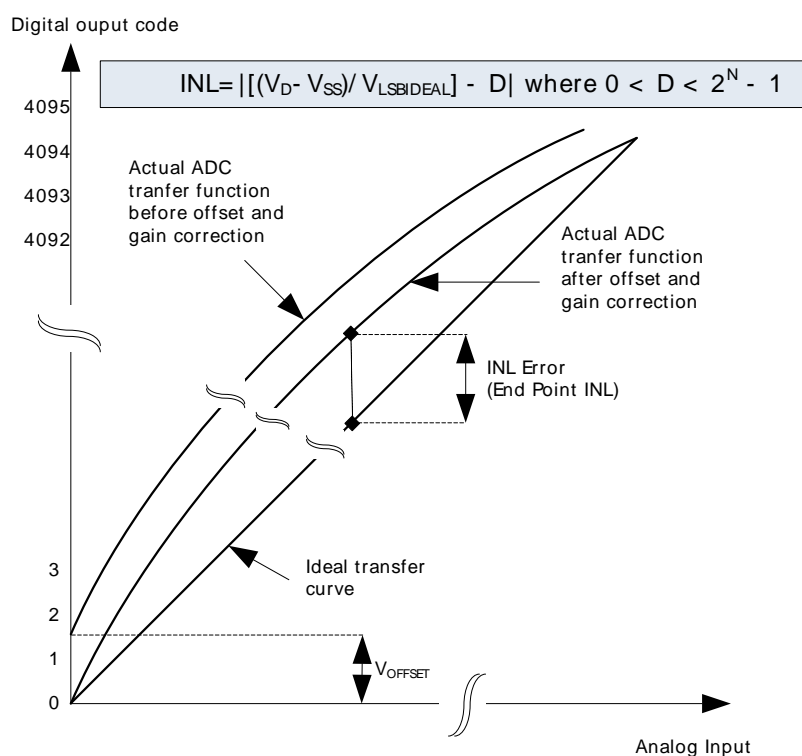
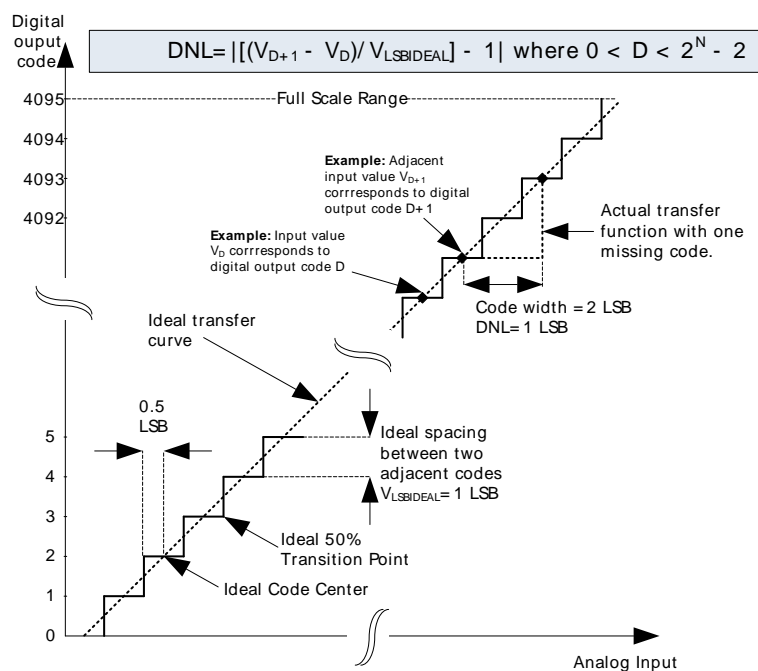
GPIO\_Px\_CTRL DRIVEMODE = STANDARD



GPIO\_Px\_CTRL DRIVEMODE = HIGH

**Figure 3.22. Calibrated HFRCO 21 MHz Band Frequency vs Supply Voltage and Temperature****Figure 3.23. Calibrated HFRCO 28 MHz Band Frequency vs Supply Voltage and Temperature**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
		1 MSamples/s, 12 bit, differential, internal 2.5V reference		64		dB
		1 MSamples/s, 12 bit, differential, 5V reference		54		dB
		1 MSamples/s, 12 bit, differential, $V_{DD}$ reference		66		dB
		1 MSamples/s, 12 bit, differential, $2xV_{DD}$ reference		68		dB
		200 kSamples/s, 12 bit, single ended, internal 1.25V reference		61		dB
		200 kSamples/s, 12 bit, single ended, internal 2.5V reference		65		dB
		200 kSamples/s, 12 bit, single ended, $V_{DD}$ reference		66		dB
		200 kSamples/s, 12 bit, differential, internal 1.25V reference		63		dB
		200 kSamples/s, 12 bit, differential, internal 2.5V reference		66		dB
		200 kSamples/s, 12 bit, differential, 5V reference		66		dB
		200 kSamples/s, 12 bit, differential, $V_{DD}$ reference	62	66		dB
		200 kSamples/s, 12 bit, differential, $2xV_{DD}$ reference		69		dB
SFDR <sub>ADC</sub>	Spurious-Free Dynamic Range (SFDR)	1 MSamples/s, 12 bit, single ended, internal 1.25V reference		64		dBc
		1 MSamples/s, 12 bit, single ended, internal 2.5V reference		76		dBc
		1 MSamples/s, 12 bit, single ended, $V_{DD}$ reference		73		dBc
		1 MSamples/s, 12 bit, differential, internal 1.25V reference		66		dBc
		1 MSamples/s, 12 bit, differential, internal 2.5V reference		77		dBc
		1 MSamples/s, 12 bit, differential, $V_{DD}$ reference		76		dBc
		1 MSamples/s, 12 bit, differential, $2xV_{DD}$ reference		75		dBc
		1 MSamples/s, 12 bit, differential, 5V reference		69		dBc
		200 kSamples/s, 12 bit, single ended, internal 1.25V reference		75		dBc
		200 kSamples/s, 12 bit, single ended, internal 2.5V reference		75		dBc
		200 kSamples/s, 12 bit, single ended, $V_{DD}$ reference		76		dBc

**Figure 3.24. Integral Non-Linearity (INL)****Figure 3.25. Differential Non-Linearity (DNL)**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
		(OPA2)BIASPROG=0x0, (OPA2)HALFBIAS=0x1, Unity Gain		13	25	μA
G <sub>OL</sub>	Open Loop Gain	(OPA2)BIASPROG=0xF, (OPA2)HALFBIAS=0x0		101		dB
		(OPA2)BIASPROG=0x7, (OPA2)HALFBIAS=0x1		98		dB
		(OPA2)BIASPROG=0x0, (OPA2)HALFBIAS=0x1		91		dB
GBW <sub>OPAMP</sub>	Gain Bandwidth Product	(OPA2)BIASPROG=0xF, (OPA2)HALFBIAS=0x0		6.1		MHz
		(OPA2)BIASPROG=0x7, (OPA2)HALFBIAS=0x1		1.8		MHz
		(OPA2)BIASPROG=0x0, (OPA2)HALFBIAS=0x1		0.25		MHz
PM <sub>OPAMP</sub>	Phase Margin	(OPA2)BIASPROG=0xF, (OPA2)HALFBIAS=0x0, C <sub>L</sub> =75 pF		64		°
		(OPA2)BIASPROG=0x7, (OPA2)HALFBIAS=0x1, C <sub>L</sub> =75 pF		58		°
		(OPA2)BIASPROG=0x0, (OPA2)HALFBIAS=0x1, C <sub>L</sub> =75 pF		58		°
R <sub>INPUT</sub>	Input Resistance			100		Mohm
R <sub>LOAD</sub>	Load Resistance		200			Ohm
I <sub>LOAD_DC</sub>	DC Load Current				11	mA
V <sub>INPUT</sub>	Input Voltage	OPAxHCMDIS=0	V <sub>SS</sub>		V <sub>DD</sub>	V
		OPAxHCMDIS=1	V <sub>SS</sub>		V <sub>DD</sub> -1.2	V
V <sub>OUTPUT</sub>	Output Voltage		V <sub>SS</sub>		V <sub>DD</sub>	V
V <sub>OFFSET</sub>	Input Offset Voltage	Unity Gain, V <sub>SS</sub> <V <sub>in</sub> <V <sub>DD</sub> , OPAxHCMDIS=0	-13	0	11	mV
		Unity Gain, V <sub>SS</sub> <V <sub>in</sub> <V <sub>DD</sub> -1.2, OPAxHCMDIS=1		1		mV
V <sub>OFFSET_DRIFT</sub>	Input Offset Voltage Drift				0.02	mV/°C
SR <sub>OPAMP</sub>	Slew Rate	(OPA2)BIASPROG=0xF, (OPA2)HALFBIAS=0x0		3.2		V/μs
		(OPA2)BIASPROG=0x7, (OPA2)HALFBIAS=0x1		0.8		V/μs
		(OPA2)BIASPROG=0x0, (OPA2)HALFBIAS=0x1		0.1		V/μs
N <sub>OPAMP</sub>	Voltage Noise	V <sub>out</sub> =1V, RESSEL=0, 0.1 Hz<f<10 kHz, OPAx- HCMDIS=0		101		μV <sub>RMS</sub>
		V <sub>out</sub> =1V, RESSEL=0, 0.1 Hz<f<10 kHz, OPAx- HCMDIS=1		141		μV <sub>RMS</sub>

## 3.15 LCD

**Table 3.20. LCD**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$f_{LCDFR}$	Frame rate		30		200	Hz
$NUM_{SEG}$	Number of segments supported			20x8		seg
$V_{LCD}$	LCD supply voltage range	Internal boost circuit enabled	2.0		3.8	V
$I_{LCD}$	Steady state current consumption.	Display disconnected, static mode, framerate 32 Hz, all segments on.		250		nA
		Display disconnected, quadruplex mode, framerate 32 Hz, all segments on, bias mode to ONETHIRD in LCD_DISPCTRL register.		550		nA
$I_{LCDBOOST}$	Steady state Current contribution of internal boost.	Internal voltage boost off		0		$\mu$ A
		Internal voltage boost on, boosting from 2.2 V to 3.0 V.		8.4		$\mu$ A
$V_{BOOST}$	Boost Voltage	VBLEV of LCD_DISPCTRL register to LEVEL0		3.02		V
		VBLEV of LCD_DISPCTRL register to LEVEL1		3.15		V
		VBLEV of LCD_DISPCTRL register to LEVEL2		3.28		V
		VBLEV of LCD_DISPCTRL register to LEVEL3		3.41		V
		VBLEV of LCD_DISPCTRL register to LEVEL4		3.54		V
		VBLEV of LCD_DISPCTRL register to LEVEL5		3.67		V
		VBLEV of LCD_DISPCTRL register to LEVEL6		3.73		V
		VBLEV of LCD_DISPCTRL register to LEVEL7		3.74		V

The total LCD current is given by Equation 3.3 (p. 50) .  $I_{LCDBOOST}$  is zero if internal boost is off.

### Total LCD Current Based on Operational Mode and Internal Boost

$$I_{LCDTOTAL} = I_{LCD} + I_{LCDBOOST} \quad (3.3)$$

Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{SCLK\_hi}}^{12}$	SCLK high period	$3 * t_{\text{HFPER-CLK}}$			ns
$t_{\text{SCLK\_lo}}^{12}$	SCLK low period	$3 * t_{\text{HFPER-CLK}}$			ns
$t_{\text{CS\_ACT\_MI}}^{12}$	CS active to MISO	5.00		35.00	ns
$t_{\text{CS\_DIS\_MI}}^{12}$	CS disable to MISO	5.00		35.00	ns
$t_{\text{SU\_MO}}^{12}$	MOSI setup time	5.00			ns
$t_{\text{H\_MO}}^{12}$	MOSI hold time	$2 + 2 * t_{\text{HF- PERCLK}}$			ns
$t_{\text{SCLK\_MI}}^{12}$	SCLK to MISO	$-264 + t_{\text{HF- PERCLK}}$		$-234 + 2 * t_{\text{HFPERCLK}}$	ns

<sup>1</sup>Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0)

<sup>2</sup>Measurement done at 10% and 90% of  $V_{\text{DD}}$  (figure shows 50% of  $V_{\text{DD}}$ )

## 3.18 Digital Peripherals

**Table 3.28. Digital Peripherals**

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$I_{\text{USART}}$	USART current	USART idle current, clock enabled		4.0		$\mu\text{A}/\text{MHz}$
$I_{\text{UART}}$	UART current	UART idle current, clock enabled		3.8		$\mu\text{A}/\text{MHz}$
$I_{\text{LEUART}}$	LEUART current	LEUART idle current, clock enabled		194.0		nA
$I_{\text{I2C}}$	I2C current	I2C idle current, clock enabled		7.6		$\mu\text{A}/\text{MHz}$
$I_{\text{TIMER}}$	TIMER current	TIMER_0 idle current, clock enabled		6.5		$\mu\text{A}/\text{MHz}$
$I_{\text{LETIMER}}$	LETIMER current	LETIMER idle current, clock enabled		85.8		nA
$I_{\text{PCNT}}$	PCNT current	PCNT idle current, clock enabled		91.4		nA
$I_{\text{RTC}}$	RTC current	RTC idle current, clock enabled		54.6		nA
$I_{\text{LCD}}$	LCD current	LCD idle current, clock enabled		72.7		nA
$I_{\text{AES}}$	AES current	AES idle current, clock enabled		1.8		$\mu\text{A}/\text{MHz}$
$I_{\text{GPIO}}$	GPIO current	GPIO idle current, clock enabled		3.4		$\mu\text{A}/\text{MHz}$
$I_{\text{PRS}}$	PRS current	PRS idle current		3.9		$\mu\text{A}/\text{MHz}$
$I_{\text{DMA}}$	DMA current	Clock enable		10.9		$\mu\text{A}/\text{MHz}$

## 4 Pinout and Package

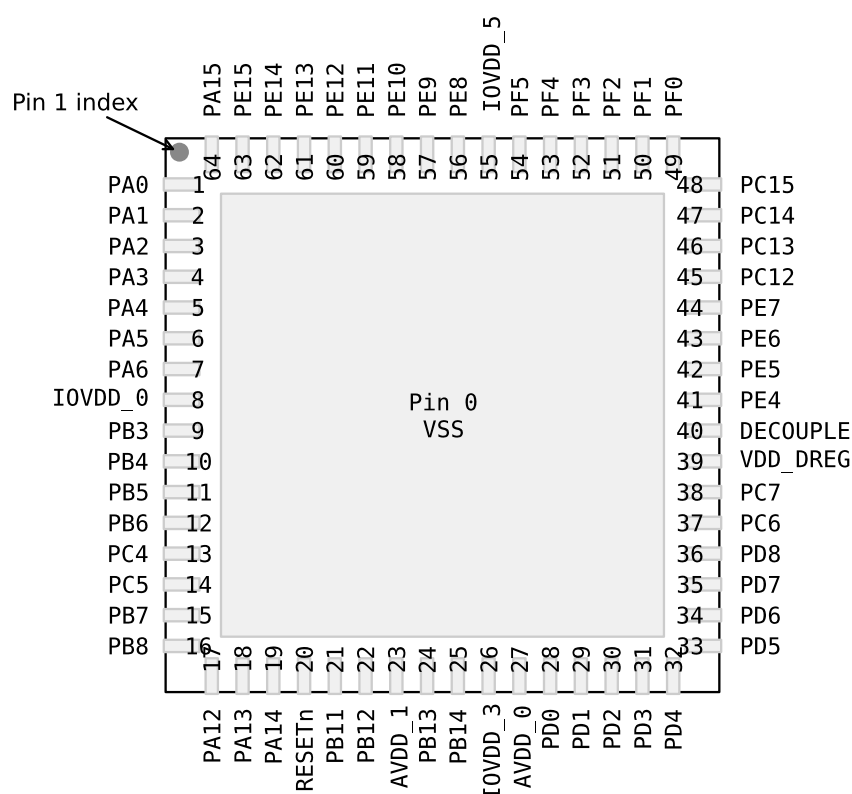
### Note

Please refer to the application note "AN0002 EFM32 Hardware Design Considerations" for guidelines on designing Printed Circuit Boards (PCB's) for the EFM32WG840.

### 4.1 Pinout

The *EFM32WG840* pinout is shown in Figure 4.1 (p. 55) and Table 4.1 (p. 55). Alternate locations are denoted by "#" followed by the location number (Multiple locations on the same pin are split with "/"). Alternate locations can be configured in the LOCATION bitfield in the \*\_ROUTE register in the module in question.

**Figure 4.1. EFM32WG840 Pinout (top view, not to scale)**



**Table 4.1. Device Pinout**

QFN64 Pin# and Name		Pin Alternate Functionality / Description			
Pin #	Pin Name	Analog	Timers	Communication	Other
0	VSS	Ground			
1	PA0	LCD_SEG13	TIM0_CC0 #0/1/4	LEU0_RX #4 I2C0_SDA #0	PRS_CH0 #0 GPIO_EM4WU0
2	PA1	LCD_SEG14	TIM0_CC1 #0/1	I2C0_SCL #0	CMU_CLK1 #0 PRS_CH1 #0



Alternate	LOCATION							
Functionality	0	1	2	3	4	5	6	Description
LCD_SEG15	PA2							LCD segment line 15. Segments 12, 13, 14 and 15 are controlled by SEGEN3.
LCD_SEG16	PA3							LCD segment line 16. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG17	PA4							LCD segment line 17. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG18	PA5							LCD segment line 18. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG19	PA6							LCD segment line 19. Segments 16, 17, 18 and 19 are controlled by SEGEN4.
LCD_SEG20/ LCD_COM4	PB3							LCD segment line 20. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 4
LCD_SEG21/ LCD_COM5	PB4							LCD segment line 21. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 5
LCD_SEG22/ LCD_COM6	PB5							LCD segment line 22. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 6
LCD_SEG23/ LCD_COM7	PB6							LCD segment line 23. Segments 20, 21, 22 and 23 are controlled by SEGEN5. This pin may also be used as LCD COM line 7
LES_ALTEX0	PD6							LESENSE alternate exite output 0.
LES_ALTEX1	PD7							LESENSE alternate exite output 1.
LES_ALTEX2	PA3							LESENSE alternate exite output 2.
LES_ALTEX3	PA4							LESENSE alternate exite output 3.
LES_ALTEX4	PA5							LESENSE alternate exite output 4.
LES_ALTEX5	PE11							LESENSE alternate exite output 5.
LES_ALTEX6	PE12							LESENSE alternate exite output 6.
LES_ALTEX7	PE13							LESENSE alternate exite output 7.
LES_CH4	PC4							LESENSE channel 4.
LES_CH5	PC5							LESENSE channel 5.
LES_CH6	PC6							LESENSE channel 6.
LES_CH7	PC7							LESENSE channel 7.
LES_CH12	PC12							LESENSE channel 12.
LES_CH13	PC13							LESENSE channel 13.
LES_CH14	PC14							LESENSE channel 14.
LES_CH15	PC15							LESENSE channel 15.
LETIM0_OUT0	PD6	PB11	PF0	PC4				Low Energy Timer LETIM0, output channel 0.
LETIM0_OUT1	PD7	PB12	PF1	PC5				Low Energy Timer LETIM0, output channel 1.
LEU0_RX	PD5	PB14	PE15	PF1	PA0			LEUART0 Receive input.
LEU0_TX	PD4	PB13	PE14	PF0	PF2			LEUART0 Transmit output. Also used as receive input in half duplex communication.
LEU1_RX	PC7	PA6						LEUART1 Receive input.
LEU1_TX	PC6	PA5						LEUART1 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	PB8							Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	PB7							Low Frequency Crystal (typically 32.768 kHz) positive pin.

Removed UART mentioned incorrectly in the QFN64 parts.

Updated Environmental information.

Updated trademark, disclaimer and contact information.

Other minor corrections.

## **7.4 Revision 1.20**

June 28th, 2013

Updated power requirements in the Power Management section.

Removed minimum load capacitance figure and table. Added reference to application note.

Other minor corrections.

## **7.5 Revision 1.10**

May 6th, 2013

Updated current consumption table and figures in Electrical characteristics section.

Other minor corrections.

## **7.6 Revision 1.00**

September 11th, 2012

Updated the HFRCO 1 MHz band typical value to 1.2 MHz.

Updated the HFRCO 7 MHz band typical value to 6.6 MHz.

Other minor corrections.

## **7.7 Revision 0.95**

May 3rd, 2012

Updated EM2/EM3 current consumption at 85°C.

## **7.8 Revision 0.90**

February 27th, 2012

Initial preliminary release.

## A Disclaimer and Trademarks

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