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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

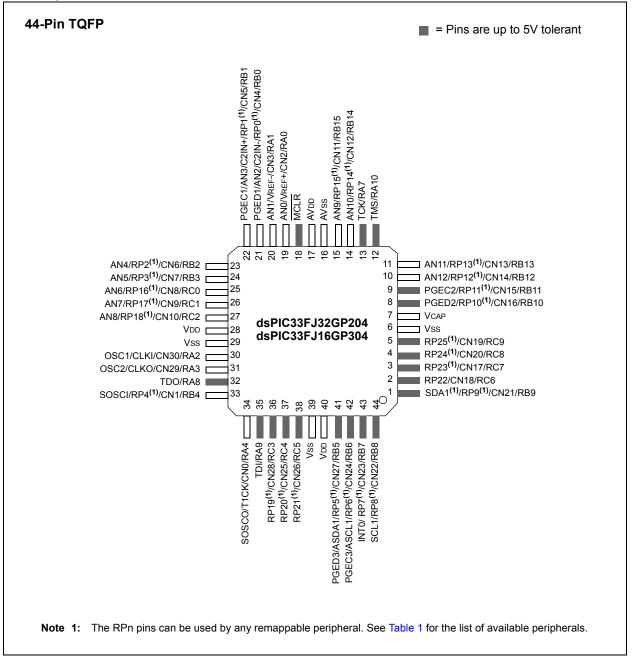
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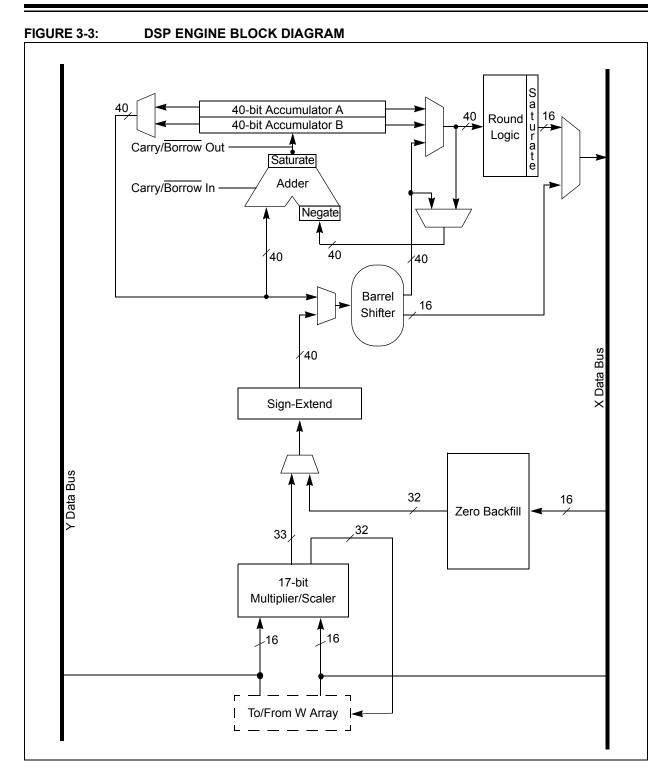
Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPs
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DCI, DMA, I ² S, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 10x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj32gp202-e-so

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Pin Diagrams (Continued)





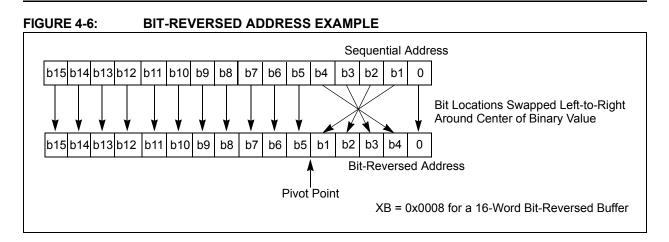


TABLE 4-24: BIT-REVERSED ADDRESS SEQUENCE (16-ENTRY)

Normal Address Bit-Reversed Address					Idress				
A3	A2	A1	A0	Decimal	A3	A2	A1	A0	Decimal
0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	8
0	0	1	0	2	0	1	0	0	4
0	0	1	1	3	1	1	0	0	12
0	1	0	0	4	0	0	1	0	2
0	1	0	1	5	1	0	1	0	10
0	1	1	0	6	0	1	1	0	6
0	1	1	1	7	1	1	1	0	14
1	0	0	0	8	0	0	0	1	1
1	0	0	1	9	1	0	0	1	9
1	0	1	0	10	0	1	0	1	5
1	0	1	1	11	1	1	0	1	13
1	1	0	0	12	0	0	1	1	3
1	1	0	1	13	1	0	1	1	11
1	1	1	0	14	0	1	1	1	7
1	1	1	1	15	1	1	1	1	15

4.8.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The TBLRDL and TBLWTL instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The TBLRDH and TBLWTH instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two 16-bit wide word address spaces, residing side by side, each with the same address range. TBLRDL and TBLWTL access the space that contains the least significant data word. TBLRDH and TBLWTH access the space that contains the upper data byte.

Two table instructions are provided to move byte or word sized (16-bit) data to and from program space. Both function as either byte or word operations.

• TBLRDL (Table Read Low): In Word mode, this instruction maps the lower word of the program space location (P<15:0>) to a data address (D<15:0>).

In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when Byte Select is '1'; the lower byte is selected when it is '0'.

• TBLRDH (Table Read High): In Word mode, this instruction maps the entire upper word of a program address (P<23:16>) to a data address. Note that D<15:8>, the 'phantom byte', will always be '0'.

In Byte mode, this instruction maps the upper or lower byte of the program word to D<7:0> of the data address, as in the TBLRDL instruction. Note that the data will always be '0' when the upper 'phantom' byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, TBLWTH and TBLWTL, are used to write individual bytes or words to a program space address. The details of their operation are explained in Section 5.0 "Flash Program Memory".

For all table operations, the area of program memory space to be accessed is determined by the Table Page register (TBLPAG). TBLPAG covers the entire program memory space of the device, including user and configuration spaces. When TBLPAG<7> = 0, the table page is located in the user memory space. When TBLPAG<7> = 1, the page is located in configuration space.

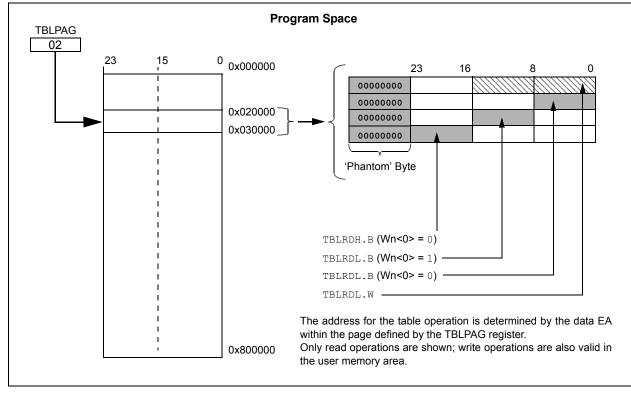


FIGURE 4-8: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	—	_	—	—	—	—
bit 15							bit 8
W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
			NVMK	EY<7:0>			
bit 7							bit 0
Legend:		SO = Settable	Only bit				
R = Readable bit		W = Writable I	bit	U = Unimplemented bit, read as '0'			

NVMKEY: NONVOLATILE MEMORY KEY REGISTER **REGISTER 5-2:**

Legend:	SO = Settable Only bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

Unimplemented: Read as '0' bit 15-8

bit 7-0 NVMKEY<7:0>: Key Register (Write Only) bits

REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

- bit 2
 IDLE: Wake-up from Idle Flag bit

 1 = Device was in Idle mode
 0 = Device was not in Idle mode

 bit 1
 BOR: Brown-out Reset Flag bit

 1 = A Brown-out Reset has occurred
 0 = A Brown-out Reset has not occurred

 bit 0
 POR: Power-on Reset Flag bit

 1 = A Power-on Reset has occurred
 - 0 = A Power-on Reset has occurred
- **Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
 - 2: If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

7.3 Interrupt Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access						
	the product page using the link above,						
	enter this URL in your browser:						
	http://www.microchip.com/wwwproducts/						
	Devices.aspx?dDocName=en530331						

7.3.1 KEY RESOURCES

- Section 6. "Interrupts" (DS70184)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

7.4 Interrupt Control and Status Registers

dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 devices implement a total of 17 registers for the interrupt controller:

- Interrupt Control Register 1 (INTCON1)
- Interrupt Control Register 2 (INTCON2)
- Interrupt Flag Status Registers (IFSx)
- Interrupt Enable Control Registers (IECx)
- Interrupt Priority Control Registers (IPCx)
- Interrupt Control and Status Register (INTTREG)

7.4.1 INTCON1 AND INTCON2

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable (NSTDIS) bit as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table.

7.4.2 IFSx

The IFS registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or external signal and is cleared via software.

7.4.3 IECx

The IEC registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

7.4.4 IPCx

The IPC registers are used to set the Interrupt Priority Level (IPL) for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels.

7.4.5 INTTREG

The INTTREG register contains the associated interrupt vector number and the new CPU Interrupt priority Level, which are latched into the vector number (VECNUM<6:0>) and Interrupt level bits (ILR<3:0>) in the INTTREG register. The new Interrupt Priority Level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence that they are listed in Table 7-1. For example, the INT0 (External Interrupt 0) is shown as having vector number 8 and a natural order priority of 0. Thus, the INT0IF bit is found in IFS0<0>, the INT0IE bit in IEC0<0>, and the INT0IP bits in the first position of IPC0 (IPC0<2:0>).

7.4.6 STATUS REGISTERS

Although they are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality:

- The CPU STATUS register, SR, contains the IPL<2:0> bits (SR<7:5>). These bits indicate the current CPU Interrupt Priority Level. The user can change the current CPU priority level by writing to the IPL bits.
- The CORCON register contains the IPL3 bit which, together with IPL<2:0>, also indicates the current CPU priority level. IPL3 is a read-only bit, so that trap events cannot be masked by the user software.

All Interrupt bits and registers are described in Register 7-1 through Register 7-19.

R-0	R-0	R/C-0	R/C-0	R-0	R/C-0	R -0	R/W-0
OA	OB	SA	SB	OAB	SAB	DA	DC
bit 15							bit 8
R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 ⁽²⁾	IPL1 ⁽²⁾	IPL0 ⁽²⁾	RA	N	OV	Z	С
bit 7		·			•		bit 0
Legend:							
C = Clear only	bit	R = Readable	bit	U = Unimplei	mented bit, read	l as '0'	

SR: CPU STATUS REGISTER⁽¹⁾ **REGISTER 7-1:**

Legend:		
C = Clear only bit	R = Readable bit	U = Unimplemented bit, read as '0'
S = Set only bit	W = Writable bit	-n = Value at POR
'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5

bit 3

IPL<2:0>: CPU Interrupt Priority Level Status bits⁽²⁾

- 111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
- 110 = CPU Interrupt Priority Level is 6 (14)
- 101 = CPU Interrupt Priority Level is 5 (13)
- 100 = CPU Interrupt Priority Level is 4 (12)
- 011 = CPU Interrupt Priority Level is 3 (11)
- 010 = CPU Interrupt Priority Level is 2 (10)
- 001 = CPU Interrupt Priority Level is 1 (9)
- 000 = CPU Interrupt Priority Level is 0 (8)

Note 1: For complete register details, see Register 3-1.

- 2: The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- 3: The IPL<2:0> Status bits are read-only when NSTDIS bit (INTCON1<15>) = 1.

CORCON: CORE CONTROL REGISTER⁽¹⁾ **REGISTER 7-2:**

U-0	U-0	U-0	R/W-0	R/W-0	R-0	R-0	R-0
—	—	—	US	EDT		DL<2:0>	
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R/W-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 ⁽²⁾	PSV	RND	IF
bit 7							bit 0

Legend:	C = Clear only bit		
R = Readable bit	W = Writable bit	-n = Value at POR	'1' = Bit is set
0' = Bit is cleared	'x = Bit is unknown	U = Unimplemented bit, read	l as '0'

IPL3: CPU Interrupt Priority Level Status bit 3⁽²⁾

- 1 = CPU Interrupt Priority Level is greater than 7
- 0 = CPU Interrupt Priority Level is 7 or less

Note 1: For complete register details, see Register 3-2.

2: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

10.9 Peripheral Pin Select Registers

The dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 devices implement 17 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (9)
- Output Remappable Peripheral Registers (8)

Note:	Input and Output Register values can only
	be changed if OSCCON[IOLOCK] = 0.
	See Section 10.6.3.1 "Control Register
	Lock" for a specific command sequence.

REGISTER 10-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	
—	—	—			INT1R<4:0>			
bit 15							bit 8	
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
_	—	_	_	—	_	—	—	
bit 7							bit 0	
Legend:								
R = Readable	bit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown			nown	

 bit 12-8
 INT1R<4:0>: Assign External Interrupt 1 (INTR1) to the corresponding RPn pin

 11111 = Input tied to Vss

 11001 = Input tied to RP25

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U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
_	_	_			SCK1R<4:0	>	
bit 15		•					bit 8
U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
	0-0	0-0	N/W-1	FV/ VV- I	SDI1R<4:0>		D/ VV- I
bit 7					00111(4.0)		bit 0
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimplei	mented bit, rea	ıd as '0'	
-n = Value at POR '1' = Bit is set				'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 7-5	• • • • • • • • • • • • • • • • • • •	it tied to RP25	0'				
bit 7-5 bit 4-0	-					:-	
Dit 4 -0	11111 = Inpu	it tied to RP25 it tied to RP1					

REGISTER 10-8: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

REGISTER 10-20: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—			RP21R<4:0>		
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—			RP20R<4:0>		
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13	Unimplemented: Read as '0'
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- bit 12-8 **RP21R<4:0>:** Peripheral Output Function is Assigned to RP21 Output Pin (see Table 10-2 for peripheral function numbers)
- bit 7-5 Unimplemented: Read as '0'
- bit 4-0 **RP20R<4:0>:** Peripheral Output Function is Assigned to RP20 Output Pin (see Table 10-2 for peripheral function numbers)

REGISTER 10-21: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	—			RP23R<4:0>		
bit 15		·					bit 8
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_	—			RP22R<4:0>		
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	nented bit, read	d as '0'	
-n = Value at P	OR	'1' = Bit is set	set '0' = Bit is cleared x = Bit is unknown				nown

bit 15-13 Unimplemented: Read as '0'

bit 12-8 **RP23R<4:0>:** Peripheral Output Function is Assigned to RP23 Output Pin (see Table 10-2 for peripheral function numbers)

bit 7-5 Unimplemented: Read as '0'

bit 4-0 **RP22R<4:0>:** Peripheral Output Function is Assigned to RP22 Output Pin (see Table 10-2 for peripheral function numbers)

11.0 TIMER1

- Note 1: This data sheet summarizes the features of the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 11. "Timers" (DS70205) of the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site: (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the real-time clock, or operate as a free-running interval timer/counter. Timer1 can operate in three modes:

- 16-bit Timer
- 16-bit Synchronous Counter
- 16-bit Asynchronous Counter

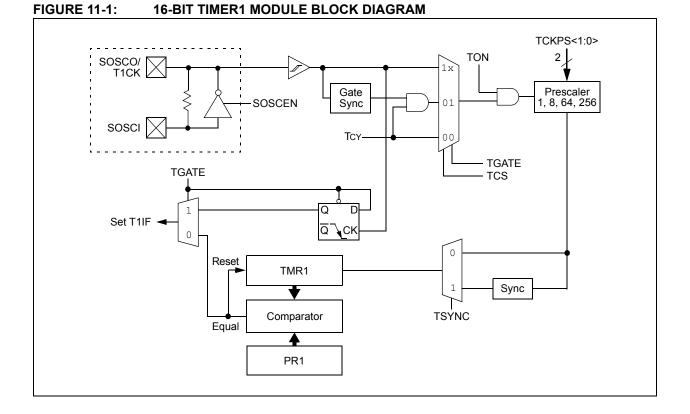
Timer1 also supports these features:

- Timer gate operation
- · Selectable prescaler settings
- Timer operation during CPU Idle and Sleep modes
- Interrupt on 16-bit Period register match or falling edge of external gate signal

Figure 11-1 illustrates a block diagram of the 16-bit timer module.

To configure Timer1 for operation:

- 1. Set the TON bit (= 1) in the T1CON register.
- 2. Select the timer prescaler ratio using the TCKPS<1:0> bits in the T1CON register.
- 3. Set the Clock and Gating modes using the TCS and TGATE bits in the T1CON register.
- 4. Set or clear the TSYNC bit in the T1CON register to select synchronous or asynchronous operation.
- 5. Load the timer period value into the PR1 register.
- 6. If interrupts are required, set the interrupt enable bit, T1IE. Use the priority bits, T1IP<2:0>, to set the interrupt priority.



14.3 Output Compare Register

REGISTER 14-1: OCxCON: OUTPUT COMPARE x CONTROL REGISTER

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
_	_	OCSIDL	—	—	_	—	
bit 15		·					bit 8
U-0	U-0	U-0	R-0 HC	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	OCFLT	OCTSEL		OCM<2:0>	
bit 7							bit 0
l egend:		HC = Cleared i	n Hardware	HS = Set in H	Hardware		

Legend:	HC = Cleared in Hardware	HS = Set in Hardware	
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	ad as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13	OCSIDL: Stop Output Compare in Idle Mode Control bit
	 1 = Output Compare x will halt in CPU Idle mode 0 = Output Compare x will continue to operate in CPU Idle mode
bit 12-5	Unimplemented: Read as '0'
bit 4	OCFLT: PWM Fault Condition Status bit
	 1 = PWM Fault condition has occurred (cleared in hardware only) 0 = No PWM Fault condition has occurred (This bit is only used when OCM<2:0> = 111.)
bit 3	OCTSEL: Output Compare Timer Select bit
	 1 = Timer3 is the clock source for Compare x 0 = Timer2 is the clock source for Compare x
bit 2-0	OCM<2:0>: Output Compare Mode Select bits
	 111 = PWM mode on OCx, Fault pin enabled 110 = PWM mode on OCx, Fault pin disabled 101 = Initialize OCx pin low, generate continuous output pulses on OCx pin 100 = Initialize OCx pin low, generate single output pulse on OCx pin 011 = Compare event toggles OCx pin 010 = Initialize OCx pin high, compare event forces OCx pin low 001 = Initialize OCx pin low, compare event forces OCx pin high 000 = Output compare channel is disabled

R/W-0	U-0	R/W-0	R/W-1 HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0 HC	R/W-0 HC	R/W-0 HC	R/W-0 HC	R/W-0 HC
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7	Onten	, tone i	AGREN	ROEN	1 214	ROER	bit (
Legend:			nented bit, read	d ac 'O'			
R = Readable	a hit	W = Writable		HS = Set in h	ardware	HC = Cleared	in hardware
-n = Value at		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	
	FUR				areu	X - DILISUIIKI	IOWIT
bit 15	12CEN: 12Cx	Enable bit					
					nd SCLx pins a by port functio	as serial port pir ns	าร
bit 14	Unimplemen	ted: Read as '	0'				
bit 13	I2CSIDL: Sto	p in Idle Mode	bit				
			ration when de ion in Idle mod		ı Idle mode		
bit 12	SCLREL: SC	Lx Release Co	ontrol bit (when	operating as	l ² C™ slave)		
	1 = Release \$ 0 = Hold SCL	SCLx clock x clock low (cl	ock stretch)				
	<u>If STREN = 1</u> Bit is R/W (i.e		n write '0' to init	tiate stretch ar	nd write '1' to re	elease clock). H	lardware clea
	at beginning o	of slave transm	ission. Hardwa	are clear at en	d of slave rece	ption.	
	If STREN = 0 Bit is R/S (i.e. transmission.	., software can	only write '1' to	o release cloc	k). Hardware cl	ear at beginnin	g of slave
bit 11			al Managemen	t Interface (IP	MI) Enable bit		
		le is enabled; a	all addresses A				
bit 10		Slave Address	L :				
			5 DIL				
		is a 10-bit slav is a 7-bit slave	e address				
bit 9	0 = I2CxADD	is a 10-bit slav is a 7-bit slave able Slew Rate	ve address e address				
bit 9	0 = I2CxADD DISSLW: Dis 1 = Slew rate	is a 7-bit slave	ve address e address e Control bit ed				
	0 = I2CxADD DISSLW: Dis 1 = Slew rate 0 = Slew rate	is a 7-bit slave able Slew Rate control disable control enable	ve address e address e Control bit ed				
	0 = I2CxADD DISSLW: Dis 1 = Slew rate 0 = Slew rate SMEN: SMB0 1 = Enable I/0	is a 7-bit slave able Slew Rate control disable control enable us Input Levels O pin threshold	ve address e address e Control bit ed bit bit s compliant wit	th SMBus spe	cification		
bit 8	0 = I2CxADD DISSLW: Dis 1 = Slew rate 0 = Slew rate SMEN: SMBu 1 = Enable I/0 0 = Disable S	is a 7-bit slave able Slew Rate control disable control enable us Input Levels O pin threshold MBus input thr	ve address e address e Control bit ed bit ls compliant wit resholds				
bit 8	0 = I2CxADD DISSLW: Dis 1 = Slew rate 0 = Slew rate SMEN: SMBu 1 = Enable I/0 0 = Disable S GCEN: Gene 1 = Enable ir (module	is a 7-bit slave able Slew Rate control disable control enable us Input Levels O pin threshold MBus input the ral Call Enable is enabled for	ve address a ddress a Control bit ed bit ls compliant wit resholds a general call a reception)	rating as I ² C s		xRSR	
bit 9 bit 8 bit 7 bit 6	 0 = I2CxADD DISSLW: Dis 1 = Slew rate 0 = Slew rate SMEN: SMBut 1 = Enable I/0 0 = Disable S GCEN: Gene 1 = Enable in (module 0 = General 	is a 7-bit slave able Slew Rate control disable control enable us Input Levels D pin threshold MBus input the ral Call Enable nterrupt when a is enabled for call address di	ve address a ddress a Control bit ed bit ls compliant wit resholds a general call a reception)	rating as I ² C s ddress is rece	lave) ived in the I2C:	xRSR	

17.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

- Note 1: This data sheet summarizes the features of the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to Section 17. "UART" (DS70188) of the "dsPIC33F/PIC24H Family Reference Manual", which is available on the Microchip web site (www.microchip.com).
 - Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 device family. The UART is a full-duplex asynchronous system that can communicate with peripheral devices, such as personal computers, LIN/J2602, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins and also includes an IrDA[®] encoder and decoder.

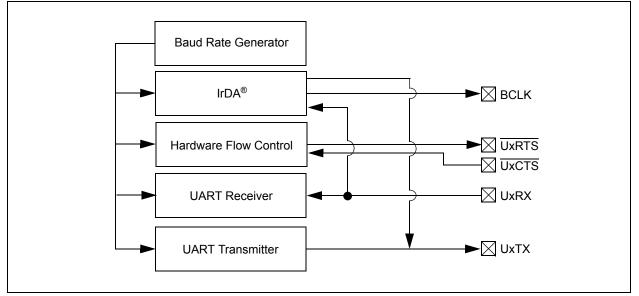
The primary features of the UART module are:

- Full-Duplex, 8-bit or 9-bit Data Transmission through the UxTX and UxRX pins
- Even, odd or no parity options (for 8-bit data)
- One or two stop bits
- Hardware Flow Control Option with UxCTS and UxRTS pins
- Fully Integrated Baud Rate Generator with 16-bit prescaler
- Baud rates ranging from 10 Mbps to 38 bps at 40 MIPS
- 4-deep first-in-first-out (FIFO) Transmit Data Buffer
- · 4-Deep FIFO Receive Data Buffer
- Parity, framing and buffer overrun error detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- · Transmit and Receive interrupts
- A separate interrupt for all UART error conditions
- · Loopback mode for diagnostic support
- · Support for Sync and Break characters
- · Support for automatic baud rate detection
- IrDA[®] encoder and decoder logic
- 16x baud clock output for IrDA[®] support

A simplified block diagram of the UART module is shown in Figure 17-1. The UART module consists of these key hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

FIGURE 17-1: UART SIMPLIFIED BLOCK DIAGRAM



REGISTER 18-4: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CH123NB<1:0>		CH123SB
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
_	—	—	—	—	CH123N	IA<1:0>	CH123SA
bit 7							bit 0

Legend:

Legenu.			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

bit 10-9 CH123NB<1:0>: Channel 1, 2, 3 Negative Input Select for Sample B bits dsPIC33FJ32GP202 devices only:

- <u>If AD12B = 1:</u> 11 = Reserved 10 = Reserved
- 01 = Reserved
- 00 = Reserved

If AD12B = 0:

- 11 = CH1 negative input is AN9, CH2 negative input is AN10, CH3 negative input is AN11
- 10 = Reserved
- 01 = CH1, CH2, CH3 negative input is VREF-
- 00 = CH1, CH2, CH3 negative input is VREF-

dsPIC33FJ32GP204 and dsPIC33FJ16GP304 devices only:

- <u>If AD12B = 1:</u> 11 = Reserved
- 10 = Reserved
- 01 = Reserved 00 = Reserved

If AD12B = 0:

11 = CH1 negative input is AN9, CH2 negative input is AN10, CH3 negative input is AN11 10 = CH1 negative input is AN6, CH2 negative input is AN7, CH3 negative input is AN8 01 = CH1, CH2, CH3 negative input is VREF-00 = CH1, CH2, CH3 negative input is VREF-

bit 8

CH123SB: Channel 1, 2, 3 Positive Input Select for Sample B bit

If AD12B = 1:			
1 = Reserved			
0 = Reserved			

If AD12B = 0:

1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5 0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

bit 7-3 Unimplemented: Read as '0'

IADL	E 20-2:	INSIRU	JCTION SET OVERVIE			1	
Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
10	BTSC	BTSC	f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
		BTSC	Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None
11	BTSS	BTSS	f,#bit4	Bit Test f, Skip if Set	1	1 (2 or 3)	None
		BTSS	Ws,#bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None
12	BTST	BTST	f,#bit4	Bit Test f	1	1	Z
		BTST.C	Ws,#bit4	Bit Test Ws to C	1	1	С
		BTST.Z	Ws,#bit4	Bit Test Ws to Z	1	1	Z
		BTST.C	Ws,Wb	Bit Test Ws <wb> to C</wb>	1	1	С
		BTST.Z	Ws,Wb	Bit Test Ws <wb> to Z</wb>	1	1	Z
13	BTSTS	BTSTS	f,#bit4	Bit Test then Set f	1	1	Z
		BTSTS.C	Ws,#bit4	Bit Test Ws to C, then Set	1	1	С
		BTSTS.Z	Ws,#bit4	Bit Test Ws to Z, then Set	1	1	Z
14	CALL	CALL	lit23	Call subroutine	2	2	None
		CALL	Wn	Call indirect subroutine	1	2	None
15	CLR	CLR	f	f = 0x0000	1	1	None
		CLR	WREG	WREG = 0x0000	1	1	None
		CLR	Ws	Ws = 0x0000	1	1	None
		CLR	Acc, Wx, Wxd, Wy, Wyd, AWB	Clear Accumulator	1	1	OA,OB,SA,SB
16	CLRWDT	CLRWDT	Acc, wa, wad, wy, wyd, Awb	Clear Watchdog Timer	1	1	WDTO,Sleep
17			c	$f = \overline{f}$	1	1	
17	COM	COM	f	<u> </u>			N,Z
		COM	f,WREG	WREG = f	1	1	N,Z
		COM	Ws,Wd	$Wd = \overline{Ws}$	1	1	N,Z
18	CP	CP	f	Compare f with WREG	1	1	C,DC,N,OV,Z
		CP	Wb,#lit5	Compare Wb with lit5	1	1	C,DC,N,OV,Z
		CP	Wb,Ws	Compare Wb with Ws (Wb – Ws)	1	1	C,DC,N,OV,Z
19	CPO	CPO	f	Compare f with 0x0000	1	1	C,DC,N,OV,Z
		CPO	Ws	Compare Ws with 0x0000	1	1	C,DC,N,OV,Z
20	CPB	CPB	f	Compare f with WREG, with Borrow	1	1	C,DC,N,OV,Z
		CPB	Wb,#lit5	Compare Wb with lit5, with Borrow	1	1	C,DC,N,OV,Z
		CPB	Wb,Ws	Compare Wb with Ws, with Borrow (Wb - Ws - \overline{C})	1	1	C,DC,N,OV,Z
21	CPSEQ	CPSEQ	Wb, Wn	Compare Wb with Wn, skip if =	1	1 (2 or 3)	None
22	CPSGT	CPSGT	Wb, Wn	Compare Wb with Wn, skip if >	1	1 (2 or 3)	None
23	CPSLT	CPSLT	Wb, Wn	Compare Wb with Wn, skip if <	1	1 (2 or 3)	None
24	CPSNE	CPSNE	Wb, Wn	Compare Wb with Wn, skip if ≠	1	1 (2 or 3)	None
25	DAW	DAW	Wn	Wn = decimal adjust Wn	1	1	С
26	DEC	DEC	f	f = f - 1	1	1	C,DC,N,OV,Z
		DEC	f,WREG	WREG = f - 1	1	1	C,DC,N,OV,Z
		DEC	Ws,Wd	Wd = Ws - 1	1	1	C,DC,N,OV,Z
27	DEC2	DEC2	f	f = f - 2	1	1	C,DC,N,OV,Z
		DEC2	f,WREG	WREG = f - 2	1	1	C,DC,N,OV,Z
		DEC2	Ws,Wd	Wd = Ws - 2	1	1	C,DC,N,OV,Z
28	DISI	DISI	#lit14	Disable Interrupts for k instruction cycles	1	1	None

TABLE 20-2: INSTRUCTION SET OVERVIEW (CONTINUED)

TABLE 22-17:PLL CLOCK TIMING SPECIFICATIONS (VDD = 3.0V TO 3.6V)

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended						
Param No.	Symbol	I Characteristic		Min	Тур ⁽¹⁾	Max	Units	Conditions
OS50	Fplli	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range ⁽²⁾		0.8		8	MHz	ECPLL, XTPLL modes
OS51	Fsys	On-Chip VCO System Frequency ⁽³⁾		100	_	200	MHz	_
OS52	TLOCK	PLL Start-up Time (Lock Time) ⁽³⁾		0.9	1.5	3.1	ms	—
OS53	DCLK	CLKO Stability (Jitter) ⁽³⁾		-3	0.5	3	%	Measured over 100 ms period

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

2: These parameters are characterized by similarity, but are tested in manufacturing at 7.7 MHz input only.

3: These parameters are characterized by similarity, but are not tested in manufacturing. This specification is based on clock cycle by clock cycle measurements. To calculate the effective jitter for individual time bases or communication clocks use this formula:

$$Peripheral Clock Jitter = \frac{DCLK}{\sqrt{\frac{FOSC}{Peripheral Bit Rate Clock}}}$$

For example: Fosc = 32 MHz, DCLK = 3%, SPI bit rate clock, (i.e., SCK) is 2 MHz.

$$SPI SCK Jitter = \left[\frac{D_{CLK}}{\sqrt{\left(\frac{32 MHz}{2 MHz}\right)}}\right] = \left[\frac{3\%}{\sqrt{16}}\right] = \left[\frac{3\%}{4}\right] = 0.75\%$$

TABLE 22-18: AC CHARACTERISTICS: INTERNAL RC ACCURACY

АС СНА	RACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \leq TA \leq +85^{\circ}C$ for industrial $-40^{\circ}C \leq TA \leq +125^{\circ}C$ for Extended						
Param No.	Characteristic	Min	Тур	Max	Units	Conditions			
	Internal FRC Accuracy @ FRC Frequency = 7.37 MHz ⁽¹⁾								
F20a	FRC	-2	_	+2	%	-40°C ≤TA ≤+85°C	VDD = 3.0-3.6V		
F20b	FRC	-5	-5 — +5 % -40°C ≤TA ≤+125°C VDD = 3.0-3.6V						

Note 1: Frequency calibrated at 25°C and 3.3V. TUN bits can be used to compensate for temperature drift.

TABLE 22-19: INTERNAL RC ACCURACY

АС СН	ARACTERISTICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended							
Param No.	Characteristic	Min	Тур	Max	Units	s Conditions			
	LPRC @ 32.768 kHz ^(1,2)								
F21a	LPRC	-15	±6	+15	%	-40°C ≤TA ≤+85°C	VDD = 3.0-3.6V		
F21b	LPRC	-40	-40 — +40 % -40°C ≤TA ≤+125°C VDD = 3.0-3.6V						

Note 1: Change of LPRC frequency as VDD changes.

2: LPRC impacts the Watchdog Timer Time-out Period (TWDT1). See Section 19.4 "Watchdog Timer (WDT)" for more information.

FIGURE 22-5: TIMER1, 2 AND 3 EXTERNAL CLOCK TIMING CHARACTERISTICS

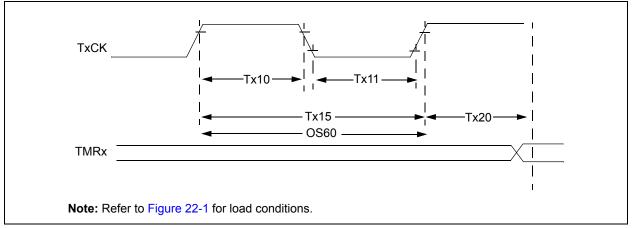


TABLE 22-22: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS⁽¹⁾

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended					
Param No.	Symbol	Characte	ristic ⁽²⁾		Min	Тур	Мах	Units	Conditions
TA10	ТтхН	TxCK High Time	Synchror no presca		0.5 TCY + 20			ns	Must also meet parameter TA15
			Synchror with pres		10			ns	
			Asynchro	onous	10	_		ns	
TA11	ΤτxL	TxCK Low Time	Synchronous no prescaler		0.5 Tcy + 20	_	—	ns	Must also meet parameter TA15
			Synchror with pres		10	_	—	ns	
			Asynchronous		10	_		ns	
TA15	ΤτχΡ	TxCK Input Period	Synchronous, no prescaler		Tcy + 40		—	ns	—
			Synchronous, with prescaler		Greater of: 20 ns or (Tcy + 40)/N		_		N = prescale value (1, 8, 64, 256)
			Asynchro	onous	20	_		ns	—
OS60	Ft1	SOSC1/T1CK Osci frequency Range (o by setting bit TCS (oscillator enabled		DC	—	50	kHz	—
TA20	TCKEXTMRL	Delay from Externa Edge to Timer Incre		ock	0.5 TCY		1.5 TCY		—

Note 1: Timer1 is a Type A.

2: These parameters are characterized by similarity, but are not tested in manufacturing.

Revision H (July 2011)

This revision includes typographical and formatting changes throughout the data sheet text.

All other major changes are referenced by their respective section in the following table.

TABLE A-7:	MAJOR SECTION UPDATES

Section Name	Update Description
Section 19.0 "Special Features"	Added Note 3 to the Connections for the On-chip Voltage Regulator diagram (see Figure 19-1).
Section 22.0 "Electrical Characteristics"	Removed Note 3 and parameter DC10 (VCORE) from the DC Temperature and Voltage Specifications (see Table 22-4).
	Updated the Characteristics definition and Conditions for parameter BO10 in the Electrical Characteristics: BOR (see Table 22-11).
	Added Note 1 to the Internal Voltage Regulator Specifications (see Table 22-13).

Revision J (June 2012)

This revision includes typographical and formatting changes throughout the data sheet text.

In addition, where applicable, new sections were added to each peripheral chapter that provide information and links to related resources, as well as helpful tips. For examples, see **Section 8.2 "Oscillator Resources"** and **Section 18.3 "ADC Helpful Tips"**.

All other major changes are referenced by their respective section in the following table.

TABLE A-8: MAJOR SECTION UPDATES

Section Name	Update Description
Section 22.0 "Electrical Characteristics"	Added Note 1 to the Operating MIPS vs. Voltage (see Table 22-1).
	Updated the notes in the following tables:
	Operating Current (IDD) (see Table 22-5)
	Idle Current (IIDLE) (see Table 22-6)
	Power-Down Current (IPD) (see Table 22-7)
	Doze Current (IDOZE) (see Table 22-8)
	Updated the conditions for Program Memory parameters D136b, D137b, and D138b (TA = +150°C) (see Table 22-12).
Section 23.0 "High Temperature Electrical Characteristics"	Removed Table 23-8: DC Characteristics: Program Memory.
Section 24.0 "DC and AC Device Characteristics Graphs"	Added new chapter.