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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	Z8
Core Size	8-Bit
Speed	25MHz
Connectivity	EBI/EMI, UART/USART
Peripherals	-
Number of I/O	24
Program Memory Size	-
Program Memory Type	ROMless
EEPROM Size	-
RAM Size	236 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z86c9325fsc">https://www.e-xfl.com/product-detail/zilog/z86c9325fsc</a>



## Z86C93

### CMOS Z8® MULTIPLY/DIVIDE MICROCONTROLLER

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#### FEATURES

- Complete microcontroller, up to 24 I/O lines, and up to 64 Kbytes of addressable external space each for program and data memory.
- 16-bit x 16-bit hardwired multiplier with 32-bit product in 17 clock cycles.
- 32-bit x 16-bit hardwired divider with 16-bit quotient and 16-bit remainder in 20 clock cycles.
- 256-byte register file, including 236 general-purpose registers, up to three I/O port registers and 16 status and control registers.
- 17-byte Expanded Register File, including two general-purpose registers and 15 status and control registers.
- Vectored, priority interrupts for I/O, counter/timers and UART.
- On-chip oscillator that accepts crystal or external clock drive.
- Two 16-bit counter timers with 6-bit prescalers.
- Third 16-bit counter/timer with 4-bit prescaler, one capture register and a fast decrement mode.
- Register Pointer for short, fast instructions that can access any one of the sixteen working register groups.
- Additional emulation signals SCLK, IACK, and /SYNC are made available.
- Two low power standby modes, STOP and HALT
- Full-duplex UART
- $3.3 \pm 10\%$  volt operation at 25 MHz
- $5.0 \pm 10\%$  volt operation at 20, 25 and 33 MHz

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#### GENERAL DESCRIPTION

The Z86C93 is a CMOS ROMless Z8 microcontroller enhanced with a hardwired 16-bit x 16-bit multiplier and 32-bit/16-bit divider and three 16-bit counter timers (Figure 1). A capture register and a fast decrement mode is also provided. It is offered in 40-pin PDIP, 44-pin PLCC, 44-pin QFP and 48-pin VQFP (Figures 2, 3, 4, 5 and 6). Besides the four additional signals (SCLK, IACK, /SYNC and /WAIT), the Z86C93 is compatible with the Z86C91, yet it offers a much more powerful mathematical capability.

The Z86C93 provides up to 16 output address lines permitting an address space of up to 64 Kbytes of data and program memory each. Eight address outputs (AD7-AD0) are provided by a multiplexed, 8-bit, Address/Data bus. The remaining 8 bits can be provided by the software configuration of Port 0 to output address bits A15-A8.

## PIN DESCRIPTION

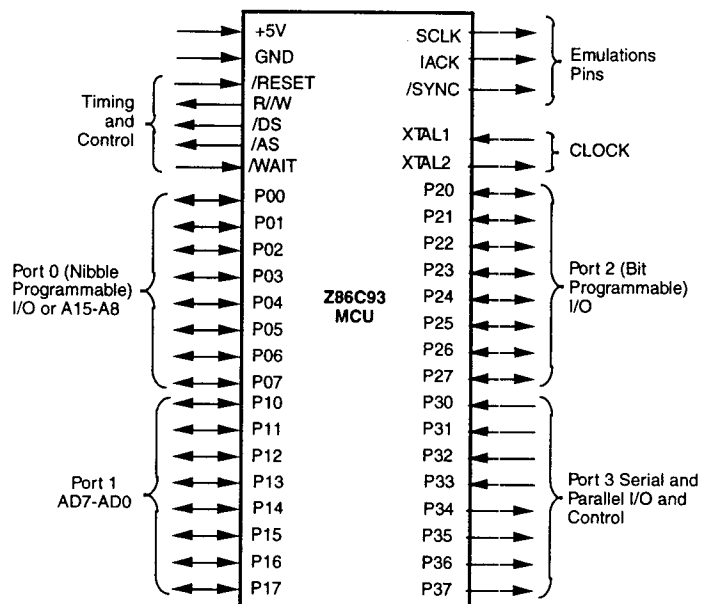


Figure 2. Pin Functions

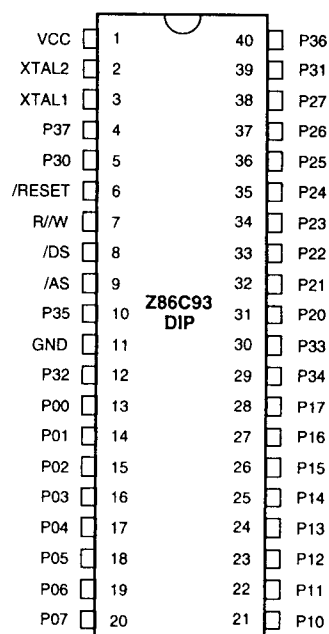
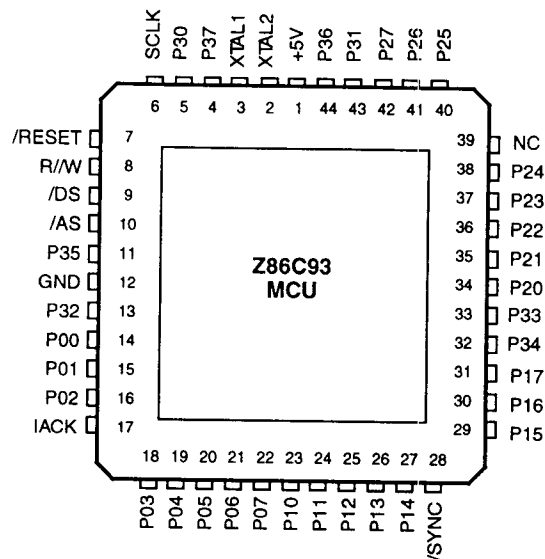


Figure 3. 40-Pin DIP

Table 1. 40-Pin DIP Pin Identification

Pin #	Symbol	Function	Direction
1	V <sub>CC</sub>	Power Supply	Input
2	XTAL1	Crystal, Oscillator Clock	Input
3	XTAL2	Crystal, Oscillator Clock	Output
4	P37	Port 3 pin 7	Output
5	P30	Port 3 pin 0	Input
6	/RESET	Reset	Input
7	R/W	Read/Write	Output
8	/DS	Data Strobe	Output
9	/AS	Address Strobe	Output
10	P35	Port 3 pin 5	Output
11	GND	Ground, GND	Input
12	P32	Port 3 pin 2	Input
13-20	P00-P07	Port 0 pin 0,1,2,3,4,5,6,7	In/Output
21-28	P10-P17	Port 1 pin 0,1,2,3,4,5,6,7	In/Output
29	P34	Port 3 pin 4	Output
30	P33	Port 3 pin 3	Input
31-38	P20-P27	Port 2 pin 0,1,2,3,4,5,6,7	In/Output
39	P31	Port 3 pin 1	Input
40	P36	Port 3 pin 6	Output

### PIN DESCRIPTION (Continued)



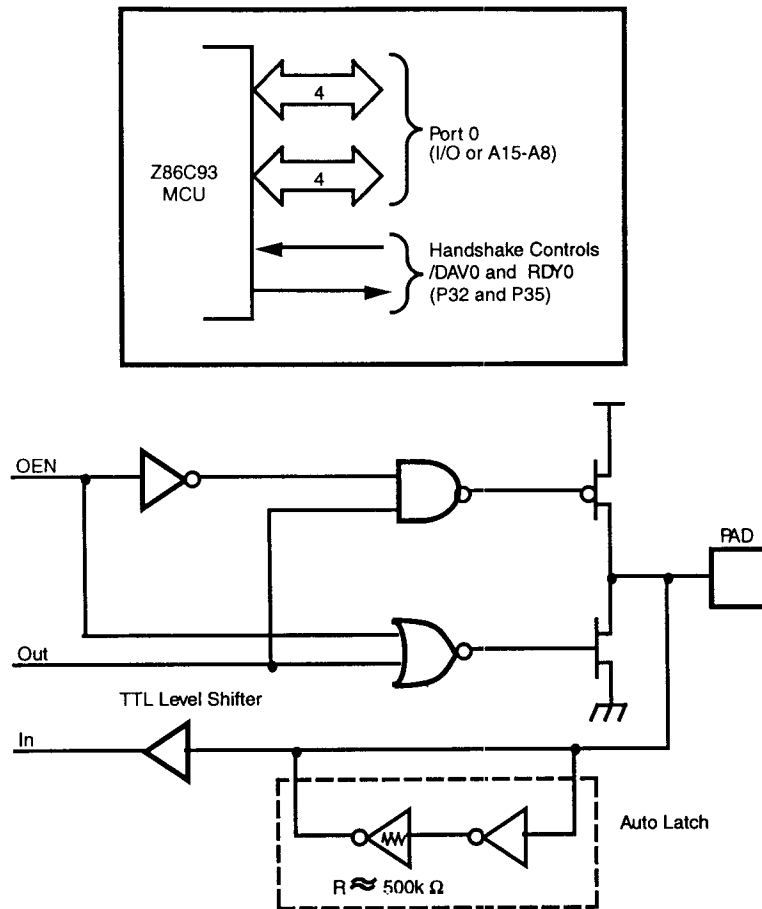
### Figure 4. 44-Pin PLCC

### Table 2. 44-Pin PLCC Pin Identification

No	Symbol	Function	Direction
1	V <sub>CC</sub>	Power Supply	Input
2	XTAL2	Crystal, Osc. Clock	Output
3	XTAL1	Crystal, Osc. Clock	Input
4	P37	Port 3 pin 7	Output
5	P30	Port 3 pin 0	Input
6	SCLK	System Clock	Output
7	/RESET	Reset	Input
8	R/W	Read/Write	Output
9	/DS	Data Strobe	Output
10	/AS	Address Strobe	Output
11	P35	Port 3 pin 5	Output
12	GND	Ground GND	Input
13	P32	Port 3 pin 2	Input

No	Symbol	Function	Direction
14-16	P00-P02	Port 0 pin 0,1,2	In/Output
17	IACK	Int. Acknowledge	Output
18-22	P03-P07	Port 0 pin 3,4,5,6,7	In/Output
23-27	P10-P14	Port 1 pin 0,1,2,3,4	In/Output
28	/SYNC	Synchronize Pin	Output
29-31	P15-P17	Port 1 pin 5,6,7	In/Output
32	P34	Port 3 pin 4	Output
33	P33	Port 3 pin 3	Input
34-38	P20-P24	Port 2 pin 0,1,2,3,4	In/Output
39	N/C	Not Connected (20 MHz)	Input
	/WAIT	WAIT (25 or 33 MHz)	Input
40-42	P25-P27	Port 2 pin 5,6,7	In/Output
43	P31	Port 3 pin 1	Input
44	P36	Port 3 pin 6	Output



**Figure 7. Port 0 Configuration**

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## PIN FUNCTIONS (Continued)

Port 1. (P10-P17). Port 1 is an 8-bit, TTL compatible port. It has multiplexed Address (A7-A0) and Data (D7-D0) ports for interfacing external memory (Figure 8).

If more than 256 external locations are required, Port 0 must output the additional lines.

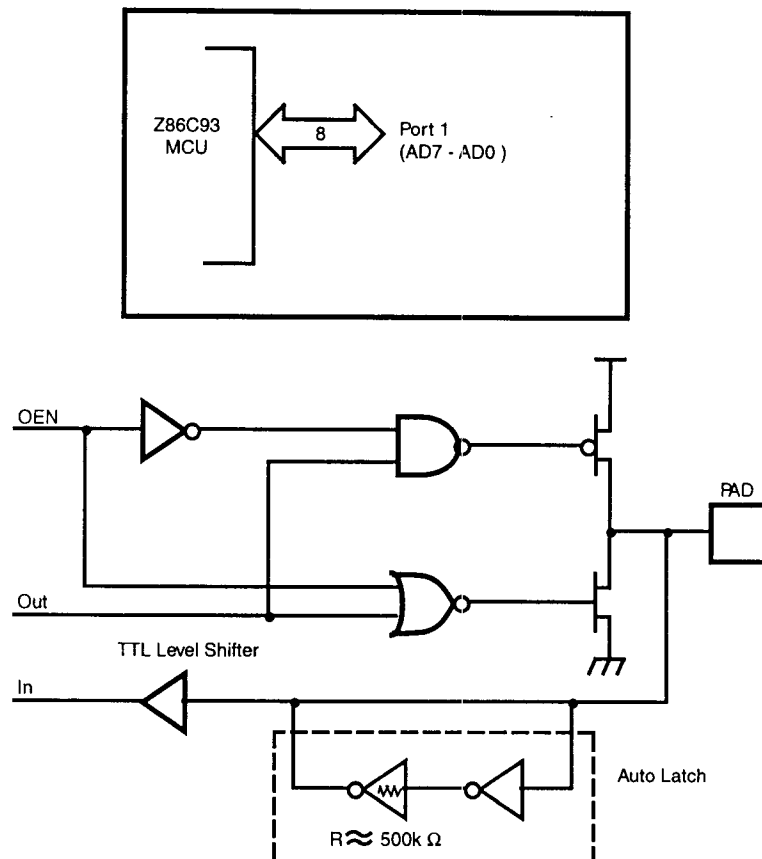


Figure 8. Port 1 Configuration

Port 3 P30-P37. Port 3 is an 8-bit, TTL compatible four fixed input and four fixed output ports. These eight I/O lines have four fixed (P30-P33) input and four fixed (P34-P37) output

ports. Port 3 pins P30 and P37 when used as serial I/O, are programmed as serial in and serial out, respectively (Figure 10 and Table 5).

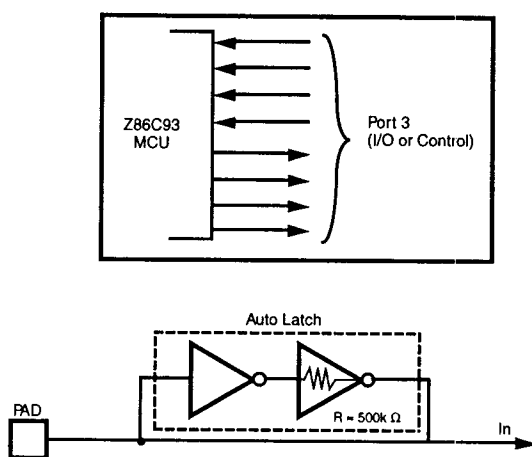


Figure 10. Port 3 Configuration

Table 5. Port 3 Pin Assignments

Pin #	I/O	CTC1	Int.	P0HS	P2HS	UART	Ext.
P30	In	$T_{IN}$	IRQ3	D/R	D/R	Serial In	
P31	In		IRQ2				
P32	In		IRQ0				
P33	In		IRQ1				
P34	Out	$T_{OUT}$		R/D	R/D	Serial Out	DM
P35	Out						
P36	Out						
P37	Out						

Port 3 is configured under software control to provide the following control functions: handshake for Ports 0 and 2 (/DAV and RDY); four external interrupt request signals (IRQ0-IRQ3); timer input and output signals ( $T_{IN}$  and  $T_{OUT}$ ), and Data Memory Select (/DM).

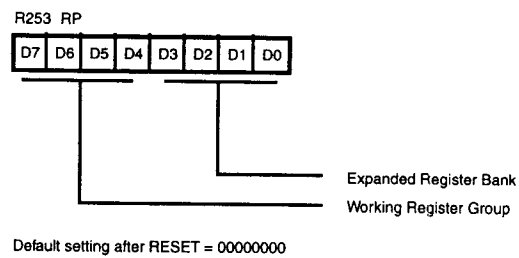
Port 3 lines P30 and P37 can be programmed as serial I/O lines for full-duplex serial asynchronous receiver/transmitter operation. The bit rate is controlled by the Counter/Timer 0.

The Z86C93 automatically adds a start bit and two stop bits to transmitted data (Figure 10). Odd parity is also available as an option. Eight data bits are always transmitted,

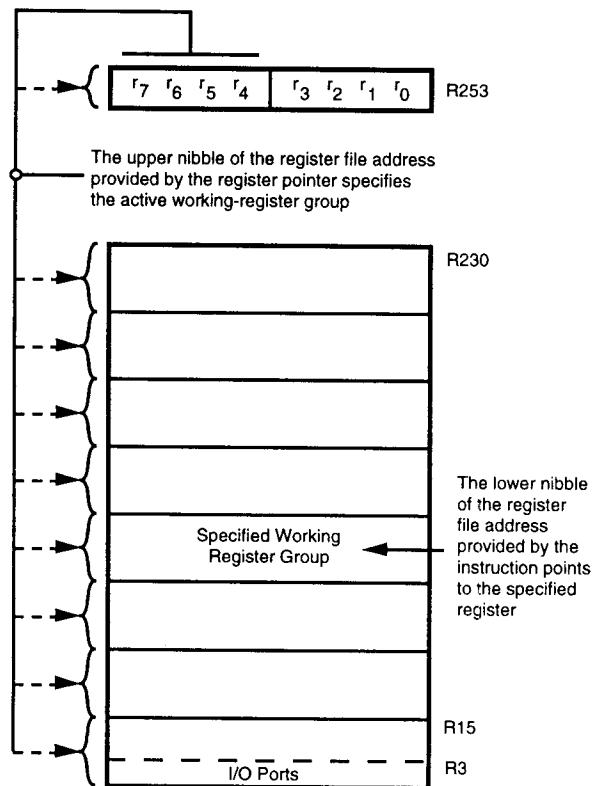
regardless of parity selection. If parity is enabled, the eighth bit is the odd parity bit. An interrupt request (IRQ4) is generated on all transmitted characters.

Received data must have a start bit, eight data bits and at least one stop bit. If parity is on, bit 7 of the received data is replaced by a parity error flag. Received characters generate the IRQ3 interrupt request.

The Auto Latch on Port 3 puts a valid CMOS level on all CMOS inputs that are not externally driven. Whether this level is zero or one, cannot be determined. A valid CMOS level rather than a floating node reduces excessive supply current flow in the input buffer.



**Figure 14. Register Pointer Register**



**Figure 15. Register Pointer**





## Interrupts

The Z86C93 has six different interrupts from nine different sources. The interrupts are maskable and prioritized. The nine sources are divided as follow: four sources are claimed by Port 3 lines P30-P33, one in Serial Out, one in Serial In, and three in the counter/timers. The Interrupt Mask Register globally or individually enables or disables the six interrupt requests. When more than one interrupt is pending, priorities are resolved by a programmable priority encoder that is controlled by the Interrupt Priority register. All Z86C93 interrupts are vectored through locations in the program memory. When an interrupt machine cycle is activated an interrupt request is granted. Thus, this disables all of the subsequent interrupts, save the Program Counter and Status Flags, and then branches to the program memory vector location reserved for that interrupt. This memory location and the next byte contain the 16-bit address of the interrupt service routine for that particular interrupt request.

To accommodate polled interrupt systems, interrupt inputs are masked and the Interrupt Request register is polled to determine which of the interrupt requests need service. Software initiated interrupts are supported by setting the appropriate bit in the Interrupt Request Register (IRQ).

Internal interrupt requests are sampled on the falling edge of the last cycle of every instruction. The interrupt request must be valid 5TpC before the falling edge of the last clock cycle of the currently executing instruction.

When the device samples a valid interrupt request, the next 48 (external) clock cycles are used to prioritize the interrupt, and push the two PC bytes and the FLAG register on the stack. The following nine cycles are used to fetch the interrupt vector from external memory. The first byte of the interrupt service routine is fetched beginning on the 58<sup>th</sup> TpC cycle following the internal sample point, which corresponds to the 63<sup>rd</sup> TpC cycle following the external interrupt sample point.

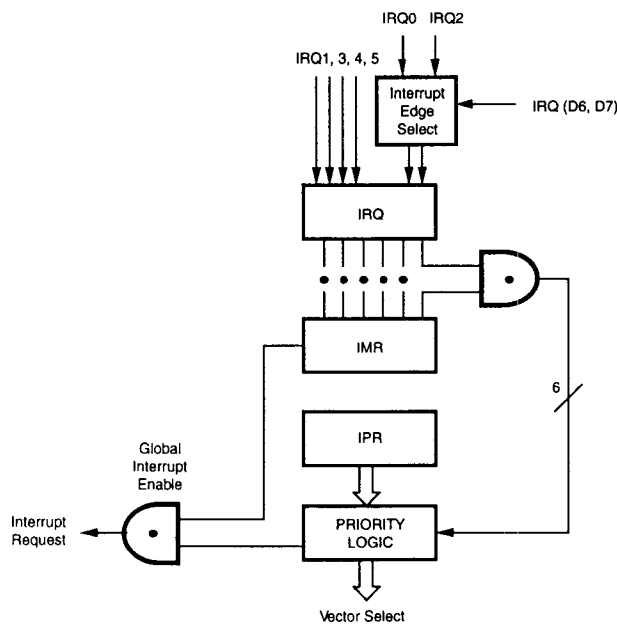


Figure 21. Interrupt Block Diagram

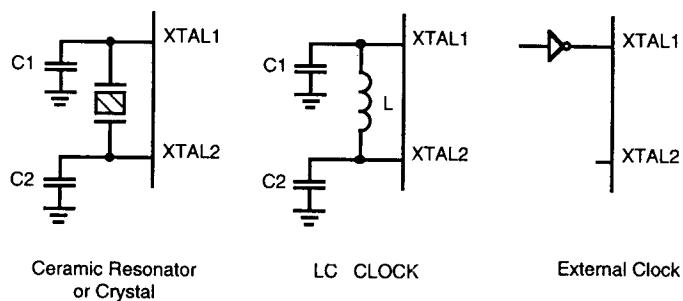
**Table 7. Interrupt Types, Sources, and Vectors**

Name	Source	Vector Location	Comments
IRQ 0	/DAV 0, P32, T2	0, 1	External (P32), Programmable Rise or Fall Edge Triggered
IRQ 1,	P33	2, 3	External (P33), Fall Edge Triggered
IRQ 2	/DAV 2, P31, T <sub>IN</sub>	4, 5	External (P31), Programmable Rise or Fall Edge Triggered
IRQ 3	P30, Serial In	6, 7	External (P30), Fall Edge Triggered
IRQ 4	T0, Serial Out	8, 9	Internal
IRQ 5	T1	10, 11	Internal

## Clock

The Z86C93 on-chip oscillator has a high-gain, parallel-resonant amplifier for connection to a crystal, LC, ceramic resonator, or any suitable external clock source (XTAL1=Input, XTAL2=Output). The external clock levels

are not TTL. The crystal should be AT cut, 1 MHz to 25 MHz max, and series resistance (RS) is less than or equal to 100 Ohms. The crystal should be connected across XTAL1 and XTAL2 using the recommended capacitors (10 pF < CL < 100 pF) from each pin to ground (Figure 20).



**Figure 22. Oscillator Configuration**

## Power Down Modes

**HALT.** Turns off the internal CPU clock but not the XTAL oscillation. The counter/timers and the external interrupts IRQ0, IRQ1, IRQ2 and IRQ3 remain active. The devices are recovered by interrupts, either externally or internally generated. During HALT mode, /DS, /AS and R/W are HIGH. The outputs retain their preview value, and the inputs are floating.

**STOP.** This instruction turns off the internal clock and external crystal oscillation and reduces the standby current to 10  $\mu$ A or less. The STOP mode is terminated by a /RESET, which causes the processor to restart the application program at address 000CH.

In order to enter STOP (or HALT) mode, it is necessary to first flush the instruction pipeline to avoid suspending execution in mid-instruction. To do this, the user executes a NOP (opcode=OFFH) immediately before the appropriate sleep instruction, i.e.:

```
FF NOP ; clear the pipeline
6F STOP ; enter STOP mode
or
FF NOP ; clear the pipeline
7F HALT ; enter HALT mode
```

## ABSOLUTE MAXIMUM RATINGS

Symbol	Description	Min	Max	Units
$V_{CC}$	Supply Voltage*	-0.3	+7.0	V
$T_{STG}$	Storage Temp	-65	+150	C
$T_A$	Oper Ambient Temp	†	†	C

\* Voltages on all pins with respect to GND.

† See Ordering Information

Stress greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for an extended period may affect device reliability.

## STANDARD TEST CONDITIONS

The characteristics listed below apply for standard test conditions as noted. All voltages are referenced to GND. Positive current flows into the referenced pin Test Load Diagram (Figure 23).

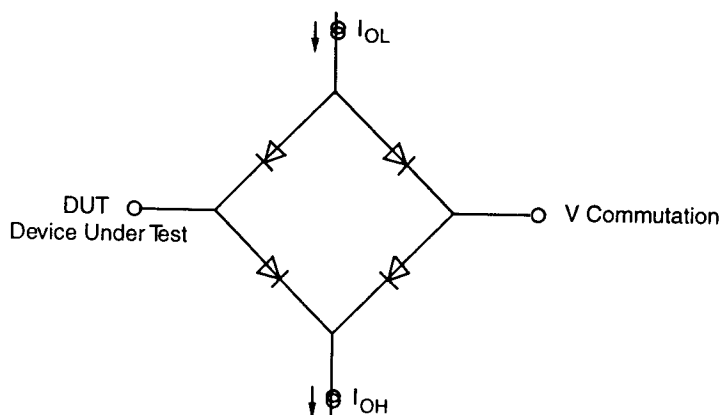


Figure 23. Test Load Diagram

## DC ELECTRICAL CHARACTERISTICS

$V_{CC} = 5.0V \pm 10\%$

Sym	Parameter	$T_A = 0^\circ\text{C to } +70^\circ\text{C}$		Typical at $25^\circ\text{C}$	Units	Conditions
		Min	Max			
	Max Input Voltage		7		V	$I_{IN} = 250 \mu\text{A}$
$V_{CH}$	Clock Input High Voltage	3.8	$V_{CC}$		V	Driven by External Clock Generator
$V_{CL}$	Clock Input Low Voltage	-0.03	0.8		V	Driven by External Clock Generator
$V_{IH}$	Input High Voltage	2.0	$V_{CC}$		V	
$V_{IL}$	Input Low Voltage	-0.3	0.8		V	
$V_{OH}$	Output High Voltage	2.4			V	$I_{OH} = -2.0 \text{ mA}$
$V_{OH}$	Output High Voltage	$V_{CC} - 100\text{mV}$			V	$I_{OH} = -100 \mu\text{A}$
$V_{OL}$	Output Low Voltage		0.4		V	$I_{OL} = +5 \text{ mA}$
$V_{RH}$	Reset Input High Voltage	3.8	$V_{CC}$		V	
$V_{RL}$	Reset Input Low Voltage	-0.03	0.8		V	
$I_{IL}$	Input Leakage	-2	2		$\mu\text{A}$	Test at 0V, $V_{CC}$
$I_{OL}$	Output Leakage	-2	2		$\mu\text{A}$	Test at 0V, $V_{CC}$
$I_{IR}$	Reset Input Current		-80		$\mu\text{A}$	$V_{RL} = 0V$
$I_{CC}$	Supply Current		55	35	mA	@ 33 MHz [1]
			40	25	mA	@ 25 MHz [1]
			30	20	mA	@ 20 MHz [1]
$I_{CC1}$	Standby Current (HALT Mode)		15	9	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC}$ @ 25 MHz [1]
			20	15		HALT Mode $V_{IN} = 0V$ , $V_{CC}$ @ 33 MHz [1]
			12	7	mA	HALT Mode $V_{IN} = 0V$ , $V_{CC}$ @ 20 MHz [1]
$I_{CC2}$	Standby Current (STOP Mode)		10	1	$\mu\text{A}$	STOP Mode $V_{IN} = 0V$ , $V_{CC}$ [1]
$I_{AL}$	Auto Latch Current	-16	16	5	$\mu\text{A}$	

### Note:

[1] All inputs driven to 0V, or  $V_{CC}$  and outputs floating.

## AC CHARACTERISTICS

### External I/O or Memory Read/Write Timing Diagram

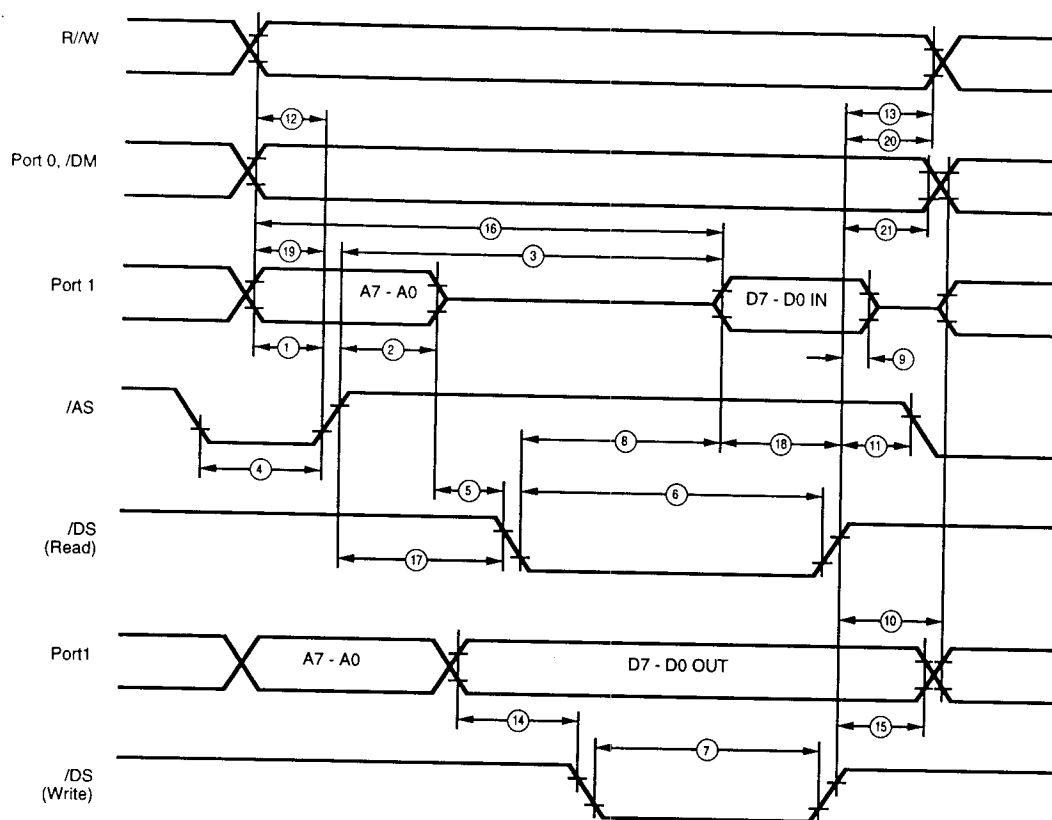


Figure 24. External I/O or Memory Read/Write Timing

## EXPANDED REGISTER FILE CONTROL REGISTERS

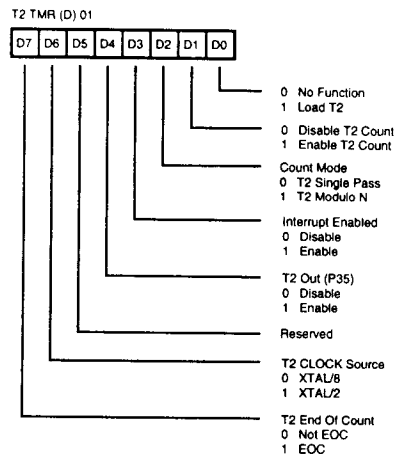


Figure 30. Timer 2 Mode Register (01H: Read/Write)

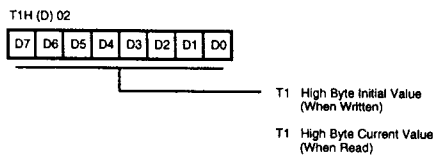


Figure 31. Counter Timer 1 Register High Byte (02H: Read/Write)

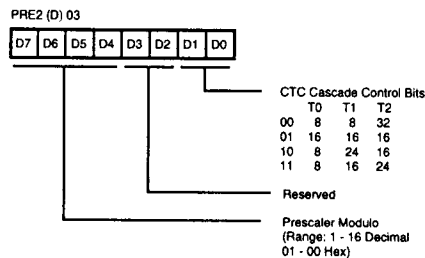


Figure 32. Prescaler 2 Register High Byte (03H: Write Only)

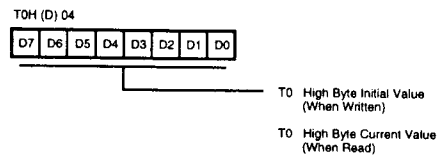


Figure 33. Counter Timer 0 Register High Byte (04H: Read/Write)

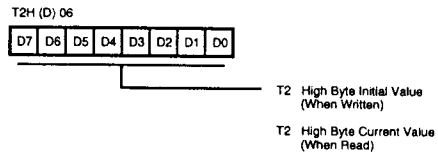


Figure 34. Counter Timer 2 Register High Byte (06H: Read/Write)

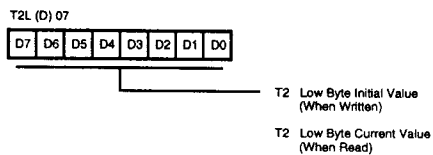


Figure 35. Counter Timer 2 Register Low Byte (07H: Read/Write)

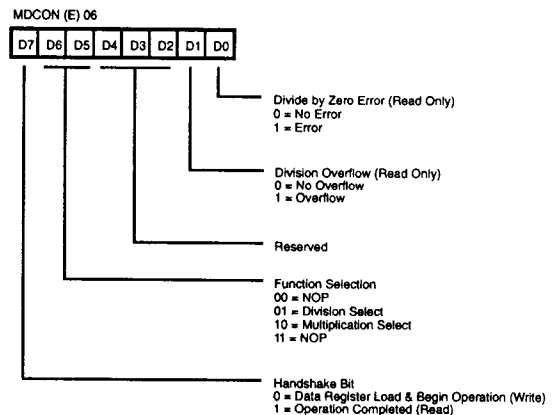
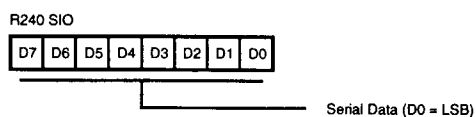
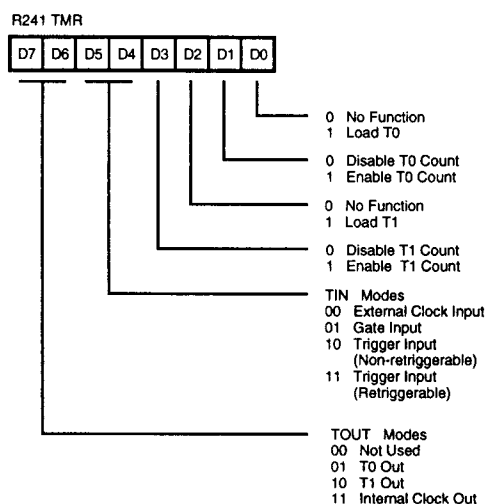


Figure 36. Multiply/Divide Control Register (MDCON)

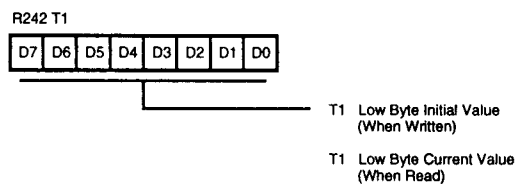
## Z8 CONTROL REGISTERS



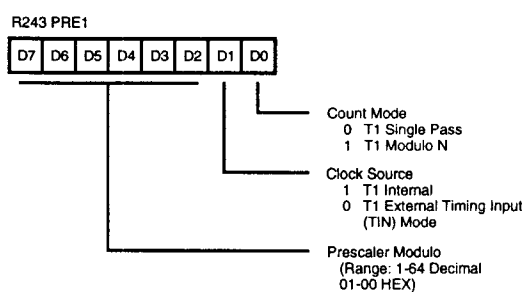
**Figure 37. Serial I/O Register**  
(F0H: Read/Write)



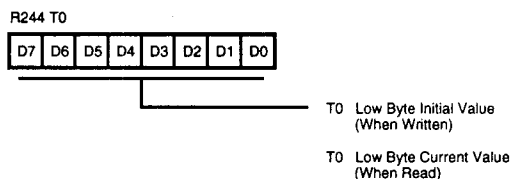
**Figure 38. Timer Mode Register**  
(F1H: Read/Write)



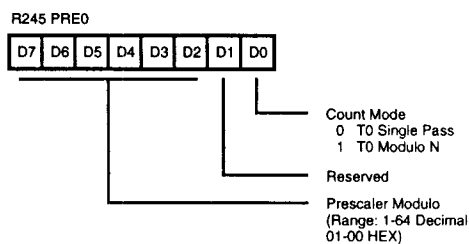
**Figure 39. Counter/Timer 1 Register**  
(F2H: Read/Write)



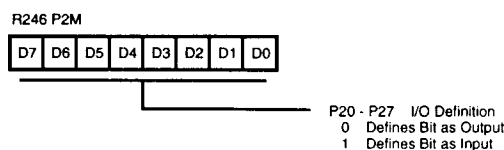
**Figure 40. Prescaler 1 Register**  
(F3H: Write Only)



**Figure 41. Counter/Timer 0 Register**  
(F4H: Read/Write)

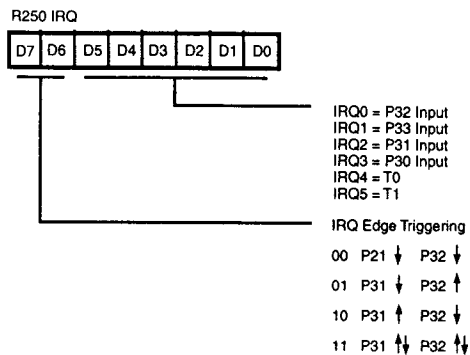


**Figure 42. Prescaler 0 Register**  
(F5H: Write Only)

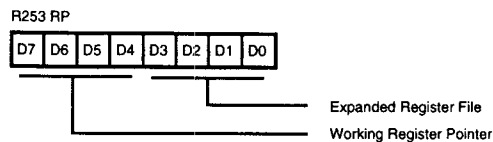


**Figure 43. Port 2 Mode Register**  
(F6H: Write Only)

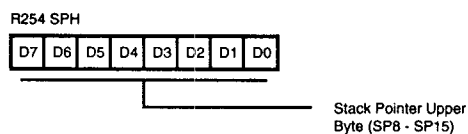




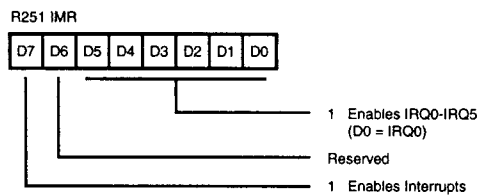
**Figure 47. Interrupt Request Register (FAH: Read/Write)**



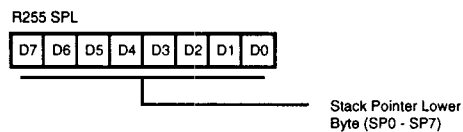
**Figure 50. Register Pointer (FDH: Read/Write)**



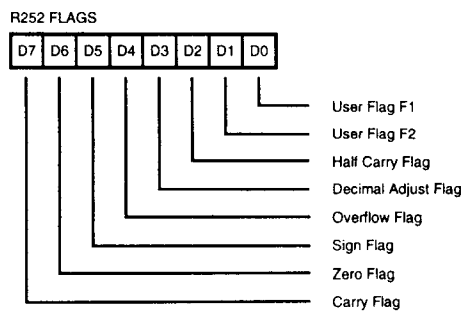
**Figure 51. Stack Pointer High (FEH: Read/Write)**



**Figure 48. Interrupt Mask Register (FBH: Read/Write)**



**Figure 52. Stack Pointer Low (FFH: Read/Write)**



**Figure 49. Flag Register (FCH: Read/Write)**

## CONDITION CODES

Value	Mnemonic	Meaning	Flags Set
1000		Always True	
0111	C	Carry	C = 1
1111	NC	No Carry	C = 0
0110	Z	Zero	Z = 1
1110	NZ	Not Zero	Z = 0
1101	PL	Plus	S = 0
0101	MI	Minus	S = 1
0100	OV	Overflow	V = 1
1100	NOV	No Overflow	V = 0
0110	EQ	Equal	Z = 1
1110	NE	Not Equal	Z = 0
1001	GE	Greater Than or Equal	(S XOR V) = 0
0001	LT	Less than	(S XOR V) = 1
1010	GT	Greater Than	[Z OR (S XOR V)] = 0
0010	LE	Less Than or Equal	[Z OR (S XOR V)] = 1
1111	UGE	Unsigned Greater Than or Equal	C = 0
0111	ULT	Unsigned Less Than	C = 1
1011	UGT	Unsigned Greater Than	(C = 0 AND Z = 0) = 1
0011	ULE	Unsigned Less Than or Equal	(C OR Z) = 1
0000		Never True	

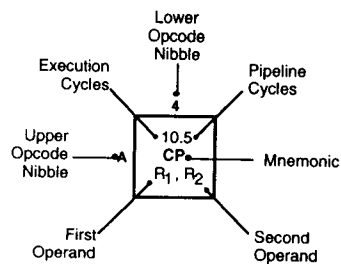
## INSTRUCTION SUMMARY (Continued)

Instruction and Operation	Address Mode dst src	Opcode Byte (Hex)	Flags Affected						
			C	Z	S	V	D	H	
<b>ADC</b> dst, src dst ← dst + src + C	†	1[ ]	*	*	*	*	0	*	
<b>ADD</b> dst, src dst ← dst + src	†	0[ ]	*	*	*	*	0	*	
<b>AND</b> dst, src dst ← dst AND src	†	5[ ]	-	*	*	0	-	-	
<b>CALL</b> dst SP ← SP - 2 @SP ← PC, PC ← dst	DA IRR	D6 D4	-	-	-	-	-	-	
<b>CCF</b> C ← NOT C		EF	*	-	-	-	-	-	
<b>CLR</b> dst dst ← 0	R IR	B0 B1	-	-	-	-	-	-	
<b>COM</b> dst dst ← NOT dst	R IR	60 61	-	*	*	0	-	-	
<b>CP</b> dst, src dst - src	†	A[ ]	*	*	*	*	-	-	
<b>DA</b> dst dst ← DA dst	R IR	40 41	*	*	*	X	-	-	
<b>DEC</b> dst dst ← dst - 1	R IR	00 01	-	*	*	*	-	-	
<b>DECW</b> dst dst ← dst - 1	RR IR	80 81	-	*	*	*	-	-	
<b>DI</b> IMR(7) ← 0		8F	-	-	-	-	-	-	
<b>DJNZ</b> r, dst r ← r - 1 if r ≠ 0 PC ← PC + dst Range: +127, -128	RA	rA r = 0 - F	-	-	-	-	-	-	
<b>EI</b> IMR(7) ← 1		9F	-	-	-	-	-	-	
<b>HALT</b>		7F	-	-	-	-	-	-	

Instruction and Operation	Address Mode dst src	Opcode Byte (Hex)	Flags Affected						
			C	Z	S	V	D	H	
<b>INC</b> dst dst ← dst + 1	r R IR	rE r = 0 - F 20 21	-	*	*	*	-	-	
<b>INCW</b> dst dst ← dst + 1	RR IR	A0 A1	-	*	*	*	-	-	
<b>IRET</b> FLAGS ← @SP; SP ← SP + 1 PC ← @SP; SP ← SP + 2; IMR(7) ← 1		BF	*	*	*	*	*	*	
<b>JP</b> cc, dst if cc is true PC ← dst	DA IRR	cD c = 0 - F 30	-	-	-	-	-	-	
<b>JR</b> cc, dst if cc is true, PC ← PC + dst Range: +127, -128	RA	cB c = 0 - F	-	-	-	-	-	-	
<b>LD</b> dst, src dst ← src	r r R r r X r lr R R R IR IR R	lm rC r8 r9 r = 0 - F C7 D7 E3 F3 E4 E5 E6 E7 F5	-	-	-	-	-	-	
<b>LDC</b> dst, src	r lrr	C2	-	-	-	-	-	-	
<b>LDCI</b> dst, src dst ← src r ← r + 1; rr ← rr + 1	lr lrr	C3	-	-	-	-	-	-	

# OPCODE MAP

		Lower Nibble (Hex)																
		0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
Upper Nibble (Hex)	0	6.5 DEC R1	6.5 DEC IR1	6.5 ADD r1, r2	6.5 ADD r1, Ir2	10.5 ADD R2, R1	10.5 ADD IR2, R1	10.5 ADD R1, IM	10.5 ADD IR1, IM	6.5 LD r1, R2	6.5 LD r2, R1	12/10.5 DJNZ r1, RA	12/10.0 JR cc, RA	6.5 LD r1, IM	12.10.0 JP cc, DA	6.5 INC r1		
	1	6.5 RLC R1	6.5 RLC IR1	6.5 ADC r1, r2	6.5 ADC r1, Ir2	10.5 ADC R2, R1	10.5 ADC IR2, R1	10.5 ADC R1, IM	10.5 ADC IR1, IM									
	2	6.5 INC R1	6.5 INC IR1	6.5 SUB r1, r2	6.5 SUB r1, Ir2	10.5 SUB R2, R1	10.5 SUB IR2, R1	10.5 SUB R1, IM	10.5 SUB IR1, IM									
	3	8.0 JP IRR1	6.1 SRP IM	6.5 SBC r1, r2	6.5 SBC r1, Ir2	10.5 SBC R2, R1	10.5 SBC IR2, R1	10.5 SBC R1, IM	10.5 SBC IR1, IM									
	4	8.5 DA R1	8.5 DA IR1	6.5 OR r1, r2	6.5 OR r1, Ir2	10.5 OR R2, R1	10.5 OR IR2, R1	10.5 OR R1, IM	10.5 OR IR1, IM									
	5	10.5 POP R1	10.5 POP IR1	6.5 AND r1, r2	6.5 AND r1, Ir2	10.5 AND R2, R1	10.5 AND IR2, R1	10.5 AND R1, IM	10.5 AND IR1, IM									
	6	6.5 COM R1	6.5 COM IR1	6.5 TCM r1, r2	6.5 TCM r1, Ir2	10.5 TCM R2, R1	10.5 TCM IR2, R1	10.5 TCM R1, IM	10.5 TCM IR1, IM								6.0 STOP	
	7	10/12.1 PUSH R2	12/14.1 PUSH IR2	6.5 TM r1, r2	6.5 TM r1, Ir2	10.5 TM R2, R1	10.5 TM IR2, R1	10.5 TM R1, IM	10.5 TM IR1, IM								7.0 HALT	
	8	10.5 DECW RR1	10.5 DECW IR1	12.0 LDE r1, Ir2	18.0 LDEI Ir1, Ir2													6.1 DI
	9	6.5 RL R1	6.5 RL IR1	12.0 LDE r2, Ir1	18.0 LDEI Ir2, Ir1													6.1 EI
	A	10.5 INCW RR1	10.5 INCW IR1	6.5 CP r1, r2	6.5 CP r1, Ir2	10.5 CP R2, R1	10.5 CP IR2, R1	10.5 CP R1, IM	10.5 CP IR1, IM								14.0 RET	
	B	6.5 CLR R1	6.5 CLR IR1	6.5 XOR r1, r2	6.5 XOR r1, Ir2	10.5 XOR R2, R1	10.5 XOR IR2, R1	10.5 XOR R1, IM	10.5 XOR IR1, IM								16.0 IRET	
	C	6.5 RRC R1	6.5 RRC IR1	12.0 LDC r1, Ir2	18.0 LDCI Ir1, Ir2				10.5 LD r1,x,R2								6.5 RCF	
	D	6.5 SRA R1	6.5 SRA IR1	12.0 LDC r2, Ir1	18.0 LDCI Ir2, Ir1	20.0 CALL* IRR1		20.0 CALL DA	10.5 LD r2,x,R1								6.5 SCF	
	E	6.5 RR R1	6.5 RR IR1		6.5 LD r1, Ir2	10.5 LD R2, R1	10.5 LD IR2, R1	10.5 LD R1, IM	10.5 LD IR1, IM								6.5 CCF	
	F	8.5 SWAP R1	8.5 SWAP IR1		6.5 LD Ir1, r2		10.5 LD R2, IR1										6.0 NOP	
		2		3		2		3		1								
		Bytes per Instruction																



## Legend:

R = 8-bit address  
r = 4-bit address  
R<sub>1</sub> or r<sub>2</sub> = Dst address  
R<sub>1</sub> or r<sub>2</sub> = Src address

## Sequence:

Opcode, First Operand,  
Second Operand

Note: The blank areas are not defined.

\* 2-byte instruction appears  
as a 3-byte instruction

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