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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 11x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1936-i-ml

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

NOTES:

3.1.1.2 Indirect Read with FSR

The program memory can be accessed as data by setting bit 7 of the FSRxH register and reading the matching INDFx register. The MOVIW instruction will place the lower 8 bits of the addressed word in the W register. Writes to the program memory cannot be performed via the INDF registers. Instructions that access the program memory via the FSR require one extra instruction cycle to complete. Example 3-2 demonstrates accessing the program memory via an FSR.

The HIGH directive will set bit<7> if a label points to a location in program memory.

EXAMPLE 3-2: ACCESSING PROGRAM MEMORY VIA FSR

constants			
RETLW	DATA0	;Index0	data
RETLW	DATA1	;Index1	data
RETLW	DATA2		
RETLW	DATA3		
my_functi	on		
; LO	IS OF CODE.		
MOVLW	LOW cons	tants	
MOVWF	FSR1L		
MOVLW	HIGH con	stants	
MOVWF	FSR1H		
MOVIW	0[FSR1]		
;THE PROG	RAM MEMORY	IS IN W	

3.2 Data Memory Organization

The data memory is partitioned in 32 memory banks with 128 bytes in a bank. Each bank consists of (Figure 3-3):

- 12 core registers
- 20 Special Function Registers (SFR)
- Up to 80 bytes of General Purpose RAM (GPR)
- 16 bytes of common RAM

The active bank is selected by writing the bank number into the Bank Select Register (BSR). Unimplemented memory will read as '0'. All data memory can be accessed either directly (via instructions that use the file registers) or indirectly via the two File Select Registers (FSR). See **Section 3.5** "Indirect Addressing" for more information.

3.2.1 CORE REGISTERS

The core registers contain the registers that directly affect the basic operation of the PIC16(L)F1934/6/7. These registers are listed below:

- INDF0
- INDF1
- PCL
- STATUS
- FSR0 Low
- FSR0 High
- FSR1 Low
- FSR1 High
- BSR
- WREG
- PCLATH
- INTCON

Note: The core registers are the first 12 addresses of every data memory bank.

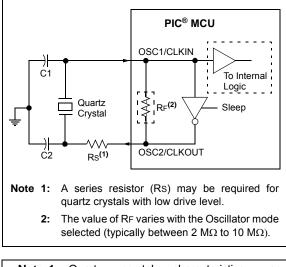
REGISTER 4-1: CONFIGURATION WORD 1

R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1			
FCMEN	IESO	CLKOUTEN	BOREN1	BOREN0	CPD	CP			
oit 13		·	•			bit			
R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1	R/P-1/1			
MCLRE	PWRTE	WDTE1	WDTE0	FOSC2	FOSC1	FOSC0			
bit 6						bit			
Legend:									
R = Readable bit		P = Programmab	le bit	U = Unimplemente	ed bit_read as '1'				
'0' = Bit is cleared		'1' = Bit is set		•	lank or after Bulk E	rase			
bit is cleared		1 Dit io oct							
bit 13	1 = Fail-Safe Clo	fe Clock Monitor En ock Monitor is enable ock Monitor is disabl	ed						
bit 12	1 = Internal/Exte	xternal Switchover b rnal Switchover moo rnal Switchover moo	de is enabled						
bit 11	1 = CLKOUT fu	ock Out Enable bit nction is disabled. I nction is enabled or		ction on RA6/CLKOU	JT				
bit 10-9	11 = BOR enable 10 = BOR enable	BOREN<1:0>: Brown-out Reset Enable bits ⁽¹⁾ 11 = BOR enabled 10 = BOR enabled during operation and disabled in Sleep 01 = BOR controlled by SBOREN bit of the PCON register 00 = BOR disabled							
bit 8		Protection bit ⁽²⁾ y code protection is y code protection is							
bit 7	-	tion bit ⁽³⁾ mory code protectio mory code protectio							
bit 6	MCLRE: RE3/MG If LVP bit = 1: This bit is igr If LVP bit = 0: 1 = RE3/MC	CLR/VPP Pin Function	on Select bit is MCLR ; Wea <u>k pul</u>	I-up enabled. R internally disabled;	Weak pull-up unde	r control of WPUE			
bit 5	bit PWRTE: Power- 1 = PWRT disal 0 = PWRT enab		(1)						
bit 4-3	WDTE<1:0>: Wa 11 = WDT enabl 10 = WDT enabl	atchdog Timer Enab	d disabled in Slee						

3: The entire program memory will be erased when the code protection is turned off.

FIGURE 5-3:

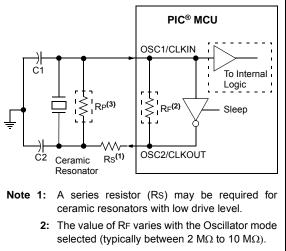
QUARTZ CRYSTAL OPERATION (LP, XT OR HS MODE)



- Note 1: Quartz crystal characteristics vary according to type, package and manufacturer. The user should consult the manufacturer data sheets for specifications and recommended application.
 - **2:** Always verify oscillator performance over the VDD and temperature range that is expected for the application.
 - **3:** For oscillator design assistance, reference the following Microchip Applications Notes:
 - AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC[®] and PIC[®] Devices" (DS00826)
 - AN849, "Basic PIC[®] Oscillator Design" (DS00849)
 - AN943, "Practical PIC[®] Oscillator Analysis and Design" (DS00943)
 - AN949, "Making Your Oscillator Work" (DS00949)

FIGURE 5-4: CERAMIC RESONATOR OPERATION

(XT OR HS MODE)



3: An additional parallel feedback resistor (RP) may be required for proper ceramic resonator operation.

5.2.1.3 Oscillator Start-up Timer (OST)

If the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) counts 1024 oscillations from OSC1. This occurs following a Power-on Reset (POR) and when the Power-up Timer (PWRT) has expired (if configured), or a wake-up from Sleep. During this time, the program counter does not increment and program execution is suspended. The OST ensures that the oscillator circuit, using a quartz crystal resonator or ceramic resonator, has started and is providing a stable system clock to the oscillator module.

In order to minimize latency between external oscillator start-up and code execution, the Two-Speed Clock Start-up mode can be selected (see **Section 5.4 "Two-Speed Clock Start-up Mode"**).

5.2.1.4 4X PLL

The oscillator module contains a 4X PLL that can be used with both external and internal clock sources to provide a system clock source. The input frequency for the 4X PLL must fall within specifications. See the PLL Clock Timing specifications in the applicable Electrical Specifications Chapter.

The 4X PLL may be enabled for use by one of two methods:

- 1. Program the PLLEN bit in Configuration Word 2 to a '1'.
- Write the SPLLEN bit in the OSCCON register to a '1'. If the PLLEN bit in Configuration Word 2 is programmed to a '1', then the value of SPLLEN is ignored.

5.2.2.3 Internal Oscillator Frequency Adjustment

The 500 kHz internal oscillator is factory calibrated. This internal oscillator can be adjusted in software by writing to the OSCTUNE register (Register 5-3). Since the HFINTOSC and MFINTOSC clock sources are derived from the 500 kHz internal oscillator a change in the OSCTUNE register value will apply to both.

The default value of the OSCTUNE register is '0'. The value is a 5-bit two's complement number. A value of 0Fh will provide an adjustment to the maximum frequency. A value of 10h will provide an adjustment to the minimum frequency.

When the OSCTUNE register is modified, the oscillator frequency will begin shifting to the new frequency. Code execution continues during this shift. There is no indication that the shift has occurred.

OSCTUNE does not affect the LFINTOSC frequency. Operation of features that depend on the LFINTOSC clock source frequency, such as the Power-up Timer (PWRT), Watchdog Timer (WDT), Fail-Safe Clock Monitor (FSCM) and peripherals, are *not* affected by the change in frequency.

5.2.2.4 LFINTOSC

The Low-Frequency Internal Oscillator (LFINTOSC) is an uncalibrated 31 kHz internal clock source.

The output of the LFINTOSC connects to a postscaler and multiplexer (see Figure 5-1). Select 31 kHz, via software, using the IRCF<3:0> bits of the OSCCON register. See **Section 5.2.2.7** "Internal Oscillator **Clock Switch Timing**" for more information. The LFINTOSC is also the frequency for the Power-up Timer (PWRT), Watchdog Timer (WDT) and Fail-Safe Clock Monitor (FSCM).

The LFINTOSC is enabled by selecting 31 kHz (IRCF<3:0> bits of the OSCCON register = 000) as the system clock source (SCS bits of the OSCCON register = 1x), or when any of the following are enabled:

- Configure the IRCF<3:0> bits of the OSCCON register for the desired LF frequency, and
- FOSC<2:0> = 100, or
- Set the System Clock Source (SCS) bits of the OSCCON register to '1x'

Peripherals that use the LFINTOSC are:

- Power-up Timer (PWRT)
- Watchdog Timer (WDT)
- Fail-Safe Clock Monitor (FSCM)

The Low-Frequency Internal Oscillator Ready bit (LFIOFR) of the OSCSTAT register indicates when the LFINTOSC is running and can be utilized.

5.2.2.5 Internal Oscillator Frequency Selection

The system clock speed can be selected via software using the Internal Oscillator Frequency Select bits IRCF<3:0> of the OSCCON register.

The output of the 16 MHz HFINTOSC and 31 kHz LFINTOSC connects to a postscaler and multiplexer (see Figure 5-1). The Internal Oscillator Frequency Select bits IRCF<3:0> of the OSCCON register select the frequency output of the internal oscillators. One of the following frequencies can be selected via software:

- 32 MHz (requires 4X PLL)
- 16 MHz
- 8 MHz
- 4 MHz
- 2 MHz
- 1 MHz
- 500 kHz (Default after Reset)
- 250 kHz
- 125 kHz
- 62.5 kHz
- 31.25 kHz
- 31 kHz (LFINTOSC)

Note:	Following any Reset, the IRCF<3:0> bits
	of the OSCCON register are set to '0111'
	and the frequency selection is set to
	500 kHz. The user can modify the IRCF
	bits to select a different frequency.

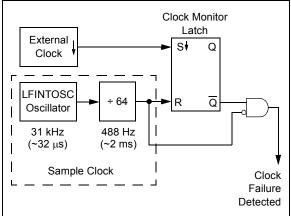
The IRCF<3:0> bits of the OSCCON register allow duplicate selections for some frequencies. These duplicate choices can offer system design trade-offs. Lower power consumption can be obtained when changing oscillator sources for a given frequency. Faster transition times can be obtained between frequency changes that use the same oscillator source.

FIGURE 5-7:	INTERNAL OSCILLATOR SWITCH TIMING
HEINTOSC/	SINTOSC (SOCH and WOY (Exabled) Otartup TimeCoycle Oycc
IRCF <3:0>	$\neq 0$ $\chi = 0$
System Clock	
NENNIOSCI L MENIIOSC	FINTOSC (Either FSCM of WDT snabled)
HFINTOSC/ MEINTOSC	2-2-2-2-2-2-2-2-2-2-2-2-2-2-2-2-2-2-2-
LFINTOSC -	
IRCF <3:0>	$\neq 0$ $X = 0$
System Clock	
LEINTOSO F LEINTOSO -	IFINTOSC/MFINTOSC
BEENTOSC/ MENTOSC	
\$PCF <3:0>	• 6 X # 0
System Crock	

5.5 Fail-Safe Clock Monitor

The Fail-Safe Clock Monitor (FSCM) allows the device to continue operating should the external oscillator fail. The FSCM can detect oscillator failure any time after the Oscillator Start-up Timer (OST) has expired. The FSCM is enabled by setting the FCMEN bit in the Configuration Word 1. The FSCM is applicable to all external Oscillator modes (LP, XT, HS, EC, Timer1 oscillator and RC).

FIGURE 5-9: FSCM BLOCK DIAGRAM



5.5.1 FAIL-SAFE DETECTION

The FSCM module detects a failed oscillator by comparing the external oscillator to the FSCM sample clock. The sample clock is generated by dividing the LFINTOSC by 64. See Figure 5-9. Inside the fail detector block is a latch. The external clock sets the latch on each falling edge of the external clock. The sample clock clears the latch on each rising edge of the sample clock. A failure is detected when an entire half-cycle of the sample clock elapses before the external clock goes low.

5.5.2 FAIL-SAFE OPERATION

When the external clock fails, the FSCM switches the device clock to an internal clock source and sets the bit flag OSFIF of the PIR2 register. Setting this flag will generate an interrupt if the OSFIE bit of the PIE2 register is also set. The device firmware can then take steps to mitigate the problems that may arise from a failed clock. The system clock will continue to be sourced from the internal clock source until the device firmware successfully restarts the external oscillator and switches back to external operation.

The internal clock source chosen by the FSCM is determined by the IRCF<3:0> bits of the OSCCON register. This allows the internal oscillator to be configured before a failure occurs.

5.5.3 FAIL-SAFE CONDITION CLEARING

The Fail-Safe condition is cleared after a Reset, executing a SLEEP instruction or changing the SCS bits of the OSCCON register. When the SCS bits are changed, the OST is restarted. While the OST is running, the device continues to operate from the INTOSC selected in OSCCON. When the OST times out, the Fail-Safe condition is cleared and the device will be operating from the external clock source. The Fail-Safe condition must be cleared before the OSFIF flag can be cleared.

5.5.4 RESET OR WAKE-UP FROM SLEEP

The FSCM is designed to detect an oscillator failure after the Oscillator Start-up Timer (OST) has expired. The OST is used after waking up from Sleep and after any type of Reset. The OST is not used with the EC or RC clock modes so that the FSCM will be active as soon as the Reset or wake-up has completed. When the FSCM is enabled, the Two-Speed Start-up is also enabled. Therefore, the device will always be executing code while the OST is operating.

Note: Due to the wide range of oscillator start-up times, the Fail-Safe circuit is not active during oscillator start-up (i.e., after exiting Reset or Sleep). After an appropriate amount of time, the user should check the Status bits in the OSCSTAT register to verify the oscillator start-up and that the system clock switchover has successfully completed.

11.3.2 ERASING FLASH PROGRAM MEMORY

While executing code, program memory can only be erased by rows. To erase a row:

- 1. Load the EEADRH:EEADRL register pair with the address of new row to be erased.
- 2. Clear the CFGS bit of the EECON1 register.
- 3. Set the EEPGD, FREE, and WREN bits of the EECON1 register.
- 4. Write 55h, then AAh, to EECON2 (Flash programming unlock sequence).
- 5. Set control bit WR of the EECON1 register to begin the erase operation.
- 6. Poll the FREE bit in the EECON1 register to determine when the row erase has completed.

See Example 11-4.

After the "BSF EECON1, WR" instruction, the processor requires two cycles to set up the erase operation. The user must place two NOP instructions after the WR bit is set. The processor will halt internal operations for the typical 2 ms erase time. This is not Sleep mode as the clocks and peripherals will continue to run. After the erase cycle, the processor will resume operation with the third instruction after the EECON1 write instruction.

11.3.3 WRITING TO FLASH PROGRAM MEMORY

Program memory is programmed using the following steps:

- 1. Load the starting address of the word(s) to be programmed.
- 2. Load the write latches with data.
- 3. Initiate a programming operation.
- 4. Repeat steps 1 through 3 until all data is written.

Before writing to program memory, the word(s) to be written must be erased or previously unwritten. Program memory can only be erased one row at a time. No automatic erase occurs upon the initiation of the write.

Program memory can be written one or more words at a time. The maximum number of words written at one time is equal to the number of write latches. See Figure 11-2 (block writes to program memory with 8 write latches) for more details. The write latches are aligned to the address boundary defined by EEADRL as shown in Table 11-1. Write operations do not cross these boundaries. At the completion of a program memory write operation, the write latches are reset to contain 0x3FFF. The following steps should be completed to load the write latches and program a block of program memory. These steps are divided into two parts. First, all write latches are loaded with data except for the last program memory location. Then, the last write latch is loaded and the programming sequence is initiated. A special unlock sequence is required to load a write latch with data or initiate a Flash programming operation. This unlock sequence should not be interrupted.

- 1. Set the EEPGD and WREN bits of the EECON1 register.
- 2. Clear the CFGS bit of the EECON1 register.
- Set the LWLO bit of the EECON1 register. When the LWLO bit of the EECON1 register is '1', the write sequence will only load the write latches and will not initiate the write to Flash program memory.
- 4. Load the EEADRH:EEADRL register pair with the address of the location to be written.
- 5. Load the EEDATH:EEDATL register pair with the program memory data to be written.
- Write 55h, then AAh, to EECON2, then set the WR bit of the EECON1 register (Flash programming unlock sequence). The write latch is now loaded.
- 7. Increment the EEADRH:EEADRL register pair to point to the next location.
- 8. Repeat steps 5 through 7 until all but the last write latch has been loaded.
- Clear the LWLO bit of the EECON1 register. When the LWLO bit of the EECON1 register is '0', the write sequence will initiate the write to Flash program memory.
- 10. Load the EEDATH:EEDATL register pair with the program memory data to be written.
- 11. Write 55h, then AAh, to EECON2, then set the WR bit of the EECON1 register (Flash programming unlock sequence). The entire latch block is now written to Flash program memory.

It is not necessary to load the entire write latch block with user program data. However, the entire write latch block will be written to program memory.

An example of the complete write sequence for eight words is shown in Example 11-5. The initial address is loaded into the EEADRH:EEADRL register pair; the eight words of data are loaded using indirect addressing.

Note: The code sequence provided in Example 11-5 must be repeated multiple times to fully program an erased program memory row.

REGISTER 11-1: EEDATL: EEPROM DATA LOW BYTE REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
			EEDA	T<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit	t	W = Writable bit		U = Unimpleme	ented bit, read as	'0'	
u = Bit is unchan	iged	x = Bit is unknow	'n	-n/n = Value at	POR and BOR/V	alue at all other Res	sets
'1' = Bit is set		'0' = Bit is cleare	d				

bit 7-0

EEDAT<7:0>: Read/write value for EEPROM data byte or Least Significant bits of program memory

REGISTER 11-2: EEDATH: EEPROM DATA HIGH BYTE REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	
—	—		EEDAT<13:8>					
bit 7							bit 0	

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 Unimplemented: Read as '0'

bit 5-0 EEDAT<13:8>: Read/write value for Most Significant bits of program memory

REGISTER 11-3: EEADRL: EEPROM ADDRESS LOW BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
			EEAD	R<7:0>			
bit 7							bit 0
Legend:							
R = Readable bit		W = Writable bit		U = Unimpleme	ented bit, read as	ʻ0'	
u = Bit is unchang	ged	x = Bit is unknowr	า	-n/n = Value at	POR and BOR/V	alue at all other Re	esets
'1' = Bit is set		'0' = Bit is cleared					

bit 7-0 EEADR<7:0>: Specifies the Least Significant bits for program memory address or EEPROM address

REGISTER 11-4: EEADRH: EEPROM ADDRESS HIGH BYTE REGISTER

U-1	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—				EEADR<14:8>	>		
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 Unimplemented: Read as '1'

bit 6-0 EEADR<14:8>: Specifies the Most Significant bits for program memory address or EEPROM address

U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0				
_	CCP3SEL	T1GSEL	P2BSEL	SRNQSEL	C2OUTSEL	SSSEL	CCP2SEL				
bit 7							bit 0				
Legend:											
R = Readabl		W = Writable		-	mented bit, read						
u = bit is unc	-	x = Bit is unk		-n/n = Value a	at POR and BOF	R/Value at all o	other Resets				
'1' = Bit is se	t	'0' = Bit is cle	ared								
bit 7	Unimplement	ed: Read as '0	,								
bit 6	•	CP3 Input/Out		ion bit							
		vices (PIC16F									
	0 = CCP3/P3	BA function is c	on RC6/TX/CK	C/CCP3/P3A/SE	EG9						
		1 = CCP3/P3A function is on RB5/AN13/CPS5/CCP3/P3A/T1G/COM1									
	-	For 40-Pin Devices (PIC16F1934/7):									
		0 = CCP3/P3A function is on RE0/AN5/CCP3/P3A/SEG21 1 = CCP3/P3A function is on RB5/AN13/CPS5/CCP3/P3A/T1G/COM1									
bit 5	TIGSEL : Timer1 Gate Input Pin Selection bit										
	0 = T1G function is on RB5/AN13/CPS5/CCP3/P3A/T1G/COM1										
	1 = T1G function is on RC4/SDI/SDA/T1G/SEG11										
bit 4	P2BSEL: CCP2 PWM B Output Pin Selection bit										
	For 28-Pin De	For 28-Pin Devices (PIC16F1936):									
		0 = P2B function is on RC0/T1OSO/T1CKI/P2B									
		1 = P2B function is on RB5/AN13/P2B/CPS5/T1G/COM1									
		For 40-Pin Devices (PIC16F1934/7): 0 = P2B function is on RC0/T1OSO/T1CKI/P2B									
	1 = P2B function is on RD2/CPS10/P2B										
bit 3	SRNQSEL: S	R Latch nQ O	utput Pin Sele	ction bit							
	0 = SRnQ function is on RA5/AN4/C2OUT/SRnQ/SS/CPS7/SEG5/VCAP										
					nQ/SS/SEG12/V	CAP					
bit 2		C2OUTSEL: Comparator C2 Output Pin Selection bit									
		0 = C2OUT function is on RA5/AN4/C2OUT/SRnQ/SS/CPS7/SEG5/VCAP									
bit 1	1 = C2OUT function is on RA0/AN0/C12IN0-/C2OUT/SRnQ/SS/SEG12/VCAP										
	SSSEL: SS Input Pin Selection bit 0 = SS function is on RA5/AN4/C2OUT/SRNQ/SS/CPS7/SEG5/Vcap										
					/SS/SEG12/Vca	P					
bit 0		CP2 Input/Out									
	0 = CCP2/P2	2A function is c	on RC1/T1OS	/CCP2/P2A							
	1 = CCP2/P2	2A function is c	n RB3/AN9/C	12IN2-/CPS3/0	CCP2/P2A/VLCI	03					

REGISTER 12-1: APFCON: ALTERNATE PIN FUNCTION CONTROL REGISTER

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELB	_	—	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0	139
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	98
IOCBF	IOCBF7	IOCBF6	IOCBF5	IOCBF4	IOCBF3	IOCBF2	IOCBF1	IOCBF0	152
IOCBN	IOCBN7	IOCBN6	IOCBN5	IOCBN4	IOCBN3	IOCBN2	IOCBN1	IOCBN0	152
IOCBP	IOCBP7	IOCBP6	IOCBP5	IOCBP4	IOCBP3	IOCBP2	IOCBP1	IOCBP0	152
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	138

 TABLE 13-1:
 SUMMARY OF REGISTERS ASSOCIATED WITH INTERRUPT-ON-CHANGE

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Interrupt-on-Change.

14.3 FVR Control Registers

REGISTER 14-1: FVRCON: FIXED VOLTAGE REFERENCE CONTROL REGISTER

R/W-0/0 R-q/q	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
FVREN FVRRDY	(1) TSEN	TSRNG	CDAF	/R<1:0>	ADFVI	R<1:0>
bit 7			·			bit (
Legend:						
R = Readable bit	W = Writable	bit	U = Unimpler	nented bit, read	as '0'	
u = Bit is unchanged	x = Bit is unkr	x = Bit is unknown		at POR and BOI	R/Value at all c	other Resets
'1' = Bit is set	'0' = Bit is cle	ared	q = Value dep	pends on condit	ion	
0 = Fixed	Fixed Voltage Refe I Voltage Referenc I Voltage Referenc	e is disabled	bit			
0 = Fixed	: Fixed Voltage Ref I Voltage Referenc I Voltage Referenc	e output is no	t ready or not e	nabled		
0 = Temp	mperature Indicato perature Indicator is perature Indicator is	s disabled	() ()			
0 = VOUT	Temperature Indica = VDD - 2VT (Low = VDD - 4VT (High	Range)	election bit ⁽³⁾			
00 = Com 01 = Com 10 = Com	<1:0>: Comparato parator and DAC I parator and DAC I parator and DAC I parator and DAC I parator and DAC I	Fixed Voltage Fixed Voltage Fixed Voltage	Reference Per Reference Per Reference Per	ipheral output is ipheral output is ipheral output is	s off. s 1x (1.024V) s 2x (2.048V) <mark>(2</mark>	
00 = ADC 01 = ADC 10 = ADC	1:0>: ADC Fixed V Fixed Voltage Re Fixed Voltage Re Fixed Voltage Re Fixed Voltage Re Fixed Voltage Re	ference Perip ference Perip ference Perip	heral output is o heral output is f heral output is f	off. 1x (1.024V) 2x (2.048V) ⁽²⁾		
	ways '1' on devices Reference output c	•).		

3: See Section 16.0 "Temperature Indicator Module" for additional information.

TABLE 14-1: SUMMARY OF REGISTERS ASSOCIATED WITH FIXED VOLTAGE REFERENCE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
FVRCON	FVREN	FVRRDY	TSEN	TSRNG	CDAFV	R<1:0>	ADFV	R<1:0>	156

Legend: Shaded cells are not used with the Fixed Voltage Reference.

23.4 PWM (Enhanced Mode)

The enhanced PWM function described in this section is available for CCP modules ECCP1, ECCP2 and ECCP3, with any differences between modules noted.

The enhanced PWM mode generates a Pulse-Width Modulation (PWM) signal on up to four different output pins with up to 10 bits of resolution. The period, duty cycle, and resolution are controlled by the following registers:

- PRx registers
- TxCON registers
- · CCPRxL registers
- CCPxCON registers

The ECCP modules have the following additional PWM registers which control Auto-shutdown, Auto-restart, Dead-band Delay and PWM Steering modes:

- · CCPxAS registers
- PSTRxCON registers
- PWMxCON registers

The enhanced PWM module can generate the following five PWM Output modes:

- Single PWM
- Half-Bridge PWM
- Full-Bridge PWM, Forward Mode
- Full-Bridge PWM, Reverse Mode
- · Single PWM with PWM Steering Mode

To select an Enhanced PWM Output mode, the PxM bits of the CCPxCON register must be configured appropriately.

The PWM outputs are multiplexed with I/O pins and are designated PxA, PxB, PxC and PxD. The polarity of the PWM pins is configurable and is selected by setting the CCPxM bits in the CCPxCON register appropriately.

Figure 23-5 shows an example of a simplified block diagram of the Enhanced PWM module.

Table 23-9 shows the pin assignments for various Enhanced PWM modes.

- Note 1: The corresponding TRIS bit must be cleared to enable the PWM output on the CCPx pin.
 - 2: Clearing the CCPxCON register will relinquish control of the CCPx pin.
 - **3:** Any pin not used in the enhanced PWM mode is available for alternate pin functions, if applicable.
 - 4: To prevent the generation of an incomplete waveform when the PWM is first enabled, the ECCP module waits until the start of a new PWM period before generating a PWM signal.

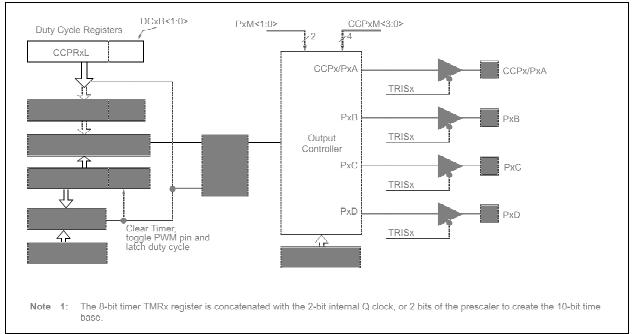


FIGURE 23-5: EXAMPLE SIMPLIFIED BLOCK DIAGRAM OF THE ENHANCED PWM MODE

24.6.10 SLEEP OPERATION

While in Sleep mode, the I²C slave module can receive addresses or data and when an address match or complete byte transfer occurs, wake the processor from Sleep (if the MSSP interrupt is enabled).

24.6.11 EFFECTS OF A RESET

A Reset disables the MSSP module and terminates the current transfer.

24.6.12 MULTI-MASTER MODE

In Multi-Master mode, the interrupt generation on the detection of the Start and Stop conditions allows the determination of when the bus is free. The Stop (P) and Start (S) bits are cleared from a Reset or when the MSSP module is disabled. Control of the I^2C bus may be taken when the P bit of the SSPSTAT register is set, or the bus is Idle, with both the S and P bits clear. When the bus is busy, enabling the SSP interrupt will generate the interrupt when the Stop condition occurs.

In multi-master operation, the SDA line must be monitored for arbitration to see if the signal level is the expected output level. This check is performed by hardware with the result placed in the BCLIF bit.

The states where arbitration can be lost are:

- · Address Transfer
- Data Transfer
- A Start Condition
- A Repeated Start Condition
- An Acknowledge Condition

24.6.13 MULTI -MASTER COMMUNICATION, BUS COLLISION AND BUS ARBITRATION

Multi-Master mode support is achieved by bus arbitration. When the master outputs address/data bits onto the SDA pin, arbitration takes place when the master outputs a '1' on SDA, by letting SDA float high and another master asserts a '0'. When the SCL pin floats high, data should be stable. If the expected data on SDA is a '1' and the data sampled on the SDA pin is '0', then a bus collision has taken place. The master will set the Bus Collision Interrupt Flag, BCLIF, and reset the I²C port to its Idle state (Figure 24-31).

If a transmit was in progress when the bus collision occurred, the transmission is halted, the BF flag is cleared, the SDA and SCL lines are deasserted and the SSPBUF can be written to. When the user services the bus collision Interrupt Service Routine and if the I^2C bus is free, the user can resume communication by asserting a Start condition.

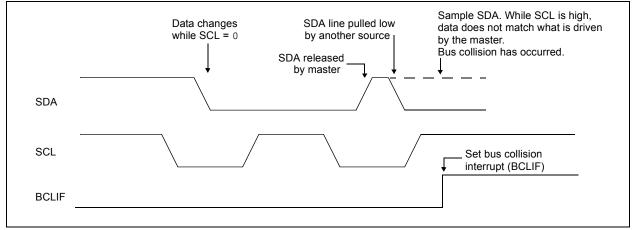
If a Start, Repeated Start, Stop or Acknowledge condition was in progress when the bus collision occurred, the condition is aborted, the SDA and SCL lines are deasserted and the respective control bits in the SSPCON2 register are cleared. When the user services the bus collision Interrupt Service Routine and if the I²C bus is free, the user can resume communication by asserting a Start condition.

The master will continue to monitor the SDA and SCL pins. If a Stop condition occurs, the SSPIF bit will be set.

A write to the SSPBUF will start the transmission of data at the first data bit, regardless of where the transmitter left off when the bus collision occurred.

In Multi-Master mode, the interrupt generation on the detection of Start and Stop conditions allows the determination of when the bus is free. Control of the I^2C bus can be taken when the P bit is set in the SSPSTAT register, or the bus is Idle and the S and P bits are cleared.

FIGURE 24-32: BUS COLLISION TIMING FOR TRANSMIT AND ACKNOWLEDGE



25.3.1 AUTO-BAUD DETECT

The EUSART module supports automatic detection and calibration of the baud rate.

In the Auto-Baud Detect (ABD) mode, the clock to the BRG is reversed. Rather than the BRG clocking the incoming RX signal, the RX signal is timing the BRG. The Baud Rate Generator is used to time the period of a received 55h (ASCII "U") which is the Sync character for the LIN bus. The unique feature of this character is that it has five rising edges including the Stop bit edge.

Setting the ABDEN bit of the BAUDCON register starts the auto-baud calibration sequence (Figure 25-6). While the ABD sequence takes place, the EUSART state machine is held in Idle. On the first rising edge of the receive line, after the Start bit, the SPBRG begins counting up using the BRG counter clock as shown in Table 25-6. The fifth rising edge will occur on the RX pin at the end of the eighth bit period. At that time, an accumulated value totaling the proper BRG period is left in the SPBRGH, SPBRGL register pair, the ABDEN bit is automatically cleared and the RCIF interrupt flag is set. The value in the RCREG needs to be read to clear the RCIF interrupt. RCREG content should be discarded. When calibrating for modes that do not use the SPBRGH register the user can verify that the SPBRGL register did not overflow by checking for 00h in the SPBRGH register.

The BRG auto-baud clock is determined by the BRG16 and BRGH bits as shown in Table 25-6. During ABD, both the SPBRGH and SPBRGL registers are used as a 16-bit counter, independent of the BRG16 bit setting. While calibrating the baud rate period, the SPBRGH and SPBRGL registers are clocked at 1/8th the BRG base clock rate. The resulting byte measurement is the average bit time when clocked at full speed.

- Note 1: If the WUE bit is set with the ABDEN bit, auto-baud detection will occur on the byte following the Break character (see Section 25.3.3 "Auto-Wake-up on Break").
 - It is up to the user to determine that the incoming character baud rate is within the range of the selected BRG clock source. Some combinations of oscillator frequency and EUSART baud rates are not possible.
 - 3: During the auto-baud process, the auto-baud counter starts counting at 1. Upon completion of the auto-baud sequence, to achieve maximum accuracy, subtract 1 from the SPBRGH:SPBRGL register pair.

TABLE 25-6:	BRG COUNTER CLOCK RATES
-------------	-------------------------

BRG16	BRGH	BRG Base Clock	BRG ABD Clock
0	0	Fosc/64	Fosc/512
0	1	Fosc/16	Fosc/128
1	0	Fosc/16	Fosc/128
1	1	Fosc/4	Fosc/32

Note: During the ABD sequence, SPBRGL and SPBRGH registers are both used as a 16-bit counter, independent of BRG16 setting.

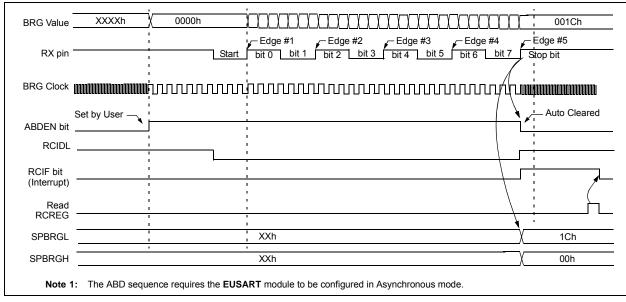


FIGURE 25-6: AUTOMATIC BAUD RATE CALIBRATION

27.11 Operation During Sleep

The LCD module can operate during Sleep. The selection is controlled by bit SLPEN of the LCDCON register. Setting the SLPEN bit allows the LCD module to go to Sleep. Clearing the SLPEN bit allows the module to continue to operate during Sleep.

If a SLEEP instruction is executed and SLPEN = 1, the LCD module will cease all functions and go into a very low-current Consumption mode. The module will stop operation immediately and drive the minimum LCD voltage on both segment and common lines. Figure 27-20 shows this operation.

The LCD module can be configured to operate during Sleep. The selection is controlled by bit SLPEN of the LCDCON register. Clearing SLPEN and correctly configuring the LCD module clock will allow the LCD module to operate during Sleep. Setting SLPEN and correctly executing the LCD module shutdown will disable the LCD module during Sleep and save power.

If a SLEEP instruction is executed and SLPEN = 1, the LCD module will immediately cease all functions, drive the outputs to Vss and go into a very Low-Current mode. The SLEEP instruction should only be executed after the LCD module has been disabled and the current cycle completed, thus ensuring that there are no DC voltages on the glass. To disable the LCD module, clear the LCDEN bit. The LCD module will complete the disabling process after the current frame, clear the LCDA bit and optionally cause an interrupt.

The steps required to properly enter Sleep with the LCD disabled are:

- Clear LCDEN
- Wait for LCDA = 0 either by polling or by interrupt
- Execute SLEEP

If SLPEN = 0 and SLEEP is executed while the LCD module clock source is FOSC/4, then the LCD module will halt with the pin driving the last LCD voltage pattern. Prolonged exposure to a fixed LCD voltage pattern will cause damage to the LCD glass. To prevent LCD glass damage, either perform the proper LCD module shutdown prior to Sleep, or change the LCD module clock to allow the LCD module to continue operation during Sleep.

If a SLEEP instruction is executed and SLPEN = 0 and the LCD module clock is either T1OSC or LFINTOSC, the module will continue to display the current contents of the LCDDATA registers. While in Sleep, the LCD data cannot be changed. If the LCDIE bit is set, the device will wake from Sleep on the next LCD frame boundary. The LCD module current consumption will not decrease in this mode; however, the overall device power consumption will be lower due to the shutdown of the CPU and other peripherals. Table 27-8 shows the status of the LCD module during a Sleep while using each of the three available clock sources.

Mater	When the LODEN bit is cleared the LOD
Note:	When the LCDEN bit is cleared, the LCD
	module will be disabled at the completion
	of frame. At this time, the port pins will
	revert to digital functionality. To minimize
	power consumption due to floating digital
	inputs, the LCD pins should be driven low
	using the PORT and TRIS registers.

If a SLEEP instruction is executed and SLPEN = 0, the module will continue to display the current contents of the LCDDATA registers. To allow the module to continue operation while in Sleep, the clock source must be either the LFINTOSC or T1OSC external oscillator. While in Sleep, the LCD data cannot be changed. The LCD module current consumption will not decrease in this mode; however, the overall consumption of the device will be lower due to shut down of the core and other peripheral functions.

Table 27-8 shows the status of the LCD module during Sleep while using each of the three available clock sources:

TABLE 27-8:	LCD MODULE STATUS
	DURING SLEEP

Clock Source	SLPEN	Operational During Sleep
T1OSC	0	Yes
11030	1	No
LFINTOSC	0	Yes
LEINTOSC	1	No
Fosc/4	0	No
F05C/4	1	No

Note:	The LFINTOSC or external T1OSC
	oscillator must be used to operate the
	LCD module during Sleep.

If LCD interrupts are being generated (Type-B waveform with a multiplex mode not static) and LCDIE = 1, the device will awaken from Sleep on the next frame boundary.

27.12 Configuring the LCD Module

The following is the sequence of steps to configure the LCD module.

- 1. Select the frame clock prescale using bits LP<3:0> of the LCDPS register.
- 2. Configure the appropriate pins to function as segment drivers using the LCDSEn registers.
- 3. Configure the LCD module for the following using the LCDCON register:
 - Multiplex and Bias mode, bits LMUX<1:0>
 - Timing source, bits CS<1:0>
 - Sleep mode, bit SLPEN
- 4. Write initial values to pixel data registers, LCDDATA0 through LCDDATA11.
- 5. Clear LCD Interrupt Flag, LCDIF bit of the PIR2 register and if desired, enable the interrupt by setting bit LCDIE of the PIE2 register.
- Configure bias voltages by setting the LCDRL, LCDREF and the associated ANSELx registers as needed.
- 7. Enable the LCD module by setting bit LCDEN of the LCDCON register.

27.13 Disabling the LCD Module

To disable the LCD module, write all '0's to the LCDCON register.

27.14 LCD Current Consumption

When using the LCD module the current consumption consists of the following three factors:

- Oscillator Selection
- · LCD Bias Source
- Capacitance of the LCD segments

The current consumption of just the LCD module can be considered negligible compared to these other factors.

27.14.1 OSCILLATOR SELECTION

The current consumed by the clock source selected must be considered when using the LCD module. See the applicable Electrical Specifications Chapter for oscillator current consumption information.

27.14.2 LCD BIAS SOURCE

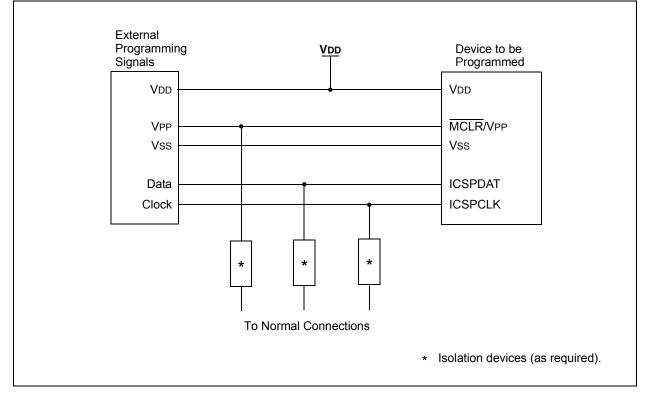
The LCD bias source, internal or external, can contribute significantly to the current consumption. Use the highest possible resistor values while maintaining contrast to minimize current.

27.14.3 CAPACITANCE OF THE LCD SEGMENTS

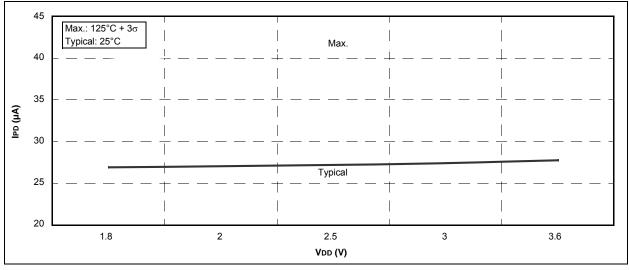
The LCD segments which can be modeled as capacitors which must be both charged and discharged every frame. The size of the LCD segment and its technology determines the segment's capacitance. For additional interface recommendations, refer to your specific device programmer manual prior to PCB design.

It is recommended that isolation devices be used to separate the programming pins from other circuitry. The type of isolation is highly dependent on the specific application and may include devices such as resistors, diodes, or even jumpers. See Figure 28-4 for more information.

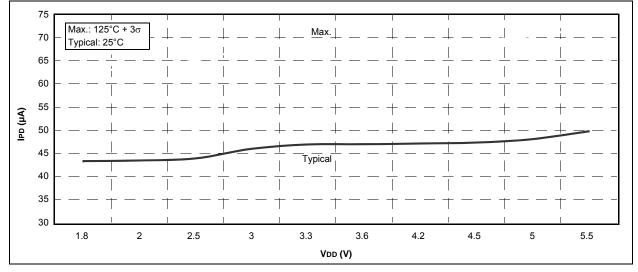


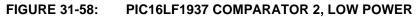


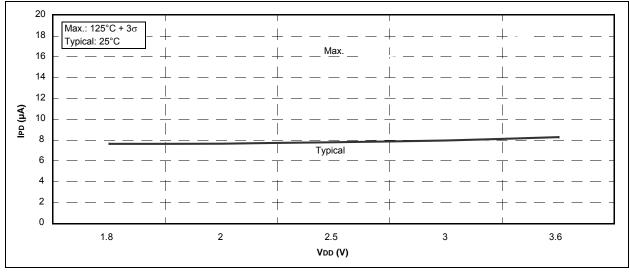












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USART

VREF. SEE ADC Reference Voltage

Synchronous Master Mode