



Welcome to [E-XFL.COM](#)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I <sup>2</sup> C, SIO, SSU, UART/USART
Peripherals	LED, POR, Voltage Detect, WDT
Number of I/O	13
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-LSSOP (0.173", 4.40mm Width)
Supplier Device Package	20-LSSOP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f211a4dsp-u0">https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f211a4dsp-u0</a>

## Notice

1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
2. Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
7. Renesas Electronics products are classified according to the following three quality grades: “Standard”, “High Quality”, and “Specific”. The recommended applications for each Renesas Electronics product depends on the product’s quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as “Specific” without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics product for any application for which it is not intended without the prior written consent of Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as “Specific” or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is “Standard” unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.
  - “Standard”: Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
  - “High Quality”: Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; safety equipment; and medical equipment not specifically designed for life support.
  - “Specific”: Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.

(Note 1) “Renesas Electronics” as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.

(Note 2) “Renesas Electronics product(s)” means any product developed or manufactured by or for Renesas Electronics.

## 1.2 Performance Overview

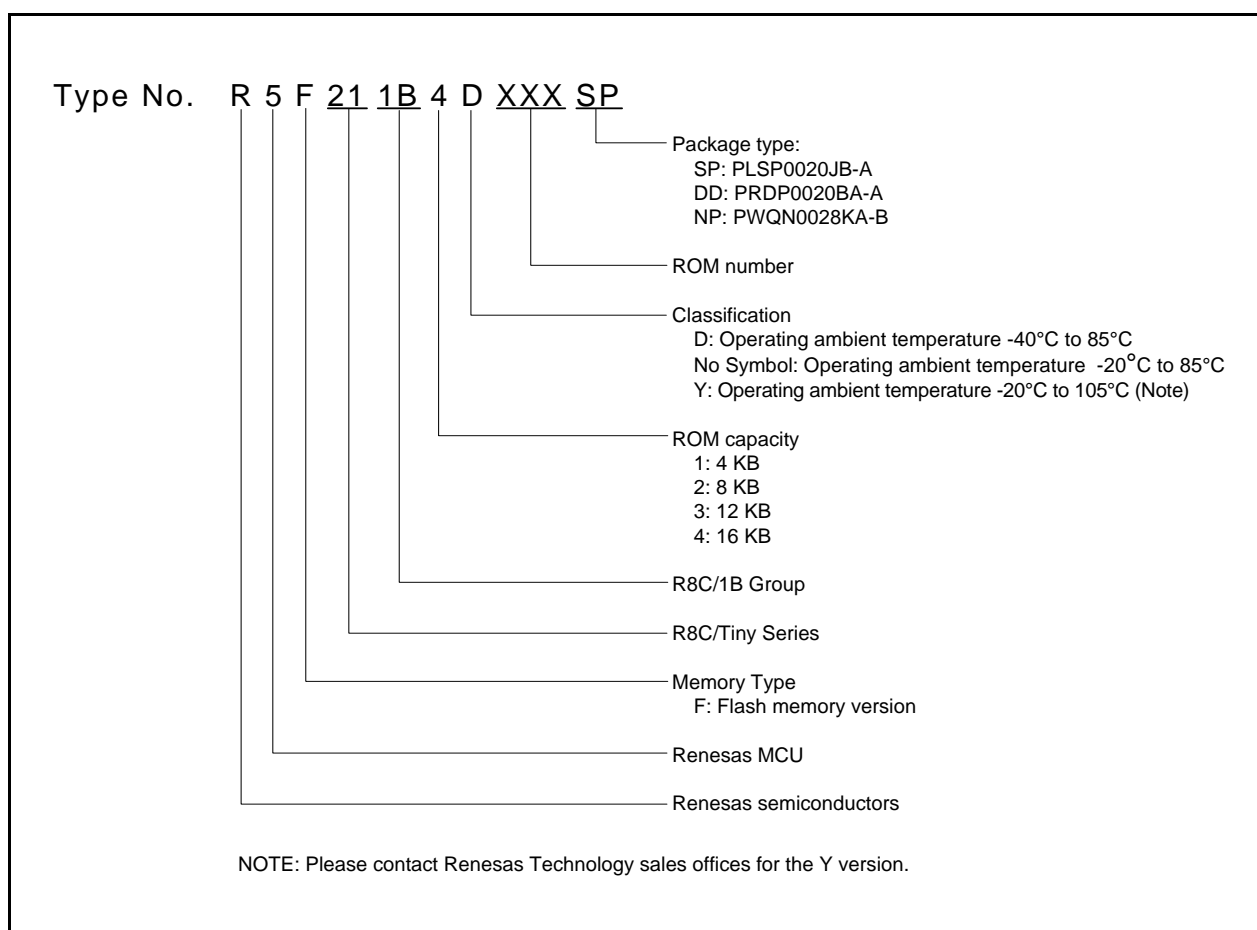
Table 1.1 outlines the Functions and Specifications for R8C/1A Group and Table 1.2 outlines the Functions and Specifications for R8C/1B Group.

**Table 1.1 Functions and Specifications for R8C/1A Group**

	Item	Specification
CPU	Number of fundamental instructions	89 instructions
	Minimum instruction execution time	50 ns ( $f(XIN) = 20$ MHz, $VCC = 3.0$ to $5.5$ V) 100 ns ( $f(XIN) = 10$ MHz, $VCC = 2.7$ to $5.5$ V)
	Operating mode	Single-chip
	Address space	1 Mbyte
	Memory capacity	See <b>Table 1.3 Product Information for R8C/1A Group</b>
Peripheral Functions	Ports	I/O ports: 13 pins (including LED drive port) Input port: 3 pins
	LED drive ports	I/O ports: 4 pins
	Timers	Timer X: 8 bits $\times$ 1 channel, timer Z: 8 bits $\times$ 1 channel (Each timer equipped with 8-bit prescaler) Timer C: 16 bits $\times$ 1 channel (Input capture and output compare circuits)
	Serial interfaces	1 channel Clock synchronous serial I/O, UART 1 channel UART
	Clock synchronous serial interface	1 channel I <sup>2</sup> C bus Interface <sup>(1)</sup> Clock synchronous serial I/O with chip select (SSU)
	A/D converter	10-bit A/D converter: 1 circuit, 4 channels
	Watchdog timer	15 bits $\times$ 1 channel (with prescaler) Reset start selectable, count source protection mode
	Interrupts	Internal: 11 sources, External: 4 sources, Software: 4 sources, Priority levels: 7 levels
	Clock generation circuits	2 circuits • Main clock oscillation circuit (with on-chip feedback resistor) • On-chip oscillator (high speed, low speed) High-speed on-chip oscillator has a frequency adjustment function
	Oscillation stop detection function	Main clock oscillation stop detection function
	Voltage detection circuit	On-chip
	Power-on reset circuit	On-chip
Electric Characteristics	Supply voltage	$VCC = 3.0$ to $5.5$ V ( $f(XIN) = 20$ MHz) $VCC = 2.7$ to $5.5$ V ( $f(XIN) = 10$ MHz)
	Current consumption	Typ. 9 mA ( $VCC = 5.0$ V, $f(XIN) = 20$ MHz, A/D converter stopped) Typ. 5 mA ( $VCC = 3.0$ V, $f(XIN) = 10$ MHz, A/D converter stopped) Typ. 35 $\mu$ A ( $VCC = 3.0$ V, wait mode, peripheral clock off) Typ. 0.7 $\mu$ A ( $VCC = 3.0$ V, stop mode)
Flash Memory	Programming and erasure voltage	$VCC = 2.7$ to $5.5$ V
	Programming and erasure endurance	100 times
Operating Ambient Temperature		-20 to 85°C
		-40 to 85°C (D version)
		-20 to 105°C (Y version) <sup>(2)</sup>
Package		20-pin molded-plastic LSSOP
		20-pin molded-plastic SDIP
		28-pin molded-plastic HWQFN

NOTE:

1. I<sup>2</sup>C bus is a trademark of Koninklijke Philips Electronics N. V.
2. Please contact Renesas Technology sales offices for the Y version.



**Figure 1.3** Type Number, Memory Size, and Package of R8C/1B Group

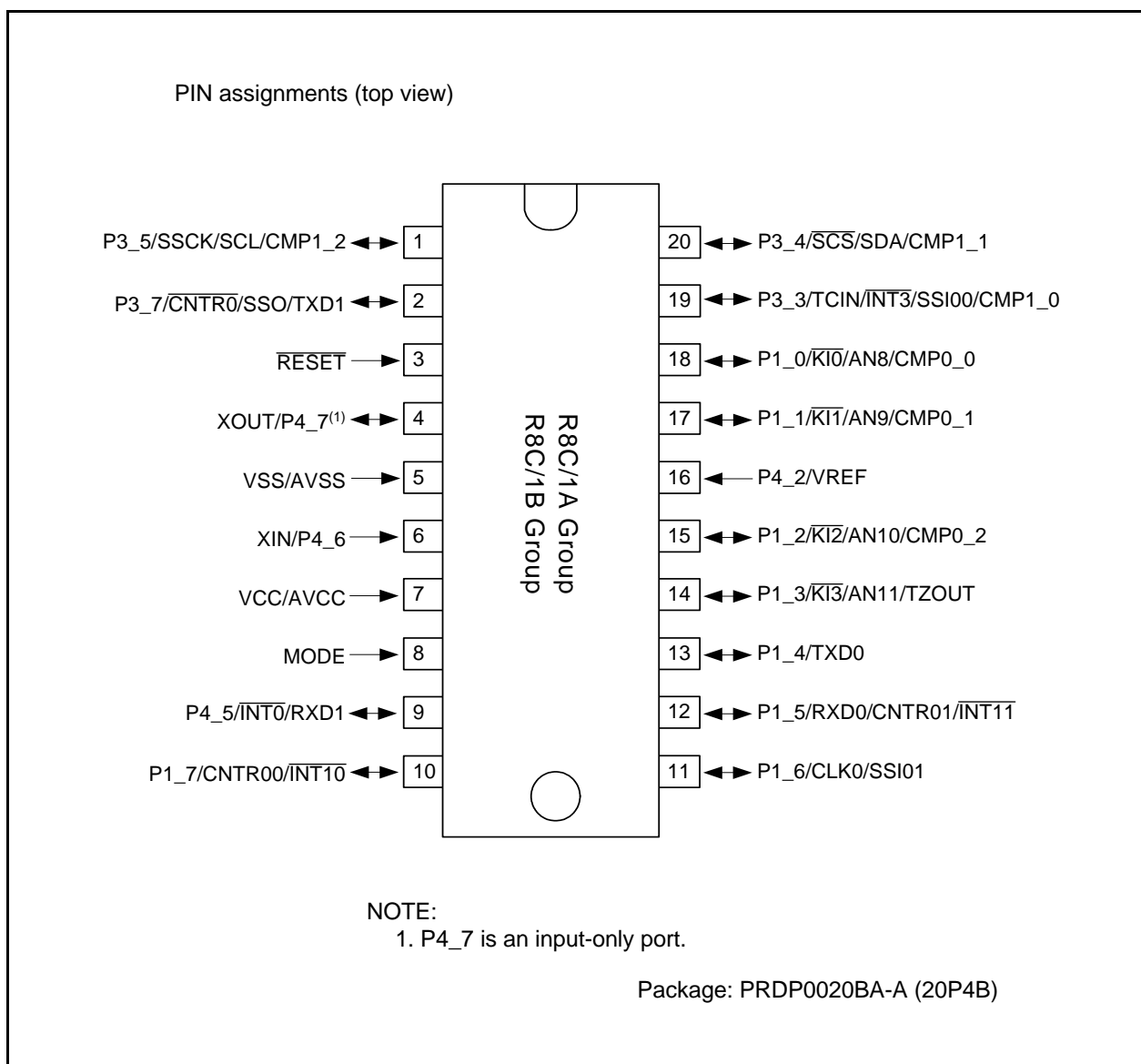


Figure 1.5 Pin Assignments for PRDP0020BA-A Package (Top View)

## 1.6 Pin Functions

Table 1.5 lists Pin Functions, Table 1.6 lists Pin Name Information by Pin Number of PLSP0020JB-A, PRDP0020BA-A Packages and Table 1.7 lists Pin Name Information by Pin Number of PWQN0028KA-B Package.

**Table 1.5 Pin Functions**

Type	Symbol	I/O Type	Description
Power Supply Input	VCC, VSS	I	Apply 2.7 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin.
Analog Power Supply Input	AVCC, AVSS	I	Power supply for the A/D converter Connect a capacitor between AVCC and AVSS.
Reset Input	RESET	I	Input "L" on this pin resets the MCU.
MODE	MODE	I	Connect this pin to VCC via a resistor.
Main Clock Input	XIN	I	These pins are provided for main clock generation circuit I/O. Connect a ceramic resonator or a crystal oscillator between the XIN and XOUT pins. To use an external clock, input it to the XIN pin and leave the XOUT pin open.
Main Clock Output	XOUT	O	
INT Interrupt	INT0, INT1, INT3	I	INT interrupt input pins
Key Input Interrupt	KI0 to KI3	I	Key input interrupt input pins
Timer X	CNTR0	I/O	Timer X I/O pin
	CNTR0	O	Timer X output pin
Timer Z	TZOUT	O	Timer Z output pin
Timer C	TCIN	I	Timer C input pin
	CMP0_0 to CMP0_2, CMP1_0 to CMP1_2	O	Timer C output pins
Serial Interface	CLK0	I/O	Transfer clock I/O pin
	RXD0, RXD1	I	Serial data input pins
	TXD0, TXD1	O	Serial data output pins
Clock synchronous serial I/O with chip select (SSU)	SSI00, SSI01	I/O	Data I/O pin.
	SCS	I/O	Chip-select signal I/O pin
	SSCK	I/O	Clock I/O pin
	SSO	I/O	Data I/O pin
I <sup>2</sup> C bus Interface	SCL	I/O	Clock I/O pin
	SDA	I/O	Data I/O pin
Reference Voltage Input	VREF	I	Reference voltage input pin to A/D converter
A/D Converter	AN8 to AN11	I	Analog input pins to A/D converter
I/O Port	P1_0 to P1_7, P3_3 to P3_5, P3_7, P4_5	I/O	CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually. Any port set to input can be set to use a pull-up resistor or not by a program. P1_0 to P1_3 also function as LED drive ports.
Input Port	P4_2, P4_6, P4_7	I	Input-only ports

I: Input      O: Output      I/O: Input and output

**Table 1.6 Pin Name Information by Pin Number of PLSP0020JB-A, PRDP0020BA-A Packages**

Pin Number	Control Pin	Port	I/O Pin Functions for Peripheral Modules					
			Interrupt	Timer	Serial Interface	Clock Synchronous Serial I/O with Chip Select	I <sup>2</sup> C bus Interface	A/D Converter
1		P3_5		CMP1_2		SSCK	SCL	
2		P3_7		CNTR0	TXD1	SSO		
3	RESET							
4	XOUT	P4_7						
5	VSS/AVSS							
6	XIN	P4_6						
7	VCC/AVCC							
8	MODE							
9		P4_5	INT0		RXD1			
10		P1_7	INT10	CNTR00				
11		P1_6			CLK0	SSI01		
12		P1_5	INT11	CNTR01	RXD0			
13		P1_4			TXD0			
14		P1_3	KI3	TZOUT				AN11
15		P1_2	KI2	CMP0_2				AN10
16	VREF	P4_2						
17		P1_1	KI1	CMP0_1				AN9
18		P1_0	KI0	CMP0_0				AN8
19		P3_3	INT3	TCIN/ CMP1_0		SSI00		
20		P3_4		CMP1_1		SCS	SDA	

**Table 1.7 Pin Name Information by Pin Number of PWQN0028KA-B Package**

Pin Number	Control Pin	Port	I/O Pin Functions for Peripheral Modules					
			Interrupt	Timer	Serial Interface	Clock Synchronous Serial I/O with Chip Select	I <sup>2</sup> C bus Interface	A/D Converter
1	NC							
2	XOUT	P4_7						
3	VSS/AVSS							
4	NC							
5	NC							
6	XIN	P4_6						
7	NC							
8	VCC/AVCC							
9	MODE							
10		P4_5	$\overline{\text{INT0}}$		RXD1			
11		P1_7	$\overline{\text{INT10}}$	CNTR00				
12		P1_6			CLK0	SSI01		
13		P1_5	$\overline{\text{INT11}}$	CNTR01	RXD0			
14		P1_4			TXD0			
15	NC							
16		P1_3	$\overline{\text{KI3}}$	TZOUT				AN11
17		P1_2	$\overline{\text{KI2}}$	CMP0_2				AN10
18	NC							
19	NC							
20	VREF	P4_2						
21	NC							
22		P1_1	$\overline{\text{KI1}}$	CMP0_1				AN9
23		P1_0	$\overline{\text{KI0}}$	CMP0_0				AN8
24		P3_3	$\overline{\text{INT3}}$	TCIN/CMP1_0		SSI00		
25		P3_4		CMP1_1		$\overline{\text{SCS}}$	SDA	
26		P3_5		CMP1_2		SSCK	SCL	
27		P3_7		$\overline{\text{CNTR0}}$	TXD1	SSO		
28	$\overline{\text{RESET}}$							



### **2.8.7 Interrupt Enable Flag (I)**

The I flag enables maskable interrupts.

Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

### **2.8.8 Stack Pointer Select Flag (U)**

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.

The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

### **2.8.9 Processor Interrupt Priority Level (IPL)**

IPL is 3 bits wide, assigns processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has higher priority than IPL, the interrupt is enabled.

### **2.8.10 Reserved Bit**

If necessary, set to 0. When read, the content is undefined.

### 3. Memory

#### 3.1 R8C/1A Group

Figure 3.1 is a Memory Map of R8C/1A Group. The R8C/1A Group has 1 Mbyte of address space from addresses 00000h to FFFFFh.

The internal ROM is allocated lower addresses, beginning with address 00000h. For example, a 16-Kbyte internal ROM area is allocated addresses 0C000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. They store the starting address of each interrupt routine.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 1-Kbyte internal RAM area is allocated addresses 00400h to 007FFh. The internal RAM is used not only for storing data but also for calling subroutines and as stacks when interrupt requests are acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh. The peripheral function control registers are allocated here. All addresses within the SFR, which have nothing allocated are reserved for future use and cannot be accessed by users.

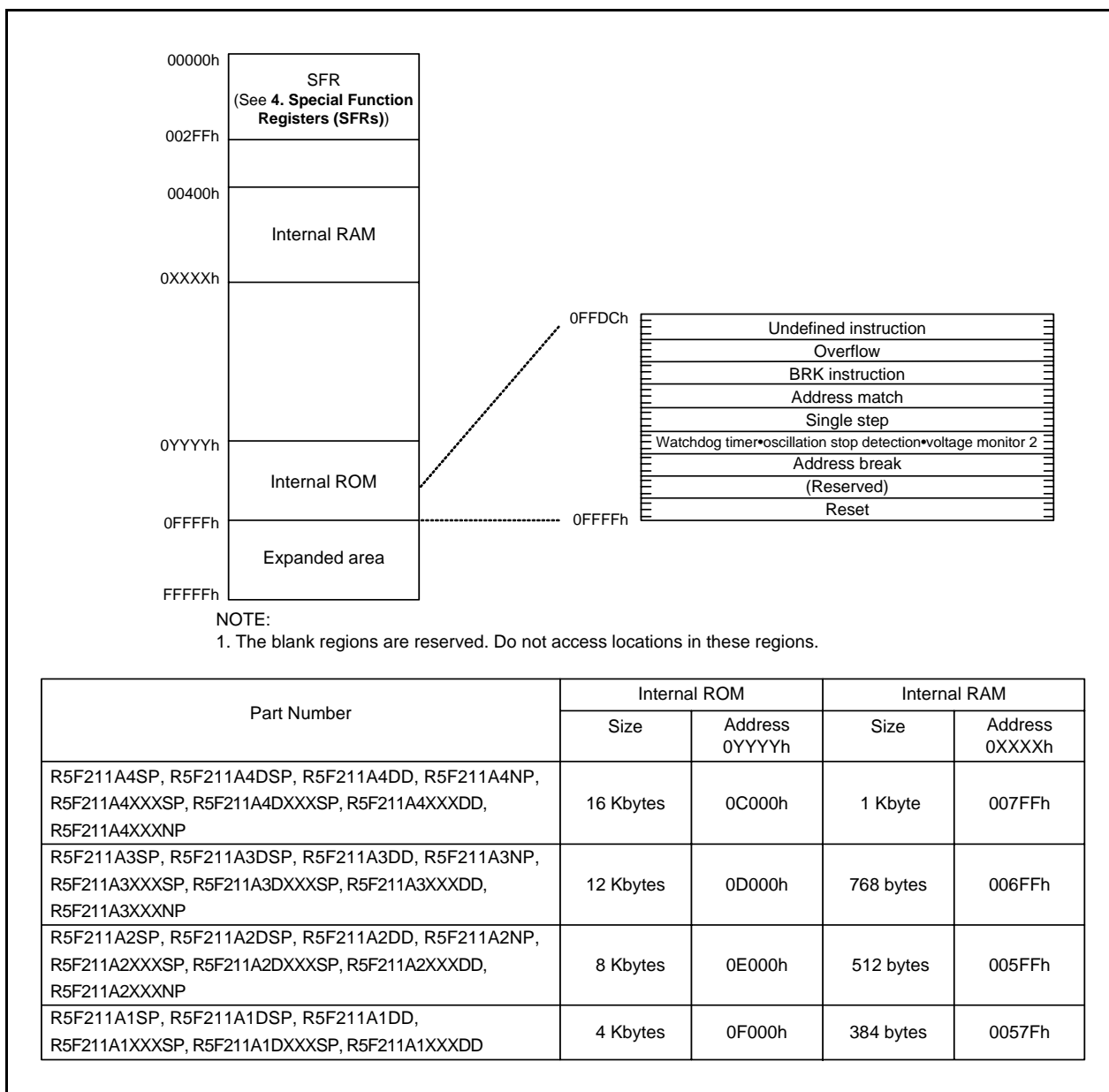


Figure 3.1 Memory Map of R8C/1A Group

### 3.2 R8C/1B Group

Figure 3.2 is a Memory Map of R8C/1B Group. The R8C/1B Group has 1 Mbyte of address space from addresses 00000h to FFFFFh.

The internal ROM (program ROM) is allocated lower addresses, beginning with address 0FFFFh. For example, a 16-Kbyte internal ROM area is allocated addresses 0C000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. They store the starting address of each interrupt routine.

The internal ROM (data flash) is allocated addresses 02400h to 02BFFh.

The internal RAM is allocated higher addresses beginning with address 00400h. For example, a 1-Kbyte internal RAM area is allocated addresses 00400h to 007FFh. The internal RAM is used not only for storing data but also for calling subroutines and as stacks when interrupt requests are acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh. The peripheral function control registers are allocated here. All addresses within the SFR, which have nothing allocated are reserved for future use and cannot be accessed by users.

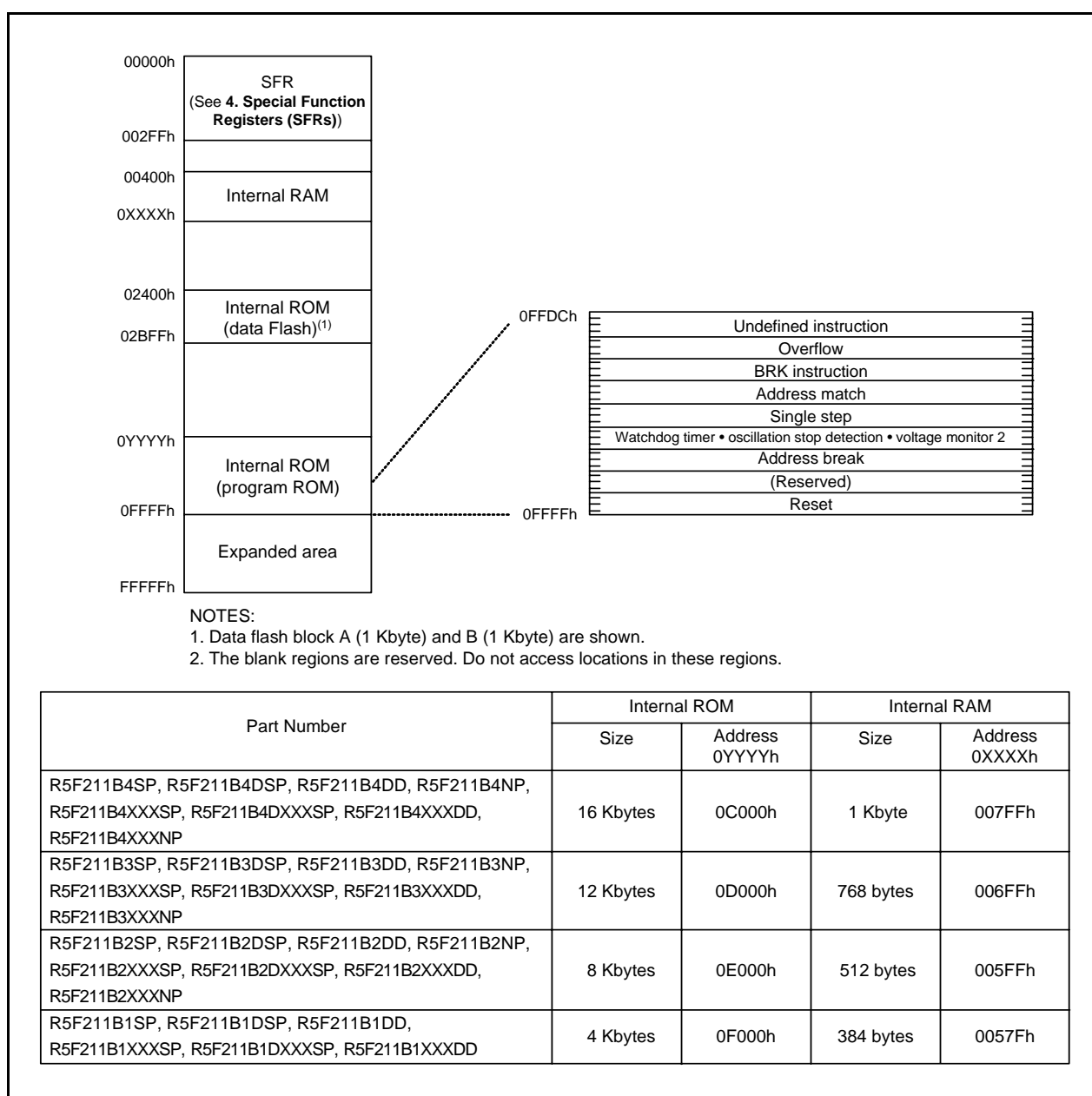


Figure 3.2 Memory Map of R8C/1B Group

**Table 4.2 SFR Information (2)<sup>(1)</sup>**

Address	Register	Symbol	After reset
0040h			
0041h			
0042h			
0043h			
0044h			
0045h			
0046h			
0047h			
0048h			
0049h			
004Ah			
004Bh			
004Ch			
004Dh	Key Input Interrupt Control Register	KUPIC	XXXXX000b
004Eh	A/D Conversion Interrupt Control Register	ADIC	XXXXX000b
004Fh	SSU/IIC Interrupt Control Register <sup>(2)</sup>	SSUAIC/IIC2AIC	XXXXX000b
0050h	Compare 1 Interrupt Control Register	CMP1IC	XXXXX000b
0051h	UART0 Transmit Interrupt Control Register	S0TIC	XXXXX000b
0052h	UART0 Receive Interrupt Control Register	S0RIC	XXXXX000b
0053h	UART1 Transmit Interrupt Control Register	S1TIC	XXXXX000b
0054h	UART1 Receive Interrupt Control Register	S1RIC	XXXXX000b
0055h			
0056h	Timer X Interrupt Control Register	TXIC	XXXXX000b
0057h			
0058h	Timer Z Interrupt Control Register	TZIC	XXXXX000b
0059h	INT1 Interrupt Control Register	INT1IC	XXXXX000b
005Ah	INT3 Interrupt Control Register	INT3IC	XXXXX000b
005Bh	Timer C Interrupt Control Register	TCIC	XXXXX000b
005Ch	Compare 0 Interrupt Control Register	CMP0IC	XXXXX000b
005Dh	INT0 Interrupt Control Register	INT0IC	XX00X000b
005Eh			
005Fh			
0060h			
0061h			
0062h			
0063h			
0064h			
0065h			
0066h			
0067h			
0068h			
0069h			
006Ah			
006Bh			
006Ch			
006Dh			
006Eh			
006Fh			
0070h			
0071h			
0072h			
0073h			
0074h			
0075h			
0076h			
0077h			
0078h			
0079h			
007Ah			
007Bh			
007Ch			
007Dh			
007Eh			
007Fh			

X: Undefined

**NOTES:**

1. The blank regions are reserved. Do not access locations in these regions.
2. Selected by the IICSEL bit in the PMR register.

**Table 4.4 SFR Information (4)(1)**

Address	Register	Symbol	After reset
00C0h	A/D Register	AD	XXh
00C1h			XXh
00C2h			
00C3h			
00C4h			
00C5h			
00C6h			
00C7h			
00C8h			
00C9h			
00CAh			
00CBh			
00CCh			
00CDh			
00CEh			
00CFh			
00D0h	A/D Control Register 2	ADCON2	00h
00D1h			
00D2h			
00D3h			
00D4h			
00D5h			
00D6h			
00D7h			
00D8h			
00D9h			
00DAh			
00DBh			
00DCh			
00DDh			
00DEh			
00DFh			
00E0h	A/D Control Register 0	ADCON0	00000XXb
00E1h			
00E2h			
00E3h			
00E4h			
00E5h			
00E6h			
00E7h			
00E8h			
00E9h			
00EAh			
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h	A/D Control Register 1	ADCON1	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00E0h	Port P1 Register	P1	XXh
00E1h			
00E2h			
00E3h			
00E4h			
00E5h			
00E6h			
00E7h			
00E8h			
00E9h			
00EAh			
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h	Port P1 Direction Register	PD1	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00E0h	Port P3 Register	P3	XXh
00E1h			
00E2h			
00E3h			
00E4h			
00E5h			
00E6h			
00E7h			
00E8h			
00E9h			
00EAh			
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h	Port P3 Direction Register	PD3	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00E0h	Port P4 Register	P4	XXh
00E1h			
00E2h			
00E3h			
00E4h			
00E5h			
00E6h			
00E7h			
00E8h			
00E9h			
00EAh			
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h	Port P4 Direction Register	PD4	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00F0h	Port Mode Register	PMR	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00F0h	Pull-Up Control Register 0	PUR0	00XX0000b
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00F0h	Pull-Up Control Register 1	PUR1	XXXXXX0Xb
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00F0h	Port P1 Drive Capacity Control Register	DRR	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
00F0h	Timer C Output Control Register	TCOUT	00h
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FCh			
00FDh			
00FEh			
00FFh			
01B3h	Flash Memory Control Register 4	FMR4	01000000b
01B4h			
01B5h	Flash Memory Control Register 1	FMR1	1000000Xb
01B6h			
01B7h	Flash Memory Control Register 0	FMR0	00000001b
0FFFh	Optional Function Select Register	OFS	(2)

X: Undefined

## NOTES:

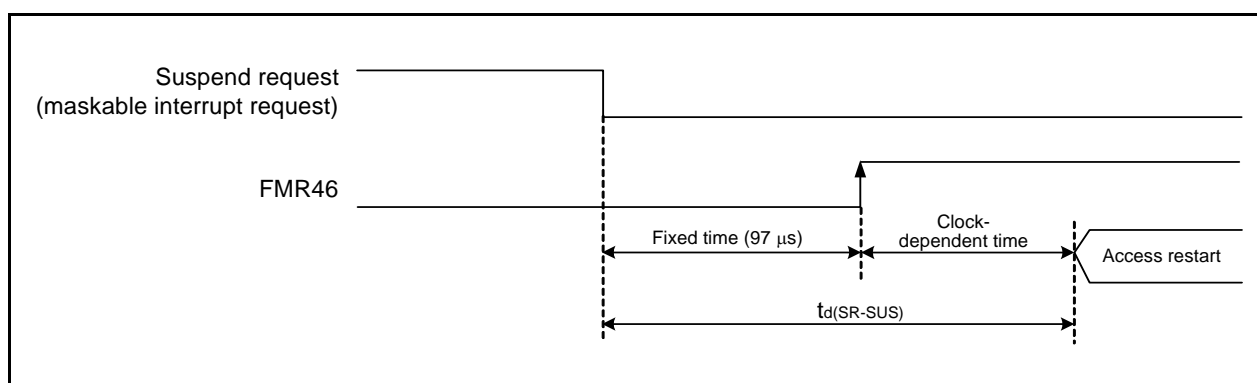
- Blank regions, 0100h to 01B2h and 01B8h to 02FFh are all reserved. Do not access locations in these regions.
- The OFS register cannot be changed by a user program. Use a flash programmer to write to it.

**Table 5.5 Flash Memory (Data flash Block A, Block B) Electrical Characteristics**

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
–	Program/erase endurance <sup>(2)</sup>		10,000 <sup>(3)</sup>	–	–	times
–	Byte program time (Program/erase endurance ≤ 1,000 times)		–	50	400	μs
–	Byte program time (Program/erase endurance > 1,000 times)		–	65	–	μs
–	Block erase time (Program/erase endurance ≤ 1,000 times)		–	0.2	9	s
–	Block erase time (Program/erase endurance > 1,000 times)		–	0.3	–	s
td(SR-SUS)	Time Delay from suspend request until suspend		–	–	97+CPU clock × 6 cycles	μs
–	Interval from erase start/restart until following suspend request		650	–	–	μs
–	Interval from program start/restart until following suspend request		0	–	–	ns
–	Time from suspend until program/erase restart		–	–	3+CPU clock × 4 cycles	μs
–	Program, erase voltage		2.7	–	5.5	V
–	Read voltage		2.7	–	5.5	V
–	Program, erase temperature		-20 <sup>(8)</sup>	–	85	°C
–	Data hold time <sup>(9)</sup>	Ambient temperature = 55 °C	20	–	–	year

## NOTES:

1. VCC = 2.7 to 5.5 V at T<sub>opr</sub> = –20 to 85 °C / –40 to 85 °C, unless otherwise specified.
2. Definition of programming/erasure endurance  
The programming and erasure endurance is defined on a per-block basis.  
If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one. However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
4. If emergency processing is required, a suspend request can be generated independent of this characteristic. In that case the normal time delay to suspend can be applied to the request. However, we recommend that a suspend request with an interval of less than 650 μs is only used once because, if the suspend state continues, erasure cannot operate and the incidence of erasure error rises.
5. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.
6. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
7. Customers desiring programming/erasure failure rate information should contact their Renesas technical support representative.
8. –40 °C for D version.
9. The data hold time includes time that the power supply is off or the clock is not supplied.

**Figure 5.2 Transition Time to Suspend****Table 5.6 Voltage Detection 1 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det1</sub>	Voltage detection level <sup>(3)</sup>		2.70	2.85	3.00	V
—	Voltage detection circuit self power consumption	VCA26 = 1, V <sub>CC</sub> = 5.0 V	—	600	—	nA
t <sub>d</sub> (E-A)	Waiting time until voltage detection circuit operation starts <sup>(2)</sup>		—	—	100	μs
V <sub>ccmin</sub>	MCU operating voltage minimum value		2.7	—	—	V

## NOTES:

1. The measurement condition is V<sub>CC</sub> = 2.7 V to 5.5 V and T<sub>opr</sub> = -40°C to 85 °C.
2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.
3. Ensure that V<sub>det2</sub> > V<sub>det1</sub>.

**Table 5.7 Voltage Detection 2 Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>det2</sub>	Voltage detection level <sup>(4)</sup>		3.00	3.30	3.60	V
—	Voltage monitor 2 interrupt request generation time <sup>(2)</sup>		—	40	—	μs
—	Voltage detection circuit self power consumption	VCA27 = 1, V <sub>CC</sub> = 5.0 V	—	600	—	nA
t <sub>d</sub> (E-A)	Waiting time until voltage detection circuit operation starts <sup>(3)</sup>		—	—	100	μs

## NOTES:

1. The measurement condition is V<sub>CC</sub> = 2.7 V to 5.5 V and T<sub>opr</sub> = -40°C to 85 °C.
2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes V<sub>det2</sub>.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.
4. Ensure that V<sub>det2</sub> > V<sub>det1</sub>.

**Table 5.8 Reset Circuit Electrical Characteristics (When Using Voltage Monitor 1 Reset)**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>por2</sub>	Power-on reset valid voltage	-20°C ≤ Topr ≤ 85°C	—	—	V <sub>det1</sub>	V
tw(V <sub>por2</sub> -V <sub>det1</sub> )	Supply voltage rising time when power-on reset is deasserted <sup>(1)</sup>	-20°C ≤ Topr ≤ 85°C, tw(por2) ≥ 0s <sup>(3)</sup>	—	—	100	ms

## NOTES:

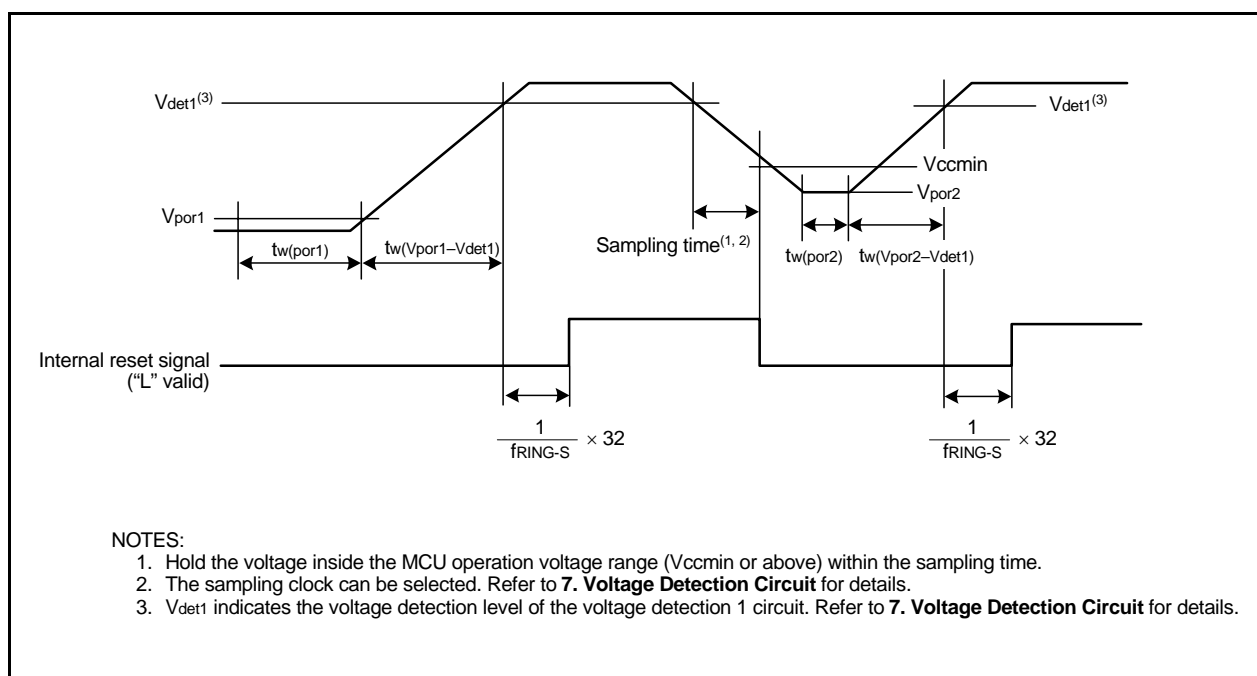
1. This condition is not applicable when using with V<sub>cc</sub> ≥ 1.0 V.
2. When turning power on after the time to hold the external power below effective voltage (V<sub>por1</sub>) exceeds 10 s, refer to **Table 5.9 Reset Circuit Electrical Characteristics (When Not Using Voltage Monitor 1 Reset)**.
3. tw(por2) is the time to hold the external power below effective voltage (V<sub>por2</sub>).

**Table 5.9 Reset Circuit Electrical Characteristics (When Not Using Voltage Monitor 1 Reset)**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V <sub>por1</sub>	Power-on reset valid voltage	-20°C ≤ Topr ≤ 85°C	—	—	0.1	V
tw(V <sub>por1</sub> -V <sub>det1</sub> )	Supply voltage rising time when power-on reset is deasserted	0°C ≤ Topr ≤ 85°C, tw(por1) ≥ 10 s <sup>(2)</sup>	—	—	100	ms
tw(V <sub>por1</sub> -V <sub>det1</sub> )	Supply voltage rising time when power-on reset is deasserted	-20°C ≤ Topr < 0°C, tw(por1) ≥ 30 s <sup>(2)</sup>	—	—	100	ms
tw(V <sub>por1</sub> -V <sub>det1</sub> )	Supply voltage rising time when power-on reset is deasserted	-20°C ≤ Topr < 0°C, tw(por1) ≥ 10 s <sup>(2)</sup>	—	—	1	ms
tw(V <sub>por1</sub> -V <sub>det1</sub> )	Supply voltage rising time when power-on reset is deasserted	0°C ≤ Topr ≤ 85°C, tw(por1) ≥ 1 s <sup>(2)</sup>	—	—	0.5	ms

## NOTES:

1. When not using voltage monitor 1, use with V<sub>cc</sub> ≥ 2.7 V.
2. tw(por1) is the time to hold the external power below effective voltage (V<sub>por1</sub>).

**Figure 5.3 Reset Circuit Electrical Characteristics**



**Table 5.10 High-Speed On-Chip Oscillator Circuit Electrical Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
—	High-speed on-chip oscillator frequency when the reset is deasserted	$V_{CC} = 5.0 \text{ V}$ , $T_{opr} = 25 \text{ }^{\circ}\text{C}$	—	8	—	MHz
—	High-speed on-chip oscillator frequency temperature • supply voltage dependence <sup>(2)</sup>	0 to +60 $^{\circ}\text{C}$ /5 V $\pm$ 5 % <sup>(3)</sup>	7.76	—	8.24	MHz
		-20 to +85 $^{\circ}\text{C}$ /2.7 to 5.5 V <sup>(3)</sup>	7.68	—	8.32	MHz
		-40 to +85 $^{\circ}\text{C}$ /2.7 to 5.5 V <sup>(3)</sup>	7.44	—	8.32	MHz

## NOTES:

1. The measurement condition is  $V_{CC} = 5.0 \text{ V}$  and  $T_{opr} = 25 \text{ }^{\circ}\text{C}$ .
2. Refer to **10.6.4 High-Speed On-Chip Oscillator Clock** for notes on high-speed on-chip oscillator clock.
3. The standard value shows when the HRA1 register is assumed as the value in shipping and the HRA2 register value is set to 00h.

**Table 5.11 Power Supply Circuit Timing Characteristics**

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
$t_{d(P-R)}$	Time for internal power supply stabilization during power-on <sup>(2)</sup>		1	—	2000	$\mu\text{s}$
$t_{d(R-S)}$	STOP exit time <sup>(3)</sup>		—	—	150	$\mu\text{s}$

## NOTES:

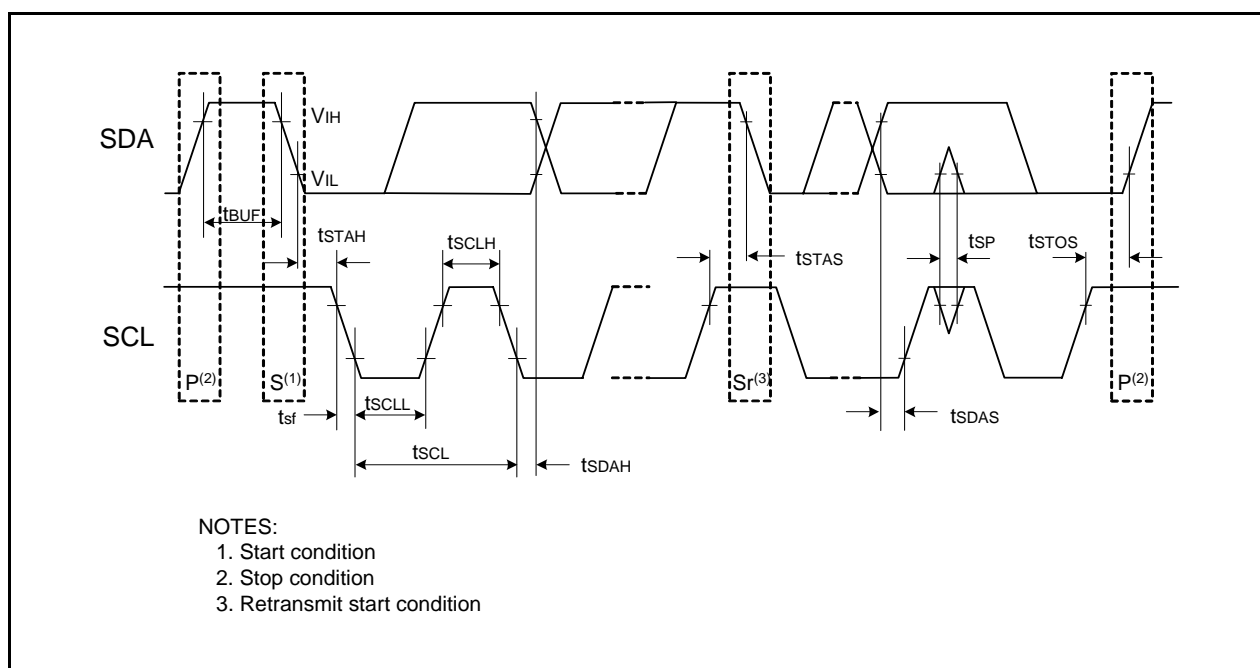
1. The measurement condition is  $V_{CC} = 2.7 \text{ to } 5.5 \text{ V}$  and  $T_{opr} = 25 \text{ }^{\circ}\text{C}$ .
2. Waiting time until the internal power supply generation circuit stabilizes during power-on.
3. Time until CPU clock supply starts after the interrupt is acknowledged to exit stop mode.

**Table 5.13** Timing Requirements of I<sup>2</sup>C bus Interface (1)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
t <sub>SCL</sub>	SCL input cycle time		12t <sub>CYC</sub> +600 <sup>(2)</sup>	—	—	ns
t <sub>SCLH</sub>	SCL input "H" width		3t <sub>CYC</sub> +300 <sup>(2)</sup>	—	—	ns
t <sub>SCLL</sub>	SCL input "L" width		5t <sub>CYC</sub> +300 <sup>(2)</sup>	—	—	ns
t <sub>sf</sub>	SCL, SDA input fall time		—	—	300	ns
t <sub>SP</sub>	SCL, SDA input spike pulse rejection time		—	—	1t <sub>CYC</sub> <sup>(2)</sup>	ns
t <sub>BUF</sub>	SDA input bus-free time		5t <sub>CYC</sub> <sup>(2)</sup>	—	—	ns
t <sub>STAH</sub>	Start condition input hold time		3t <sub>CYC</sub> <sup>(2)</sup>	—	—	ns
t <sub>STAS</sub>	Retransmit start condition input setup time		3t <sub>CYC</sub> <sup>(2)</sup>	—	—	ns
t <sub>STOS</sub>	Stop condition input setup time		3t <sub>CYC</sub> <sup>(2)</sup>	—	—	ns
t <sub>SDAS</sub>	Data input setup time		1t <sub>CYC</sub> +20 <sup>(2)</sup>	—	—	ns
t <sub>SDAH</sub>	Data input hold time		0	—	—	ns

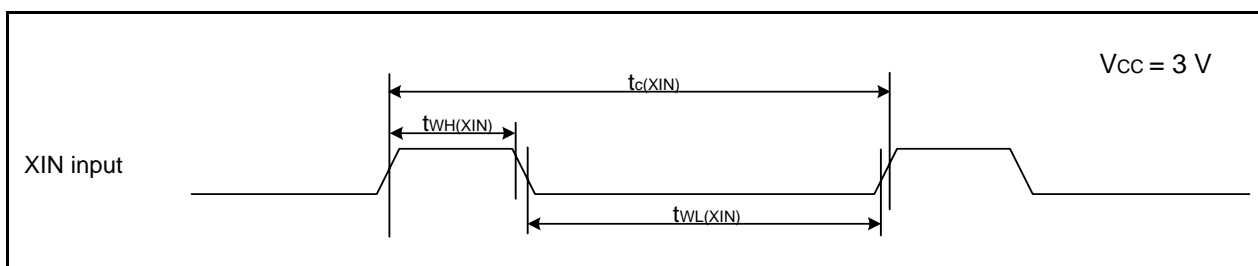
## NOTES:

1. V<sub>CC</sub> = 2.7 to 5.5 V, V<sub>SS</sub> = 0 V and T<sub>a</sub> = -20 to 85 °C / -40 to 85 °C, unless otherwise specified.
2. 1t<sub>CYC</sub> = 1/f<sub>1</sub>(s)

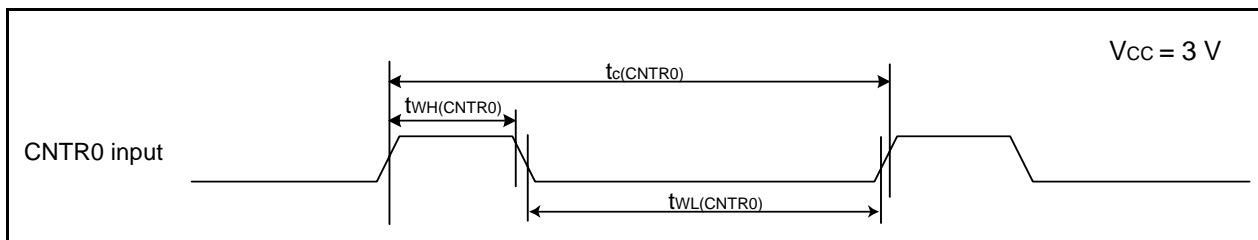
**Figure 5.7** I/O Timing of I<sup>2</sup>C bus Interface

**Timing requirements (Unless Otherwise Specified:  $V_{CC} = 3\text{ V}$ ,  $V_{SS} = 0\text{ V}$  at  $T_a = 25\text{ }^{\circ}\text{C}$ ) [ $V_{CC} = 3\text{ V}$ ]****Table 5.23 XIN Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{XIN})$	XIN input cycle time	100	—	ns
$t_{WH}(\text{XIN})$	XIN input "H" width	40	—	ns
$t_{WL}(\text{XIN})$	XIN input "L" width	40	—	ns

**Figure 5.13 XIN Input Timing Diagram when  $V_{CC} = 3\text{ V}$** **Table 5.24 CNTR0 Input, CNTR1 Input,  $\overline{\text{INT1}}$  Input**

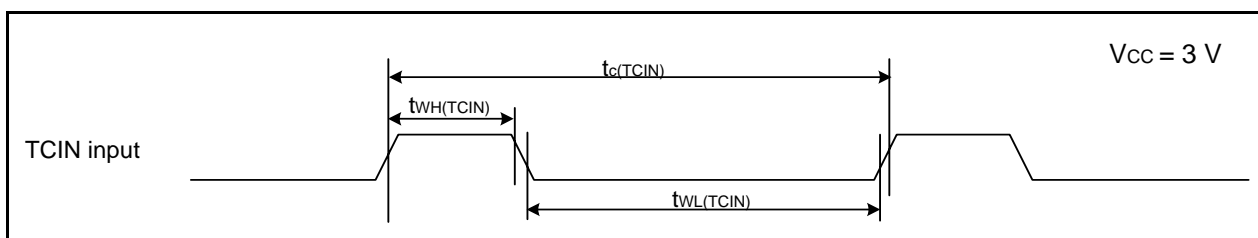
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{CNTR0})$	CNTR0 input cycle time	300	—	ns
$t_{WH}(\text{CNTR0})$	CNTR0 input "H" width	120	—	ns
$t_{WL}(\text{CNTR0})$	CNTR0 input "L" width	120	—	ns

**Figure 5.14 CNTR0 Input, CNTR1 Input,  $\overline{\text{INT1}}$  Input Timing Diagram when  $V_{CC} = 3\text{ V}$** **Table 5.25 TCIN Input,  $\overline{\text{INT3}}$  Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_c(\text{TCIN})$	TCIN input cycle time	1,200 <sup>(1)</sup>	—	ns
$t_{WH}(\text{TCIN})$	TCIN input "H" width	600 <sup>(2)</sup>	—	ns
$t_{WL}(\text{TCIN})$	TCIN input "L" width	600 <sup>(2)</sup>	—	ns

**NOTES:**

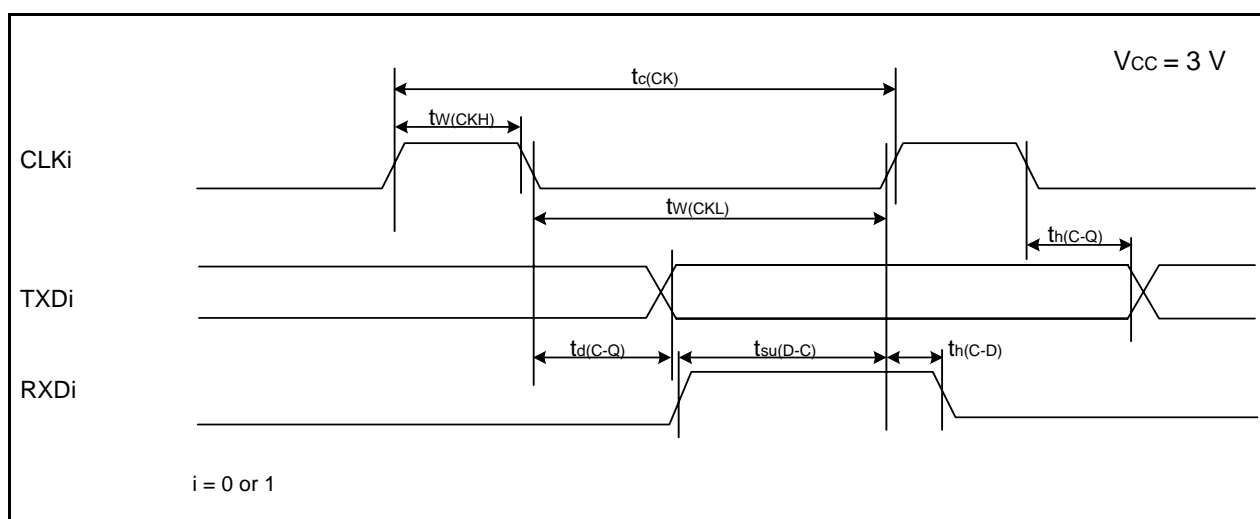
1. When using the timer C input capture mode, adjust the cycle time to (1/timer C count source frequency x 3) or above.
2. When using the timer C input capture mode, adjust the width to (1/timer C count source frequency x 1.5) or above.

**Figure 5.15 TCIN Input,  $\overline{\text{INT3}}$  Input Timing Diagram when  $V_{CC} = 3\text{ V}$**

**Table 5.26 Serial Interface**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	300	—	ns
$t_{w(CKH)}$	CLKi input “H” width	150	—	ns
$t_{w(CKL)}$	CLKi input “L” width	150	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	80	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	70	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	ns

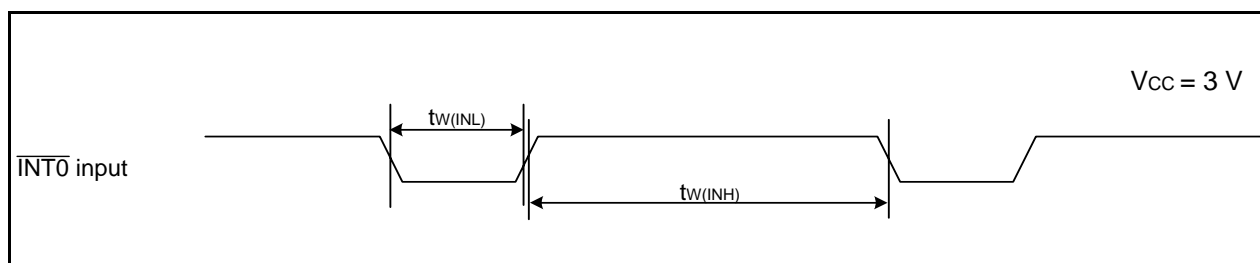
i = 0 or 1

**Figure 5.16 Serial Interface Timing Diagram when Vcc = 3 V****Table 5.27 External Interrupt  $\overline{INT0}$  Input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{INT0}$ input “H” width	380 <sup>(1)</sup>	—	ns
$t_{w(INL)}$	$\overline{INT0}$ input “L” width	380 <sup>(2)</sup>	—	ns

**NOTES:**

1. When selecting the digital filter by the  $\overline{INT0}$  input filter select bit, use an  $\overline{INT0}$  input HIGH width of either (1/digital filter clock frequency x 3) or the minimum value of standard, whichever is greater
2. When selecting the digital filter by the  $\overline{INT0}$  input filter select bit, use an  $\overline{INT0}$  input LOW width of either (1/digital filter clock frequency x 3) or the minimum value of standard, whichever is greater

**Figure 5.17 External Interrupt  $\overline{INT0}$  Input Timing Diagram when Vcc = 3 V**

## Package Dimensions

Diagrams showing the latest package dimensions and mounting information are available in the “Packages” section of the Renesas Technology website.

