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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

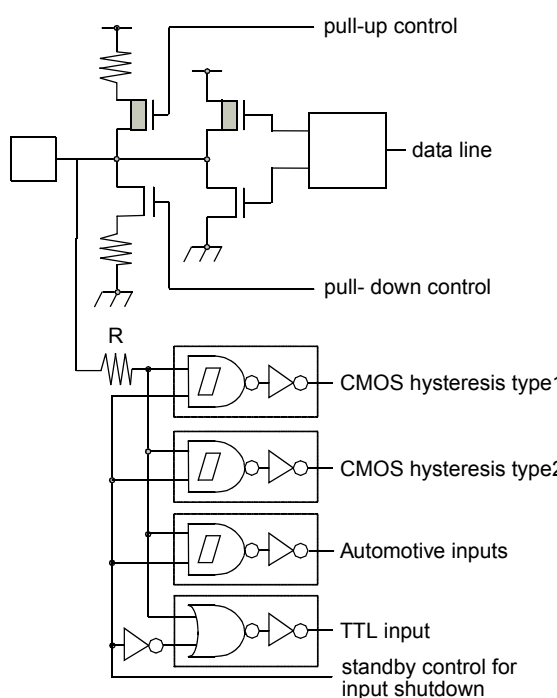
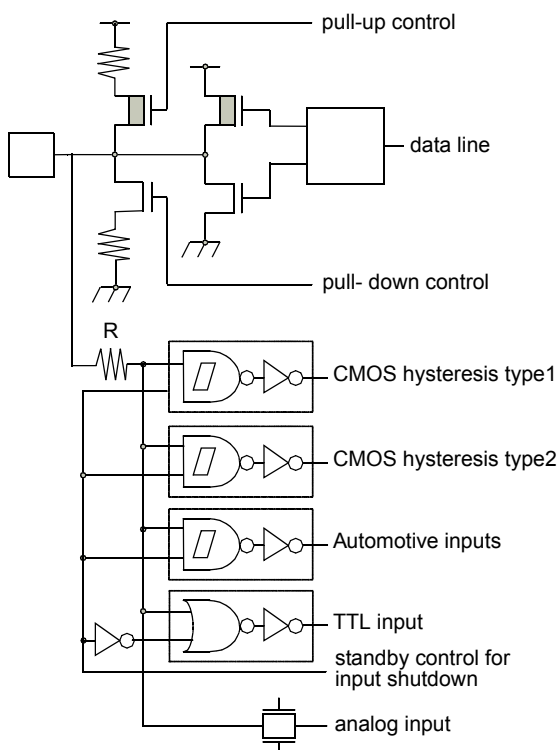
Details

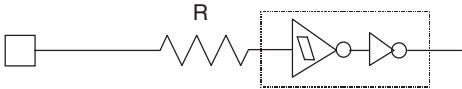
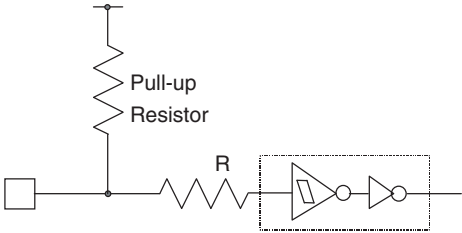
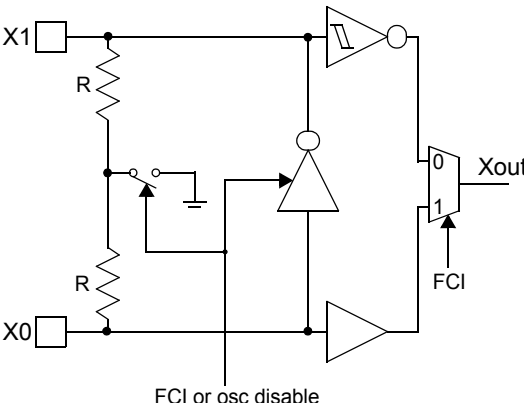
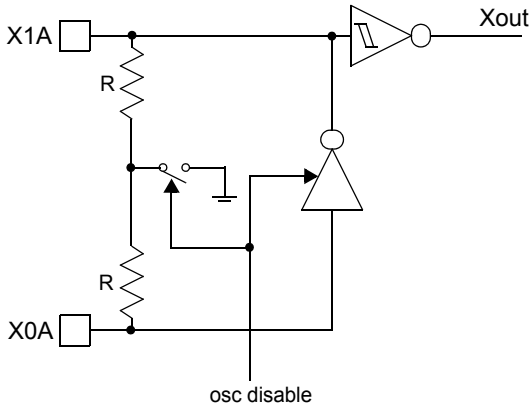
Product Status	Obsolete
Core Processor	FR60 RISC
Core Size	32-Bit Single-Core
Speed	96MHz
Connectivity	CANbus, EBI/EMI, I ² C, LINbus, UART/USART
Peripherals	DMA, LVD, PWM, WDT
Number of I/O	108
Program Memory Size	1.0625MB (1.0625M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	48K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 32x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb91f467bapmc-gse2-w012

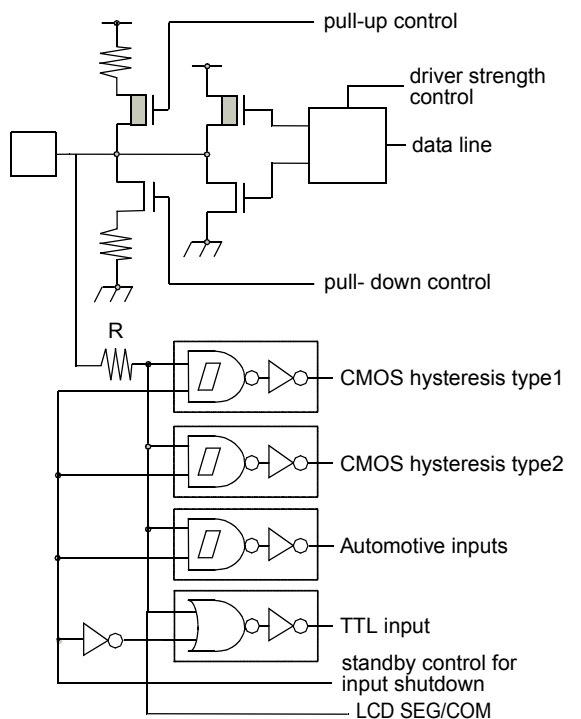
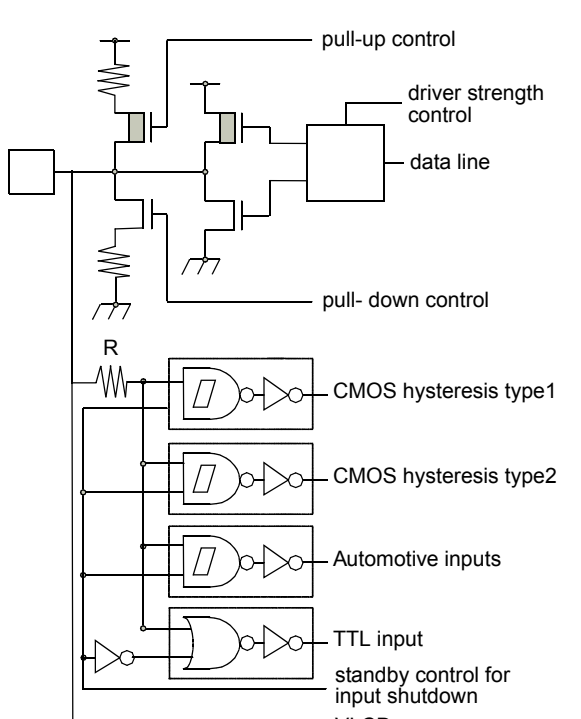
3.2.1 Power supply/Ground pins

Pin no.	Pin name	I/O	Function
1, 19, 37, 55, 73, 81, 86, 91, 109, 127	VSS5	Supply	Ground pins
54, 72, 90, 108, 126	VDD5		Power supply pins
88, 89	VDD5R		Power supply pins for internal regulator
105	AVSS5		Analog ground pin for A/D converter
107	AVCC5		Power supply pin for A/D converter
106	AVRH5		Reference power supply pin for A/D converter
87	VCC18C		Capacitor connection pin for internal regulator
18, 36, 144	VDD35		Power supply pins for external bus part of I/O ring

1. For information about the I/O circuit type, refer to “[I/O Circuit Types](#)”.

Type	Circuit	Remarks
C	 pull-up control data line pull-down control R CMOS hysteresis type1 CMOS hysteresis type2 Automotive inputs TTL input standby control for input shutdown	CMOS level output ($I_{OL} = 3\text{mA}$, $I_{OH} = -3\text{mA}$) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function TTL input with input shutdown function Programmable pull-up resistor: 50kΩ approx.
D	 pull-up control data line pull-down control R CMOS hysteresis type1 CMOS hysteresis type2 Automotive inputs TTL input standby control for input shutdown analog input	CMOS level output ($I_{OL} = 3\text{mA}$, $I_{OH} = -3\text{mA}$) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function TTL input with input shutdown function Programmable pull-up resistor: 50kΩ approx. Analog input

Type	Circuit	Remarks
G		Mask ROM and EVA device: CMOS Hysteresis input pin Flash device: CMOS input pin 12 V withstand (for MD [2:0])
H		CMOS Hysteresis input pin Pull-up resistor value: 50 kΩ approx.
J1		High-speed oscillation circuit: ■ Programmable between oscillation mode (external crystal or resonator connected to X0/X1 pins) and Fast external Clock Input (FCI) mode (external clock connected to X0 pin) ■ Feedback resistor = approx. $2 * 0.5 \text{ M}\Omega$. Feedback resistor is grounded in the center when the oscillator is disabled or in FCI mode.
J2		Low-speed oscillation circuit: ■ Feedback resistor = approx. $2 * 5 \text{ M}\Omega$. Feedback resistor is grounded in the center when the oscillator is disabled.

Type	Circuit	Remarks
K	 The diagram for Type K shows a driver circuit with a pull-up control, driver strength control, and pull-down control. It includes a data line and a resistor R. Below the driver, there are four input stages: CMOS hysteresis type1, CMOS hysteresis type2, Automotive inputs, and a TTL input. A standby control for input shutdown is also shown, connected to the LCD SEG/COM line.	CMOS level output (programmable $I_{OL} = 5\text{mA}$, $I_{OH} = -5\text{mA}$ and $I_{OL} = 2\text{mA}$, $I_{OH} = -2\text{mA}$) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function TTL input with input shutdown function Programmable pull-up resistor: $50\text{k}\Omega$ approx. LCD SEG/COM output
L	 The diagram for Type L is similar to Type K, showing a driver circuit with pull-up control, driver strength control, and pull-down control. It includes a data line and a resistor R. Below the driver, there are four input stages: CMOS hysteresis type1, CMOS hysteresis type2, Automotive inputs, and a TTL input. A standby control for input shutdown is also shown, connected to the VLCD line.	CMOS level output (programmable $I_{OL} = 5\text{mA}$, $I_{OH} = -5\text{mA}$ and $I_{OL} = 2\text{mA}$, $I_{OH} = -2\text{mA}$) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function) TTL input with input shutdown function Programmable pull-up resistor: $50\text{k}\Omega$ approx. Analog input LCD Voltage input

6. Notes on Debugger

6.1 Execution of the RETI Command

If single-step execution is used in an environment where an interrupt occurs frequently, the corresponding interrupt handling routine will be executed repeatedly to the exclusion of other processing. This will prevent the main routine and the handlers for low priority level interrupts from being executed (For example, if the time-base timer interrupt is enabled, stepping over the RETI instruction will always break on the first line of the time-base timer interrupt handler).

Disable the corresponding interrupts when the corresponding interrupt handling routine no longer needs debugging.

6.2 Break Function

If the range of addresses that cause a hardware break (including event breaks) is set to the address of the current system stack pointer or to an area that contains the stack pointer, execution will break after each instruction regardless of whether the user program actually contains data access instructions.

To prevent this, do not set (word) access to the area containing the address of the system stack pointer as the target of the hardware break (including an event breaks).

6.3 Operand Break

It may cause malfunctions if a stack pointer exists in the area which is set as the DSU operand break. Do not set the access to the areas containing the address of system stack pointer as a target of data event break.

6.4 Notes on PS Register

As the PS register is processed in advance by some instructions, when the debugger is being used, the exception handling may result in execution breaking in an interrupt handling routine or the displayed values of the flags in the PS register being updated. As the microcontroller is designed to carry out reprocessing correctly upon returning from such an EIT event, the operation before and after the EIT always proceeds according to specification.

■ **The following behavior may occur if any of the following occurs in the instruction immediately after a DIV0U/DIV0S instruction:**

- (a) a user interrupt or NMI is accepted;
- (b) single-step execution is performed;
- (c) execution breaks due to a data event or from the emulator menu.
 - 1. D0 and D1 flags are updated in advance.
 - 2. An EIT handling routine (user interrupt/NMI or emulator) is executed.
 - 3. Upon returning from the EIT, the DIV0U/DIV0S instruction is executed and the D0 and D1 flags are updated to the same values as those in 1.

■ **The following behavior occurs when an ORCCR, STILM, MOV Ri,PS instruction is executed to enable a user interrupt or NMI source while that interrupt is in the active state.**

- 1. The PS register is updated in advance.
- 2. An EIT handling routine (user interrupt/NMI or emulator) is executed.
- 3. Upon returning from the EIT, the above instructions are executed and the PS register is updated to the same value as in 1.

8. CPU and Control Unit

The FR family CPU is a high performance core that is designed based on the RISC architecture with advanced instructions for embedded applications.

8.1 Features

- Adoption of RISC architecture
Basic instruction: 1 instruction per cycle
- General-purpose registers: 32-bit × 16 registers
- 4 Gbytes linear memory space
- Multiplier installed
32-bit × 32-bit multiplication: 5 cycles
16-bit × 16-bit multiplication: 3 cycles
- Enhanced interrupt processing function
Quick response speed (6 cycles)
Multiple-interrupt support
Level mask function (16 levels)
- Enhanced instructions for I/O operation
Memory-to-memory transfer instruction
Bit processing instruction
Basic instruction word length: 16 bits
- Low-power consumption
Sleep mode/stop mode

8.2 Internal Architecture

- The FR family CPU uses the Harvard architecture in which the instruction bus and data bus are independent of each other.
- A 32-bit ↔ 16-bit buffer is connected to the 32-bit bus (D-bus) to provide an interface between the CPU and peripheral resources.
- A Harvard ↔ Princeton bus converter is connected to both the I-bus and D-bus to provide an interface between the CPU and the bus controller.

9.3 Flash Access in CPU mode

9.3.1 Flash Configuration

9.3.1.1 Flash Memory Map MB91F467BA

Address									
0014:FFFFh 0014:C000h	SA6 (8KB)				SA7 (8KB)				ROMS7
0014:BFFFh 0014:8000h	SA4 (8KB)				SA5 (8KB)				
0014:7FFFh 0014:4000h	SA2 (8KB)				SA3 (8KB)				
0014:3FFFh 0014:0000h	SA0 (8KB)				SA1 (8KB)				
0013:FFFFh 0012:0000h	SA22 (64KB)				SA23 (64KB)				ROMS6
0011:FFFFh 0010:0000h	SA20 (64KB)				SA21 (64KB)				
000F:FFFFh 000E:0000h	SA18 (64KB)				SA19 (64KB)				ROMS5
000D:FFFFh 000C:0000h	SA16 (64KB)				SA17 (64KB)				ROMS4
000B:FFFFh 000A:0000h	SA14 (64KB)				SA15 (64KB)				ROMS3
0009:FFFFh 0008:0000h	SA12 (64KB)				SA13 (64KB)				ROMS2
0007:FFFFh 0006:0000h	SA10 (64KB)				SA11 (64KB)				ROMS1
0005:FFFFh 0004:0000h	SA8 (64KB)				SA9 (64KB)				ROMS0
	addr+0	addr+1	addr+2	addr+3	addr+4	addr+5	addr+6	addr+7	
16bit read/write	dat[31:16]		dat[15:0]		dat[31:16]		dat[15:0]		
32bit read/write	dat[31:0]				dat[31:0]				
64bit read	dat[63:0]								

9.3.1.2 Flash Memory Map MB91F466BA

Addr									
0014:FFFFh 0014:C000h	SA6 (8KB)				SA7 (8KB)				ROMS7
0014:BFFFh 0014:8000h	SA4 (8KB)				SA5 (8KB)				
0014:7FFFh 0014:4000h	SA2 (8KB)				SA3 (8KB)				
0014:3FFFh 0014:0000h	SA0 (8KB)				SA1 (8KB)				
0013:FFFFh 0012:0000h	SA22 (64KB)				SA23 (64KB)				ROMS6
0011:FFFFh 0010:0000h	SA20 (64KB)				SA21 (64KB)				
000F:FFFFh 000E:0000h	SA18 (64KB)				SA19 (64KB)				ROMS5
000D:FFFFh 000C:0000h	SA16 (64KB)				SA17 (64KB)				ROMS4
000B:FFFFh 000A:0000h	SA14 (64KB)				SA15 (64KB)				ROMS3
0009:FFFFh 0008:0000h	SA12 (64KB)				SA13 (64KB)				ROMS2
0007:FFFFh 0006:0000h	SA10 (64KB)				SA11 (64KB)				ROMS1
0005:FFFFh 0004:0000h	SA8 (64KB)				SA9 (64KB)				ROMS0
	addr+0	addr+1	addr+2	addr+3	addr+4	addr+5	addr+6	addr+7	
16bit read/write	dat[31:16]		dat[15:0]		dat[31:16]		dat[15:0]		
32bit read	dat[31:0]				dat[31:0]				
64bit read	dat[63:0]								
Legend	Memory not available in this area				Memory available in this area				

MB91F465BB

FA[20:0]	
001F:FFFFh 001F:0000h	SA19 (64KB)
001E:FFFFh 001E:0000h	SA18 (64KB)
001D:FFFFh 001D:0000h	SA17 (64KB)
001C:FFFFh 001C:0000h	SA16 (64KB)
001B:FFFFh 001B:0000h	SA15 (64KB)
001A:FFFFh 001A:0000h	SA14 (64KB)
0019:FFFFh 0019:0000h	SA13 (64KB)
0018:FFFFh 0018:0000h	SA12 (64KB)
	SA11 (64KB)
	SA10 (64KB)
	SA9 (64KB)
	SA8 (64KB)
0017:FFFFh 0017:E000h	SA7 (8KB)
0017:DFFFh 0017:C000h	SA6 (8KB)
0017:BFFFh 0017:A000h	SA5 (8KB)
0017:9FFFh 0017:8000h	SA4 (8KB)
	SA3 (8KB)
	SA2 (8KB)
	SA1 (8KB)
	SA0 (8KB)
	FA[1:0]=00 FA[1:0]=10
16bit write mode	DQ[15:0] DQ[15:0]

Remark: Always keep FA[0] = 0 and FA[20] = 1

Legend

Memory available in this area
Memory not available in this area

MB91F464BB

FA[20:0]	
001F:FFFFh 001F:0000h	SA19 (64KB)
001E:FFFFh 001E:0000h	SA18 (64KB)
001D:FFFFh 001D:0000h	SA17 (64KB)
001C:FFFFh 001C:0000h	SA16 (64KB)
001B:FFFFh 001B:0000h	SA15 (64KB)
001A:FFFFh 001A:0000h	SA14 (64KB)
	SA13 (64KB)
	SA12 (64KB)
	SA11 (64KB)
	SA10 (64KB)
	SA9 (64KB)
	SA8 (64KB)
0017:FFFFh 0017:E000h	SA7 (8KB)
0017:DFFFh 0017:C000h	SA6 (8KB)
0017:BFFFh 0017:A000h	SA5 (8KB)
0017:9FFFh 0017:8000h	SA4 (8KB)
	SA3 (8KB)
	SA2 (8KB)
	SA1 (8KB)
	SA0 (8KB)
	FA[1:0]=00 FA[1:0]=10
16bit write mode	DQ[15:0] DQ[15:0]

Remark: Always keep FA[0] = 0 and FA[20] = 1

Legend

Memory available in this area
Memory not available in this area

9.5 Poweron Sequence in Parallel Programming Mode

The flash memory can be accessed in programming mode after a certain wait time, which is needed for Security Vector fetch:

- Minimum wait time after VDD5/VDD5R power on: 2.76 ms
- Minimum wait time after INITX rising: 1.0 ms

9.6 Flash Security

9.6.1 Vector Addresses

Two Flash Security Vectors (FSV1, FSV2) are located parallel to the Boot Security Vectors (BSV1, BSV2) controlling the protection functions of the Flash Security Module:

FSV1: 0x14:8000 BSV1: 0x14:8004
 FSV2: 0x14:8008 BSV2: 0x14:800C

9.6.2 Security Vector FSV1

The setting of the Flash Security Vector FSV1 is responsible for the read and write protection modes and the individual write protection of the 8 KBytes sectors.

9.6.2.1 FSV1 (bit31 to bit16)

The setting of the Flash Security Vector FSV1 bits [31:16] is responsible for the read and write protection modes.

Table 2. Explanation of the bits in the Flash Security Vector FSV1[31:16]

FSV1[31:19]	FSV1[18] Write Protection Level	FSV1[17] Write Protection	FSV1[16] Read Protection	Flash Security Mode
set all to '0'	set to '0'	set to '0'	set to '1'	Read Protection (all device modes, except INTVEC mode MD[2:0]="000")
set all to '0'	set to '0'	set to '1'	set to '0'	Write Protection (all device modes, without exception)
set all to '0'	set to '0'	set to '1'	set to '1'	Read Protection (all device modes, except INTVEC mode MD[2:0]="000") and Write Protection (all device modes)
set all to '0'	set to '1'	set to '0'	set to '1'	Read Protection (all device modes, except INTVEC mode MD[2:0]="000")
set all to '0'	set to '1'	set to '1'	set to '0'	Write Protection (all device modes, except INTVEC mode MD[2:0]="000")
set all to '0'	set to '1'	set to '1'	set to '1'	Read Protection (all device modes, except INTVEC mode MD[2:0]="000") and Write Protection (all device modes except INTVEC mode MD[2:0]="000")

Address	Register				Block
	+0	+1	+2	+3	
000440 _H	ICR00 [R/W] ---11111	ICR01 [R/W] ---11111	ICR02 [R/W] ---11111	ICR03 [R/W] ---11111	Interrupt Controller
000444 _H	ICR04 [R/W] ---11111	ICR05 [R/W] ---11111	ICR06 [R/W] ---11111	ICR07 [R/W] ---11111	
000448 _H	ICR08 [R/W] ---11111	ICR09 [R/W] ---11111	ICR10 [R/W] ---11111	ICR11 [R/W] ---11111	
00044C _H	ICR12 [R/W] ---11111	ICR13 [R/W] ---11111	ICR14 [R/W] ---11111	ICR15 [R/W] ---11111	
000450 _H	ICR16 [R/W] ---11111	ICR17 [R/W] ---11111	ICR18 [R/W] ---11111	ICR19 [R/W] ---11111	
000454 _H	ICR20 [R/W] ---11111	ICR21 [R/W] ---11111	ICR22 [R/W] ---11111	ICR23 [R/W] ---11111	
000458 _H	ICR24 [R/W] ---11111	ICR25 [R/W] ---11111	ICR26 [R/W] ---11111	ICR27 [R/W] ---11111	
00045C _H	ICR28 [R/W] ---11111	ICR29 [R/W] ---11111	ICR30 [R/W] ---11111	ICR31 [R/W] ---11111	
000460 _H	ICR32 [R/W] ---11111	ICR33 [R/W] ---11111	ICR34[R/W] ---11111	ICR35 [R/W] ---11111	
000464 _H	ICR36 [R/W] ---11111	ICR37 [R/W] ---11111	ICR38 [R/W] ---11111	ICR39 [R/W] ---11111	
000468 _H	ICR40 [R/W] ---11111	ICR41 [R/W] ---11111	ICR42 [R/W] ---11111	ICR43 [R/W] ---11111	
00046C _H	ICR44 [R/W] ---11111	ICR45 [R/W] ---11111	ICR46 [R/W] ---11111	ICR47 [R/W] ---11111	
000470 _H	ICR48 [R/W] ---11111	ICR49 [R/W] ---11111	ICR50 [R/W] ---11111	ICR51 [R/W] ---11111	
000474 _H	ICR52 [R/W] ---11111	ICR53 [R/W] ---11111	ICR54 [R/W] ---11111	ICR55 [R/W] ---11111	
000478 _H	ICR56 [R/W] ---11111	ICR57 [R/W] ---11111	ICR58 [R/W] ---11111	ICR59 [R/W] ---11111	
00047C _H	ICR60 [R/W] ---11111	ICR61 [R/W] ---11111	ICR62 [R/W] ---11111	ICR63 [R/W] ---11111	Interrupt Controller
000480 _H	RSRR [R/W] 10000000	STCR [R/W] 00110011	TBCR [R/W] 00XXXX00	CTBR [W] XXXXXXXXXX	Clock Control
000484 _H	CLKR [R/W] ---- 0000	WPR [W] XXXXXXXXXX	DIVR0 [R/W] 00000011	DIVR1 [R/W] 00000000	
000488 _H	Reserved				Reserved
00048C _H	PLLDIVM [R/W] ---- 0000	PLLDIVN [R/W] -- 000000	PLLDIVG [R/W] ---- 0000	PLLMULG [R/W] 00000000	PLL Interface
000490 _H	PLLCTRL [R/W] ---- 0000	Reserved			
000494 _H	OSCC1 [R/W] ----- 010	OSCS1 [R/W] 00001111	OSCC2 [R/W] ----- 010	OSCS2 [R/W] 00001111	Main/Sub Oscillator Control (Reserved)
000498 _H	PORTEN [R/W] ----- 00	Reserved			Port Input Enable Control

Address	Register				Block
	+0	+1	+2	+3	
000D00 _H	PDRD00 [R] XXXXXXXX	PDRD01 [R] XXXXXXXX	Reserved		R-bus Port Data Direct Read Register
000D04 _H	Reserved	PDRD05 [R] -- XXXXXX	PDRD06 [R] XXXXXXXX	PDRD07 [R] XXXXXXXX	
000D08 _H	PDRD08 [R] X -- X ---X	PDRD09 [R] ----- XX	PDRD10 [R] ----- X	Reserved	
000D0C _H	Reserved		PDRD14 [R] XXXXXXXX	PDRD15 [R] XXXXXXXX	
000D10 _H	PDRD16 [R] XXXXXXXX	PDRD17 [R] XXXXXXXX	PDRD18 [R] - XXX - XXX	PDRD19 [R] - XXX - XXX	
000D14 _H	PDRD20 [R] - XXX - XXX	PDRD21 [R] ----- X	PDRD22 [R] XXXXXXXX	PDRD23 [R] XXXXXXXX	
000D18 _H	PDRD24 [R] XXXXXXXX	Reserved	PDRD26 [R] XXXXXXXX	PDRD27 [R] XXXXXXXX	
000D1C _H	PDRD28 [R] XXXXXXXX	PDRD29 [R] XXXXXXXX	Reserved		
000D20 _H to 000D3C _H	Reserved				
000D40 _H	DDR00 [R/W] 00000000	DDR01 [R/W] 00000000	Reserved		R-bus Port Direction Register
000D44 _H	Reserved	DDR05 [R/W] -- 000000	DDR06 [R/W] 00000000	DDR07 [R/W] 00000000	
000D48 _H	DDR08 [R/W] 0 -- 0 ---0	DDR09 [R/W] ----- 00	DDR10 [R/W] ----- 0	Reserved	
000D4C _H	Reserved		DDR14 [R/W] 00000000	DDR15 [R/W] 00000000	
000D50 _H	DDR16 [R/W] 00000000	DDR17 [R/W] 00000000	DDR18 [R/W] - 000 - 000	DDR19 [R/W] - 000 - 000	
000D54 _H	DDR20 [R/W] - 000 - 000	DDR21 [R/W] ----- 00	DDR22 [R/W] 00000000	DDR23 [R/W] 00000000	
000D58 _H	DDR24 [R/W] 00000000	Reserved	DDR26 [R/W] 00000000	DDR27 [R/W] 00000000	
000D5C _H	DDR28 [R/W] 00000000	DDR29 [R/W] 00000000	Reserved		
000D60 _H to 000D7C _H	Reserved				Reserved

Address	Register				Block
	+0	+1	+2	+3	
00C580 _H	TREQR25 [R] 00000000 00000000		TREQR15 [R] 00000000 00000000		CAN 5 Status Flags Note: Not on MB91F465BB/MB91F464 BB
00C584 _H to 00C58C _H	Reserved				
00C590 _H	NEWDT25 [R] 00000000 00000000		NEWDT15 [R] 00000000 00000000		
00C594 _H to 00C59C _H	Reserved				
00C5A0 _H	INTPND25 [R] 00000000 00000000		INTPND15 [R] 00000000 00000000		
00C5A4 _H to 00C5AC _H	Reserved				
00C5B0 _H	MSGVAL25 [R] 00000000 00000000		MSGVAL15 [R] 00000000 00000000		
00C5B4 _H to 00E5FC _H	Reserved				
00F000 _H	BCTRL [R/W] ----- 11111100 00000000				EDSU / MPU
00F004 _H	BSTAT [R/W] ----- 000 00000000 10 -- 000000				
00F008 _H	BIAC [R] ----- 00000000 00000000				
00F00C _H	BOAC [R] ----- 00000000 00000000				
00F010 _H	BIRQ [R/W] ----- 00000000 00000000				
00F014 _H to 00F01C _H	Reserved				
00F020 _H	BCR0 [R/W] ----- 00000000 00000000 00000000				
00F024 _H	BCR1 [R/W] ----- 00000000 00000000 00000000				
00F028 _H	BCR2 [R/W] ----- 00000000 00000000 00000000				
00F02C _H	BCR3 [R/W] ----- 00000000 00000000 00000000				
00F030 _H to 00F07C _H	Reserved				Reserved

12.2 Flash Memory and External Bus Area

12.2.1 MB91F467BA/466BA

64bit read	dat[63:0]								
32bit read/write	dat[31:0]				dat[31:0]				
16bit read/write	dat[31:16]		dat[15:0]		dat[31:16]		dat[15:0]		
Address	Register								Block
	+ 0	+ 1	+ 2	+ 3	+ 4	+ 5	+ 6	+ 7	
040000 _H to 05FFF8 _H	SA8 (64KB)				SA9 (64KB)				ROMS0
060000 _H to 07FFF8 _H	SA10 (64KB)				SA11 (64KB)				ROMS1
080000 _H to 09FFF8 _H	SA12 (64KB)				SA13 (64KB)				ROMS2
0A0000 _H to 0BFFF8 _H	SA14 (64KB)				SA15 (64KB)				ROMS3
0C0000 _H to 0DFFF8 _H	SA16 (64KB)				SA17 (64KB)				ROMS4
0E0000 _H to 0FFFF0 _H	SA18 (64KB)				SA19 (64KB)				ROMS5
0FFFF8 _H	FMV [R] 06 00 00 00 _H				FRV [R] 00 00 BF F8 _H				
100000 _H to 11FFF8 _H	SA20 (64KB, MB91F467BA) Reserved (MB91F466BA)				SA21 (64KB, MB91F467BA) Reserved (MB91F466BA)				ROMS6
120000 _H to 13FFF8 _H	SA22 (64KB, MB91F467BA) Reserved (MB91F466BA)				SA23 (64KB, MB91F467B) Reserved (MB91F466BA)				
140000 _H to 143FF8 _H	SA0 (8KB)				SA1 (8KB)				ROMS7
144000 _H to 17FF8 _H	SA2 (8KB)				SA3 (8KB)				
148000 _H to 14BFF8 _H	SA4 (8KB)				SA5 (8KB)				
14C000 _H to 14FFF8 _H	SA6 (8KB)				SA7 (8KB)				
150000 _H to 17FFF8 _H	Reserved								

Interrupt	Interrupt number		Interrupt level [1]		Interrupt vector [2]		DMA Resource number
	Decimal	Hexa-decimal	Setting Register	Register address	Offset	Default vector address	
PPG 2	114	72	ICR49	471 _H	234 _H	000FFE34 _H	98
PPG 3	115	73			230 _H	000FFE30 _H	99
PPG 4	116	74	ICR50	472 _H	22C _H	000FFE2C _H	100
PPG 5	117	75			228 _H	000FFE28 _H	101
PPG 6	118	76	ICR51	473 _H	224 _H	000FFE24 _H	102
PPG 7	119	77			220 _H	000FFE20 _H	103
PPG 8	120	78	ICR52	474 _H	21C _H	000FFE1C _H	104
PPG 9	121	79			218 _H	000FFE18 _H	105
PPG 10	122	7A	ICR53	475 _H	214 _H	000FFE14 _H	106
PPG 11	123	7B			210 _H	000FFE10 _H	107
PPG 12	124	7C	ICR54	476 _H	20C _H	000FFE0C _H	108
PPG 13	125	7D			208 _H	000FFE08 _H	109
PPG 14	126	7E	ICR55	477 _H	204 _H	000FFE04 _H	110
PPG 15	127	7F			200 _H	000FFE00 _H	111
Up/Down Counter 0	128	80	ICR56	478 _H	1FC _H	000FFDFC _H	—
Up/Down Counter 1	129	81			1F8 _H	000FFDF8 _H	—
Reserved	130	82	ICR57	479 _H	1F4 _H	000FFDF4 _H	—
Reserved	131	83			1F0 _H	000FFDF0 _H	—
Real Time Clock	132	84	ICR58	47A _H	1EC _H	000FFDEC _H	—
Calibration Unit	133	85			1E8 _H	000FFDE8 _H	—
A/D Converter 0	134	86	ICR59	47B _H	1E4 _H	000FFDE4 _H	14, 112
System reserved	135	87			1E0 _H	000FFDE0 _H	—
Alarm Comparator 0	136	88	ICR60	47C _H	1DC _H	000FFDDC _H	—
Reserved	137	89			1D8 _H	000FFDD8 _H	—
Low Voltage Detection	138	8A	ICR61	47D _H	1D4 _H	000FFDD4 _H	—
Reserved	139	8B			1D0 _H	000FFDD0 _H	—
Time base Overflow	140	8C	ICR62	47E _H	1CC _H	000FFDCC _H	—
PLL Clock Gear	141	8D			1C8 _H	000FFDC8 _H	—
DMA Controller	142	8E	ICR63	47F _H	1C4 _H	000FFDC4 _H	—
Main/Sub OSC stability wait	143	8F			1C0 _H	000FFDC0 _H	—
Security vector	144	90	—	—	1BC _H	000FFDBC _H	—
Used by the INT instruction.	145 to 255	91 to FF	—	—	1B8 _H to 000 _H	000FFDB8 _H to 000FFC00 _H	—

1. The Interrupt Control Registers (ICRs) are located in the interrupt controller and set the interrupt level for each interrupt request. An ICR is provided for each interrupt request.
2. The vector address for each EIT (exception, interrupt or trap) is calculated by adding the listed offset to the table base register value (TBR) . The TBR specifies the top of the EIT vector table. The addresses listed in the table are for the default TBR value (000FFC00_H) . The TBR is initialized to this value by a reset. The TBR is set to 000FFC00_H after the internal boot ROM is executed.
3. ICR23 and ICR47 can be exchanged by setting the REALOS compatibility bit (addr 0C03_H : IOS[0])
4. Used by REALOS
5. Memory Protection Unit (MPU) support

14. Recommended Settings

14.1 PLL and Clock Gear Settings

Please note that for MB91F467BA/466BA and MB91F465BB/464BB the core base clock frequencies are valid in the 1.8V operation mode of the Main regulator and Flash.

Table 7. Recommended PLL divider and clock gear settings

PLL Input (CLK) [MHz]	Frequency Parameter		Clockgear Parameter		PLL Output (X) [MHz]	Core Base Clock [MHz]	Remarks
	DIVM	DIVN	DIVG	MULG	MULG		
4	2	25	16	24	200	100	Not on MB91F467BA/466BA
4	2	24	16	24	192	96	
4	2	23	16	24	184	92	
4	2	22	16	24	176	88	
4	2	21	16	20	168	84	
4	2	20	16	20	160	80	
4	2	19	16	20	152	76	
4	2	18	16	20	144	72	
4	2	17	16	16	136	68	
4	2	16	16	16	128	64	
4	2	15	16	16	120	60	
4	2	14	16	16	112	56	
4	2	13	16	12	104	52	
4	2	12	16	12	96	48	
4	2	11	16	12	88	44	
4	4	10	16	24	160	40	
4	4	9	16	24	144	36	
4	4	8	16	24	128	32	
4	4	7	16	24	112	28	
4	6	6	16	24	144	24	
4	8	5	16	28	160	20	
4	10	4	16	32	160	16	
4	12	3	16	32	144	12	

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Input "L" voltage	V _{ILXDF}	X0	-	V _{SS} - 0.3	-	0.2 × V _{DD}	V	External clock in "Fast Clock Input mode"
Output "H" voltage	V _{OH2}	Normal outputs	4.5V ≤ V _{DD} ≤ 5.5V, I _{OH} = - 2mA	V _{DD} - 0.5	-	-	V	Driving strength set to 2 mA
			3.0V ≤ V _{DD} ≤ 4.5V, I _{OH} = - 1.6mA					
	V _{OH5}	Normal outputs	4.5V ≤ V _{DD} ≤ 5.5V, I _{OH} = - 5mA	V _{DD} - 0.5	-	-	V	Driving strength set to 5 mA
			3.0V ≤ V _{DD} ≤ 4.5V, I _{OH} = - 3mA					
	V _{OH3}	I ² C outputs	3.0V ≤ V _{DD} ≤ 5.5V, I _{OH} = - 3mA	V _{DD} - 0.5	-	-	V	
Output "L" voltage	V _{OL2}	Normal outputs	4.5V ≤ V _{DD} ≤ 5.5V, I _{OH} = + 2mA	-	-	0.4	V	Driving strength set to 2 mA
			3.0V ≤ V _{DD} ≤ 4.5V, I _{OH} = + 1.6mA					
	V _{OL5}	Normal outputs	4.5V ≤ V _{DD} ≤ 5.5V, I _{OH} = + 5mA	-	-	0.4	V	Driving strength set to 5 mA
			3.0V ≤ V _{DD} ≤ 4.5V, I _{OH} = + 3mA					
	V _{OL3}	I ² C outputs	3.0V ≤ V _{DD} ≤ 5.5V, I _{OH} = + 3mA	-	-	0.4	V	
Input leakage current	I _{IL}	Pnn_m ^[1]	3.0V ≤ V _{DD} ≤ 5.5V V _{SS} 5 < V _I < V _{DD} T _A =25 °C	- 1	-	+ 1	mA	
			3.0V ≤ V _{DD} ≤ 5.5V V _{SS} 5 < V _I < V _{DD} T _A =125 °C	- 3	-	+ 3		
Analog input leakage current	I _{AIN}	ANn ^[2]	3.0V ≤ V _{DD} ≤ 5.5V T _A =25 °C	- 1	-	+ 1	mA	
			3.0V ≤ V _{DD} ≤ 5.5V T _A =125 °C	- 3	-	+ 3	mA	
Pull-up resistance	R _{UP}	Pnn_m ^[3] INITX	3.0V ≤ V _{DD} ≤ 3.6V	40	100	160	kW	
			4.5V ≤ V _{DD} ≤ 5.5V	25	50	100		
Pull-down resistance	R _{DOWN}	Pnn_m ^[4]	3.0V ≤ V _{DD} ≤ 3.6V	40	100	180	kW	
			4.5V ≤ V _{DD} ≤ 5.5V	25	50	100		
Input capacitance	C _{IN}	All except V _{DD} 5, V _{DD} 5R, V _{SS} 5, AV _{CC} 5, AV _{SS} 5, AVRH5	f = 1 MHz	-	5	15	pF	

Parameter	Symbol	Pin name	Condition	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current F467BA F466BA	I_{CC}	V_{DD5R}	CLKB: 96 MHz CLKP: 48 MHz CLKT: 48 MHz CLKCAN: 48 MHz	–	120	150	mA	Code fetch from Flash
	I_{CCH}	V_{DD5R}	$T_A = +25\text{ }^{\circ}\text{C}$	–	30	150	μA	At stop mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.4	2.0	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	1.0	5.0	mA	
			$T_A = +25\text{ }^{\circ}\text{C}$	–	100	500	μA	RTC: 4 MHz mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.5	2.4	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	1.1	5.4	mA	
			$T_A = +25\text{ }^{\circ}\text{C}$	–	50	250	μA	RTC: 100 kHz mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.45	2.2	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	1.05	5.2	mA	
	I_{LVE}	V_{DD5}	–	–	70	150	μA	External low voltage detection
	I_{LVI}	V_{DD5R}	–	–	50	100	μA	Internal low voltage detection
Power supply current F465BB F464BB	I_{OSC}	V_{DD5}	–	–	250	500	μA	Main clock (4 MHz)
			–	–	20	40	μA	Sub clock (32 kHz)
	I_{CC}	V_{DD5R}	CLKB: 100 MHz CLKP: 50 MHz CLKT: 50 MHz CLKCAN: 50 MHz	–	110	140	mA	Code fetch from Flash
	I_{CCH}	V_{DD5R}	$T_A = +25\text{ }^{\circ}\text{C}$	–	30	150	μA	At stop mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.3	2.0	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	0.75	5.0	mA	
			$T_A = +25\text{ }^{\circ}\text{C}$	–	100	500	μA	RTC: 4 MHz mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.5	2.4	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	0.85	5.4	mA	
			$T_A = +25\text{ }^{\circ}\text{C}$	–	50	250	μA	RTC: 100 kHz mode ^[5]
			$T_A = +105\text{ }^{\circ}\text{C}$	–	0.4	2.2	mA	
			$T_A = +125\text{ }^{\circ}\text{C}$	–	0.8	5.2	mA	
	I_{LVE}	V_{DD5}	–	–	70	150	μA	External low voltage detection
	I_{LVI}	V_{DD5R}	–	–	50	100	μA	Internal low voltage detection
	I_{OSC}	V_{DD5}	–	–	250	500	μA	Main clock (4 MHz)
			–	–	20	40	μA	Sub clock (32 kHz)

1. Pnn_m includes all GPIO pins. Analog (AN) channels and PullUp/PullDown are disabled.
2. ANn includes all pins where AN channels are enabled.
3. Pnn_m includes all GPIO pins. The pull up resistors must be enabled by PPER/PPCR setting and the pins must be in input direction.
4. Pnn_m includes all GPIO pins. The pull down resistors must be enabled by PPER/PPCR setting and the pins must be in input direction.
5. Main regulator OFF, sub regulator set to 1.2V, Low voltage detection disabled.

16. Ordering Information

Part number	Package	Remarks
MB91F465BBPMC-GSE2 MB91F467BAPMC-GSE2	144-pin plastic LQFP (FPT-144P-M08)	Lead-free package

18. Revision History

Spanion Publication Number: DS07-16609-1E

Version	Date	Remark
2.0	2008-06-19	Initial version
2.1	2008-08-15	Proof reading results from FJ incorporated; Corrected pinout drawings; IO CIRCUIT TYPES: corrected some typos like on the other datasheets; HANDLING DEVICES: updated the section "Notes on PS register" for better understanding; Interrupt Vector Table: corrected the footnotes FLASH: added note about the operation mode switching capability in Boot ROM; corrected flash security vector FSV2 assignments, corrected section about parallel programming, corrected section pin connections in parallel programming mode so that there is only one page added section "Poweron Sequence in parallel programming mode"; ELECTRICAL CHARACTERISTICS: removed the note that analog input/output pins cannot accept +B signal input; splitted I_{LV} into external and internal LV detection current ADC Characteristics: Corrected the items about nonlinearity error; Corrected the company name
3.0	2009-01-09	Page 1: Corrected document name field in top header Block Diagram: Removed SCK0 (LIN-USART0 is asynchronous only) Added Ta=125C characteristics

19. Main Changes in this Edition

Page	Section	Change Results
104	15. Electrical Characteristics 15.4. A/D converter characteristics	Corrected the column "Value" and "Unit" of the parameter "Zero reading voltage" and "Full scale reading voltage". (Value : AVRL - 1.5 → AVRL - 1.5 LSB AVRL + 0.5 → AVRL + 0.5 LSB AVRL + 2.5 → AVRL + 2.5 LSB AVRH - 3.5 → AVRH - 3.5 LSB AVRH - 1.5 → AVRH - 1.5 LSB AVRH + 0.5 → AVRH + 0.5 LSB Unit : LSB → V)

NOTE: Please see "Document History" for later revised information.