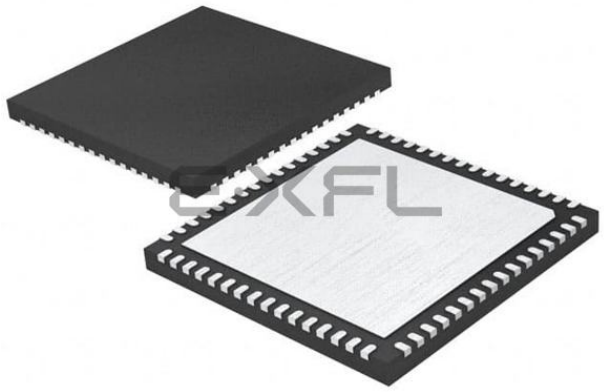

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## What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Active |
| Core Processor | dsPIC |
| Core Size | 16-Bit |
| Speed | 70 MIPs |
| Connectivity | CANbus, I²C, IrDA, LINbus, SPI, UART/USART |
| Peripherals | Brown-out Detect/Reset, DMA, POR, PWM, WDT |
| Number of I/O | 53 |
| Program Memory Size | 128KB (43K x 24) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 8K x 16 |
| Voltage - Supply (Vcc/Vdd) | 3V ~ 3.6V |
| Data Converters | A/D 16x10b/12b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 64-VFQFN Exposed Pad |
| Supplier Device Package | 64-VQFN (9x9) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep128gp506-i-mr |

# 3.0 CPU

**Note 1:** This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"CPU"** (DS70359) in the "*dsPIC33/PIC24 Family Reference Manual*", which is available from the Microchip web site (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for digital signal processing. The CPU has a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M x 24 bits of user program memory space.

An instruction prefetch mechanism helps maintain throughput and provides predictable execution. Most instructions execute in a single-cycle effective execution rate, with the exception of instructions that change the program flow, the double-word move (`MOV.D`) instruction, PSV accesses and the table instructions. Overhead-free program loop constructs are supported using the `DO` and `REPEAT` instructions, both of which are interruptible at any point.

## 3.1 Registers

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X devices have sixteen, 16-bit working registers in the programmer's model. Each of the working registers can act as a data, address or address offset register. The 16th working register (W15) operates as a Software Stack Pointer for interrupts and calls.

## 3.2 Instruction Set

The instruction set for dsPIC33EPXXXGP50X and dsPIC33EPXXXMC20X/50X devices has two classes of instructions: the MCU class of instructions and the DSP class of instructions. The instruction set for PIC24EPXXXGP/MC20X devices has the MCU class of instructions only and does not support DSP instructions. These two instruction classes are seamlessly integrated into the architecture and execute from a single execution unit. The instruction set includes many addressing modes and was designed for optimum C compiler efficiency.

## 3.3 Data Space Addressing

The base Data Space can be addressed as 64 Kbytes (32K words).

The Data Space includes two ranges of memory, referred to as X and Y data memory. Each memory range is accessible through its own independent Address Generation Unit (AGU). The MCU class of instructions operates solely through the X memory AGU, which accesses the entire memory map as one linear Data Space. On dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices, certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y Data Spaces have memory locations that are device-specific, and are described further in the data memory maps in **Section 4.2 "Data Address Space"**.

The upper 32 Kbytes of the Data Space memory map can optionally be mapped into Program Space (PS) at any 32-Kbyte aligned program word boundary. The Program-to-Data Space mapping feature, known as Program Space Visibility (PSV), lets any instruction access Program Space as if it were Data Space. Moreover, the Base Data Space address is used in conjunction with a Read or Write Page register (DSRPAG or DSWPAG) to form an Extended Data Space (EDS) address. The EDS can be addressed as 8M words or 16 Mbytes. Refer to the **"Data Memory"** (DS70595) and **"Program Memory"** (DS70613) sections in the *"dsPIC33/PIC24 Family Reference Manual"* for more details on EDS, PSV and table accesses.

On the dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices, overhead-free circular buffers (Modulo Addressing) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. The X AGU Circular Addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data re-ordering for radix-2 FFT algorithms. PIC24EPXXXGP/MC20X devices do not support Modulo and Bit-Reversed Addressing.

## 3.4 Addressing Modes

The CPU supports these addressing modes:

- Inherent (no operand)
- Relative
- Literal
- Memory Direct
- Register Direct
- Register Indirect

Each instruction is associated with a predefined addressing mode group, depending upon its functional requirements. As many as six addressing modes are supported for each instruction.

**TABLE 4-21: ECAN1 REGISTER MAP WHEN WIN (C1CTRL1<0>) = 0 OR 1 FOR dsPIC33EPXXXMC/GP50X DEVICES ONLY**

| File Name | Addr. | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| C1CTRL1 | 0400 | — | — | CSIDL | ABAT | CANCKS | REQOP<2:0> | | | OPMODE<2:0> | | | — | CANCAP | — | — | WIN | 0480 |
| C1CTRL2 | 0402 | — | — | — | — | — | — | — | — | — | — | — | DNCNT<4:0> | | | | | 0000 |
| C1VEC | 0404 | — | — | — | FILHIT<4:0> | | | | | — | ICODE<6:0> | | | | | | | 0040 |
| C1FCTRL | 0406 | DMABS<2:0> | | | — | — | — | — | — | — | — | — | FSA<4:0> | | | | | 0000 |
| C1FIFO | 0408 | — | — | FBP<5:0> | | | | | | — | — | FNRB<5:0> | | | | | | 0000 |
| C1INTF | 040A | — | — | TXBO | TXBP | RXBP | TXWAR | RXWAR | EWARN | IVRIF | WAKIF | ERRIF | — | FIFOIF | RBOVIF | RBIF | TBIF | 0000 |
| C1INTE | 040C | — | — | — | — | — | — | — | — | IVRIE | WAKIE | ERRIE | — | FIFOIE | RBOVIE | RBIE | TBIE | 0000 |
| C1EC | 040E | TERRCNT<7:0> | | | | | | | | RERRCNT<7:0> | | | | | | | | 0000 |
| C1CFG1 | 0410 | — | — | — | — | — | — | — | — | SJW<1:0> | | BRP<5:0> | | | | | | 0000 |
| C1CFG2 | 0412 | — | WAKFIL | — | — | — | SEG2PH<2:0> | | | SEG2PHTS | SAM | SEG1PH<2:0> | | | PRSEG<2:0> | | | 0000 |
| C1FEN1 | 0414 | FLTEN15 | FLTEN14 | FLTEN13 | FLTEN12 | FLTEN11 | FLTEN10 | FLTEN9 | FLTEN8 | FLTEN7 | FLTEN6 | FLTEN5 | FLTEN4 | FLTEN3 | FLTEN2 | FLTEN1 | FLTEN0 | FFFF |
| C1FMSKSEL1 | 0418 | F7MSK<1:0> | | F6MSK<1:0> | | F5MSK<1:0> | | F4MSK<1:0> | | F3MSK<1:0> | | F2MSK<1:0> | | F1MSK<1:0> | | F0MSK<1:0> | | 0000 |
| C1FMSKSEL2 | 041A | F15MSK<1:0> | | F14MSK<1:0> | | F13MSK<1:0> | | F12MSK<1:0> | | F11MSK<1:0> | | F10MSK<1:0> | | F9MSK<1:0> | | F8MSK<1:0> | | 0000 |

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-22: ECAN1 REGISTER MAP WHEN WIN (C1CTRL1<0>) = 0 FOR dsPIC33EPXXXMC/GP50X DEVICES ONLY**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | 0400-041E | See definition when WIN = x | | | | | | | | | | | | | | | | |
| C1RXFUL1 | 0420 | RXFUL15 | RXFUL14 | RXFUL13 | RXFUL12 | RXFUL11 | RXFUL10 | RXFUL9 | RXFUL8 | RXFUL7 | RXFUL6 | RXFUL5 | RXFUL4 | RXFUL3 | RXFUL2 | RXFUL1 | RXFUL0 | 0000 |
| C1RXFUL2 | 0422 | RXFUL31 | RXFUL30 | RXFUL29 | RXFUL28 | RXFUL27 | RXFUL26 | RXFUL25 | RXFUL24 | RXFUL23 | RXFUL22 | RXFUL21 | RXFUL20 | RXFUL19 | RXFUL18 | RXFUL17 | RXFUL16 | 0000 |
| C1RXOVF1 | 0428 | RXOVF15 | RXOVF14 | RXOVF13 | RXOVF12 | RXOVF11 | RXOVF10 | RXOVF9 | RXOVF8 | RXOVF7 | RXOVF6 | RXOVF5 | RXOVF4 | RXOVF3 | RXOVF2 | RXOVF1 | RXOVF0 | 0000 |
| C1RXOVF2 | 042A | RXOVF31 | RXOVF30 | RXOVF29 | RXOVF28 | RXOVF27 | RXOVF26 | RXOVF25 | RXOVF24 | RXOVF23 | RXOVF22 | RXOVF21 | RXOVF20 | RXOVF19 | RXOVF18 | RXOVF17 | RXOVF16 | 0000 |
| C1TR01CON | 0430 | TXEN1 | TXABT1 | TXLARB1 | TXERR1 | TXREQ1 | RTREN1 | TX1PRI<1:0> | | TXEN0 | TXABAT0 | TXLARB0 | TXERR0 | TXREQ0 | RTREN0 | TX0PRI<1:0> | | 0000 |
| C1TR23CON | 0432 | TXEN3 | TXABT3 | TXLARB3 | TXERR3 | TXREQ3 | RTREN3 | TX3PRI<1:0> | | TXEN2 | TXABAT2 | TXLARB2 | TXERR2 | TXREQ2 | RTREN2 | TX2PRI<1:0> | | 0000 |
| C1TR45CON | 0434 | TXEN5 | TXABT5 | TXLARB5 | TXERR5 | TXREQ5 | RTREN5 | TX5PRI<1:0> | | TXEN4 | TXABAT4 | TXLARB4 | TXERR4 | TXREQ4 | RTREN4 | TX4PRI<1:0> | | 0000 |
| C1TR67CON | 0436 | TXEN7 | TXABT7 | TXLARB7 | TXERR7 | TXREQ7 | RTREN7 | TX7PRI<1:0> | | TXEN6 | TXABAT6 | TXLARB6 | TXERR6 | TXREQ6 | RTREN6 | TX6PRI<1:0> | | xxxx |
| C1RXD | 0440 | ECAN1 Receive Data Word | | | | | | | | | | | | | | | | xxxx |
| C1TXD | 0442 | ECAN1 Transmit Data Word | | | | | | | | | | | | | | | | xxxx |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

### 4.4.3 DATA MEMORY ARBITRATION AND BUS MASTER PRIORITY

EDS accesses from bus masters in the system are arbitrated.

The arbiter for data memory (including EDS) arbitrates between the CPU, the DMA and the ICD module. In the event of coincidental access to a bus by the bus masters, the arbiter determines which bus master access has the highest priority. The other bus masters are suspended and processed after the access of the bus by the bus master with the highest priority.

By default, the CPU is Bus Master 0 (M0) with the highest priority and the ICD is Bus Master 4 (M4) with the lowest priority. The remaining bus master (DMA Controller) is allocated to M3 (M1 and M2 are reserved and cannot be used). The user application may raise or lower the priority of the DMA Controller to be above that of the CPU by setting the appropriate bits in the EDS Bus Master Priority Control (MSTRPR) register. All bus masters with raised priorities will maintain the same priority relationship relative to each other (i.e., M1 being highest and M3 being lowest, with M2 in between). Also, all the bus masters with priorities below that of the CPU maintain the same priority relationship relative to each other. The priority schemes for bus masters with different MSTRPR values are tabulated in Table 4-62.

This bus master priority control allows the user application to manipulate the real-time response of the system, either statically during initialization or dynamically in response to real-time events.

**TABLE 4-62: DATA MEMORY BUS ARBITER PRIORITY**

| Priority | MSTRPR<15:0> Bit Setting(1) | |
|---|---|---|
| | 0x0000 | 0x0020 |
| M0 (highest) | CPU | DMA |
| M1 | Reserved | CPU |
| M2 | Reserved | Reserved |
| M3 | DMA | Reserved |
| M4 (lowest) | ICD | ICD |

**Note 1:** All other values of MSTRPR<15:0> are reserved.

**FIGURE 4-18: ARBITER ARCHITECTURE**

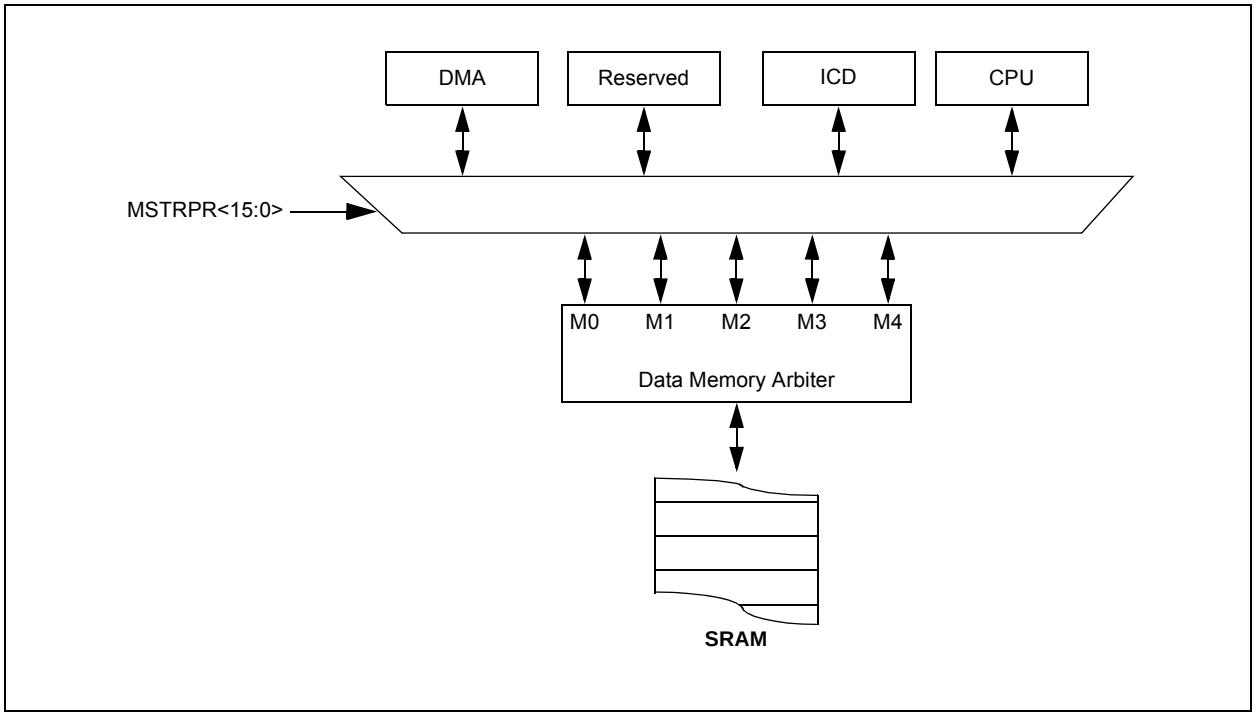


**TABLE 11-2: INPUT PIN SELECTION FOR SELECTABLE INPUT SOURCES**

| Peripheral Pin Select Input Register Value | Input/ Output | Pin Assignment | Peripheral Pin Select Input Register Value | Input/ Output | Pin Assignment |
|---|---|---|---|---|---|
| 000 0000 | I | Vss | 010 1101 | I | RPI45 |
| 000 0001 | I | C1OUT(1) | 010 1110 | I | RPI46 |
| 000 0010 | I | C2OUT(1) | 010 1111 | I | RPI47 |
| 000 0011 | I | C3OUT(1) | 011 0000 | — | — |
| 000 0100 | I | C4OUT(1) | 011 0001 | — | — |
| 000 0101 | — | — | 011 0010 | — | — |
| 000 0110 | I | PTGO30(1) | 011 0011 | I | RPI51 |
| 000 0111 | I | PTGO31(1) | 011 0100 | I | RPI52 |
| 000 1000 | I | FINDX1(1,2) | 011 0101 | I | RPI53 |
| 000 1001 | I | FHOME1(1,2) | 011 0110 | I/O | RP54 |
| 000 1010 | — | — | 011 0111 | I/O | RP55 |
| 000 1011 | — | — | 011 1000 | I/O | RP56 |
| 000 1100 | — | — | 011 1001 | I/O | RP57 |
| 000 1101 | — | — | 011 1010 | I | RPI58 |
| 000 1110 | — | — | 011 1011 | — | — |
| 000 1111 | — | — | 011 1100 | — | — |
| 001 0000 | — | — | 011 1101 | — | — |
| 001 0001 | — | — | 011 1110 | — | — |
| 001 0010 | — | — | 011 1111 | — | — |
| 001 0011 | — | — | 100 0000 | — | — |
| 001 0100 | I/O | RP20 | 100 0001 | — | — |
| 001 0101 | — | — | 100 0010 | — | — |
| 001 0110 | — | — | 100 0011 | — | — |
| 001 0111 | — | — | 100 0100 | — | — |
| 001 1000 | I | RPI24 | 100 0101 | — | — |
| 001 1001 | I | RPI25 | 100 0110 | — | — |
| 001 1010 | — | — | 100 0111 | — | — |
| 001 1011 | I | RPI27 | 100 1000 | — | — |
| 001 1100 | I | RPI28 | 100 1001 | — | — |
| 001 1101 | — | — | 100 1010 | — | — |
| 001 1110 | — | — | 100 1011 | — | — |
| 001 1111 | — | — | 100 1100 | — | — |
| 010 0000 | I | RPI32 | 100 1101 | — | — |
| 010 0001 | I | RPI33 | 100 1110 | — | — |
| 010 0010 | I | RPI34 | 100 1111 | — | — |
| 010 0011 | I/O | RP35 | 101 0000 | — | — |
| 010 0100 | I/O | RP36 | 101 0001 | — | — |
| 010 0101 | I/O | RP37 | 101 0010 | — | — |
| 010 0110 | I/O | RP38 | 101 0011 | — | — |
| 010 0111 | I/O | RP39 | 101 0100 | — | — |

**Legend:** Shaded rows indicate PPS Input register values that are unimplemented.

**Note 1:** See **Section 11.4.4.1 “Virtual Connections”** for more information on selecting this pin assignment.

**2:** These inputs are available on dsPIC33EPXXXGP/MC50X devices only.

**REGISTER 11-5: RPINR8: PERIPHERAL PIN SELECT INPUT REGISTER 8**

| U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | IC4R<6:0> | | | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | IC3R<6:0> | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as ‘0’

bit 14-8 **IC4R<6:0>:** Assign Input Capture 4 (IC4) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)

1111001 = Input tied to RPI121
.
.
.
0000001 = Input tied to CMP1
0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as ‘0’

bit 6-0 **IC3R<6:0>:** Assign Input Capture 3 (IC3) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)

1111001 = Input tied to RPI121
.
.
.
0000001 = Input tied to CMP1
0000000 = Input tied to Vss

**REGISTER 17-3: QEI1STAT: QEI1 STATUS REGISTER**

| U-0 | U-0 | HS, R/C-0 | R/W-0 | HS, R/C-0 | R/W-0 | HS, R/C-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | PCHEQIRQ | PCHEQIEN | PCLEQIRQ | PCLEQIEN | POSOVIRQ | POSOVIEN |
| bit 15 | | | | | | | bit 8 |

| HS, R/C-0 | R/W-0 | HS, R/C-0 | R/W-0 | HS, R/C-0 | R/W-0 | HS, R/C-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PCIIRQ(1) | PCIIEN | VELOVIRQ | VELOVIEN | HOMIRQ | HOMIEN | IDXIRQ | IDXIEN |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | HS = Hardware Settable bit | C = Clearable bit | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **PCHEQIRQ:** Position Counter Greater Than or Equal Compare Status bit
1 = POS1CNT ≥ QEI1GEC
0 = POS1CNT < QEI1GEC

bit 12 **PCHEQIEN:** Position Counter Greater Than or Equal Compare Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

bit 11 **PCLEQIRQ:** Position Counter Less Than or Equal Compare Status bit
1 = POS1CNT ≤ QEI1LEC
0 = POS1CNT > QEI1LEC

bit 10 **PCLEQIEN:** Position Counter Less Than or Equal Compare Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

bit 9 **POSOVIRQ:** Position Counter Overflow Status bit
1 = Overflow has occurred
0 = No overflow has occurred

bit 8 **POSOVIEN:** Position Counter Overflow Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

bit 7 **PCIIRQ:** Position Counter (Homing) Initialization Process Complete Status bit(1)
1 = POS1CNT was reinitialized
0 = POS1CNT was not reinitialized

bit 6 **PCIIEN:** Position Counter (Homing) Initialization Process Complete interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

bit 5 **VELOVIRQ:** Velocity Counter Overflow Status bit
1 = Overflow has occurred
0 = No overflow has not occurred

bit 4 **VELOVIEN:** Velocity Counter Overflow Interrupt Enable bit
1 = Interrupt is enabled
0 = Interrupt is disabled

bit 3 **HOMIRQ:** Status Flag for Home Event Status bit
1 = Home event has occurred
0 = No Home event has occurred

**Note 1:** This status bit is only applicable to PIMOD<2:0> modes, '011' and '100'.

**REGISTER 17-19: INT1HLDH: INTERVAL 1 TIMER HOLD HIGH WORD REGISTER**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| INTHLD<31:24> | | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| INTHLD<23:16> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-0 **INTHLD<31:16>:** Hold Register for Reading and Writing INT1TMRH bits

**REGISTER 17-20: INT1HLDL: INTERVAL 1 TIMER HOLD LOW WORD REGISTER**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| INTHLD<15:8> | | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| INTHLD<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-0 **INTHLD<15:0>:** Hold Register for Reading and Writing INT1TMRL bits

**REGISTER 21-3: CxVEC: ECANx INTERRUPT CODE REGISTER**

| U-0 | U-0 | U-0 | R-0 | R-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | FILHIT4 | FILHIT3 | FILHIT2 | FILHIT1 | FILHIT0 |
| bit 15 | | | | | | | bit 8 |

| U-0 | R-1 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | ICODE6 | ICODE5 | ICODE4 | ICODE3 | ICODE2 | ICODE1 | ICODE0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **FILHIT<4:0>:** Filter Hit Number bits

10000-11111 = Reserved
01111 = Filter 15
•
•
•
00001 = Filter 1
00000 = Filter 0

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **ICODE<6:0>:** Interrupt Flag Code bits

1000101-1111111 = Reserved
1000100 = FIFO almost full interrupt
1000011 = Receiver overflow interrupt
1000010 = Wake-up interrupt
1000001 = Error interrupt
1000000 = No interrupt
•
•
•
0010000-0111111 = Reserved
0001111 = RB15 buffer interrupt
•
•
•
0001001 = RB9 buffer interrupt
0001000 = RB8 buffer interrupt
0000111 = TRB7 buffer interrupt
0000110 = TRB6 buffer interrupt
0000101 = TRB5 buffer interrupt
0000100 = TRB4 buffer interrupt
0000011 = TRB3 buffer interrupt
0000010 = TRB2 buffer interrupt
0000001 = TRB1 buffer interrupt
0000000 = TRB0 buffer interrupt

**NOTES:**

**REGISTER 23-2: AD1CON2: ADC1 CONTROL REGISTER 2**

| R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| VCFG2 | VCFG1 | VCFG0 | — | — | CSCNA | CHPS1 | CHPS0 |
| bit 15 | | | | | | | bit 8 |

| R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| BUFS | SMPI4 | SMPI3 | SMPI2 | SMPI1 | SMPI0 | BUFM | ALTS |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **VCFG<2:0>:** Converter Voltage Reference Configuration bits

| Value | VREFH | VREFL |
|---|---|---|
| 000 | AVDD | Avss |
| 001 | External VREF+ | Avss |
| 010 | AVDD | External VREF- |
| 011 | External VREF+ | External VREF- |
| 1xx | AVDD | AVSS |

bit 12-11 **Unimplemented:** Read as '0'

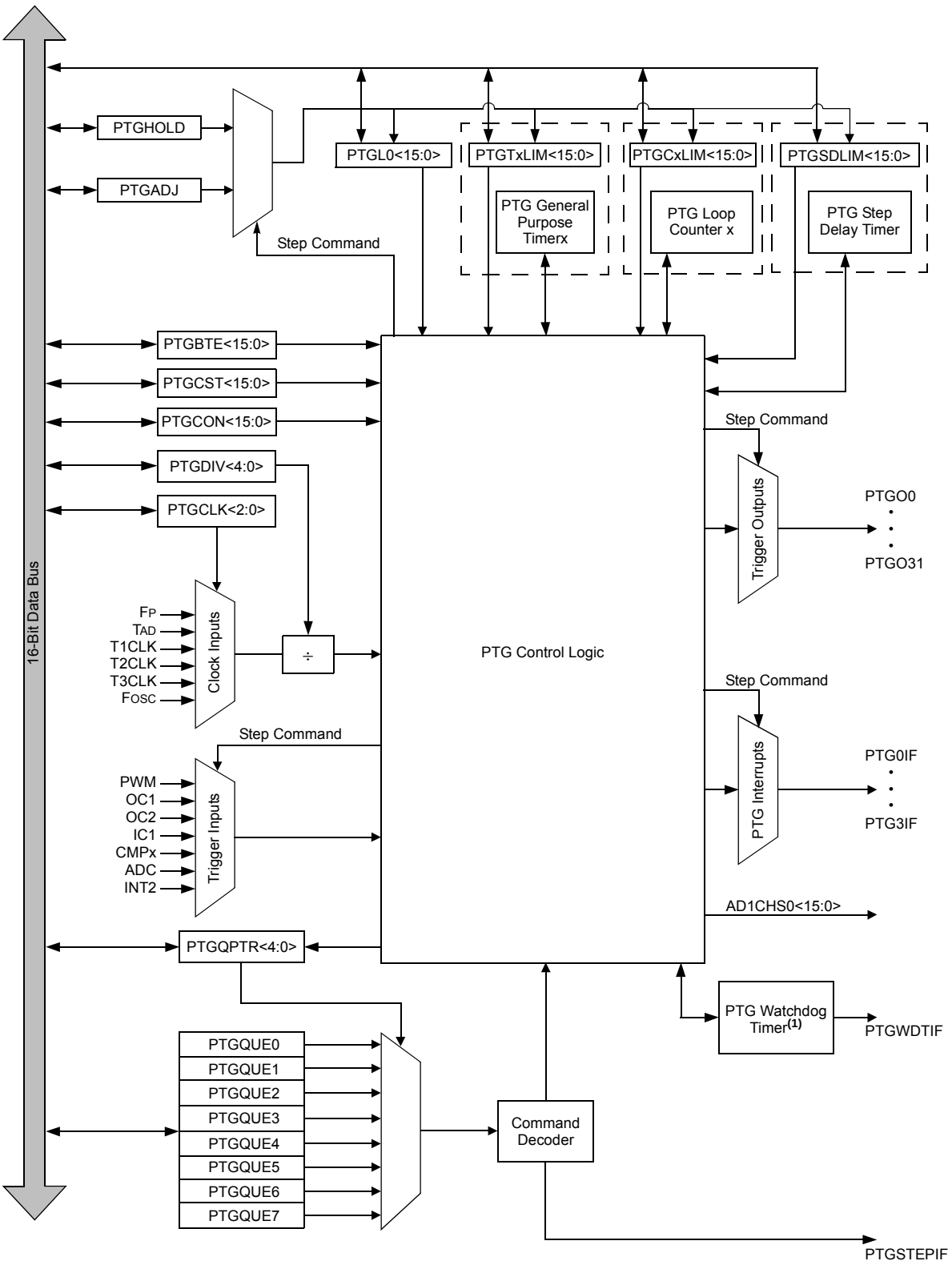
bit 10 **CSCNA:** Input Scan Select bit
1 = Scans inputs for CH0+ during Sample MUXA
0 = Does not scan inputs

bit 9-8 **CHPS<1:0>:** Channel Select bits
In 12-bit mode (AD21B = 1), the CHPS<1:0> bits are Unimplemented and are Read as '0':
1x = Converts CH0, CH1, CH2 and CH3
01 = Converts CH0 and CH1
00 = Converts CH0

bit 7 **BUFS:** Buffer Fill Status bit (only valid when BUFM = 1)
1 = ADC is currently filling the second half of the buffer; the user application should access data in the first half of the buffer
0 = ADC is currently filling the first half of the buffer; the user application should access data in the second half of the buffer

bit 6-2 **SMPI<4:0>:** Increment Rate bits
When ADDMAEN = 0:
x1111 = Generates interrupt after completion of every 16th sample/conversion operation
x1110 = Generates interrupt after completion of every 15th sample/conversion operation
•
•
•
x0001 = Generates interrupt after completion of every 2nd sample/conversion operation
x0000 = Generates interrupt after completion of every sample/conversion operation
When ADDMAEN = 1:
11111 = Increments the DMA address after completion of every 32nd sample/conversion operation
11110 = Increments the DMA address after completion of every 31st sample/conversion operation
•
•
•
00001 = Increments the DMA address after completion of every 2nd sample/conversion operation
00000 = Increments the DMA address after completion of every sample/conversion operation

**FIGURE 24-1: PTG BLOCK DIAGRAM**




**Note 1:** This is a dedicated Watchdog Timer for the PTG module and is independent of the device Watchdog Timer.

**REGISTER 25-3: CM4CON: COMPARATOR 4 CONTROL REGISTER**

| R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| CON | COE | CPOL | — | — | — | CEVT | COUT |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| EVPOL1 | EVPOL0 | — | CREF(1) | — | — | CCH1(1) | CCH0(1) |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **CON:** Comparator Enable bit
1 = Comparator is enabled
0 = Comparator is disabled

bit 14 **COE:** Comparator Output Enable bit
1 = Comparator output is present on the CxOUT pin
0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit
1 = Comparator output is inverted
0 = Comparator output is not inverted

bit 12-10 **Unimplemented:** Read as '0'

bit 9 **CEVT:** Comparator Event bit
1 = Comparator event according to EVPOL<1:0> settings occurred; disables future triggers and interrupts until the bit is cleared
0 = Comparator event did not occur

bit 8 **COUT:** Comparator Output bit
When CPOL = 0 (non-inverted polarity):
1 = VIN+ > VIN-
0 = VIN+ < VIN-
When CPOL = 1 (inverted polarity):
1 = VIN+ < VIN-
0 = VIN+ > VIN-

bit 7-6 **EVPOL<1:0>:** Trigger/Event/Interrupt Polarity Select bits
11 = Trigger/event/interrupt generated on any change of the comparator output (while CEVT = 0)
10 = Trigger/event/interrupt generated only on high-to-low transition of the polarity selected comparator output (while CEVT = 0)
If CPOL = 1 (inverted polarity):
Low-to-high transition of the comparator output.
If CPOL = 0 (non-inverted polarity):
High-to-low transition of the comparator output.
01 = Trigger/event/interrupt generated only on low-to-high transition of the polarity selected comparator output (while CEVT = 0)
If CPOL = 1 (inverted polarity):
High-to-low transition of the comparator output.
If CPOL = 0 (non-inverted polarity):
Low-to-high transition of the comparator output.
00 = Trigger/event/interrupt generation is disabled

**Note 1:** Inputs that are selected and not available will be tied to VSS. See the **"Pin Diagrams"** section for available inputs for each package.

**FIGURE 30-12: QEA/QEB INPUT CHARACTERISTICS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**

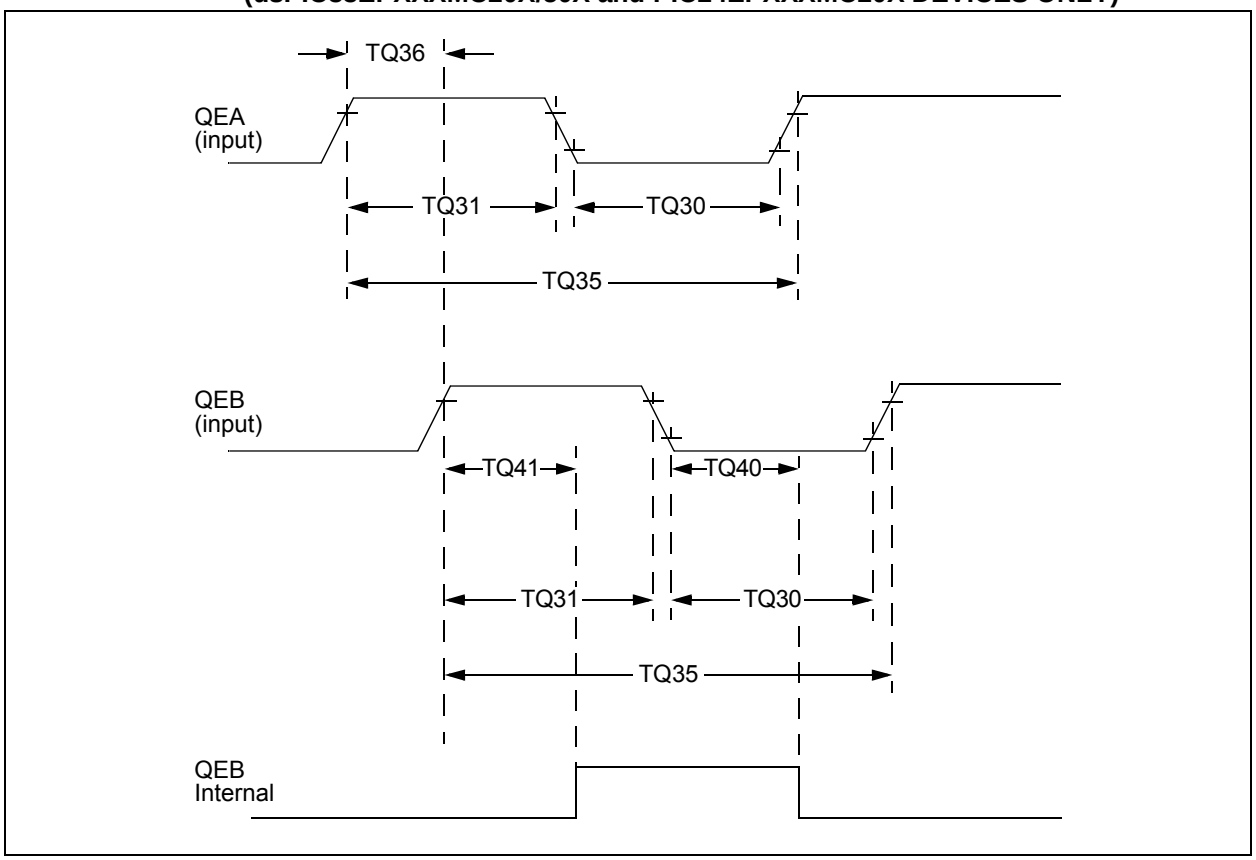



**TABLE 30-31: QUADRATURE DECODER TIMING REQUIREMENTS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Typ.(2)** | **Max.** | **Units** | **Conditions** |
| TQ30 | TQUL | Quadrature Input Low Time | 6 TCY | — | ns | |
| TQ31 | TQUH | Quadrature Input High Time | 6 TCY | — | ns | |
| TQ35 | TQUIN | Quadrature Input Period | 12 TCY | — | ns | |
| TQ36 | TQUP | Quadrature Phase Period | 3 TCY | — | ns | |
| TQ40 | TQUFL | Filter Time to Recognize Low, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)** |
| TQ41 | TQUFH | Filter Time to Recognize High, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)** |

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**3:** N = Index Channel Digital Filter Clock Divide Select bits. Refer to **"Quadrature Encoder Interface (QEI)"** (DS70601) in the "*dsPIC33/PIC24 Family Reference Manual*". Please see the Microchip web site for the latest family reference manual sections.

**TABLE 30-38: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param.** | **Symbol** | **Characteristic(1)** | **Min.** | **Typ.(2)** | **Max.** | **Units** | **Conditions** |
| SP70 | FscP | Maximum SCK2 Input Frequency | — | — | Lesser of FP or 11 | MHz | **(Note 3)** |
| SP72 | TscF | SCK2 Input Fall Time | — | — | — | ns | See Parameter DO32 **(Note 4)** |
| SP73 | TscR | SCK2 Input Rise Time | — | — | — | ns | See Parameter DO31 **(Note 4)** |
| SP30 | TdoF | SDO2 Data Output Fall Time | — | — | — | ns | See Parameter DO32 **(Note 4)** |
| SP31 | TdoR | SDO2 Data Output Rise Time | — | — | — | ns | See Parameter DO31 **(Note 4)** |
| SP35 | TscH2doV, TscL2doV | SDO2 Data Output Valid after SCK2 Edge | — | 6 | 20 | ns | |
| SP36 | TdoV2scH, TdoV2scL | SDO2 Data Output Setup to First SCK2 Edge | 30 | — | — | ns | |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDI2 Data Input to SCK2 Edge | 30 | — | — | ns | |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDI2 Data Input to SCK2 Edge | 30 | — | — | ns | |
| SP50 | TssL2scH, TssL2scL | $\overline{SS2}$ ↓ to SCK2 ↑ or SCK2 ↓ Input | 120 | — | — | ns | |
| SP51 | TssH2doZ | $\overline{SS2}$ ↑ to SDO2 Output High-Impedance | 10 | — | 50 | ns | **(Note 4)** |
| SP52 | TscH2ssH TscL2ssH | $\overline{SS2}$ ↑ after SCK2 Edge | 1.5 TCY + 40 | — | — | ns | **(Note 4)** |
| SP60 | TssL2doV | SDO2 Data Output Valid after $\overline{SS2}$ Edge | — | — | 50 | ns | |

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK2 is 91 ns. Therefore, the SCK2 clock generated by the master must not violate this specification.

**4:** Assumes 50 pF load on all SPI2 pins.

**TABLE 30-53: OP AMP/COMPARATOR SPECIFICATIONS (CONTINUED)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)(1)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ.(2)** | **Max.** | **Units** | **Conditions** |
| **Op Amp DC Characteristics** | | | | | | | |
| CM40 | VCMR | Common-Mode Input Voltage Range | AVSS | — | AVDD | V | |
| CM41 | CMRR | Common-Mode Rejection Ratio(3) | — | 40 | — | db | VCM = AVDD/2 |
| CM42 | VOFFSET | Op Amp Offset Voltage(3) | — | ±5 | — | mV | |
| CM43 | VGAIN | Open-Loop Voltage Gain(3) | — | 90 | — | db | |
| CM44 | IOS | Input Offset Current | — | — | — | — | See pad leakage currents in Table 30-11 |
| CM45 | IB | Input Bias Current | — | — | — | — | See pad leakage currents in Table 30-11 |
| CM46 | IOUT | Output Current | — | — | 420 | µA | With minimum value of RFEEDBACK (CM48) |
| CM48 | RFEEDBACK | Feedback Resistance Value | 8 | — | — | kΩ | |
| CM49a | VOADC | Output Voltage Measured at OAx Using ADC(3,4) | AVSS + 0.077<br>AVSS + 0.037<br>AVSS + 0.018 | —<br>—<br>— | AVDD – 0.077<br>AVDD – 0.037<br>AVDD – 0.018 | V<br>V<br>V | IOUT = 420 µA<br>IOUT = 200 µA<br>IOUT = 100 µA |
| CM49b | VOUT | Output Voltage Measured at OAxOUT Pin(3,4,5) | AVSS + 0.210<br>AVSS + 0.100<br>AVSS + 0.050 | —<br>—<br>— | AVDD – 0.210<br>AVDD – 0.100<br>AVDD – 0.050 | V<br>V<br>V | IOUT = 420 µA<br>IOUT = 200 µA<br>IOUT = 100 µA |
| CM51 | RINT1(6) | Internal Resistance 1 (Configuration A and B)(3,4,5) | 198 | 264 | 317 | Ω | Min = -40ºC<br>Typ = +25ºC<br>Max = +125ºC |

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

**2:** Data in "Typ" column is at 3.3V, +25°C unless otherwise stated.

**3:** Parameter is characterized but not tested in manufacturing.

**4:** See Figure 25-6 for configuration information.

**5:** See Figure 25-7 for configuration information.

**6:** Resistances can vary by ±10% between op amps.

**TABLE 30-58: ADC MODULE SPECIFICATIONS (12-BIT MODE)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)[1]<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ.** | **Max.** | **Units** | **Conditions** |
| **ADC Accuracy (12-Bit Mode)** | | | | | | | |
| AD20a | Nr | Resolution | 12 Data Bits | | | bits | |
| AD21a | INL | Integral Nonlinearity | -2.5 | — | 2.5 | LSb | -40°C ≤ TA ≤ +85°C **(Note 2)** |
| | | | -5.5 | — | 5.5 | LSb | +85°C < TA ≤ +125°C **(Note 2)** |
| AD22a | DNL | Differential Nonlinearity | -1 | — | 1 | LSb | -40°C ≤ TA ≤ +85°C **(Note 2)** |
| | | | -1 | — | 1 | LSb | +85°C < TA ≤ +125°C **(Note 2)** |
| AD23a | GERR | Gain Error[3] | -10 | — | 10 | LSb | -40°C ≤ TA ≤ +85°C **(Note 2)** |
| | | | -10 | — | 10 | LSb | +85°C < TA ≤ +125°C **(Note 2)** |
| AD24a | EOFF | Offset Error | -5 | — | 5 | LSb | -40°C ≤ TA ≤ +85°C **(Note 2)** |
| | | | -5 | — | 5 | LSb | +85°C < TA ≤ +125°C **(Note 2)** |
| AD25a | — | Monotonicity | — | — | — | — | Guaranteed |
| **Dynamic Performance (12-Bit Mode)** | | | | | | | |
| AD30a | THD | Total Harmonic Distortion[3] | — | 75 | — | dB | |
| AD31a | SINAD | Signal to Noise and Distortion[3] | — | 68 | — | dB | |
| AD32a | SFDR | Spurious Free Dynamic Range[3] | — | 80 | — | dB | |
| AD33a | FNYQ | Input Signal Bandwidth[3] | — | 250 | — | kHz | |
| AD34a | ENOB | Effective Number of Bits[3] | 11.09 | 11.3 | — | bits | |

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

**2:** For all accuracy specifications, VINL = AVSS = VREFL = 0V and AVDD = VREFH = 3.6V.

**3:** Parameters are characterized but not tested in manufacturing.

**TABLE 31-12: ADC MODULE SPECIFICATIONS (12-BIT MODE)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +150°C | | | | |
|---|---|---|---|---|---|---|---|
| Param No. | Symbol | Characteristic | Min | Typ | Max | Units | Conditions |
| **ADC Accuracy (12-Bit Mode)(1)** | | | | | | | |
| HAD20a | Nr | Resolution(3) | 12 Data Bits | | | bits | |
| HAD21a | INL | Integral Nonlinearity | -5.5 | — | 5.5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD22a | DNL | Differential Nonlinearity | -1 | — | 1 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD23a | GERR | Gain Error | -10 | — | 10 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD24a | EOFF | Offset Error | -5 | — | 5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| **Dynamic Performance (12-Bit Mode)(2)** | | | | | | | |
| HAD33a | FNYQ | Input Signal Bandwidth | — | — | 200 | kHz | |

**Note 1:** These parameters are characterized, but are tested at 20 ksps only.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

**3:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**TABLE 31-13: ADC MODULE SPECIFICATIONS (10-BIT MODE)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +150°C | | | | |
|---|---|---|---|---|---|---|---|
| Param No. | Symbol | Characteristic | Min | Typ | Max | Units | Conditions |
| **ADC Accuracy (10-Bit Mode)(1)** | | | | | | | |
| HAD20b | Nr | Resolution(3) | 10 Data Bits | | | bits | |
| HAD21b | INL | Integral Nonlinearity | -1.5 | — | 1.5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD22b | DNL | Differential Nonlinearity | -0.25 | — | 0.25 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD23b | GERR | Gain Error | -2.5 | — | 2.5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| HAD24b | EOFF | Offset Error | -1.25 | — | 1.25 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| **Dynamic Performance (10-Bit Mode)(2)** | | | | | | | |
| HAD33b | FNYQ | Input Signal Bandwidth | — | — | 400 | kHz | |

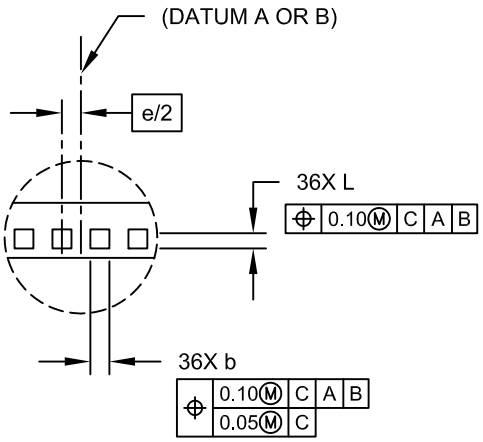
**Note 1:** These parameters are characterized, but are tested at 20 ksps only.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

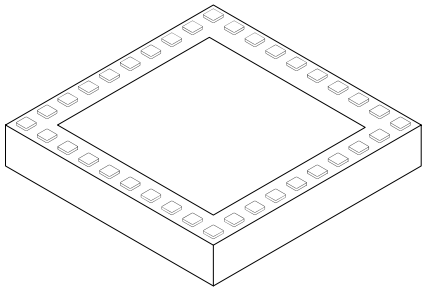
**3:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

## 36-Terminal Very Thin Thermal Leadless Array Package (TL) – 5x5x0.9 mm Body with Exposed Pad [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




**DETAIL A**



| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension | Limits | MIN | NOM | MAX |
| Number of Pins | N | | 36 | |
| Number of Pins per Side | ND | | 10 | |
| Number of Pins per Side | NE | | 8 | |
| Pitch | e | | 0.50 BSC | |
| Overall Height | A | 0.80 | 0.90 | 1.00 |
| Standoff | A1 | 0.025 | - | 0.075 |
| Overall Width | E | | 5.00 BSC | |
| Exposed Pad Width | E2 | 3.60 | 3.75 | 3.90 |
| Overall Length | D | | 5.00 BSC | |
| Exposed Pad Length | D2 | 3.60 | 3.75 | 3.90 |
| Contact Width | b | 0.20 | 0.25 | 0.30 |
| Contact Length | L | 0.20 | 0.25 | 0.30 |
| Contact-to-Exposed Pad | K | 0.20 | - | - |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-187C Sheet 2 of 2

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