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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	63
Number of Logic Elements/Cells	504
Total RAM Bits	-
Number of I/O	118
Number of Gates	6000
Voltage - Supply	4.75V ~ 5.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	160-BQFP
Supplier Device Package	160-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/intel/epf8636aqc160-3n

FLEX 8000 devices provide a large number of storage elements for applications such as digital signal processing (DSP), wide-data-path manipulation, and data transformation. These devices are an excellent choice for bus interfaces, TTL integration, coprocessor functions, and high-speed controllers. The high-pin-count packages can integrate multiple 32-bit buses into a single device. [Table 3](#) shows FLEX 8000 performance and LE requirements for typical applications.

Table 3. FLEX 8000 Performance

Application	LEs Used	Speed Grade			Units
		A-2	A-3	A-4	
16-bit loadable counter	16	125	95	83	MHz
16-bit up/down counter	16	125	95	83	MHz
24-bit accumulator	24	87	67	58	MHz
16-bit address decode	4	4.2	4.9	6.3	ns
16-to-1 multiplexer	10	6.6	7.9	9.5	ns

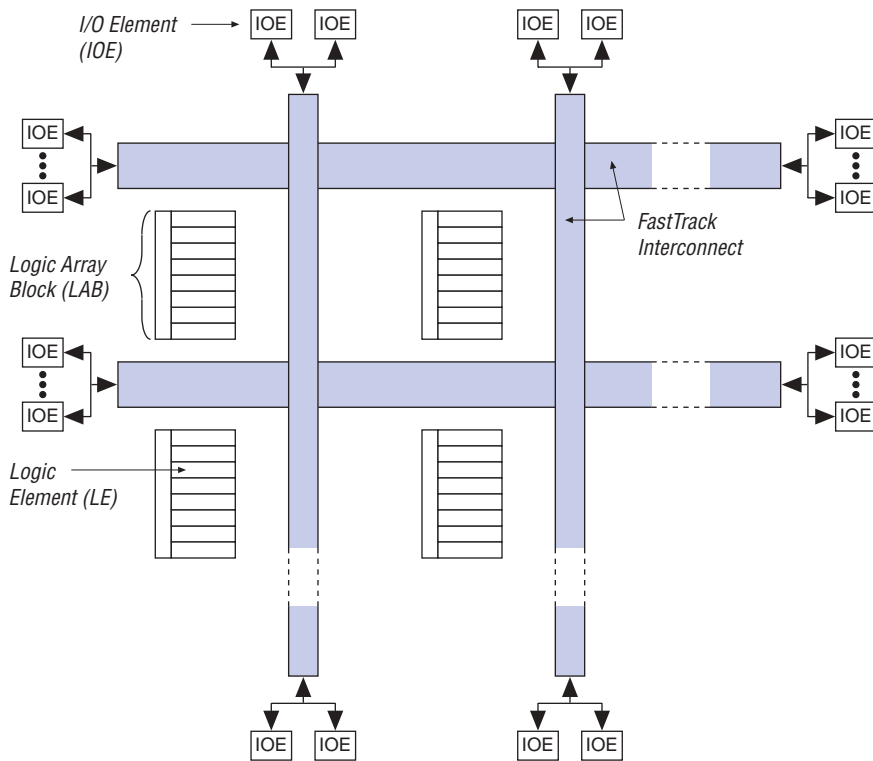
All FLEX 8000 device packages provide four dedicated inputs for synchronous control signals with large fan-outs. Each I/O pin has an associated register on the periphery of the device. As outputs, these registers provide fast clock-to-output times; as inputs, they offer quick setup times.

The logic and interconnections in the FLEX 8000 architecture are configured with CMOS SRAM elements. FLEX 8000 devices are configured at system power-up with data stored in an industry-standard parallel EPROM or an Altera serial configuration devices, or with data provided by a system controller. Altera offers the EPC1, EPC1213, EPC1064, and EPC1441 configuration devices, which configure FLEX 8000 devices via a serial data stream. Configuration data can also be stored in an industry-standard 32 K × 8 bit or larger configuration device, or downloaded from system RAM. After a FLEX 8000 device has been configured, it can be reconfigured in-circuit by resetting the device and loading new data. Because reconfiguration requires less than 100 ms, real-time changes can be made during system operation. For information on how to configure FLEX 8000 devices, go to the following documents:

- [Configuration Devices for APEX & FLEX Devices Data Sheet](#)
- [BitBlaster Serial Download Cable Data Sheet](#)
- [ByteBlasterMV Parallel Port Download Cable Data Sheet](#)
- [Application Note 33 \(Configuring FLEX 8000 Devices\)](#)
- [Application Note 38 \(Configuring Multiple FLEX 8000 Devices\)](#)

Figure 1 shows a block diagram of the FLEX 8000 architecture. Each group of eight LEs is combined into an LAB; LABs are arranged into rows and columns. The I/O pins are supported by I/O elements (IOEs) located at the ends of rows and columns. Each IOE contains a bidirectional I/O buffer and a flipflop that can be used as either an input or output register.

Figure 1. FLEX 8000 Device Block Diagram



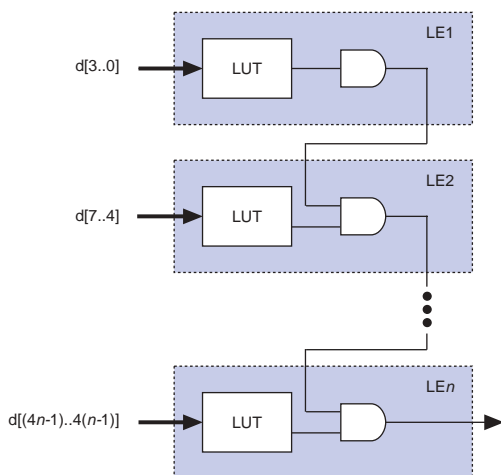
Signal interconnections within FLEX 8000 devices and between device pins are provided by the FastTrack Interconnect, a series of fast, continuous channels that run the entire length and width of the device. IOEs are located at the end of each row (horizontal) and column (vertical) FastTrack Interconnect path.

The MAX+PLUS II Compiler can create cascade chains automatically during design processing; designers can also insert cascade chain logic manually during design entry. Cascade chains longer than eight LEs are automatically implemented by linking LABs together. The last LE of an LAB cascades to the first LE of the next LAB.

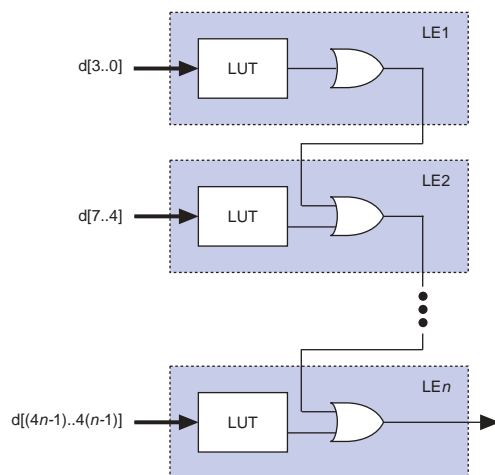
Figure 5 shows how the cascade function can connect adjacent LEs to form functions with a wide fan-in. These examples show functions of $4n$ variables implemented with n LEs. For a device with an A-2 speed grade, the LE delay is 2.4 ns; the cascade chain delay is 0.6 ns. With the cascade chain, 4.2 ns is needed to decode a 16-bit address.

Figure 5. FLEX 8000 Cascade Chain Operation

AND Cascade Chain



OR Cascade Chain



LE Operating Modes

The FLEX 8000 LE can operate in one of four modes, each of which uses LE resources differently. See Figure 6. In each mode, seven of the ten available inputs to the LE—the four data inputs from the LAB local interconnect, the feedback from the programmable register, and the carry-in and cascade-in from the previous LE—are directed to different destinations to implement the desired logic function. The three remaining inputs to the LE provide clock, clear, and preset control for the register. The MAX+PLUS II software automatically chooses the appropriate mode for each application. Design performance can also be enhanced by designing for the operating mode that supports the desired application.

Asynchronous Clear

A register is cleared by one of the two LABCTRL signals. When the CLRn port receives a low signal, the register is set to zero.

Asynchronous Preset

An asynchronous preset is implemented as either an asynchronous load or an asynchronous clear. If DATA3 is tied to VCC, asserting LABCTRL1 asynchronously loads a 1 into the register. Alternatively, the MAX+PLUS II software can provide preset control by using the clear and inverting the input and output of the register. Inversion control is available for the inputs to both LEs and IOEs. Therefore, if a register is preset by only one of the two LABCTRL signals, the DATA3 input is not needed and can be used for one of the LE operating modes.

Asynchronous Clear & Preset

When implementing asynchronous clear and preset, LABCTRL1 controls the preset and LABCTRL2 controls the clear. The DATA3 input is tied to VCC; therefore, asserting LABCTRL1 asynchronously loads a 1 into the register, effectively presetting the register. Asserting LABCTRL2 clears the register.

Asynchronous Load with Clear

When implementing an asynchronous load with the clear, LABCTRL1 implements the asynchronous load of DATA3 by controlling the register preset and clear. LABCTRL2 implements the clear by controlling the register clear.

Asynchronous Load with Preset

When implementing an asynchronous load in conjunction with a preset, the MAX+PLUS II software provides preset control by using the clear and inverting the input and output of the register. Asserting LABCTRL2 clears the register, while asserting LABCTRL1 loads the register. The MAX+PLUS II software inverts the signal that drives the DATA3 signal to account for the inversion of the register's output.

Asynchronous Load without Clear or Preset

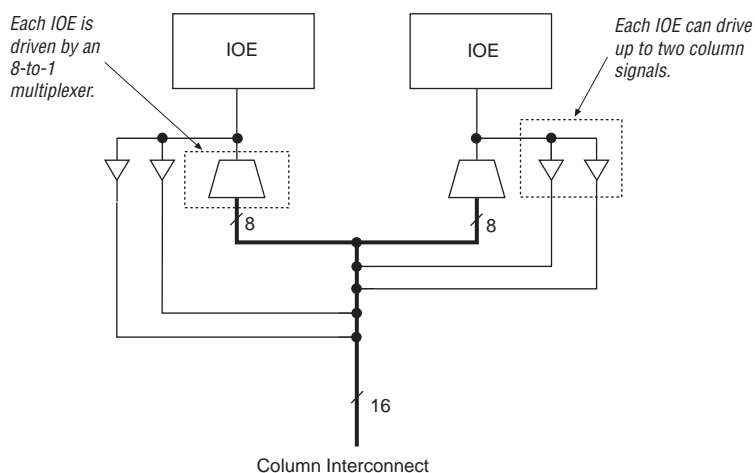
When implementing an asynchronous load without the clear or preset, LABCTRL1 implements the asynchronous load of DATA3 by controlling the register preset and clear.

Each LE in an LAB can drive up to two separate column interconnect channels. Therefore, all 16 available column channels can be driven by the LAB. The column channels run vertically across the entire device, and share access to LABs in the same column but in different rows. The MAX+PLUS II Compiler chooses which LEs must be connected to a column channel. A row interconnect channel can be fed by the output of the LE or by two column channels. These three signals feed a multiplexer that connects to a specific row channel. Each LE is connected to one 3-to-1 multiplexer. In an LAB, the multiplexers provide all 16 column channels with access to 8 row channels.

Each column of LABs has a dedicated column interconnect that routes signals out of the LABs into the column. The column interconnect can then drive I/O pins or feed into the row interconnect to route the signals to other LABs in the device. A signal from the column interconnect, which can be either the output of an LE or an input from an I/O pin, must transfer to the row interconnect before it can enter an LAB. [Table 4](#) summarizes the FastTrack Interconnect resources available in each FLEX 8000 device.

Table 4. FLEX 8000 FastTrack Interconnect Resources				
Device	Rows	Channels per Row	Columns	Channels per Column
EPF8282A EPF8282AV	2	168	13	16
EPF8452A	2	168	21	16
EPF8636A	3	168	21	16
EPF8820A	4	168	21	16
EPF81188A	6	168	21	16
EPF81500A	6	216	27	16

[Figure 9](#) shows the interconnection of four adjacent LABs, with row, column, and local interconnects, as well as the associated cascade and carry chains.

Figure 12. FLEX 8000 Column-to-IOE Connections

In addition to general-purpose I/O pins, FLEX 8000 devices have four dedicated input pins. These dedicated inputs provide low-skew, device-wide signal distribution, and are typically used for global clock, clear, and preset control signals. The signals from the dedicated inputs are available as control signals for all LABs and I/O elements in the device. The dedicated inputs can also be used as general-purpose data inputs because they can feed the local interconnect of each LAB in the device.

Signals enter the FLEX 8000 device either from the I/O pins that provide general-purpose input capability or from the four dedicated inputs. The IOEs are located at the ends of the row and column interconnect channels.

I/O pins can be used as input, output, or bidirectional pins. Each I/O pin has a register that can be used either as an input register for external data that requires fast setup times, or as an output register for data that requires fast clock-to-output performance. The MAX+PLUS II Compiler uses the programmable inversion option to invert signals automatically from the row and column interconnect when appropriate.

The clock, clear, and output enable controls for the IOEs are provided by a network of I/O control signals. These signals can be supplied by either the dedicated input pins or by internal logic. The IOE control-signal paths are designed to minimize the skew across the device. All control-signal sources are buffered onto high-speed drivers that drive the signals around the periphery of the device. This “peripheral bus” can be configured to provide up to four output enable signals (10 in EPF81500A devices), and up to two clock or clear signals. [Figure 13 on page 22](#) shows how two output enable signals are shared with one clock and one clear signal.

Table 10. FLEX 8000 5.0-V Device Recommended Operating Conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{CCINT}	Supply voltage for internal logic and input buffers	(3), (4)	4.75 (4.50)	5.25 (5.50)	V
V_{CCIO}	Supply voltage for output buffers, 5.0-V operation	(3), (4)	4.75 (4.50)	5.25 (5.50)	V
	Supply voltage for output buffers, 3.3-V operation	(3), (4)	3.00 (3.00)	3.60 (3.60)	V
V_I	Input voltage		-0.5	$V_{CCINT} + 0.5$	V
V_O	Output voltage		0	V_{CCIO}	V
T_A	Operating temperature	For commercial use	0	70	° C
		For industrial use	-40	85	° C
t_R	Input rise time			40	ns
t_F	Input fall time			40	ns

Table 11. FLEX 8000 5.0-V Device DC Operating Conditions Notes (5), (6)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IH}	High-level input voltage		2.0		$V_{CCINT} + 0.5$	V
V_{IL}	Low-level input voltage		-0.5		0.8	V
V_{OH}	5.0-V high-level TTL output voltage	$I_{OH} = -4$ mA DC (7) $V_{CCIO} = 4.75$ V	2.4			V
	3.3-V high-level TTL output voltage	$I_{OH} = -4$ mA DC (7) $V_{CCIO} = 3.00$ V	2.4			V
	3.3-V high-level CMOS output voltage	$I_{OH} = -0.1$ mA DC (7) $V_{CCIO} = 3.00$ V	$V_{CCIO} - 0.2$			V
V_{OL}	5.0-V low-level TTL output voltage	$I_{OL} = 12$ mA DC (7) $V_{CCIO} = 4.75$ V			0.45	V
	3.3-V low-level TTL output voltage	$I_{OL} = 12$ mA DC (7) $V_{CCIO} = 3.00$ V			0.45	V
	3.3-V low-level CMOS output voltage	$I_{OL} = 0.1$ mA DC (7) $V_{CCIO} = 3.00$ V			0.2	V
I_I	Input leakage current	$V_I = V_{CC}$ or ground	-10		10	μA
I_{OZ}	Tri-state output off-state current	$V_O = V_{CC}$ or ground	-40		40	μA
I_{CC0}	V_{CC} supply current (standby)	$V_I =$ ground, no load		0.5	10	mA

Table 15. FLEX 8000 3.3-V Device DC Operating Conditions *Note (4)*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IH}	High-level input voltage		2.0		$V_{CC} + 0.3$	V
V_{IL}	Low-level input voltage		-0.3		0.8	V
V_{OH}	High-level output voltage	$I_{OH} = -0.1$ mA DC (5)	$V_{CC} - 0.2$			V
V_{OL}	Low-level output voltage	$I_{OL} = 4$ mA DC (5)			0.45	V
I_I	Input leakage current	$V_I = V_{CC}$ or ground	-10		10	μ A
I_{OZ}	Tri-state output off-state current	$V_O = V_{CC}$ or ground	-40		40	μ A
I_{CC0}	V_{CC} supply current (standby)	$V_I =$ ground, no load (6)		0.3	10	mA

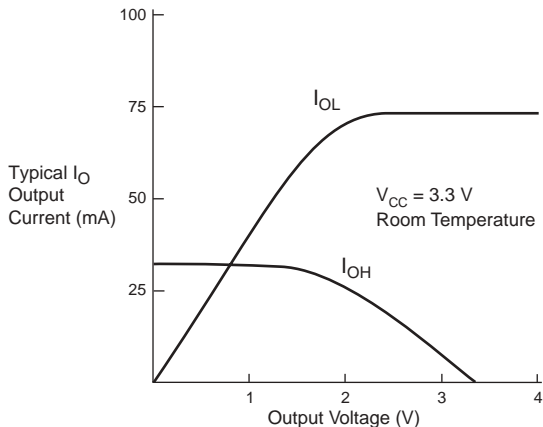
Table 16. FLEX 8000 3.3-V Device Capacitance *Note (7)*

Symbol	Parameter	Conditions	Min	Max	Unit
C_{IN}	Input capacitance	$V_{IN} = 0$ V, $f = 1.0$ MHz		10	pF
C_{OUT}	Output capacitance	$V_{OUT} = 0$ V, $f = 1.0$ MHz		10	pF

Notes to tables:

- (1) See the *Operating Requirements for Altera Devices Data Sheet*.
- (2) Minimum DC input voltage is -0.3 V. During transitions, the inputs may undershoot to -2.0 V or overshoot to 5.3 V for input currents less than 100 mA and periods shorter than 20 ns.
- (3) The maximum V_{CC} rise time is 100 ms. V_{CC} must rise monotonically.
- (4) These values are specified in [Table 14 on page 29](#).
- (5) The I_{OH} parameter refers to high-level TTL output current; the I_{OL} parameter refers to low-level TTL output current.
- (6) Typical values are for $T_A = 25^\circ$ C and $V_{CC} = 3.3$ V.
- (7) Capacitance is sample-tested only.

Figure 16 shows the typical output drive characteristics of 5.0-V FLEX 8000 devices. The output driver is compliant with *PCI Local Bus Specification, Revision 2.2*.

Figure 18. Output Drive Characteristics of EPF8282AV Devices

Timing Model

The continuous, high-performance FastTrack Interconnect routing structure ensures predictable performance and accurate simulation and timing analysis. This predictable performance contrasts with that of FPGAs, which use a segmented connection scheme and hence have unpredictable performance. Timing simulation and delay prediction are available with the MAX+PLUS II Simulator and Timing Analyzer, or with industry-standard EDA tools. The Simulator offers both pre-synthesis functional simulation to evaluate logic design accuracy and post-synthesis timing simulation with 0.1-ns resolution. The Timing Analyzer provides point-to-point timing delay information, setup and hold time prediction, and device-wide performance analysis.

Tables 17 through 20 describe the FLEX 8000 timing parameters and their symbols.

Table 19. FLEX 8000 Interconnect Timing Parameters *Note (1)*

Symbol	Parameter
$t_{LABCASC}$	Cascade delay between LEs in different LABs
$t_{LABCARRY}$	Carry delay between LEs in different LABs
t_{LOCAL}	LAB local interconnect delay
t_{ROW}	Row interconnect routing delay (4)
t_{COL}	Column interconnect routing delay
t_{DIN_C}	Dedicated input to LE control delay
t_{DIN_D}	Dedicated input to LE data delay (4)
t_{DIN_IO}	Dedicated input to IOE control delay

Table 20. FLEX 8000 External Reference Timing Characteristics *Note (5)*

Symbol	Parameter
t_{DRR}	Register-to-register delay via 4 LEs, 3 row interconnects, and 4 local interconnects (6)
t_{ODH}	Output data hold time after clock (7)

Notes to tables:

- (1) Internal timing parameters cannot be measured explicitly. They are worst-case delays based on testable and external parameters specified by Altera. Internal timing parameters should be used for estimating device performance. Post-compilation timing simulation or timing analysis is required to determine actual worst-case performance.
- (2) These values are specified in [Table 10 on page 28](#) or [Table 14 on page 29](#).
- (3) For the t_{OD3} and t_{ZX3} parameters, $V_{CCIO} = 3.3\text{ V}$ or 5.0 V .
- (4) The t_{ROW} and t_{DIN_D} delays are worst-case values for typical applications. Post-compilation timing simulation or timing analysis is required to determine actual worst-case performance.
- (5) External reference timing characteristics are factory-tested, worst-case values specified by Altera. A representative subset of signal paths is tested to approximate typical device applications.
- (6) For more information on test conditions, see [Application Note 76 \(Understanding FLEX 8000 Timing\)](#).
- (7) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies to global and non-global clocking, and for LE and I/O element registers.

The FLEX 8000 timing model shows the delays for various paths and functions in the circuit. See [Figure 19](#). This model contains three distinct parts: the LE; the IOE; and the interconnect, including the row and column FastTrack Interconnect, LAB local interconnect, and carry and cascade interconnect paths. Each parameter shown in [Figure 19](#) is expressed as a worst-case value in [Tables 22 through 49](#). Hand-calculations that use the FLEX 8000 timing model and these timing parameters can be used to estimate FLEX 8000 device performance. Timing simulation or timing analysis after compilation is required to determine the final worst-case performance. [Table 21](#) summarizes the interconnect paths shown in [Figure 19](#).



For more information on timing parameters, go to [Application Note 76 \(Understanding FLEX 8000 Timing\)](#).

Table 21. FLEX 8000 Timing Model Interconnect Paths

Source	Destination	Total Delay
LE-Out	LE in same LAB	t_{LOCAL}
LE-Out	LE in same row, different LAB	$t_{ROW} + t_{LOCAL}$
LE-Out	LE in different row	$t_{COL} + t_{ROW} + t_{LOCAL}$
LE-Out	IOE on column	t_{COL}
LE-Out	IOE on row	t_{ROW}
IOE on row	LE in same row	$t_{ROW} + t_{LOCAL}$
IOE on column	Any LE	$t_{COL} + t_{ROW} + t_{LOCAL}$

Tables 22 through 49 show the FLEX 8000 internal and external timing parameters.

Table 22. EPF8282A Internal I/O Element Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t_{IOD}		0.7		0.8		0.9	ns
t_{IOC}		1.7		1.8		1.9	ns
t_{IOE}		1.7		1.8		1.9	ns
t_{IOCO}		1.0		1.0		1.0	ns
t_{IOCOMB}		0.3		0.2		0.1	ns
t_{IOSU}	1.4		1.6		1.8		ns
t_{IOH}	0.0		0.0		0.0		ns
t_{IOCLR}		1.2		1.2		1.2	ns
t_{IN}		1.5		1.6		1.7	ns
t_{OD1}		1.1		1.4		1.7	ns
t_{OD2}		—		—		—	ns
t_{OD3}		4.6		4.9		5.2	ns
t_{XZ}		1.4		1.6		1.8	ns
t_{ZX1}		1.4		1.6		1.8	ns
t_{ZX2}		—		—		—	ns
t_{ZX3}		4.9		5.1		5.3	ns

Table 26. EPF8282AV I/O Element Timing Parameters

Symbol	Speed Grade				Unit
	A-3		A-4		
	Min	Max	Min	Max	
t_{IOD}		0.9		2.2	ns
t_{IOC}		1.9		2.0	ns
t_{IOE}		1.9		2.0	ns
t_{IOCO}		1.0		2.0	ns
t_{IOCOMB}		0.1		0.0	ns
t_{IOSU}	1.8		2.8		ns
t_{IOH}	0.0		0.2		ns
t_{IOCLR}		1.2		2.3	ns
t_{IN}		1.7		3.4	ns
t_{OD1}		1.7		4.1	ns
t_{OD2}		—		—	ns
t_{OD3}		5.2		7.1	ns
t_{XZ}		1.8		4.3	ns
t_{ZX1}		1.8		4.3	ns
t_{ZX2}		—		—	ns
t_{ZX3}		5.3		8.3	ns

Table 27. EPF8282AV Interconnect Timing Parameters

Symbol	Speed Grade				Unit
	A-3		A-4		
	Min	Max	Min	Max	
$t_{LABCASC}$		0.4		1.3	ns
$t_{LABCARRY}$		0.4		0.8	ns
t_{LOCAL}		0.8		1.5	ns
t_{ROW}		4.2		6.3	ns
t_{COL}		2.5		3.8	ns
t_{DIN_C}		5.5		8.0	ns
t_{DIN_D}		7.2		10.8	ns
t_{DIN_IO}		5.5		9.0	ns

Table 28. EPF8282AV Logic Element Timing Parameters

Symbol	Speed Grade				Unit
	A-3		A-4		
	Min	Max	Min	Max	
t_{LUT}		3.2		7.3	ns
t_{CLUT}		0.0		1.4	ns
t_{RLUT}		1.5		5.1	ns
t_{GATE}		0.0		0.0	ns
t_{CASC}		0.9		2.8	ns
t_{CICO}		0.6		1.5	ns
t_{CGEN}		0.7		2.2	ns
t_{CGENR}		1.5		3.7	ns
t_C		2.5		4.7	ns
t_{CH}	4.0		6.0		ns
t_{CL}	4.0		6.0		ns
t_{CO}		0.6		0.9	ns
t_{COMB}		0.6		0.9	ns
t_{SU}	1.2		2.4		ns
t_H	1.5		4.6		ns
t_{PRE}		0.8		1.3	ns
t_{CLR}		0.8		1.3	ns

Table 29. EPF8282AV External Timing Parameters

Symbol	Speed Grade				Unit
	A-3		A-4		
	Min	Max	Min	Max	
t _{DRR}		24.8		50.1	ns
t _{ODH}	1.0		1.0		ns

Table 34. EPF8636A I/O Element Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t_{IOD}		0.7		0.8		0.9	ns
t_{IOC}		1.7		1.8		1.9	ns
t_{IOE}		1.7		1.8		1.9	ns
t_{IOCO}		1.0		1.0		1.0	ns
t_{IOCOMB}		0.3		0.2		0.1	ns
t_{IOSU}	1.4		1.6		1.8		ns
t_{IOH}	0.0		0.0		0.0		ns
t_{IOCLR}		1.2		1.2		1.2	ns
t_{IN}		1.5		1.6		1.7	ns
t_{OD1}		1.1		1.4		1.7	ns
t_{OD2}		1.6		1.9		2.2	ns
t_{OD3}		4.6		4.9		5.2	ns
t_{XZ}		1.4		1.6		1.8	ns
t_{ZX1}		1.4		1.6		1.8	ns
t_{ZX2}		1.9		2.1		2.3	ns
t_{ZX3}		4.9		5.1		5.3	ns

Table 35. EPF8636A Interconnect Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
$t_{LABCASC}$		0.3		0.4		0.4	ns
$t_{LABCARRY}$		0.3		0.4		0.4	ns
t_{LOCAL}		0.5		0.5		0.7	ns
t_{ROW}		5.0		5.0		5.0	ns
t_{COL}		3.0		3.0		3.0	ns
t_{DIN_C}		5.0		5.0		5.5	ns
t_{DIN_D}		7.0		7.0		7.5	ns
t_{DIN_IO}		5.0		5.0		5.5	ns

Table 38. EPF8820A I/O Element Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t_{IOD}		0.7		0.8		0.9	ns
t_{IOC}		1.7		1.8		1.9	ns
t_{IOE}		1.7		1.8		1.9	ns
t_{IOCO}		1.0		1.0		1.0	ns
t_{IOCOMB}		0.3		0.2		0.1	ns
t_{IOSU}	1.4		1.6		1.8		ns
t_{IOH}	0.0		0.0		0.0		ns
t_{IOCLR}		1.2		1.2		1.2	ns
t_{IN}		1.5		1.6		1.7	ns
t_{OD1}		1.1		1.4		1.7	ns
t_{OD2}		1.6		1.9		2.2	ns
t_{OD3}		4.6		4.9		5.2	ns
t_{XZ}		1.4		1.6		1.8	ns
t_{ZX1}		1.4		1.6		1.8	ns
t_{ZX2}		1.9		2.1		2.3	ns
t_{ZX3}		4.9		5.1		5.3	ns

Table 39. EPF8820A Interconnect Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
$t_{LABCASC}$		0.3		0.3		0.4	ns
$t_{LABCARRY}$		0.3		0.3		0.4	ns
t_{LOCAL}		0.5		0.6		0.8	ns
t_{ROW}		5.0		5.0		5.0	ns
t_{COL}		3.0		3.0		3.0	ns
t_{DIN_C}		5.0		5.0		5.5	ns
t_{DIN_D}		7.0		7.0		7.5	ns
t_{DIN_IO}		5.0		5.0		5.5	ns

Table 42. EPF81188A I/O Element Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t_{IOD}		0.7		0.8		0.9	ns
t_{IOC}		1.7		1.8		1.9	ns
t_{IOE}		1.7		1.8		1.9	ns
t_{IOCO}		1.0		1.0		1.0	ns
t_{IOCOMB}		0.3		0.2		0.1	ns
t_{IOSU}	1.4		1.6		1.8		ns
t_{IOH}	0.0		0.0		0.0		ns
t_{IOCLR}		1.2		1.2		1.2	ns
t_{IN}		1.5		1.6		1.7	ns
t_{OD1}		1.1		1.4		1.7	ns
t_{OD2}		1.6		1.9		2.2	ns
t_{OD3}		4.6		4.9		5.2	ns
t_{XZ}		1.4		1.6		1.8	ns
t_{ZX1}		1.4		1.6		1.8	ns
t_{ZX2}		1.9		2.1		2.3	ns
t_{ZX3}		4.9		5.1		5.3	ns

Table 43. EPF81188A Interconnect Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
$t_{LABCASC}$		0.3		0.3		0.4	ns
$t_{LABCARRY}$		0.3		0.3		0.4	ns
t_{LOCAL}		0.5		0.6		0.8	ns
t_{ROW}		5.0		5.0		5.0	ns
t_{COL}		3.0		3.0		3.0	ns
t_{DIN_C}		5.0		5.0		5.5	ns
t_{DIN_D}		7.0		7.0		7.5	ns
t_{DIN_IO}		5.0		5.0		5.5	ns

Table 44. EPF81188A LE Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t_{LUT}		2.0		2.5		3.2	ns
t_{CLUT}		0.0		0.0		0.0	ns
t_{RLUT}		0.9		1.1		1.5	ns
t_{GATE}		0.0		0.0		0.0	ns
t_{CASC}		0.6		0.7		0.9	ns
t_{CICO}		0.4		0.5		0.6	ns
t_{CGEN}		0.4		0.5		0.7	ns
t_{CGENR}		0.9		1.1		1.5	ns
t_C		1.6		2.0		2.5	ns
t_{CH}	4.0		4.0		4.0		ns
t_{CL}	4.0		4.0		4.0		ns
t_{CO}		0.4		0.5		0.6	ns
t_{COMB}		0.4		0.5		0.6	ns
t_{SU}	0.8		1.1		1.2		ns
t_H	0.9		1.1		1.5		ns
t_{PRE}		0.6		0.7		0.8	ns
t_{CLR}		0.6		0.7		0.8	ns

Table 45. EPF81188A External Timing Parameters

Symbol	Speed Grade						Unit
	A-2		A-3		A-4		
	Min	Max	Min	Max	Min	Max	
t _{DRR}		16.0		20.0		25.0	ns
t _{ODH}	1.0		1.0		1.0		ns

Operating Modes

The FLEX 8000 architecture uses SRAM elements that require configuration data to be loaded whenever the device powers up and begins operation. The process of physically loading the SRAM programming data into the device is called *configuration*. During initialization, which occurs immediately after configuration, the device resets registers, enables I/O pins, and begins to operate as a logic device. The I/O pins are tri-stated during power-up, and before and during configuration. The configuration and initialization processes together are called *command mode*; normal device operation is called *user mode*.

SRAM elements allow FLEX 8000 devices to be reconfigured in-circuit with new programming data that is loaded into the device. Real-time reconfiguration is performed by forcing the device into command mode with a device pin, loading different programming data, reinitializing the device, and resuming user-mode operation. The entire reconfiguration process requires less than 100 ms and can be used to dynamically reconfigure an entire system. In-field upgrades can be performed by distributing new configuration files.

Configuration Schemes

The configuration data for a FLEX 8000 device can be loaded with one of six configuration schemes, chosen on the basis of the target application. Both active and passive schemes are available. In the active configuration schemes, the FLEX 8000 device functions as the controller, directing the loading operation, controlling external configuration devices, and completing the loading process. The clock source for all active configuration schemes is an oscillator on the FLEX 8000 device that operates between 2 MHz and 6 MHz. In the passive configuration schemes, an external controller guides the FLEX 8000 device. [Table 51](#) shows the data source for each of the six configuration schemes.

Table 51. Data Source for Configuration		
Configuration Scheme	Acronym	Data Source
Active serial	AS	Altera configuration device
Active parallel up	APU	Parallel configuration device
Active parallel down	APD	Parallel configuration device
Passive serial	PS	Serial data path
Passive parallel synchronous	PPS	Intelligent host
Passive parallel asynchronous	PPA	Intelligent host

Table 53. FLEX 8000 160-, 192- & 208-Pin Package Pin-Outs (Part 1 of 2)

Pin Name	160-Pin PQFP EPF8452A	160-Pin PQFP EPF8636A	192-Pin PGA EPF8636A EPF8820A	208-Pin PQFP EPF8636A (1)	208-Pin PQFP EPF8820A (1)	208-Pin PQFP EPF8188A (1)
nSP (2)	120	1	R15	207	207	5
MSEL0 (2)	117	3	T15	4	4	21
MSEL1 (2)	84	38	T3	49	49	33
nSTATUS (2)	37	83	B3	108	108	124
nCONFIG (2)	40	81	C3	103	103	107
DCLK (2)	1	120	C15	158	158	154
CONF_DONE (2)	4	118	B15	153	153	138
nWS	30	89	C5	114	114	118
nRS	71	50	B5	66	116	121
RDCLK	73	48	C11	64	137	137
nCS	29	91	B13	116	145	142
CS	27	93	A16	118	148	144
RDYnBUSY	125	155	A8	201	127	128
CLKUSR	76	44	A10	59	134	134
ADD17	78	43	R5	57	43	46
ADD16	91	33	U3	43	42	45
ADD15	92	31	T5	41	41	44
ADD14	94	29	U4	39	40	39
ADD13	95	27	R6	37	39	37
ADD12	96	24	T6	31	35	36
ADD11	97	23	R7	30	33	31
ADD10	98	22	T7	29	31	30
ADD9	99	21	T8	28	29	29
ADD8	101	20	U9	24	25	26
ADD7	102	19	U10	23	23	25
ADD6	103	18	U11	22	21	24
ADD5	104	17	U12	21	19	18
ADD4	105	13	R12	14	14	17
ADD3	106	11	U14	12	13	16
ADD2	109	9	U15	10	11	10
ADD1	110	7	R13	8	10	9
ADD0	123	157	U16	203	9	8
DATA7	144	137	H17	178	178	177
DATA6	150	132	G17	172	176	175
DATA5	152	129	F17	169	174	172

Notes to tables:

- (1) Perform a complete thermal analysis before committing a design to this device package. See [Application Note 74 \(Evaluating Power for Altera Devices\)](#) for more information.
- (2) This pin is a dedicated pin and is not available as a user I/O pin.
- (3) SDOUT will drive out during configuration. After configuration, it may be used as a user I/O pin. By default, the MAX+PLUS II software will not use SDOUT as a user I/O pin; the user can override the MAX+PLUS II software and use SDOUT as a user I/O pin.
- (4) If the device is not configured to use the JTAG BST circuitry, this pin is available as a user I/O pin.
- (5) JTAG pins are available for EPF8636A devices only. These pins are dedicated user I/O pins.
- (6) If this pin is used as an input in user mode, ensure that it does not toggle before or during configuration.
- (7) TRST is a dedicated input pin for JTAG use. This pin must be grounded if JTAG BST is not used.
- (8) Pin 52 is a V_{CC} pin on EPF8452A devices only.
- (9) The user I/O pin count includes dedicated input pins and all I/O pins.
- (10) Unused dedicated inputs should be tied to ground on the board.
- (11) SDOUT does not exist in the EPF8636GC192 device.
- (12) These pins are no connect (N.C.) pins for EPF8636A devices only. They are user I/O pins in EPF8820A devices.
- (13) EPF8636A devices have 132 user I/O pins; EPF8820A devices have 148 user I/O pins.
- (14) For EPF81500A devices, these pins are dedicated JTAG pins and are not available as user I/O pins. If JTAG BST is not used, TDI, TCK, TMS, and TRST should be tied to GND.

Revision History

The information contained in the *FLEX 8000 Programmable Logic Device Family Data Sheet* version 11.1 supersedes information published in previous versions. The *FLEX 8000 Programmable Logic Device Family Data Sheet* version 11.1 contains the following change: minor textual updates.