Infineon Technologies - MB91F467BAPMC-GSE2-W016 Datasheet

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What is "Embedded - Microcontrollers"?

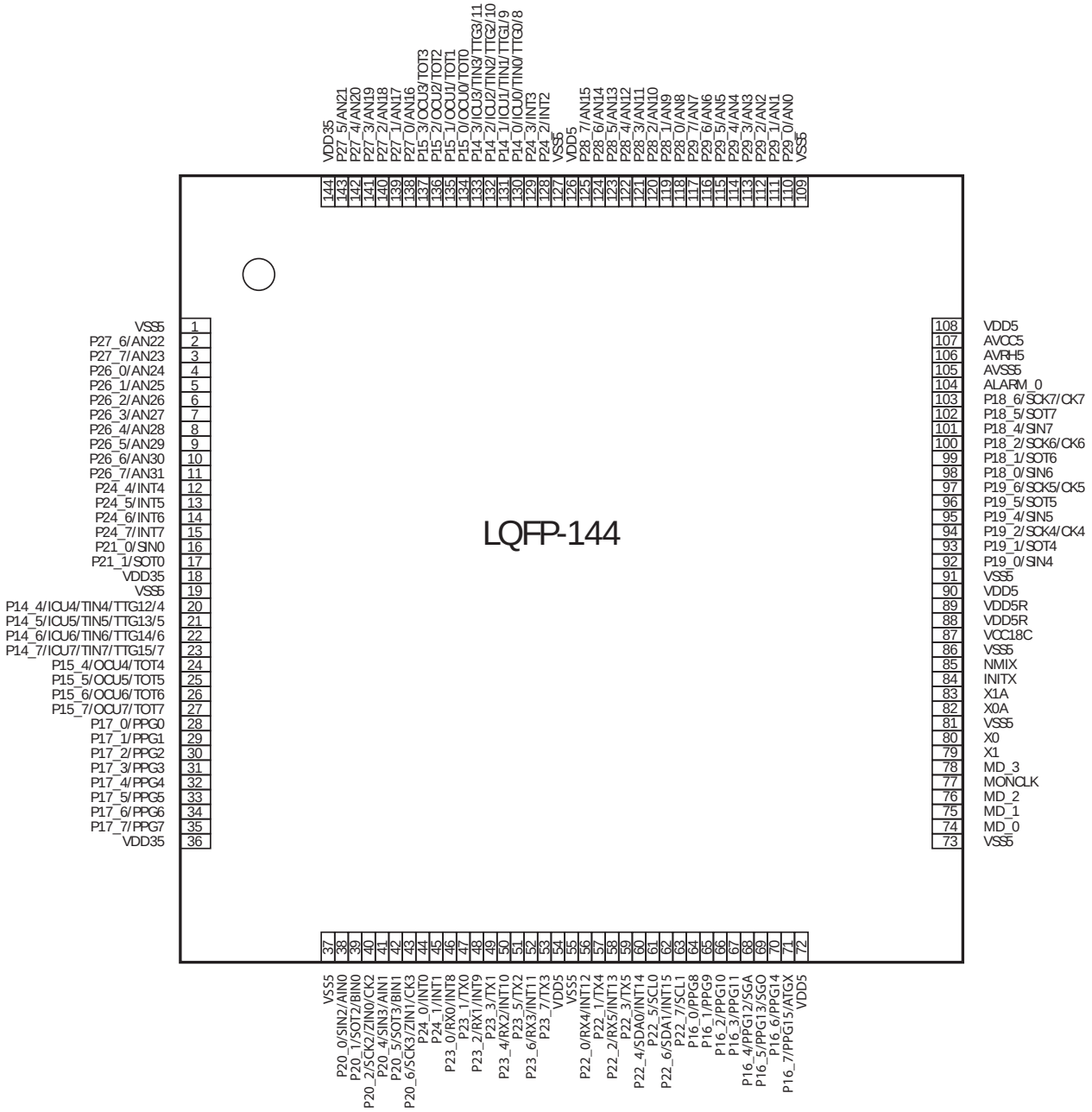
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	FR60 RISC
Core Size	32-Bit Single-Core
Speed	96MHz
Connectivity	CANbus, EBI/EMI, I²C, LINbus, UART/USART
Peripherals	DMA, LVD, PWM, WDT
Number of I/O	108
Program Memory Size	1.0625MB (1.0625M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	48K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 32x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb91f467bapmc-gse2-w016

2.2 MB91F467BA/466BA with MD_3=0

(TOP VIEW)

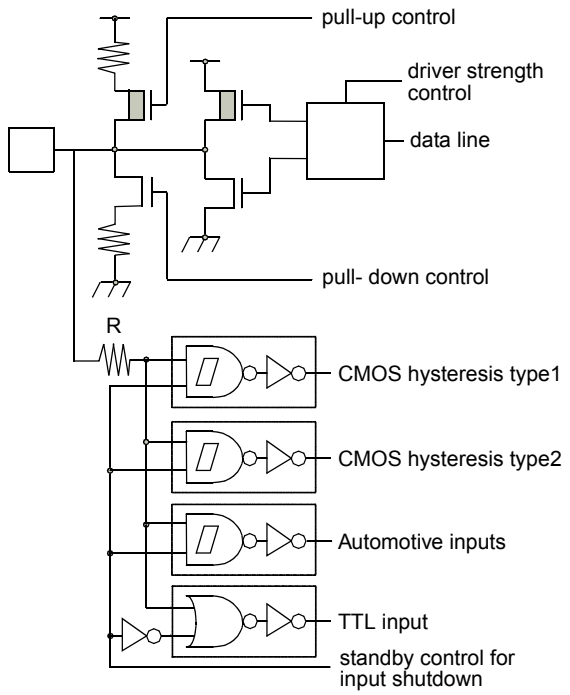
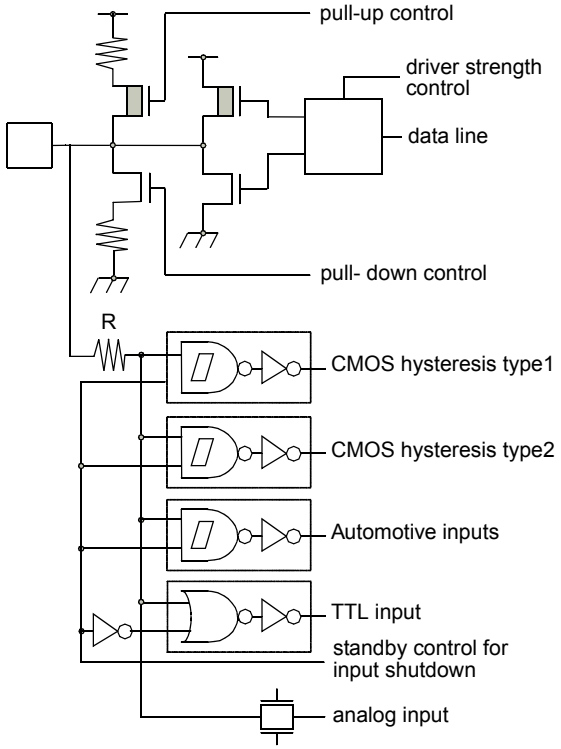


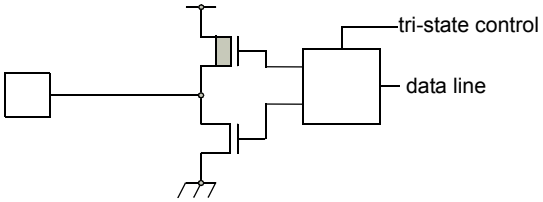
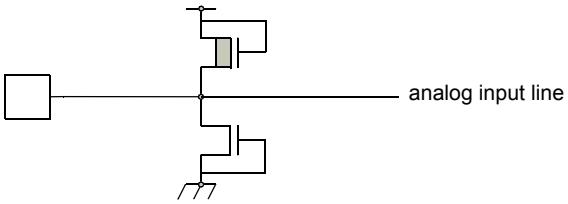
Pin no.	Pin name	I/O	I/O circuit type[1]	Function
48	P23_2	I/O	A	General-purpose input/output port
	RX1			RX input pin of CAN1
	INT9			External interrupt input pins
49	P23_3	I/O	A	General-purpose input/output port
	TX1			TX output pin of CAN1
50	P23_4	I/O	A	General-purpose input/output port
	RX2			RX input pin of CAN2
	INT10			External interrupt input pin
51	P23_5	I/O	A	General-purpose input/output port
	TX2			TX output pin of CAN2
52	P23_6	I/O	A	General-purpose input/output port
	INT11			External interrupt input pin
	MB91F467BA/MB91F466BA: RX3			RX input pin of CAN3
53	P23_7	I/O	A	General-purpose input/output port
	MB91F467BA/MB91F466BA: TX3			TX output pin of CAN3
56	P22_0	I/O	A	General-purpose input/output port
	INT12			External interrupt input pin
	MB91F467BA/MB91F466BA: RX4			RX input pin of CAN4
57	P22_1	I/O	A	General-purpose input/output port
	MB91F467BA/MB91F466BA: TX4			TX output pin of CAN4
58	P22_2	I/O	A	General-purpose input/output port
	INT13			External interrupt input pin
	MB91F467BA/MB91F466BA: RX5			RX input pin of CAN5
59	P22_3	I/O	A	General-purpose input/output port
	MB91F467BA/MB91F466BA: TX5			TX output pin of CAN5
60	P22_4	I/O	C	General-purpose input/output port
	SDA0			I^2C bus DATA input/output pin (open drain)
	INT14			External interrupt input pin
61	P22_5	I/O	C	General-purpose input/output port
	SCL0			I^2C bus clock input/output pin (open drain)
62	P22_6	I/O	C	General-purpose input/output port
	SDA1			I^2C bus DATA input/output pin (open drain)
	INT15			External interrupt input pin
63	P22_7	I/O	C	General-purpose input/output port
	SCL1			I^2C bus clock input/output pin (open drain)

Pin no.	Pin name	I/O	I/O circuit type[1]	Function
95	P19_4	I/O	A	General-purpose input/output ports
	SIN5			Data input pin of USART5
96	P19_5	I/O	A	General-purpose input/output ports
	SOT5			Data output pin of USART5
97	P19_6	I/O	A	General-purpose input/output ports
	SCK5			Clock input/output pin of USART5
	CK5			External clock input pin of free-run timer 5
98	P18_0	I/O	A	General-purpose input/output ports
	SIN6			Data input pin of USART6
99	P18_1	I/O	A	General-purpose input/output ports
	SOT6			Data output pin of USART6
100	P18_2	I/O	A	General-purpose input/output ports
	SCK6			Clock input/output pin of USART6
	CK6			External clock input pin of free-run timer 6
101	P18_4	I/O	A	General-purpose input/output ports
	SIN7			Data input pin of USART7
102	P18_5	I/O	A	General-purpose input/output ports
	SOT7			Data output pin of USART7
103	P18_6	I/O	A	General-purpose input/output ports
	SCK7			Clock input/output pin of USART7
	CK7			External clock input pin of free-run timer 7
104	ALARM_0	I	N	Alarm comparator input pin
110 to 117	P29_0 to P29_7	I/O	B	General-purpose input/output ports
	AN0 to AN7			Analog input pins of A/D converter
118 to 125	P28_0 to P28_7	I/O	B	General-purpose input/output ports
	AN8 to AN15			Analog input pins of A/D converter
128	P24_2	I/O	A	General-purpose input/output ports
	INT2			External interrupt input pin
129	P24_3	I/O	A	General-purpose input/output ports
	INT3			External interrupt input pin
130 to 133	P14_0 to P14_3	I/O	A	General-purpose input/output ports
	ICU0 to ICU3			Input capture input pins
	TIN0 to TIN3			External trigger input pins of reload timer
	TTG0/8 to TTG3/11			External trigger input pins of PPG timer
134 to 137	P15_0 to P15_3	I/O	A	General-purpose input/output ports
	OCU0 to OCU3			Output compare output pins
	TOT0 to TOT3			Reload timer output pins
138 to 143	P27_0 to P27_5	I/O	B	General-purpose input/output ports
	AN16 to AN21			Analog input pins of A/D converter

1. For information about the I/O circuit type, refer to “I/O Circuit Types”.

4. I/O Circuit Types

Type	Circuit	Remarks
A		CMOS level output (programmable I_{OL} = 5mA, I_{OH} = -5mA and I_{OL} = 2mA, I_{OH} = -2mA) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function TTL input with input shutdown function Programmable pull-up resistor: 50kΩ approx.
B		CMOS level output (programmable I_{OL} = 5mA, I_{OH} = -5mA and I_{OL} = 2mA, I_{OH} = -2mA) 2 different CMOS hysteresis inputs with input shutdown function Automotive input with input shutdown function TTL input with input shutdown function Programmable pull-up resistor: 50kΩ approx. Analog input

Type	Circuit	Remarks
M		CMOS level tri-state output (I_{OL} = 5mA, I_{OH} = -5mA)
N		Analog input pin with protection

5. Handling Devices

5.1 Preventing Latch-up

Latch-up may occur in a CMOS IC if a voltage higher than ($V_{DD}5$, $V_{DD}35$ or $HV_{DD}5$ [1]) or less than ($V_{SS}5$ or $HV_{SS}5$ [1]) is applied to an input or output pin or if a voltage exceeding the rating is applied between the power supply pins and ground pins. If latch-up occurs, the power supply current increases rapidly, sometimes resulting in thermal breakdown of the device. Therefore, be very careful not to apply voltages in excess of the absolute maximum ratings.

Note: 1. $HV_{DD}5$, $HV_{SS}5$ are available only on devices having Stepper Motor Controller.

5.2 Handling of Unused Input Pins

If unused input pins are left open, abnormal operation may result. Any unused input pins should be connected to pull-up or pull-down resistor (2KΩ to 10KΩ) or enable internal pullup or pulldown resisters (PPER/PPCR) before the input enable (PORTEN) is activated by software. The mode pins MD_x can be connected to $V_{SS}5$ or $V_{DD}5$ directly. Unused ALARM input pins can be connected to $AV_{SS}5$ directly.

5.3 Power Supply Pins

In MB91460 series, devices including multiple power supply pins and ground pins are designed as follows; pins necessary to be at the same potential are interconnected internally to prevent malfunctions such as latch-up. All of the power supply pins and ground pins must be externally connected to the power supply and ground respectively in order to reduce unnecessary radiation, to prevent strobe signal malfunctions due to the ground level rising and to follow the total output current ratings. Furthermore, the power supply pins and ground pins of the MB91460 series must be connected to the current supply source via a low impedance. It is also recommended to connect a ceramic capacitor of approximately 0.1 μF as a bypass capacitor between power supply pin and ground pin near this device. This series has a built-in step-down regulator. Connect a bypass capacitor of 4.7 μF (use a X7R ceramic capacitator) to VCC18C pin for the regulator.

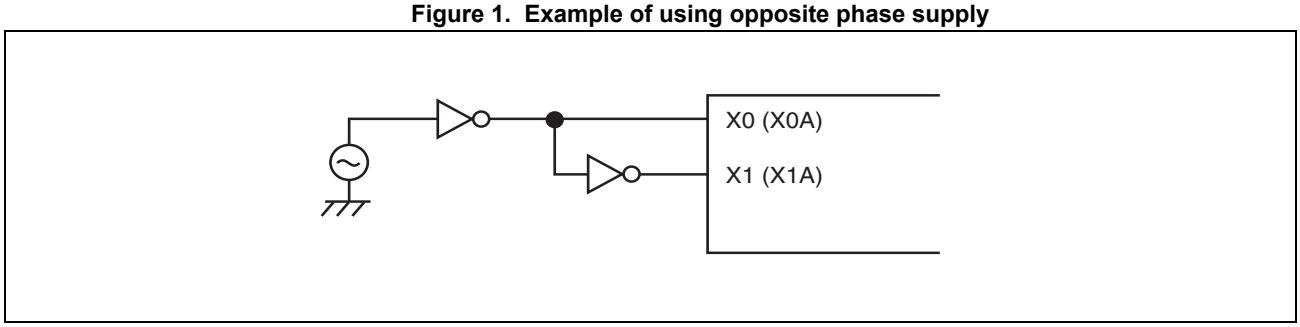
5.4 Crystal Oscillator Circuit

Noise in proximity to the X0 (X0A) and X1 (X1A) pins can cause the device to operate abnormally. Printed circuit boards should be designed so that the X0 (X0A) and X1 (X1A) pins, and crystal oscillator, as well as bypass capacitors connected to ground, are located near the device and ground.
It is recommended that the printed circuit board layout be designed such that the X0 and X1 pins or X0A and X1A pins are surrounded by ground plane for the stable operation. Please request the oscillator manufacturer to evaluate the oscillational characteristics of the crystal and this device.

5.5 Notes on using External Clock

When using the external clock, it is necessary to simultaneously supply the X0 (X0A) and the X1 (X1A) pins. In the described combination, X1 (X1A) should be supplied with a clock signal which has the opposite phase to the X0 (X0A) pins. At X0 and X1, a frequency up to 16 MHz is possible.

Figure 1. Example of using opposite phase supply



5.6 Mode Pins (MD_x)

These pins should be connected directly to the power supply or ground pins. To prevent the device from entering test mode accidentally due to noise, minimize the lengths of the patterns between each mode pin and power supply pin or ground pin on the printed circuit board as possible and connect them with low impedance.

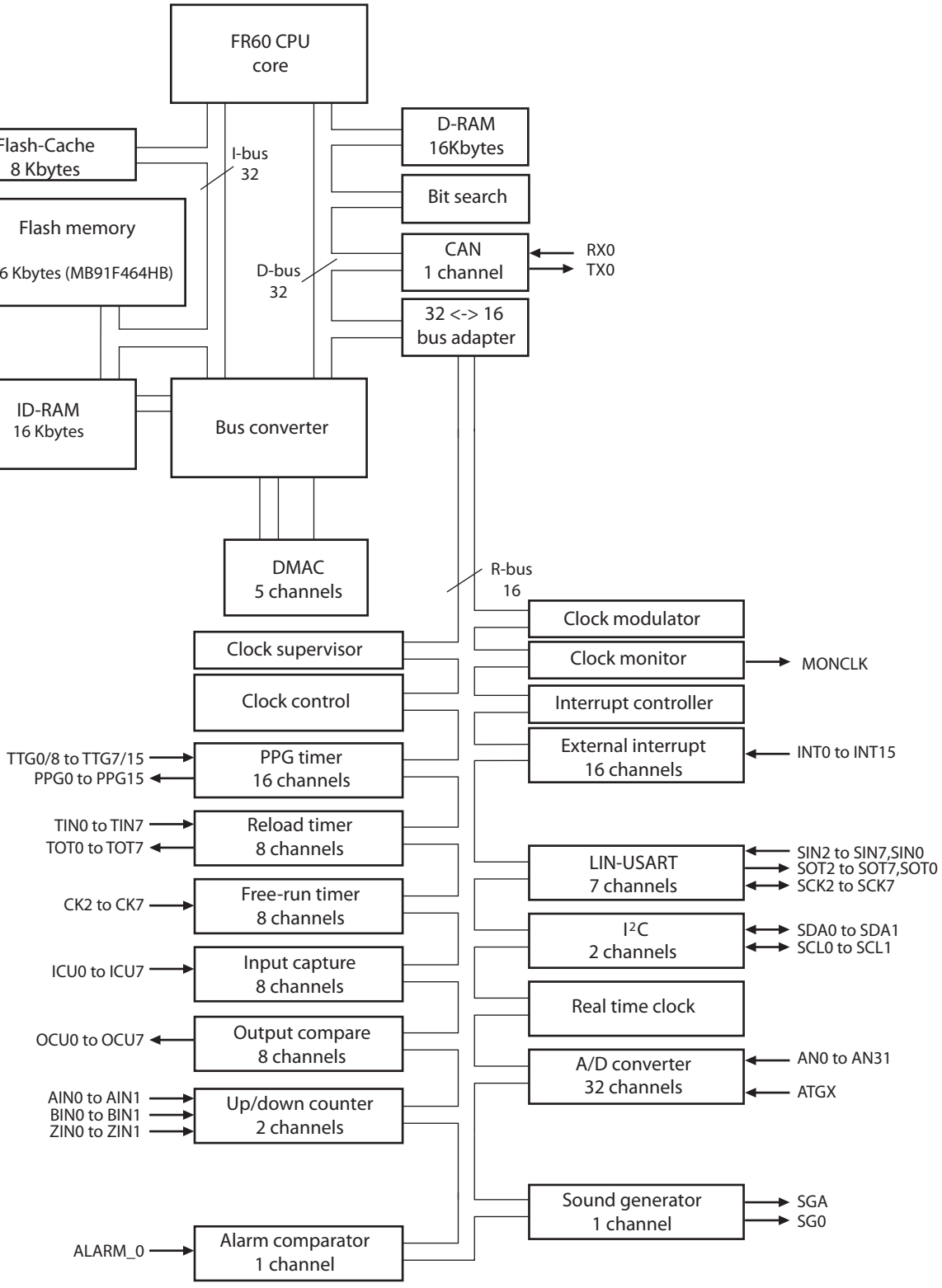
5.7 Notes on Operating in PLL Clock Mode

If the oscillator is disconnected or the clock input stops when the PLL clock is selected, the microcontroller may continue to operate at the free-running frequency of the self-oscillating circuit of the PLL. However, this self-running operation cannot be guaranteed.

5.8 Pull-up Control

The AC standard is not guaranteed in case a pull-up resistor is connected to the pin serving as an external bus pin.

7.4 MB91F465BB/464BB with MD_3=0

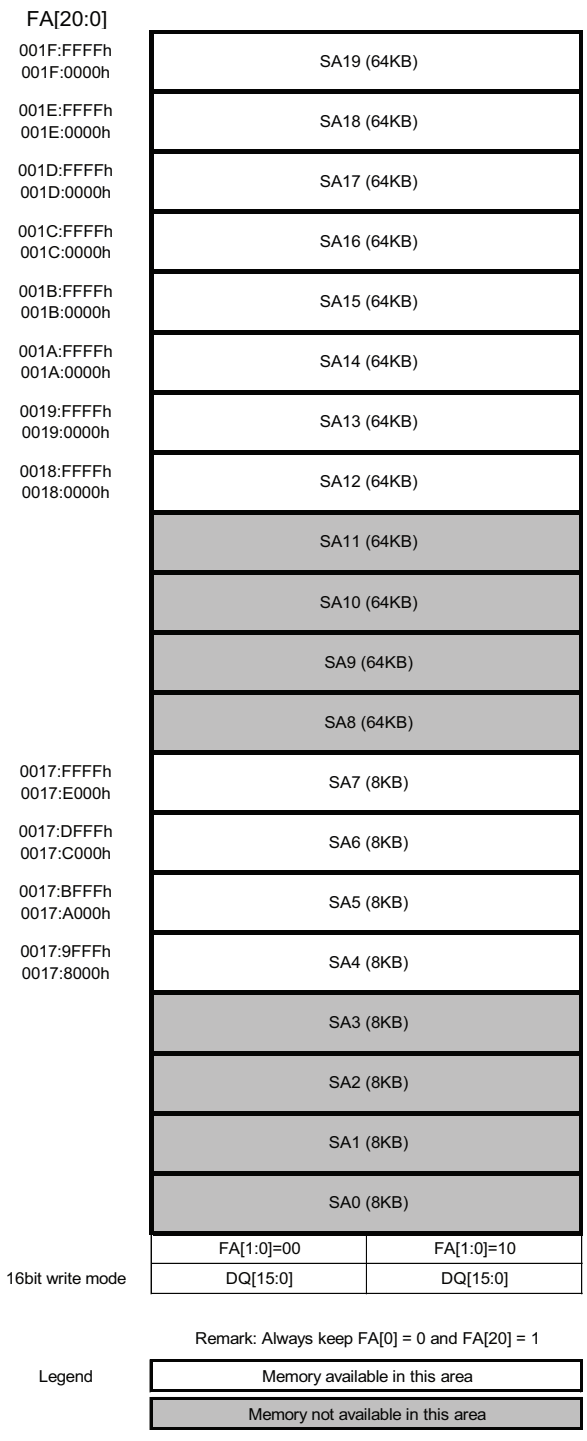


9.3.1.2 Flash Memory Map MB91F466BA

Addr									
0014:FFFFh 0014:C000h	SA6 (8KB)				SA7 (8KB)				ROMS7
0014:BFFFh 0014:8000h	SA4 (8KB)				SA5 (8KB)				
0014:7FFFh 0014:4000h	SA2 (8KB)				SA3 (8KB)				
0014:3FFFh 0014:0000h	SA0 (8KB)				SA1 (8KB)				
0013:FFFFh 0012:0000h	SA22 (64KB)				SA23 (64KB)				ROMS6
0011:FFFFh 0010:0000h	SA20 (64KB)				SA21 (64KB)				
000F:FFFFh 000E:0000h	SA18 (64KB)				SA19 (64KB)				ROMS5
000D:FFFFh 000C:0000h	SA16 (64KB)				SA17 (64KB)				ROMS4
000B:FFFFh 000A:0000h	SA14 (64KB)				SA15 (64KB)				ROMS3
0009:FFFFh 0008:0000h	SA12 (64KB)				SA13 (64KB)				ROMS2
0007:FFFFh 0006:0000h	SA10 (64KB)				SA11 (64KB)				ROMS1
0005:FFFFh 0004:0000h	SA8 (64KB)				SA9 (64KB)				ROMS0
	addr+0	addr+1	addr+2	addr+3	addr+4	addr+5	addr+6	addr+7	
16bit read/write	dat[31:16]		dat[15:0]		dat[31:16]		dat[15:0]		
32bit read	dat[31:0]				dat[31:0]				
64bit read	dat[63:0]								

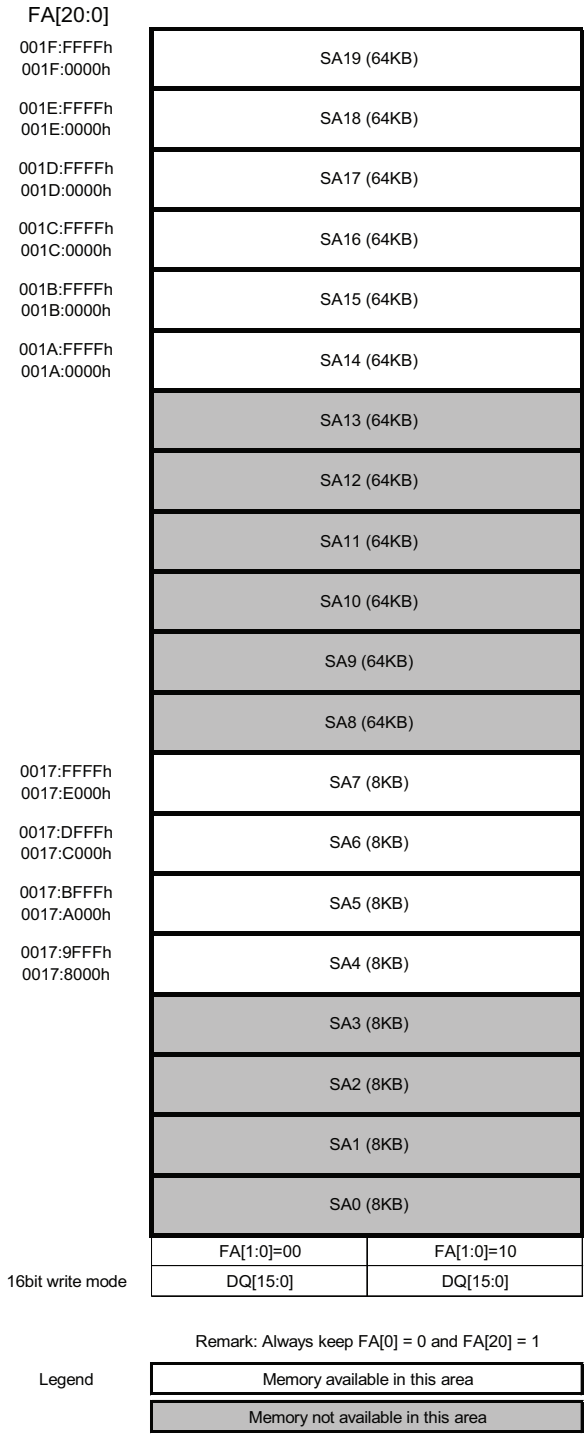
Legend	Memory not available in this area	Memory available in this area

MB91F465BB



Remark: Always keep FA[0] = 0 and FA[20] = 1

MB91F464BB



Remark: Always keep FA[0] = 0 and FA[20] = 1

9.4.2 Pin Connections in Parallel Programming Mode

Resetting after setting the MD[2:0] pins to [111] will halt CPU functioning. At this time, the Flash memory's interface circuit enables direct control of the Flash memory unit from external pins by directly linking some of the signals to GP-Ports. Please see table below for signal mapping.

In this mode, the Flash memory appears to the external pins as a stand-alone unit. This mode is generally set when writing/erasing using the parallel Flash programmer. In this mode, all operations of the 8.5 Mbits Flash memory's Auto Algorithms are available.

Table 1. Correspondence between MBM29LV400TC and Flash Memory Control Signals

MBM29LV400TCE xternal pins	FR-CPU mode	MB91F467BA/466BA/F465BB/F464BB External Pins			Comment
		Flash memory mode	Normal function	Pin number	
-	INITX	-	INITX	84	
RESET	-	FRSTX	GP16_6	70	
-	-	MD2	MD2	76	Set to ‘1’
-	-	MD1	MD1	75	Set to ‘1’
-	-	MD0	MD0	74	Set to ‘1’
RY/BY	FMCS:RDY bit	RY/BYX	GP18_2	100	
BYTE	Internally fixed to ‘H’	BYTEX	GP16_4	68	
WE	Internal control signal + control via interface circuit	WEX	GP16_7	71	
OE		OEX	GP07_7	3	
CE		CEX	GP07_6	2	
-		ATDIN	GP18_6	103	Set to ‘0’
-		EQIN	GP18_5	102	Set to ‘0’
-		TESTX	GP16_5	69	Set to ‘1’
-		RDYI	GP18_4	101	Set to ‘0’
A-1	Internal address bus	FA0	GP05_5	17	Set to ‘0’
A0 to A3		FA1 to FA4	GP19_0 to GP19_2, GP19_4	92 to 95	
A4 to A7		FA5 to FA8	GP19_5 to GP19_6, GP18_0 to GP18_1	96 to 99	
A8 to A11		FA9 to FA12	GP06_0 to GP06_3	4 to 7	
A12 to A15		FA13 to FA16	GP06_4 to GP06_7	8 to 11	
A16 to A18		FA17 to FA19	GP05_0 to GP05_2	12 to 14	
A19		FA20	GP05_3	15	See note [1]
-		FA21	GP05_4	16	See note [2]
DQ0 to DQ7	Internal data bus	DQ0 to DQ7	GP00_0 to GP00_7	28 to 35	
DQ8 to DQ15		DQ8 to DQ15	GP01_0 to GP01_7	20 to 27	

1. A19 is used as address bit on MB91F467BA/F466BA. For MB91F465BB/F464BB, set this pin to ‘1’.
2. For MB91F467BA/F466BA, set this pin to ‘1’. For MB91F465BB/F464BB, this pin can be left open.

9.5 Poweron Sequence in Parallel Programming Mode

The flash memory can be accessed in programming mode after a certain wait time, which is needed for Security Vector fetch:

- Minimum wait time after VDD5/VDD5R power on: 2.76 ms
- Minimum wait time after INITX rising: 1.0 ms

9.6 Flash Security

9.6.1 Vector Addresses

Two Flash Security Vectors (FSV1, FSV2) are located parallel to the Boot Security Vectors (BSV1, BSV2) controlling the protection functions of the Flash Security Module:

FSV1: 0x14:8000 BSV1: 0x14:8004
FSV2: 0x14:8008 BSV2: 0x14:800C

9.6.2 Security Vector FSV1

The setting of the Flash Security Vector FSV1 is responsible for the read and write protection modes and the individual write protection of the 8 KBytes sectors.

9.6.2.1 FSV1 (bit31 to bit16)

The setting of the Flash Security Vector FSV1 bits [31:16] is responsible for the read and write protection modes.

Table 2. Explanation of the bits in the Flash Security Vector FSV1[31:16]

FSV1[31:19]	FSV1[18] Write Protection Level	FSV1[17] Write Protection	FSV1[16] Read Protection	Flash Security Mode
set all to ‘0’	set to ‘0’	set to ‘0’	set to ‘1’	Read Protection (all device modes, except INTVEC mode MD[2:0]=”000”)
set all to ‘0’	set to ‘0’	set to ‘1’	set to ‘0’	Write Protection (all device modes, without exception)
set all to ‘0’	set to ‘0’	set to ‘1’	set to ‘1’	Read Protection (all device modes, except INTVEC mode MD[2:0]=”000”) and Write Protection (all device modes)
set all to ‘0’	set to ‘1’	set to ‘0’	set to ‘1’	Read Protection (all device modes, except INTVEC mode MD[2:0]=”000”)
set all to ‘0’	set to ‘1’	set to ‘1’	set to ‘0’	Write Protection (all device modes, except INTVEC mode MD[2:0]=”000”)
set all to ‘0’	set to ‘1’	set to ‘1’	set to ‘1’	Read Protection (all device modes, except INTVEC mode MD[2:0]=”000”) and Write Protection (all device modes except INTVEC mode MD[2:0]=”000”)

Address	Register				Block
	+0	+1	+2	+3	
000000_H	PDR00 [R/W] XXXXXXXX	PDR01 [R/W] XXXXXXXX	Reserved	Reserved	R-bus Port Data Register
000004_H	Reserved	PDR05 [R/W] - - XXXXXX	PDR06 [R/W] XXXXXXXX	PDR07 [R/W] XXXXXXXX	
000008_H	PDR08 [R/W] X - - X - - - X	PDR09 [R/W] - - - - - - XX	PDR10 [R/W] - - - - - - - X	Reserved	
$00000C_H$	Reserved	Reserved	PDR14 [R/W] XXXXXXXX	PDR15 [R/W] XXXXXXXX	
000010_H	PDR16 [R/W] XXXXXXXX	PDR17 [R/W] XXXXXXXX	PDR18 [R/W] - XXX - XXX	PDR19 [R/W] - XXX - XXX	
000014_H	PDR20 [R/W] - XXX - XXX	PDR21 [R/W] - - - - - - XX	PDR22 [R/W] XXXXXXXX	PDR23 [R/W] XXXXXXXX	
000018_H	PDR24 [R/W] XXXXXXXX	Reserved	PDR26 [R/W] XXXXXXXX	PDR27 [R/W] XXXXXXXX	
$00001C_H$	PDR28 [R/W] XXXXXXXX	PDR29 [R/W] XXXXXXXX	Reserved	Reserved	
000020_H to $00002C_H$	Reserved				
000030_H	EIRR0 [R/W] MB91F467BA: 00000000:MD3=0 11110000:MD3=1 MB91F465BB: XXXXXXXX	ENIR0 [R/W] 00000000	ELVR0 [R/W] 00000000 00000000		External interrupt (INT 0 to INT 7)
000034_H	EIRR1 [R/W] MB91F467BA: 00000000 MB91F465BB: XXXXXXXX	ENIR1 [R/W] 00000000	ELVR1 [R/W] 00000000 00000000		External interrupt (INT 8 to INT 15)
000038_H	DICR [R/W] - - - - - - - 0	HRCL [R/W] 0 - - 11111	RBSYNC		Delay interrupt
$00003C_H$	Reserved				Reserved
000040_H	SCR00 [R/W,W] 00000000	SMR00 [R/W,W] 00000000	SSR00 [R/W,R] 00001000	RDR00/TDR00 [R/W] 00000000	LIN-USART 0
000044_H	ESCR00 [R/W] 00000X00	ECCR00 [R/W,R,W] -00000XX	Reserved		
000048_H $00004C_H$	Reserved				Reserved
000050_H	SCR02 [R/W,W] 00000000	SMR02 [R/W,W] 00000000	SSR02 [R/W,R] 00001000	RDR02/TDR02 [R/W] 00000000	LIN-USART 2
000054_H	ESCR02 [R/W] 00000X00	ECCR02 [R/W,R,W] -00000XX	Reserved		

Address	Register				Block
	+0	+1	+2	+3	
$000D00_H$	PDRD00 [R] XXXXXXXX	PDRD01 [R] XXXXXXXX	Reserved		R-bus Port Data Direct Read Register
$000D04_H$	Reserved	PDRD05 [R] - - XXXXXX	PDRD06 [R] XXXXXXXX	PDRD07 [R] XXXXXXXX	
$000D08_H$	PDRD08 [R] X - - X - - -X	PDRD09 [R] - - - - - - XX	PDRD10 [R] - - - - - - - X	Reserved	
$000D0C_H$	Reserved		PDRD14 [R] XXXXXXXX	PDRD15 [R] XXXXXXXX	
$000D10_H$	PDRD16 [R] XXXXXXXX	PDRD17 [R] XXXXXXXX	PDRD18 [R] - XXX - XXX	PDRD19 [R] - XXX - XXX	
$000D14_H$	PDRD20 [R] - XXX - XXX	PDRD21 [R] - - - - - - - X	PDRD22 [R] XXXXXXXX	PDRD23 [R] XXXXXXXX	
$000D18_H$	PDRD24 [R] XXXXXXXX	Reserved	PDRD26 [R] XXXXXXXX	PDRD27 [R] XXXXXXXX	
$000D1C_H$	PDRD28 [R] XXXXXXXX	PDRD29 [R] XXXXXXXX	Reserved		
$000D20_H$ to $000D3C_H$	Reserved				
$000D40_H$	DDR00 [R/W] 00000000	DDR01 [R/W] 00000000	Reserved		R-bus Port Direction Register
$000D44_H$	Reserved	DDR05 [R/W] - - 000000	DDR06 [R/W] 00000000	DDR07 [R/W] 00000000	
$000D48_H$	DDR08 [R/W] 0 - - 0 - - -0	DDR09 [R/W] - - - - - - 00	DDR10 [R/W] - - - - - - -0	Reserved	
$000D4C_H$	Reserved		DDR14 [R/W] 00000000	DDR15 [R/W] 00000000	
$000D50_H$	DDR16 [R/W] 00000000	DDR17 [R/W] 00000000	DDR18 [R/W] - 000 - 000	DDR19 [R/W] - 000 - 000	
$000D54_H$	DDR20 [R/W] - 000 - 000	DDR21 [R/W] - - - - - - 00	DDR22 [R/W] 00000000	DDR23 [R/W] 00000000	
$000D58_H$	DDR24 [R/W] 00000000	Reserved	DDR26 [R/W] 00000000	DDR27 [R/W] 00000000	
$000D5C_H$	DDR28 [R/W] 00000000	DDR29 [R/W] 00000000	Reserved		
$000D60_H$ to $000D7C_H$	Reserved				Reserved

Address	Register				Block
	+0	+1	+2	+3	
$000E40_H$	PILR00 [R/W] 00000000	PILR01 [R/W] 00000000	Reserved		R-bus Port Input Level Select Register
$000E44_H$	Reserved	PILR05 [R/W] - - 000000	PILR06 [R/W] 00000000	PILR07 [R/W] 00000000	
$000E48_H$	PILR08 [R/W] 0 - - 0 - - - 0	PILR09 [R/W] - - - - - - 00	PILR10 [R/W] - - - - - - - 0	Reserved	
$000E4C_H$	Reserved		PILR14 [R/W] 00000000	PILR15 [R/W] 00000000	
$000E50_H$	PILR16 [R/W] 00000000	PILR17 [R/W] 00000000	PILR18 [R/W] - - - - - 000	PILR19 [R/W] - 000 - 000	
$000E54_H$	PILR20 [R/W] - 000 - 000	PILR21 [R/W] - - - - - - 00	PILR22 [R/W] 00000000	PILR23 [R/W] 00000000	
$000E58_H$	PILR24 [R/W] 00000000	Reserved	PILR26 [R/W] 00000000	PILR27 [R/W] 00000000	
$000E5C_H$	PILR28 [R/W] 00000000	PILR29 [R/W] 00000000	Reserved		
$000E60_H$ to $000E7C_H$	Reserved				Reserved
$000E80_H$	EPILR00 [R/W] 00000000	EPILR01 [R/W] 00000000	Reserved		R-bus Port Extra Input Level Select Register
$000E84_H$	Reserved	EPILR05 [R/W] - - 000000	EPILR06 [R/W] 00000000	EPILR07 [R/W] 00000000	
$000E88_H$	EPILR08 [R/W] 0 - - 0- - - 0	EPILR09 [R/W] - - - - - - 00	EPILR10 [R/W] - - - - - - - 0	Reserved	
$000E8C_H$	Reserved		EPILR14 [R/W] 00000000	EPILR15 [R/W] 00000000	
$000E90_H$	EPILR16 [R/W] 00000000	EPILR17 [R/W] 00000000	EPILR18 [R/W] - - - - - 000	EPILR19 [R/W] - 000 - 000	
$000E94_H$	EPILR20 [R/W] - 000 - 000	EPILR21 [R/W] - - - - - - 00	EPILR22 [R/W] 00000000	EPILR23 [R/W] 00000000	
$000E98_H$	EPILR24 [R/W] 00000000	Reserved	EPILR26 [R/W] 00000000	EPILR27 [R/W] 00000000	
$000E9C_H$	EPILR28 [R/W] 00000000	EPILR29 [R/W] 00000000	Reserved		
$000EA0_H$ to $000EBC_H$	Reserved				Reserved

Address	Register				Block
	+0	+1	+2	+3	
$00C280_H$	TREQR22 [R] 00000000 00000000		TREQR12 [R] 00000000 00000000		CAN 2 Status Flags
$00C284_H$ to $00C28C_H$	Reserved		Reserved		
$00C290_H$	NEWDT22 [R] 00000000 00000000		NEWDT12 [R] 00000000 00000000		
$00C294_H$ to $00C29C_H$	Reserved		Reserved		
$00C2A0_H$	INTPND22 [R] 00000000 00000000		INTPND12 [R] 00000000 00000000		
$00C2A4_H$ to $00C2AC_H$	Reserved		Reserved		
$00C2B0_H$	MSGVAL22 [R] 00000000 00000000		MSGVAL12 [R] 00000000 00000000		
$00C2B4_H$ to $00C2FC_H$	Reserved				Reserved
$00C300_H$	CTRLR3 [R/W] 00000000 00000001		STATR3 [R/W] 00000000 00000000		CAN 3 Control Register **Note:** Not on MB91F465BB/MB91F464BB
$00C304_H$	ERRCNT3 [R] 00000000 00000000		BTR3 [R/W] 00100011 00000001		
$00C308_H$	INTR3 [R] 00000000 00000000		TESTR3 [R/W] 00000000 X0000000		
$00C30C_H$	BRPE3 [R/W] 00000000 00000000		CBSYNC3		

Address	Register				Block
	+0	+1	+2	+3	
$00C380_H$	TREQR23 [R] 00000000 00000000		TREQR13 [R] 00000000 00000000		CAN 3 Status Flags **Note**: Not on MB91F465BB/MB91F464BB
$00C384_H$ to $00C38C_H$	Reserved				
$00C390_H$	NEWDT23 [R] 00000000 00000000		NEWDT13 [R] 00000000 00000000		
$00C394_H$ to $00C39C_H$	Reserved				
$00C3A0_H$	INTPND23 [R] 00000000 00000000		INTPND13 [R] 00000000 00000000		
$00C3A4_H$ to $00C3AC_H$	Reserved				
$00C3B0_H$	MSGVAL23 [R] 00000000 00000000		MSGVAL13 [R] 00000000 00000000		
$00C3B4_H$ to $00C3FC_H$	Reserved				
$00C400_H$	CTRLR4 [R/W] 00000000 00000001		STATR4 [R/W] 00000000 00000000		CAN 4 Control Register **Note**: Not on MB91F465BB/MB91F464BB
$00C404_H$	ERRCNT4 [R] 00000000 00000000		BTR4 [R/W] 00100011 00000001		
$00C408_H$	INTR4 [R] 00000000 00000000		TESTR4 [R/W] 00000000 X0000000		
$00C40C_H$	BRPE4 [R/W] 00000000 00000000		CBSYNC4		
$00C410_H$	IF1CREQ4 [R/W] 00000000 00000001		IF1CMSK4 [R/W] 00000000 00000000		CAN 4 IF 1 Register **Note:** Not on MB91F465BB/MB91F464BB
$00C414_H$	IF1MSK24 [R/W] 11111111 11111111		IF1MSK14 [R/W] 11111111 11111111		
$00C418_H$	IF1ARB24 [R/W] 00000000 00000000		IF1ARB14 [R/W] 00000000 00000000		
$00C41C_H$	IF1MCTR4 [R/W] 00000000 00000000		Reserved		
$00C420_H$	IF1DTA14 [R/W] 00000000 00000000		IF1DTA24 [R/W] 00000000 00000000		
$00C424_H$	IF1DTB14 [R/W] 00000000 00000000		IF1DTB24 [R/W] 00000000 00000000		
$00C428_H$ to $00C42C_H$	Reserved				
$00C430_H$	IF1DTA24 [R/W] 00000000 00000000		IF1DTA14 [R/W] 00000000 00000000		
$00C434_H$	IF1DTB24 [R/W] 00000000 00000000		IF1DTB14 [R/W] 00000000 00000000		
$00C438_H$ to $00C43C_H$	Reserved				

15.7.4 I ^{2}C AC Timings at $V_{DD}5$ = 3.0 to 5.5 V

■ Conditions during AC measurements
All AC tests were measured under the following conditions:
- ❒ -IO_{drive} = 3 mA
- ❒ -$V_{DD}5$ = 3.0 V to 5.5 V, I_{load} = 3 mA
- ❒ -$V_{SS}5$ = 0 V
- ❒ -Ta = - 40 °C to + 125 °C
- ❒ -C_l = 50 pF
- ❒ -VOL = 0.3 × $V_{DD}5$
- ❒ -VOH = 0.7 × $V_{DD}5$
- ❒ -EPILR = 0, PILR = 0 (CMOS Hysteresis 0.3 × $V_{DD}5$/0.7 × $V_{DD}5$)

15.7.4.1 Fast mode:

($V_{DD}5$ = 3.5 V to 5.5 V, $V_{SS}5$ = $AV_{SS}5$ = 0 V, T_A = –40 °C to + 125 °C)

Parameter	Symbol	Pin name	Value		Unit	Remark
			Min	Max		
SCL clock frequency	f_{SCL}	SCLn	0	400	kHz	
Hold time (repeated) START condition. After this period, the first clock pulse is generated	$t_{HD;STA}$	SCLn, SDAn	0.6	–	µs	
LOW period of the SCL clock	t_{LOW}	SCLn	1.3	–	µs	
HIGH period of the SCL clock	t_{HIGH}	SCLn	0.6	–	µs	
Setup time for a repeated START condition	$t_{SU;STA}$	SCLn, SDAn	0.6	–	µs	
Data hold time for I^{2}C-bus devices	$t_{HD;DAT}$	SCLn, SDAn	0	0.9	µs	
Data setup time	$t_{SU;DAT}$	SCLn SDAn	100	–	ns	
Rise time of both SDA and SCL signals	t_r	SCLn, SDAn	20 + 0.1Cb	300	ns	
Fall time of both SDA and SCL signals	t_f	SCLn, SDAn	20 + 0.1Cb	300	ns	
Setup time for STOP condition	$t_{SU;STO}$	SCLn, SDAn	0.6	–	µs	
Bus free time between a STOP and START condition	t_{BUF}	SCLn, SDAn	1.3	–	µs	
Capacitive load for each bus line	C_b	SCLn, SDAn	–	400	pF	
Pulse width of spike suppressed by input filter	t_{SP}	SCLn, SDAn	0	(1..1.5) × t_{CLKP}	ns	[1]

1. The noise filter will suppress single spikes with a pulse width of 0ns and between (1 to 1.5) cycles of peripheral clock, depending on the phase relationship between I^{2}C signals (SDA, SCL) and peripheral clock.

Note: t_{CLKP} is the cycle time of the peripheral clock.

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