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What is "Embedded - Microcontrollers"?

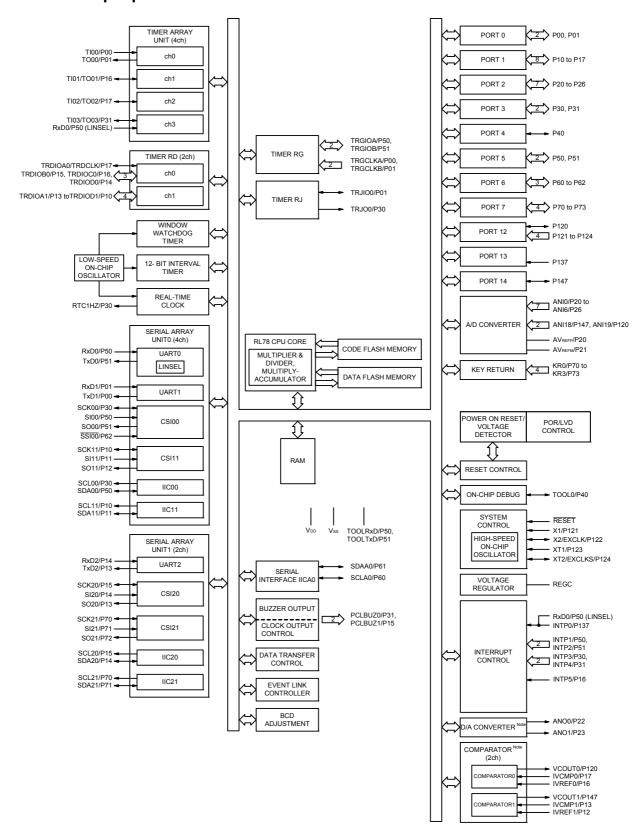
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	RL78
Core Size	16-Bit
Speed	32MHz
Connectivity	CSI, I ² C, LINbus, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	48
Program Memory Size	384KB (384K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 5.5V
Data Converters	A/D 12x8/10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-WFLGA
Supplier Device Package	64-FLGA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f104lkala-u0

RL78/G14 1. OUTLINE

1.5.4 40-pin products



Note Mounted on the 96 KB or more code flash memory products.

2. ELECTRICAL SPECIFICATIONS (TA = -40 to +85°C)

This chapter describes the following electrical specifications.

Target products A: Consumer applications TA = -40 to +85°C

R5F104xxAxx

D: Industrial applications TA = -40 to +85°C

R5F104xxDxx

- G: Industrial applications when TA = -40 to +105°C products is used in the range of TA = -40 to +85°C R5F104xxGxx
- Caution 1. The RL78 microcontrollers have an on-chip debug function, which is provided for development and evaluation. Do not use the on-chip debug function in products designated for mass production, because the guaranteed number of rewritable times of the flash memory may be exceeded when this function is used, and product reliability therefore cannot be guaranteed. Renesas Electronics is not liable for problems occurring when the on-chip debug function is used.
- Caution 2. With products not provided with an EVDD0, EVDD1, EVSS0, or EVSS1 pin, replace EVDD0 and EVDD1 with VDD, or replace EVSS0 and EVSS1 with VSS.
- Caution 3. The pins mounted depend on the product. Refer to 2.1 Port Functions to 2.2.1 Functions for each product in the RL78/G14 User's Manual.

(TA = -40 to +85°C, 1.6 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

(3/5)

Items	Symbol	Conditions	3	MIN.	TYP.	MAX.	Unit
Input voltage, high	VIH1	P00 to P06, P10 to P17, P30, P31, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P100 to P102, P110, P111, P120, P140 to P147	Normal input buffer	0.8 EVDD0		EVDD0	V
	VIH2	P01, P03, P04, P10, P14 to P17, P30, P43, P44, P50, P53 to P55,	TTL input buffer 4.0 V ≤ EVDD0 ≤ 5.5 V	2.2		EV _{DD0}	V
		P80, P81, P142, P143	TTL input buffer 3.3 V ≤ EVDD0 < 4.0 V	2.0		EV _{DD0}	V
			TTL input buffer 1.6 V ≤ EVDD0 < 3.3 V	1.5		EV _{DD0}	V
	VIH3	P20 to P27, P150 to P156		0.7 Vdd		VDD	V
	VIH4	P60 to P63		0.7 EVDD0		6.0	V
	VIH5	P121 to P124, P137, EXCLK, EX	CLKS, RESET	0.8 VDD		VDD	V
Input voltage, low	VIL1	P00 to P06, P10 to P17, P30, P31, P40 to P47, P50 to P57, P64 to P67, P70 to P77, P80 to P87, P100 to P102, P110, P111, P120, P140 to P147	Normal input buffer	0		0.2 EVDD0	V
	VIL2	P01, P03, P04, P10, P14 to P17, P30, P43, P44, P50, P53 to P55,	TTL input buffer 4.0 V ≤ EVDD0 ≤ 5.5 V	0		0.8	V
		P80, P81, P142, P143	TTL input buffer 3.3 V ≤ EVDD0 < 4.0 V	0		0.5	V
			TTL input buffer 1.6 V ≤ EVDD0 < 3.3 V	0		0.32	V
	VIL3	P20 to P27, P150 to P156	1	0		0.3 VDD	V
	VIL4	P60 to P63		0		0.3 EVDD0	V
	VIL5	P121 to P124, P137, EXCLK, EX	CLKS, RESET	0		0.2 VDD	V

Caution The maximum value of ViH of pins P00, P02 to P04, P10, P11, P13 to P15, P17, P30, P43 to P45, P50 to P55, P71, P74, P80 to P82, and P142 to P144 is EVDD0, even in the N-ch open-drain mode.

Remark Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

(1) Flash ROM: 16 to 64 KB of 30- to 64-pin products

(TA = -40 to +85°C, 1.6 V \leq EVDD0 \leq VDD \leq 5.5 V, VSS = EVSS0 = 0 V)(2/2)

Parameter	Symbol			Conditions		MIN.	TYP.	MAX.	Unit
Supply current	IDD2	HALT mode	HS (high-speed main)	fhoco = 64 MHz,	V _{DD} = 5.0 V		0.80	3.09	mA
lote 1	Note 2		mode Note 7	fih = 32 MHz Note 4	V _{DD} = 3.0 V		0.80	3.09	
				fhoco = 32 MHz,	V _{DD} = 5.0 V		0.49	2.40	
				fiH = 32 MHz Note 4	V _{DD} = 3.0 V		0.49	2.40	
				fHOCO = 48 MHz,	V _{DD} = 5.0 V		0.62	2.40	
				f _{IH} = 24 MHz Note 4	V _{DD} = 3.0 V		0.62	2.40	
				fhoco = 24 MHz,	V _{DD} = 5.0 V		0.4	1.83	
				fiH = 24 MHz Note 4	V _{DD} = 3.0 V		0.4	1.83	
				fhoco = 16 MHz,	V _{DD} = 5.0 V		0.37	1.38	
				fiH = 16 MHz Note 4	V _{DD} = 3.0 V		0.37	1.38	
			LS (low-speed main)	fHOCO = 8 MHz,	V _{DD} = 3.0 V		260	710	μΑ
			mode Note 7	fiH = 8 MHz Note 4	V _{DD} = 2.0 V		260	710	
			LV (low-voltage main)	fHOCO = 4 MHz,	V _{DD} = 3.0 V		420	700	μА
			mode Note 7	fiH = 4 MHz Note 4	V _{DD} = 2.0 V		420	700	
			HS (high-speed main)	f _{MX} = 20 MHz Note 3,	Square wave input		0.28	1.55	mA
			mode Note 7	V _{DD} = 5.0 V	Resonator connection		0.40	1.74	
			f _{MX} = 20 MHz Note 3,	Square wave input		0.28	1.55		
			V _{DD} = 3.0 V	Resonator connection		0.40	1.74		
			f _{MX} = 10 MHz Note 3,	Square wave input		0.19	0.86		
			V _{DD} = 5.0 V	Resonator connection		0.25	0.93		
					Square wave input		0.19	0.86	
				V _{DD} = 3.0 V	Resonator connection		0.25	0.93	
			LS (low-speed main)) f _{MX} = 8 MHz Note 3,	Square wave input		95	550	μА
			mode Note 7	V _{DD} = 3.0 V	Resonator connection		140	590	
				f _{MX} = 8 MHz Note 3,	Square wave input		95	550	
				V _{DD} = 2.0 V	Resonator connection		140	590	
			Subsystem clock	fsuB = 32.768 kHz Note 5,	Square wave input		0.25	0.57	μА
			operation	TA = -40°C	Resonator connection		0.44	0.76	1
				fsuB = 32.768 kHz Note 5,	Square wave input		0.30	0.57	
				$T_A = +25^{\circ}C$	Resonator connection		0.49	0.76	
				fsuB = 32.768 kHz Note 5,			0.36	1.17	
				T _A = +50°C	Resonator connection		0.59	1.36	
				fsuB = 32.768 kHz Note 5,	Square wave input		0.49	1.97	
				$T_A = +70^{\circ}C$	Resonator connection		0.72	2.16	
				fsuB = 32.768 kHz Note 5.	Square wave input		0.97	3.37	
		TA = +85°C	Resonator connection	-	1.16	3.56			
	IDD3	T _Δ = -40°C		1.03011ator confineditori	-	0.18	0.51	μА	
		TA = +25°C				0.10	0.51	μΛ	
I A	TA = +50°C				0.24	1.10			
	T _A = +70					0.29	1.10		
		TA = +85°C				0.41	3.30		

(Notes and Remarks are listed on the next page.)

(2) Flash ROM: 96 to 256 KB of 30- to 100-pin products

(TA = -40 to +85°C, 1.6 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

(2/2)

Parameter	Symbol			Conditions		MIN.	TYP.	MAX.	Unit
Supply cur-	IDD2	HALT mode	HS (high-speed main)	fHOCO = 64 MHz,	V _{DD} = 5.0 V		0.79	3.32	mA
rent Note 1	Note 2		mode Note 7	fih = 32 MHz Note 4	V _{DD} = 3.0 V		0.79	3.32	•
				fHOCO = 32 MHz,	V _{DD} = 5.0 V		0.49	2.63	•
				fih = 32 MHz Note 4	V _{DD} = 3.0 V		0.49	2.63	•
				fносо = 48 MHz,	V _{DD} = 5.0 V		0.62	2.57	•
				fih = 24 MHz Note 4	V _{DD} = 3.0 V		0.62	2.57	•
				fHOCO = 24 MHz,	V _{DD} = 5.0 V		0.4	2.00	•
				fih = 24 MHz Note 4	V _{DD} = 3.0 V		0.4	2.00	•
				fHOCO = 16 MHz,	V _{DD} = 5.0 V		0.38	1.49	-
				fih = 16 MHz Note 4	V _{DD} = 3.0 V		0.38	1.49	
			LS (low-speed main)	fHOCO = 8 MHz,	V _{DD} = 3.0 V		250	800	μА
			mode Note 7	fih = 8 MHz Note 4	V _{DD} = 2.0 V		250	800	•
			LV (low-voltage main)	fHOCO = 4 MHz,	V _{DD} = 3.0 V		420	755	μА
			mode Note 7	fih = 4 MHz Note 4	V _{DD} = 2.0 V		420	755	•
			HS (high-speed main)	f _{MX} = 20 MHz Note 3,	Square wave input		0.30	1.63	mA
			mode Note 7	V _{DD} = 5.0 V	Resonator connection		0.40	1.85	•
				f _{MX} = 20 MHz Note 3,	Square wave input		0.30	1.63	•
				V _{DD} = 3.0 V	Resonator connection		0.40	1.85	-
				f _{MX} = 10 MHz Note 3, V _{DD} = 5.0 V f _{MX} = 10 MHz Note 3, V _{DD} = 3.0 V	Square wave input		0.20	0.89	•
					Resonator connection		0.25	0.97	
					Square wave input		0.20	0.89	
					Resonator connection		0.25	0.97	
			LS (low-speed main)	fmx = 8 MHz Note 3,	Square wave input		110	580	μА
			mode Note 7	V _{DD} = 3.0 V	Resonator connection		140	630	
				MX = 8 MHz Note 3,	Square wave input		110	580	
				V _{DD} = 2.0 V	Resonator connection		140	630	
			Subsystem clock oper-	fsuB = 32.768 kHz Note 5,	Square wave input		0.28	0.66	μΑ
			ation	TA = -40°C	Resonator connection		0.47	0.85	
				fsuB = 32.768 kHz Note 5,	Square wave input		0.34	0.66	
				TA = +25°C	Resonator connection		0.53	0.85	-
				fsuB = 32.768 kHz Note 5,	Square wave input		0.37	2.35	
				TA = +50°C	Resonator connection		0.56	2.54	
				fsuB = 32.768 kHz Note 5,	Square wave input		0.61	4.08	
				T _A = +70°C	Resonator connection		0.80	4.27	
				fsuB = 32.768 kHz Note 5,	Square wave input		1.55	8.09	
				T _A = +85°C	Resonator connection		1.74	8.28	
	IDD3	STOP mode	TA = -40°C				0.19	0.57	μΑ
	Note 6 Note 8 T _A = +25°C	T _A = +25°C				0.25	0.57		
			TA = +50°C				0.33	2.26	
			T _A = +70°C				0.52	3.99	
			T _A = +85°C				1.46	8.00	

(Notes and Remarks are listed on the next page.)

- Note 1. Total current flowing into VDD, EVDD0, and EVDD1, including the input leakage current flowing when the level of the input pin is fixed to VDD, EVDD0, and EVDD1, or Vss, EVss0, and EVss1. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, D/A converter, comparator, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
- Note 2. During HALT instruction execution by flash memory.
- Note 3. When high-speed on-chip oscillator and subsystem clock are stopped.
- Note 4. When high-speed system clock and subsystem clock are stopped.
- Note 5. When high-speed on-chip oscillator and high-speed system clock are stopped. When RTCLPC = 1 and setting ultra-low current consumption (AMPHS1 = 1). The current flowing into the RTC is included. However, not including the current flowing into the 12-bit interval timer and watchdog timer.
- Note 6. Not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.
- Note 7. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.

HS (high-speed main) mode: $2.7 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V} @ 1 \text{ MHz to } 32 \text{ MHz}$

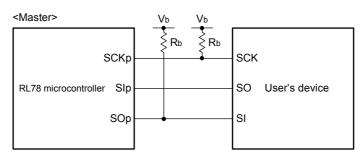
 $2.4 \text{ V} \le \text{Vdd} \le 5.5 \text{ V@1 MHz}$ to 16 MHz

LS (low-speed main) mode: 1.8 V \leq VDD \leq 5.5 V@1 MHz to 8 MHz LV (low-voltage main) mode: 1.6 V \leq VDD \leq 5.5 V@1 MHz to 4 MHz

- Note 8. Regarding the value for current to operate the subsystem clock in STOP mode, refer to that in HALT mode.
- Remark 1. fmx: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
- Remark 2. fHOCO: High-speed on-chip oscillator clock frequency (64 MHz max.)

 Remark 3. fH: High-speed on-chip oscillator clock frequency (32 MHz max.)
- Remark 4. fsub: Subsystem clock frequency (XT1 clock oscillation frequency)
- Remark 5. Except subsystem clock operation and STOP mode, temperature condition of the TYP. value is TA = 25°C

CSI mode connection diagram (during communication at different potential



- **Remark 1.** Rb[Ω]: Communication line (SCKp, SOp) pull-up resistance, Cb[F]: Communication line (SCKp, SOp) load capacitance, Vb[V]: Communication line voltage
- **Remark 2.** p: CSI number (p = 00, 01, 10, 20, 30, 31), m: Unit number (m = 0, 1), n: Channel number (n = 0 to 3), g: PIM and POM number (g = 0, 1, 3 to 5, 14)
- Remark 3. fmck: Serial array unit operation clock frequency (Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00))
- Remark 4. CSI01 of 48-, 52-, 64-pin products, and CSI11 and CSI21 cannot communicate at different potential. Use other CSI for communication at different potential.

(9) Communication at different potential (1.8 V, 2.5 V, 3 V) (CSI mode) (slave mode, SCKp... external clock input)

(TA = -40 to +85°C, 1.8 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

Parameter	Symbol	Cor	nditions	, ,	h-speed mode		r-speed mode		-voltage mode	Unit
				MIN.	MAX.	MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	tkCY2	$4.0 \text{ V} \leq \text{EV}_{\text{DD0}} \leq 5.5 \text{ V},$	24 MHz < fmck	14/fмск		_		_		ns
Note 1		$2.7~V \leq V_b \leq 4.0~V$	20 MHz < fмcк ≤ 24 MHz	12/fмск		_		_		ns
			8 MHz < fмcк ≤ 20 MHz	10/fмск		_		_		ns
			4 MHz < fмcк ≤ 8 MHz	8/fмск		16/fмск		_		ns
			fмcк ≤ 4 MHz	6/fмск		10/fмск		10/fмск		ns
		$2.7 \text{ V} \le \text{EV}_{\text{DD0}} < 4.0 \text{ V},$	24 MHz < fmck	20/fмск		_		_		ns
		$2.3~V \leq V_b \leq 2.7~V$	20 MHz < fмcк ≤ 24 MHz	16/fмск		_		_		ns
			16 MHz < fмcк ≤ 20 MHz	14/fмск		_		_		ns
			8 MHz < fмcк ≤ 16 MHz	12/fмск		_		_		ns
			4 MHz < fмcк ≤ 8 MHz	8/fмск		16/fмск		_		ns
			fмcк ≤ 4 MHz	6/fмск		10/fмск		10/fмск		ns
		1.8 V ≤ EVDD0 < 3.3 V,	24 MHz < fmck	48/fмск		_		_		ns
		1.6 V ≤ V _b ≤ 2.0 V Note 2	20 MHz < fмcк ≤ 24 MHz	36/fмск		_		_		ns
		Note 2	16 MHz < fмcк ≤ 20 MHz	32/fмск		_		_		ns
			8 MHz < fмcк ≤ 16 MHz	26/fмск		_		_		ns
			4 MHz < fмcк ≤ 8 MHz	16/fмск		16/fмск		_		ns
			fмcк ≤ 4 MHz	10/fмск		10/fмск		10/fмск		ns
SCKp high-/ low-level width	tĸH2, tĸL2	4.0 V ≤ EVDD0 ≤ 5.5 V, 2	2.7 V ≤ V _b ≤ 4.0 V	tксү2/2 - 12		tkcy2/2 - 50		tксү2/2 - 50		ns
		2.7 V ≤ EVDD0 < 4.0 V, 2	$2.3~V \leq V_b \leq 2.7~V$	tксү2/2 - 18		tkcy2/2 - 50		tксү2/2 - 50		ns
		1.8 V ≤ EVDD0 < 3.3 V,	$1.6 \text{ V} \leq \text{V}_b \leq 2.0 \text{ V Note 2}$	tксү2/2 - 50		tkcy2/2 - 50		tксү2/2 - 50		ns
SIp setup time (to SCKp↑) Note 3	tsık2	4.0 V ≤ EVDD0 ≤ 5.5 V, 2	$2.7 \text{ V} \le \text{V}_{\text{b}} \le 4.0 \text{ V}$	1/fмск + 20		1/fмск + 30		1/fмск + 30		ns
		2.7 V ≤ EVDD0 < 4.0 V, 2	$2.3~V \leq V_b \leq 2.7~V$	1/fмск + 20		1/fмск + 30		1/fмск + 30		ns
		1.8 V ≤ EVDD0 < 3.3 V,	$1.6~\text{V} \leq \text{V}_\text{b} \leq 2.0~\text{V}~\text{Note}~2$	1/fмск + 30		1/fмск + 30		1/fмск + 30		ns
SIp hold time (from SCKp↑) Note 4	tksi2			1/fмск + 31		1/fмск + 31		1/fмск + 31		ns
Delay time from SCKp↓ to SOp	tkso2	$4.0 \text{ V} \le \text{EV}_{\text{DD0}} \le 5.5 \text{ V}, \Omega$ Cb = 30 pF, Rb = 1.4 k Ω			2/fмск + 120		2/fмск + 573		2/fмск + 573	ns
output Note 5		$2.7 \text{ V} \le \text{EV}_{\text{DD0}} < 4.0 \text{ V}, \Omega$ Cb = 30 pF, Rb = 2.7 k Ω			2/fмск + 214		2/fмск + 573		2/fмск + 573	ns
		1.8 V ≤ EV _{DD0} < 3.3 V, C _b = 30 pF, Rv = 5.5 kΩ	$1.6 \text{ V} \le \text{V}_b \le 2.0 \text{ V} \text{ Note 2},$		2/fмск + 573		2/fмск + 573		2/fмск + 573	ns

 $(\textbf{Notes},\,\textbf{Caution},\, \text{and}\,\, \textbf{Remarks}$ are listed on the next page.)

2.6.4 Comparator

(TA = -40 to +85°C, 1.6 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, Vss = EVss0 = EVss1 = 0 V)

Parameter	Symbol	Col	nditions	MIN.	TYP.	MAX.	Unit
Input voltage range	Ivref			0		EVDD0 - 1.4	V
	Ivcmp			-0.3		EV _{DD0} + 0.3	V
Output delay	td V _{DD} = 3.0 V Input slew rate > 50 mV/μs		Comparator high-speed mode, standard mode			1.2	μs
			Comparator high-speed mode, window mode			2.0	μs
			Comparator low-speed mode, standard mode		3.0	5.0	μs
High-electric-potential reference voltage	VTW+	Comparator high-speed mode	e, window mode		0.76 VDD		V
Low-electric-potential ref- erence voltage	VTW-	Comparator high-speed mode	e, window mode		0.24 VDD		V
Operation stabilization wait time	tсмр			100			μs
Internal reference voltage Note	VBGR	$2.4 \text{ V} \le \text{VDD} \le 5.5 \text{ V}, \text{ HS (h}$	nigh-speed main) mode	1.38	1.45	1.50	٧

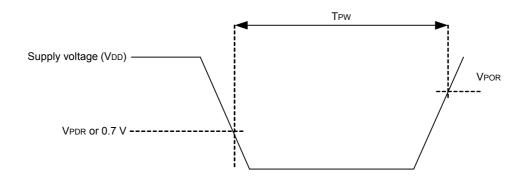
Note Not usable in LS (low-speed main) mode, LV (low-voltage main) mode, sub-clock operation, or STOP mode.

2.6.5 POR circuit characteristics

 $(TA = -40 \text{ to } +85^{\circ}\text{C}, Vss = 0 \text{ V})$

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Power on/down reset threshold	VPOR	Voltage threshold on VDD rising	1.47	1.51	1.55	V
	VPDR	Voltage threshold on VDD falling Note 1	1.46	1.50	1.54	V
Minimum pulse width Note 2	Tpw		300			μs

- **Note 1.** However, when the operating voltage falls while the LVD is off, enter STOP mode, or enable the reset status using the external reset pin before the voltage falls below the operating voltage range shown in 2.4 AC Characteristics.
- Note 2. Minimum time required for a POR reset when VDD exceeds below VPDR. This is also the minimum time required for a POR reset from when VDD exceeds below 0.7 V to when VDD exceeds VPOR while STOP mode is entered or the main system clock is stopped through setting bit 0 (HIOSTOP) and bit 7 (MSTOP) in the clock operation status control register (CSC).



Remark 4. fsub:

- Note 1. Total current flowing into VDD and EVDD0, including the input leakage current flowing when the level of the input pin is fixed to VDD, EVDD0 or Vss, EVss0. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing data flash rewrite.
- Note 2. During HALT instruction execution by flash memory.
- Note 3. When high-speed on-chip oscillator and subsystem clock are stopped.
- Note 4. When high-speed system clock and subsystem clock are stopped.
- Note 5. When high-speed on-chip oscillator and high-speed system clock are stopped. When RTCLPC = 1 and setting ultra-low current consumption (AMPHS1 = 1). The current flowing into the RTC is included. However, not including the current flowing into the 12-bit interval timer and watchdog timer.
- Note 6. Not including the current flowing into the RTC, 12-bit interval timer, and watchdog timer.

Subsystem clock frequency (XT1 clock oscillation frequency)

Note 7. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below. HS (high-speed main) mode: $2.7 \text{ V} \le \text{V}_{\text{DD}} \le 5.5 \text{ V}_{\text{@}1} \text{ MHz}$ to 32 MHz

2.4 V ≤ V_{DD} ≤ 5.5 V@1 MHz to 16 MHz

- Note 8. Regarding the value for current to operate the subsystem clock in STOP mode, refer to that in HALT mode.
- Remark 1. fmx: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
- Remark 2. fHoco: High-speed on-chip oscillator clock frequency (64 MHz max.)

 Remark 3. fH: High-speed on-chip oscillator clock frequency (32 MHz max.)
- Remark 5. Except subsystem clock operation and STOP mode, temperature condition of the TYP. value is TA = 25°C

- Note 1. Total current flowing into VDD, EVDD0, and EVDD1, including the input leakage current flowing when the level of the input pin is fixed to VDD, EVDD0, and EVDD1, or Vss, EVsso, and EVss1. The values below the MAX. column include the peripheral operation current. However, not including the current flowing into the A/D converter, D/A converter, comparator, LVD circuit, I/O port, and on-chip pull-up/pull-down resistors and the current flowing during data flash rewrite.
- Note 2. When high-speed on-chip oscillator and subsystem clock are stopped.
- Note 3. When high-speed system clock and subsystem clock are stopped.
- Note 4. When high-speed on-chip oscillator and high-speed system clock are stopped. When AMPHS1 = 1 (Ultra-low power consumption oscillation). However, not including the current flowing into the 12-bit interval timer and watchdog timer.
- Note 5. Relationship between operation voltage width, operation frequency of CPU and operation mode is as below.

HS (high-speed main) mode: $2.7 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V} @ 1 \text{ MHz to } 32 \text{ MHz}$

 $2.4 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V@1 MHz}$ to 16 MHz

- Remark 1. fmx: High-speed system clock frequency (X1 clock oscillation frequency or external main system clock frequency)
- Remark 2. fHoco: High-speed on-chip oscillator clock frequency (64 MHz max.)
 Remark 3. fH: High-speed on-chip oscillator clock frequency (32 MHz max.)
- Remark 4. fsub: Subsystem clock frequency (XT1 clock oscillation frequency)
- Remark 5. Except subsystem clock operation, temperature condition of the TYP. value is Ta = 25°C

(4) Peripheral Functions (Common to all products)

(TA = -40 to +105°C, 2.4 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

Parameter	Symbol	Condit	ions	MIN.	TYP.	MAX.	Unit
Low-speed on-chip oscilla- tor operating current	I _{FIL} Note 1				0.20		μА
RTC operating current	I _{RTC} Notes 1, 2, 3				0.02		μΑ
12-bit interval timer operat- ing current	IT Notes 1, 2, 4				0.02		μА
Watchdog timer operating current	I _{WDT} Notes 1, 2, 5	fı∟ = 15 kHz			0.22		μΑ
A/D converter operating current	I _{ADC} Notes 1, 6	When conversion at maximum speed	Normal mode, AV _{REFP} = V _{DD} = 5.0 V		1.3	1.7	mA
			Low voltage mode, AV _{REFP} = V _{DD} = 3.0 V		0.5	0.7	mA
A/D converter reference voltage current	IADREF Note 1				75.0		μΑ
Temperature sensor operating current	I _{TMPS} Note 1				75.0		μΑ
D/A converter operating current	I _{DAC} Notes 1, 11, 13	Per D/A converter channel				1.5	mA
Comparator operating cur-	I _{CMP} Notes 1, 12, 13	V _{DD} = 5.0 V,	Window mode		12.5		μΑ
rent		Regulator output voltage = 2.1 V	Comparator high-speed mode		6.5		μΑ
			Comparator low-speed mode		1.7		μΑ
		V _{DD} = 5.0 V,	Window mode		8.0		μΑ
		Regulator output voltage = 1.8 V	Comparator high-speed mode		4.0		μΑ
			Comparator low-speed mode		1.3		μΑ
LVD operating current	I _{LVD} Notes 1, 7				0.08		μΑ
Self-programming operating current	IFSP Notes 1, 9				2.50	12.20	mA
BGO operating current	I _{BGO} Notes 1, 8				2.50	12.20	mA
SNOOZE operating current	ISNOZ Note 1	ADC operation	The mode is performed Note 10		0.50	1.10	mA
			The A/D conversion operations are performed, Low voltage mode, AVREFP = VDD = 3.0 V		1.20	2.04	
		CSI/UART operation			0.70	1.54	
		DTC operation			3.10		

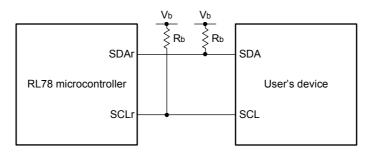
- Note 1. Current flowing to VDD.
- Note 2. When high speed on-chip oscillator and high-speed system clock are stopped.
- Note 3. Current flowing only to the real-time clock (RTC) (excluding the operating current of the low-speed on-chip oscillator and the XT1 oscillator). The supply current of the RL78 microcontrollers is the sum of the values of either IDD1 or IDD2, and IRTC, when the real-time clock operates in operation mode or HALT mode. When the low-speed on-chip oscillator is selected, IFIL should be added. IDD2 subsystem clock operation includes the operational current of the real-time clock.
- Note 4. Current flowing only to the 12-bit interval timer (excluding the operating current of the low-speed on-chip oscillator and the XT1 oscillator). The supply current of the RL78 microcontrollers is the sum of the values of either IDD1 or IDD2, and IIT, when the 12-bit interval timer operates in operation mode or HALT mode. When the low-speed on-chip oscillator is selected, IFIL should be added.

(2) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output) (TA = -40 to +105°C, 2.4 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, Vss = EVss0 = EVss1 = 0 V)

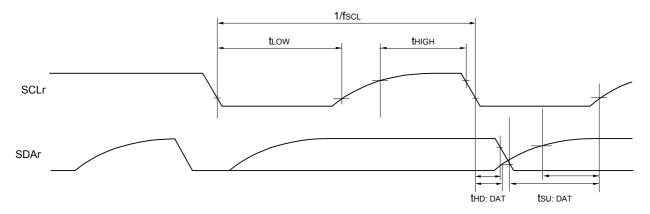
Parameter	Symbol	l Conditions		HS (high-sp mo	•	Unit
				MIN.	MAX.	
SCKp cycle time	tkcy1	tkcy1 ≥ 4/fclk	2.7 V ≤ EVDD0 ≤ 5.5 V	250		ns
			2.4 V ≤ EV _{DD0} ≤ 5.5 V	500		ns
SCKp high-/low-level width	tkH1, tkL1	4.0 V ≤ EV _{DD0} :	4.0 V ≤ EV _{DD0} ≤ 5.5 V			ns
		2.7 V ≤ EVDD0 :	2.7 V ≤ EV _{DD0} ≤ 5.5 V			ns
		2.4 V ≤ EV _{DD0} ≤ 5.5 V		tkcy1/2 - 76		ns
SIp setup time (to SCKp↑) Note 1	tsık1	4.0 V ≤ EV _{DD0} :	≤ 5.5 V	66		ns
		2.7 V ≤ EV _{DD0} :	2.7 V ≤ EV _{DD0} ≤ 5.5 V			ns
		2.4 V ≤ EV _{DD0} ≤ 5.5 V		113		ns
SIp hold time (from SCKp↑) Note 2	tksi1			38		ns
Delay time from SCKp↓ to SOp output Note 3	tkso1	C = 30 pF Note	4		50	ns

- Note 1. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes "to SCKp↓" when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
- Note 2. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The SIp hold time becomes "from SCKp↓" when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
- Note 3. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes "from SCKp↑" when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.
- **Note 4.** C is the load capacitance of the SCKp and SOp output lines.
- Caution Select the normal input buffer for the SIp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).
- **Remark 1.** p: CSI number (p = 00, 01, 10, 11, 20, 21, 30, 31), m: Unit number (m = 0, 1), n: Channel number (n = 0 to 3), g: PIM number (g = 0, 1, 3 to 5, 14)
- Remark 2. fmck: Serial array unit operation clock frequency (Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00 to 03, 10 to 13))

Simplified I²C mode connection diagram (during communication at different potential)



Simplified I²C mode serial transfer timing (during communication at different potential)



Remark 1. $Rb[\Omega]$: Communication line (SDAr, SCLr) pull-up resistance, Cb[F]: Communication line (SDAr, SCLr) load capacitance, Vb[V]: Communication line voltage

Remark 2. r: IIC number (r = 00, 01, 10, 11, 20, 30, 31), g: PIM, POM number (g = 0, 1, 3 to 5, 14)

Remark 3. fmck: Serial array unit operation clock frequency

(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number (m = 0, 1),

n: Channel number (n = 0, 2), mn = 00, 01, 02, 10, 12, 13)

3.6 Analog Characteristics

3.6.1 A/D converter characteristics

Classification of A/D converter characteristics

Reference Voltage Input channel	Reference voltage (+) = AVREFP Reference voltage (-) = AVREFM	Reference voltage (+) = VDD Reference voltage (-) = VSS	Reference voltage (+) = V _{BGR} Reference voltage (-)= AV _{REFM}
ANI0 to ANI14	Refer to 3.6.1 (1).	Refer to 3.6.1 (3).	Refer to 3.6.1 (4).
ANI16 to ANI20	Refer to 3.6.1 (2).		
Internal reference voltage Temperature sensor output voltage	Refer to 3.6.1 (1) .		_

(1) When reference voltage (+) = AVREFP/ANI0 (ADREFP1 = 0, ADREFP0 = 1), reference voltage (-) = AVREFM/ANI1 (ADREFM = 1), target pin: ANI2 to ANI14, internal reference voltage, and temperature sensor output voltage

(TA = -40 to +105°C, 2.4 V \leq AVREFP \leq VDD \leq 5.5 V, Vss = 0 V, Reference voltage (+) = AVREFP, Reference voltage (-) = AVREFM = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Resolution	RES			8		10	bit
Overall error Note 1	AINL	10-bit resolution AV _{REFP} = V _{DD} Note 3	2.4 V ≤ AVREFP ≤ 5.5 V		1.2	±3.5	LSB
Conversion time	tconv	10-bit resolution	$3.6~V \leq V_{DD} \leq 5.5~V$	2.125		39	μs
		Target pin: ANI2 to ANI14	$2.7 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$	3.1875		39	μs
			$2.4~V \leq V_{DD} \leq 5.5~V$	17		39	μs
		10-bit resolution	$3.6~V \leq V_{DD} \leq 5.5~V$	2.375		39	μs
and tempera age (HS (high	Target pin: Internal reference voltage, and temperature sensor output volt-	$2.7~\text{V} \leq \text{V}_{\text{DD}} \leq 5.5~\text{V}$	3.5625		39	μs	
		age (HS (high-speed main) mode)	$2.4~\text{V} \leq \text{Vdd} \leq 5.5~\text{V}$	17		39	μs
Zero-scale error Notes 1, 2	Ezs	10-bit resolution AVREFP = VDD Note 3	2.4 V ≤ AVREFP ≤ 5.5 V			±0.25	%FSR
Full-scale error Notes 1, 2	Ers	10-bit resolution AVREFP = VDD Note 3	2.4 V ≤ AVREFP ≤ 5.5 V			±0.25	%FSR
Integral linearity error Note 1	ILE	10-bit resolution AVREFP = VDD Note 3	2.4 V ≤ AVREFP ≤ 5.5 V			±2.5	LSB
Differential linearity error Note 1	DLE	10-bit resolution AVREFP = VDD Note 3	2.4 V ≤ AVREFP ≤ 5.5 V			±1.5	LSB
Analog input voltage	Vain	ANI2 to ANI14		0		AVREFP	V
		Internal reference voltage output (2.4 V ≤ V _{DD} ≤ 5.5 V, HS (high-speed main) mode)			V _{BGR} Note 4		
		Temperature sensor output voltage (2.4 V ≤ V _{DD} ≤ 5.5 V, HS (high-speed main) mode)			V _{TMPS25} Note 4		

Note 1. Excludes quantization error (±1/2 LSB).

Note 2. This value is indicated as a ratio (%FSR) to the full-scale value.

Note 3. When AVREFP \leq VDD, the MAX. values are as follows.

Overall error: Add ± 1.0 LSB to the MAX. value when AVREFP = VDD. Zero-scale error/Full-scale error: Add $\pm 0.05\%$ FSR to the MAX. value when AVREFP = VDD. Integral linearity error/ Differential linearity error: Add ± 0.5 LSB to the MAX. value when AVREFP = VDD.

Note 4. Refer to 3.6.2 Temperature sensor characteristics/internal reference voltage characteristic.

3.6.4 Comparator

(TA = -40 to +105°C, 2.4 V \leq EVDD0 = EVDD1 \leq VDD \leq 5.5 V, VSS = EVSS0 = EVSS1 = 0 V)

Parameter	Symbol	Col	nditions	MIN.	TYP.	MAX.	Unit
Input voltage range	Ivref			0		EV _{DD0} - 1.4	V
	Ivcmp			-0.3		EV _{DD0} + 0.3	V
Output delay	td V _{DD} = 3.0 V Input slew rate > 50 mV/μs		Comparator high-speed mode, standard mode			1.2	μs
			Comparator high-speed mode, window mode			2.0	μs
			Comparator low-speed mode, standard mode		3.0	5.0	μs
High-electric-potential reference voltage	VTW+	Comparator high-speed mode	e, window mode		0.76 VDD		V
Low-electric-potential ref- erence voltage	VTW-	Comparator high-speed mode	e, window mode		0.24 VDD		V
Operation stabilization wait time	tсмр			100			μs
Internal reference voltage Note	VBGR	$2.4 \text{ V} \le \text{VDD} \le 5.5 \text{ V}, \text{ HS (h}$	nigh-speed main) mode	1.38	1.45	1.50	V

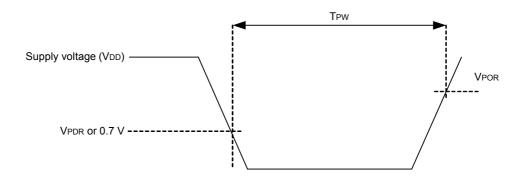
Note Not usable in sub-clock operation or STOP mode.

3.6.5 POR circuit characteristics

$(TA = -40 \text{ to } +105^{\circ}\text{C}, Vss = 0 \text{ V})$

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Power on/down reset threshold	VPOR	Voltage threshold on VDD rising	1.45	1.51	1.57	V
	VPDR	Voltage threshold on VDD falling Note 1	1.44	1.50	1.56	V
Minimum pulse width Note 2	Tpw		300			μs

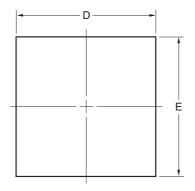
- **Note 1.** However, when the operating voltage falls while the LVD is off, enter STOP mode, or enable the reset status using the external reset pin before the voltage falls below the operating voltage range shown in 3.4 AC Characteristics.
- Note 2. Minimum time required for a POR reset when VDD exceeds below VPDR. This is also the minimum time required for a POR reset from when VDD exceeds below 0.7 V to when VDD exceeds VPOR while STOP mode is entered or the main system clock is stopped through setting bit 0 (HIOSTOP) and bit 7 (MSTOP) in the clock operation status control register (CSC).

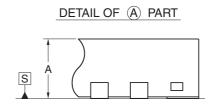


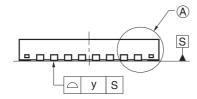
4.2 32-pin products

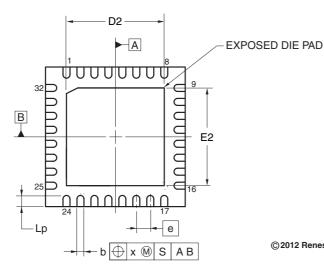
R5F104BAANA, R5F104BCANA, R5F104BDANA, R5F104BEANA, R5F104BFANA, R5F104BGANA R5F104BADNA, R5F104BCDNA, R5F104BDNA, R5F104BEDNA, R5F104BFDNA, R5F104BGDNA R5F104BAGNA, R5F104BCGNA, R5F104BDGNA, R5F104BEGNA, R5F104BGNA, R5F104BGNA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-HWQFN32-5x5-0.50	PWQN0032KB-A	P32K8-50-3B4-4	0.06









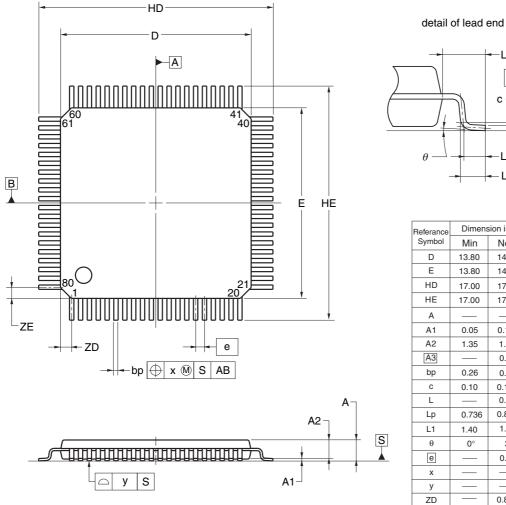
Referance	Dimension in Millimeters					
Symbol	Min	Nom	Max			
D	4.95	5.00	5.05			
Е	4.95	5.00	5.05			
Α	0.70	0.75	0.80			
b	0.18	0.25	0.30			
е		0.50				
Lp	0.30	0.40	0.50			
х			0.05			
у			0.05			

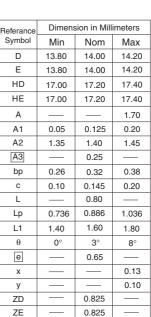
	ITEM		D2		E2			
			MIN	NOM	MAX	MIN	MOM	MAX
	EXPOSED DIE PAD VARIATIONS	Α	3.45	3.50	3.55	3.45	3.50	3.55

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R5F104MFAFA, R5F104MGAFA, R5F104MHAFA, R5F104MJAFA R5F104MFDFA, R5F104MGDFA, R5F104MHDFA, R5F104MJDFA R5F104MFGFA, R5F104MGGFA, R5F104MHGFA, R5F104MJGFA R5F104MKAFA, R5F104MLAFA R5F104MKGFA, R5F104MLGFA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP80-14x14-0.65	PLQP0080JB-E	P80GC-65-UBT-2	0.69





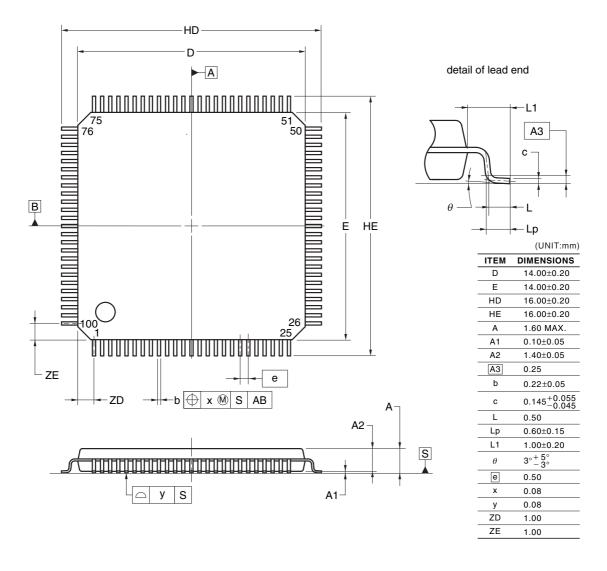
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4.10 100-pin products

R5F104PFAFB, R5F104PGAFB, R5F104PHAFB, R5F104PJAFB R5F104PFDFB, R5F104PGDFB, R5F104PHDFB, R5F104PJDFB R5F104PFGFB, R5F104PGGFB, R5F104PHGFB, R5F104PJGFB

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LFQFP100-14x14-0.50	PLQP0100KE-A	P100GC-50-GBR-1	0.69



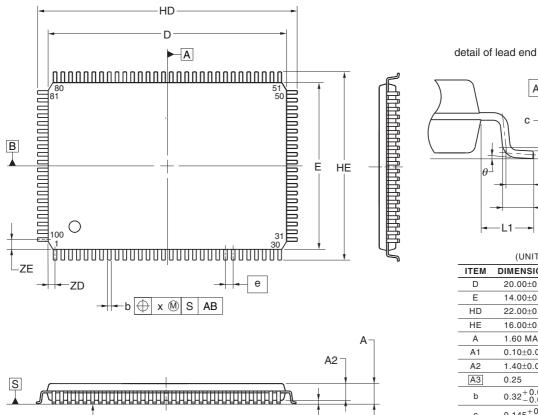
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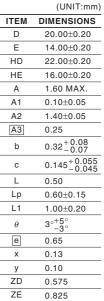
-Lp

R5F104PFAFA, R5F104PGAFA, R5F104PHAFA, R5F104PJAFA R5F104PFDFA, R5F104PGDFA, R5F104PHDFA, R5F104PJDFA R5F104PFGFA, R5F104PGGFA, R5F104PHGFA, R5F104PJGFA R5F104PKAFA, R5F104PLAFA R5F104PKGFA, R5F104PLGFA

JEITA Package Code	RENESAS Code	Previous Code	MASS (TYP.) [g]
P-LQFP100-14x20-0.65	PLQP0100JC-A	P100GF-65-GBN-1	0.92



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