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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	14KB (8K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 11x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UQFN Exposed Pad
Supplier Device Package	28-UQFN (4x4)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1936-i-mv">https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1936-i-mv</a>

**TABLE 3-9: PIC16(L)F1936 MEMORY MAP, BANK 15**

Bank 15	
791h	LCDCON
792h	LCDPS
793h	LCDREF
794h	LCDCST
795h	LCDRL
796h	—
797h	—
798h	LCDSE0
799h	LCDSE1
79Ah	—
79Bh	—
79Ch	—
79Dh	—
79Eh	—
79Fh	—
7A0h	LCDDATA0
7A1h	LCDDATA1
7A2h	—
7A3h	LCDDATA3
7A4h	LCDDATA4
7A5h	—
7A6h	LCDDATA6
7A7h	LCDDATA7
7A8h	—
7A9h	LCDDATA9
7AAh	LCDDATA10
7ABh	—
7ACh	—
7ADh	—
7AEh	—
7AFh	—
7B0h	—
7B1h	—
7B2h	—
7B3h	—
7B4h	—
7B5h	—
7B6h	—
7B7h	—
7B8h	Unimplemented Read as '0'
7EFh	

**Legend:**  = Unimplemented data memory locations, read as '0'.

**TABLE 3-10: PIC16(L)F1934/7 MEMORY MAP, BANK 15**

Bank 15	
791h	LCDCON
792h	LCDPS
793h	LCDREF
794h	LCDCST
795h	LCDRL
796h	—
797h	—
798h	LCDSE0
799h	LCDSE1
79Ah	LCDSE2
79Bh	—
79Ch	—
79Dh	—
79Eh	—
79Fh	—
7A0h	LCDDATA0
7A1h	LCDDATA1
7A2h	LCDDATA2
7A3h	LCDDATA3
7A4h	LCDDATA4
7A5h	LCDDATA5
7A6h	LCDDATA6
7A7h	LCDDATA7
7A8h	LCDDATA8
7A9h	LCDDATA9
7AAh	LCDDATA10
7ABh	LCDDATA11
7ACh	—
7ADh	—
7AEh	—
7AFh	—
7B0h	—
7B1h	—
7B2h	—
7B3h	—
7B4h	—
7B5h	—
7B6h	—
7B7h	—
7B8h	Unimplemented Read as '0'
7EFh	

**Legend:**  = Unimplemented data memory locations, read as '0'.

# PIC16(L)F1934/6/7

**TABLE 3-12: SPECIAL FUNCTION REGISTER SUMMARY (CONTINUED)**

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets	
Bank 1												
080h <sup>(2)</sup>	INDF0	Addressing this location uses contents of FSR0H/FSR0L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx	
081h <sup>(2)</sup>	INDF1	Addressing this location uses contents of FSR1H/FSR1L to address data memory (not a physical register)								xxxx xxxx	xxxx xxxx	
082h <sup>(2)</sup>	PCL	Program Counter (PC) Least Significant Byte								0000 0000	0000 0000	
083h <sup>(2)</sup>	STATUS	—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	---1 1000	---q quuu	
084h <sup>(2)</sup>	FSR0L	Indirect Data Memory Address 0 Low Pointer								0000 0000	uuuu uuuu	
085h <sup>(2)</sup>	FSR0H	Indirect Data Memory Address 0 High Pointer								0000 0000	0000 0000	
086h <sup>(2)</sup>	FSR1L	Indirect Data Memory Address 1 Low Pointer								0000 0000	uuuu uuuu	
087h <sup>(2)</sup>	FSR1H	Indirect Data Memory Address 1 High Pointer								0000 0000	0000 0000	
088h <sup>(2)</sup>	BSR	—	—	—	BSR<4:0>					---0 0000	---0 0000	
089h <sup>(2)</sup>	WREG	Working Register								0000 0000	uuuu uuuu	
08Ah <sup>(1, 2)</sup>	PCLATH	—	Write Buffer for the upper 7 bits of the Program Counter								-000 0000	-000 0000
08Bh <sup>(2)</sup>	INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	0000 0000	0000 0000	
08Ch	TRISA	PORTA Data Direction Register								1111 1111	1111 1111	
08Dh	TRISB	PORTB Data Direction Register								1111 1111	1111 1111	
08Eh	TRISC	PORTC Data Direction Register								1111 1111	1111 1111	
08Fh <sup>(3)</sup>	TRISD	PORTD Data Direction Register								1111 1111	1111 1111	
090h	TRISE	—	—	—	—	$\text{—}^{(4)}$	TRISE2 <sup>(3)</sup>	TRISE1 <sup>(3)</sup>	TRISE0 <sup>(3)</sup>	---- 1111	---- 1111	
091h	PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	0000 0000	0000 0000	
092h	PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	LCDIE	—	CCP2IE	0000 00-0	0000 00-0	
093h	PIE3	—	CCP5IE	CCP4IE	CCP3IE	TMR6IE	—	TMR4IE	—	-000 0-0-	-000 0-0-	
094h	—	Unimplemented								—	—	
095h	OPTION_REG	WPUEN	INTEDG	TMROCS	TMROSE	PSA	PS<2:0>			1111 1111	1111 1111	
096h	PCON	STKOVF	STKUNF	—	—	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	00-- 11qq	qq-- qquu	
097h	WDTCON	—	—	WDTPS<4:0>					SWDTEN	--01 0110	--01 0110	
098h	OSCTUNE	—	—	TUN<5:0>						--00 0000	--00 0000	
099h	OSCCON	SPLLEN	IRCF<3:0>				—	SCS<1:0>		0011 1-00	0011 1-00	
09Ah	OSCSTAT	T1OSCR	PLLRC	OSTS	HFIOFR	HFIOFL	MFIOFR	LFIOFR	HFIOFS	00q0 0q0-	qqqq qq0-	
09Bh	ADRESL	A/D Result Register Low								xxxx xxxx	uuuu uuuu	
09Ch	ADRESH	A/D Result Register High								xxxx xxxx	uuuu uuuu	
09Dh	ADCON0	—	CHS<4:0>					$\text{GO}/\overline{\text{DONE}}$	ADON	-000 0000	-000 0000	
09Eh	ADCON1	ADFM	ADCS<2:0>			—	ADNREF	ADPREF1	ADPREF0	0000 -000	0000 -000	
09Fh	—	Unimplemented								—	—	

**Legend:** x = unknown, u = unchanged, q = value depends on condition, - = unimplemented, read as '0', r = reserved.  
Shaded locations are unimplemented, read as '0'.

- Note** 1: The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<14:8>, whose contents are transferred to the upper byte of the program counter.  
2: These registers can be addressed from any bank.  
3: These registers/bits are not implemented on PIC16(L)F1936 devices, read as '0'.  
4: Unimplemented, read as '1'.

# PIC16(L)F1934/6/7

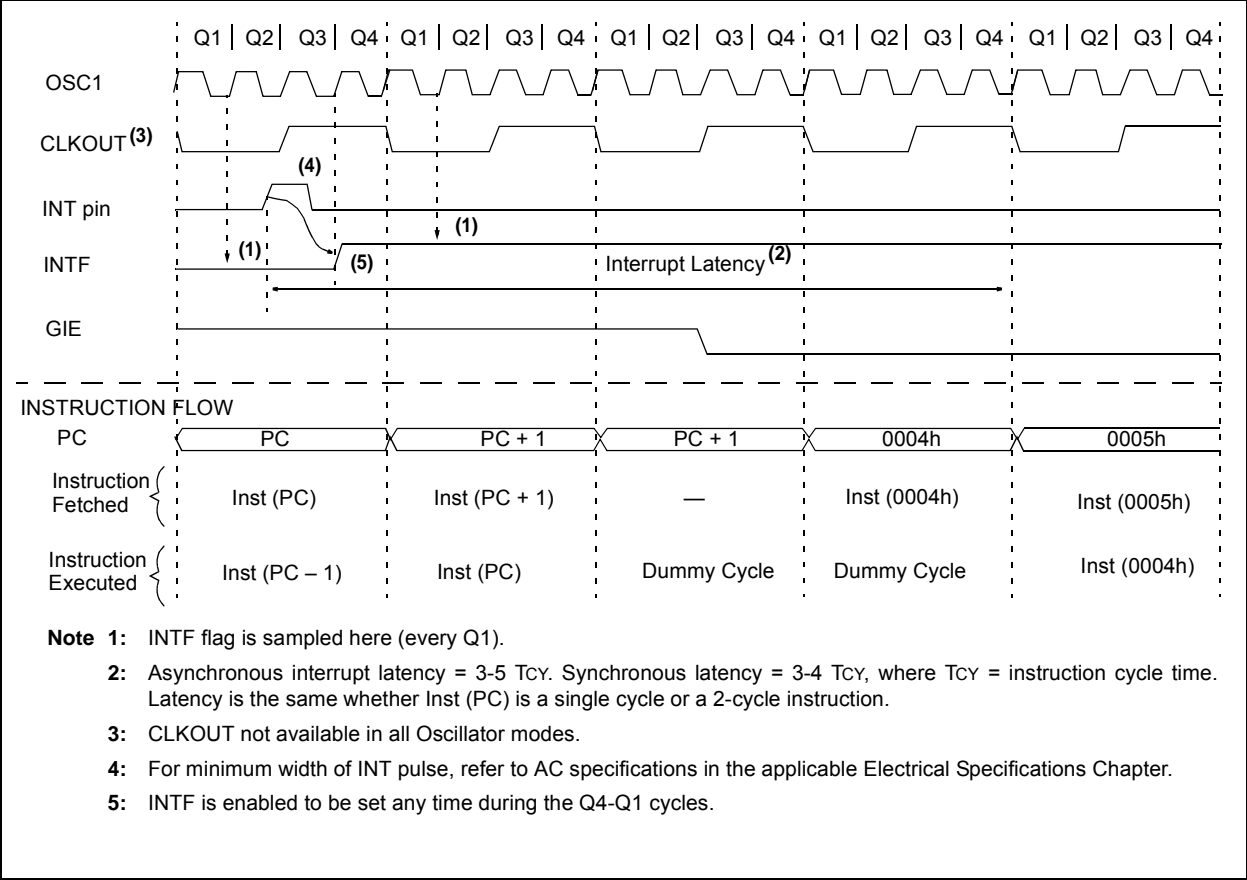
TABLE 6-5: SUMMARY OF REGISTERS ASSOCIATED WITH RESETS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BORCON	SBOREN	—	—	—	—	—	—	BORRDY	87
PCON	STKOVF	STKUNF	—	—	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	91
STATUS	—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	29
WDTCON	—	—	WDTPS<4:0>					SWDTEN	113

**Legend:** — = unimplemented location, read as '0'. Shaded cells are not used by Resets.

**Note 1:** Other (non Power-up) Resets include  $\overline{\text{MCLR}}$  Reset and Watchdog Timer Reset during normal operation.

FIGURE 7-3: INT PIN INTERRUPT TIMING



# PIC16(L)F1934/6/7

## REGISTER 11-1: EEDATL: EEPROM DATA LOW BYTE REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
EEDAT<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-0                      **EEDAT<7:0>**: Read/write value for EEPROM data byte or Least Significant bits of program memory

## REGISTER 11-2: EEDATH: EEPROM DATA HIGH BYTE REGISTER

U-0	U-0	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
—	—	EEDAT<13:8>					
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-6                      **Unimplemented**: Read as '0'

bit 5-0                      **EEDAT<13:8>**: Read/write value for Most Significant bits of program memory

## REGISTER 11-3: EEADRL: EEPROM ADDRESS LOW BYTE REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
EEADR<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7-0                      **EEADR<7:0>**: Specifies the Least Significant bits for program memory address or EEPROM address

## REGISTER 11-4: EEADRH: EEPROM ADDRESS HIGH BYTE REGISTER

U-1	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	EEADR<14:8>						
bit 7				bit 0			

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
u = Bit is unchanged                  x = Bit is unknown                  -n/n = Value at POR and BOR/Value at all other Resets  
'1' = Bit is set                          '0' = Bit is cleared

bit 7                          **Unimplemented**: Read as '1'

bit 6-0                      **EEADR<14:8>**: Specifies the Most Significant bits for program memory address or EEPROM address

## REGISTER 12-9: ANSELB: PORTB ANALOG SELECT REGISTER

U-0	U-0	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
—	—	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **ANSB<5:0>:** Analog Select between Analog or Digital Function on Pins RB<5:0>, respectively

0 = Digital I/O. Pin is assigned to port or digital special function.

1 = Analog input. Pin is assigned as analog input<sup>(1)</sup>. Digital input buffer disabled.

**Note 1:** When setting a pin to an analog input, the corresponding TRIS bit must be set to Input mode in order to allow external control of the voltage on the pin.

## REGISTER 12-10: WPUB: WEAK PULL-UP PORTB REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
WPUB7	WPUB6	WPUB5	WPUB4	WPUB3	WPUB2	WPUB1	WPUB0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0 **WPUB<7:0>:** Weak Pull-up Register bits

1 = Pull-up enabled

0 = Pull-up disabled

**Note 1:** Global WPUEN bit of the OPTION\_REG register must be cleared for individual pull-ups to be enabled.

**2:** The weak pull-up device is automatically disabled if the pin is configured as an output.

NOTES:



## REGISTER 18-1: CMxCON0: COMPARATOR X CONTROL REGISTER 0

R/W-0/0	R-0/0	R/W-0/0	R/W-0/0	U-0	R/W-1/1	R/W-0/0	R/W-0/0
CxON	CxOUT	CxOE	CxPOL	—	CxSP	CxHYS	CxSYNC
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7      **CxON:** Comparator Enable bit  
1 = Comparator is enabled and consumes no active power  
0 = Comparator is disabled
- bit 6      **CxOUT:** Comparator Output bit  
If CxPOL = 1 (inverted polarity):  
1 = CxVP < CxVN  
0 = CxVP > CxVN  
If CxPOL = 0 (non-inverted polarity):  
1 = CxVP > CxVN  
0 = CxVP < CxVN
- bit 5      **CxOE:** Comparator Output Enable bit  
1 = CxOUT is present on the CxOUT pin. Requires that the associated TRIS bit be cleared to actually drive the pin. Not affected by CxON.  
0 = CxOUT is internal only
- bit 4      **CxPOL:** Comparator Output Polarity Select bit  
1 = Comparator output is inverted  
0 = Comparator output is not inverted
- bit 3      **Unimplemented:** Read as '0'
- bit 2      **CxSP:** Comparator Speed/Power Select bit  
1 = Comparator operates in normal power, higher speed mode  
0 = Comparator operates in low-power, low-speed mode
- bit 1      **CxHYS:** Comparator Hysteresis Enable bit  
1 = Comparator hysteresis enabled  
0 = Comparator hysteresis disabled
- bit 0      **CxSYNC:** Comparator Output Synchronous Mode bit  
1 = Comparator output to Timer1 and I/O pin is synchronous to changes on Timer1 clock source. Output updated on the falling edge of Timer1 clock source.  
0 = Comparator output to Timer1 and I/O pin is asynchronous.

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## REGISTER 18-2: CMxCON1: COMPARATOR CX CONTROL REGISTER 1

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	R/W-0/0	R/W-0/0
CxINTP	CxINTN	CxPCH<1:0>		—	—	CxNCH<1:0>	
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7 **CxINTP:** Comparator Interrupt on Positive Going Edge Enable bits  
 1 = The CxIF interrupt flag will be set upon a positive going edge of the CxOUT bit  
 0 = No interrupt flag will be set on a positive going edge of the CxOUT bit
- bit 6 **CxINTN:** Comparator Interrupt on Negative Going Edge Enable bits  
 1 = The CxIF interrupt flag will be set upon a negative going edge of the CxOUT bit  
 0 = No interrupt flag will be set on a negative going edge of the CxOUT bit
- bit 5-4 **CxPCH<1:0>:** Comparator Positive Input Channel Select bits  
 00 = CxVP connects to CxIN+ pin  
 01 = CxVP connects to DAC Voltage Reference  
 10 = CxVP connects to FVR Voltage Reference  
 11 = CxVP connects to Vss
- bit 3-2 **Unimplemented:** Read as '0'
- bit 1-0 **CxNCH<1:0>:** Comparator Negative Input Channel Select bits  
 00 = CxVN connects to C12IN0- pin  
 01 = CxVN connects to C12IN1- pin  
 10 = CxVN connects to C12IN2- pin  
 11 = CxVN connects to C12IN3- pin

## REGISTER 18-3: CMOUT: COMPARATOR OUTPUT REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R-0/0	R-0/0
—	—	—	—	—	—	MC2OUT	MC1OUT
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

- bit 7-2 **Unimplemented:** Read as '0'
- bit 1 **MC2OUT:** Mirror Copy of C2OUT bit
- bit 0 **MC1OUT:** Mirror Copy of C1OUT bit

## 23.4 PWM (Enhanced Mode)

The enhanced PWM function described in this section is available for CCP modules ECCP1, ECCP2 and ECCP3, with any differences between modules noted.

The enhanced PWM mode generates a Pulse-Width Modulation (PWM) signal on up to four different output pins with up to 10 bits of resolution. The period, duty cycle, and resolution are controlled by the following registers:

- PRx registers
- TxCON registers
- CCPRxL registers
- CCPxCON registers

The ECCP modules have the following additional PWM registers which control Auto-shutdown, Auto-restart, Dead-band Delay and PWM Steering modes:

- CCPxAS registers
- PSTRxCON registers
- PWMxCON registers

The enhanced PWM module can generate the following five PWM Output modes:

- Single PWM
- Half-Bridge PWM
- Full-Bridge PWM, Forward Mode
- Full-Bridge PWM, Reverse Mode
- Single PWM with PWM Steering Mode

To select an Enhanced PWM Output mode, the PxM bits of the CCPxCON register must be configured appropriately.

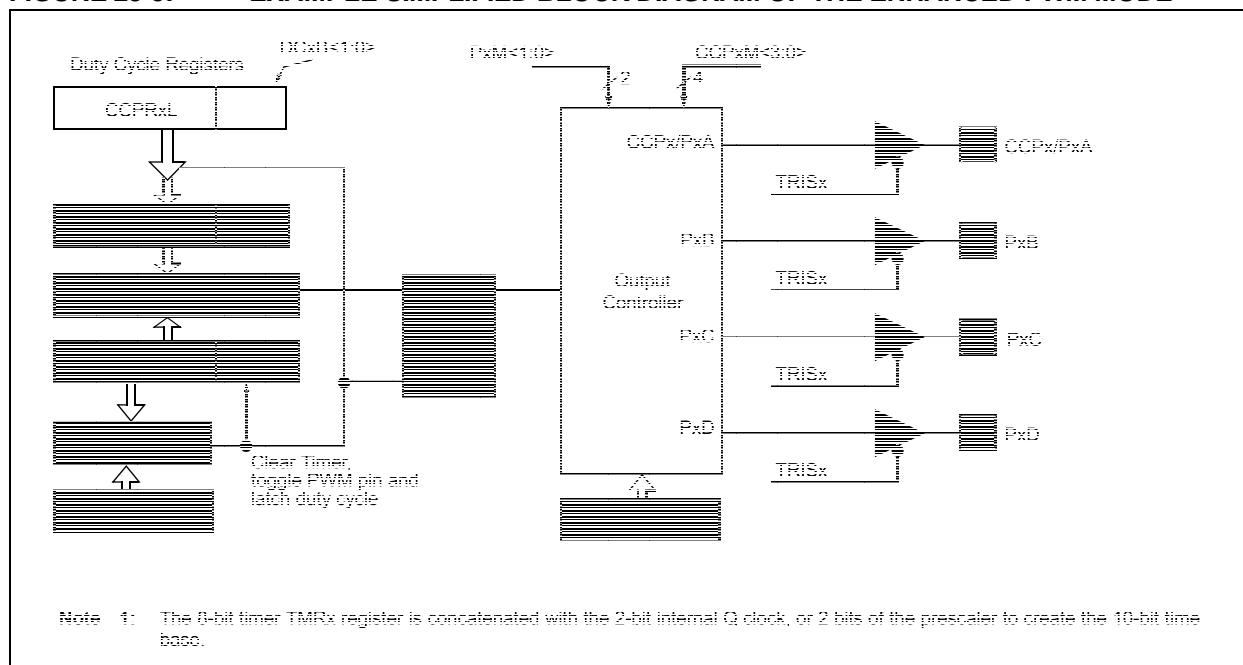
The PWM outputs are multiplexed with I/O pins and are designated PxA, PxB, PxC and PxD. The polarity of the PWM pins is configurable and is selected by setting the CCPxM bits in the CCPxCON register appropriately.

Figure 23-5 shows an example of a simplified block diagram of the Enhanced PWM module.

Table 23-9 shows the pin assignments for various Enhanced PWM modes.

- Note 1:** The corresponding TRIS bit must be cleared to enable the PWM output on the CCPx pin.
- 2:** Clearing the CCPxCON register will relinquish control of the CCPx pin.
- 3:** Any pin not used in the enhanced PWM mode is available for alternate pin functions, if applicable.
- 4:** To prevent the generation of an incomplete waveform when the PWM is first enabled, the ECCP module waits until the start of a new PWM period before generating a PWM signal.

**FIGURE 23-5: EXAMPLE SIMPLIFIED BLOCK DIAGRAM OF THE ENHANCED PWM MODE**



## 24.2.6 SPI OPERATION IN SLEEP MODE

In SPI Master mode, module clocks may be operating at a different speed than when in Full Power mode; in the case of the Sleep mode, all clocks are halted.

Special care must be taken by the user when the MSSP clock is much faster than the system clock.

In Slave mode, when MSSP interrupts are enabled, after the master completes sending data, an MSSP interrupt will wake the controller from Sleep.

If an exit from Sleep mode is not desired, MSSP interrupts should be disabled.

In SPI Master mode, when the Sleep mode is selected, all module clocks are halted and the transmission/reception will remain in that state until the device wakes. After the device returns to Run mode, the module will resume transmitting and receiving data.

In SPI Slave mode, the SPI Transmit/Receive Shift register operates asynchronously to the device. This allows the device to be placed in Sleep mode and data to be shifted into the SPI Transmit/Receive Shift register. When all 8 bits have been received, the MSSP interrupt flag bit will be set and if enabled, will wake the device.

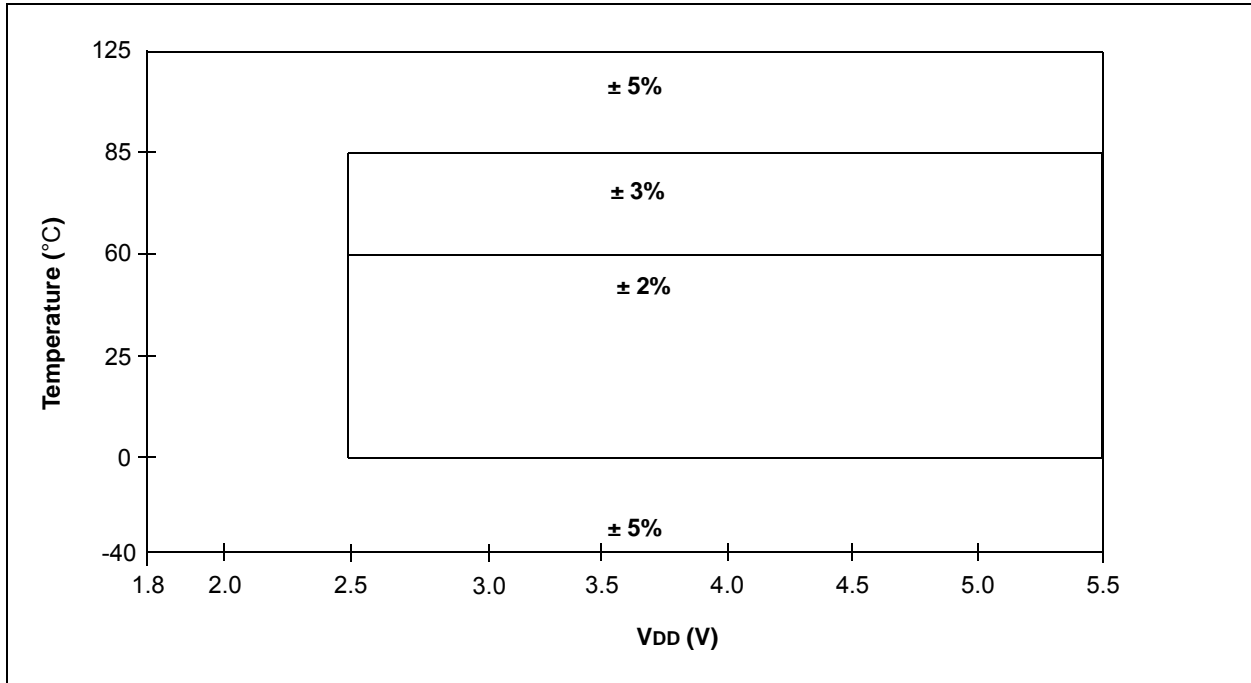
**TABLE 24-1: SUMMARY OF REGISTERS ASSOCIATED WITH SPI OPERATION**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	—	ANSA5	ANSA4	ANSA3	ANSA2	ANSA1	ANSA0	134
APFCON	—	CCP3SEL	T1GSEL	P2BSEL	SRNQSEL	C2OUTSEL	SSSEL	CCP2SEL	131
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	98
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSP1IE	CCP1IE	TMR2IE	TMR1IE	99
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSP1IF	CCP1IF	TMR2IF	TMR1IF	102
SSPBUF	Synchronous Serial Port Receive Buffer/Transmit Register								243*
SSPCON1	WCOL	SSPOV	SSPEN	CKP	SSPM<3:0>				287
SSPCON3	ACKTIM	PCIE	SCIE	BOEN	SDAHT	SBCDE	AHEN	DHEN	289
SSPSTAT	SMP	CKE	D/A	P	S	R/W	UA	BF	286
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	133
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISB2	TRISC1	TRISC0	142

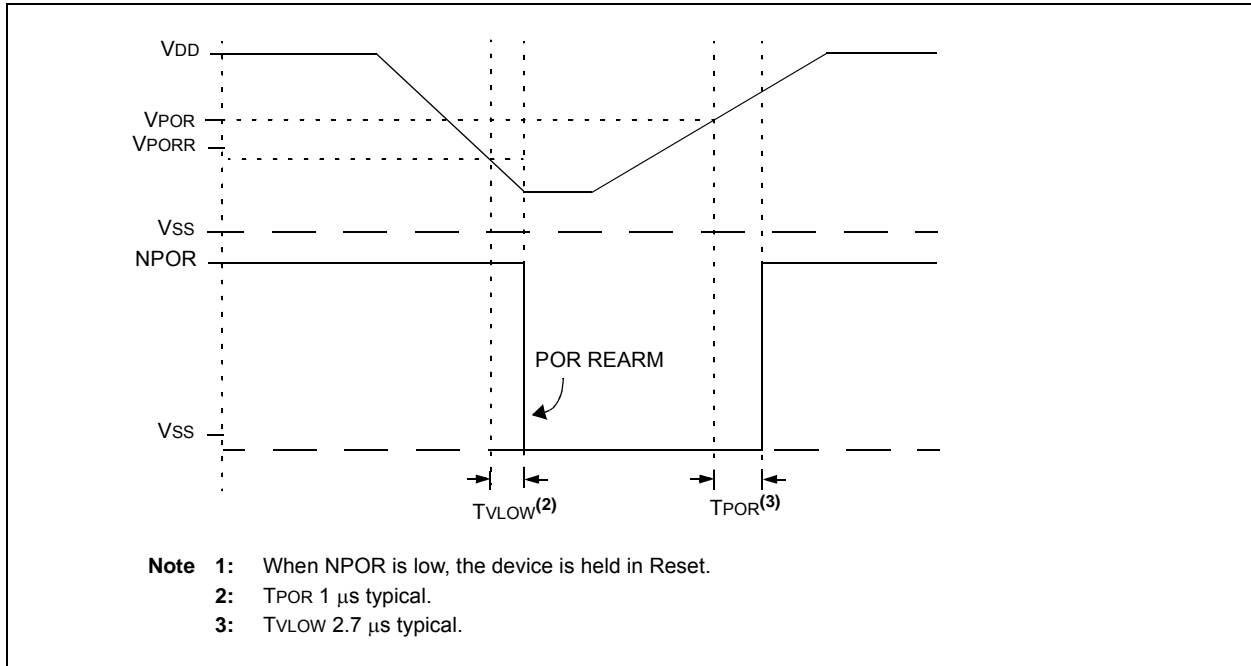
**Legend:** — = Unimplemented location, read as '0'. Shaded cells are not used by the MSSP in SPI mode.

\* Page provides register information.

**FIGURE 30-3: HFINTOSC FREQUENCY ACCURACY OVER DEVICE V<sub>DD</sub> AND TEMPERATURE**



**FIGURE 30-4: POR AND POR REARM WITH SLOW RISING  $V_{DD}$**



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## 30.6 Thermal Considerations

Standard Operating Conditions (unless otherwise stated)					
Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$					
Param No.	Sym.	Characteristic	Typ.	Units	Conditions
TH01	$\theta_{JA}$	Thermal Resistance Junction to Ambient	60	$^{\circ}\text{C}/\text{W}$	28-pin SPDIP package
			80	$^{\circ}\text{C}/\text{W}$	28-pin SOIC package
			90	$^{\circ}\text{C}/\text{W}$	28-pin SSOP package
			27.5	$^{\circ}\text{C}/\text{W}$	28-pin UQFN 4x4mm package
			27.5	$^{\circ}\text{C}/\text{W}$	28-pin QFN 6x6mm package
			47.2	$^{\circ}\text{C}/\text{W}$	40-pin PDIP package
			46	$^{\circ}\text{C}/\text{W}$	44-pin TQFP package
			24.4	$^{\circ}\text{C}/\text{W}$	44-pin QFN 8x8mm package
TH02	$\theta_{JC}$	Thermal Resistance Junction to Case	31.4	$^{\circ}\text{C}/\text{W}$	28-pin SPDIP package
			24	$^{\circ}\text{C}/\text{W}$	28-pin SOIC package
			24	$^{\circ}\text{C}/\text{W}$	28-pin SSOP package
			24	$^{\circ}\text{C}/\text{W}$	28-pin UQFN 4x4mm package
			24	$^{\circ}\text{C}/\text{W}$	28-pin QFN 6x6mm package
			24.7	$^{\circ}\text{C}/\text{W}$	40-pin PDIP package
			14.5	$^{\circ}\text{C}/\text{W}$	44-pin TQFP package
			20	$^{\circ}\text{C}/\text{W}$	44-pin QFN 8x8mm package
TH03	$T_{JMAX}$	Maximum Junction Temperature	150	$^{\circ}\text{C}$	
TH04	PD	Power Dissipation	—	W	$PD = P_{INTERNAL} + P_{I/O}$
TH05	$P_{INTERNAL}$	Internal Power Dissipation	—	W	$P_{INTERNAL} = I_{DD} \times V_{DD}^{(1)}$
TH06	$P_{I/O}$	I/O Power Dissipation	—	W	$P_{I/O} = \sum (I_{OL} \times V_{OL}) + \sum (I_{OH} \times (V_{DD} - V_{OH}))$
TH07	$P_{DER}$	Derated Power	—	W	$P_{DER} = P_{DMAX} (T_J - T_A) / \theta_{JA}^{(2)}$

**Note 1:**  $I_{DD}$  is current to run the chip alone without driving any load on the output pins.

**2:**  $T_A$  = Ambient Temperature

**3:**  $T_J$  = Junction Temperature

**TABLE 30-5: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER AND BROWN-OUT RESET PARAMETERS**

Standard Operating Conditions (unless otherwise stated) Operating Temperature $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
30	TMCL	MCLR Pulse Width (low)	2	—	—	$\mu\text{s}$	
31	TWDTLP	Low-Power Watchdog Timer Time-out Period	10	16	27	ms	$V_{DD} = 3.3\text{V}-5\text{V}$ 1:16 Prescaler used
32	TOST	Oscillator Start-up Timer Period <sup>(1), (2)</sup>	—	1024	—	$T_{osc}$	(Note 3)
33*	TPWRT	Power-up Timer Period, $\overline{\text{PWRTE}} = 0$	40	65	140	ms	
34*	TIOZ	I/O high-impedance from MCLR Low or Watchdog Timer Reset	—	—	2.0	$\mu\text{s}$	
35	VBOR	Brown-out Reset Voltage	2.38 1.80	2.5 1.9	2.73 2.11	V	BORV=2.5V BORV=1.9V
36*	VHYST	Brown-out Reset Hysteresis	0	25	60	mV	$-40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$
37*	TBORDC	Brown-out Reset DC Response Time	1	3	35	$\mu\text{s}$	$V_{DD} \leq V_{BOR}$

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

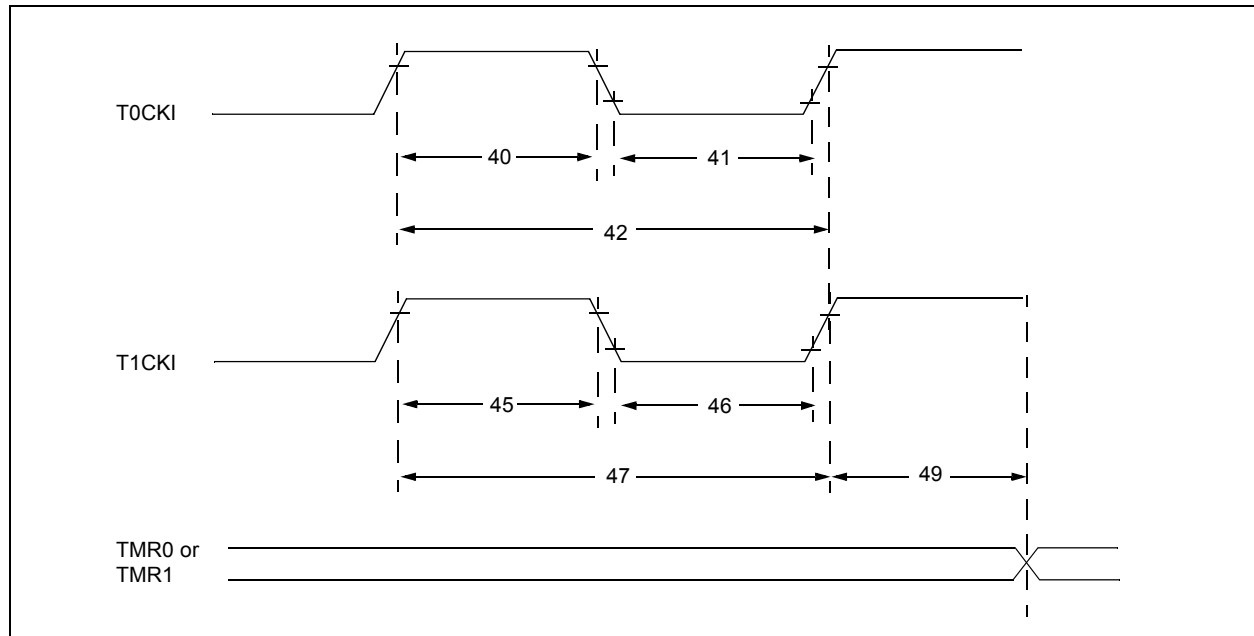
**Note 1:** Instruction cycle period ( $T_{CY}$ ) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to the OSC1 pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.

2: By design.

3: Period of the slower clock.

4: To ensure these voltage tolerances,  $V_{DD}$  and  $V_{SS}$  must be capacitively decoupled as close to the device as possible. 0.1  $\mu\text{F}$  and 0.01  $\mu\text{F}$  values in parallel are recommended.

**FIGURE 30-10: TIMER0 AND TIMER1 EXTERNAL CLOCK TIMINGS**





## 32.11 PICkit 2 Development Programmer/Debugger and PICkit 2 Debug Express

The PICkit™ 2 Development Programmer/Debugger is a low-cost development tool with an easy to use interface for programming and debugging Microchip's Flash families of microcontrollers. The full featured Windows® programming interface supports baseline (PIC10F, PIC12F5xx, PIC16F5xx), midrange (PIC12F6xx, PIC16F), PIC18F, PIC24, dsPIC30, dsPIC33, and PIC32 families of 8-bit, 16-bit, and 32-bit microcontrollers, and many Microchip Serial EEPROM products. With Microchip's powerful MPLAB Integrated Development Environment (IDE) the PICkit™ 2 enables in-circuit debugging on most PIC® microcontrollers. In-Circuit-Debugging runs, halts and single steps the program while the PIC microcontroller is embedded in the application. When halted at a breakpoint, the file registers can be examined and modified.

The PICkit 2 Debug Express include the PICkit 2, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

## 32.12 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an MMC card for file storage and data applications.

## 32.13 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page ([www.microchip.com](http://www.microchip.com)) for the complete list of demonstration, development and evaluation kits.

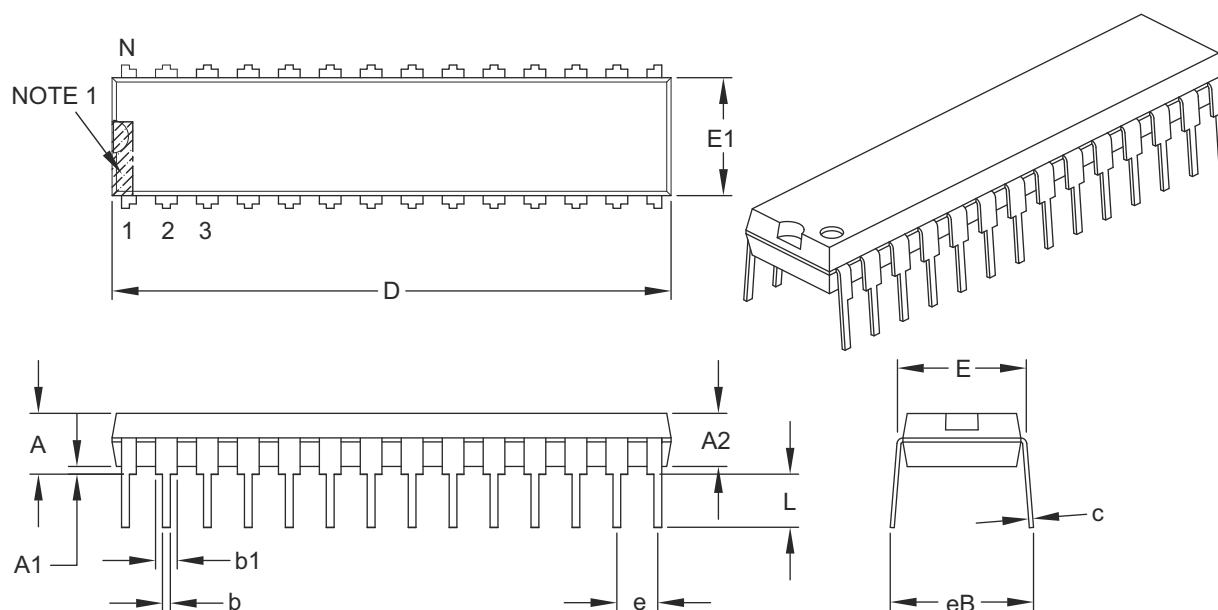
# PIC16(L)F1934/6/7

## 33.2 Package Details

The following sections give the technical details of the packages.

### 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	INCHES		
		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	.100 BSC		
Top to Seating Plane	A	–	–	.200
Molded Package Thickness	A2	.120	.135	.150
Base to Seating Plane	A1	.015	–	–
Shoulder to Shoulder Width	E	.290	.310	.335
Molded Package Width	E1	.240	.285	.295
Overall Length	D	1.345	1.365	1.400
Tip to Seating Plane	L	.110	.130	.150
Lead Thickness	c	.008	.010	.015
Upper Lead Width	b1	.040	.050	.070
Lower Lead Width	b	.014	.018	.022
Overall Row Spacing §	eB	–	–	.430

**Notes:**

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- Dimensioning and tolerancing per ASME Y14.5M.

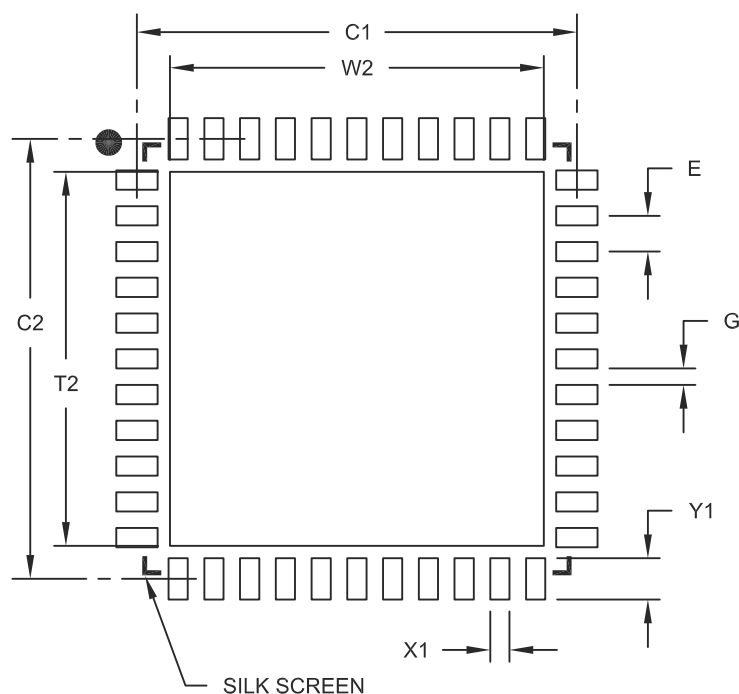
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

# PIC16(L)F1934/6/7

## 44-Lead Plastic Quad Flat, No Lead Package (ML) – 8x8 mm Body [QFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packages>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			6.80
Optional Center Pad Length	T2			6.80
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.80
Distance Between Pads	G	0.25		

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103A

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