



Welcome to **E-XFL.COM**

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Mounting Type Package / Case	Surface Mount 388-BBGA
Operating Temperature	0°C ~ 70°C (TA)
Oscillator Type	External
Data Converters	-
Voltage - Supply (Vcc/Vdd)	1.43V ~ 1.58V
RAM Size	32K x 8
EEPROM Size	-
Program Memory Type	ROMIess
Program Memory Size	-
Number of I/O	99
Peripherals	DMA, PWM, WDT
Connectivity	EBI/EMI, Ethernet, I²C, SPI, UART/USART, USB
Speed	200MHz
Core Size	32-Bit Single-Core
Core Processor	Coldfire V4E
Product Status	Not For New Designs



Maximum Ratings

1 Maximum Ratings

Table 1 lists maximum and minimum ratings for supply and operating voltages and storage temperature. Operating outside of these ranges may cause erratic behavior or damage to the processor.

Table 1. Absolute Maximum Ratings

Rating	Symbol	Value	Units
External (I/O pads) supply voltage (3.3-V power pins)	EV _{DD}	-0.3 to +4.0	V
Internal logic supply voltage	IV _{DD}	-0.5 to +2.0	V
Memory (I/O pads) supply voltage (2.5-V power pins)	SD V _{DD}	-0.3 to +4.0 SDR Memory -0.3 to +2.8 DDR Memory	V
PLL supply voltage	PLL V _{DD}	-0.5 to +2.0	V
Internal logic supply voltage, input voltage level	V _{in}	-0.5 to +3.6	V
Storage temperature range	T _{stg}	-55 to +150	°C

2 Thermal Characteristics

2.1 Operating Temperatures

Table 2 lists junction and ambient operating temperatures.

Table 2. Operating Temperatures

Characteristic	Symbol	Value	Units
Maximum operating junction temperature	T _j	105	°C
Maximum operating ambient temperature	T _{Amax}	<70 ¹	°C
Minimum operating ambient temperature	T _{Amin}	-0	°C

This published maximum operating ambient temperature should be used only as a system design guideline. All device operating parameters are guaranteed only when the junction temperature lies within the specified range.

2.2 Thermal Resistance

Table 3 lists thermal resistance values.

Table 3. Thermal Resistance

Characteristic		Symbol	Value	Unit
324 pin TEPBGA — Junction to ambient, natural convection	Four layer board (2s2p)	θ_{JMA}	20-22 ^{1,2}	°CW
388 pin TEPBGA — Junction to ambient, natural convection	Four layer board (2s2p)	θ_{JMA}	19 ^{1,2}	°CW



Table 3.	Thermal	Resistance	(continued)	١
I abic o.	HILCHINA	I ICSISIALICC	(COIILIIIACA)	,

Characteristic		Symbol	Value	Unit
Junction to ambient (@200 ft/min)	Four layer board (2s2p)	θ_{JMA}	16 ^{1,2}	°CW
Junction to board	_	$\theta_{\sf JB}$	11 ³	°CW
Junction to case	_	θJC	7 ⁴	°CW
Junction to top of package	Natural convection	Ψ_{jt}	2 ^{1,5}	°CW

 $[\]theta_{JA}$ and Ψ_{jt} parameters are simulated in accordance with EIA/JESD Standard 51-2 for natural convection. Freescale recommends the use of θ_{JA} and power dissipation specifications in the system design to prevent device junction temperatures from exceeding the rated specification. System designers should be aware that device junction temperatures can be significantly influenced by board layout and surrounding devices. Conformance to the device junction temperature specification can be verified by physical measurement in the customer's system using the Ψ_{jt} parameter, the device power dissipation, and the method described in EIA/JESD Standard 51-2.

3 DC Electrical Specifications

Table 4 lists DC electrical operating temperatures. This table is based on an operating voltage of EV_{DD} = 3.3 $V_{DC} \pm 0.3 V_{DC}$ and IV_{DD} of 1.5 \pm 0.07 V_{DC} .

Table 4. DC Electrical Specifications

Characteristic	Symbol	Min	Max	Units
External (I/O pads) operation voltage range	EV _{DD}	3.0	3.6	V
Memory (I/O pads) operation voltage range (DDR Memory)	SD V _{DD}	2.30	2.70	V
Internal logic operation voltage range ¹	IV _{DD}	1.43	1.58	V
PLL Analog operation voltage range ¹	PLL V _{DD}	1.43	1.58	V
USB oscillator operation voltage range	USB_OSV _{DD}	3.0	3.6	V
USB digital logic operation voltage range	USBV _{DD}	3.0	3.6	V
USB PHY operation voltage range	USB_PHYV _{DD}	3.0	3.6	V
USB oscillator analog operation voltage range	USB_OSCAV _{DD}	1.43	1.58	V
USB PLL operation voltage range	USB_PLLV _{DD}	1.43	1.58	V
Input high voltage SSTL 3.3V/2.5V ²	V _{IH}	V _{REF} + 0.3	SD V _{DD} + 0.3	V
Input low voltage SSTL 3.3V/2.5V ²	V _{IL}	V _{SS} - 0.3	V _{REF} - 0.3	V
Input high voltage 3.3V I/O pins	V _{IH}	0.7 x EV _{DD}	EV _{DD} + 0.3	V
Input low voltage 3.3V I/O pins	V _{IL}	V _{SS} - 0.3	0.35 x EV _{DD}	V

² Per JEDEC JESD51-6 with the board horizontal.

Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.

Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).

Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written as Psi-JT.



Hardware Design Considerations

Table 4. DC Electrical Specifications (continued)

Characteristic	Symbol	Min	Max	Units
Output high voltage I _{OH} = 8 mA, 16 mA,24 mA	V _{OH}	2.4	_	V
Output low voltage I _{OL} = 8 mA, 16 mA,24 mA ⁵	V _{OL}	_	0.5	V
Capacitance ³ , V _{in} = 0 V, f = 1 MHz	C _{IN}	_	TBD	pF
Input leakage current	I _{in}	-1.0	1.0	μΑ

 IV_{DD} and PLL V_{DD} should be at the same voltage. PLL V_{DD} should have a filtered input. Please see Figure 2 for an example circuit. There are three PLL V_{DD} inputs. A filter circuit should used on each PLL V_{DD} input.

4 Hardware Design Considerations

4.1 PLL Power Filtering

To further enhance noise isolation, an external filter is strongly recommended for PLL analog V_{DD} pins. The filter shown in Figure 2 should be connected between the board V_{DD} and the PLL V_{DD} pins. The resistor and capacitors should be placed as close to the dedicated PLL V_{DD} pin as possible.

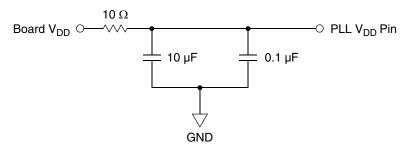


Figure 2. System PLL V_{DD} Power Filter

4.2 Supply Voltage Sequencing and Separation Cautions

Figure 3 shows situations in sequencing the I/O V_{DD} (EV $_{DD}$), SDRAM V_{DD} (SD V_{DD}), PLL V_{DD} (PLL V_{DD}), and Core V_{DD} (IV $_{DD}$).

 $^{^{2}\,}$ This specification is guaranteed by design and is not 100% tested.

 $^{^{3}\,}$ Capacitance C_{IN} is periodically sampled rather than 100% tested.



Output Driver Capability and Loading

4.4.1 Bias Resistor

The USBRBIAS resistor should be placed as close to the dedicated USB 2.0 pins as possible. The tolerance should be $\pm 1\%$.



5 Output Driver Capability and Loading

Table 6 lists values for drive capability and output loading.

Table 6. I/O Driver Capability¹

Signal	Drive Capability	Output Load (C _L)
SDRAMC (SDADDR[12:0], SDDATA[31:0], RAS, CAS, SDDM[3:0], SDWE, SDBA[1:0]	24 mA	15 pF
SDRAMC DQS and clocks (SDDQS[3:0], SDRDQS, SDCLK[1:0], SDCLK[1:0], SDCKE)	24 mA	15 pF
SDRAMC chip selects (SDCS[3:0])	24 mA	15 pF
FlexBus (AD[31:0], FBCS[5:0], ALE, R/W, BE/BWE[3:0], OE)	16 mA	30 pF
FEC (EnMDIO, EnMDC, EnTXEN, EnTXD[3:0], EnTXER	8 mA	15 pF
Timer (TOUT[3:0])	8 mA	50 pF
DACK[1:0]	8 mA	30 pF
PSC (PSCnTXD[3:0], PSCnRTS/PSCnFSYNC,	8 mA	30 pF
DSPI (DSPISOUT, DSPICS0/SS, DSPICS[2:3], DSPICS5/PCSS)	24 mA	50 pF
PCI (PCIAD[31:0], PCIBG[4:1], PCIBG0/PCIREQOUT, PCIDEVSEL, PCICXBE[3:0], PCIFRM, PCIPERR, PCIRESET, PCISERR, PCISTOP, PCIPAR, PCITRDY, PCIIRDY	16 mA	50 pF
I2C (SCL, SDA)	8 mA	50 pF
BDM (PSTCLK, PSTDDATA[7:0], DSO/TDO,	8 mA	25 pF
RSTO	8 mA	50 pF

The device's pads have balanced sink and source current. The drive capability is the same as the sink capability.



8.1 FlexBus AC Timing Characteristics

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the system clock.

Table 10. FlexBus AC Timing Specifications

Num	Characteristic	Min	Max	Unit	Notes
	Frequency of Operation	25	66	Mhz	1
FB1	Clock Period (CLKIN)	15.15	40	ns	2
FB2	Address, Data, and Control Output Valid (AD[31:0], FBCS[5:0], R/W, ALE, TSIZ[1:0], BE/BWE[3:0], OE, and TBST)	_	7.0	ns	3
FB3	Address, Data, and Control Output Hold ((AD[31:0], FBCS[5:0], R/W, ALE, TSIZ[1:0], BE/BWE[3:0], OE, and TBST)	1		ns	3, 4
FB4	Data Input Setup	3.5	_	ns	
FB5	Data Input Hold	0	_	ns	
FB6	Transfer Acknowledge (TA) Input Setup	4	_	ns	
FB7	Transfer Acknowledge (TA) Input Hold	0	_	ns	
FB8	Address Output Valid (PCIAD[31:0])	_	7.0	ns	5
FB9	Address Output Hold (PCIAD[31:0])	0		ns	5

¹ The frequency of operation is the same as the PCI frequency of operation. The MCF547X supports a single external reference clock (CLKIN). This signal defines the frequency of operation for FlexBus and PCI.

² Max cycle rate is determined by CLKIN and how the user has the system PLL configured.

³ Timing for chip selects only applies to the FBCS[5:0] signals. Please see Section 9.2, "DDR SDRAM AC Timing Characteristics" for SDCS[3:0] timing.

⁴ The FlexBus supports programming an extension of the address hold. Please consult the MCF547X specification manual for more information.

These specs are used when the PCIAD[31:0] signals are configured as 32-bit, non-muxed FlexBus address signals.



FlexBus

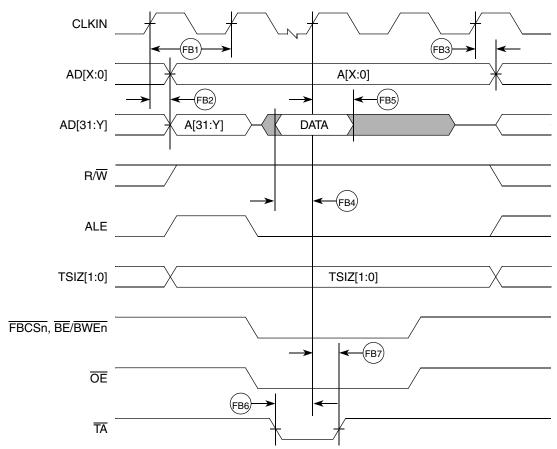


Figure 11. FlexBus Read Timing



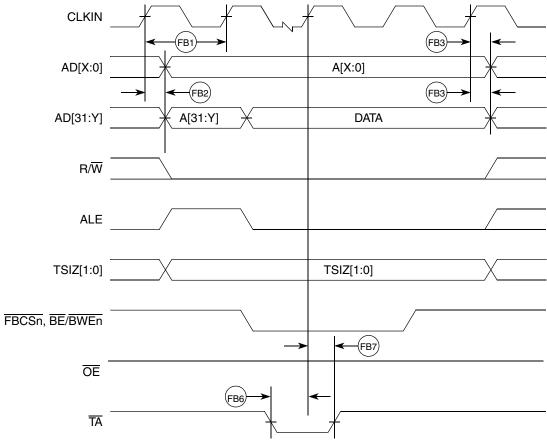


Figure 12. FlexBus Write Timing

9 SDRAM Bus

The SDRAM controller supports accesses to main SDRAM memory from any internal master. It supports standard SDRAM or double data rate (DDR) SDRAM, but it does not support both at the same time. The SDRAM controller uses SSTL2 and SSTL3 I/O drivers. Both SSTL drive modes are programmable for Class I or Class II drive strength.

9.1 SDR SDRAM AC Timing Characteristics

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the memory bus clock, when operating in SDR mode on write cycles and relative to SDR_DQS on read cycles. The MCF547x SDRAM controller is a DDR controller that has an SDR mode. Because it is designed to support DDR, a DQS pulse must be supplied to the MCF547x for each data beat of an SDR read. The MCF547x accomplishes this by asserting a signal called SDR_DQS during read cycles. Care must be taken during board design to adhere to the following guidelines and specs with regard to the SDR_DQS signal and its usage.



SDRAM Bus

Table 11. SDR Timing Specifications

Symbol	Characteristic	Min	Max	Unit	Notes
	Frequency of Operation	0	133	Mhz	1
SD1	Clock Period (t _{CK})	7.52	12	ns	2
SD2	Clock Skew (t _{SK})		TBD		
SD3	Pulse Width High (t _{CKH})	0.45	0.55	SDCLK	3
SD4	Pulse Width Low (t _{CKL})	0.45	0.55	SDCLK	4
SD5	Address, CKE, CAS, RAS, WE, BA, CS - Output Valid (t _{CMV})		0.5 × SDCLK + 1.0ns	ns	
SD6	Address, CKE, CAS, RAS, WE, BA, CS - Output Hold (t _{CMH})	2.0		ns	
SD7	SDRDQS Output Valid (t _{DQSOV})		Self timed	ns	5
SD8	SDDQS[3:0] input setup relative to SDCLK (t _{DQSIS})	0.25 × SDCLK	0.40 × SDCLK	ns	6
SD9	SDDQS[3:0] input hold relative to SDCLK (t _{DQSIH})	Does not apply	. 0.5 SDCLK fixe	d width.	7
SD10	Data Input Setup relative to SDCLK (reference only) (t _{DIS})	0.25 × SDCLK		ns	8
SD11	Data Input Hold relative to SDCLK (reference only) (t _{DIH})	1.0		ns	
SD12	Data and Data Mask Output Valid (t _{DV})		0.75 × SDCLK +0.500ns	ns	
SD13	Data and Data Mask Output Hold (t _{DH})	1.5		ns	

¹ The frequency of operation is 2x or 4x the CLKIN frequency of operation. The MCF547X supports a single external reference clock (CLKIN). This signal defines the frequency of operation for FlexBus and PCI, but SDRAM clock operates at the same frequency as the internal bus clock. Please see the PLL chapter of the MCF547X Reference Manual for more information on setting the SDRAM clock rate.

² SDCLK is one SDRAM clock in (ns).

³ Pulse width high plus pulse width low cannot exceed min and max clock period.

⁴ Pulse width high plus pulse width low cannot exceed min and max clock period.

⁵ SDR_DQS is designed to pulse 0.25 clock before the rising edge of the memory clock. This is a guideline only. Subtle variation from this guideline is expected. SDR_DQS only pulses during a read cycle and one pulse occurs for each data beat.

⁶ SDR_DQS is designed to pulse 0.25 clock before the rising edge of the memory clock. This spec is a guideline only. Subtle variation from this guideline is expected. SDR_DQS only pulses during a read cycle and one pulse occurs for each data beat.

The SDR_DQS pulse is designed to be 0.5 clock in width. The timing of the rising edge is most important. The falling edge does not affect the memory controller.

Because a read cycle in SDR mode uses the DQS circuit within the MCF547X, it is most critical that the data valid window be centered 1/4 clk after the rising edge of DQS. Ensuring that this happens results in successful SDR reads. The input setup spec is provided as guidance.



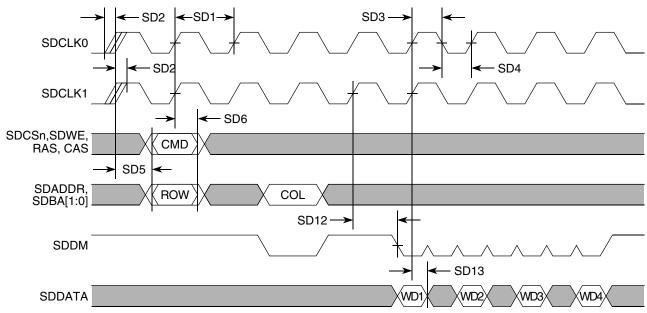


Figure 13. SDR Write Timing

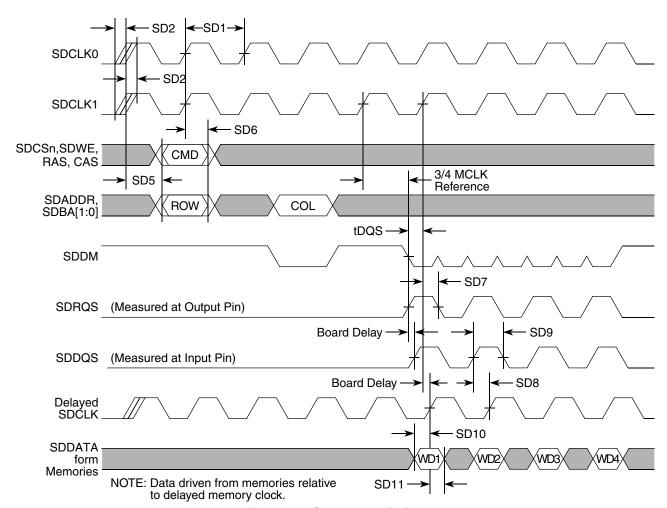


Figure 14. SDR Read Timing

MCF547x ColdFire® Microprocessor, Rev. 4



SDRAM Bus

9.2 DDR SDRAM AC Timing Characteristics

When using the DDR SDRAM controller, the following timing numbers must be followed to properly latch or drive data onto the memory bus. All timing numbers are relative to the four DQS byte lanes.

Table 12shows the DDR clock crossover specifications.

Table 12. DDR Clock Crossover Specifications

Symbol	Characteristic	Min	Max	Unit
V _{MP}	Clock output mid-point voltage	1.05	1.45	٧
V _{OUT}	Clock output voltage level	-0.3	SD_VDD + 0.3	V
V _{ID}	Clock output differential voltage (peak to peak swing)	0.7	SD_VDD + 0.6	V
V _{IX}	Clock crossing point voltage ¹	1.05	1.45	V

The clock crossover voltage is only guaranteed when using the highest drive strength option for the SDCLK[1:0] and SDCLK[1:0] signals.

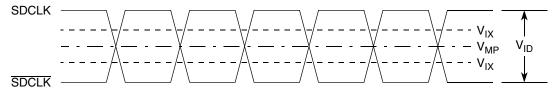


Figure 15. DDR Clock Timing Diagram

Table 13. DDR Timing Specifications

Symbol	Characteristic	Min	Max	Unit	Notes
	Frequency of Operation	50 ¹	133	MHz	2
DD1	Clock Period (t _{CK})	7.52	12	ns	3
DD2	Pulse Width High (t _{CKH})	0.45	0.55	SDCLK	4
DD3	Pulse Width Low (t _{CKL})	0.45	0.55	SDCLK	5
DD4	Address, SDCKE, CAS, RAS, WE, SDBA, SDCS—Output Valid (t _{CMV})	_	0.5 × SDCLK + 1.0 ns	ns	6
DD5	Address, SDCKE, $\overline{\text{CAS}}$, $\overline{\text{RAS}}$, $\overline{\text{WE}}$, SDBA, $\overline{\text{SDCS}}$ —Output Hold (t_{CMH})	2.0	_	ns	
DD6	Write Command to first DQS Latching Transition (t _{DQSS})	_	1.25	SDCLK	
DD7	Data and Data Mask Output Setup (DQ->DQS) Relative to DQS (DDR Write Mode) (t _{QS})	1.0	_	ns	7 8
DD8	Data and Data Mask Output Hold (DQS->DQ) Relative to DQS (DDR Write Mode) (t _{QH})	1.0	_	ns	9
DD9	Input Data Skew Relative to DQS (Input Setup) (t _{IS})		1	ns	10
DD10	Input Data Hold Relative to DQS (t _{IH})	0.25 × SDCLK + 0.5ns	_	ns	11
DD11	DQS falling edge to SDCLK rising (output setup time) (t _{DSS})	0.5	_	ns	
DD12	DQS falling edge from SDCLK rising (output hold time) (t _{DSH})	0.5	_	ns	



Table 13. DDR Timing Specifications (continued)

Symbol	Characteristic	Min	Max	Unit	Notes
DD13	DQS input read preamble width (t _{RPRE})	0.9	1.1	SDCLK	
DD14	DQS input read postamble width (t _{RPST})	0.4	0.6	SDCLK	
DD15	DQS output write preamble width (t _{WPRE})	0.25	_	SDCLK	
DD16	DQS output write postamble width (t _{WPST})	0.4	0.6	SDCLK	

- 1 DDR memories typically have a minimum speed specification of 83 MHz. Check memory component specifications to verify.
- The frequency of operation is 2x or 4x the CLKIN frequency of operation. The MCF547X supports a single external reference clock (CLKIN). This signal defines the frequency of operation for FlexBus and PCI, but SDRAM clock operates at the same frequency as the internal bus clock. Please see the reset configuration signals description in the "Signal Descriptions" chapter within the MCF547x Reference Manual.
- SDCLK is one memory clock in (ns).
- ⁴ Pulse width high plus pulse width low cannot exceed max clock period.
- ⁵ Pulse width high plus pulse width low cannot exceed max clock period.
- ⁶ Command output valid should be 1/2 the memory bus clock (SDCLK) plus some minor adjustments for process, temperature, and voltage variations.
- ⁷ This specification relates to the required input setup time of today's DDR memories. SDDATA[31:24] is relative to SDDQS3, SDDATA[23:16] is relative to SDDQS2, SDDATA[15:8] is relative to SDDQS1, and SDDATA[7:0] is relative SDDQS0.
- ⁸ The first data beat is valid before the first rising edge of SDDQS and after the SDDQS write preamble. The remaining data beats is valid for each subsequent SDDQS edge.
- This specification relates to the required hold time of today's DDR memories. SDDATA[31:24] is relative to SDDQS3, SDDATA[23:16] is relative to SDDQS2, SDDATA[15:8] is relative to SDDQS1, and SDDATA[7:0] is relative SDDQS0.
- ¹⁰ Data input skew is derived from each SDDQS clock edge. It begins with a SDDQS transition and ends when the last data line becomes valid. This input skew must include DDR memory output skew and system level board skew (due to routing or other factors).
- ¹¹ Data input hold is derived from each SDDQS clock edge. It begins with a SDDQS transition and ends when the first data line becomes invalid.



SDRAM Bus

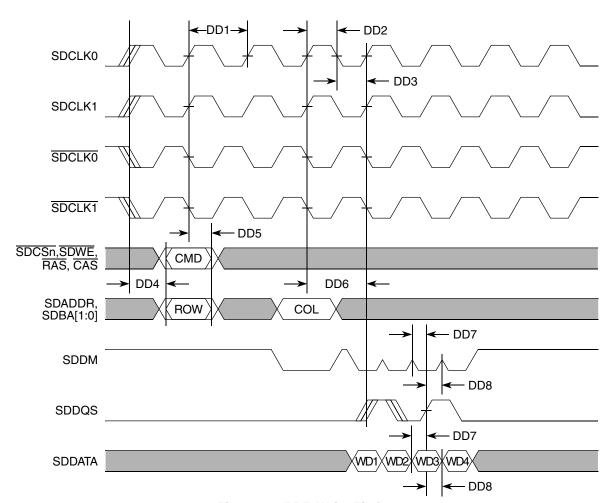


Figure 16. DDR Write Timing



Num	Characteristic	Min	Max	Unit
M1	RXD[3:0], RXDV, RXER to RXCLK setup	5	_	ns
M2	RXCLK to RXD[3:0], RXDV, RXER hold	5	_	ns
МЗ	RXCLK pulse width high	35%	65%	RXCLK period
M4	RXCLK pulse width low	35%	65%	RXCLK period

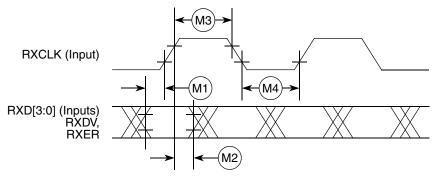


Figure 19. MII Receive Signal Timing Diagram

11.2 MII Transmit Signal Timing

Table 16. MII Transmit Signal Timing

Num	Characteristic	Min	Max	Unit
M5	TXCLK to TXD[3:0], TXEN, TXER invalid	0	_	ns
M6	TXCLK to TXD[3:0], TXEN, TXER valid	_	25	ns
M7	TXCLK pulse width high	35%	65%	TXCLK period
M8	TXCLK pulse width low	35%	65%	TXCLK period

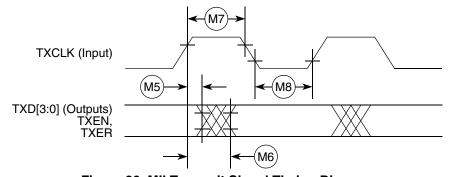


Figure 20. MII Transmit Signal Timing Diagram

Fast Ethernet AC Timing Specifications

11.3 MII Async Inputs Signal Timing (CRS, COL)

Table 17. MII Transmit Signal Timing

Num	Characteristic	Min	Max	Unit
М9	CRS, COL minimum pulse width	1.5		TX_CLK period

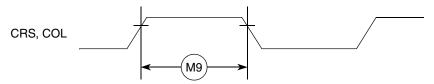


Figure 21. MII Async Inputs Timing Diagram

11.4 MII Serial Management Channel Timing (MDIO, MDC)

Table 18. MII Serial Management Channel Signal Timing

Num	Characteristic	Min	Max	Unit
M10	MDC falling edge to MDIO output invalid (min prop delay)	0	_	ns
M11	MDC falling edge to MDIO output valid (max prop delay)	_	25	ns
M12	MDIO (input) to MDC rising edge setup	10	_	ns
M13	MDIO (input) to MDC rising edge hold	0	_	ns
M14	MDC pulse width high	40%	60%	MDC period
M15	MDC pulse width low	40%	60%	MDC period

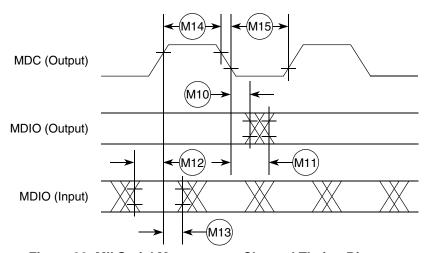


Figure 22. MII Serial Management Channel TIming Diagram

24 Freescale Semiconductor

MCF547x ColdFire® Microprocessor, Rev. 4



JTAG and Boundary Scan Timing

- Output numbers depend on the value programmed into the IFDR; an IFDR programmed with the maximum frequency (IFDR = 0x20) results in minimum output timings as shown in Table 21. The I²C interface is designed to scale the actual data transition time to move it to the middle of the SCL low period. The actual position is affected by the prescale and division values programmed into the IFDR; however, the numbers given in Table 21 are minimum values.
- Because SCL and SDA are open-collector-type outputs, which the processor can only actively drive low, the time SCL or SDA take to reach a high level depends on external signal capacitance and pull-up resistor values.
- ³ Specified at a nominal 50-pF load.

Figure 23 shows timing for the values in Table 20 and Table 21.

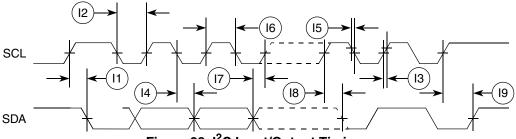


Figure 23. I²C Input/Output Timings

14 JTAG and Boundary Scan Timing

Table 22. JTAG and Boundary Scan Timing

Num	Characteristics ¹	Symbol	Min	Max	Unit
J1	TCLK Frequency of Operation	f _{JCYC}	DC	10	MHz
J2	TCLK Cycle Period	t _{JCYC}	2	_	t _{CK}
J3	TCLK Clock Pulse Width	t _{JCW}	15.15	_	ns
J4	TCLK Rise and Fall Times	t _{JCRF}	0.0	3.0	ns
J5	Boundary Scan Input Data Setup Time to TCLK Rise	t _{BSDST}	5.0	_	ns
J6	Boundary Scan Input Data Hold Time after TCLK Rise	t _{BSDHT}	24.0	_	ns
J7	TCLK Low to Boundary Scan Output Data Valid	t _{BSDV}	0.0	15.0	ns
J8	TCLK Low to Boundary Scan Output High Z	t _{BSDZ}	0.0	15.0	ns
J9	TMS, TDI Input Data Setup Time to TCLK Rise	t _{TAPBST}	5.0	_	ns
J10	TMS, TDI Input Data Hold Time after TCLK Rise	t _{TAPBHT}	10.0	_	ns
J11	TCLK Low to TDO Data Valid	t _{TDODV}	0.0	20.0	ns
J12	TCLK Low to TDO High Z	t _{TDODZ}	0.0	15.0	ns
J13	TRST Assert Time	t _{TRSTAT}	100.0	_	ns
J14	TRST Setup Time (Negation) to TCLK High	t _{TRSTST}	10.0	_	ns

¹ MTMOD is expected to be a static signal. Hence, it is not associated with any timing



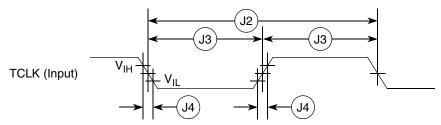


Figure 24. Test Clock Input Timing

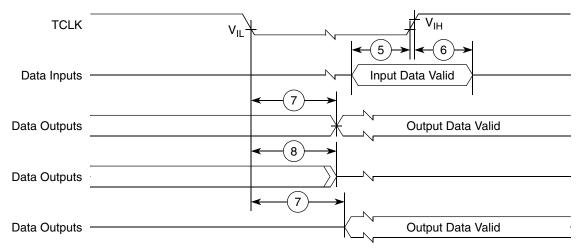


Figure 25. Boundary Scan (JTAG) Timing

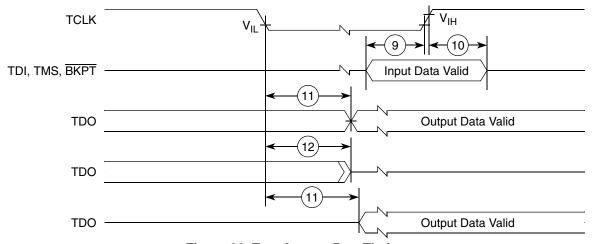


Figure 26. Test Access Port Timing

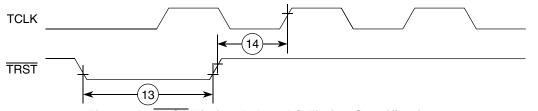


Figure 27. TRST Timing Debug AC Timing Specifications

MCF547x ColdFire® Microprocessor, Rev. 4



JTAG and Boundary Scan Timing

Table 23 lists specifications for the debug AC timing parameters shown in Figure 29.

Table 23. Debug AC Timing Specifications

Num	Characteristic	66 MHz		Units	
Num	Characteristic	Min	Max	Onits	
D1	PSTDDATA to PSTCLK setup	4.5	_	ns	
D2	PSTCLK to PSTDDATA hold	4.5	_	ns	
D3	DSI-to-DSCLK setup	1	_	PSTCLKs	
D4 ¹	DSCLK-to-DSO hold	4	_	PSTCLKs	
D5	DSCLK cycle time	5	_	PSTCLKs	

¹ DSCLK and DSI are synchronized internally. D4 is measured from the synchronized DSCLK input relative to the rising edge of CLKOUT.

Figure 28 shows real-time trace timing for the values in Table 23.

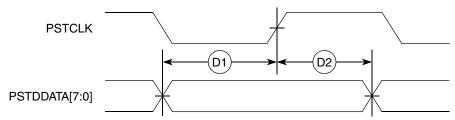


Figure 28. Real-Time Trace AC Timing

Figure 29 shows BDM serial port AC timing for the values in Table 23.

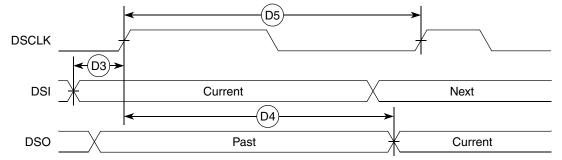
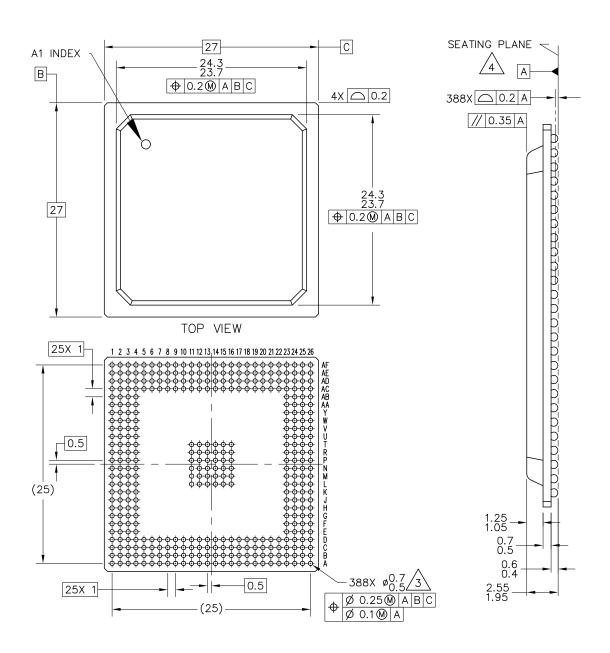


Figure 29. BDM Serial Port AC Timing



17 Case Drawing



© FREESCALE SEMICONDUCTOR, BOTTOM ALL RIGHTS RESERVED.	PRINT VERSION NO	SIDE VIEW T TO SCALE		
1 MM PITCH (OMPAC)		DOCUMENT NO: 98ARS23880W REV: C		REV: C
		CASE NUMBER: 1164-02 25 JAN		25 JAN 2007
		ANDARD: JEI	DEC MS-034 AAL-1	



THIS PAGE INTENTIONALLY BLANK



How to Reach Us:

Home Page:

www.freescale.com

Web Support:

http://www.freescale.com/support

USA/Europe or Locations Not Listed: Freescale Semiconductor, Inc. Technical Information Center, EL516 2100 East Elliot Road

Tempe, Arizona 85284 +1-800-521-6274 or +1-480-768-2130 www.freescale.com/support

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH **Technical Information Center** Schatzbogen 7 81829 Muenchen, Germany +44 1296 380 456 (English) +46 8 52200080 (English) +49 89 92103 559 (German) +33 1 69 35 48 48 (French)

Japan:

Freescale Semiconductor Japan Ltd. Headquarters ARCO Tower 15F 1-8-1, Shimo-Meguro, Meguro-ku, Tokyo 153-0064 Japan 0120 191014 or +81 3 5437 9125 support.japan@freescale.com

www.freescale.com/support

Asia/Pacific:

Freescale Semiconductor Hong Kong Ltd. Technical Information Center 2 Dai King Street Tai Po Inďustrial Estate Tai Po, N.T., Hong Kong +800 2666 8080 support.asia@freescale.com

For Literature Requests Only: Freescale Semiconductor Literature Distribution Center P.O. Box 5405 Denver, Colorado 80217 1-800-441-2447 or 303-675-2140 Fax: 303-675-2150 LDCForFreescaleSemiconductor@hibbertgroup.com

Document Number: MCF5475EC

Rev. 4 12/2007 Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductor products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document.

Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals", must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.

RoHS-compliant and/or Pb-free versions of Freescale products have the functionality and electrical characteristics as their non-RoHS-compliant and/or non-Pb-free counterparts. For further information, see http://www.freescale.com or contact your Freescale sales representative.

For information on Freescale's Environmental Products program, go to http://www.freescale.com/epp.

Freescale™ and the Freescale logo are trademarks of Freescale Semiconductor, Inc. All other product or service names are the property of their respective owners. © Freescale Semiconductor, Inc. 2007. All rights reserved.

