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Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LVD, POR, PWM, WDT
Number of I/O	86
Program Memory Size	384KB (384K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z32f38412als

Revision History

Each instance in this document's revision history reflects a change from its previous edition. For more details, refer to the corresponding page(s) or appropriate links furnished in the table below.

Date	Revision Level	Description	Page
Jun 2017	03	Updated part numbers to include the Cortex M identifier.	All
Mar 2016	02	Update to reflect new part, revision B (0x0002); Added timing information for most of the peripherals; corrected typos.	All
Dec 2015	01	Original issue.	

MCCR4 Miscellaneous Clock Control Register 4

The Miscellaneous Clock Control Register 4 is the alternative ADC and NMI Debounce Clock Control register.

0x4000_00A8

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
							ADCCSEL																								
0	0	0	0	0			000									0	0	0	0	0											
							RW																								

26	ADCCSEL	ADC clock source select bit
24		0xx RING OSC 1MHz
		100 MCLK (bus clock)
		101 INT OSC 20MHz
		110 External Main OSC
		111 PLL Clock
23	ADCCDIV	ADC Clock N divider
16		
10	NMIDCSEL	Debounce Clock for NMI source select bit
8		0xx RING OSC 1MHz
		100 MCLK (bus clock)
		101 INT OSC 20MHz
		110 External Main OSC
		111 PLL Clock
7	NMIDDIV	NMI Debounce Clock N divider
0		

8. Internal SRAM

Overview

The Z32F3841 MCU implements zero-wait on the chip's SRAM. The size of the SRAM is 16 KB. The SRAM base address is 0x2000_0000.

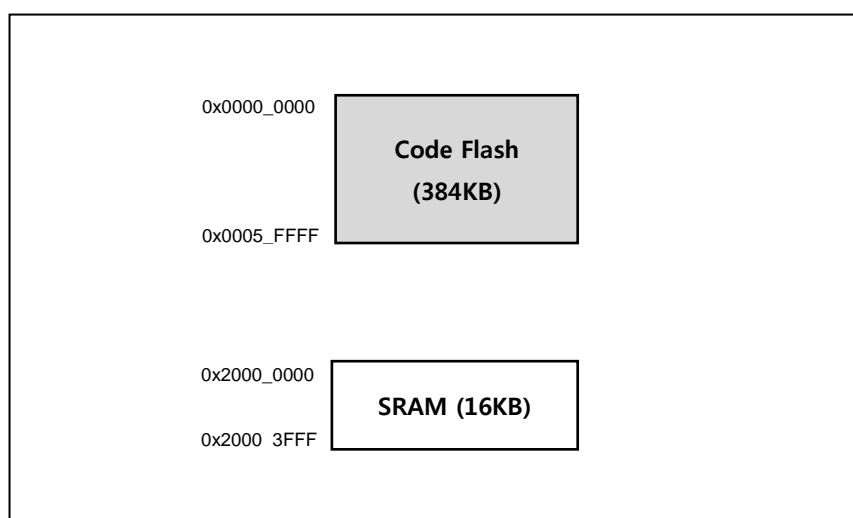


Figure 8.1. SRAM Block Diagram

Registers

The base address of the watchdog timer is 0x4000_0200 and the register map is listed in Table 10.1. Initial watchdog time-out period is set to 2000-milliseconds.

Table 10.1. Watchdog Timer Register Map

Name	Offset	R/W	Description	Reset
WDT.LR	0x0000	W	WDT Load register	0x00000000
WDT.CNT	0x0004	R	WDT Current counter register	0x0000FFFF
WDT.CON	0x0008	R/W	WDT Control register	0x0000805C

WDT.LR Watchdog Timer Load Register

The Watchdog Timer Load register is used to update the WDT CNT register. To update the WDT CNT register, the WEN bit of WDT CON should be set to 1 and written into the WDT LR register with a target value of WDT CNT.

WDT.LR=0x4000_0200

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
WDTLR																																
0x0000_0000																																
RW																																
								31	WDTLR								Watchdog timer load value register															
								0	Keeping WEN bit as '1', write WDTLR register will update WDTCNT value with written value																							

WDT.CNT Watchdog Timer Current Counter Register

The Watchdog Timer Current Counter register represents the current count value of the 32-bit down counter. When the counter value reaches 0, the interrupt or reset is awoken.

WDT.CNT=0x4000_0204

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
WDTCNT																																
0x0000_FFFF																																
RW																																
								31	WDTCNT								Watchdog timer current counter register															
								0									32-bit down counter will run from the written value.															

Functional Description

The MCCR3 register must be configured to enable the clock source and divider for the Watch Dog Timer (WDT) to run. To prevent the WDT from resetting or interrupting, load a new value into the WDTLR register before the WDTCNT reaches 0.

The watchdog timer count is enabled by setting WDTEN (WDT.CON[4]) to 1. When the watchdog timer is enabled, the down counter starts counting from the load value. If WDTRE (WDT.CON[6]) is set to 1, WDT reset is asserted when the WDT counter value reaches 0 (underflow event) from the WDTLR value. Before the WDT counter goes down to 0, the software can write a certain value to the WDTLR register to reload the WDT counter.

Timing Diagram

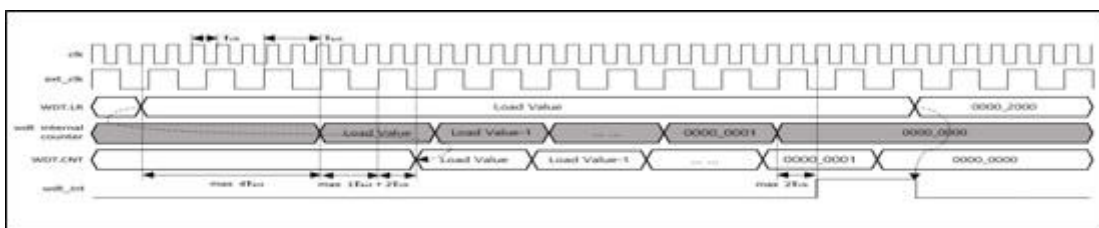


Figure 10.2. Timing Diagram in Interrupt Mode Operation when WDT Clock is External Clock

In WDT interrupt mode, after the WDT underflow occurs, a certain count value is reloaded to prevent the next WDT interrupt in a short time period. This reloading action can only be activated when the watchdog timer counter is set to Interrupt mode (set WDTIE of WDT.CON). It takes up to 5 cycles from the load value to the CNT value. The WDT interrupt signal and CNT value data might be delayed by a maximum of 2 system bus clocks in synchronous logic.

Prescale Table

The WDT includes a 32-bit down counter with programmable prescaler to define different time-out intervals.

The clock sources of the watchdog timer can include the peripheral clock (PCLK) or one of 3 external clock sources. An external clock source can be enabled by CKSEL (WDT.CON[3]) set to '1' and external clock source chosen in MCCR3 register of the System Control Unit block.

To make the WDT counter base clock, users can control the 3-bit prescaler WPRS [2:0] in the WDT.CON register and the maximum prescaled value is "clock source frequency/256". The prescaled WDT counter clock frequency values are listed in Table 10.2.

Selectable clock source (40 kHz ~ 16 MHz) and the time out interval when 1 count

$$\text{Time out period} = \{(\text{Load Value}) * (1/\text{pre-scaled WDT counter clock frequency}) + \max 5T_{\text{ext}}\} + \max 4T_{\text{clk}}$$

*Time out period (time out period from load Value to interrupt set '1')

PWM Timer Output

Figure 11.5 shows the timing diagram in PWM output mode. The Tn.GRB value decides the PWM pulse period. An additional comparison point is provided with the Tn.GRA register value which defines the pulse width of PWM output.

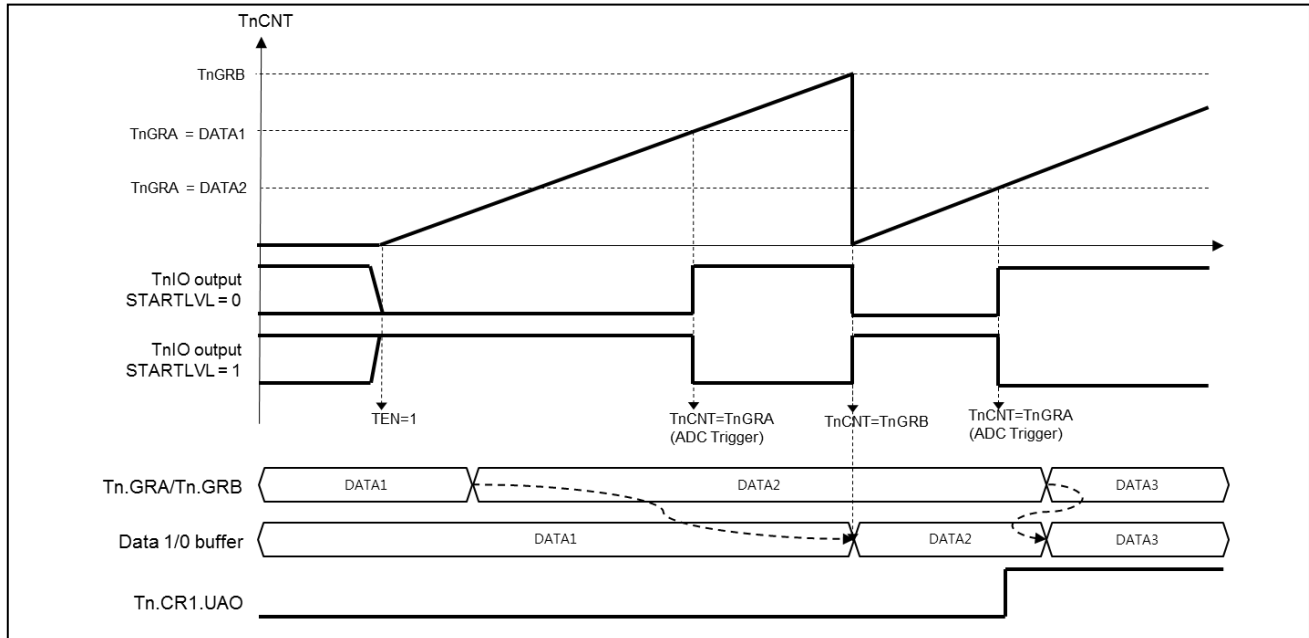


Figure 11.5. PWM Output Operation

The period of PWM pulse can be calculated as shown in the following equation:

The period = TMCLK Period * Tn.GRB value

Match A interrupt time = TMCLK Period * Tn.GRA value

If Tn.GRB = 0, the timer cannot be started even if TnCR2.TEN is "1" because the period is "0".

The value in Tn.GRA and Tn.GRB is loaded into the internal compare data buffer 0 and 1 when the loading condition occurs. In this periodic mode with TnCR1.UAO = 0, the Tn.CR2.TCLR write operation and the GRB match event will load the compare data buffers.

When TnCR1.UAO is 1, the internal compare data buffer is updated when the Tn.GRA or Tn.GRB data is updated.

The TnIO output signal generates a PWM pulse. The Tn.GRB value defines the output pulse period and the Tn.GRA value defines the pulse width of one shot pulse. The active level of the PWM pulse can be controlled by the Tn.CR1.STARTLVL bit value.

ADC Trigger generation is available at Match A interrupt time.

FRT.MR FRT Mode Register

FRT is a 32-bit up counter. It can be used in power down mode. The SUB OSC clock is directly connected to FRT. The clock is uncontrollable in the SCU block. The FRT Mode Register is an 8-bit register.

FRTMR=0x4000_0600

7	6	5	4	3	2	1	0
			CLKSEL		MCD	OVIE	MIE
0	0	0	00		0	0	0
			RW		RW	RW	RW

3	CLKSEL	FRT counter clock source control
2		0 Internal Oscillator clock divided by 16
		1 External Oscillator clock divided by 16
		2 Sub Oscillator clock
		3 Reserved
1	MCD	Counter Match Clear Disable bit
		0 Counter Match Clear function is enabled. Whenever the counter matches FRT.PER, the counter will be set zero and waiting for MF to be cleared.
		1 Counter Match Clear function is disabled. The counter will keep countering without set zero
1	OVIE	Overflow Interrupt Enable bit
		0 Not effect
		1 Interrupt enabled
0	MIE	Match Interrupt Enable bit
		0 Not effect
		1 Interrupt enabled

FRT.CR FRT Control Register

The FRT Control register is an 8-bit register.

FRTCR=0x4000_3E04

7	6	5	4	3	2	1	0
				CNTREQ	FCLR	FHOLD	FEN
0	0	0	0	0	0	0	0
				RW	WO	R/W	R/W

3	CNTREQ	FRT Counter read request bit
		0 No
		1 Request to read FCNT (cleared when CNTACK(FSR[1]) is high)
2	FCLR	FRT Counter register clear bit
		0 No
		1 Clear the counter
1	FHOLD	FRT Counter register hold bit
		0 No
		1 Hold the counter
0	FEN	FRT enable bit
		0 FRT Disabled
		1 FRT Enabled

FRT.PER FRT Period Match Register

The FRT Period Match register is a 32-bit register.

FRTPER=0x4000_3E08

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
DATA																															
0x0000_0000																															
R/W																															

32	DATA	FRT match data
0		

FRT.CNT FRT Counter Register

The FRT Counter Register is a 32-bit register.

FRTCNT=0x4000_3E0C

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CNT																															
0x0000_0000																															
RO																															

32	CNT	FRT Counter
0		

FRT.SRFRT Status Register

FRT Status Register is an 8-bit register.FRTSR=0x4000_0610

7	6	5	4	3	2	1	0
					RACK	OVIF	MIF
0	0	0	0	0	0	0	0
					WC1	WC1	WC1

2	RACK	Read Counter Acknowledge bit
0		Not ready to read CNT value
1		Ready to read CNT value
1	OVIF	Overflow interrupt flag bit
0		Overflow interrupt did not occur
1		Overflow interrupt occurred
0	MIF	Match interrupt flag bit
0		Match interrupt did not occur.
1		Match Interrupt occurred
		In Counter Match Clear mode, this bit should be cleared for restarting the counter.

Un.RBR Receive Buffer Register

The UART Receive Buffer Register is an 8-bit read-only register.

U0.RBR=0x4000_8000, U1.RBR=0x4000_8100
U2.RBR=0x4000_8200, U3.RBR=0x4000_8300

7	6	5	4	3	2	1	0
RBR[7:0]							
-							
RO							

7	RBR	Receive Buffer Register
0		

Un.THR Transmit Data Hold Register

The UART Transmit Data Hold Register is an 8-bit write-only register.

U0.THR=0x4000_8000, U1.THR=0x4000_8100
U2.THR=0x4000_8200, U3.THR=0x4000_8300

7	6	5	4	3	2	1	0
THR							
-							
WO							

7	THR	Transmit Data Hold Register
0		

Un.LCR UART Line Control Register

The UART Line Control Register is an 8-bit register.

U0.LCR=0x4000_800C, U1.LCR=0x4000_810C

U2.LCR=0x4000_820C, U3.LCR=0x4000_830C

7	6	5	4	3	2	1	0
	BREAK	STICKP	PARITY	PEN	STOPBIT	DLEN	
0	0	0	0	0	0	0	0
	R/W	R/W	R/W	R/W	R/W	R/W	R/W

6	BREAK	When this bit is set, TxD pin will be driven at low state in order to notice the alert to the receiver.
0		Normal transfer mode
1		Break transmit mode
5	STICKP	Force parity and it will be effective when PEN bit is set.
0		Parity stuck is disabled
1		Parity stuck is enabled and parity always the bit of PARITY.
4	PARITY	Parity mode selection bit and stuck parity select bit
0		Odd parity mode
1		Even parity mode
3	PEN	Parity bit transfer enable
0		The parity bit disabled
1		The parity bit enabled
2	STOPBIT	The number of stop bit followed by data bits.
0		1 stop bit
1		1.5 / 2 stop bit
		In case of 5 bit data case, 1.5 stop bit is added. In case of 6,7 or 8 bit data, 2 stop bit is added
1	DLEN	The data length in one transfer word.
0		00 5 bit data
		01 6 bit data
		10 7 bit data
		11 8 bit data

The parity bit is generated according to bits 3,4,5 of the UnLCR register. Table 13.4 shows the variation of parity bit generation.

Table 13.4. Parity Bit Generation

STICKP	PARITY	PEN	Parity
X	X	0	No Parity
0	0	1	Odd Parity
0	1	1	Even Parity
1	0	1	Force parity as "1"
1	1	1	Force parity as "0"

Un.IDTR Inter-frame Delay Time Register

The UART Inter-frame Time Register is an 8-bit register. A dummy delay can be inserted between two continuous transmits.

U0.IDTR=0x4000_8030, U1.IDTR=0x4000_8130

U2.IDTR=0x4000_8230, U3.IDTR=0x4000_8330

7	6	5	4	3	2	1	0
					WAITVAL		
0	0	0	0	0	000		
RW							

2 WAITVAL
0

Wait time is decided by this value

$$\text{Wait Time} = \frac{\text{WAITVAL}}{\text{BAUDRATE}}$$

Functional Description

The UART module is compatible with the 16450 UART. Additionally, dedicated DMA channels and fractional baud rate compensation logic are provided. The UART does not have an internal FIFO block. Therefore, data transfers are established interactively or with DMA support.

Two DMA channels are provided for each UART module – one channel for TX transfer and the other channel for RX transfer. Each channel has a 32-bit memory address register and a 16-bit transfer counter register. Prior to the DMA operation, the DMA memory address register and transfer count register should be configured. For the RX operation, the memory address is the destination memory address and for the TX operation, the memory address is the source memory address.

The transfer counter register stores the number of data transfers. When a single transfer is done, the counter is decremented by 1. When the counter reaches zero, the DMA done flag is delivered to the UART control block. If the interrupt is enabled, this flag generates the interrupt.

Receiver Sampling Timing

The UART operates per the following timing:

If the falling edge is on the receive line, the UART judges it as the start bit. From the start timing, the UART oversamples 16 times of 1-bit and detects the bit value at the 7th sample of 16 samples.

Pin Description

Table 15.1. I²C Interface External Pins

PIN NAME	TYPE	DESCRIPTION
SCL0	I/O	I ² C channel 0 Serial clock bus line (open-drain)
SDA0	I/O	I ² C channel 0 Serial data bus line (open-drain)
SCL1	I/O	I ² C channel 1 Serial clock bus line (open-drain)
SDA1	I/O	I ² C channel 1 Serial data bus line (open-drain)

Registers

The base address of I²C0 is 0x4000_A000 and the base address of I²C1 is 0x4000_A100. The register map is described in Tables 15.2 and 15.3.

Table 15.2. I²C Interface Base Address

Channel	Base address
I²C0	0x4000_A000
I²C1	0x4000_A100

Table 15.3. I²C Register Map

Name	Offset	R/W	Description	Reset
IC0.DR	0xA000	R/W	I ² C0 Data Register	0xFF
IC0.SR	0xA008	R, R/W	I ² C0 Status Register	0x00
IC0.SAR	0xA00C	R/W	I ² C0 Slave Address Register	0x00
IC0.CR	0xA014	R/W	I ² C0 Control Register	0x00
IC0.SCLL	0xA018	R/W	I ² C0 SCL LOW duration Register	0xFFFF
IC0.SCLH	0xA01C	R/W	I ² C0 SCL HIGH duration Register	0xFFFF
IC0.SDH	0xA020	R/W	I ² C0 SDA Hold Register	0x7F
IC1.DR	0xA100	R/W	I ² C1 Data Register	0xFF
IC1.SR	0xA108	R, R/W	I ² C1 Status Register	0x00
IC1.SAR	0xA10C	R/W	I ² C1 Slave Address Register	0x00
IC1.CR	0xA114	R/W	I ² C1 Control Register	0x00
IC1.SCLL	0xA118	R/W	I ² C1 SCL LOW duration Register	0xFFFF
IC1.SCLH	0xA11C	R/W	I ² C1 SCL HIGH duration Register	0xFFFF
IC1.SDH	0xA120	R/W	I ² C1 SDA Hold Register	0x007F

ICn.SCLH I²C SCL HIGH Duration Register

ICnSCLH is a 16-bit read/write register. The SCL HIGH time is set by writing this register in master mode.

IC0.SDLH=0x4000_A01C, IC1.SDLH=0x4000_A11C															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SCLH															
0xFFFF															
RW															

15	SCLH	SCL HIGH duration value. $SCLH = (PCLK * SCLH[15:0]) + 3 PCLKs$
0		Default value is 0xFFFF.

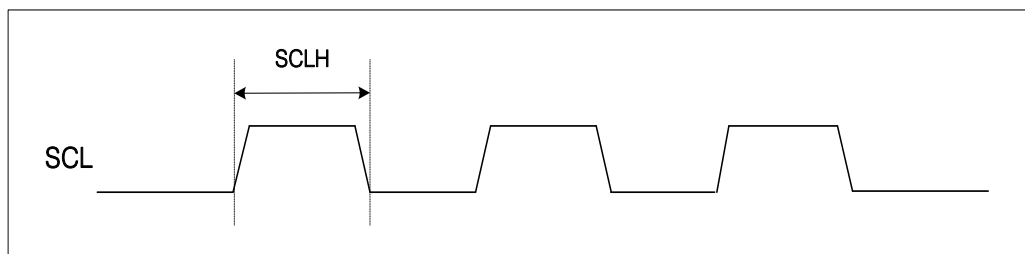


Figure 15.3.SCL HIGH Timing

Slave Transmitter

The slave transmitter shows the flow of the transmitter in Slave mode, as shown in Figure 15.13.

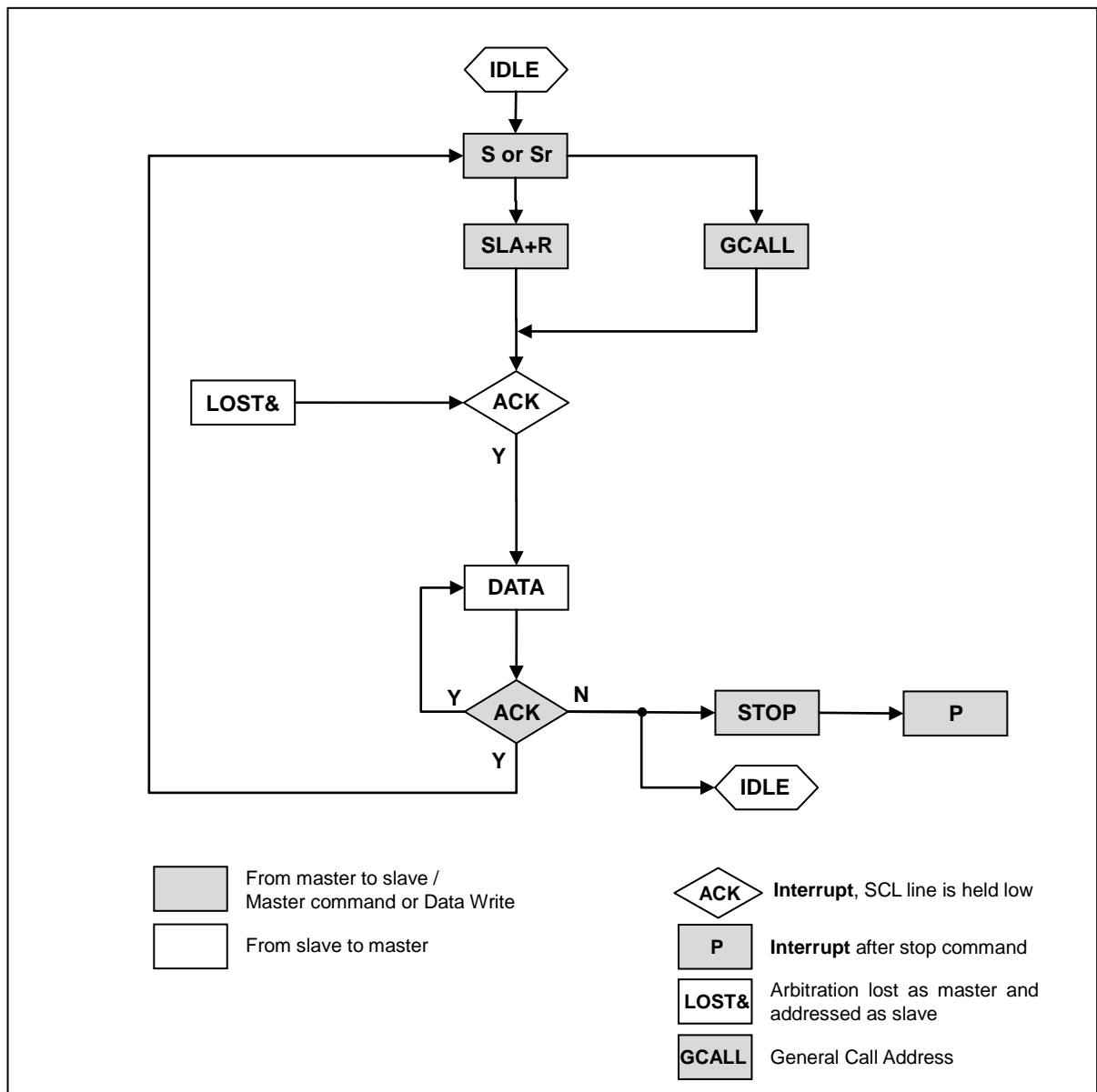


Figure 15.13. Transmitter Flowchart in Slave Mode

Slave Receiver

The slave receiver shows the flow of the receiver in Slave mode, as shown in Figure 15.14.

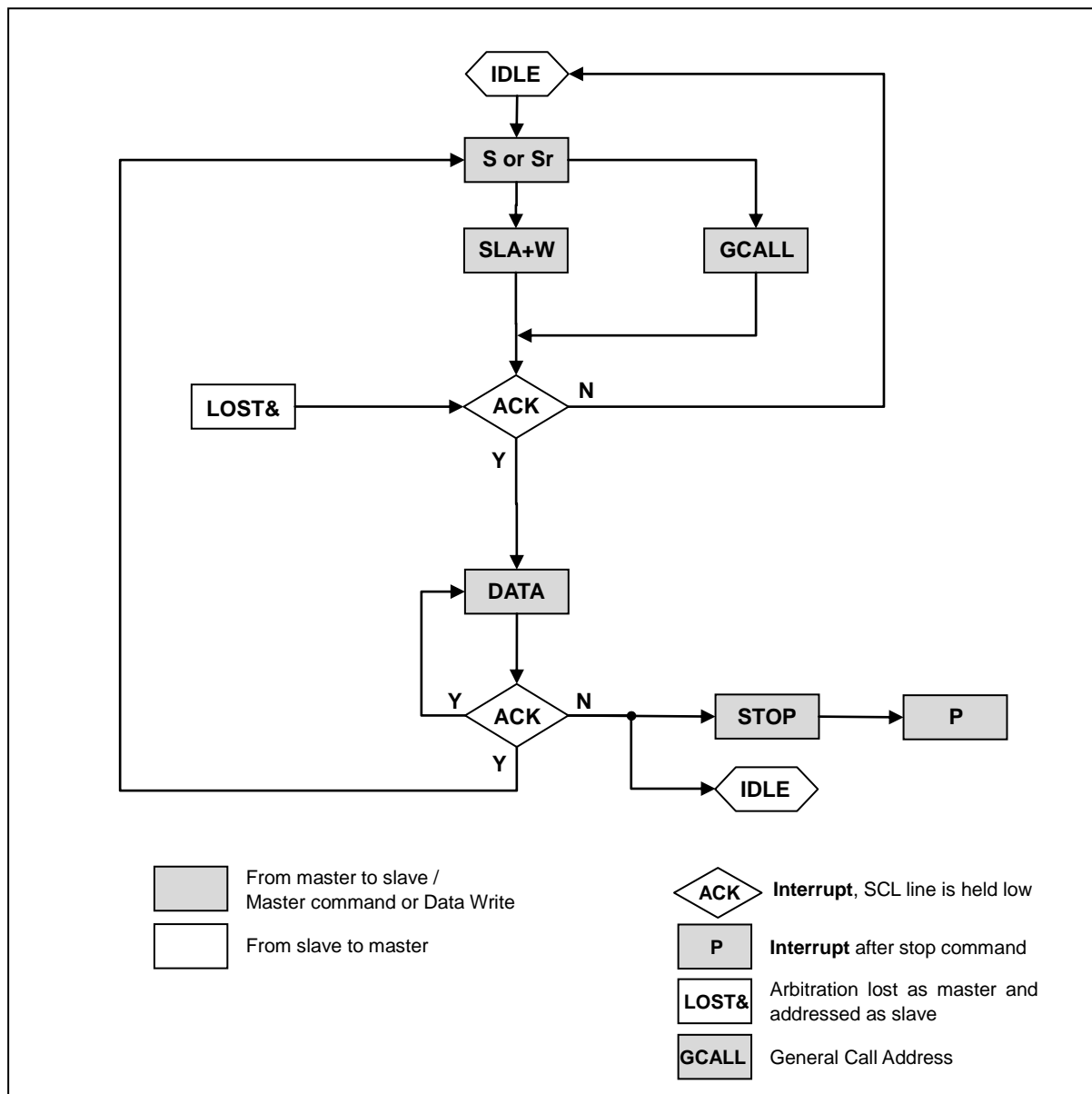


Figure 15.14. Receiver Flowchart in Slave Mode

Table 16.1. MPWM Register Map

PWM Output	Level	NORMAL mode		MOTOR mode
		UP mode	UPDOWN mode	
WH	Default level	LOW	HIGH	LOW
	Active level	HIGH	LOW	HIGH
WL	Default level	LOW	LOW	HIGH
	Active level	HIGH	HIGH	LOW
VH	Default level	LOW	HIGH	LOW
	Active level	HIGH	LOW	HIGH
VL	Default level	LOW	LOW	HIGH
	Active level	HIGH	HIGH	LOW
UH	Default level	LOW	HIGH	LOW
	Active level	HIGH	LOW	HIGH
UL	Default level	LOW	LOW	HIGH
	Active level	HIGH	HIGH	LOW

Figure 16.2 shows the polarity control block. This is an example of WH signal polarity control.

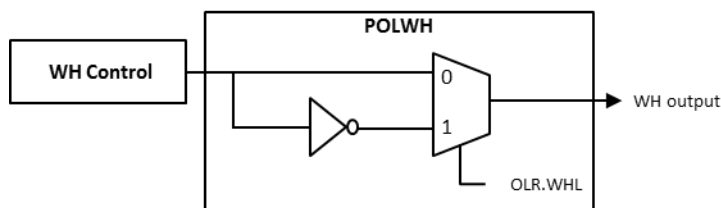


Figure 16.2 Polarity Control Block

MPn.FOR MPWM Force Output Level Register

The PWM force output register is an 8-bit register. The PWM output level can be forced by an abnormal event from an external or user-intended condition. When the forced condition occurs, each PWM output level which is programmed in the FOLR register will be forced.

MP0.FOR=0x4000_4008, MP1.FOR=0x4000_5008,

7	6	5	4	3	2	1	0
		WHFL	VHFL	UHFL	WLFL	VLFL	ULFL
0	0	0	0	0	0	0	0
		RW	RW	RW	RW	RW	RW

5	WHFL	Select WH Output Force Level
0		Output Force Level is 'L'
1		Output Force Level is 'H'
4	VHFL	Select VH Output Force Level
0		Output Force Level is 'L'
1		Output Force Level is 'H'
3	UHFL	Select UH Output Force Level
0		Output Force Level is 'L'

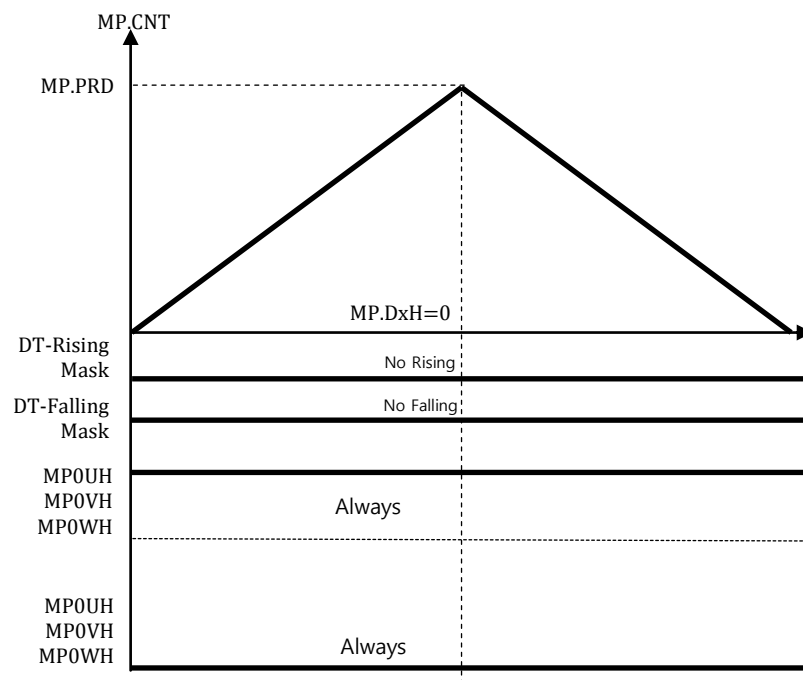


Figure 16.16. H-side Always On ($T_{DUTY} = \text{Period}$: Dead-time Disabled)

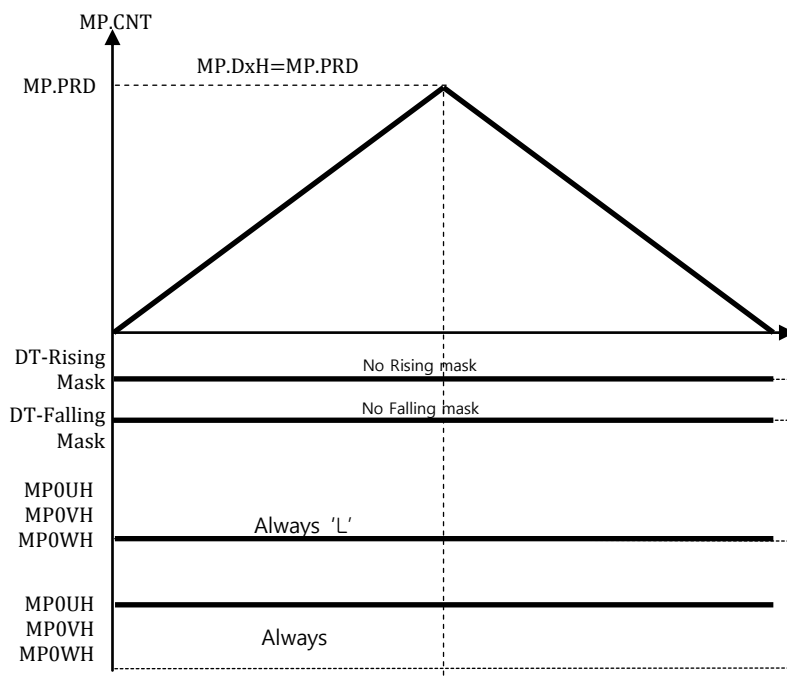


Figure 16.17. L-side Always On ($T_{DUTY} = '0'$: Dead-time Disabled)

Symmetrical Mode vs Asymmetrical Mode

In symmetrical mode, the wave form is symmetrical on both sides of the mid-point of the period. The duty comparison is performed twice in both up and down count periods.

ADn.SR ADCn Status Register

The ADC Status Register is a 32-bit register.

AD0.SR=0x4000_B024, AD1.SR=0x4000_B124

7	6	5	4	3	2	1	0
EOC	ABUSY	DOVRUN	DMAIRQ	TRGIRQ	EOSIRQ	-	EOCIRQ
0	0	0	0	0	0	-	0
RO	RO	RO	RO	RC	RC	-	RC

7	EOC	ADC End-of-Conversion flag (Start-of-Conversion made by ADC_CLK clears this bit , not ASTART)
6	ABUSY	ADC conversion busy flag
5	DOVRUN	DMA overrun flag (not interrupt) (DMA ACK didn't come until end of next conversion)
4	DMAIRQ	DMA done received (DMA transfer is completed)
3	TRGIRQ	ADC Trigger interrupt flag(Write "1" to clear flag) (0: no int / 1: int occurred)
2	EOSIRQ	This flag will be set upon final end of a sequence (Write "1" to clear flag) 0 None. 1 End-of-Sequence(burst) Interrupt occurred
0	EOCIRQ	This flag will be set upon each conversion in a sequence is occurred(Write "1" to clear flag) 0 None. 1 End-of-Conversion Interrupt occurred

ADn.IER Interrupt Enable Register

AD0.IER=0x4000_B028, AD1.IER=0x4000_B128

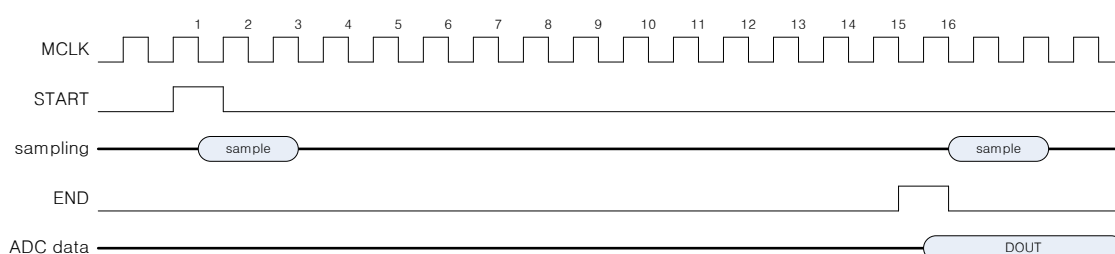
7	6	5	4	3	2	1	0
			DMAIRQE	TRGIRQE	EOSIRQE	-	EOCIRQE
			0	0	0	-	0
			RW	RW	RW	-	RW

4	DMAIRQE	DMA done interrupt enable 0: interrupt disable 1: interrupt enable
3	TRGIRQE	ADC trigger conversion interrupt enable
2	EOSIRQE	ADC sequence conversion interrupt enable
0	EOCIRQE	ADC single conversion interrupt enable

General ADC Setup Procedure

1. Allow the modification of the I/O pins to use the ADC inputs needed by writing the unlock sequence as described in PORT CONTROL UNIT (PCU), no pullups enabled.
2. Enable the ADC peripherals needed in PER2 register.
3. Enable the ADC peripheral clock in the PCER2 register.
4. Select the alternating function for the ADC inputs (Port n MUX registers).
5. Configure the ADC Pins to Analog
6. Configure the ADC mode in the ADCnMODE register and enabled the channel ADCn.
7. Configure the ADCnCR1 register and write an appropriate clock divider value.
8. Configure any special features such as triggers, sequencing, etc.
9. Start ADC conversion

ADC Single Mode Timing Diagram



ADC Sequencing Mode Timing Diagram

