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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	16MHz
Connectivity	I²C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, IR, POR, PWM, WDT
Number of I/O	30
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 22x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm8l151k4t3

Contents

1 Introduction

This document describes the features, pinout, mechanical data and ordering information of the medium-density STM8L151x4/6 and STM8L152x4/6 devices (STM8L151Cx/Kx/Gx, STM8L152Cx/Kx microcontrollers with a 16-Kbyte or 32-Kbyte Flash memory density). These devices are referred to as medium-density devices in the STM8L15x and STM8L16x reference manual (RM0031) and in the STM8L Flash programming manual (PM0054).

For more details on the whole STMicroelectronics ultra-low-power family please refer to *Section 2.2: Ultra-low-power continuum on page 13*.

For information on the debug module and SWIM (single wire interface module), refer to the STM8 SWIM communication protocol and debug module user manual (UM0470).For information on the STM8 core, please refer to the STM8 CPU programming manual (PM0044).

The medium-density devices provide the following benefits:

- Integrated system
  - Up to 32 Kbyte of medium-density embedded Flash program memory
  - 1 Kbyte of data EEPROM
  - Internal high speed and low-power low speed RC
  - Embedded reset
- Ultra-low power consumption
  - 195 µA/MHz + 440 µA (consumption)
  - 0.9 µA with LSI in Active-halt mode
  - Clock gated system and optimized power management
  - Capability to execute from RAM for Low power wait mode and Low power run mode
- Advanced features
  - Up to 16 MIPS at 16 MHz CPU clock frequency
  - Direct memory access (DMA) for memory-to-memory or peripheral-to-memory access
- Short development cycles
  - Application scalability across a common family product architecture with compatible pinout, memory map and modular peripherals
  - Wide choice of development tools

All devices offer 12-bit ADC, DAC, two comparators, Real-time clock three 16-bit timers, one 8-bit timer as well as standard communication interface such as SPI, I2C and USART. A 4x28-segment LCD is available on the medium-density STM8L152xx line. *Table 2: Medium-density STM8L151x4/6 and STM8L152x4/6 low-power device features and peripheral counts* and *Section 3: Functional overview* give an overview of the complete range of peripherals proposed in this family.

Figure 1 on page 14 shows the general block diagram of the device family.

Note: *ADC1 can be served by DMA1.*

3.10   Digital-to-analog converter (DAC)

- 12-bit DAC with output buffer
- Synchronized update capability using TIM4
- DMA capability
- External triggers for conversion
- Input reference voltage V_{REF+} for better resolution

Note: *DAC can be served by DMA1.*

3.11   Ultra-low-power comparators

The medium-density STM8L151x4/6 and STM8L152x4/6 embed two comparators (COMP1 and COMP2) sharing the same current bias and voltage reference. The voltage reference can be internal or external (coming from an I/O).

- One comparator with fixed threshold (COMP1).
- One comparator rail to rail with fast or slow mode (COMP2). The threshold can be one of the following:
    - DAC output
    - External I/O
    - Internal reference voltage or internal reference voltage sub multiple (1/4, 1/2, 3/4)

The two comparators can be used together to offer a window function. They can wake up from Halt mode.

3.12   System configuration controller and routing interface

The system configuration controller provides the capability to remap some alternate functions on different I/O ports. TIM4 and ADC1 DMA channels can also be remapped.

The highly flexible routing interface allows application software to control the routing of different I/Os to the TIM1 timer input captures. It also controls the routing of internal analog signals to ADC1, COMP1, COMP2, DAC and the internal reference voltage V_{REFINT}. It also provides a set of registers for efficiently managing the charge transfer acquisition sequence (*Section 3.13: Touch sensing*).

3.13   Touch sensing

Medium-density STM8L151x4/6 and STM8L152x4/6 devices provide a simple solution for adding capacitive sensing functionality to any application. Capacitive sensing technology is able to detect finger presence near an electrode which is protected from direct touch by a dielectric (example, glass, plastic). The capacitive variation introduced by a finger (or any conductive object) is measured using a proven implementation based on a surface charge transfer acquisition principle. It consists of charging the electrode capacitance and then transferring a part of the accumulated charges into a sampling capacitor until the voltage across this capacitor has reached a specific threshold. In medium-density STM8L151x4/6

3.14.2 16-bit general purpose timers

- 16-bit autoreload (AR) up/down-counter
- 7-bit prescaler adjustable to fixed power of 2 ratios (1…128)
- 2 individually configurable capture/compare channels
- PWM mode
- Interrupt capability on various events (capture, compare, overflow, break, trigger)
- Synchronization with other timers or external signals (external clock, reset, trigger and enable)

3.14.3 8-bit basic timer

The 8-bit timer consists of an 8-bit up auto-reload counter driven by a programmable prescaler. It can be used for timebase generation with interrupt generation on timer overflow or for DAC trigger generation.

3.15 Watchdog timers

The watchdog system is based on two independent timers providing maximum security to the applications.

3.15.1 Window watchdog timer

The window watchdog (WWDG) is used to detect the occurrence of a software fault, usually generated by external interferences or by unexpected logical conditions, which cause the application program to abandon its normal sequence.

3.15.2 Independent watchdog timer

The independent watchdog peripheral (IWDG) can be used to resolve processor malfunctions due to hardware or software failures.

It is clocked by the internal LSI RC clock source, and thus stays active even in case of a CPU clock failure.

3.16 Beeper

The beeper function outputs a signal on the BEEP pin for sound generation. The signal is in the range of 1, 2 or 4 kHz.

Table 9. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5430	RI	Reserved area (1 byte)		0x00
0x00 5431		RI_ICR1	Timer input capture routing register 1	0x00
0x00 5432		RI_ICR2	Timer input capture routing register 2	0x00
0x00 5433		RI_IOIR1	I/O input register 1	undefined
0x00 5434		RI_IOIR2	I/O input register 2	undefined
0x00 5435		RI_IOIR3	I/O input register 3	undefined
0x00 5436		RI_IOCMR1	I/O control mode register 1	0x00
0x00 5437		RI_IOCMR2	I/O control mode register 2	0x00
0x00 5438		RI_IOCMR3	I/O control mode register 3	0x00
0x00 5439		RI_IOSR1	I/O switch register 1	0x00
0x00 543A		RI_IOSR2	I/O switch register 2	0x00
0x00 543B		RI_IOSR3	I/O switch register 3	0x00
0x00 543C		RI_IOGCR	I/O group control register	0x3F
0x00 543D		RI_ASCR1	Analog switch register 1	0x00
0x00 543E		RI_ASCR2	Analog switch register 2	0x00
0x00 543F		RI_RCR	Resistor control register 1	0x00
0x00 5440	COMP	COMP_CSR1	Comparator control and status register 1	0x00
0x00 5441		COMP_CSR2	Comparator control and status register 2	0x00
0x00 5442		COMP_CSR3	Comparator control and status register 3	0x00
0x00 5443		COMP_CSR4	Comparator control and status register 4	0x00
0x00 5444		COMP_CSR5	Comparator control and status register 5	0x00

1. These registers are not impacted by a system reset. They are reset at power-on.

8   Unique ID

STM8 devices feature a 96-bit unique device identifier which provides a reference number that is unique for any device and in any context. The 96 bits of the identifier can never be altered by the user.

The unique device identifier can be read in single bytes and may then be concatenated using a custom algorithm.

The unique device identifier is ideally suited:

- For use as serial numbers
- For use as security keys to increase the code security in the program memory while using and combining this unique ID with software cryptographic primitives and protocols before programming the internal memory.
- To activate secure boot processes

Table 14. Unique ID registers (96 bits)

Address	Content description	Unique ID bits							
		7	6	5	4	3	2	1	0
0x4926	X co-ordinate on the wafer	U_ID[7:0]							
0x4927		U_ID[15:8]							
0x4928	Y co-ordinate on the wafer	U_ID[23:16]							
0x4929		U_ID[31:24]							
0x492A	Wafer number	U_ID[39:32]							
0x492B	Lot number	U_ID[47:40]							
0x492C		U_ID[55:48]							
0x492D		U_ID[63:56]							
0x492E		U_ID[71:64]							
0x492F		U_ID[79:72]							
0x4930		U_ID[87:80]							
0x4931		U_ID[95:88]							

9.3 Operating conditions

Subject to general operating conditions for V_{DD} and T_A.

9.3.1 General operating conditions

Table 18. General operating conditions

Symbol	Parameter	Conditions		Min.	Max.	Unit
f_{SYSCLK}[1]	System clock frequency	1.65 V ≤V_{DD} < 3.6 V		0	16	MHz
V_{DD}	Standard operating voltage	-		1.65[2]	3.6	V
V_{DDA}	Analog operating voltage	ADC and DAC not used	Must be at the same potential as V_{DD}	1.65[2]	3.6	V
		ADC or DAC used		1.8	3.6	V
P_D[3]	Power dissipation at T_A= 85 °C for suffix 6 devices	LQFP48		-	288	mW
		UFQFPN48		-	169	
		LQFP32		-	288	
		UFQFPN32		-	169	
		UFQFPN28		-	169	
		WLCSP28		-	286	
	Power dissipation at T_A= 125 °C for suffix 3 devices and at T_A= 105 °C for suffix 7 devices	LQFP48		-	77	
		UFQFPN48		-	156	
		LQFP32		-	85	
		UFQFPN32		-	131	
		UFQFPN28		-	42	
		WLCSP28		-	71	
T_A	Temperature range	1.65 V ≤V_{DD} < 3.6 V (6 suffix version)		-40	85	°C
		1.65 V ≤V_{DD} < 3.6 V (7 suffix version)		-40	105	
		1.65 V ≤V_{DD} < 3.6 V (3 suffix version)		-40	125	
T_J	Junction temperature range	-40 °C ≤T_A < 85 °C (6 suffix version)		-40	105[4]	°C
		-40 °C ≤ T_A < 105 °C (7 suffix version)		-40	110[4]	
		-40 °C ≤ T_A < 125 °C (3 suffix version)		-40	130	

1. f_{SYSCLK} = f_{CPU}

2. 1.8 V at power-up, 1.65 V at power-down if BOR is disabled

3. To calculate $P_{Dmax}(T_A)$, use the formula $P_{Dmax}=(T_{Jmax} - T_A)/\Theta_{JA}$ with T_{Jmax} in this table and Θ_{JA} in "Thermal characteristics" table.

4. T_{Jmax} is given by the test limit. Above this value the product behavior is not guaranteed.

9.3.2 Embedded reset and power control block characteristics

Table 19. Embedded reset and power control block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{VDD}	V_{DD} rise time rate	BOR detector enabled	$0^{(1)}$	-	$\infty^{(1)}$	μs/V
	V_{DD} fall time rate	BOR detector enabled	$20^{(1)}$	-	$\infty^{(1)}$	
t_{TEMP}	Reset release delay	V_{DD} rising BOR detector enabled	-	3	-	ms
		V_{DD} rising BOR detector disabled	-	1	-	
V_{PDR}	Power-down reset threshold	Falling edge	$1.30^{(2)}$	1.50	1.65	V
V_{BOR0}	Brown-out reset threshold 0 (BOR_TH[2:0]=000)	Falling edge	1.67	1.70	1.74	V
		Rising edge	1.69	1.75	1.80	
V_{BOR1}	Brown-out reset threshold 1 (BOR_TH[2:0]=001)	Falling edge	1.87	1.93	1.97	
		Rising edge	1.96	2.04	2.07	
V_{BOR2}	Brown-out reset threshold 2 (BOR_TH[2:0]=010)	Falling edge	2.22	2.3	2.35	
		Rising edge	2.31	2.41	2.44	
V_{BOR3}	Brown-out reset threshold 3 (BOR_TH[2:0]=011)	Falling edge	2.45	2.55	2.60	
		Rising edge	2.54	2.66	2.7	
V_{BOR4}	Brown-out reset threshold 4 (BOR_TH[2:0]=100)	Falling edge	2.68	2.80	2.85	
		Rising edge	2.78	2.90	2.95	
V_{PVD0}	PVD threshold 0	Falling edge	1.80	1.84	1.88	V
		Rising edge	1.88	1.94	1.99	
V_{PVD1}	PVD threshold 1	Falling edge	1.98	2.04	2.09	
		Rising edge	2.08	2.14	2.18	
V_{PVD2}	PVD threshold 2	Falling edge	2.2	2.24	2.28	
		Rising edge	2.28	2.34	2.38	
V_{PVD3}	PVD threshold 3	Falling edge	2.39	2.44	2.48	
		Rising edge	2.47	2.54	2.58	
V_{PVD4}	PVD threshold 4	Falling edge	2.57	2.64	2.69	
		Rising edge	2.68	2.74	2.79	
V_{PVD5}	PVD threshold 5	Falling edge	2.77	2.83	2.88	
		Rising edge	2.87	2.94	2.99	
V_{PVD6}	PVD threshold 6	Falling edge	2.97	3.05	3.09	
		Rising edge	3.08	3.15	3.20	

1. Data guaranteed by design.

2. Data based on characterization results.

Figure 12. POR/BOR thresholds
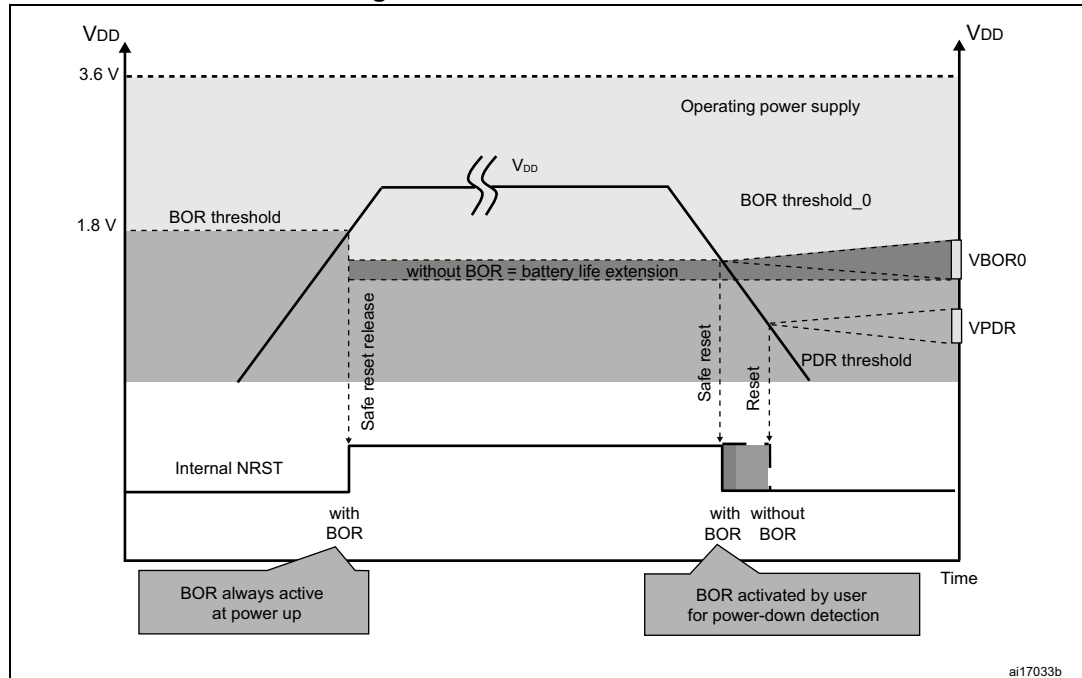
9.3.3 Supply current characteristics

Total current consumption

The MCU is placed under the following conditions:

 l   All I/O pins in input mode with a static value at V_{DD} or V_{SS} (no load)

 l   All peripherals are disabled except if explicitly mentioned.

In the following table, data is based on characterization results, unless otherwise specified.

Subject to general operating conditions for V_{DD} and T_A.

Table 20. Total current consumption in Run mode

Symbol	Parameter	Conditions[1]			Typ	Max				Unit
						55 °C	85 °C[2]	105°C[3]	125 °C[4]	
$I_{DD(RUN)}$	Supply current in run mode[5]	All peripherals OFF, code executed from RAM, V_{DD} from 1.65 V to 3.6 V	HSI RC osc. (16 MHz)[6]	f_{CPU} = 125 kHz	0.39	0.47	0.49	0.52	0.55	mA
				f_{CPU} = 1 MHz	0.48	0.56	0.58	0.61	0.65	
				f_{CPU} = 4 MHz	0.75	0.84	0.86	0.91	0.99	
				f_{CPU} = 8 MHz	1.10	1.20	1.25	1.31	1.40	
				f_{CPU} = 16 MHz	1.85	1.93	2.12[8]	2.29[8]	2.36[8]	
			HSE external clock ($f_{CPU}=f_{HSE}$)[7]	f_{CPU} = 125 kHz	0.05	0.06	0.09	0.11	0.12	
				f_{CPU} = 1 MHz	0.18	0.19	0.20	0.22	0.23	
				f_{CPU} = 4 MHz	0.55	0.62	0.64	0.71	0.77	
				f_{CPU} = 8 MHz	0.99	1.20	1.21	1.22	1.24	
				f_{CPU} = 16 MHz	1.90	2.22	2.23[8]	2.24[8]	2.28[8]	
			LSI RC osc. (typ. 38 kHz)	$f_{CPU} = f_{LSI}$	0.040	0.045	0.046	0.048	0.050	
			LSE external clock (32.768 kHz)	$f_{CPU} = f_{LSE}$	0.035	0.040	0.048[8]	0.050	0.062	
$I_{DD(RUN)}$	Supply current in Run mode	All peripherals OFF, code executed from Flash, V_{DD} from 1.65 V to 3.6 V	HSI RC osc.[9]	f_{CPU} = 125 kHz	0.43	0.55	0.56	0.58	0.62	mA
				f_{CPU} = 1 MHz	0.60	0.77	0.80	0.82	0.87	
				f_{CPU} = 4 MHz	1.11	1.34	1.37	1.39	1.43	
				f_{CPU} = 8 MHz	1.90	2.20	2.23	2.31	2.40	
				f_{CPU} = 16 MHz	3.8	4.60	4.75	4.87	4.88	
			HSE external clock ($f_{CPU}=f_{HSE}$)[7]	f_{CPU} = 125 kHz	0.30	0.36	0.39	0.44	0.47	
				f_{CPU} = 1 MHz	0.40	0.50	0.52	0.55	0.56	
				f_{CPU} = 4 MHz	1.15	1.31	1.40	1.45	1.48	
				f_{CPU} = 8 MHz	2.17	2.33	2.44	2.56	2.77	
				f_{CPU} = 16 MHz	4.0	4.46	4.52	4.59	4.77	
			LSI RC osc.	$f_{CPU} = f_{LSI}$	0.110	0.123	0.130	0.140	0.150	
			LSE ext. clock (32.768 kHz)[10]	$f_{CPU} = f_{LSE}$	0.100	0.101	0.104	0.119	0.122	

1. All peripherals OFF, V_{DD} from 1.65 V to 3.6 V, HSI internal RC osc., $f_{CPU}=f_{SYSCLK}$

2. For devices with suffix 6

3. For devices with suffix 7

4. For devices with suffix 3

Output driving current

Subject to general operating conditions for V_{DD} and T_A unless otherwise specified.

Table 39. Output driving current (high sink ports)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
High sink	V_{OL} [1]	Output low level voltage for an I/O pin	I_{IO} = +2 mA, V_{DD} = 3.0 V	-	0.45	V
			I_{IO} = +2 mA, V_{DD} = 1.8 V	-	0.45	V
			I_{IO} = +10 mA, V_{DD} = 3.0 V	-	0.7	V
	V_{OH} [2]	Output high level voltage for an I/O pin	I_{IO} = -2 mA, V_{DD} = 3.0 V	V_{DD}-0.45	-	V
			I_{IO} = -1 mA, V_{DD} = 1.8 V	V_{DD}-0.45	-	V
			I_{IO} = -10 mA, V_{DD} = 3.0 V	V_{DD}-0.7	-	V

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 16* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.

2. The I_{IO} current sourced must always respect the absolute maximum rating specified in *Table 16* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VDD}.

Table 40. Output driving current (true open drain ports)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
Open drain	V_{OL} [1]	Output low level voltage for an I/O pin	I_{IO} = +3 mA, V_{DD} = 3.0 V	-	0.45	V
			I_{IO} = +1 mA, V_{DD} = 1.8 V	-	0.45	

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 16* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.

Table 41. Output driving current (PA0 with high sink LED driver capability)

I/O Type	Symbol	Parameter	Conditions	Min	Max	Unit
IR	V_{OL} [1]	Output low level voltage for an I/O pin	I_{IO} = +20 mA, V_{DD} = 2.0 V	-	0.45	V

1. The I_{IO} current sunk must always respect the absolute maximum rating specified in *Table 16* and the sum of I_{IO} (I/O ports and control pins) must not exceed I_{VSS}.

I²C - Inter IC control interface

Subject to general operating conditions for V_{DD}, f_{SYSCLK}, and T_A unless otherwise specified.

The STM8L I²C interface (I2C1) meets the requirements of the Standard I²C communication protocol described in the following table with the restriction mentioned below:

Refer to I/O port characteristics for more details on the input/output alternate function characteristics (SDA and SCL).

Table 44. I2C characteristics

Symbol	Parameter	Standard mode I²C		Fast mode I²C[1]		Unit
		Min[2]	Max[2]	Min[2]	Max[2]	
$t_{w(SCLL)}$	SCL clock low time	4.7	-	1.3	-	µs
$t_{w(SCLH)}$	SCL clock high time	4.0	-	0.6	-	
$t_{su(SDA)}$	SDA setup time	250	-	100	-	ns
$t_{h(SDA)}$	SDA data hold time	0	-	0	900	
$t_{r(SDA)}$ $t_{r(SCL)}$	SDA and SCL rise time	-	1000	-	300	
$t_{f(SDA)}$ $t_{f(SCL)}$	SDA and SCL fall time	-	300	-	300	
$t_{h(STA)}$	START condition hold time	4.0	-	0.6	-	µs
$t_{su(STA)}$	Repeated START condition setup time	4.7	-	0.6	-	
$t_{su(STO)}$	STOP condition setup time	4.0	-	0.6	-	µs
$t_{w(STO:STA)}$	STOP to START condition time (bus free)	4.7	-	1.3	-	µs
C_b	Capacitive load for each bus line	-	400		400	pF

1. f_{SYSCLK} must be at least equal to 8 MHz to achieve max fast I²C speed (400 kHz).

2. Data based on standard I²C protocol requirement, not tested in production.

Note: *For speeds around 200 kHz, the achieved speed can have a± 5% tolerance*
For other speed ranges, the achieved speed can have a± 2% tolerance
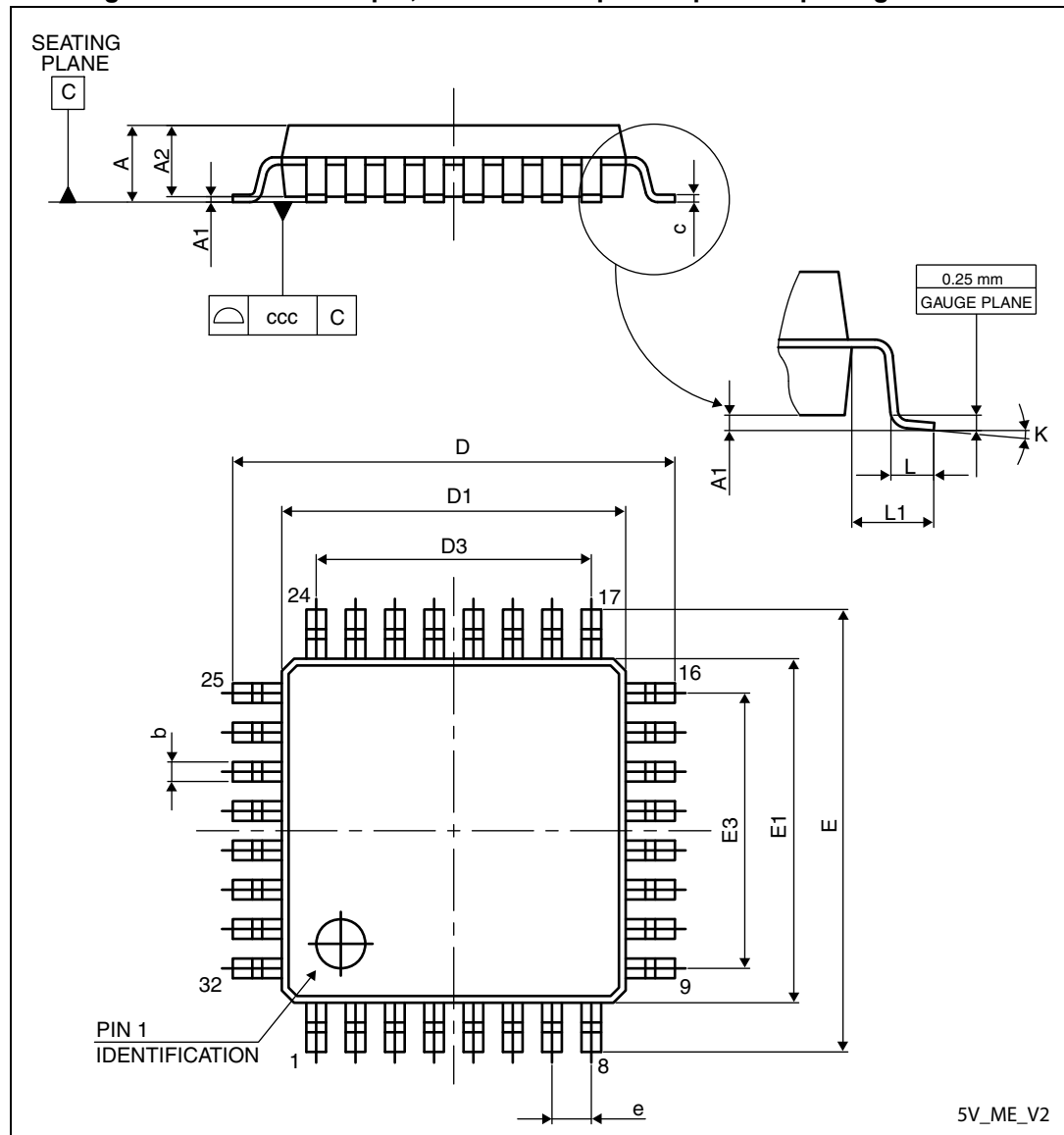*The above variations depend on the accuracy of the external components used.*

Figure 44. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package recommended footprint

ai14911d
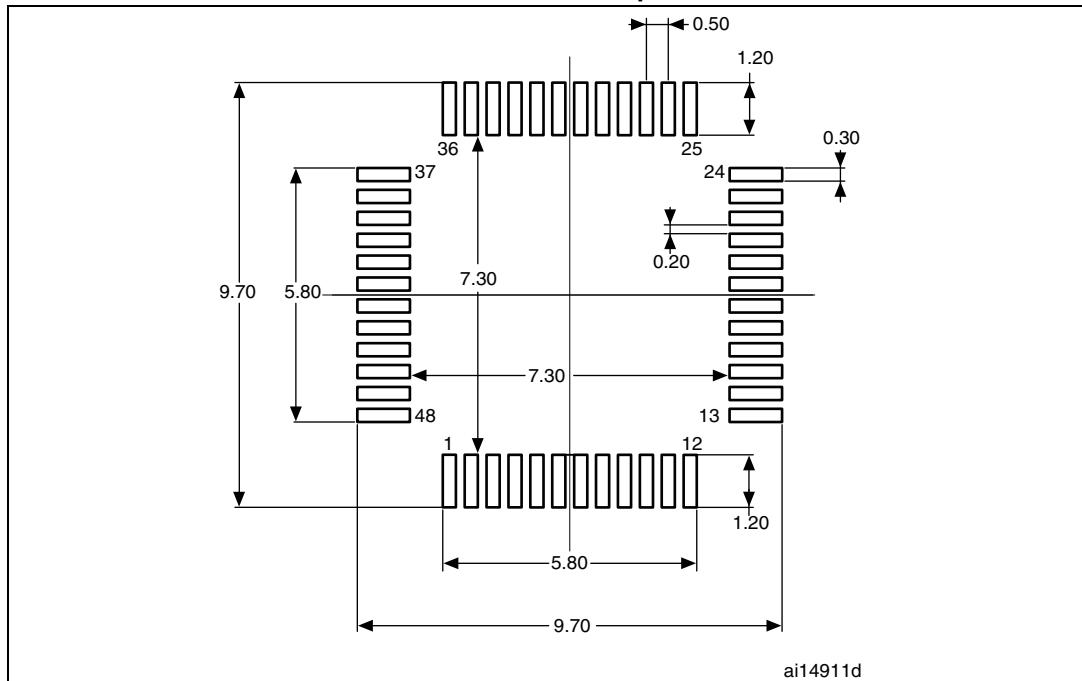
1. Dimensions are expressed in millimeters.

10.4 LQFP32 package information

Figure 49. LQFP32 - 32-pin, 7 x 7 mm low-profile quad flat package outline
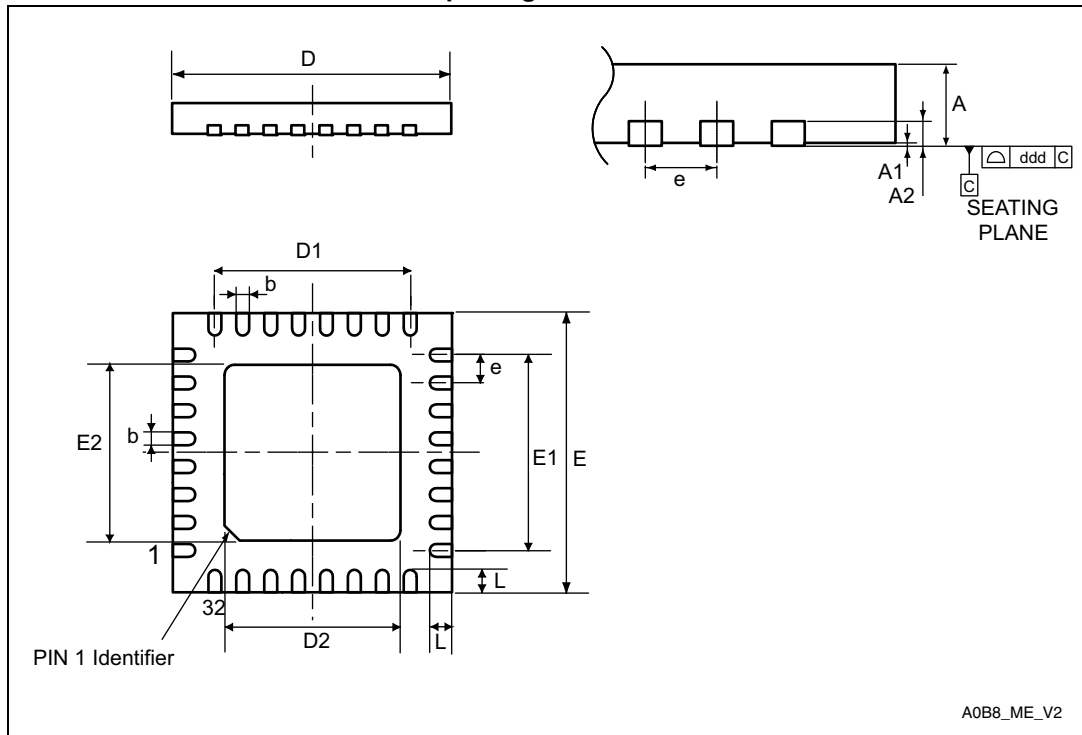

1. Drawing is not to scale.

Samples to run qualification activity.

10.5   UFQFPN32 package information

Figure 52. UFQFPN32 - 32-pin, 5 x 5 mm, 0.5 mm pitch ultra thin fine pitch quad flat package outline
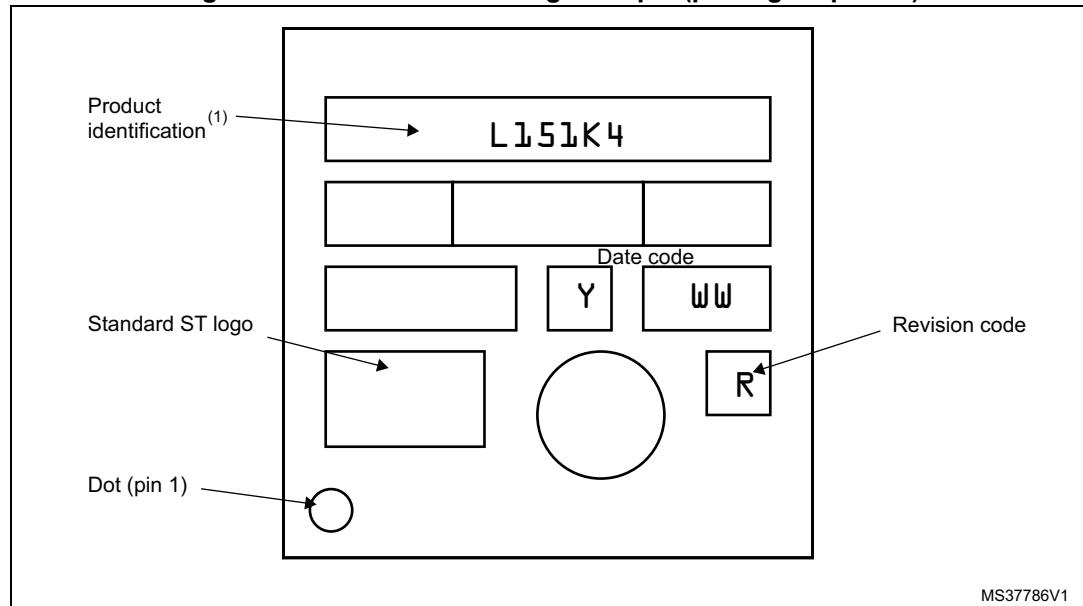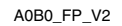

1.   Drawing is not to scale.

Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location. Other optional marking or inset/upset marks, which depend on supply chain operations, are not indicated below.

Figure 54. UFQFPN32 marking example (package top view)

1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 56. UFQFPN28 - 28-lead, 4 x 4 mm, 0.5 mm pitch, ultra thin fine pitch quad flat package recommended footprint
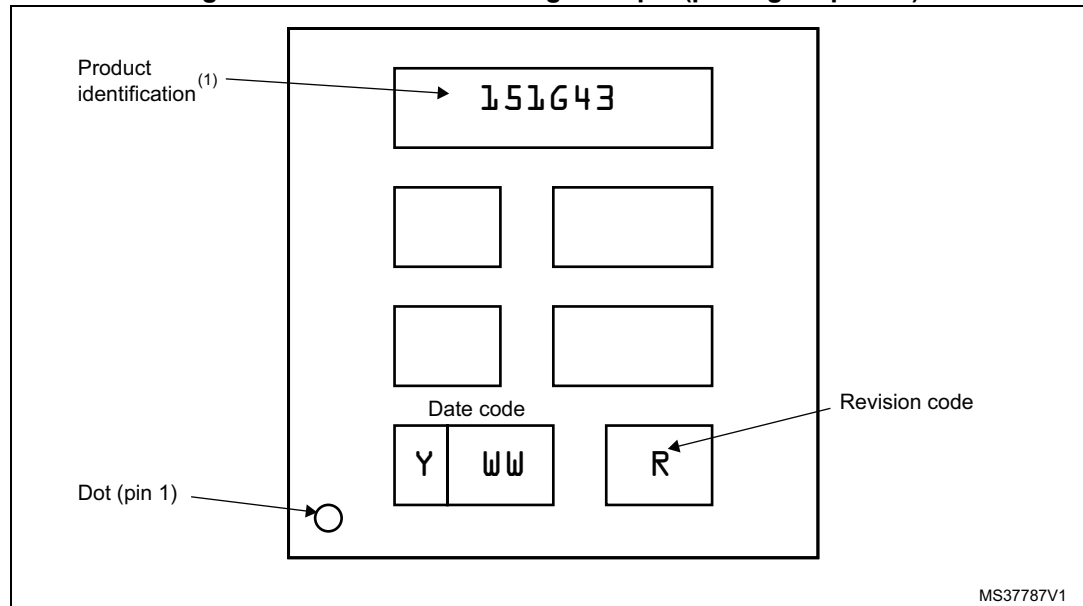

1. Dimensions are expressed in millimeters.

Device marking

The following figure gives an example of topside marking orientation versus pin 1 identifier location. Other optional marking or inset/upset marks, which depend on supply chain operations, are not indicated below.

Figure 57. UFQFPN28 marking example (package top view)

1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

10.8 Thermal characteristics

The maximum chip junction temperature (T_{Jmax}) must never exceed the values given in *Table 18: General operating conditions on page 66*.

The maximum chip-junction temperature, T_{Jmax}, in degree Celsius, may be calculated using the following equation:

$$T_{Jmax} = T_{Amax} + (P_{Dmax} \times \Theta_{JA})$$

Where:

- T_{Amax} is the maximum ambient temperature in $^\circ$C

- Θ_{JA} is the package junction-to-ambient thermal resistance in $^\circ$C/W

- P_{Dmax} is the sum of P_{INTmax} and $P_{I/Omax}$ ($P_{Dmax} = P_{INTmax} + P_{I/Omax}$)

- P_{INTmax} is the product of I_{DD} and V_{DD}, expressed in Watts. This is the maximum chip internal power.

- $P_{I/Omax}$ represents the maximum power dissipation on output pins
  Where:
  $P_{I/Omax} = \Sigma (V_{OL}*I_{OL}) + \Sigma((V_{DD}-V_{OH})*I_{OH})$,
  taking into account the actual V_{OL}/I_{OL} and V_{OH}/I_{OH} of the I/Os at low and high level in the application.

Table 68. Thermal characteristics[1]

Symbol	Parameter	Value	Unit
Θ_{JA}	Thermal resistance junction-ambient LQFP 48- 7 x 7 mm	65	$^\circ$C/W
Θ_{JA}	Thermal resistance junction-ambient UFQFPN 48- 7 x 7mm	32	$^\circ$C/W
Θ_{JA}	Thermal resistance junction-ambient LQFP 32 - 7 x 7 mm	59	$^\circ$C/W
Θ_{JA}	Thermal resistance junction-ambient UFQFPN 32 - 5 x 5 mm	38	$^\circ$C/W
Θ_{JA}	Thermal resistance junction-ambient UFQFPN28 - 4 x 4 mm	118	$^\circ$C/W
Θ_{JA}	Thermal resistance junction-ambient WLCSP28	70	$^\circ$C/W

1. Thermal resistances are based on JEDEC JESD51-2 with 4-layer PCB in a natural convection environment.