

Welcome to [E-XFL.COM](#)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DCI, DMA, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 10x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj32gp202-e-sp">https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj32gp202-e-sp</a>

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

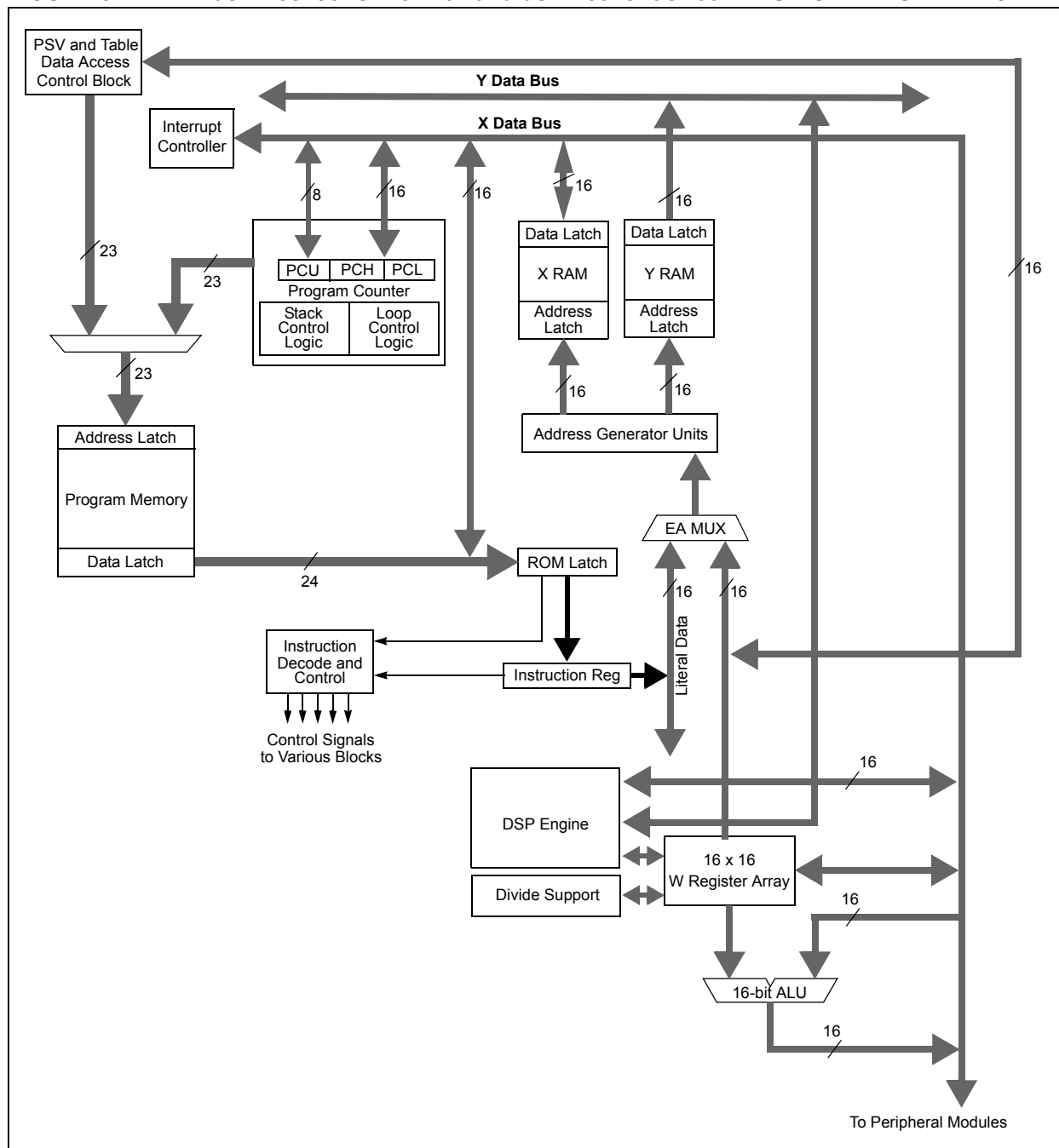
## 3.3 Special MCU Features

The dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 features a 17-bit by 17-bit single-cycle multiplier that is shared by both the MCU ALU and DSP engine. The multiplier can perform signed, unsigned and mixed-sign multiplication. Using a 17-bit by 17-bit multiplier for 16-bit by 16-bit multiplication not only allows you to perform mixed-sign multiplication, it also achieves accurate results for special operations, such as  $(-1.0) \times (-1.0)$ .

The dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 supports 16/16 and 32/16 divide operations, both fractional and integer. All divide instructions are iterative operations. They must be executed within a **REPEAT** loop, resulting in a total execution time of 19 instruction cycles. The divide operation can be interrupted during any of those 19 cycles without loss of data.

A 40-bit barrel shifter is used to perform up to a 16-bit left or right shift in a single cycle. The barrel shifter can be used by both MCU and DSP instructions.

**FIGURE 3-1: dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 CPU CORE BLOCK DIAGRAM**



# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

REGISTER 5-2: NVMKEY: NONVOLATILE MEMORY KEY REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
NVMKEY<7:0>							
bit 7							bit 0

<b>Legend:</b>	SO = Settable Only bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8      **Unimplemented:** Read as '0'

bit 7-0      **NVMKEY<7:0>:** Key Register (Write Only) bits

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

---

## REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0 (CONTINUED)

- bit 1      **IC1IF:** Input Capture Channel 1 Interrupt Flag Status bit  
            1 = Interrupt request has occurred  
            0 = Interrupt request has not occurred
- bit 0      **INT0IF:** External Interrupt 0 Flag Status bit  
            1 = Interrupt request has occurred  
            0 = Interrupt request has not occurred

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 8.3 Oscillator Control Registers

### REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER<sup>(1,3)</sup>

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
—	COSC<2:0>			—	NOSC<2:0> <sup>(2)</sup>		
bit 15							bit 8

R/W-0	R/W-0	R-0	U-0	R/C-0	U-0	R/W-0	R/W-0
CLKLOCK	IOLOCK	LOCK	—	CF	—	LPOSCEN	OSWEN
bit 7				bit 0			

<b>Legend:</b>	y = Value set from Configuration bits on POR	C = Clear only bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits (read-only)

- 111 = Fast RC oscillator (FRC) with Divide-by-n
- 110 = Fast RC oscillator (FRC) with Divide-by-16
- 101 = Low-Power RC oscillator (LPRC)
- 100 = Secondary oscillator (Sosc)
- 011 = Primary oscillator (XT, HS, EC) with PLL
- 010 = Primary oscillator (XT, HS, EC)
- 001 = Fast RC oscillator (FRC) with PLL
- 000 = Fast RC oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits<sup>(2)</sup>

- 111 = Fast RC oscillator (FRC) with Divide-by-n
- 110 = Fast RC oscillator (FRC) with Divide-by-16
- 101 = Low-Power RC oscillator (LPRC)
- 100 = Secondary oscillator (Sosc)
- 011 = Primary oscillator (XT, HS, EC) with PLL
- 010 = Primary oscillator (XT, HS, EC)
- 001 = Fast RC oscillator (FRC) with PLL
- 000 = Fast RC oscillator (FRC)

bit 7 **CLKLOCK:** Clock Lock Enable bit

If clock switching is enabled and FSCM is disabled (FOSC<FCKSM> = 0b01)

- 1 = Clock switching is disabled, system clock source is locked
- 0 = Clock switching is enabled, system clock source can be modified by clock switching

bit 6 **IOLOCK:** Peripheral Pin Select Lock bit

- 1 = Peripheral Pin Select is locked, write to Peripheral Pin Select register is not allowed
- 0 = Peripheral Pin Select is unlocked, write to Peripheral Pin Select register is allowed

bit 5 **LOCK:** PLL Lock Status bit (read-only)

- 1 = Indicates that PLL is in lock, or PLL start-up timer is satisfied
- 0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled

bit 4 **Unimplemented:** Read as '0'

**Note 1:** Writes to this register require an unlock sequence. Refer to **Section 7. "Oscillator"** (DS70186) in the *dsPIC33F/PIC24H Family Reference Manual* for details.

**2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

**3:** This register is reset only on a Power-on Reset (POR).

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 9.6 Power-Saving Control Registers

**REGISTER 9-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1**

U-0	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
—	—	T3MD	T2MD	T1MD	—	—	—
bit 15						bit 8	

R/W-0	U-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0
I2C1MD	—	U1MD	—	SPI1MD	—	—	AD1MD <sup>(1)</sup>
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13        **T3MD:** Timer3 Module Disable bit  
              1 = Timer3 module is disabled  
              0 = Timer3 module is enabled
- bit 12        **T2MD:** Timer2 Module Disable bit  
              1 = Timer2 module is disabled  
              0 = Timer2 module is enabled
- bit 11        **T1MD:** Timer1 Module Disable bit  
              1 = Timer1 module is disabled  
              0 = Timer1 module is enabled
- bit 10-8      **Unimplemented:** Read as '0'
- bit 7         **I2C1MD:** I2C1 Module Disable bit  
              1 = I2C1 module is disabled  
              0 = I2C1 module is enabled
- bit 6         **Unimplemented:** Read as '0'
- bit 5         **U1MD:** UART1 Module Disable bit  
              1 = UART1 module is disabled  
              0 = UART1 module is enabled
- bit 4         **Unimplemented:** Read as '0'
- bit 3         **SPI1MD:** SPI1 Module Disable bit  
              1 = SPI1 module is disabled  
              0 = SPI1 module is enabled
- bit 2-1       **Unimplemented:** Read as '0'
- bit 0         **AD1MD:** ADC1 Module Disable bit<sup>(1)</sup>  
              1 = ADC1 module is disabled  
              0 = ADC1 module is enabled

**Note 1:** PCFGx bits have no effect if the ADC module is disabled by setting this bit. In this case, all port pins multiplexed with ANx will be in Digital mode.

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 10.0 I/O PORTS

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 10. “I/O Ports”** (DS70193) of the “dsPIC33F/PIC24H Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

All of the device pins (except VDD, VSS, MCLR and OSC1/CLKI) are shared among the peripherals and the parallel I/O ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity.

### 10.1 Parallel I/O (PIO) Ports

A parallel I/O port that shares a pin with a peripheral is generally subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port

has ownership of the output data and control signals of the I/O pin. The logic also prevents “loop through”, in which a port's digital output can drive the input of a peripheral that shares the same pin. **Figure 10-1** shows how ports are shared with other peripherals and the associated I/O pin to which they are connected.

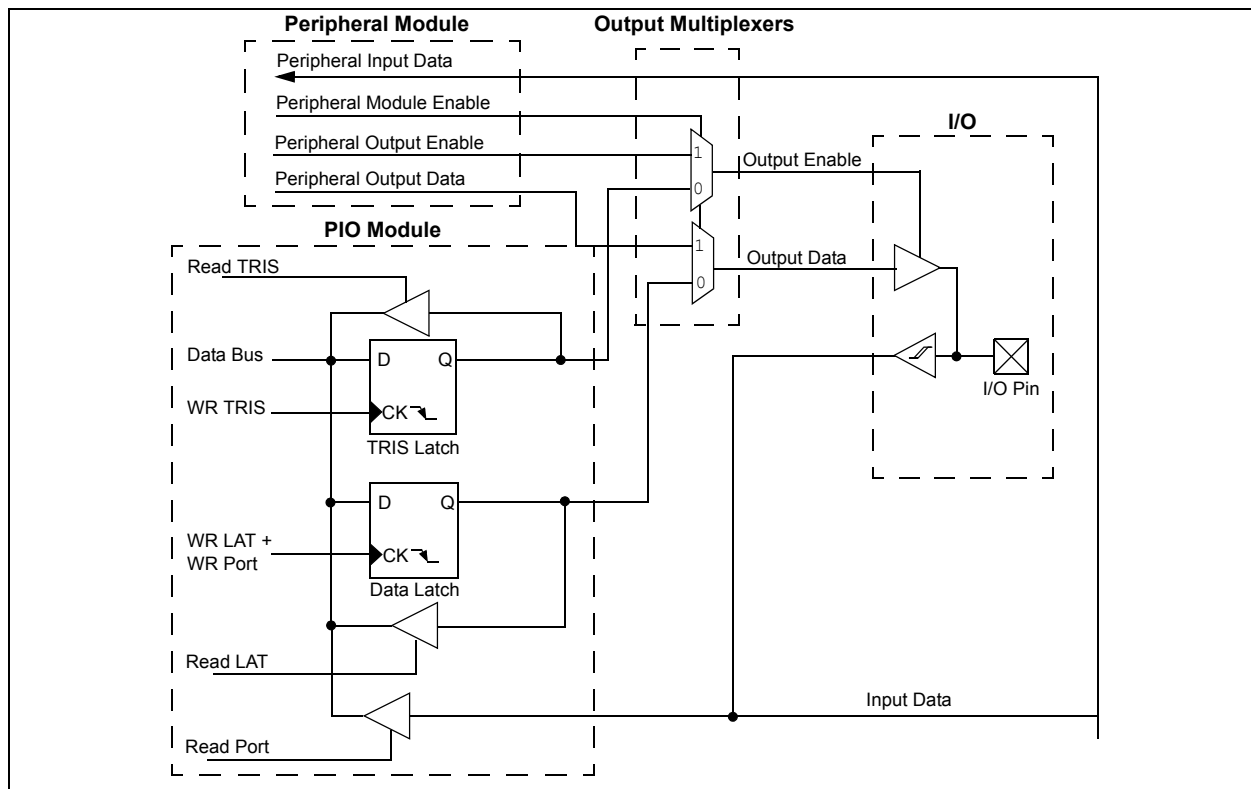
When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin can be read, but the output driver for the parallel port bit is disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin can be driven by a port.

All port pins have three registers directly associated with their operation as digital I/O. The data direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a ‘1’, then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx) read the latch. Writes to the latch, write the latch. Reads from the port (PORTx) read the port pins, while writes to the port pins write the latch.

Any bit and its associated data and control registers that are not valid for a particular device will be disabled. That means the corresponding LATx and TRISx registers and the port pin will read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless regarded as a dedicated port because there is no other competing source of outputs.

**FIGURE 10-1: BLOCK DIAGRAM OF A TYPICAL SHARED PORT STRUCTURE**



# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## REGISTER 10-8: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SCK1R<4:0>				
bit 15							
			bit 8				

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SDI1R<4:0>				
bit 7							
			bit 0				

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13      **Unimplemented:** Read as '0'

bit 12-8      **SCK1R<4:0>:** Assign SPI 1 Clock Input (SCK1IN) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•  
•  
•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5      **Unimplemented:** Read as '0'

bit 4-0      **SDI1R<4:0>:** Assign SPI 1 Data Input (SDI1) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•  
•  
•

00001 = Input tied to RP1

00000 = Input tied to RP0

## dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 11.0 TIMER1

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 11. “Timers”** (DS70205) of the *“dsPIC33F/PIC24H Family Reference Manual”*, which is available from the Microchip web site: ([www.microchip.com](http://www.microchip.com)).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to [Section 4.0 “Memory Organization”](#) in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the real-time clock, or operate as a free-running interval timer/counter. Timer1 can operate in three modes:

- 16-bit Timer
- 16-bit Synchronous Counter
- 16-bit Asynchronous Counter

Timer1 also supports these features:

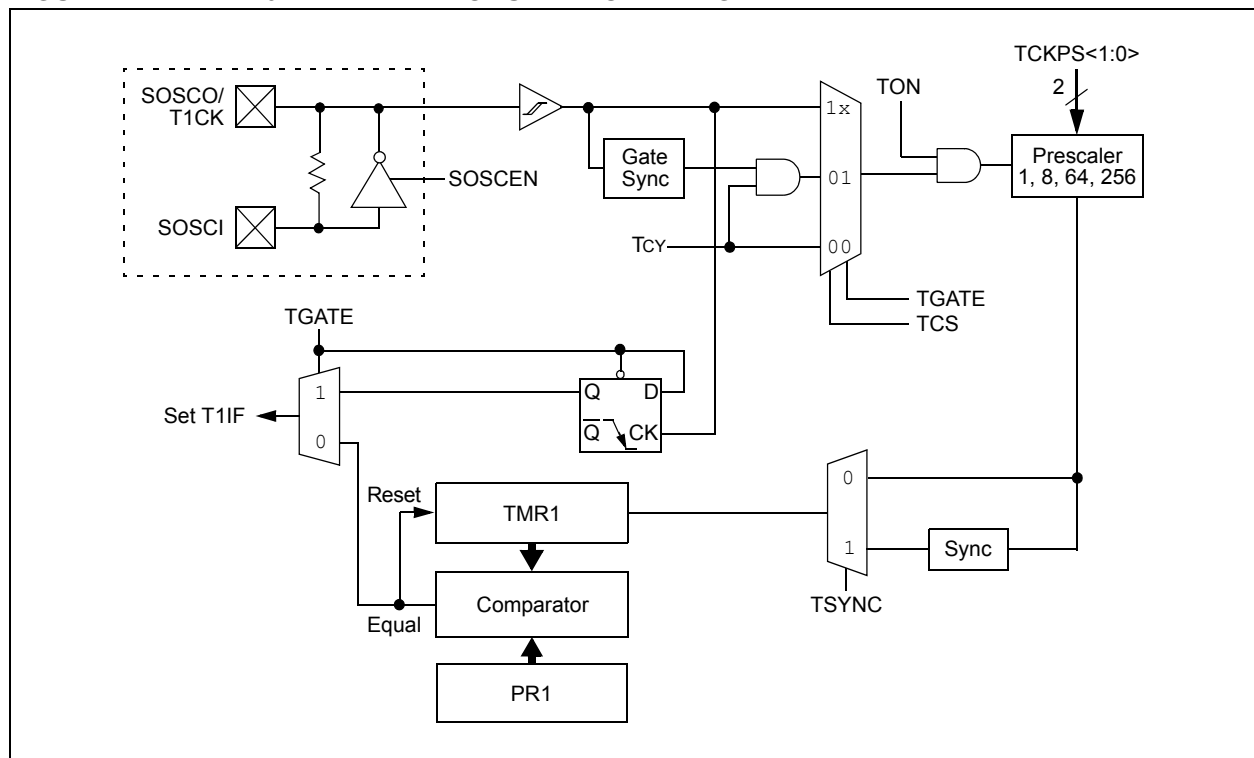
- Timer gate operation
- Selectable prescaler settings
- Timer operation during CPU Idle and Sleep modes
- Interrupt on 16-bit Period register match or falling edge of external gate signal

Figure 11-1 illustrates a block diagram of the 16-bit timer module.

To configure Timer1 for operation:

1. Set the TON bit (= 1) in the T1CON register.
2. Select the timer prescaler ratio using the TCKPS<1:0> bits in the T1CON register.
3. Set the Clock and Gating modes using the TCS and TGATE bits in the T1CON register.
4. Set or clear the TSYNC bit in the T1CON register to select synchronous or asynchronous operation.
5. Load the timer period value into the PR1 register.
6. If interrupts are required, set the interrupt enable bit, T1IE. Use the priority bits, T1IP<2:0>, to set the interrupt priority.

**FIGURE 11-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM**



# **dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304**

---

NOTES:

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## REGISTER 15-3: SPIxCON2: SPIx CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
FRMEN	SPIFSD	FRMPOL	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0
—	—	—	—	—	—	FRMDLY	—
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **FRMEN:** Framed SPIx Support bit  
1 = Framed SPIx support enabled ( $\overline{\text{SSx}}$  pin used as frame sync pulse input/output)  
0 = Framed SPIx support disabled
- bit 14      **SPIFSD:** Frame Sync Pulse Direction Control bit  
1 = Frame sync pulse input (slave)  
0 = Frame sync pulse output (master)
- bit 13      **FRMPOL:** Frame Sync Pulse Polarity bit  
1 = Frame sync pulse is active-high  
0 = Frame sync pulse is active-low
- bit 12-2    **Unimplemented:** Read as '0'
- bit 1      **FRMDLY:** Frame Sync Pulse Edge Select bit  
1 = Frame sync pulse coincides with first bit clock  
0 = Frame sync pulse precedes first bit clock
- bit 0      **Unimplemented:** This bit must not be set to '1' by the user application

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

---

## 17.1 UART Helpful Tips

1. In multi-node direct-connect UART networks, UART receive inputs react to the complementary logic level defined by the URXINV bit (UxMODE<4>), which defines the idle state, the default of which is logic high, (i.e., URXINV = 0). Because remote devices do not initialize at the same time, it is likely that one of the devices, because the RX line is floating, will trigger a start bit detection and will cause the first byte received after the device has been initialized to be invalid. To avoid this situation, the user should use a pull-up or pull-down resistor on the RX pin depending on the value of the URXINV bit.
  - a) If URXINV = 0, use a pull-up resistor on the RX pin.
  - b) If URXINV = 1, use a pull-down resistor on the RX pin.
2. The first character received on a wake-up from Sleep mode caused by activity on the UxRX pin of the UART module will be invalid. In Sleep mode, peripheral clocks are disabled. By the time the oscillator system has restarted and stabilized from Sleep mode, the baud rate bit sampling clock relative to the incoming UxRX bit timing is no longer synchronized, resulting in the first character being invalid. This is to be expected.

## 17.2 UART Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](#), contains the latest updates and additional information.

<b>Note:</b> In the event you are not able to access the product page using the link above, enter this URL in your browser: <a href="http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en530331">http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en530331</a>
--

### 17.2.1 KEY RESOURCES

- **Section 17. “UART”** (DS70188)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 18.0 10-BIT/12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 16. “Analog-to-Digital Converter (ADC)”** (DS70183) of the “dsPIC33F/PIC24H Family Reference Manual”, which is available on the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 devices have up to 13 Analog-to-Digital Conversion (ADC) module input channels.

The AD12B bit (AD1CON1<10>) allows each of the ADC modules to be configured as either a 10-bit, 4-sample-and-hold ADC (default configuration) or a 12-bit, 1-sample-and-hold ADC.

**Note:** The ADC module must be disabled before the AD12B bit can be modified.

### 18.1 Key Features

The 10-bit ADC configuration has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 1.1 Msps
- Up to 13 analog input pins
- External voltage reference input pins
- Simultaneous sampling of up to four analog input pins
- Automatic Channel Scan mode
- Selectable conversion trigger source
- Selectable Buffer Fill modes
- Four result alignment options (signed/unsigned, fractional/integer)
- Operation during CPU Sleep and Idle modes
- 16-word conversion result buffer

The 12-bit ADC configuration supports all the above features, except:

- In the 12-bit configuration, conversion speeds of up to 500 ksps are supported.
- There is only one sample and hold (S/H) amplifier in the 12-bit configuration, so simultaneous sampling of multiple channels is not supported.

Depending on the particular device pinout, the ADC can have up to 13 analog input pins, designated AN0 through AN12. In addition, there are two analog input pins for external voltage reference connections. These voltage reference inputs can be shared with other analog input pins.

The actual number of analog input pins and external voltage reference input configuration will depend on the specific device. Refer to the specific device data sheet for further details.

A block diagram of the ADC for the dsPIC33FJ16GP304 and dsPIC33FJ32GP204 devices is shown in [Figure 18-1](#). A block diagram of the ADC for the dsPIC33FJ32GP202 device is shown in [Figure 18-2](#).

### 18.2 ADC Initialization

To configure the ADC module:

1. Select port pins as analog inputs (AD1PCFGH<15:0> or AD1PCFGL<15:0>).
2. Select voltage reference source to match expected range on analog inputs (AD1CON2<15:13>).
3. Select the analog conversion clock to match desired data rate with processor clock (AD1CON3<7:0>).
4. Determine how many sample-and-hold channels will be used (AD1CON2<9:8> and AD1PCFGH<15:0> or AD1PCFGL<15:0>).
5. Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
6. Select the way conversion results are presented in the buffer (AD1CON1<9:8>).
  - c) Turn on the ADC module (AD1CON1<15>).
7. Configure ADC interrupt (if required):
  - a) Clear the AD1IF bit.
  - b) Select ADC interrupt priority.

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

**TABLE 20-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
29	DIV	DIV.S Wm, Wn	Signed 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.SD Wm, Wn	Signed 32/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.U Wm, Wn	Unsigned 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.UD Wm, Wn	Unsigned 32/16-bit Integer Divide	1	18	N,Z,C,OV
30	DIVF	DIVF Wm, Wn	Signed 16/16-bit Fractional Divide	1	18	N,Z,C,OV
31	DO	DO #lit14, Expr	Do code to PC + Expr, lit14 + 1 times	2	2	None
		DO Wn, Expr	Do code to PC + Expr, (Wn) + 1 times	2	2	None
32	ED	ED Wm*Wm, Acc, Wx, Wy, Wxd	Euclidean Distance (no accumulate)	1	1	OA,OB,OAB,SA,SB,SAB
33	EDAC	EDAC Wm*Wm, Acc, Wx, Wy, Wxd	Euclidean Distance	1	1	OA,OB,OAB,SA,SB,SAB
34	EXCH	EXCH Wns, Wnd	Swap Wns with Wnd	1	1	None
35	FBCL	FBCL Ws, Wnd	Find Bit Change from Left (MSb) Side	1	1	C
36	FF1L	FF1L Ws, Wnd	Find First One from Left (MSb) Side	1	1	C
37	FF1R	FF1R Ws, Wnd	Find First One from Right (LSb) Side	1	1	C
38	GOTO	GOTO Expr	Go to address	2	2	None
		GOTO Wn	Go to indirect	1	2	None
39	INC	INC f	f = f + 1	1	1	C,DC,N,OV,Z
		INC f, WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		INC Ws, Wd	Wd = Ws + 1	1	1	C,DC,N,OV,Z
40	INC2	INC2 f	f = f + 2	1	1	C,DC,N,OV,Z
		INC2 f, WREG	WREG = f + 2	1	1	C,DC,N,OV,Z
		INC2 Ws, Wd	Wd = Ws + 2	1	1	C,DC,N,OV,Z
41	IOR	IOR f	f = f.IOR. WREG	1	1	N,Z
		IOR f, WREG	WREG = f.IOR. WREG	1	1	N,Z
		IOR #lit10, Wn	Wd = lit10.IOR. Wd	1	1	N,Z
		IOR Wb, Ws, Wd	Wd = Wb.IOR. Ws	1	1	N,Z
		IOR Wb, #lit5, Wd	Wd = Wb.IOR. lit5	1	1	N,Z
42	LAC	LAC Wso, #Slit4, Acc	Load Accumulator	1	1	OA,OB,OAB,SA,SB,SAB
43	LNK	LNK #lit14	Link Frame Pointer	1	1	None
44	LSR	LSR f	f = Logical Right Shift f	1	1	C,N,OV,Z
		LSR f, WREG	WREG = Logical Right Shift f	1	1	C,N,OV,Z
		LSR Ws, Wd	Wd = Logical Right Shift Ws	1	1	C,N,OV,Z
		LSR Wb, Wns, Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N,Z
		LSR Wb, #lit5, Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N,Z
45	MAC	MAC Wm*Wn, Acc, Wx, Wxd, Wy, Wyd, AWB	Multiply and Accumulate	1	1	OA,OB,OAB,SA,SB,SAB
		MAC Wm*Wm, Acc, Wx, Wxd, Wy, Wyd	Square and Accumulate	1	1	OA,OB,OAB,SA,SB,SAB
46	MOV	MOV f, Wn	Move f to Wn	1	1	None
		MOV f	Move f to f	1	1	N,Z
		MOV f, WREG	Move f to WREG	1	1	None
		MOV #lit16, Wn	Move 16-bit literal to Wn	1	1	None
		MOV.b #lit8, Wn	Move 8-bit literal to Wn	1	1	None
		MOV Wn, f	Move Wn to f	1	1	None
		MOV Wso, Wdo	Move Ws to Wd	1	1	None
		MOV WREG, f	Move WREG to f	1	1	None
		MOV.D Wns, Wd	Move Double from W(ns):W(ns + 1) to Wd	1	2	None
		MOV.D Ws, Wnd	Move Double from Ws to W(nd + 1):W(nd)	1	2	None
47	MOVSAC	MOVSAC Acc, Wx, Wxd, Wy, Wyd, AWB	Prefetch and store accumulator	1	1	None

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

## 22.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304 family are listed below. Exposure to these maximum rating conditions for extended periods can affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

### Absolute Maximum Ratings<sup>(1)</sup>

Ambient temperature under bias .....	-40°C to +125°C
Storage temperature .....	-65°C to +160°C
Voltage on VDD with respect to VSS .....	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to VSS <sup>(4)</sup> .....	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to VSS when VDD ≥ 3.0V <sup>(4)</sup> .....	-0.3V to +5.6V
Voltage on any 5V tolerant pin with respect to VSS when VDD < 3.0V <sup>(4)</sup> .....	-0.3V to 3.6V
Maximum current out of VSS pin .....	300 mA
Maximum current into VDD pin <sup>(2)</sup> .....	250 mA
Maximum current sourced/sunk by any 2x I/O pin <sup>(3)</sup> .....	8 mA
Maximum current sourced/sunk by any 4x I/O pin <sup>(3)</sup> .....	15 mA
Maximum current sourced/sunk by any 8x I/O pin <sup>(3)</sup> .....	25 mA
Maximum current sunk by all ports .....	200 mA
Maximum current sourced by all ports <sup>(2)</sup> .....	200 mA

**Note 1:** Stresses above those listed under “Absolute Maximum Ratings” can cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods can affect device reliability.

**2:** Maximum allowable current is a function of device maximum power dissipation (see [Table 22-2](#)).

**3:** Exceptions are CLKOUT, which is able to sink/source 25 mA, and the VREF+, VREF-, SCLx, SDAX, PGECx and PGEDx pins, which are able to sink/source 12 mA.

**4:** Refer to the “[Pin Diagrams](#)” section for 5V tolerant pins.

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

**TABLE 22-7: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)**

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature    -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended		
Parameter No. <sup>(5)</sup>	Typical <sup>(2)</sup>	Max	Units	Conditions	
Power-Down Current (IPD) <sup>(1)</sup>					
DC60d	55	500	μA	-40°C	3.3V      Base Power-Down Current <sup>(3,4)</sup>
DC60a	63	300	μA	+25°C	
DC60b	85	350	μA	+85°C	
DC60c	146	600	μA	+125°C	
DC61d	8	15	μA	-40°C	3.3V      Watchdog Timer Current: ΔIWD <sup>(3,5)</sup>
DC61a	2	3	μA	+25°C	
DC61b	2	2	μA	+85°C	
DC61c	3	5	μA	+125°C	

**Note 1:** IPD (Sleep) current is measured as follows:

- CPU core is off, oscillator is configured in EC mode and external clock active, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)
- CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to VSS
- MCLR = VDD, WDT and FSCM are disabled, all peripheral modules are disabled (PMDx bits are all ones)
- VREGS bit (RCON<8>) = 0 (i.e., core regulator is set to stand-by while the device is in Sleep mode)
- RTCC is disabled.
- JTAG is disabled

**2:** Data in the “Typ” column is at 3.3V, +25°C unless otherwise stated.

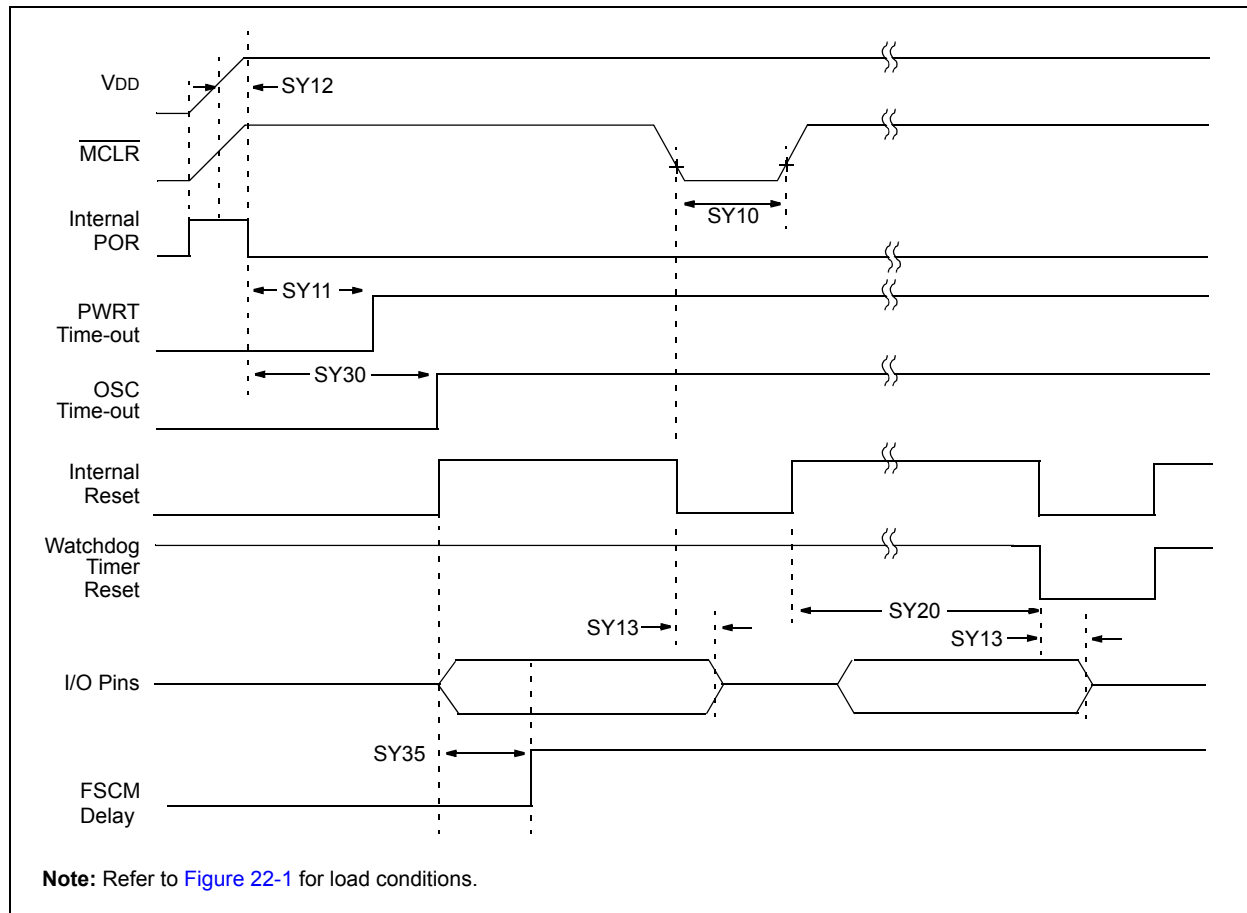
**3:** The Watchdog Timer Current is the additional current consumed when the WDT module is enabled. This current should be added to the base IPD current.

**4:** These currents are measured on the device containing the most memory in this family.

**5:** These parameters are characterized, but are not tested in manufacturing.

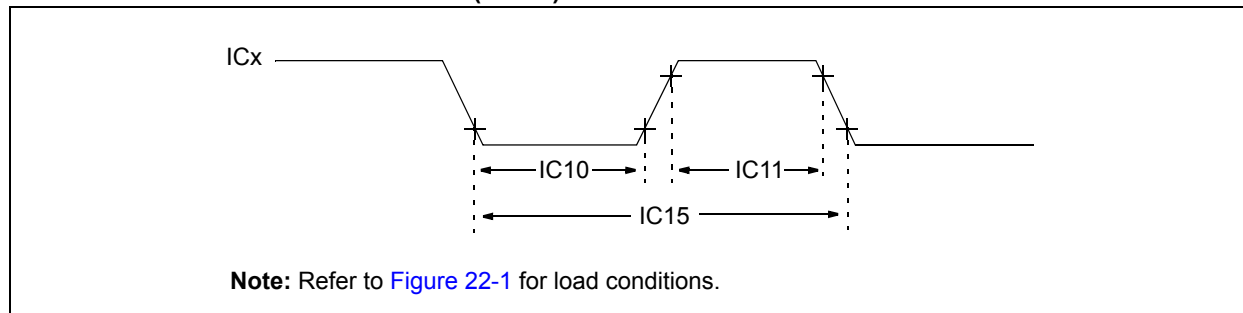
# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

**FIGURE 22-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS**



# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

**FIGURE 22-6: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS**

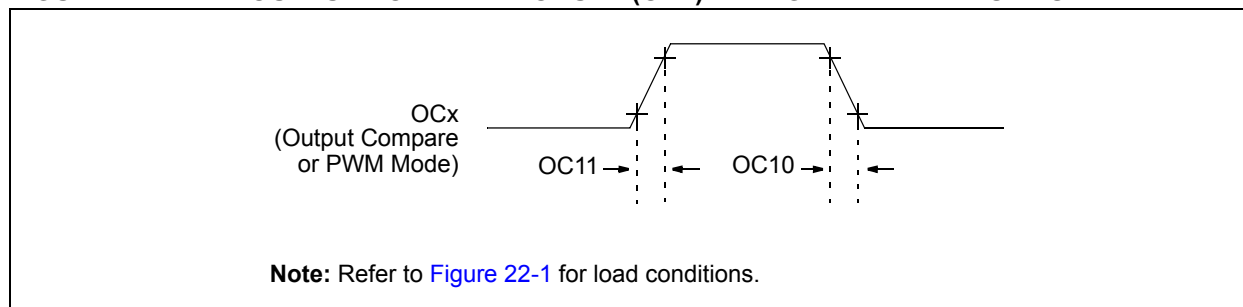


**TABLE 22-25: INPUT CAPTURE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Max	Units	Conditions
IC10	TccL	ICx Input Low Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	—
			With Prescaler	10	—	ns	
IC11	TccH	ICx Input High Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	—
			With Prescaler	10	—	ns	
IC15	TccP	ICx Input Period		$(T_{CY} + 40)/N$	—	ns	N = prescale value (1, 4, 16)

**Note 1:** These parameters are characterized but not tested in manufacturing.

**FIGURE 22-7: OUTPUT COMPARE MODULE (OCx) TIMING CHARACTERISTICS**



**TABLE 22-26: OUTPUT COMPARE MODULE TIMING REQUIREMENTS**

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
OC10	TccF	OCx Output Fall Time	—	—	—	ns	See parameter D032
OC11	TccR	OCx Output Rise Time	—	—	—	ns	See parameter D031

**Note 1:** These parameters are characterized but not tested in manufacturing.

FIGURE 24-9: TYPICAL I<sub>PD</sub> CURRENT @ V<sub>DD</sub> = 3.3V, +85°C

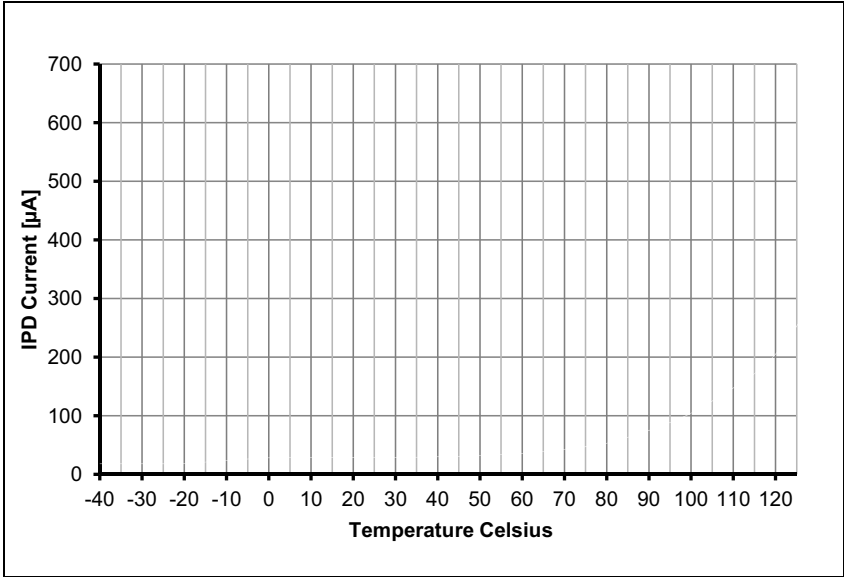


FIGURE 24-10: TYPICAL I<sub>DD</sub> CURRENT @ V<sub>DD</sub> = 3.3V, +85°C

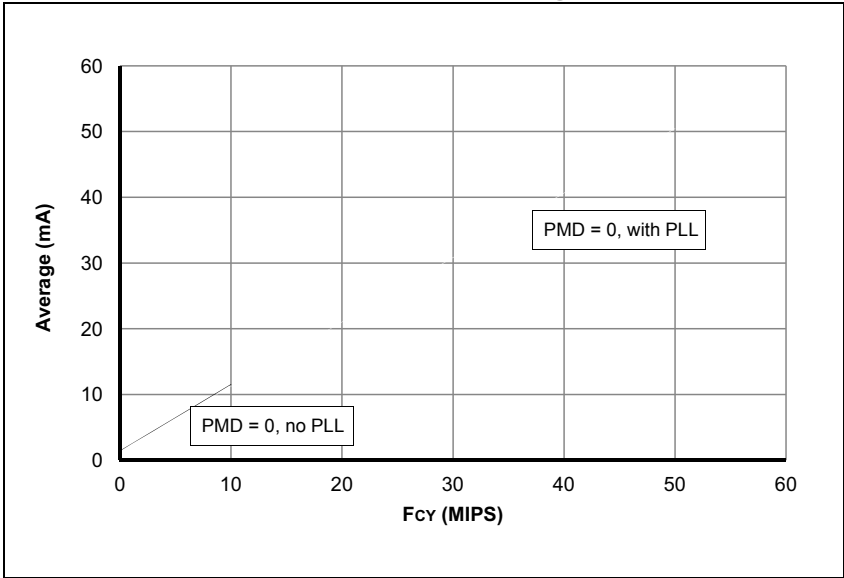


FIGURE 24-11: TYPICAL I<sub>DOZE</sub> CURRENT @ V<sub>DD</sub> = 3.3V, +85°C

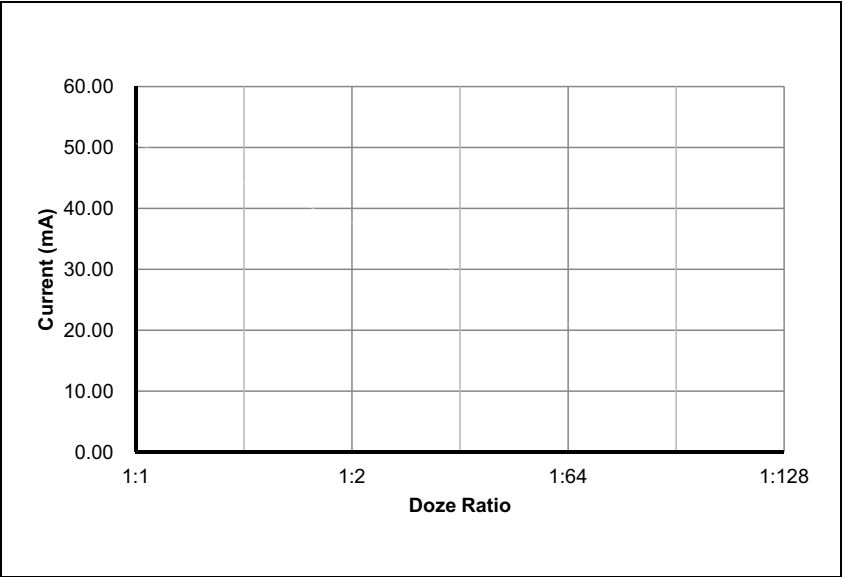
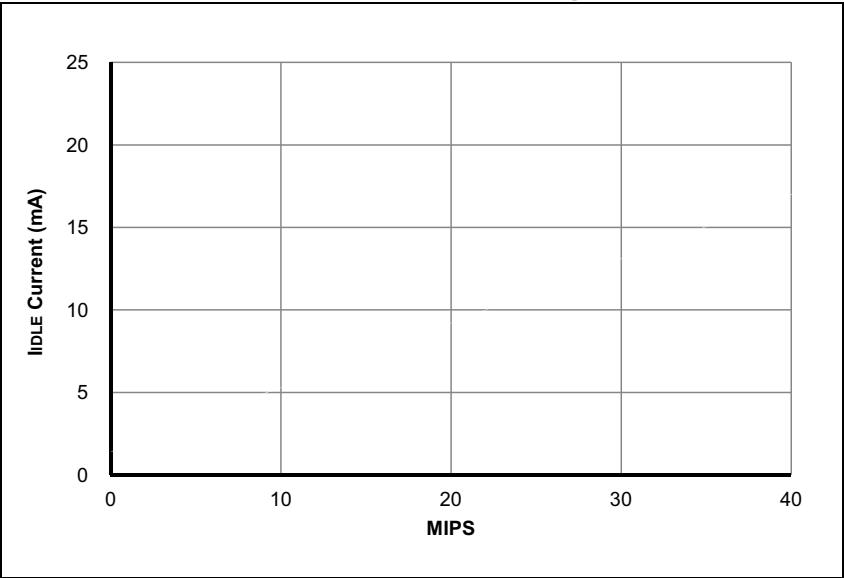


FIGURE 24-12: TYPICAL I<sub>IDLE</sub> CURRENT @ V<sub>DD</sub> = 3.3V, +85°C



# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

**TABLE A-1: MAJOR SECTION UPDATES (CONTINUED)**

Section Name	Update Description
<b>Section 14.0 “Serial Peripheral Interface (SPI)”</b>	<p>Removed the following sections, which are now available in the related section of the dsPIC33F/PIC24H Family Reference Manual:</p> <ul style="list-style-type: none"> <li>• 14.1 “Interrupts”</li> <li>• 14.2 “Receive Operations”</li> <li>• 14.3 “Transmit Operations”</li> <li>• 14.4 “SPI Setup” (retained Figure 14-1: SPI Module Block Diagram)</li> </ul>
<b>Section 15.0 “Inter-Integrated Circuit (I<sup>2</sup>C™)”</b>	<p>Removed the following sections, which are now available in the related section of the dsPIC33F/PIC24H Family Reference Manual:</p> <ul style="list-style-type: none"> <li>• 15.3 “I<sup>2</sup>C Interrupts”</li> <li>• 15.4 “Baud Rate Generator” (retained Figure 15-1: I<sup>2</sup>C Block Diagram)</li> <li>• 15.5 “I<sup>2</sup>C Module Addresses”</li> <li>• 15.6 “Slave Address Masking”</li> <li>• 15.7 “IPMI Support”</li> <li>• 15.8 “General Call Address Support”</li> <li>• 15.9 “Automatic Clock Stretch”</li> <li>• 15.10 “Software Controlled Clock Stretching (STREN = 1)”</li> <li>• 15.11 “Slope Control”</li> <li>• 15.12 “Clock Arbitration”</li> <li>• 15.13 “Multi-Master Communication, Bus Collision, and Bus Arbitration”</li> <li>• 15.14 “Peripheral Pin Select Limitations”</li> </ul>
<b>Section 16.0 “Universal Asynchronous Receiver Transmitter (UART)”</b>	<p>Removed the following sections, which are now available in the related section of the dsPIC33F/PIC24H Family Reference Manual:</p> <ul style="list-style-type: none"> <li>• 16.1 “UART Baud Rate Generator”</li> <li>• 16.2 “Transmitting in 8-bit Data Mode”</li> <li>• 16.3 “Transmitting in 9-bit Data Mode”</li> <li>• 16.4 “Break and Sync Transmit Sequence”</li> <li>• 16.5 “Receiving in 8-bit or 9-bit Data Mode”</li> <li>• 16.6 “Flow Control Using <math>\overline{UxCTS}</math> and <math>\overline{UxRTS}</math> Pins”</li> <li>• 16.7 “Infrared Support”</li> </ul> <p>Removed IrDA references and Note 1, and updated the bit and bit value descriptions for UTXINV (UxSTA&lt;14&gt;) in the UARTx Status and Control Register (see Register 16-2).</p>
<b>Section 17.0 “10-bit/12-bit Analog-to-Digital Converter (ADC)”</b>	<p>Removed Equation 17-1: ADC Conversion Clock Period and Figure 17-2: ADC Transfer Function (10-Bit Example).</p> <p>Added ADC1 Module Block Diagram for dsPIC33FJ16GP304 and dsPIC33FJ32GP204 Devices (Figure 18-1) and ADC1 Module Block Diagram FOR dsPIC33FJ32GP202 Devices (Figure 17-2).</p> <p>Added Note 2 to Figure 17-3: ADC Conversion Clock Period Block Diagram.</p> <p>Added device-specific information to Note 1 in the ADC1 Input Scan Select Register Low (see Register 17-6), and updated the default bit value for bits 12-10 (CSS12-CSS10) from U-0 to R/W-0.</p> <p>Added device-specific information to Note 1 in the ADC1 Port Configuration Register Low (see Register 17-7), and updated the default bit value for bits 12-10 (PCFG12-PCFG10) from U-0 to R/W-0.</p>

# dsPIC33FJ32GP202/204 and dsPIC33FJ16GP304

Registers .....	163
I <sup>2</sup> C Module	
I2C1 Register Map .....	38
In-Circuit Debugger .....	196
In-Circuit Emulation .....	189
In-Circuit Serial Programming (ICSP) .....	189, 196
Input Capture	
Registers .....	149
Input Change Notification .....	116
Instruction Addressing Modes .....	45
File Register Instructions .....	45
Fundamental Modes Supported .....	46
MAC Instructions .....	46
MCU Instructions .....	45
Move and Accumulator Instructions .....	46
Other Instructions .....	46
Instruction Set	
Overview .....	200
Summary .....	197
Instruction-Based Power-Saving Modes .....	109
Idle .....	110
Sleep .....	109
Internal RC Oscillator	
Use with WDT .....	194
Internet Address .....	295
Interrupt Control and Status Registers .....	74
IECx .....	74
IFSx .....	74
INTCON1 .....	74
INTCON2 .....	74
IPCx .....	74
Interrupt Setup Procedures .....	96
Initialization .....	96
Interrupt Disable .....	96
Interrupt Service Routine .....	96
Trap Service Routine .....	96
Interrupt Vector Table (IVT) .....	71
Interrupts Coincident with Power Save Instructions .....	110
<b>J</b>	
JTAG Boundary Scan Interface .....	189
<b>M</b>	
Memory Organization .....	29
Microchip Internet Web Site .....	295
Modulo Addressing .....	47
Applicability .....	48
Operation Example .....	47
Start and End Address .....	47
W Address Register Selection .....	47
MPLAB ASM30 Assembler, Linker, Librarian .....	206
MPLAB Integrated Development Environment Software .....	205
MPLAB PM3 Device Programmer .....	208
MPLAB REAL ICE In-Circuit Emulator System .....	207
MPLINK Object Linker/MPLIB Object Librarian .....	206
<b>N</b>	
NVM Module	
Register Map .....	44
<b>O</b>	
Open-Drain Configuration .....	116
Output Compare .....	151
Registers .....	154

<b>P</b>	
Packaging .....	267
Details .....	269
Marking .....	267, 268
Peripheral Module Disable (PMD) .....	110
Pinout I/O Descriptions (table) .....	11
PMD Module	
Register Map .....	44
PORTA	
Register Map .....	43
PORTB	
Register Map .....	43
Power-on Reset (POR) .....	67
Power-Saving Features .....	109
Clock Frequency and Switching .....	109
Program Address Space .....	29
Construction .....	50
Data Access from Program Memory Using	
Program Space Visibility .....	53
Data Access from Program Memory Using	
Table Instructions .....	52
Data Access from, Address Generation .....	51
Memory Map .....	29
Table Read Instructions	
TBLRDH .....	52
TBLRDL .....	52
Visibility Operation .....	53
Program Memory	
Interrupt Vector .....	30
Organization .....	30
Reset Vector .....	30
<b>R</b>	
Reader Response .....	296
Registers	
AD1CHS0 (ADC1 Input Channel 0 Select) .....	185
AD1CHS123 (ADC1 Input Channel 1, 2, 3 Select) .....	183
AD1CON1 (ADC1 Control 1) .....	179
AD1CON2 (ADC1 Control 2) .....	181
AD1CON3 (ADC1 Control 3) .....	182
AD1CSSL (ADC1 Input Scan Select Low) .....	187
AD1PCFGL (ADC1 Port Configuration Low) .....	187
CLKDIV (Clock Divisor) .....	103
CORCON (Core Control) .....	23, 75
I2CxCON (I2Cx Control) .....	164
I2CxMSK (I2Cx Slave Mode Address Mask) .....	168
I2CxSTAT (I2Cx Status) .....	166
ICxCON (Input Capture x Control) .....	149
IEC0 (Interrupt Enable Control 0) .....	83, 85, 86
IFS0 (Interrupt Flag Status 0) .....	79
IFS1 (Interrupt Flag Status 1) .....	81
IFS4 (Interrupt Flag Status 4) .....	82
INTCON1 (Interrupt Control 1) .....	76
INTCON2 (Interrupt Control 2) .....	78
INTTREG Interrupt Control and Status Register .....	95
IPC0 (Interrupt Priority Control 0) .....	87
IPC1 (Interrupt Priority Control 1) .....	88
IPC16 (Interrupt Priority Control 16) .....	94
IPC2 (Interrupt Priority Control 2) .....	89
IPC3 (Interrupt Priority Control 3) .....	90
IPC4 (Interrupt Priority Control 4) .....	91
IPC5 (Interrupt Priority Control 5) .....	92
IPC7 (Interrupt Priority Control 7) .....	93
NVMCOM (Flash Memory Control) .....	57, 58
OCxCON (Output Compare x Control) .....	154
OSCCON (Oscillator Control) .....	101