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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	20MHz
Connectivity	EBI/EMI, UART/USART
Peripherals	-
Number of I/O	24
Program Memory Size	-
Program Memory Type	ROMIess
EEPROM Size	-
RAM Size	236 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z86c9320fsc

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# PIN DESCRIPTION (Continued)

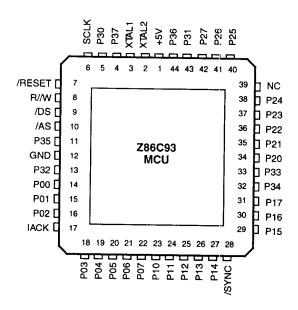


Figure 4. 44-Pin PLCC

Table 2. 44-Pin PLCC Pin Identification

No	Symbol	Function	Direction	No	Symbol	Function	Direction
1	V <sub>cc</sub>	Power Supply	Input	14-16	P00-P02	Port 0 pin 0,1,2	In/Output
2	XTĂĽ2	Crystal, Osc. Clock	Output	17	IACK	Int. Acknowledge	Output
3	XTAL1	Crystal, Osc. Clock	Input	18-22	P03-P07	Port 0 pin 3,4,5,6,7	In/Output
4	P37	Port 3 pin 7	Output	23-27	P10-P14	Port 1 pin 0,1,2,3,4	In/Output
5	P30	Port 3 pin 0	Input	28	/SYNC	Synchronize Pin	Output
6	SCLK	System Clock	Output	29-31	P15-P17	Port 1 pin 5,6,7	In/Output
7	/RESET	Reset	Input	32	P34	Port 3 pin 4	Output
8	R//W	Read/Write	Output	33	P33	Port 3 pin 3	Input
9	/DS	Data Strobe	Output	34-38	P20-P24	Port 2 pin 0,1,2,3,4	In/Output
10	/AS	Address Strobe	Output	39	N/C	Not Connected (20 MH	
11	P35	Port 3 pin 5	Output		M/AIT	WAIT (25 or 33 MHz)	Input
12	GND	Ground GND	Input	40-42	P25-P27	Port 2 pin 5,6,7	In/Output
13	P32	Port 3 pin 2	Input	43	P31	Port 3 pin 1	Input
		<del></del>		44	P36	Port 3 pin 6	Output

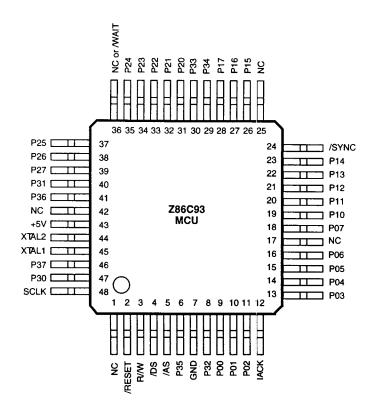


Figure 6. 48-Pin VQFP Package

Table 4. 48-Pin VQFP Pin Identification

No	Symbol	Function	Direction	No	Symbol	Function	Direction
1	N/C	Not Connected	Input	25	N/C	Not Connected	Input
2	/RESET	Reset	Input	26-28	P15-P17	Port 1 pin 5,6,7	In/Output
3	R/W	Read/Write	Output	29	F34	Port 3 pin 4	Output
4	/DS	Data Strobe	Output	30	P33	Port 3 pin 33	Input
5	/AS	Address Strobe	Output	31-35	P20-P24	Port 2 pin 0,1,2,3,4	In/Output
6	P35	Port 3 pin 5	Input	36	N/C	Not Connected (20 MH	lz)Input
7	GND	Ground GND	Input		M/AIT	WAIT (25 or 33 MHz)	Input
8	P32	Port 3 pin 2	Input	37-39	P25-P27	Port 2 pin 5,6,7	In/Output
9-11	P00-P02	Port 0 pin 3,4,5,6	In/Output	40	F31	Port 3 pin 1	Input
12	IACK	Int. Acknowledge	Output	41	P36	Port 3 pin 6	Output
13-16	P03-P06	Port O pin 2.4 5.6	In/Output	42	N/C	Not Connected	Input
13-16	N/C	Port 0 pin 3,4,5,6 Not Connected	Input	43	V <sub>cc</sub>	Power Supply	Input
18	P07	Port 0 pin 7	In/Output	44	XTAL2	Crystal, Osc. Clock	Output
19-23	P10-P14	Port 1 pin 0,1,2,3,4	In/Output	45	XTAL1	Crystal, Osc. Clock	Input
24	/SYNC				P37	Port 3 pin 7	Output
	JOTING	Synchionize Fin	Synchronize Pin Output 46		P30	Port 3 pin 0	Input
				47		,	1
				48	SCLK	System Clock	Output

### **PIN FUNCTIONS**

/DS. (output, active Low). Data Strobe is activated once for each external memory transfer. For a READ operation, data must be available prior to the trailing edge of /DS. For WRITE operations, the falling edge of /DS indicates that output data is valid.

/AS. (output, active Low). Address Strobe is pulsed once at the beginning of each machine cycle. Address output is via Port 1 for all external programs. When /RESET is asserted, /AS toggles. Memory address transfers are valid at the trailing edge of /AS.

XTAL1, XTAL2. Crystal 1, Crystal 2(time-based input and output, respectively). These pins connect a parallel-resonant crystal, ceramic resonator, LC, or any external single-phase clock to the on-chip oscillator and buffer.

R/W. (output, read High/write Low). The Read/Write signal is Low when the MCU is writing to the external program or data memory. It is High when the MCU is reading from the external program or data memory.

/RESET. (input, active Low). To avoid asynchronous and noisy reset problems, the Z86C93 is equipped with a reset filter of four external clocks (4TpC). If the external /RESET signal is less than 4TpC in duration, no reset occurs.

On the 5th clock after the /RESET is detected, an internal RST signal is latched and held for an internal register count of 18 external clocks, or for the duration of the external /RESET, whichever is longer. During the reset cycle, /DS is held active Low while /AS cycles at a rate of 2TpC. When /RESET is deactivated, program execution begins at location 000CH. Reset time must be held Low for 50 ms or until  $\rm V_{cc}$  is stable, whichever is longer.

SCLK. System Clock (output). The internal system clock is available at this pin. Available in the PLCC, QFP and VQFP packages only.

IACK. Interrupt Acknowledge (output, active High). This output, when High, indicates that the Z86C93 is in an interrupt cycle. Available in the PLCC, QFP and VQFP packages only.

/SYNC. (output, active Low). This signal indicates the last clock cycle of the currently executing instruction. Available in the PLCC, QFP and VQFP packages only.

WAIT. (input, active Low). Introduces asynchronous wait states into the external memory fetch cycle. When this inut goes Low during an external memory access, the Z86C93 freezes the fetch cycle until tis pin goes High. This pin is sampled after /DS goes Low; should be pulled up if not used. Available in the 25 MHz and 33 MHz devices only.

Port 0 P00-P07. Port 0 is an 8-bit, nibble programmable, bidirectional, TTL compatible port. These eight I/O lines can be configured under software control as a nibble I/O port, or as an address port for interfacing external memory. When used as an I/O port, Port 0 may be placed under handshake control. In this configuration, Port 3, lines P32 and P35 are used as the handshake control /DAV0 and RDY0 (Data Available and Ready). Handshake signal assignment is dictated by the I/O direction of the upper nibble P04-P07. The lower nibble must have the same direction as the upper nibble to be under handshake control. Port 0 comes up as A15-A8 Address lines after /RESET.

For external memory references, Port 0 can provide address bits A11-A8 (lower nibble) or A15-A8 (lower and upper nibble) depending on the required address space. If the address range requires 12 bits or less, the upper nibble of Port 0 can be programmed independently as I/O while the lower nibble is used for addressing. If one or both nibbles are needed for I/O operation, they must be configured by writing to the Port 0 Mode register. After a hardware reset, Port 0 lines are defined as address lines A15-A8, and extended timing is set to accommodate slow memory access. The initialization routine can include reconfiguration to eliminate this extended timing mode (Figure 7). The /OEN (Output Enable) signal in Figure 7 is an internal signal.

The Auto Latch on Port 0 puts valid CMOS levels on all CMOS inputs which are not externally driven. Whether this level is 0 or 1, cannot be determined. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer.

Port 2. (P20-P27). Port 2 is an 8-bit, bit programmable, bidirectional, TTL compatible port. Each of these eight I/O lines can be independently programmed as an input or output or globally as an open-drain output. Port 2 is always available for I/O operation. When used as an I/O port, Port 2 is placed under handshake control. In this configuration, Port 3 lines P31 and P36 are used as the handshake control lines /DAV2 and RDY2. The handshake signal

assignment for Port 3 lines P31 and P36 is dictated by the direction (input or output) assigned to P27 (Figure 9).

The Auto Latch on Port 2 puts valid CMOS levels on all CMOS inputs which are not externally driven. Whether this level is 0 or 1, cannot be determined. A valid CMOS level, rather than a floating node, reduces excessive supply current flow in the input buffer.

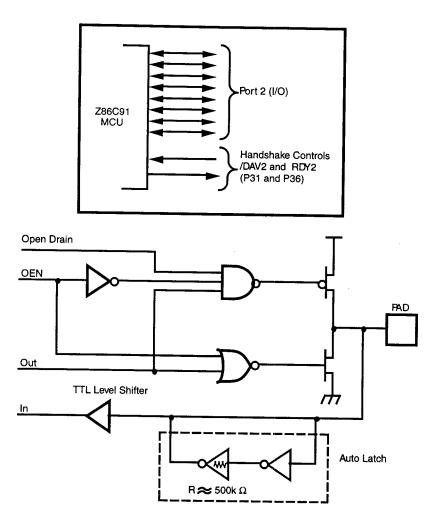
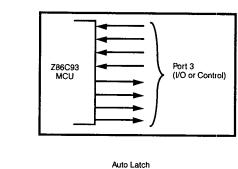


Figure 9. Port 2 Configuration

Port 3 P30-P37. Port 3 is an 8-bit, TTL compatible four fixed input and four fixed output ports. These eight I/O lines have four fixed (P30-P33) input and four fixed (P34-P37) output

ports. Port 3 pins P30 and P37 when used as serial I/O, are programmed as serial in and serial out, respectively (Figure 10 and Table 5).



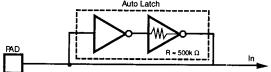


Figure 10. Port 3 Configuration

Table 5. Port 3 Pin Assignments

Pin#	1/0	CTC1	Int.	P0HS	P2HS	UART	Ext.
P30	ln		IRQ3			Serial In	
P31	In	T <sub>IN</sub>	IRQ2		D/R		
P32	ln		IRQ0	D/R			
P33	In		IRQ1				
P34	Out						DM
P35	Out			R/D			
P36	Out	Tout		, –	R/D		
P37	Out	001			. ,, &	Serial Out	

Port 3 is configured under software control to provide the following control functions: handshake for Ports 0 and 2 (/DAV and RDY); four external interrupt request signals (IRQ0-IRQ3); timer input and output signals ( $T_{IN}$  and  $T_{OUT}$ ), and Data Memory Select (/DM).

Port 3 lines P30 and P37 can be programmed as serial I/O lines for full-duplex serial asynchronous receiver/transmitter operation. The bit rate is controlled by the Counter/Timer 0.

The Z86C93 automatically adds a start bit and two stop bits to transmitted data (Figure 10). Odd parity is also available as an option. Eight data bits are always transmitted,

regardless of parity selection. If parity is enabled, the eighth bit is the odd parity bit. An interrupt request (IRQ4) is generated on all transmitted characters.

Received data must have a start bit, eight data bits and at least one stop bit. If parity is on, bit 7 of the received data is replaced by a parity error flag. Received characters generate the IRQ3 interrupt request.

The Auto Latch on Port 3 puts a valid CMOS level on all CMOS inputs that are not externally driven. Whether this level is zero or one, cannot be determined. A valid CMOS level rather than a floating node reduces excessive supply current flow in the input buffer.

## PIN FUNCTIONS (Continued)

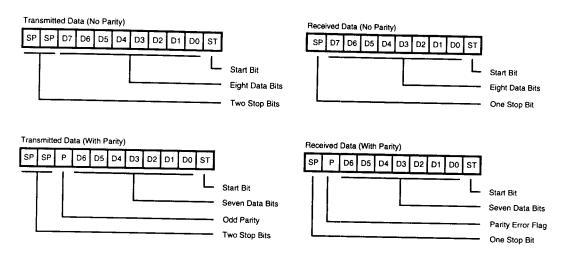


Figure 11. Serial Data Formats

### **ADDRESS SPACE**

Program Memory. The Z86C93 can address up to 64 Kbytes of external program memory. Program execution begins at external location 000CH after a reset.

Data Memory. The Z96C93 can address up to 64 Kbytes of external data memory. External data memory is included with, or separated from, the external program memory

space. /DM, an optional I/O function that can be programmed to appear on pin P34 is used to distinguish between data and program memory space (Figure 12). The state of the /DM signal is controlled by the type instruction being executed. An LDC opcode references PROGRAM (/DM inactive) memory, and an LDE instruction references DATA (/DM active Low) memory.

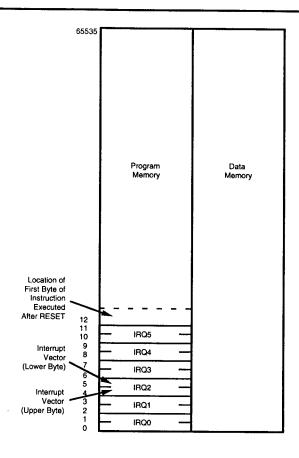


Figure 12. Program and Data Memory Configuration

Expanded Register File. The register file has been expanded to allow for additional system control registers, and for mapping of additional peripheral devices along with I/O ports into the register address area (Figure 13). The Z8 register address space R0 through R15 has now been implemented as 16 groups of 16 registers per group. These register groups are known as the ERF (Expanded Register File). Bits 7-4 of register RP select the working register group. Bits 3-0 of register RP select the expanded register group (Figure 14). The registers that are used in the multiply/divide unit reside in the Expanded Register File at Bank E and those for the additional timer control words reside in Bank D. The rest of the Expanded Register is not physically implemented and is open for future expansion.

Register File. The Register File consists of four I/O port registers, 236 general-purpose registers and 16 control

and status registers. The instructions can access registers directly or indirectly via an 8-bit address field. The Z86C93 also allows short 4-bit register addressing using the Register Pointer (Figure 15). In the 4-bit mode, the Register File is divided into 16 working register groups, each occupying 16 continuous locations. The Register Pointer addresses the starting location of the active working-register group.

Note: Register Group E0-EF can only be accessed through working registers and indirect addressing modes.

Stack. The Z86C93 has a 16-bit Stack Pointer (R254-R255), used for external stack, that resides anywhere in the data memory. An 8-bit Stack Pointer (R255) is used for the internal stack that resides within the 236 general-purpose registers (R4-R239). The high byte of the Stack Pointer (SPH, Bits 8-15) can be used as a general-purpose register when using internal stack only.

### **FUNCTIONAL DESCRIPTION**

This section breaks down the Z86C93 into its main functional parts.

### Multiply/Divide Unit

The Multiply/Divide unit describes the basic features, implementation details of the interface between the Z8 and the multiply/divide unit.

### Basic features:

- 16-bit by 16-bit multiply with 32-bit product
- 32-bit by 16-bit divide with 16-bit quotient and 16-bit remainder
- Unsigned integer data format
- Simple interface to Z8

Interface to Z8. The following is a brief description of the register mapping in the multiply/divide unit and its interface to the Z8 (Figure 16).

The multiply/divide unit is interfaced like a peripheral. The only addressing mode available with the peripheral interface is register addressing. In other words, all of the operands are in the respective registers before a multiplication/division can start.

Register mapping. The registers used in the multiply/divide unit are mapped onto the expanded register file in Bank E. The exact register locations used are shown below.

REGISTER	ADDRESS
MREG0	(E) 00
MREG1	(E) 01
MREG2	(E) 02
MREG3	(E) 03
MREG4	(E) 04
MREG5	(E) 05
MDCON	(E) 06
GPR	(E) 14
GPR	(E) 15

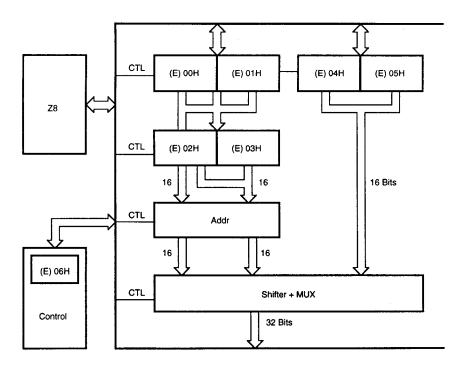


Figure 16. Multiply/Divide Unit Block Diagram

The counters are programmed to start, stop, restart to continue, or restart from the initial value. The counters can also be programmed to stop upon reaching zero (single pass mode) or to automatically reload the initial value and continue counting (modulo-n continuous mode).

The counters, but not the prescalers, are read at any time without disturbing their value or count mode. The clock source for T1 is user-definable and is either the internal microprocessor clock divided by four, or an external signal input via Port 3. The Timer Mode register configures the external timer input (P31) as an external clock, a trigger input that is retriggerable or non-retriggerable, or as a gate input for the internal clock. The counter/timers are cascaded by connecting the T0 output to the input of T1. Either T0 or T1 can be outputted via P36.

The following are the enhancements made to the counter/ timer block on the Z86C93 (Figure 18):

- T0 counter length is extended to 16 bits. For example, T0 now has a 6-bit prescaler and 16-bit down counter.
- T1 counter length is extended to 16 bits. For example, T1 now has a 6-bit prescaler and 16-bit down counter.
- A new counter/timer T2 is added. T2 has a 4-bit prescaler and a 16-bit down counter with capture register.

These three counters are cascadable as shown in Table 6. The result is that T2 may be extendable to 32 bits and T1 extendable to 24 bits. Bits 1 and 0 (CAS1 AND CAS0) of the T2 Prescaler Register (PRE2) determine the counter length.

**Table 6. Counter Length Configurations** 

CAS 1	CAS0	ТО	T1	T2
0	0	8	8	32
0	1	16	16	16
1	0	8	24	16
1	1	8	16	24

The controlling clock input to T2 is programmed to XTAL/2 or XTAL/8 (only when T2 counter length is 16 bits), which results in a resolution of 100 ns at an external XTAL clock speed of 20 MHz.

Capture Register. T2 has a 16-bit capture register associated with T2 HIGH BYTE and T2 LOW BYTE registers. The negative going transition on pin P33 enables the latching of the current T2 value (16 bits) into the capture register. The register mapping of the capture register is in Bank D (Figure 13). Note that the negative transition on P33 is capable of generating an interrupt. Also, the negative transition on P33 always latches the current T2 value into the capture register. There is no need for a control bit to enable/disable the latching; the capture register is read only.

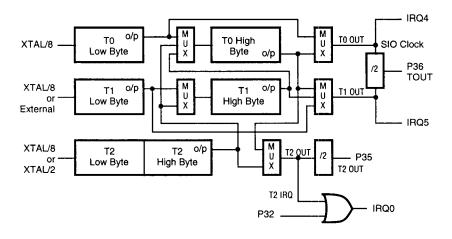


Figure 18. Counter/Timer Block Diagram

Name	Source	Vector Location	Comments
IRQ 0	/DAV 0, P32, T2	0, 1	External (P32), Programmable Rise or Fall Edge Triggered External (P33), Fall Edge Triggered External (P31), Programmable Rise or Fall Edge Triggered
IRQ 1,	P33	2, 3	
IRQ 2	/DAV 2, P31, T <sub>IN</sub>	4, 5	
IRQ 3	P30, Serial In	6, 7	External (P30), Fall Edge Triggered
IRQ 4	T0, Serial Out	8, 9	Internal
IRQ 5	TI	10, 11	Internal

### Clock

The Z86C93 on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, LC, ceramic resonator, or any suitable external clock source (XTAL1=Input, XTAL2=Output). The external clock levels

are not TTL. The crystal should be AT cut, 1 MHz to 25 MHz max, and series resistance (RS) is less than or equal to 100 Ohms. The crystal should be connected across XTAL1 and XTAL2 using the recommended capacitors (10 pF<CL<100 pF) from each pin to ground (Figure 20).

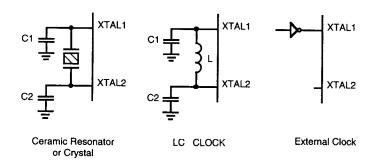


Figure 22. Oscillator Configuration

### Power Down Modes

HALT. Turns off the internal CPU clock but not the XTAL oscillation. The counter/timers and the external interrupts IRQ0, IRQ1, IRQ2 and IRQ3 remain active. The devices are recovered by interrupts, either externally or internally generated. During HALT mode, /DS, /AS and R/W are HIGH. The outputs retain their preview value, and the inputs are floating.

STOP. This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10  $\mu$ A or less. The STOP mode is terminated by a /RESET, which causes the processor to restart the application program at address 000CH.

In order to enter STOP (or HALT) mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user executes a NOP (opcode=OFFH) immediately before the appropriate sleep instruction, i.e.:

FF NOP ; clear the pipeline 6F STOP ; enter STOP mode

FF NOP ; clear the pipeline 7F HALT ; enter HALT mode

### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Description	Min	Max	Units
V <sub>cc</sub> T <sub>stg</sub> T <sub>4</sub>	Supply Voltage* Storage Temp Oper Ambient Temp	-0.3 -65 +	+7.0 +150 +	V C C

- Voltages on all pins with respect to GND.
- † See Ordering Information

Stress greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability.

### STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin Test Load Diagram (Figure 23).

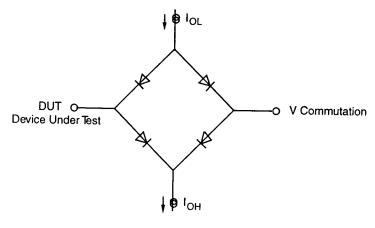


Figure 23. Test Load Diagram

# DC ELECTRICAL CHARACTERISTICS $V_{\text{CC}} = 3.3 V \pm 10\%$

Sym	Parameter	T <sub>A</sub> = 0°C to +70°C Min Max		Typical at 25℃	Units	Conditions
	Max Input Voltage		7		V	I <sub>IN</sub> 250 μA
н	Clock Input High Voltage	0.8 V <sub>cc</sub>	V <sub>cc</sub>		٧	Driven by External Clock Generator
L	Clock Input Low Voltage	-0.03	0.1xV <sub>cc</sub>		٧	Driven by External Clock Generator
	Input High Voltage	$0.7xV_{cc}$	V <sub>cc</sub>		V	,
	Input Low Voltage	-0.3	0.1xV <sub>cc</sub>		٧	
н	Output High Voltge	1.8			٧	I <sub>DH</sub> = -1.0 mA
i	Output High Voltge	V <sub>cc</sub> - 100mV			V	$I_{0H}^{(H)} = -100  \mu A$
	Output Low Voltage	00	0.4		V	$I_{01} = +1.0 \text{ mA}$
1	Reset Input High Voltage	$0.8xV_{cc}$	V <sub>cc</sub>		٧	o.
	Reset Input Low Voltage	-0.03	0.1xV <sub>cc</sub>		V	
	Input Leakage	-2	2		μA	Test at OV, V <sub>cc</sub>
	Output Leakage	-2	2		μA	Test at OV, V <sub>cc</sub>
	Reset Input Current		-80		μA	$V_{RI} = 0V$
	Supply Current		30	20	mA	@ 25 MHz [1]
,	Stand By Current (HALT Mode)		12	8	mA	HALT Mode V <sub>IN</sub> =0V, V <sub>CC</sub> @ 25 MHz [1]
2	Stand By Current (HALT Mode)		8	1	μA	STOP Mode V <sub>N</sub> =0V, V <sub>CC</sub> [1]
	Auto Latch Low Current	-10	10	5	μA	00

Note: [1] All inputs driven to 0V,  $V_{\rm cc}$  and outputs floating.

AC CHARACTERISTICS External I/O or Memory Read and Write; DSR/DSW; WAIT Timing Table

						_ = 0°C				
No	Sym	Parameter	33 I Min	MHz Max		MHz Max	20 Min	MHz Max	Typical V <sub>cc</sub> =5.0V <b>ଡ</b> 25℃	Units
1	TdA(AS)	Address Valid To /AS Rise Delay	13		22		26			ns
2	TdAS(A)	/AS Rise To Address Hold Time	20		25		28			ns
4	TdAS(DI) TwAS	/AS Rise Data in Req'd Valid Delay /AS Low Width	00	90		130		160		ns
_	TWAS	/AS LOW WIGH	20		28		36			ns
5	TdAZ(DSR)	Address Float To /DS (Read)	0		0		0			ns
6	TwDSR	/DS (Read) Low Width	65		100		130			ns
7	TwDSW	/DS (Write) Low Width	40		65		75			ns
8	TdDSR(DI)	/DS (Read) To Data in Req'd Valid Delay		30		78		100		ns
9	ThDSR(DI)	/DS Rise (Read) to Data In Hold Time	0		0		0			ns
10	TdDS(A)	/DS Rise To Address Active Delay	25		34		40			ns
11 12	TdDS(AS)	/DS Rise To /AS Delay	16		30		36			ns
	TdR/W(AS)	R/W To /AS Rise Delay	12		26		32			ns
13	TdDS(R/W)	/DS Rise To R/W Valid Delay	12	-	30		36			ns
14	TdDO(DSW)	Data Out To /DS (Write) Delay	12		34		40			ns
15 16	ThDSW(DO)	/DS Rise (Write) To Data Out Hold Time	12		34		40			ns
10	TdA(DI)	Address To Data In Req'd Valid Delay		110		160		200		ns
17	TdAS(DSR)	/AS Rise To /DS (Read) Delay	20		40		48			ns
18	TaDI(DSR)	Data In Set-up Time To /DS Rise Read	16		30		36			ns
19 20	TdDM(AS) TdDS(DM)	/DM To /AS Rise Delay	10		22		26			ns
		/DS Rise To /DM Valid Delay							34*	ns
21	ThDS(A)	/DS Rise To Address Valid Hold Time							34*	ns
22 23	TdXT(SCR)	XTAL Falling to SCLK Rising							20*	ns
24	TdXT(SCF) TdXT(DSRF)	XTAL Falling to SCLK Falling							23*	ns
		XTAL Falling to/DS Read Falling							29*	ns
25 26	TdXT(DSRR)	XTAL Falling to /DS Read Rising							29*	ns
26 27	TdXT(DSWF)	XTAL Falling to /DS Write Falling							29*	ns
28	TdXT(DSWF) TsW(XT)	XTAL Falling to /DS Write Rising							29*	ns
29	ThW(XT)	Wait Set-up Time Wait Hold Time							10*	ns
30	TwW	Wait Width (One Wait Time)							15*	ns
		Trace Trider (One Walt Time)							25*	ns

When using extended memory timing add 2 TpC.
Timing numbers given are for minimum TpC.
\* Preliminary value to be characterized.

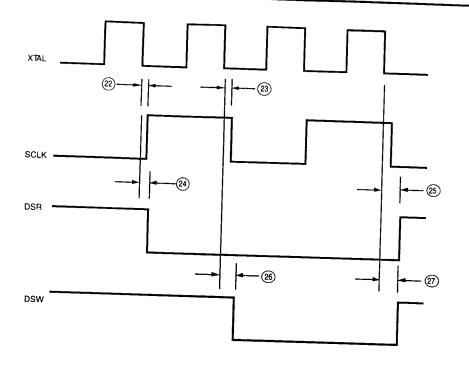


Figure 25. XTAL/SCLK To DSR and DSW Timing

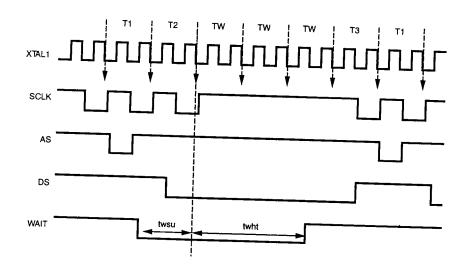


Figure 26. XTAL/SCLK To WAIT Timing (25 MHz Device Only)

**AC CHARACTERISTICS** Handshake Timing Diagrams

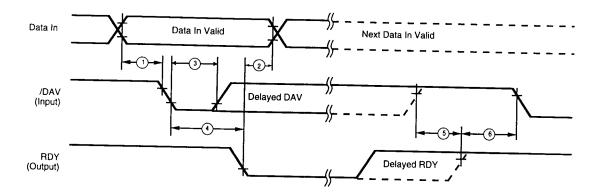


Figure 28. Input Handshake Timing

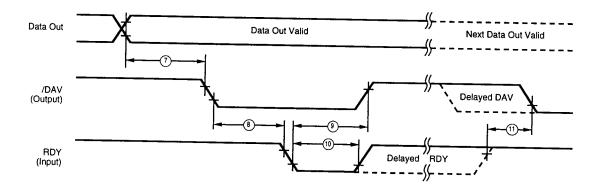
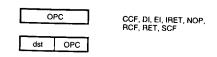


Figure 29. Output Handshake Timing

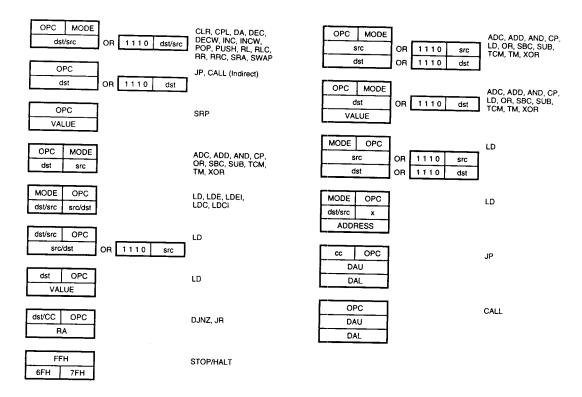
# AC CHARACTERISTICS Handshake Timing Table

No	Symbol	Parameter	T, = 0°0	to +70°C		D.4.
1	ToDI/DAVA		Min	Max	Units	Data Direction
2	TsDI(DAV) ThDI(DAV)	Data In Setup Time to /DAV	0			
5	` '	RDY to Data In Hold Time	ñ		ns	ln
	TwDAV	/DAV Width	40		ns	In
	TdDAVIf(RDYf)	/DAV to RDY Delay	40		ns	In
	T ID NIII (DD)			70	ns	In
	TdDAVIr(RDYr)	DAV Rise to RDY Wait Time				
	TdRDYOr(DAVIf)	RDY Rise to DAV Delay	0	40	ns	ln
	TdD0(DAV)	Data Out to DAV Delay	0	_	ns	In
	TdDAV0f(RDYIf)	/DAV to RDY Delay	_	TpC	ns	Out
			0		ns	Out
	TdRDYIf(DAVOr)	RDY to /DAV Rise Delay				
0	TwRDY	RDY Width	40	70	ns	Out
	TdRDYIr(DAVOf)	RDY Rise to DAV Wait Time	40		ns	Out
		THE THIS TO DAY WAIT TIME		40	ns	Out

### **INSTRUCTION FORMATS**



### One-Byte Instructions



### **Two-Byte Instructions**

Three-Byte Instructions

### **INSTRUCTION SUMMARY**

Note: Assignment of a value is indicated by the symbol "  $\leftarrow$  ". For example:

notation "addr (n)" is used to refer to bit (n) of a given operand location. For example:

dst ← dst + src

dst (7)

indicates that the source data is added to the destination data and the result is stored in the destination location. The

refers to bit 7 of the destination operand.

# INSTRUCTION SUMMARY (Continued)

Instruction and Operation	M	ddress ode st src		ode (Hex)	F	Flag Affe	cte			D	Н
NOP			FF		-	-	-	-		•	-
OR dst, src dst←dst OR src	†	· · · · · ·	4[ ]		-	*		: (	) .		_
POP dst dst←@SP; SP←SP + 1	R		50 51	<u> </u>	-	-	-	-			-
PUSH src SP←SP - 1; @SP←src		R IR	70 71	<u> </u>	-	-	-	-	-		_
RCF C←0			CF	·	0	-	-	-	-		-
<b>RET</b> PC←@SP; SP←SP + 2		.,	AF	<u>.</u>	-	-	-	-	-		_
RL dst	R IR		90 91		*	*	*	*	-	•	-
RLC dst	R IR		10 11		*	*	*	*	-	-	<del>-</del> -
RR dst	R IR		E0 E1	:	*	*	*	*	-	-	_
RRC dst	R IR		C0 C1	:	*	*	*	*	-	-	-
SBC dst, src dst←dst←src←C	†		3[]		k	*	*	*	1	k	<
SCF C←1			DF	1	l	-	-	•	-	-	_
SRA dst	R IR		D0 D1	k	k	*	*	0	-	-	_
SRP src RP←src		lm .	31	-		-	-	-	•	-	-

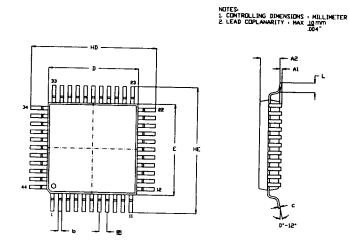
Instruction and Operation	Address Mode	Opcode Byte (Hex)	Flags Affected					
	dst src		С	Z	S	٧	D	Н
STOP		6F	-	-		-	-	-
SUB dst, src dst←dst←src	†	2[ ]	*	*	*	*	1	*
<b>SWAP</b> dst	R IR	F0 F1	X	*	*	X	-	-
TCM dst, src (NOT dst) AND src	†	6[]	-	*	*	0	-	-
TM dst, src dst AND src	†	7[]	-	*	*	0	-	-
XOR dst, src dst←dst XOR src	t	B[ ]	-	*	*	0	-	•

† These instructions have an identical set of addressing modes, which are encoded for brevity. The first opcode nibble is found in the instruction set table above. The second nibble is expressed symbolically by a '[ ]' in this table, and its value is found in the following table to the left of the applicable addressing mode pair.

For example, the opcode of an ADC instruction using the addressing modes  ${\bf r}$  (destination) and  ${\bf lr}$  (source) is 13.

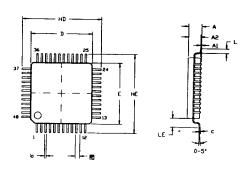
Addre dst	ss Mode src	Lower Opcode Nibble		
r	r	[2]		
r	Ir	[3]		
R	R	[4]		
R	IR	[5]		
R	IM	[6]		
IR	IM	[7]		

# PACKAGE INFORMATION (Continued)



SYMBOL	MILLIMETER		INCH		
	MIN	MAX	NIM	MAX	
Al	0.05	0.25	.002	.010	
SA	2.05	2.25	.081	.089	
b	0.25 -	0.45	.010	.018	
c	0.13	0.20	.005	.008	
HD	13.70	14.30	.539	.563	
D	9.90	10.10	.390	.398	
HE	13.70	14.30	.539	.563	
E	9.90	10.10	.390	.398	
8	0.80 TYP		.031	TYP	
L .	0.60	1.20	024	047	

44-Pin QFP Package Diagram



ZYMBOL	HILLIMETER		INCH		
STRIBLE.	MIN	MAX	MIN	MAX	
Α	1.35	1.60	.053	.063	
A1	0.05	0.20	.002	.008	
A2	1.30	1.50	.051	.059	
b	0.15	0.26 `	.006	.010	
c	0.10	0.18	.004	.007	
HB	8.60	9.40	.339	.370	
D	6.90	7.10	.272	.280	
HE	8.60	9.40	.339	.370	
Ε	6.90	7.10	.272	.280	
8	0.50 TYP		.020	TYP	
L	0.30	0.70	.012	.028	
LE	0.90	1.10	.035	.043	

1. CONTROLLING DIMENSIONS - MI 2. MAX COPLANARITY : 10mm

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