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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, LCD, POR, PWM, WDT
Number of I/O	82
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 16x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f439vit6">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f439vit6</a>

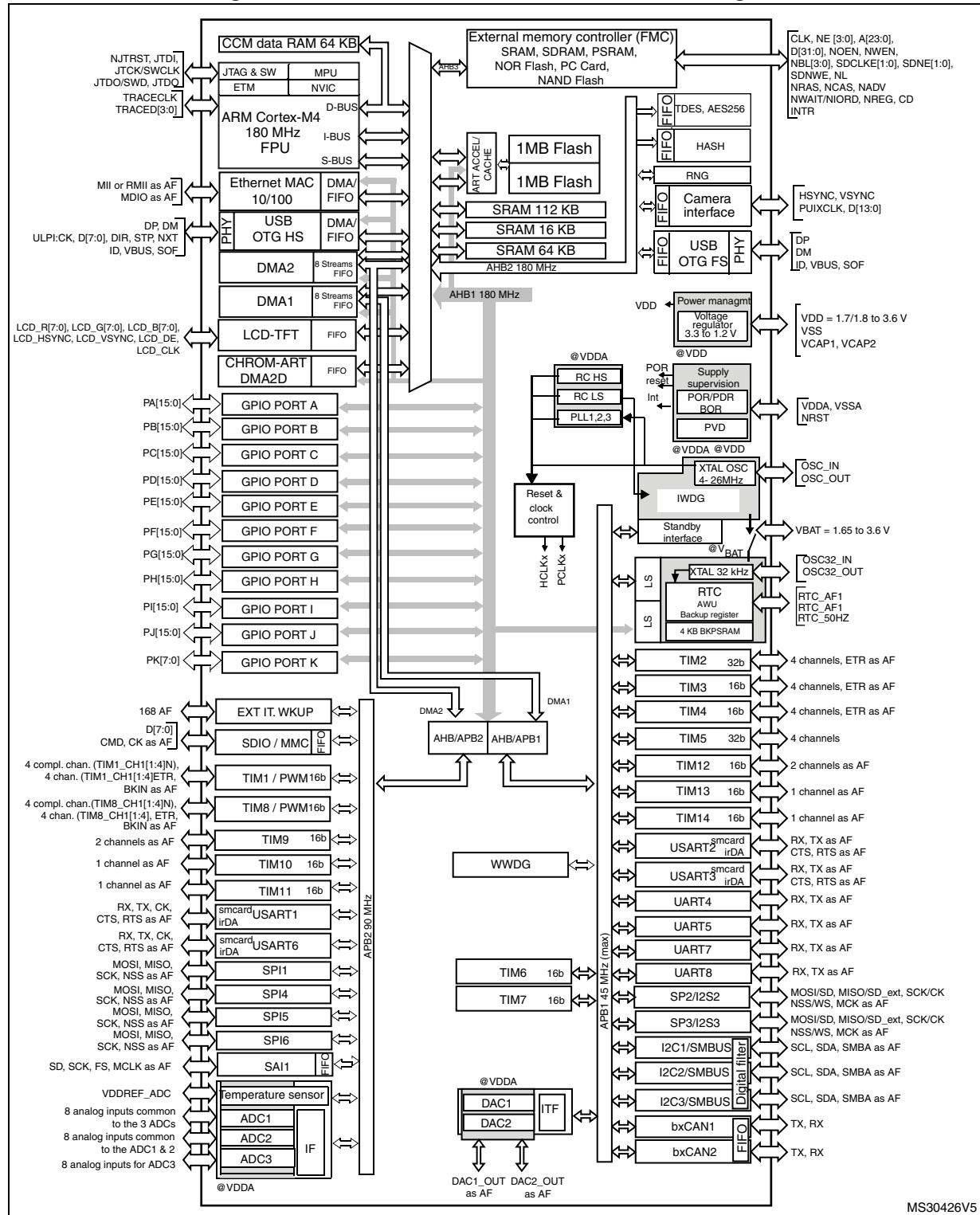
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Table 2. STM32F437xx and STM32F439xx features and peripheral counts (continued)

Peripherals		STM32F437 Vx	STM32F439 Vx	STM32F437Zx	STM32F437AI	STM32F439AI	STM32F439Zx	STM32F437Ix	STM32F439Ix	STM32F439Bx	STM32F439Nx	
Communication interfaces	SPI / I <sup>2</sup> S	4/2 (full duplex) <sup>(2)</sup>				6/2 (full duplex) <sup>(2)</sup>						
	I <sup>2</sup> C			3								
	USART/ UART			4/4								
	USB OTG FS			Yes								
	USB OTG HS			Yes								
	CAN			2								
	SAI			1								
	SDIO			Yes								
Camera interface				Yes								
LCD-TFT		No	Yes	No	Yes	Yes	No	Yes				
Chrom-ART Accelerator™ (DMA2D)				Yes								
Cryptography				Yes								
GPIOs		82		114		140		168		168		
12-bit ADC Number of channels			3									
	16		24									
12-bit DAC Number of channels		Yes		2								
Maximum CPU frequency		180 MHz										
Operating voltage		1.7 to 3.6 V <sup>(3)</sup>										
Operating temperatures			Ambient temperatures: -40 to +85 °C / -40 to +105 °C									
			Junction temperature: -40 to + 125 °C									
Package	LQFP100	WLCSP143 LQFP144	UFBGA169	WLCSP143 LQFP144	UFBGA176 LQFP176	LQFP208	TFBGA216					

1. For the LQFP100 package, only FMC Bank1 or Bank2 are available. Bank1 can only support a multiplexed NOR/PSRAM memory using the NE1 Chip Select. Bank2 can only support a 16- or 8-bit NAND Flash memory using the NCE2 Chip Select. The interrupt line cannot be used since Port G is not available in this package.
2. The SPI2 and SPI3 interfaces give the flexibility to work in an exclusive way in either the SPI mode or the I2S audio mode.
3. V<sub>DD</sub>/V<sub>DDA</sub> minimum value of 1.7 V is obtained with the use of an external power supply supervisor (refer to [Section 3.17.2: Internal reset OFF](#)).

Figure 4. STM32F437xx and STM32F439xx block diagram



1. The timers connected to APB2 are clocked from TIMxCLK up to 180 MHz, while the timers connected to APB1 are clocked from TIMxCLK either up to 90 MHz or 180 MHz depending on TIMPRE bit configuration in the RCC\_DCKCFGR register.
2. The LCD-TFT is available only on STM32F439xx devices.

## 3 Functional overview

### 3.1 ARM® Cortex®-M4 with FPU and embedded Flash and SRAM

The ARM® Cortex®-M4 with FPU processor is the latest generation of ARM processors for embedded systems. It was developed to provide a low-cost platform that meets the needs of MCU implementation, with a reduced pin count and low-power consumption, while delivering outstanding computational performance and an advanced response to interrupts.

The ARM® Cortex®-M4 with FPU core is a 32-bit RISC processor that features exceptional code-efficiency, delivering the high-performance expected from an ARM core in the memory size usually associated with 8- and 16-bit devices.

The processor supports a set of DSP instructions which allow efficient signal processing and complex algorithm execution.

Its single precision FPU (floating point unit) speeds up software development by using metalanguage development tools, while avoiding saturation.

The STM32F43x family is compatible with all ARM tools and software.

*Figure 4* shows the general block diagram of the STM32F43x family.

*Note:* Cortex-M4 with FPU core is binary compatible with the Cortex-M3 core.

### 3.2 Adaptive real-time memory accelerator (ART Accelerator™)

The ART Accelerator™ is a memory accelerator which is optimized for STM32 industry-standard ARM® Cortex®-M4 with FPU processors. It balances the inherent performance advantage of the ARM® Cortex®-M4 with FPU over Flash memory technologies, which normally requires the processor to wait for the Flash memory at higher frequencies.

To release the processor full 225 DMIPS performance at this frequency, the accelerator implements an instruction prefetch queue and branch cache, which increases program execution speed from the 128-bit Flash memory. Based on CoreMark benchmark, the performance achieved thanks to the ART Accelerator is equivalent to 0 wait state program execution from Flash memory at a CPU frequency up to 180 MHz.

### 3.3 Memory protection unit

The memory protection unit (MPU) is used to manage the CPU accesses to memory to prevent one task to accidentally corrupt the memory or resources used by any other active task. This memory area is organized into up to 8 protected areas that can in turn be divided up into 8 subareas. The protection area sizes are between 32 bytes and the whole 4 gigabytes of addressable memory.

The MPU is especially helpful for applications where some critical or certified code has to be protected against the misbehavior of other tasks. It is usually managed by an RTOS (real-time operating system). If a program accesses a memory location that is prohibited by the MPU, the RTOS can detect it and take action. In an RTOS environment, the kernel can dynamically update the MPU area setting, based on the process to be executed.

The MPU is optional and can be bypassed for applications that do not need it.

The DMA can be used with the main peripherals:

- SPI and I<sup>2</sup>S
- I<sup>2</sup>C
- USART
- General-purpose, basic and advanced-control timers TIMx
- DAC
- SDIO
- Cryptographic acceleration
- Camera interface (DCMI)
- ADC
- SAI1.

### 3.9 Flexible memory controller (FMC)

All devices embed an FMC. It has four Chip Select outputs supporting the following modes: PCCard/Compact Flash, SDRAM/LPSDR SDRAM, SRAM, PSRAM, NOR Flash and NAND Flash.

Functionality overview:

- 8-, 16-, 32-bit data bus width
- Read FIFO for SDRAM controller
- Write FIFO
- Maximum FMC\_CLK/FMC\_SDCLK frequency for synchronous accesses is 90 MHz.

#### LCD parallel interface

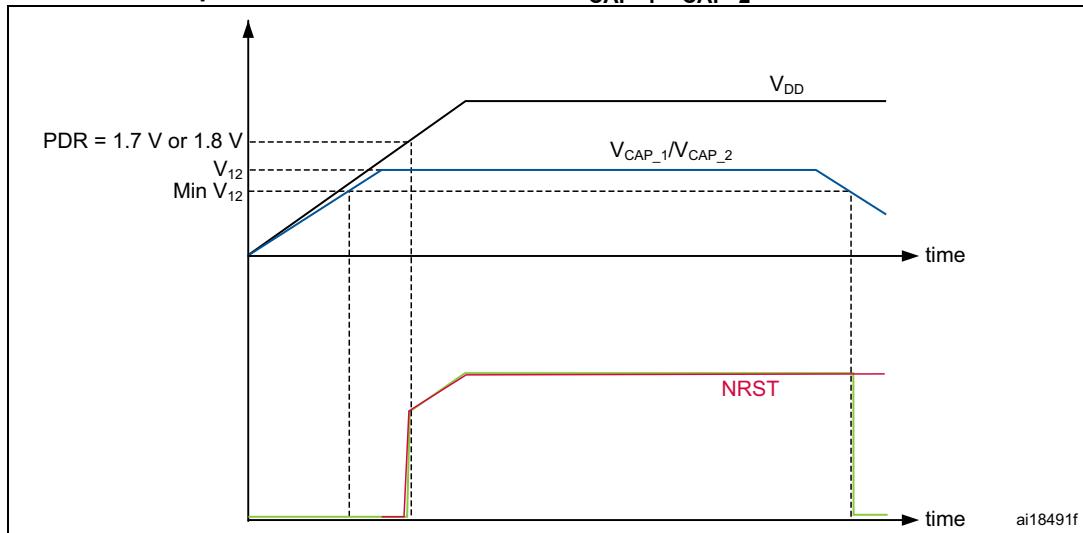
The FMC can be configured to interface seamlessly with most graphic LCD controllers. It supports the Intel 8080 and Motorola 6800 modes, and is flexible enough to adapt to specific LCD interfaces. This LCD parallel interface capability makes it easy to build cost-effective graphic applications using LCD modules with embedded controllers or high performance solutions using external controllers with dedicated acceleration.

### 3.10 LCD-TFT controller (available only on STM32F439xx)

The LCD-TFT display controller provides a 24-bit parallel digital RGB (Red, Green, Blue) and delivers all signals to interface directly to a broad range of LCD and TFT panels up to XGA (1024x768) resolution with the following features:

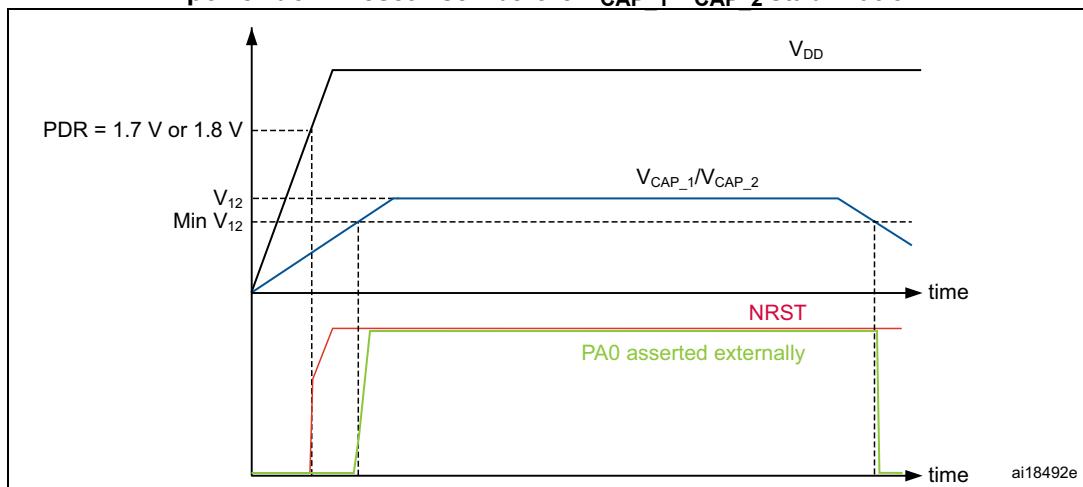
- 2 displays layers with dedicated FIFO (64x32-bit)
- Color Look-Up table (CLUT) up to 256 colors (256x24-bit) per layer
- Up to 8 Input color formats selectable per layer
- Flexible blending between two layers using alpha value (per pixel or constant)
- Flexible programmable parameters for each layer
- Color keying (transparency color)
- Up to 4 programmable interrupt events.

**Figure 9. Startup in regulator OFF: slow  $V_{DD}$  slope  
- power-down reset risen after  $V_{CAP\_1}/V_{CAP\_2}$  stabilization**



1. This figure is valid whatever the internal reset mode (ON or OFF).

**Figure 10. Startup in regulator OFF mode: fast  $V_{DD}$  slope  
- power-down reset risen before  $V_{CAP\_1}/V_{CAP\_2}$  stabilization**



1. This figure is valid whatever the internal reset mode (ON or OFF).

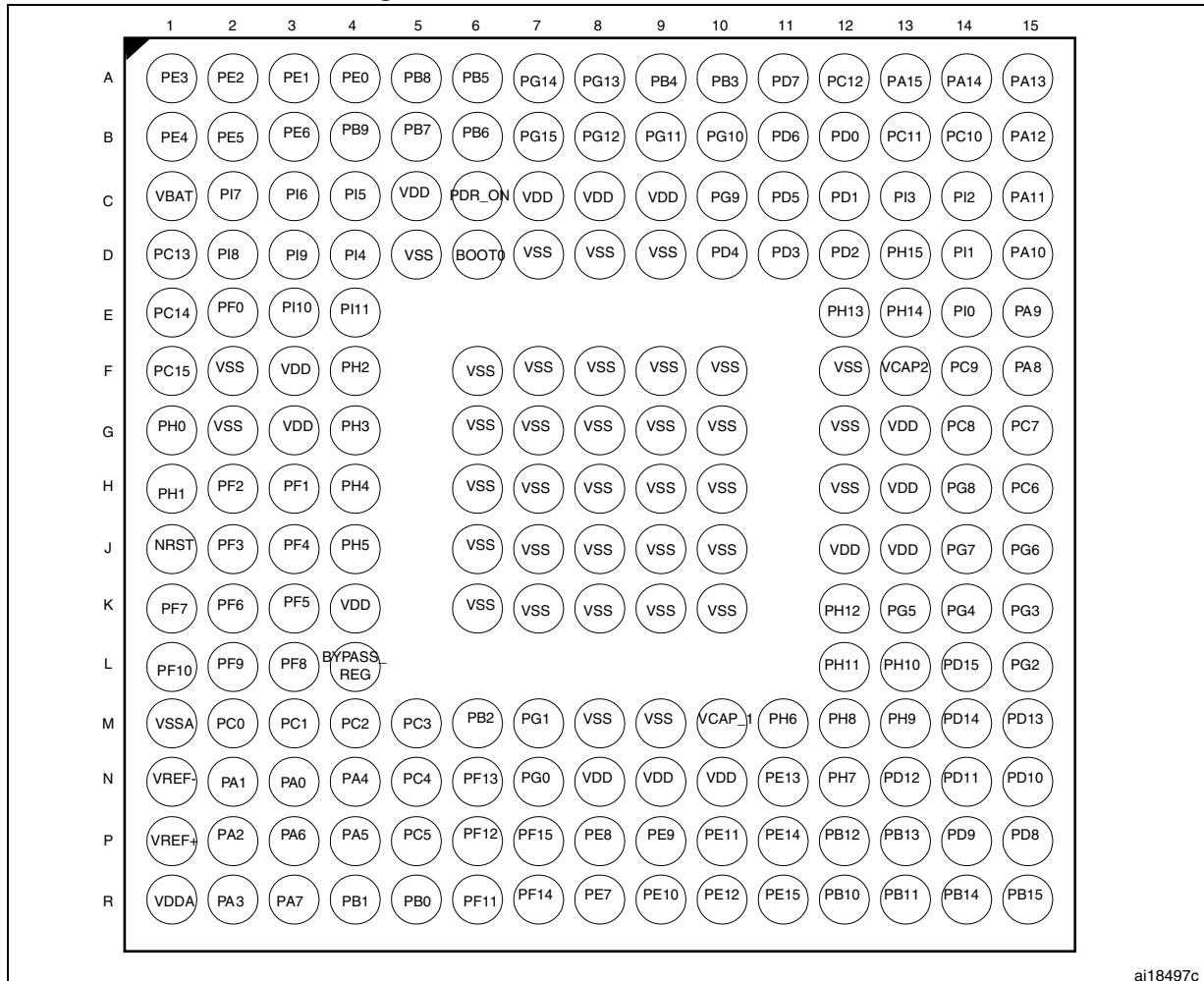
MS30422V2

Figure 15. STM32F43x LQFP208 pinout

	LQFP208	
PE2	53	1
PE3	54	2
PE4	55	3
PE5	56	4
PE6	57	5
VBAT	58	6
PI8	59	7
PC13	60	8
PC14	61	9
PC15	62	10
PI9	63	11
PI10	64	12
PI11	65	13
VSS	66	14
VDD	67	15
PF0	68	16
PF1	69	17
PF2	70	18
PI12	71	19
PI13	72	20
PI14	73	21
PF3	74	22
PF4	75	23
PF5	76	24
VSS	77	25
VDD	78	26
PF6	79	27
PF7	80	28
PF8	81	29
PF9	82	30
PF10	83	31
PH0	84	32
PH1	85	33
NRST	86	34
PC0	87	35
PC1	88	36
PC2	89	37
PC3	90	38
VDD	91	39
VSSA	92	40
VREF+	93	41
VDDA	94	42
PA0	95	43
PA1	96	44
PA2	97	45
PH2	98	46
PH3	99	47
PH4	100	48
PH5	101	49
PA3	102	50
VSS	103	51
VDD	104	52
PA4	53	PIT
PA5	54	P16
PA6	55	P15
PA7	56	P14
PC4	57	VDD
PC5	58	PDR_ON
VDD	59	VSS
VSS	60	202
PB0	61	201 PE1
PB1	62	200 PE0
PB2	63	199 PB8
PB3	64	198 PB9
PB4	65	197 BOOT0
PJ0	66	196 PB7
PJ1	67	195 PB6
PJ2	68	194 PB5
PJ3	69	193 PB4
PJ4	70	192 PB3
PJ5	71	191 PG15
PJ6	72	190 PK7
PJ7	73	189 PK6
PF13	74	188 PK5
PF14	75	187 PK4
PF15	76	186 PK3
PG0	77	185 VDD
PG1	78	184 VSS
PE7	79	183 PG14
PE8	80	182 PG13
PE9	81	181 PG12
VDD	82	180 PG11
VSS	83	179 PG10
VDD	84	178 PG9
FE10	85	177 PJ15
FE11	86	176 PJ14
FE12	87	175 PJ13
FE13	88	174 PJ12
FE14	89	173 PD7
FE15	90	172 PD6
PB10	91	171 VDD
VCAP1	92	170 VSS
VSS	93	169 PD5
VDD	94	168 PD4
PJ5	95	167 PD3
PH6	96	166 PD2
PH7	97	165 PD1
PH8	98	164 PD0
PH9	99	163 PC12
PH10	100	162 PC11
PH11	101	161 PC10
PH12	102	160 PA15
VDD	103	159 PA14
VDD	104	158 VDD
		157 P13
		156 PI2
		155 PI1
		154 PIO
		153 PH15
		152 PH14
		151 PH13
		150 VDD
		149 VSS
		148 VCAP2
		147 PA13
		146 PA12
		145 PA11
		144 PA10
		143 PA9
		142 PA8
		141 PC9
		140 PC8
		139 PC7
		138 PC6
		137 VDD
		136 VSS
		135 PG8
		134 PG7
		133 PG6
		132 PG5
		131 PG4
		130 PG3
		129 PG2
		128 PK2
		127 PK1
		126 PK0
		125 VSS
		124 VDD
		123 PJ11
		122 PJ10
		121 PJ9
		120 PJ8
		119 PJ7
		118 PJ6
		117 PD15
		116 PD14
		115 VDD
		114 VSS
		113 PD13
		112 PD12
		111 PD11
		110 PD10
		109 PD9
		108 PD8
		107 PB15
		106 PB14
		105 PB13

- The above figure shows the package top view.

Figure 17. STM32F43x UFBGA176 ballout



ai18497c

- The above figure shows the package top view.

**Table 9. Legend/abbreviations used in the pinout table**

Name	Abbreviation	Definition					
Pin name	Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name						
Pin type	S	Supply pin					
	I	Input only pin					
	I/O	Input / output pin					
I/O structure	FT	5 V tolerant I/O					
	TTa	3.3 V tolerant I/O directly connected to ADC					
	B	Dedicated BOOT0 pin					
	RST	Bidirectional reset pin with weak pull-up resistor					
Notes	Unless otherwise specified by a note, all I/Os are set as floating inputs during and after reset						
Alternate functions	Functions selected through GPIOx_AFR registers						
Additional functions	Functions directly selected/enabled through peripheral registers						

**Table 10. STM32F437xx and STM32F439xx pin and ball definitions**

Pin number								Pin name (function after reset) <sup>(1)</sup>	Pin type	I / O structure	Notes	Alternate functions	Additional functions
LQFP100	LQFP144	UFBGA169	UFBGA176	LQFP176	WLCSP143	LQFP208	TFBGA216						
1	1	B2	A2	1	D8	1	A3	PE2	I/O	FT	-	TRACECLK, SPI4_SCK, SAI1_MCLK_A, ETH_MII_TXD3, FMC_A23, EVENTOUT	-
2	2	C1	A1	2	C10	2	A2	PE3	I/O	FT	-	TRACED0, SAI1_SD_B, FMC_A19, EVENTOUT	-
3	3	C2	B1	3	B11	3	A1	PE4	I/O	FT	-	TRACED1, SPI4_NSS, SAI1_FS_A, FMC_A20, DCMI_D4, LCD_B0, EVENTOUT	-

Table 10. STM32F437xx and STM32F439xx pin and ball definitions (continued)

Pin number									Pin name (function after reset) <sup>(1)</sup>	Pin type	I / O structure	Notes	Alternate functions	Additional functions
LQFP100	LQFP144	UFBGA169	UFBGA176	LQFP176	WL CSP143	LQFP208	TFBGA216							
68	101	E8	E15	120	E2	143	E15	PA9	I/O	FT	-	TIM1_CH2, I2C3_SMBA, USART1_TX, DCMI_D0, EVENTOUT	OTG_FS_VBUS	
69	102	E9	D15	121	D5	144	D15	PA10	I/O	FT	-	TIM1_CH3, USART1_RX, OTG_FS_ID, DCMI_D1, EVENTOUT	-	
70	103	E10	C15	122	D4	145	C15	PA11	I/O	FT	-	TIM1_CH4, USART1_CTS, CAN1_RX, LCD_R4, OTG_FS_DM, EVENTOUT	-	
71	104	E11	B15	123	E1	146	B15	PA12	I/O	FT	-	TIM1_ETR, USART1_RTS, CAN1_TX, LCD_R5, OTG_FS_DP, EVENTOUT	-	
72	105	E12	A15	124	D3	147	A15	PA13 (JTMS-SWDIO)	I/O	FT	-	JTMS-SWDIO, EVENTOUT	-	
73	106	D12	F13	125	D1	148	E11	V <sub>CAP_2</sub>	S		-	-	-	
74	107	J10	F12	126	D2	149	F10	V <sub>SS</sub>	S		-	-	-	
75	108	H4	G13	127	C1	150	F11	V <sub>DD</sub>	S		-	-	-	
-	-	D13	E12	128	-	151	E12	PH13	I/O	FT	-	TIM8_CH1N, CAN1_TX, FMC_D21, LCD_G2, EVENTOUT	-	
-	-	C13	E13	129	-	152	E13	PH14	I/O	FT	-	TIM8_CH2N, FMC_D22, DCMI_D4, LCD_G3, EVENTOUT	-	
-	-	C12	D13	130	-	153	D13	PH15	I/O	FT	-	TIM8_CH3N, FMC_D23, DCMI_D11, LCD_G4, EVENTOUT	-	
-	-	B13	E14	131	-	154	E14	PI0	I/O	FT	-	TIM5_CH4, SPI2_NSS/I2S2_WS <sup>(7)</sup> , FMC_D24, DCMI_D13, LCD_G5, EVENTOUT	-	

Table 11. FMC pin definition (continued)

Pin name	CF	NOR/PSRAM/ SRAM	NOR/PSRAM Mux	NAND16	SDRAM
PE11	D8	D8	DA8	D8	D8
PE12	D9	D9	DA9	D9	D9
PE13	D10	D10	DA10	D10	D10
PE14	D11	D11	DA11	D11	D11
PE15	D12	D12	DA12	D12	D12
PD8	D13	D13	DA13	D13	D13
PD9	D14	D14	DA14	D14	D14
PD10	D15	D15	DA15	D15	D15
PH8		D16			D16
PH9		D17			D17
PH10		D18			D18
PH11		D19			D19
PH12		D20			D20
PH13		D21			D21
PH14		D22			D22
PH15		D23			D23
PI0		D24			D24
PI1		D25			D25
PI2		D26			D26
PI3		D27			D27
PI6		D28			D28
PI7		D29			D29
PI9		D30			D30
PI10		D31			D31
PD7		NE1	NE1	NCE2	
PG9		NE2	NE2	NCE3	
PG10	NCE4_1	NE3	NE3		
PG11	NCE4_2				
PG12		NE4	NE4		
PD3		CLK	CLK		
PD4	NOE	NOE	NOE	NOE	
PD5	NWE	NWE	NWE	NWE	
PD6	NWAIT	NWAIT	NWAIT	NWAIT	
PB7		NL(NADV)	NL(NADV)		

Table 12. STM32F437xx and STM32F439xx alternate function mapping (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/ 10/11	I2C1/ 2/3	SPI1/2/ 3/4/5/6	SPI2/3/ SAI1	SPI3/ USART1/ 2/3	USART6/ UART4/5/7/ 8	CAN1/2/ TIM12/13/14/ LCD	OTG2_HS/ OTG1_FS	ETH	FMC/SDIO/ OTG2_FS	DCMI	LCD	SYS
Port G	PG9	-	-	-	-	-	-	-	-	USART6_RX	-	-	-	FMC_NE2/ FMC_NCE3	DCMI_VSYNC (1)	-	EVEN TOUT
	PG10	-	-	-	-	-	-	-	-	-	LCD_G3	-	-	FMC_NCE4_1/ FMC_NE3	DCMI_D2	LCD_B2	EVEN TOUT
	PG11	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_TX_EN/ ETH_RMII_TX_EN	FMC_NCE4_2	DCMI_D3	LCD_B3	EVEN TOUT
	PG12	-	-	-	-	-	SPI6_MISO	-	-	USART6_RTS	LCD_B4	-	-	FMC_NE4	-	LCD_B1	EVEN TOUT
	PG13	-	-	-	-	-	SPI6_SCK	-	-	USART6_CTS	-	-	ETH_MII_TXD0/ ETH_RMII_TXD0	FMC_A24	-	-	EVEN TOUT
	PG14	-	-	-	-	-	SPI6_MOSI	-	-	USART6_TX	-	-	ETH_MII_TXD1/ ETH_RMII_TXD1	FMC_A25	-	-	EVEN TOUT
	PG15	-	-	-	-	-	-	-	-	USART6_CTS	-	-	-	FMC_SDNCAS	DCMI_D13	-	EVEN TOUT
Port H	PH0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PH1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	EVEN TOUT
	PH2	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_CRS	FMC_SDCKE0	-	LCD_R0	EVEN TOUT
	PH3	-	-	-	-	-	-	-	-	-	-	-	ETH_MII_COL	FMC_SDNE0	-	LCD_R1	EVEN TOUT
	PH4	-	-	-	-	-	I2C2_SCL	-	-	-	-	-	OTG_HS_ULPI_NXT	-	-	-	EVEN TOUT
	PH5	-	-	-	-	-	I2C2_SDA	SPI5_N_SS	-	-	-	-	-	FMC_SDN_WE	-	-	EVEN TOUT
	PH6	-	-	-	-	-	I2C2_SMBA	SPI5_SCK	-	-	-	TIM12_CH1	-	-	FMC_SDNE1	DCMI_D8	-

### On-chip peripheral current consumption

The MCU is placed under the following conditions:

- At startup, all I/O pins are in analog input configuration.
- All peripherals are disabled unless otherwise mentioned.
- I/O compensation cell enabled.
- The ART accelerator is ON.
- Scale 1 mode selected, internal digital voltage  $V_{12} = 1.32$  V.
- HCLK is the system clock.  $f_{PCLK1} = f_{HCLK}/4$ , and  $f_{PCLK2} = f_{HCLK}/2$ .

The given value is calculated by measuring the difference of current consumption

- with all peripherals clocked off
- with only one peripheral clocked on
- $f_{HCLK} = 180$  MHz (Scale1 + over-drive ON),  $f_{HCLK} = 144$  MHz (Scale 2),  
 $f_{HCLK} = 120$  MHz (Scale 3)"

- Ambient operating temperature is 25 °C and  $V_{DD}=3.3$  V.

**Table 35. Peripheral current consumption**

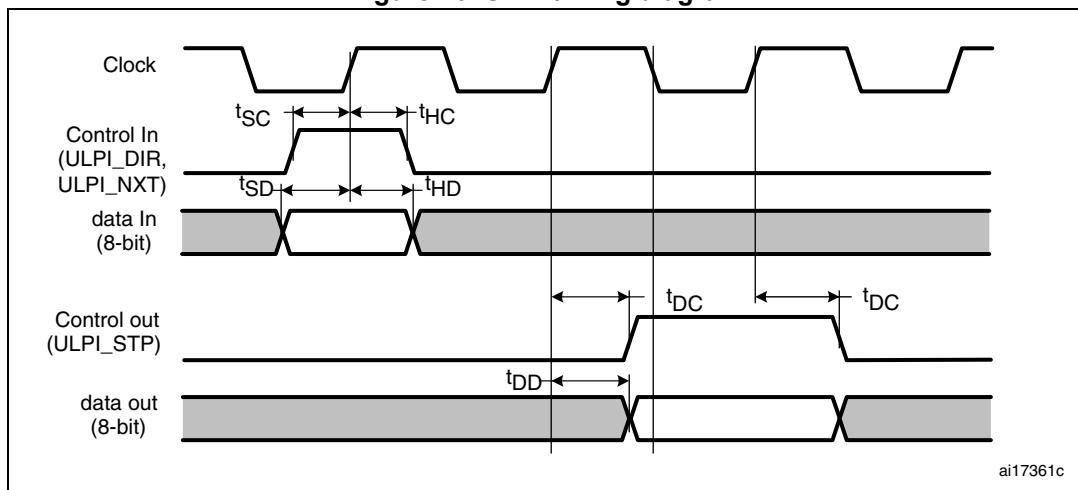
Peripheral	$I_{DD(\text{Typ})}^{(1)}$			Unit
	Scale 1	Scale 2	Scale 3	
AHB1 (up to 180 MHz)	GPIOA	2.50	2.36	2.08
	GPIOB	2.56	2.36	2.08
	GPIOC	2.44	2.29	2.00
	GPIOD	2.50	2.36	2.08
	GPIOE	2.44	2.29	2.00
	GPIOF	2.44	2.29	2.00
	GPIOG	2.39	2.22	2.00
	GPIOH	2.33	2.15	1.92
	GPIOI	2.39	2.22	2.00
	GPIOJ	2.33	2.15	1.92
	GPIOK	2.33	2.15	1.92
	OTG_HS+ULPI	27.00	24.86	21.92
	CRC	0.44	0.42	0.33
	BKPSRAM	0.78	0.69	0.58
	DMA1	25.33	23.26	20.50
	DMA2	24.72	22.71	20.00
	DMA2D	28.50	26.32	23.33
	ETH_MAC ETH_MAC_TX ETH_MAC_RX ETH_MAC_PTP	21.56	20.07	17.75

Table 69. USB HS clock timing parameters<sup>(1)</sup>

Symbol	Parameter		Min	Typ	Max	Unit
	$f_{HCLK}$ value to guarantee proper operation of USB HS interface		30	-	-	MHz
$F_{START\_8BIT}$	Frequency (first transition) 8-bit ±10%		54	60	66	MHz
$F_{STEADY}$	Frequency (steady state) ±500 ppm		59.97	60	60.03	MHz
$D_{START\_8BIT}$	Duty cycle (first transition) 8-bit ±10%		40	50	60	%
$D_{STEADY}$	Duty cycle (steady state) ±500 ppm		49.975	50	50.025	%
$t_{STEADY}$	Time to reach the steady state frequency and duty cycle after the first transition		-	-	1.4	ms
$t_{START\_DEV}$	Clock startup time after the de-assertion of SuspendM	Peripheral	-	-	5.6	ms
$t_{START\_HOST}$		Host	-	-	-	
$t_{PREP}$	PHY preparation time after the first transition of the input clock		-	-	-	μs

1. Guaranteed by design.

Figure 46. ULPI timing diagram



ai17361c

Table 74. ADC characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_S^{(2)}$	Sampling rate ( $f_{ADC} = 30$ MHz, and $t_S = 3$ ADC cycles)	12-bit resolution Single ADC	-	-	2	MspS
		12-bit resolution Interleave Dual ADC mode	-	-	3.75	MspS
		12-bit resolution Interleave Triple ADC mode	-	-	6	MspS
$I_{VREF+}^{(2)}$	ADC $V_{REF}$ DC current consumption in conversion mode		-	300	500	$\mu$ A
$I_{VDDA}^{(2)}$	ADC $V_{DDA}$ DC current consumption in conversion mode		-	1.6	1.8	mA

1.  $V_{DDA}$  minimum value of 1.7 V is obtained with the use of an external power supply supervisor (refer to [Section 3.17.2: Internal reset OFF](#)).
2. Guaranteed by characterization results.
3.  $V_{REF+}$  is internally connected to  $V_{DDA}$  and  $V_{REF-}$  is internally connected to  $V_{SSA}$ .
4.  $R_{ADC}$  maximum value is given for  $V_{DD}=1.7$  V, and minimum value for  $V_{DD}=3.3$  V.
5. For external triggers, a delay of  $1/f_{PCLK2}$  must be added to the latency specified in [Table 74](#).

Equation 1:  $R_{AIN}$  max formula

$$R_{AIN} = \frac{(k - 0.5)}{f_{ADC} \times C_{ADC} \times \ln(2^{N+2})} - R_{ADC}$$

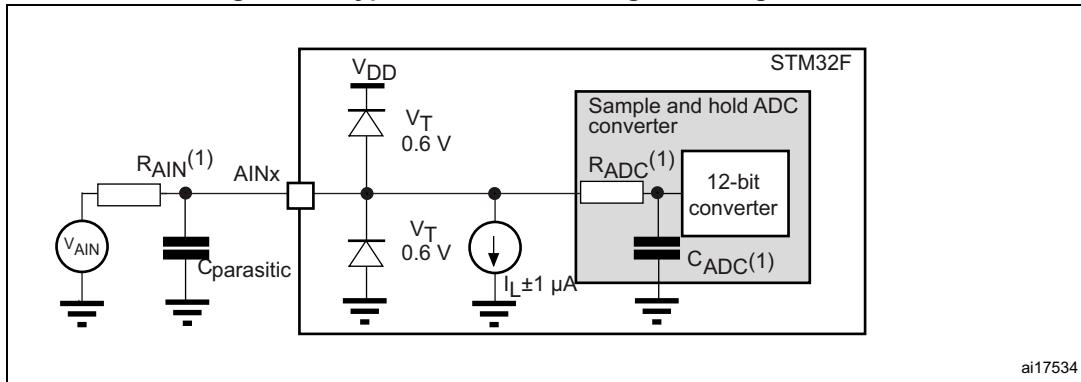
The formula above ([Equation 1](#)) is used to determine the maximum external impedance allowed for an error below 1/4 of LSB. N = 12 (from 12-bit resolution) and k is the number of sampling periods defined in the ADC\_SMPR1 register.

Table 75. ADC static accuracy at  $f_{ADC} = 18$  MHz

Symbol	Parameter	Test conditions	Typ	Max <sup>(1)</sup>	Unit
ET	Total unadjusted error	$f_{ADC} = 18$ MHz $V_{DDA} = 1.7$ to $3.6$ V $V_{REF} = 1.7$ to $3.6$ V $V_{DDA} - V_{REF} < 1.2$ V	$\pm 3$	$\pm 4$	LSB
EO	Offset error		$\pm 2$	$\pm 3$	
EG	Gain error		$\pm 1$	$\pm 3$	
ED	Differential linearity error		$\pm 1$	$\pm 2$	
EL	Integral linearity error		$\pm 2$	$\pm 3$	

1. Guaranteed by characterization results.

Figure 51. Typical connection diagram using the ADC



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1. Refer to [Table 74](#) for the values of  $R_{AIN}$ ,  $R_{ADC}$  and  $C_{ADC}$ .
2.  $C_{parasitic}$  represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (roughly  $5\text{ pF}$ ). A high  $C_{parasitic}$  value downgrades conversion accuracy. To remedy this,  $f_{ADC}$  should be reduced.

### 6.3.23 $V_{BAT}$ monitoring characteristics

**Table 82.  $V_{BAT}$  monitoring characteristics**

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor bridge for $V_{BAT}$	-	50	-	KΩ
Q	Ratio on $V_{BAT}$ measurement	-	4	-	
$E_r^{(1)}$	Error on Q	-1	-	+1	%
$T_{S\_vbat}^{(2)(2)}$	ADC sampling time when reading the $V_{BAT}$ 1 mV accuracy	5	-	-	μs

1. Guaranteed by design.
2. Shortest sampling time can be determined in the application by multiple iterations.

### 6.3.24 Reference voltage

The parameters given in [Table 83](#) are derived from tests performed under ambient temperature and  $V_{DD}$  supply voltage conditions summarized in [Table 17](#).

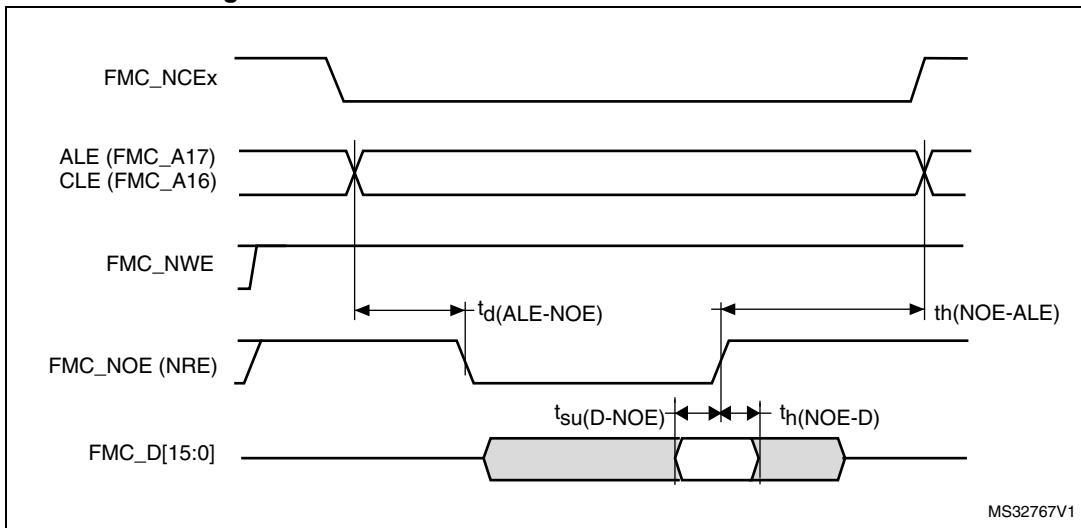
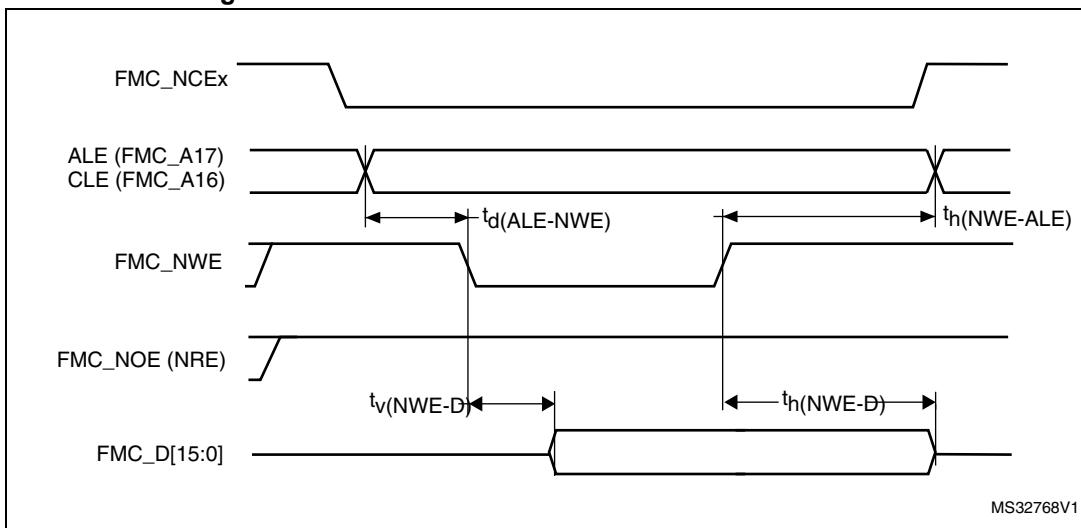
**Table 83. internal reference voltage**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{REFINT}$	Internal reference voltage	$-40^{\circ}\text{C} < T_A < +105^{\circ}\text{C}$	1.18	1.21	1.24	V
$T_{S\_vrefint}^{(1)}$	ADC sampling time when reading the internal reference voltage		10	-	-	μs
$V_{RERINT\_s}^{(2)}$	Internal reference voltage spread over the temperature range	$V_{DD} = 3\text{V} \pm 10\text{mV}$	-	3	5	mV
$T_{Coef}^{(2)}$	Temperature coefficient		-	30	50	ppm/ $^{\circ}\text{C}$
$t_{START}^{(2)}$	Startup time		-	6	10	μs

1. Shortest sampling time can be determined in the application by multiple iterations.
2. Guaranteed by design, not tested in production

**Table 84. Internal reference voltage calibration values**

Symbol	Parameter	Memory address
$V_{REFIN\_CAL}$	Raw data acquired at temperature of $30^{\circ}\text{C}$ $V_{DDA} = 3.3\text{ V}$	0x1FFF 7A2A - 0x1FFF 7A2B

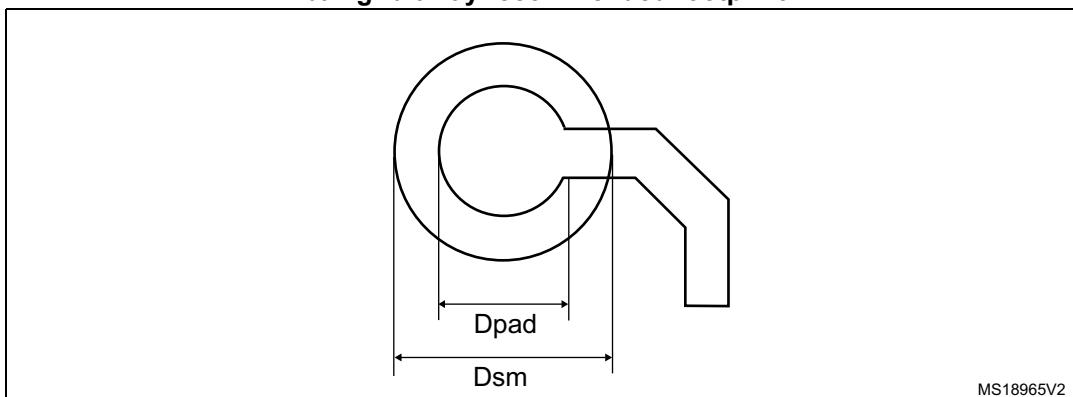
**Figure 69. NAND controller waveforms for read access****Figure 70. NAND controller waveforms for write access**

**Table 116. UFBGA169 - 169-ball 7 x 7 mm 0.50 mm pitch, ultra fine pitch ball grid array package mechanical data (continued)**

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
F	0.450	0.500	0.550	0.0177	0.0197	0.0217
ddd	-	-	0.100	-	-	0.0039
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.050	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.

**Figure 96. UFBGA169 - 169-ball, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array recommended footprint**



**Table 117. UFBGA169 recommended PCB design rules (0.5 mm pitch BGA)**

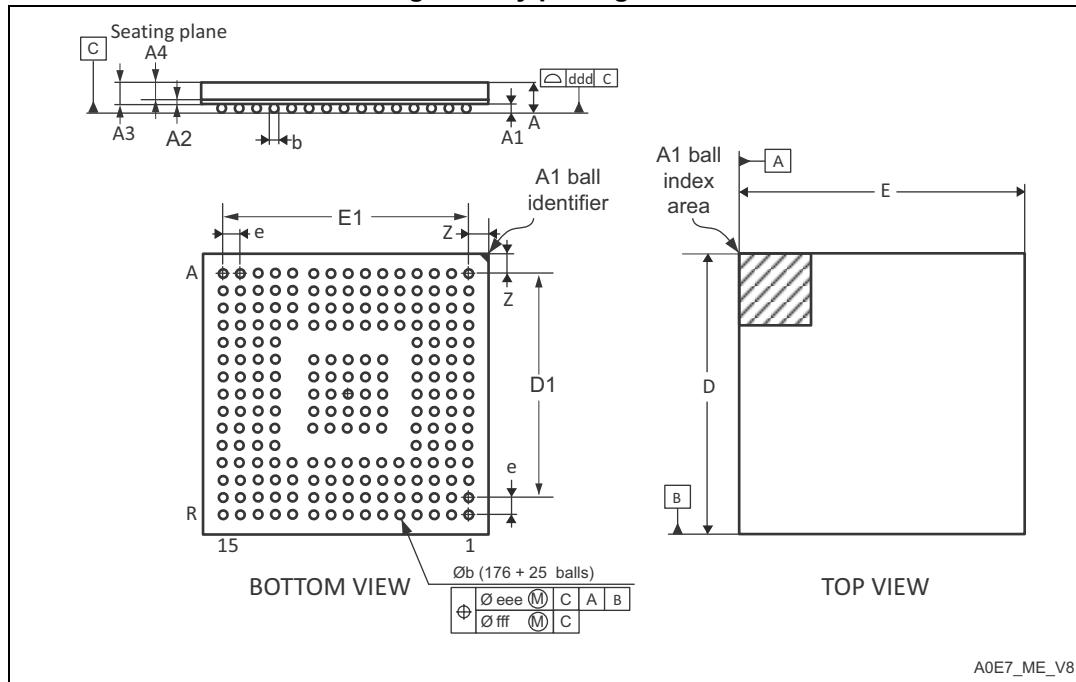
Dimension	Recommended values
Pitch	0.5
Dpad	0.27 mm
Dsm	0.35 mm typ. (depends on the soldermask registration tolerance)
Solder paste	0.27 mm aperture diameter.

**Note:** Non-solder mask defined (NSMD) pads are recommended.

4 to 6 mils solder paste screen printing process.

## 7.7 UFBGA176+25 package information

**Figure 98. UFBGA176+25 - ball 10 x 10 mm, 0.65 mm pitch ultra thin fine pitch ball grid array package outline**



1. Drawing is not to scale.

**Table 118. UFBGA176+25 - ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package mechanical data**

Symbol	millimeters			inches <sup>(1)</sup>		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	-	-	0.600	-	-	0.0236
A1	-	-	0.110	-	-	0.0043
A2	-	0.130	-	-	0.0051	-
A3	-	0.450	-	-	0.0177	-
A4	-	0.320	-	-	0.0126	-
b	0.240	0.290	0.340	0.0094	0.0114	0.0134
D	9.850	10.000	10.150	0.3878	0.3937	0.3996
D1	-	9.100	-	-	0.3583	-
E	9.850	10.000	10.150	0.3878	0.3937	0.3996
E1	-	9.100	-	-	0.3583	-
e	-	0.650	-	-	0.0256	-
Z	-	0.450	-	-	0.0177	-
ddd	-	-	0.080	-	-	0.0031