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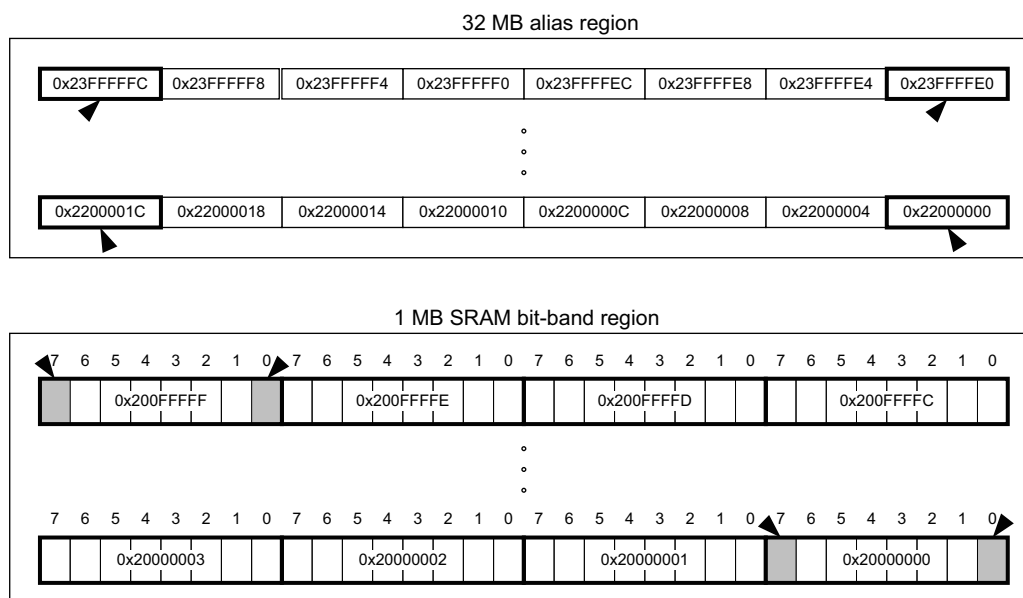
Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M4/M4F
Core Size	32-Bit Dual-Core
Speed	120MHz
Connectivity	EBI/EMI, I ² C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	57
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.6V
Data Converters	A/D 6x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsam4cms4cb-au

- The alias word at 0x22000000 maps to bit[0] of the bit-band byte at 0x20000000: $0x22000000 = 0x20000000 + (0 \times 32) + (0 \times 4)$.
- The alias word at 0x2200001C maps to bit[7] of the bit-band byte at 0x20000000: $0x2200001C = 0x20000000 + (0 \times 32) + (7 \times 4)$.

Figure 12-4. Bit-band Mapping



Directly Accessing an Alias Region

Writing to a word in the alias region updates a single bit in the bit-band region.

Bit[0] of the value written to a word in the alias region determines the value written to the targeted bit in the bit-band region. Writing a value with bit[0] set to 1 writes a 1 to the bit-band bit, and writing a value with bit[0] set to 0 writes a 0 to the bit-band bit.

Bits[31:1] of the alias word have no effect on the bit-band bit. Writing 0x01 has the same effect as writing 0xFF. Writing 0x00 has the same effect as writing 0x0E.

Reading a word in the alias region:

- 0x00000000 indicates that the targeted bit in the bit-band region is set to 0
- 0x00000001 indicates that the targeted bit in the bit-band region is set to 1

Directly Accessing a Bit-band Region

“Behavior of Memory Accesses” describes the behavior of direct byte, halfword, or word accesses to the bit-band regions.

12.4.2.6 Memory Endianness

The processor views memory as a linear collection of bytes numbered in ascending order from zero. For example, bytes 0–3 hold the first stored word, and bytes 4–7 hold the second stored word. “Little-endian Format” describes how words of data are stored in memory.

Little-endian Format

In little-endian format, the processor stores the least significant byte of a word at the lowest-numbered byte, and the most significant byte at the highest-numbered byte. For example:

12.6.11.20 VMSR

Move to floating-point System Register from ARM Core register.

Syntax

`VMSR{cond} FPSCR, Rt`

where:

cond is an optional condition code, see “Conditional Execution”.

Rt is the general-purpose register to be transferred to the FPSCR.

Operation

This instruction moves the value of a general-purpose register to the FPSCR. See “Floating-point Status Control Register” for more information.

Restrictions

The restrictions are:

- *Rt* cannot be PC or SP.

Condition Flags

This instruction updates the FPSCR.

12.6.11.21 VMUL

Floating-point Multiply.

Syntax

`VMUL{cond}.F32 {Sd}, Sn, Sm`

where:

`cond` is an optional condition code, see “Conditional Execution”.

`Sd` is the destination floating-point value.

`Sn, Sm` are the operand floating-point values.

Operation

This instruction:

1. Multiplies two floating-point values.
2. Places the results in the destination register.

Restrictions

There are no restrictions.

Condition Flags

These instructions do not change the flags.

12.9.1.2 CPUID Base Register

Name: SCB_CPUID

Access: Read/Write

31	30	29	28	27	26	25	24
Implementer							
23	22	21	20	19	18	17	16
Variant				Constant			
15	14	13	12	11	10	9	8
PartNo							
7	6	5	4	3	2	1	0
PartNo				Revision			

The SCB_CPUID register contains the processor part number, version, and implementation information.

- **Implementer: Implementer Code**

0x41: ARM.

- **Variant: Variant Number**

It is the r value in the rn timer product revision identifier:

0x0: Revision 0.

- **Constant: Reads as 0xF**

Reads as 0xF.

- **PartNo: Part Number of the Processor**

0xC24 = Cortex-M4.

- **Revision: Revision Number**

It is the p value in the rn timer product revision identifier:

0x0: Patch 0.

12.11.2 Memory Protection Unit (MPU) User Interface

Table 12-41. Memory Protection Unit (MPU) Register Mapping

Offset	Register	Name	Access	Reset
0xE000ED90	MPU Type Register	MPU_TYPE	Read-only	0x00000800
0xE000ED94	MPU Control Register	MPU_CTRL	Read/Write	0x00000000
0xE000ED98	MPU Region Number Register	MPU_RNR	Read/Write	0x00000000
0xE000ED9C	MPU Region Base Address Register	MPU_RBAR	Read/Write	0x00000000
0xE000EDA0	MPU Region Attribute and Size Register	MPU_RASR	Read/Write	0x00000000
0xE000EDA4	MPU Region Base Address Register Alias 1	MPU_RBAR_A1	Read/Write	0x00000000
0xE000EDA8	MPU Region Attribute and Size Register Alias 1	MPU_RASR_A1	Read/Write	0x00000000
0xE000EDAC	MPU Region Base Address Register Alias 2	MPU_RBAR_A2	Read/Write	0x00000000
0xE000EDB0	MPU Region Attribute and Size Register Alias 2	MPU_RASR_A2	Read/Write	0x00000000
0xE000EDB4	MPU Region Base Address Register Alias 3	MPU_RBAR_A3	Read/Write	0x00000000
0xE000EDB8	MPU Region Attribute and Size Register Alias 3	MPU_RASR_A3	Read/Write	0x00000000

15.5 Reset Controller (RSTC) User Interface

Table 15-1. Register Mapping

Offset	Register	Name	Access	Reset
0x00	Control Register	RSTC_CR	Write-only	—
0x04	Status Register	RSTC_SR	Read-only	0x0000_0000 ⁽¹⁾
0x08	Mode Register	RSTC_MR	Read/Write	0x0000 0001
0x0C	Coprocessor Mode Register	RSTC_CPMR	Read/Write	0x0000_0000

Note: 1. This value assumes that a general reset has been performed, subject to change if other types of reset are generated.

- **SMOS: Supply Monitor Output Status**

0 (HIGH): The supply monitor detected VDDIO higher than its threshold at its last measurement.

1 (LOW): The supply monitor detected VDDIO lower than its threshold at its last measurement.

- **OSCSEL: 32 kHz Oscillator Selection Status**

0 (RC): The slow clock, SLCK, is generated by the embedded 32 kHz RC oscillator.

1 (CRYST): The slow clock, SLCK, is generated by the 32 kHz crystal oscillator.

- **LCDS: LCD Status**

0 (DISABLED): LCD controller is disabled.

1 (ENABLED): LCD controller is enabled.

- **FWUPIS: FWUP Input Status**

0 (LOW): FWUP input is tied low.

1 (HIGH): FWUP input is tied high.

- **LPDBCS0: Low Power Debouncer Wakeup Status on WKUP0/TMP0 (cleared on read)**

0 (NO): No tamper detection or wakeup due to the assertion of the WKUP0/TMP0 pin has occurred since the last read of SUPC_SR.

1 (PRESENT): At least one tamper detection and wakeup (if enabled by WKUPEN0) due to the assertion of the WKUP0/TMP0 pin has occurred since the last read of SUPC_SR. The SUPC interrupt line is asserted while LPDBCS0 is 1.

- **LPDBCS1: Low Power Debouncer Wakeup Status on WKUP10/TMP1 (cleared on read)**

0 (NO): No tamper detection or wakeup due to the assertion of the WKUP10 pin has occurred since the last read of SUPC_SR.

1 (PRESENT): At least one tamper detection and wakeup (if enabled by WKUPEN10) due to the assertion of the WKUP10/TMP1 pin has occurred since the last read of SUPC_SR. The SUPC interrupt line is asserted while LPDBCS1 is 1.

- **BUPPORS: Backup Area Power-On Reset Status**

0 (BUPPOR_DISABLED): Backup POR is disabled.

1 (BUPPOR_ENABLED): Backup POR is enabled.

Note: The value written in BUPPOREN is effective when BUPPORENS has the same value in Supply Controller Status Register.

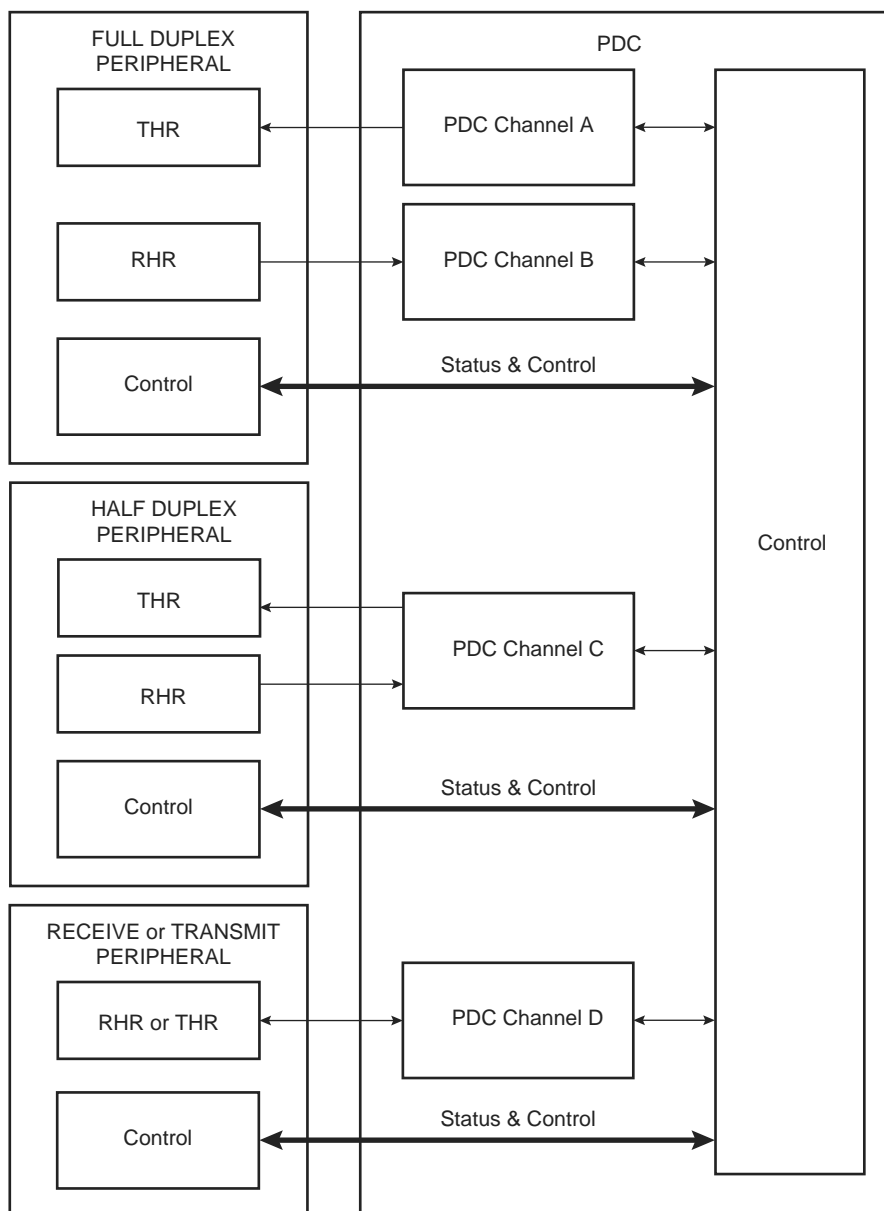
- **WKUPIsx: WKUPx Input Status (cleared on read)**

0 (DIS): The corresponding wakeup input is disabled, or was inactive at the time the debouncer triggered a wakeup event.

1 (EN): The corresponding wakeup input was active at the time the debouncer triggered a wakeup event since the last read of SUPC_SR.

28.3 Block Diagram

Figure 28-1. Block Diagram



32.6.22 PIO Pull-Up Enable Register

Name: PIO_PUER

Address: 0x400E0E64 (PIOA), 0x400E1064 (PIOB), 0x4800C064 (PIOC)

Access: Write-only

31	30	29	28	27	26	25	24
P31	P30	P29	P28	P27	P26	P25	P24
23	22	21	20	19	18	17	16
P23	P22	P21	P20	P19	P18	P17	P16
15	14	13	12	11	10	9	8
P15	P14	P13	P12	P11	P10	P9	P8
7	6	5	4	3	2	1	0
P7	P6	P5	P4	P3	P2	P1	P0

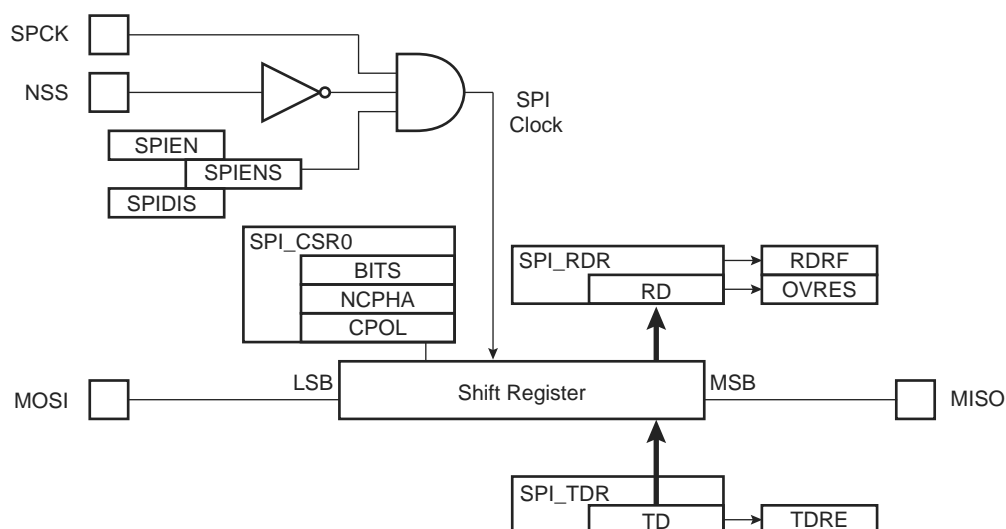
This register can only be written if the WPEN bit is cleared in the PIO Write Protection Mode Register.

- **P0–P31: Pull-Up Enable**

0: No effect.

1: Enables the pull-up resistor on the I/O line.

Figure 33-13. Slave Mode Functional Block Diagram



33.7.5 Register Write Protection

To prevent any single software error from corrupting SPI behavior, certain registers in the address space can be write-protected by setting the WPEN bit in the SPI Write Protection Mode Register (SPI_WPMR).

If a write access to a write-protected register is detected, the WPVS flag in the SPI Write Protection Status Register (SPI_WPSR) is set and the WPVSR field indicates the register in which the write access has been attempted.

The WPVS bit is automatically cleared after reading SPI_WPSR.

The following registers can be write-protected:

- SPI Mode Register
- SPI Chip Select Register

In SPI Slave mode, the transmitter does not require a falling edge of the slave select line (NSS) to initiate a character transmission but only a low level. However, this low level must be present on the slave select line (NSS) at least one t_{bit} before the first serial clock cycle corresponding to the MSB bit.

36.6.7.6 Character Reception

When a character reception is completed, it is transferred to the Receive Holding register (US_RHR) and the RXRDY bit in the Status register (US_CSR) rises. If a character is completed while RXRDY is set, the OVRE (Overrun Error) bit is set. The last character is transferred into US_RHR and overwrites the previous one. The OVRE bit is cleared by writing a 1 to the RSTSTA (Reset Status) bit in the US_CR.

To ensure correct behavior of the receiver in SPI Slave mode, the master device sending the frame must ensure a minimum delay of one t_{bit} between each character transmission. The receiver does not require a falling edge of the slave select line (NSS) to initiate a character reception but only a low level. However, this low level must be present on the slave select line (NSS) at least one t_{bit} before the first serial clock cycle corresponding to the MSB bit.

36.6.7.7 Receiver Timeout

Because the receiver baud rate clock is active only during data transfers in SPI mode, a receiver timeout is impossible in this mode, whatever the time-out value is (field TO) in the US_RTOR.

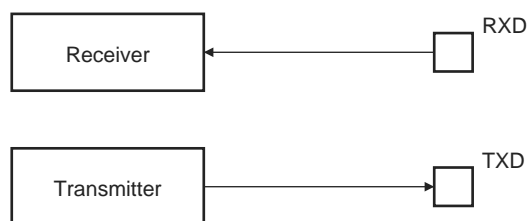
36.6.8 Test Modes

The USART can be programmed to operate in three different test modes. The internal loopback capability allows on-board diagnostics. In Loopback mode, the USART interface pins are disconnected or not and reconfigured for loopback internally or externally.

36.6.8.1 Normal Mode

Normal mode connects the RXD pin on the receiver input and the transmitter output on the TXD pin.

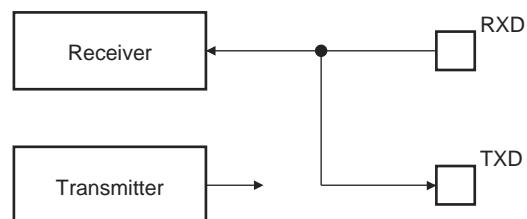
Figure 36-39. Normal Mode Configuration



36.6.8.2 Automatic Echo Mode

Automatic echo mode allows bit-by-bit retransmission. When a bit is received on the RXD pin, it is sent to the TXD pin, as shown in Figure 36-40. Programming the transmitter has no effect on the TXD pin. The RXD pin is still connected to the receiver input, thus the receiver remains active.

Figure 36-40. Automatic Echo Mode Configuration



- **ETRGS: External Trigger Status (cleared on read)**

0: External trigger has not occurred since the last read of the Status Register.

1: External trigger has occurred since the last read of the Status Register.

- **CLKSTA: Clock Enabling Status**

0: Clock is disabled.

1: Clock is enabled.

- **MTIOA: TIOA Mirror**

0: TIOA is low. If TC_CM Rx.WAVE = 0, this means that TIOA pin is low. If TC_CM Rx.WAVE = 1, this means that TIOA is driven low.

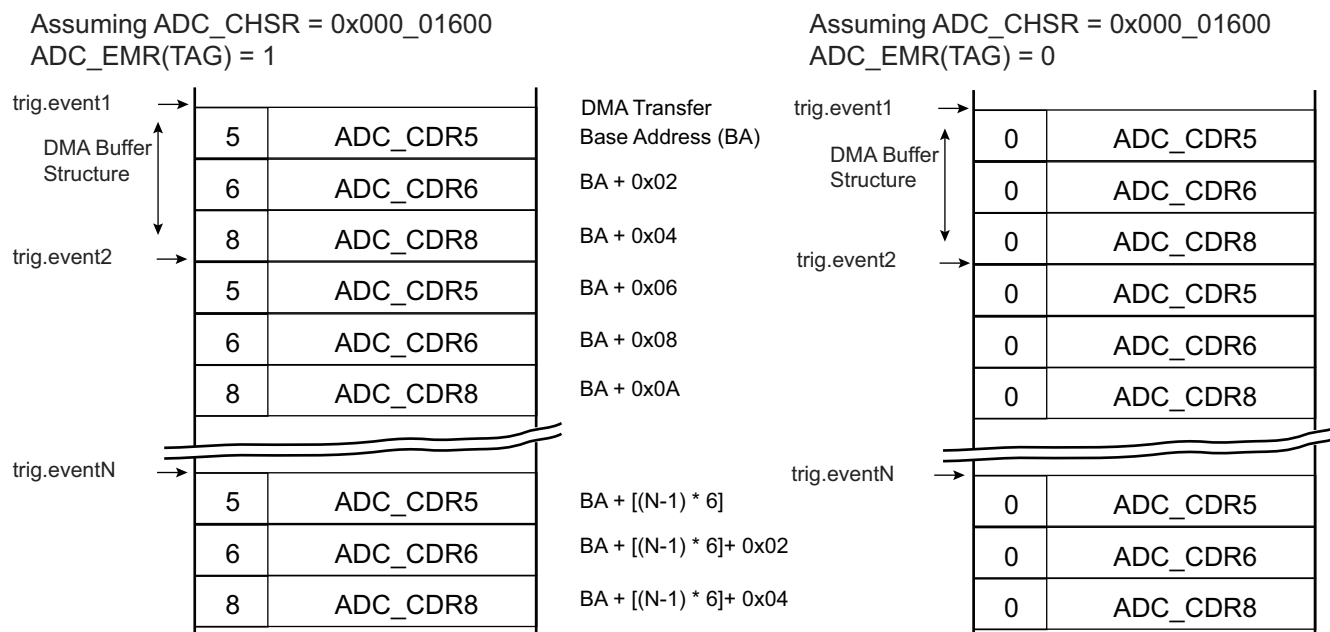
1: TIOA is high. If TC_CM Rx.WAVE = 0, this means that TIOA pin is high. If TC_CM Rx.WAVE = 1, this means that TIOA is driven high.

- **MTIOB: TIOB Mirror**

0: TIOB is low. If TC_CM Rx.WAVE = 0, this means that TIOB pin is low. If TC_CM Rx.WAVE = 1, this means that TIOB is driven low.

1: TIOB is high. If TC_CM Rx.WAVE = 0, this means that TIOB pin is high. If TC_CM Rx.WAVE = 1, this means that TIOB is driven high.

Figure 40-12. Buffer Structure



40.6.13 Register Write Protection

To prevent any single software error from corrupting ADC behavior, certain registers in the address space can be write-protected by setting the WPEN bit in the “ADC Write Protection Mode Register” (ADC_WPMR).

If a write access to a write-protected register is detected, the WPVS flag in the “ADC Write Protection Status Register” (ADC_WPSR) is set and the field WPVSR indicates the register in which the write access has been attempted.

The WPVS bit is automatically cleared after reading the ADC_WPSR.

The following registers can be write-protected:

- “ADC Mode Register”
- “ADC Channel Sequence 1 Register”
- “ADC Channel Enable Register”
- “ADC Channel Disable Register”
- “ADC Temperature Sensor Mode Register”
- “ADC Temperature Compare Window Register”
- “ADC Extended Mode Register”
- “ADC Compare Window Register”
- “ADC Analog Control Register”

40.7.20 ADC Write Protection Status Register

Name: ADC_WPSR

Address: 0x400380E8

Access: Read-only

31	30	29	28	27	26	25	24
–	–	–	–	–	–	–	–
23	22	21	20	19	18	17	16
WPVSR							
15	14	13	12	11	10	9	8
WPVSR							
7	6	5	4	3	2	1	0
–	–	–	–	–	–	–	WPVS

- **WPVS: Write Protection Violation Status**

0: No write protection violation has occurred since the last read of the ADC_WPSR register.

1: A write protection violation has occurred since the last read of the ADC_WPSR register. If this violation is an unauthorized attempt to write a protected register, the associated violation is reported into field WPVSR.

- **WPVSR: Write Protection Violation Source**

When WPVS = 1, WPVSR indicates the register address offset at which a write access has been attempted.

- **URAT: Unspecified Register Access (cleared by writing SWRST in AES_CR)**

Value	Name	Description
0	IDR_WR_PROCESSING	Input Data Register written during the data processing when SMOD = 0x2 mode.
1	ODR_RD_PROCESSING	Output Data Register read during the data processing.
2	MR_WR_PROCESSING	Mode Register written during the data processing.
3	ODR_RD_SUBKGEN	Output Data Register read during the sub-keys generation.
4	MR_WR_SUBKGEN	Mode Register written during the sub-keys generation.
5	WOR_RD_ACCESS	Write-only register read access.

Only the last Unspecified Register Access Type is available through the URAT field.

- **TAGRDY: GCM Tag Ready**

0: GCM Tag is not valid.

1: GCM Tag generation is complete (cleared by reading GCM Tag, starting another processing or when writing a new key).

43.6.5 ICM Interrupt Disable Register

Name: ICM_IDR

Address: 0x40044014

Access: Write-only

31	30	29	28	27	26	25	24
–	–	–	–	–	–	–	URAD
23	22	21	20	19	18	17	16
RSU				REC			
15	14	13	12	11	10	9	8
RWC				RBE			
7	6	5	4	3	2	1	0
RDM				RHC			

- **RHC: Region Hash Completed Interrupt Disable**

0: No effect

1: When RHC[*i*] is set to one, the Region *i* Hash Completed interrupt is disabled.

- **RDM: Region Digest Mismatch Interrupt Disable**

0: No effect

1: When RDM[*i*] is set to one, the Region *i* Digest Mismatch interrupt is disabled.

- **RBE: Region Bus Error Interrupt Disable**

0: No effect

1: When RBE[*i*] is set to one, the Region *i* Bus Error interrupt is disabled.

- **RWC: Region Wrap Condition Detected Interrupt Disable**

0: No effect

1: When RWC[*i*] is set to one, the Region *i* Wrap Condition interrupt is disabled.

- **REC: Region End bit Condition detected Interrupt Disable**

0: No effect

1: When REC[*i*] is set to one, the region *i* End bit Condition interrupt is disabled.

- **RSU: Region Status Updated Interrupt Disable**

0: No effect

1: When RSU[*i*] is set to one, the region *i* Status Updated interrupt is disabled.

- **URAD: Undefined Register Access Detection Interrupt Disable**

0: No effect

1: Undefined Register Access Detection interrupt is disabled.

Figure 46-8. SMC Timings - NCS Controlled Read and Write

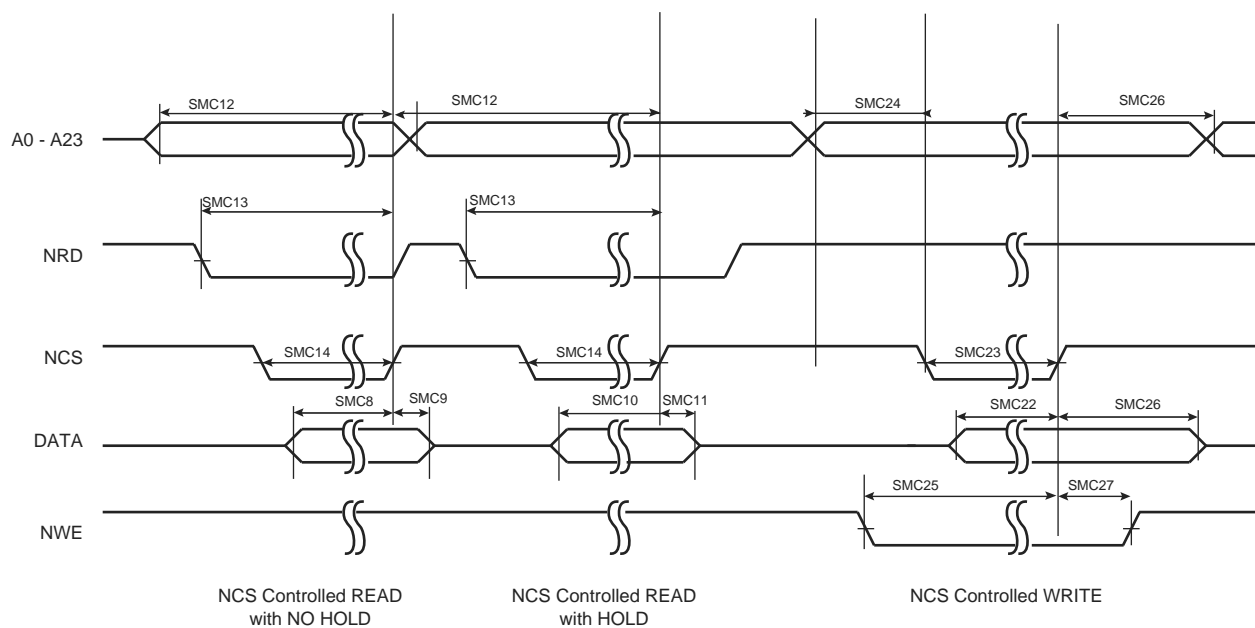
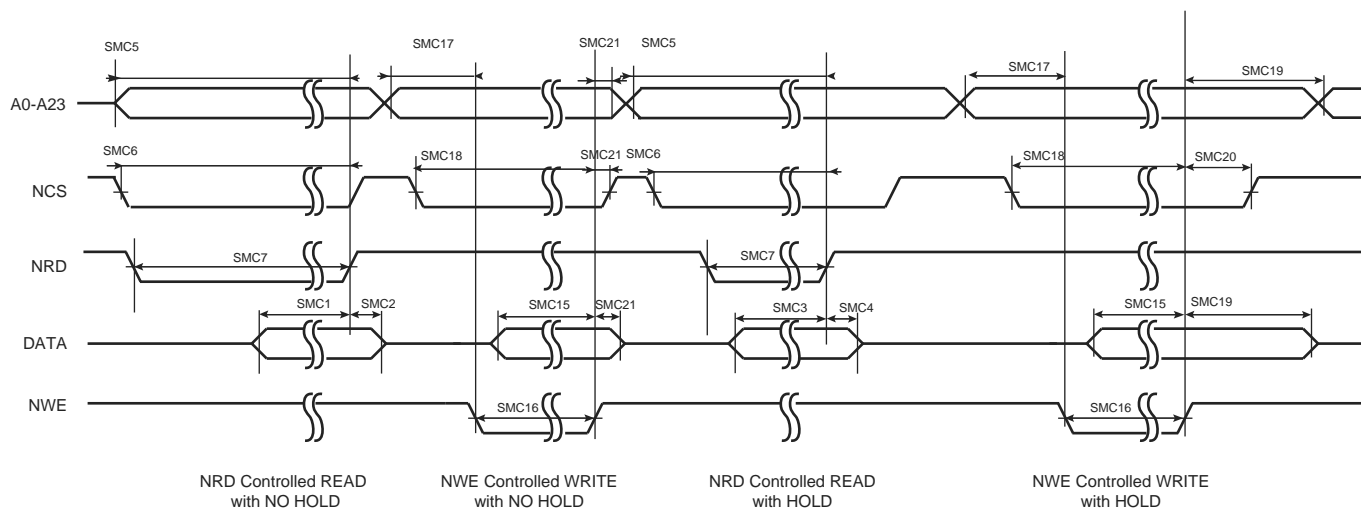


Figure 46-9. SMC Timings - NRD Controlled Read and NWE Controlled Write



Example: Calculated track time is lower than actual ADC clock period

- Assuming: $f_{CK_ADC} = 1 \text{ MHz}$ ($t_{CK_ADC} = 1 \mu\text{s}$), $R_{SOURCE} = 100\Omega$ and $V_{DDIN} = 3.3\text{V}$
- The minimum required track time is: $t_{TRACK} = 0.12 \times 100 + 500 = 512 \text{ ns}$
- t_{TRACK} being less than t_{CK_ADC} , TRACKTIM is set to 0. Actual track time is $t_{CK_ADC} = 1 \mu\text{s}$
- The calculated sampling rate is: $f_s = 1 \text{ MHz} / 24 = 41.7 \text{ kHz}$
- The maximum allowable source resistance is: $R_{SOURCE_MAX} = (1000 - 500) / 0.12 = 4.1 \text{ k}\Omega$

Example: Calculated track time is greater than actual ADC clock period

- Assuming: $f_{CK_ADC} = 16 \text{ MHz}$ ($t_{CK_ADC} = 62.5 \text{ ns}$), $R_{SOURCE} = 600\Omega$ and $V_{DDIN} = 2.8\text{V}$
- The minimum required track time is: $t_{TRACK} = 0.12 \times 600 + 1000 = 1072 \text{ ns}$
- TRACKTIM = floor ($1072 / 62.5$) = 17. Actual track time is: $(17 + 1) \times t_{CK_ADC} = 1.125 \mu\text{s}$
- The calculated sampling rate is: $f_s = 16 \text{ MHz} / (24 + 17) = 390.2 \text{ kHz}$
- The maximum allowable source resistance is: $R_{SOURCE_MAX} = (1125 - 1000) / 0.12 = 1.04 \text{ k}\Omega$

46.5.18 Programmable Voltage Reference Characteristics

SAM4CM embeds a programmable voltage reference designed to drive the 10-bit ADC ADVREF input. Table 46-43 shows the electrical characteristics of this internal voltage reference. If necessary, this voltage reference can be bypassed with some level of configurability: the user can either choose to feed the ADVREF input with an external voltage source or with the VDDIO internal power rail. Refer to programming details in Section 40.7.18 “ADC Analog Control Register”.

Table 46-43. Programmable Voltage Reference Characteristics

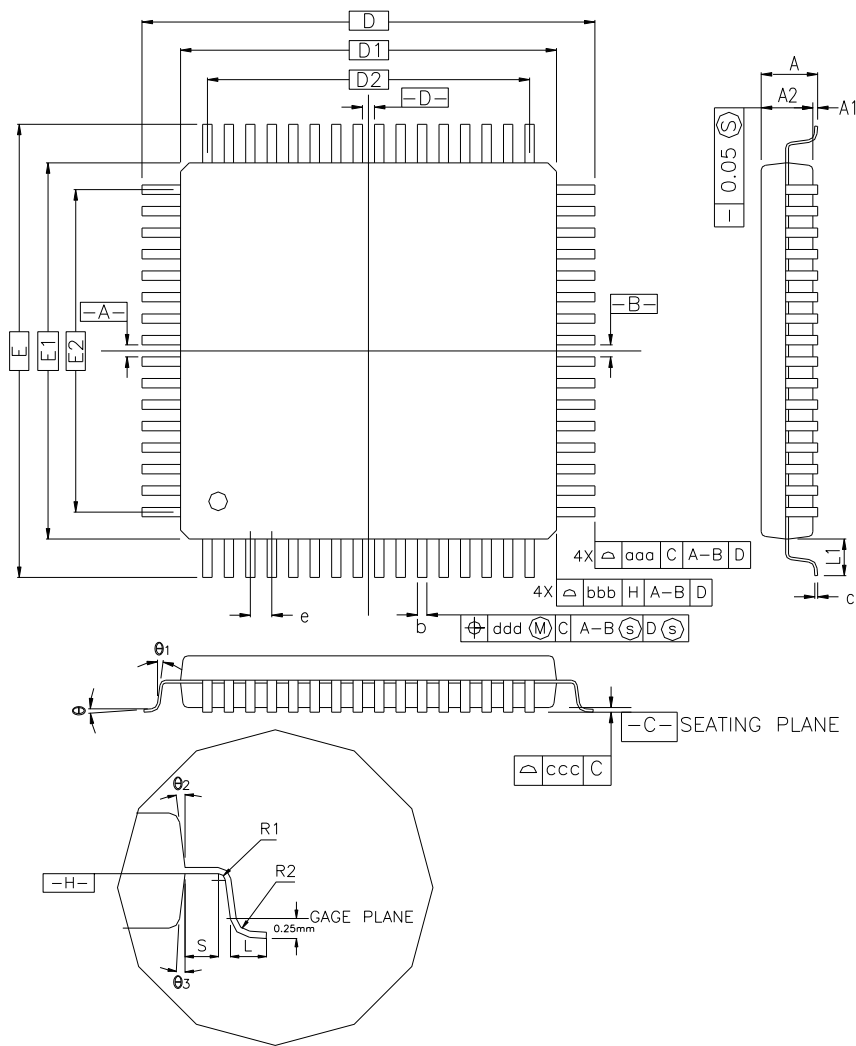
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDIN}	Voltage reference supply range	—	2	—	3.6	V
V_{ADVREF}	Programmable output range	Refer to Table 46-44. $V_{DDIN} > V_{ADVREF} + 100\text{mV}$	1.6	—	3.4	V
ACC	Reference voltage accuracy	With respect to the programmed value. $V_{DDIN} = 3.3\text{V}$; $T_J = 25^\circ\text{C}$	-3	—	3	%
T_C	Temperature coefficient	Box method ⁽¹⁾	—	—	250	ppm/ $^\circ\text{C}$
t_{ON}	Start-up time	$V_{DDIN} = 2.4\text{V}$ $V_{DDIN} = 3\text{V}$ $V_{DDIN} = 3.6\text{V}$	—	—	100 70 40	μs
Z_{LOAD}	Load impedance	Resistive	4	—	—	$\text{k}\Omega$
		Capacitive	0.1	—	1	μF
I_{VDDIN}	Current consumption on VDDIN ⁽²⁾	ADC is OFF	—	20	30	μA

- Notes: 1. $TC = (\max(V_{ADVREF}) - \min(V_{ADVREF})) / ((T_{MAX} - T_{MIN}) * V_{ADVREF}(25^\circ\text{C}))$.
2. Does not include the current consumed by the ADC ADVREF input if ADC is ON

47. Mechanical Characteristics

47.1 100-lead LQFP Package

Figure 47-1. 100-lead LQFP Package Drawing



COTROL DIMENSIONS ARE IN MILLIMETERS.

SYMBOL	MILLIMETER			INCH		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	—	—	1.60	—	—	0.063
A1	0.05	—	0.15	0.002	—	0.006
A2	1.35	1.40	1.45	0.053	0.055	0.057
D	16.00 BSC.			0.630 BSC.		
D1	14.00 BSC.			0.551 BSC.		
E	16.00 BSC.			0.630 BSC.		
E1	14.00 BSC.			0.551 BSC.		
R2	0.08	—	0.20	0.003	—	0.008
R1	0.08	—	—	0.003	—	—
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	—	—	0°	—	—
θ2	11°	12°	13°	11°	12°	13°
θ3	11°	12°	13°	11°	12°	13°
c	0.09	—	0.20	0.004	—	0.008
L	0.45	0.60	0.75	0.018	0.024	0.030
L1	1.00 REF			0.039 REF		
S	0.20	—	—	0.008	—	—
b	0.17	0.20	0.27	0.007	0.008	0.011
e	0.50 BSC.			0.020 BSC.		
D2	12.00			0.472		
E2	12.00			0.472		
TOLERANCES OF FORM AND POSITION						
aaa	0.20			0.008		
bbb	0.20			0.008		
ccc	0.08			0.003		
ddd	0.08			0.003		

Table 47-1. Device and LQFP Package Maximum Weight

SAM4CM	800	mg
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Table 47-2. LQFP Package Reference

JEDEC Drawing Reference	MS-026
JESD97 Classification	e3

Table 47-3. LQFP Package Characteristics

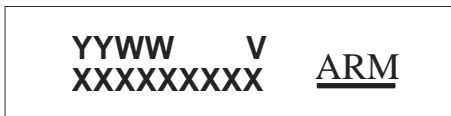
Moisture Sensitivity Level	3
----------------------------	---

This package respects the recommendations of the NEMI User Group.

48. Marking

All devices are marked with the Atmel logo and the ordering code.

Additional marking is as follows:



where

- “YY”: Manufactory year
- “WW”: Manufactory week
- “V”: Revision
- “XXXXXXXXXX”: Lot number