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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

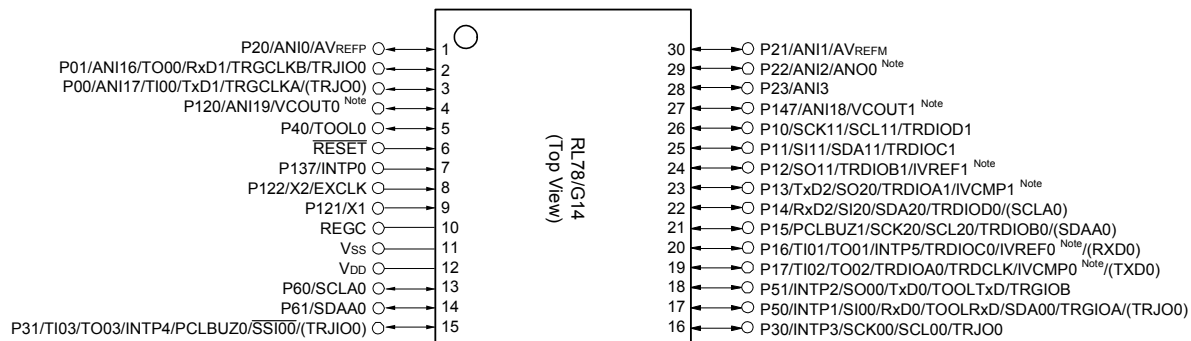
#### Details

Product Status	Obsolete
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I <sup>2</sup> C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	22
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	5.5K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 8x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	32-WFQFN Exposed Pad
Supplier Device Package	32-HWQFN (5x5)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f104begna-u0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f104begna-u0</a>

## 1.3 Pin Configuration (Top View)

### 1.3.1 30-pin products

- 30-pin plastic LSSOP (7.62 mm (300), 0.65 mm pitch)



**Note** Mounted on the 96 KB or more code flash memory products.

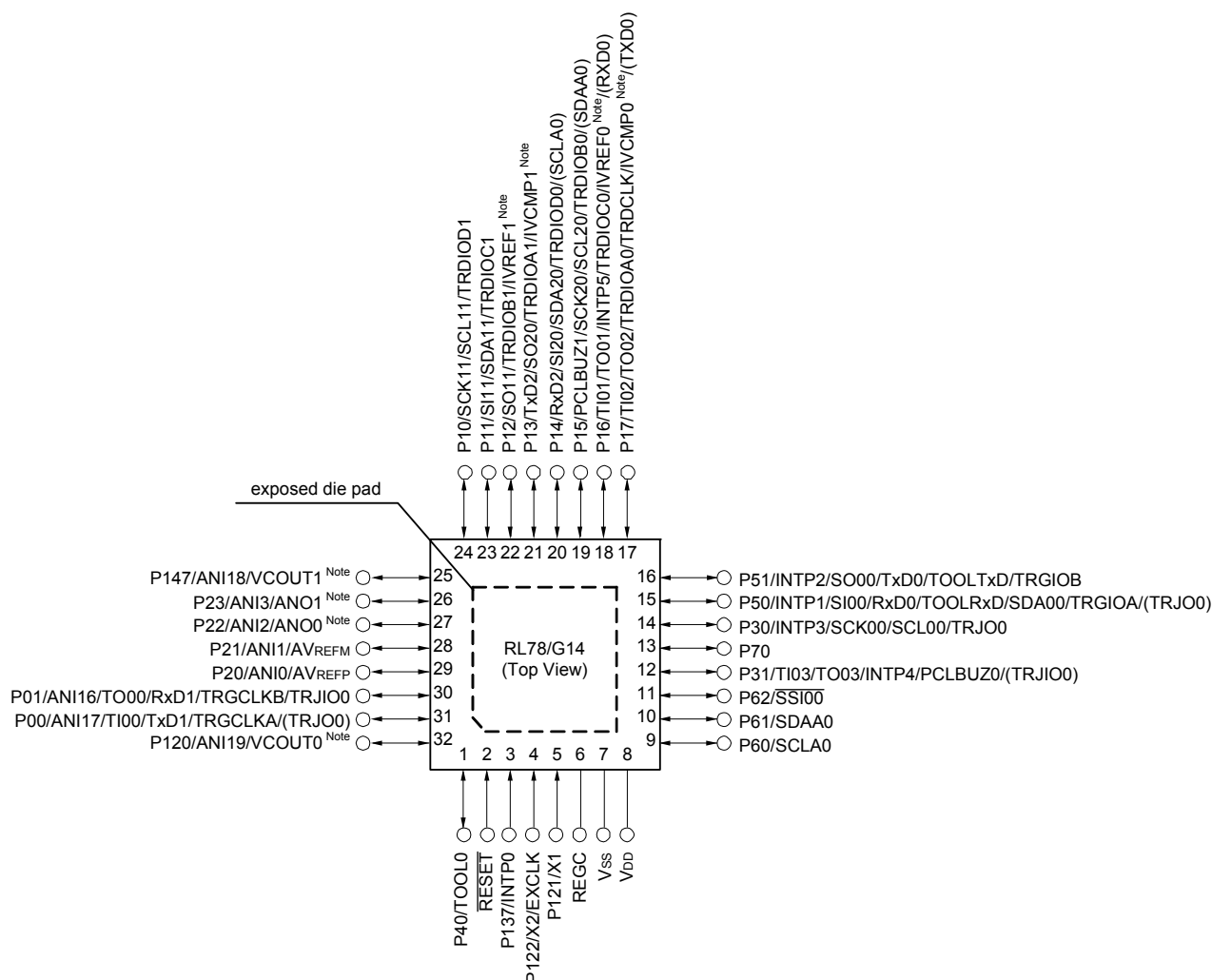
**Caution** Connect the REGC pin to Vss pin via a capacitor (0.47 to 1  $\mu$ F).

**Remark 1.** For pin identification, see 1.4 Pin Identification.

**Remark 2.** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register 0, 1 (PIOR0, 1).

### 1.3.2 32-pin products

- 32-pin plastic HWQFN (5 × 5 mm, 0.5 mm pitch)



**Note** Mounted on the 96 KB or more code flash memory products.

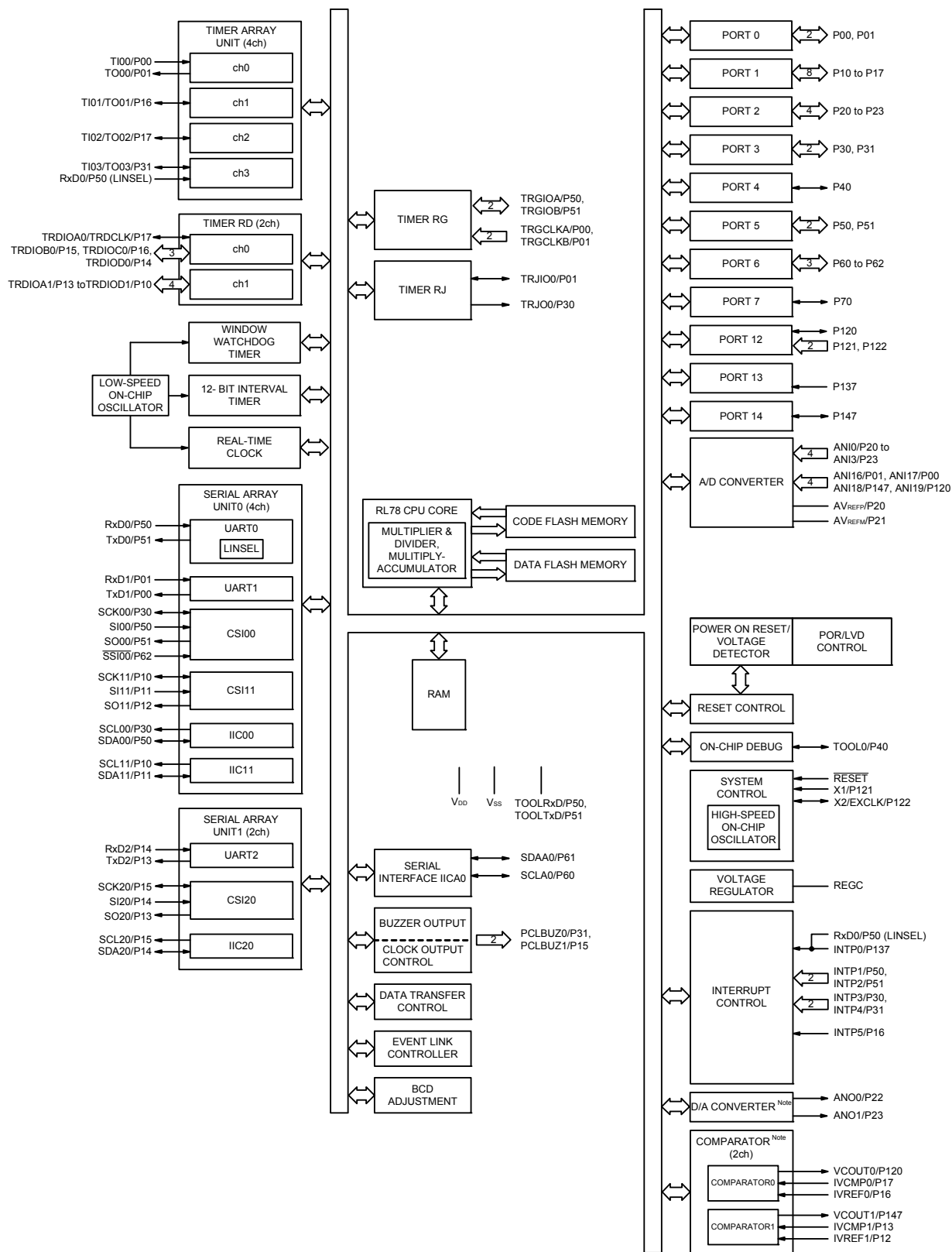
**Caution** Connect the REGC pin to Vss pin via a capacitor (0.47 to 1  $\mu$ F).

**Remark 1.** For pin identification, see 1.4 Pin Identification.

**Remark 2.** Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register 0, 1 (PIOR0, 1).

**Remark 3.** It is recommended to connect an exposed die pad to Vss.

## 1.5.2 32-pin products



**Note** Mounted on the 96 KB or more code flash memory products.

(2/2)

Item		48-pin	64-pin
		R5F104Gx (x = K, L)	R5F104Lx (x = K, L)
Clock output/buzzer output		2	2
		• 2.44 kHz, 4.88 kHz, 9.76 kHz, 1.25 MHz, 2.5 MHz, 5 MHz, 10 MHz (Main system clock: f <sub>MAIN</sub> = 20 MHz operation) • 256 Hz, 512 Hz, 1.024 kHz, 2.048 kHz, 4.096 kHz, 8.192 kHz, 16.384 kHz, 32.768 kHz (Subsystem clock: f <sub>SUB</sub> = 32.768 kHz operation)	
8/10-bit resolution A/D converter		10 channels	12 channels
D/A converter		2 channels	
Comparator		2 channels	
Serial interface		[48-pin products] • CSI: 2 channels/UART (UART supporting LIN-bus): 1 channel/simplified I <sup>2</sup> C: 2 channels • CSI: 1 channel/UART: 1 channel/simplified I <sup>2</sup> C: 1 channel • CSI: 2 channels/UART: 1 channel/simplified I <sup>2</sup> C: 2 channels [64-pin products] • CSI: 2 channels/UART (UART supporting LIN-bus): 1 channel/simplified I <sup>2</sup> C: 2 channels • CSI: 2 channels/UART: 1 channel/simplified I <sup>2</sup> C: 2 channels • CSI: 2 channels/UART: 1 channel/simplified I <sup>2</sup> C: 2 channels	
		I <sup>2</sup> C bus	1 channel
Data transfer controller (DTC)		32 sources	33 sources
Event link controller (ELC)		Event input: 22 Event trigger output: 9	
Vectored interrupt sources	Internal	24	24
	External	10	13
Key interrupt		6	8
Reset		• Reset by $\overline{\text{RESET}}$ pin • Internal reset by watchdog timer • Internal reset by power-on-reset • Internal reset by voltage detector • Internal reset by illegal instruction execution <sup>Note</sup> • Internal reset by RAM parity error • Internal reset by illegal-memory access	
Power-on-reset circuit		• Power-on-reset: 1.51 ±0.04 V (T <sub>A</sub> = −40 to +85°C) 1.51 ±0.06 V (T <sub>A</sub> = −40 to +105°C) • Power-down-reset: 1.50 ±0.04 V (T <sub>A</sub> = −40 to +85°C) 1.50 ±0.06 V (T <sub>A</sub> = −40 to +105°C)	
Voltage detector		1.63 V to 4.06 V (14 stages)	
On-chip debug function		Provided	
Power supply voltage		V <sub>DD</sub> = 1.6 to 5.5 V (T <sub>A</sub> = −40 to +85°C) V <sub>DD</sub> = 2.4 to 5.5 V (T <sub>A</sub> = −40 to +105°C)	
Operating ambient temperature		T <sub>A</sub> = −40 to +85°C (A: Consumer applications, D: Industrial applications), T <sub>A</sub> = −40 to +105°C (G: Industrial applications)	

**Note** The illegal instruction is generated when instruction code FFH is executed.  
 Reset by the illegal instruction execution is not issued by emulation with the in-circuit emulator or on-chip debug emulator.

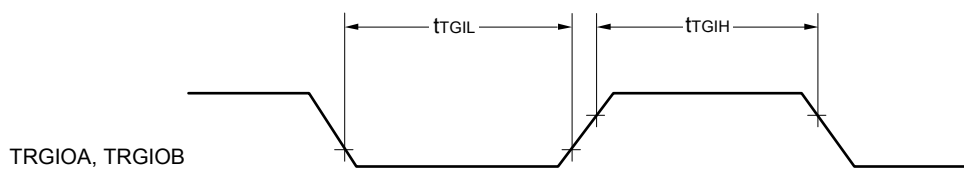
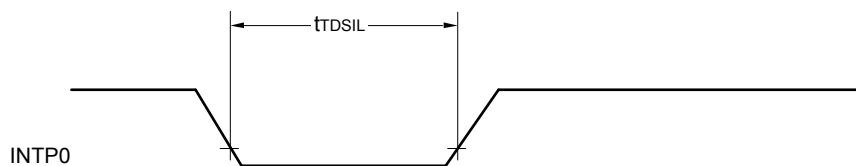
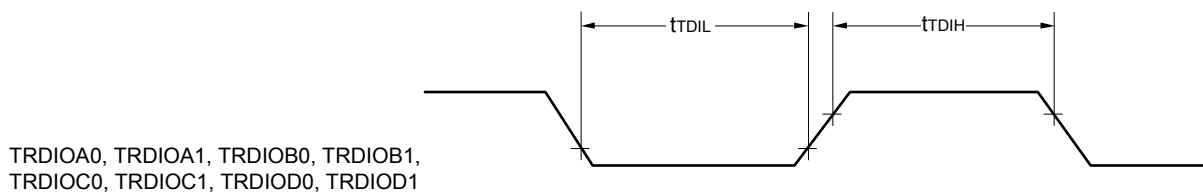
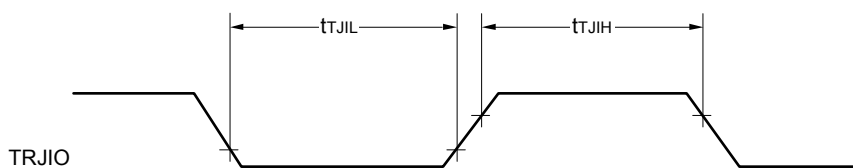
(TA = -40 to +85°C, 1.6 V ≤ EVDD0 = EVDD1 ≤ VDD ≤ 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

(3/5)

Items	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Input voltage, high	VIH1	P00 to P06, P10 to P17, P30, P31, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P100 to P102, P110, P111, P120, P140 to P147	0.8 EVDD0		EVDD0	V
	VIH2	P01, P03, P04, P10, P14 to P17, P30, P43, P44, P50, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EVDD0 ≤ 5.5 V	2.2	EVDD0	V
			TTL input buffer 3.3 V ≤ EVDD0 < 4.0 V	2.0	EVDD0	V
			TTL input buffer 1.6 V ≤ EVDD0 < 3.3 V	1.5	EVDD0	V
	VIH3	P20 to P27, P150 to P156	0.7 VDD		VDD	V
	VIH4	P60 to P63	0.7 EVDD0		6.0	V
	VIH5	P121 to P124, P137, EXCLK, EXCLKS, $\overline{\text{RESET}}$	0.8 VDD		VDD	V
Input voltage, low	VIL1	P00 to P06, P10 to P17, P30, P31, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P100 to P102, P110, P111, P120, P140 to P147	0		0.2 EVDD0	V
	VIL2	P01, P03, P04, P10, P14 to P17, P30, P43, P44, P50, P53 to P55, P80, P81, P142, P143	TTL input buffer 4.0 V ≤ EVDD0 ≤ 5.5 V	0	0.8	V
			TTL input buffer 3.3 V ≤ EVDD0 < 4.0 V	0	0.5	V
			TTL input buffer 1.6 V ≤ EVDD0 < 3.3 V	0	0.32	V
	VIL3	P20 to P27, P150 to P156	0		0.3 VDD	V
	VIL4	P60 to P63	0		0.3 EVDD0	V
	VIL5	P121 to P124, P137, EXCLK, EXCLKS, $\overline{\text{RESET}}$	0		0.2 VDD	V

**Caution** The maximum value of VIH of pins P00, P02 to P04, P10, P11, P13 to P15, P17, P30, P43 to P45, P50 to P55, P71, P74, P80 to P82, and P142 to P144 is EVDD0, even in the N-ch open-drain mode.

**Remark** Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.



**Note 4.** This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to **Note 3** above to calculate the maximum transfer rate under conditions of the customer.

**Note 5.** Use it with  $EV_{DD0} \geq V_b$ .

**Note 6.** The smaller maximum transfer rate derived by using  $f_{mck}/6$  or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when  $1.8 \text{ V} \leq EV_{DD0} < 3.3 \text{ V}$  and  $1.6 \text{ V} \leq V_b \leq 2.0 \text{ V}$

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

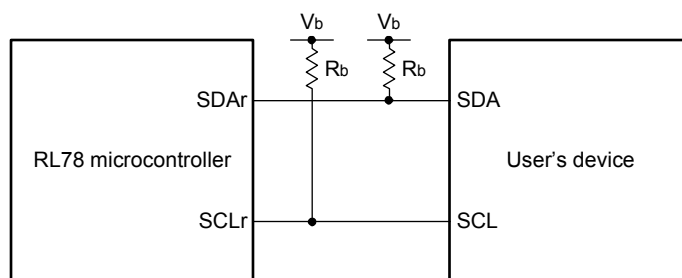
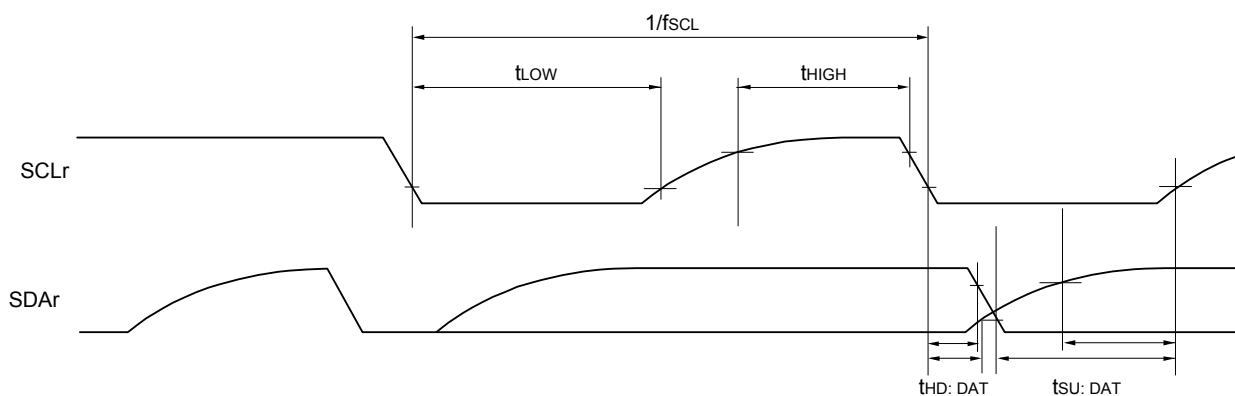
\* This value is the theoretical value of the relative difference between the transmission and reception sides

**Note 7.** This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to **Note 6** above to calculate the maximum transfer rate under conditions of the customer.

**Caution** Select the TTL input buffer for the RxDq pin and the N-ch open drain output ( $V_{DD}$  tolerance (for the 30- to 52-pin products)/ $EV_{DD}$  tolerance (for the 64- to 100-pin products)) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For  $V_{IH}$  and  $V_{IL}$ , see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)



**Simplified I<sup>2</sup>C mode connection diagram (during communication at different potential)****Simplified I<sup>2</sup>C mode serial transfer timing (during communication at different potential)**

**Remark 1.**  $R_b[\Omega]$ : Communication line (SDAr, SCLr) pull-up resistance,  $C_b[F]$ : Communication line (SDAr, SCLr) load capacitance,  $V_b[V]$ : Communication line voltage

**Remark 2.**  $r$ : IIC number ( $r = 00, 01, 10, 11, 20, 30, 31$ ),  $g$ : PIM, POM number ( $g = 0, 1, 3$  to  $5, 14$ )

**Remark 3.**  $f_{MCK}$ : Serial array unit operation clock frequency  
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn).  $m$ : Unit number ( $m = 0, 1$ ),  
 $n$ : Channel number ( $n = 0, 2$ ),  $mn = 00, 01, 02, 10, 12, 13$ )

- Note 1.** Total current flowing into V<sub>DD</sub> and EV<sub>DD0</sub>, including the input leakage current flowing when the level of the input pin is fixed to V<sub>DD</sub>, EV<sub>DD0</sub> or V<sub>SS</sub>, EV<sub>SS0</sub>. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
- Note 2.** When high-speed on-chip oscillator and subsystem clock are stopped.
- Note 3.** When high-speed system clock and subsystem clock are stopped.
- Note 4.** When high-speed on-chip oscillator and high-speed system clock are stopped. When AMPHS1 = 1 (Ultra-low power consumption oscillation). However, not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.
- Note 5.** Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.  
 HS (high-speed main) mode:  $2.7\text{ V} \leq V_{DD} \leq 5.5\text{ V}@1\text{ MHz to }32\text{ MHz}$   
 $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}@1\text{ MHz to }16\text{ MHz}$

**Remark 1.** f<sub>MX</sub>: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)

**Remark 2.** f<sub>HOCO</sub>: High-speed on-chip oscillator clock frequency (64 MHz max.)

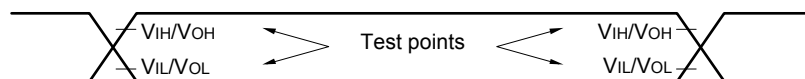
**Remark 3.** f<sub>IH</sub>: High-speed on-chip oscillator clock frequency (32 MHz max.)

**Remark 4.** f<sub>SUB</sub>: Subsystem clock frequency (XT1 clock oscillation frequency)

**Remark 5.** Except subsystem clock operation, temperature condition of the TYP. value is TA = 25°C

### 3.5 Peripheral Functions Characteristics

#### AC Timing Test Points



#### 3.5.1 Serial array unit

##### (1) During communication at same potential (UART mode)

( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq \text{EVDD0} = \text{EVDD1} \leq 5.5\text{ V}$ ,  $\text{Vss} = \text{EVss0} = \text{EVss1} = 0\text{ V}$ )

Parameter	Symbol	Conditions	HS (high-speed main) Mode		Unit
			MIN.	MAX.	
Transfer rate Note 1		$2.4\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$		$f_{\text{MCK}}/12$ Note 2	bps
		Theoretical value of the maximum transfer rate $f_{\text{MCK}} = f_{\text{CLK}}$ Note 3		2.6	Mbps

**Note 1.** Transfer rate in the SNOOZE mode is 4800 bps only.

However, the SNOOZE mode cannot be used when  $\text{FRQSEL4} = 1$ .

**Note 2.** The following conditions are required for low voltage interface when  $\text{EVDD0} < V_{\text{DD}}$ .

$2.4\text{ V} \leq \text{EVDD0} < 2.7\text{ V}$ : MAX. 1.3 Mbps

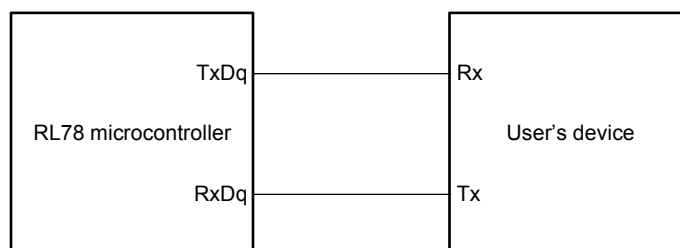
**Note 3.** The maximum operating frequencies of the CPU/peripheral hardware clock ( $f_{\text{CLK}}$ ) are:

HS (high-speed main) mode: 32 MHz ( $2.7\text{ V} \leq V_{\text{DD}} \leq 5.5\text{ V}$ )

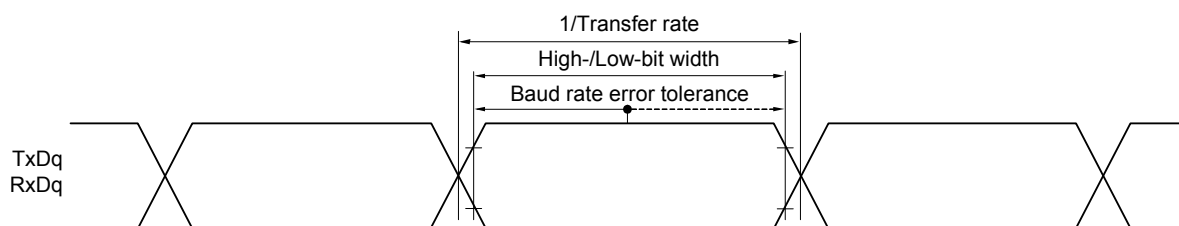
16 MHz ( $2.4\text{ V} \leq V_{\text{DD}} \leq 5.5\text{ V}$ )

**Caution** Select the normal input buffer for the RxDq pin and the normal output mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg).

#### UART mode connection diagram (during communication at same potential)



#### UART mode bit width (during communication at same potential) (reference)



**Remark 1.** q: UART number (q = 0 to 3), g: PIM and POM number (g = 0, 1, 5, 14)

**Remark 2.**  $f_{\text{MCK}}$ : Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number,

n: Channel number (mn = 00 to 03, 10 to 13))

**Note 5.** The smaller maximum transfer rate derived by using  $f_{MCK}/12$  or the following expression is the valid maximum transfer rate.

Expression for calculating the transfer rate when  $2.4\text{ V} \leq E_{VDD0} < 3.3\text{ V}$  and  $1.6\text{ V} \leq V_b \leq 2.0\text{ V}$

$$\text{Maximum transfer rate} = \frac{1}{\{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\} \times 3} \text{ [bps]}$$

$$\text{Baud rate error (theoretical value)} = \frac{\frac{1}{\text{Transfer rate} \times 2} - \{-C_b \times R_b \times \ln(1 - \frac{1.5}{V_b})\}}{(\frac{1}{\text{Transfer rate}}) \times \text{Number of transferred bits}} \times 100 \text{ [%]}$$

\* This value is the theoretical value of the relative difference between the transmission and reception sides

**Note 6.** This value as an example is calculated when the conditions described in the "Conditions" column are met. Refer to **Note 5** above to calculate the maximum transfer rate under conditions of the customer.

**Caution** Select the TTL input buffer for the RxDq pin and the N-ch open drain output ( $V_{DD}$  tolerance (for the 30- to 52-pin products)/ $E_{VDD}$  tolerance (for the 64- to 100-pin products)) mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg). For  $V_{IH}$  and  $V_{IL}$ , see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)

**(6) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (master mode, SCKp... internal clock output)****( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq \text{EVDD0} = \text{EVDD1} \leq \text{VDD} \leq 5.5\text{ V}$ ,  $\text{VSS} = \text{EVSS0} = \text{EVSS1} = 0\text{ V}$ )****(2/3)**

Parameter	Symbol	Conditions	HS (high-speed main) mode		Unit
			MIN.	MAX.	
Slp setup time (to SCKp $\uparrow$ ) <sup>Note</sup>	tsik1	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 1.4\text{ k}\Omega$	162		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	354		ns
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$	958		ns
Slp hold time (from SCKp $\uparrow$ ) <sup>Note</sup>	tkS11	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 1.4\text{ k}\Omega$	38		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	38		ns
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$	38		ns
Delay time from SCKp $\downarrow$ to SOp output <sup>Note</sup>	tkSO1	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 1.4\text{ k}\Omega$		200	ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$		390	ns
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 30\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$		966	ns

**Note** When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.

**Caution** Select the TTL input buffer for the Slp pin and the N-ch open drain output ( $\text{VDD}$  tolerance (for the 30- to 52-pin products)/ $\text{EVDD}$  tolerance (for the 64- to 100-pin products)) mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For  $\text{V}_{IH}$  and  $\text{V}_{IL}$ , see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the page after the next page.)

**(8) Communication at different potential (1.8 V, 2.5 V, 3 V) (simplified I<sup>2</sup>C mode)****( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq \text{EVDD0} = \text{EVDD1} \leq \text{VDD} \leq 5.5\text{ V}$ ,  $\text{VSS} = \text{EVSS0} = \text{EVSS1} = 0\text{ V}$ )****(1/2)**

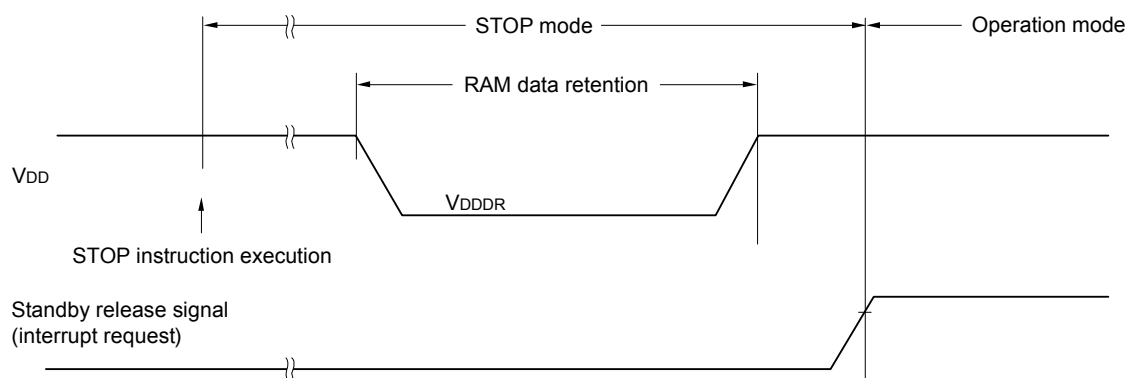
Parameter	Symbol	Conditions	HS (high-speed main) mode		Unit
			MIN.	MAX.	
SCLr clock frequency	f <sub>SCL</sub>	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$		400 Note 1	kHz
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$		400 Note 1	kHz
		$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.8\text{ k}\Omega$		100 Note 1	kHz
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$		100 Note 1	kHz
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$		100 Note 1	kHz
Hold time when SCLr = "L"	t <sub>LOW</sub>	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	1200		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	1200		ns
		$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.8\text{ k}\Omega$	4600		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	4600		ns
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$	4650		ns
Hold time when SCLr = "H"	t <sub>HIGH</sub>	$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	620		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 50\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	500		ns
		$4.0\text{ V} \leq \text{EVDD0} \leq 5.5\text{ V}$ , $2.7\text{ V} \leq \text{Vb} \leq 4.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.8\text{ k}\Omega$	2700		ns
		$2.7\text{ V} \leq \text{EVDD0} < 4.0\text{ V}$ , $2.3\text{ V} \leq \text{Vb} \leq 2.7\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 2.7\text{ k}\Omega$	2400		ns
		$2.4\text{ V} \leq \text{EVDD0} < 3.3\text{ V}$ , $1.6\text{ V} \leq \text{Vb} \leq 2.0\text{ V}$ , $\text{Cb} = 100\text{ pF}$ , $\text{Rb} = 5.5\text{ k}\Omega$	1830		ns

### 3.7 RAM Data Retention Characteristics

( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $V_{SS} = 0\text{V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Data retention supply voltage	$V_{DDDR}$		1.44 Note		5.5	V

**Note** The value depends on the POR detection voltage. When the voltage drops, the RAM data is retained before a POR reset is effected, but RAM data is not retained when a POR reset is effected.



### 3.8 Flash Memory Programming Characteristics

( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$ ,  $V_{SS} = 0\text{ V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
System clock frequency	fCLK	$2.4\text{ V} \leq V_{DD} \leq 5.5\text{ V}$	1		32	MHz
Number of code flash rewrites Notes 1, 2, 3	C <sub>erwr</sub>	Retained for 20 years $T_A = 85^\circ\text{C}$ Note 4	1,000			Times
Number of data flash rewrites Notes 1, 2, 3		Retained for 1 year $T_A = 25^\circ\text{C}$		1,000,000		
		Retained for 5 years $T_A = 85^\circ\text{C}$ Note 4	100,000			
		Retained for 20 years $T_A = 85^\circ\text{C}$ Note 4	10,000			

**Note 1.** 1 erase + 1 write after the erase is regarded as 1 rewrite. The retaining years are until next rewrite after the rewrite.

**Note 2.** When using flash memory programmer and Renesas Electronics self-programming library

**Note 3.** These are the characteristics of the flash memory and the results obtained from reliability testing by Renesas Electronics Corporation.

**Note 4.** This temperature is the average value at which data are retained.

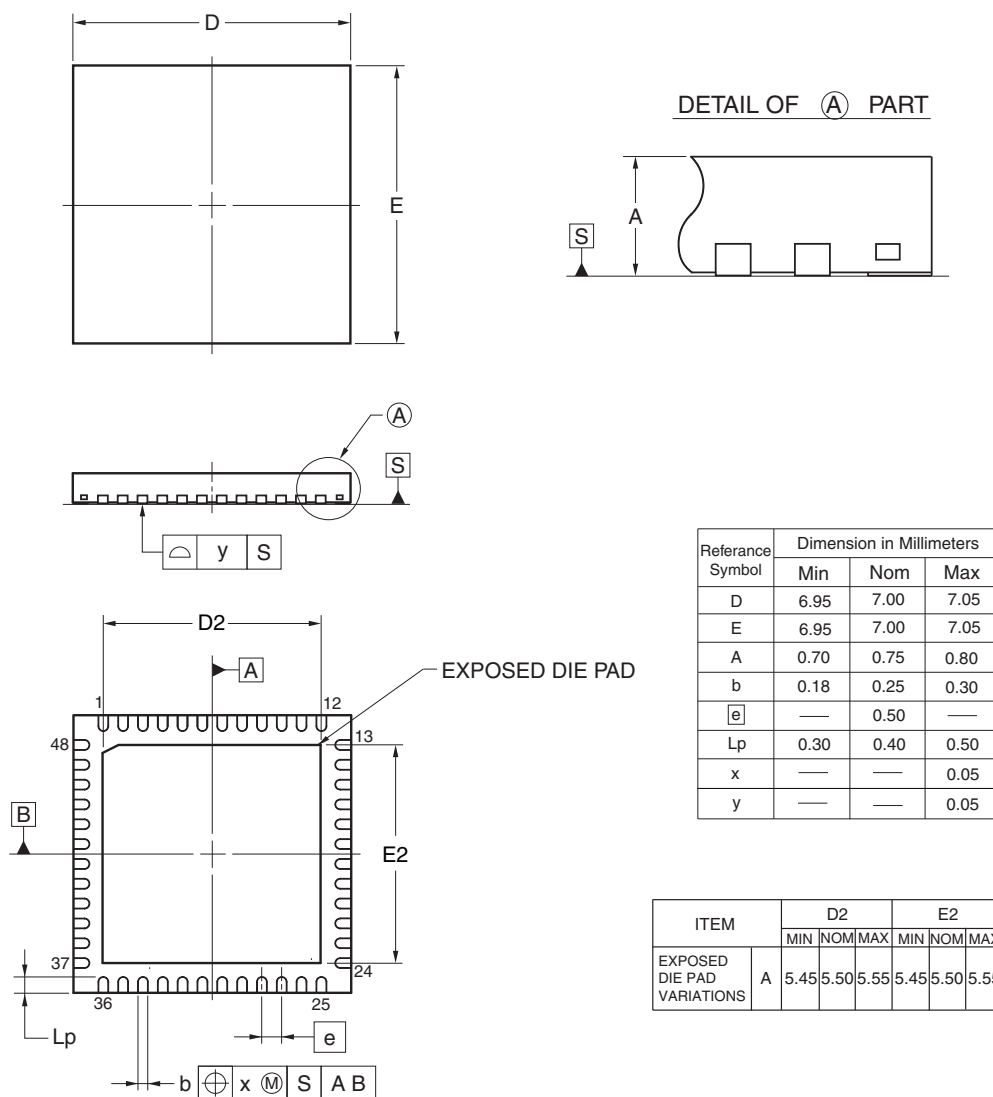
### 3.9 Dedicated Flash Memory Programmer Communication (UART)

( $T_A = -40$  to  $+105^\circ\text{C}$ ,  $2.4\text{ V} \leq V_{DD0} = V_{DD1} \leq V_{DD} \leq 5.5\text{ V}$ ,  $V_{SS} = V_{SS0} = V_{SS1} = 0\text{ V}$ )

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Transfer rate		During serial programming	115,200		1,000,000	bps

R5F104GAANA, R5F104GCANA, R5F104GDANA, R5F104GEANA, R5F104GFANA, R5F104GGANA,  
 R5F104GHANA, R5F104GJANA  
 R5F104GADNA, R5F104GCDNA, R5F104GDDNA, R5F104GEDNA, R5F104GFDNA, R5F104GGDNA,  
 R5F104GHDNA, R5F104GJDNA  
 R5F104GAGNA, R5F104GCGNA, R5F104GDGNA, R5F104GEGNA, R5F104GFGNA, R5F104GGGNA,  
 R5F104GHGNA, R5F104GJGNA  
 R5F104GKANA, R5F104GLANA  
 R5F104GKGNA, R5F104GLGNA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-HWQFN48-7x7-0.50	PWQN0048KB-A	48PJN-A P48K8-50-5B4-5	0.13



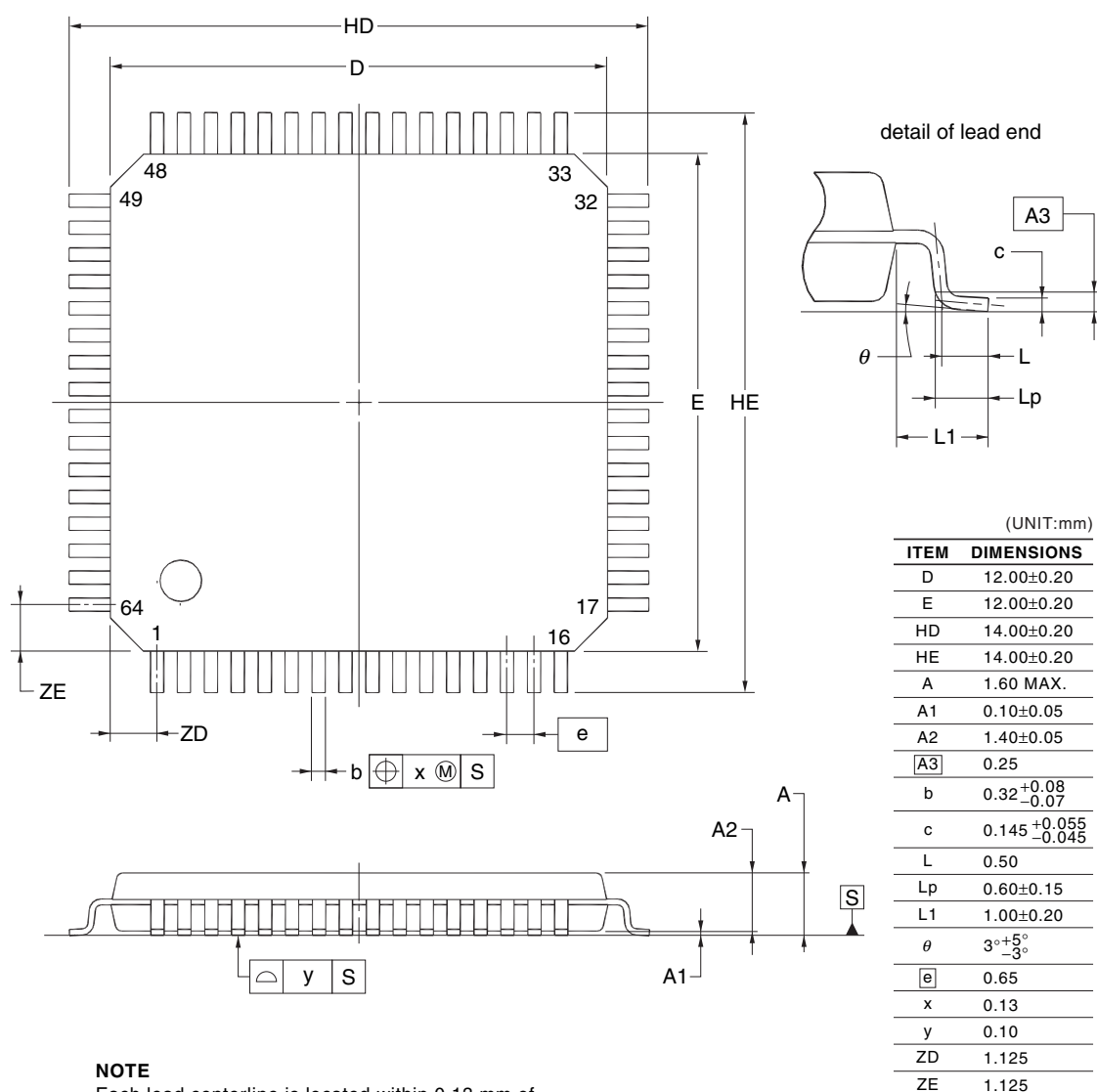
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## 4.8 64-pin products

R5F104LCAFA, R5F104LDAFA, R5F104LEAFA, R5F104LFAFA, R5F104LGAFa, R5F104LHAFA, R5F104LJAFA  
 R5F104LCDFA, R5F104LDDFA, R5F104LEDFA, R5F104LFDFA, R5F104LGDFa, R5F104LHDFa, R5F104LJDFA  
 R5F104LCGFA, R5F104LDGFA, R5F104LEGFA, R5F104LFGFA, R5F104LGGFA, R5F104LHGFA, R5F104LJGFA  
 R5F104LKAFA, R5F104LLAFA  
 R5F104LKGFA, R5F104LLGFA

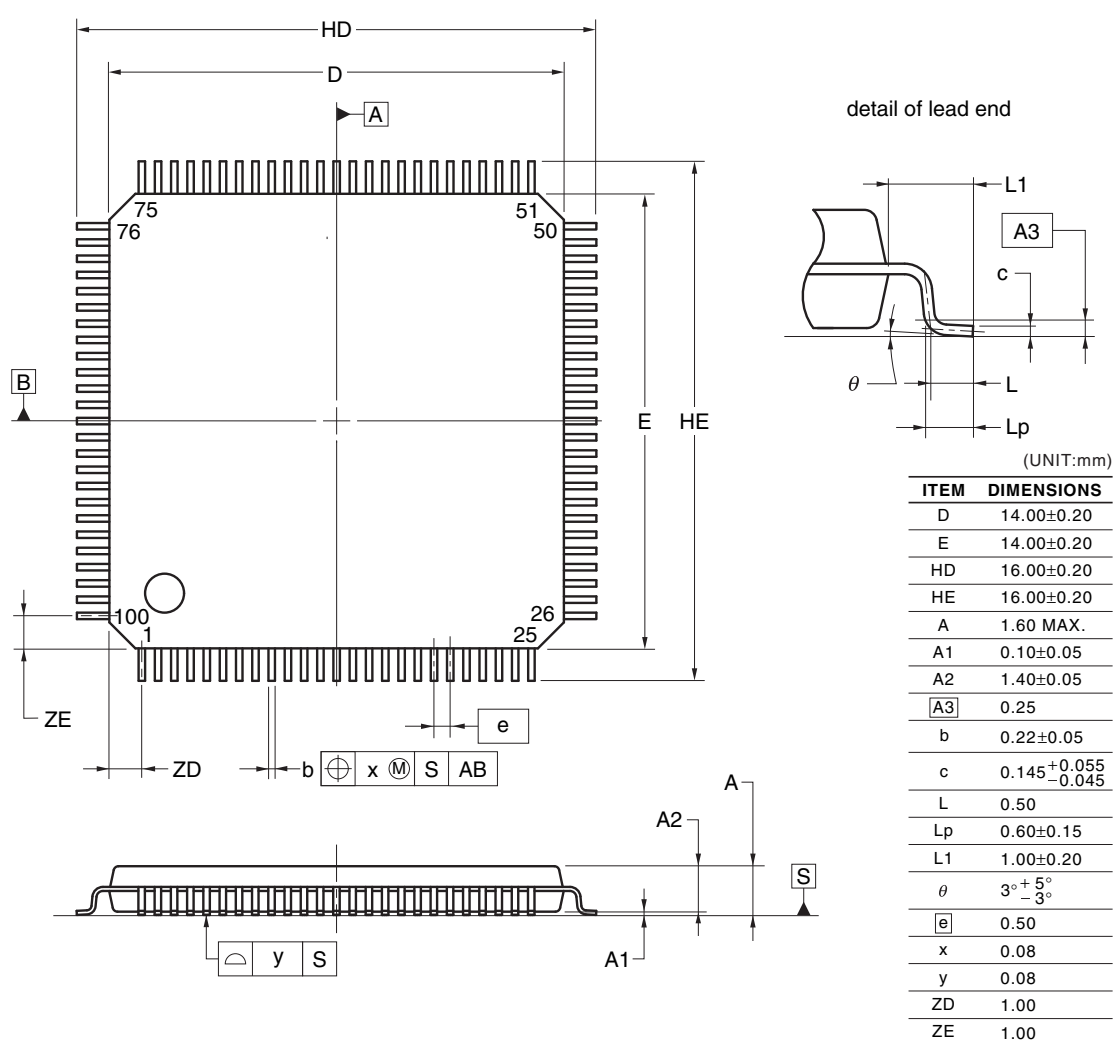
JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP64-12x12-0.65	PLQP0064JA-A	P64GK-65-UET-2	0.51



### 4.10 100-pin products

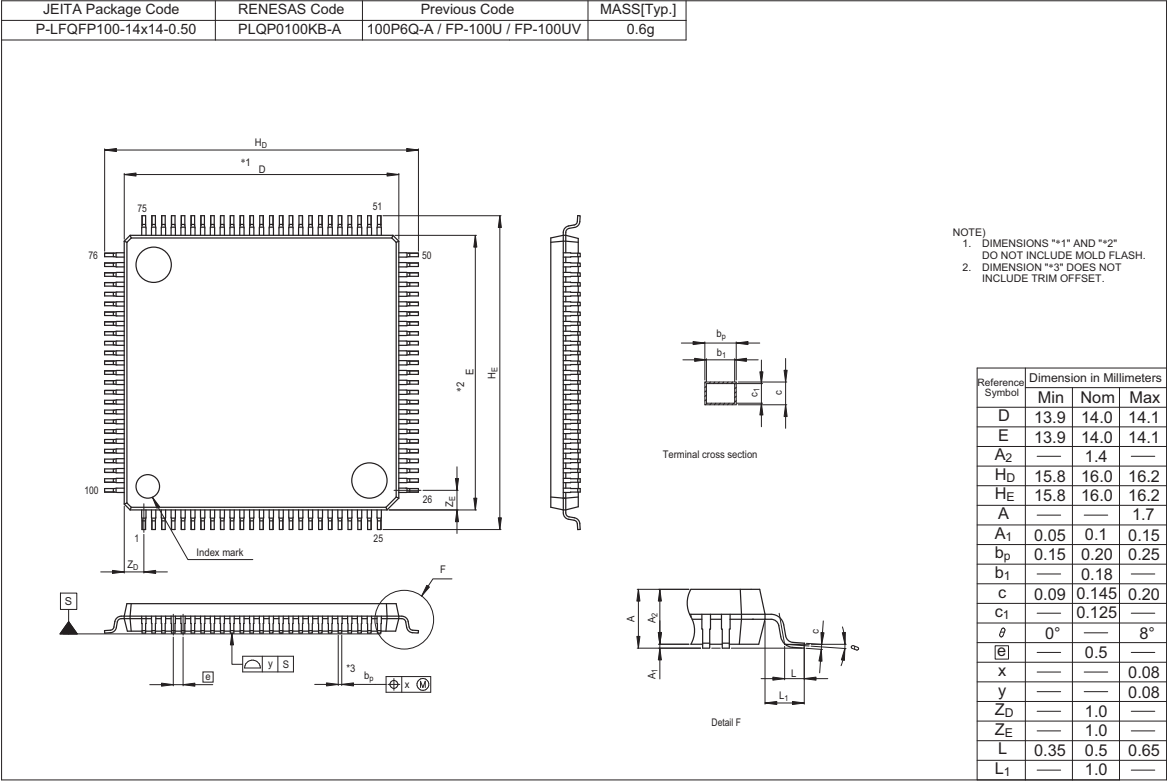
R5F104PFAFB, R5F104PGAFA, R5F104PHAFA, R5F104PJAFB  
 R5F104PFDFA, R5F104PGDFA, R5F104PHDFA, R5F104PJDFB  
 R5F104PFGFB, R5F104PGGFB, R5F104PHGFB, R5F104PJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP100-14x14-0.50	PLQP0100KE-A	P100GC-50-GBR-1	0.69



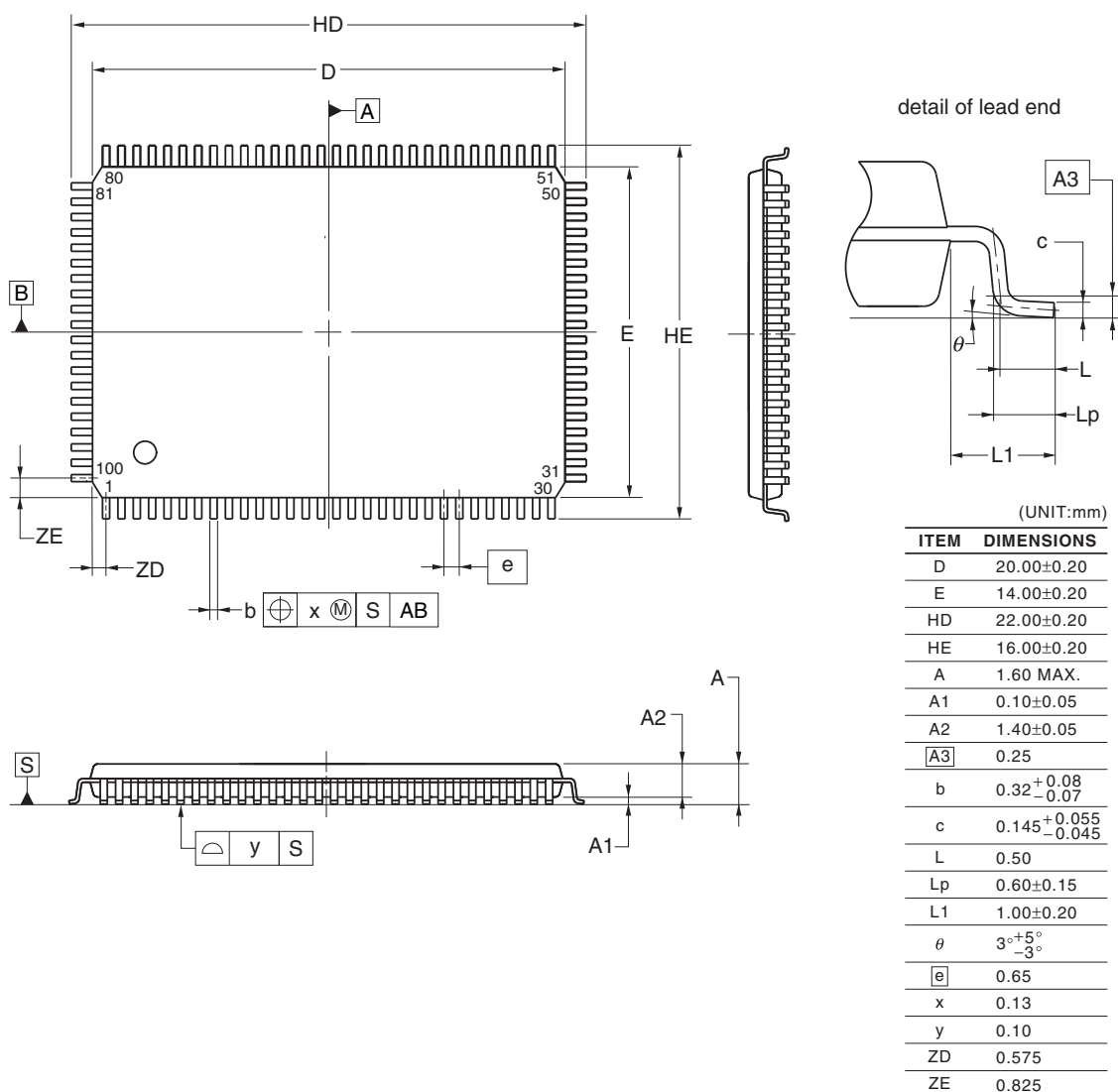
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R5F104PKAFB, R5F104PLAFB  
R5F104PKGFB, R5F104PLGFB



R5F104PFAFA, R5F104PGAFA, R5F104PHAFA, R5F104PJFAFA  
 R5F104PFDFA, R5F104PGDFA, R5F104PHDFA, R5F104PJDFA  
 R5F104PFGFA, R5F104PGGFA, R5F104PHGFA, R5F104PJGFA  
 R5F104PKAFA, R5F104PLAFA  
 R5F104PKGFA, R5F104PLGFA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP100-14x20-0.65	PLQP0100JC-A	P100GF-65-GBN-1	0.92



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## NOTES FOR CMOS DEVICES

- (1) **VOLTAGE APPLICATION WAVEFORM AT INPUT PIN:** Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN).
- (2) **HANDLING OF UNUSED INPUT PINS:** Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.
- (3) **PRECAUTION AGAINST ESD:** A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.
- (4) **STATUS BEFORE INITIALIZATION:** Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.
- (5) **POWER ON/OFF SEQUENCE:** In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.
- (6) **INPUT OF SIGNAL DURING POWER OFF STATE :** Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.