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Details

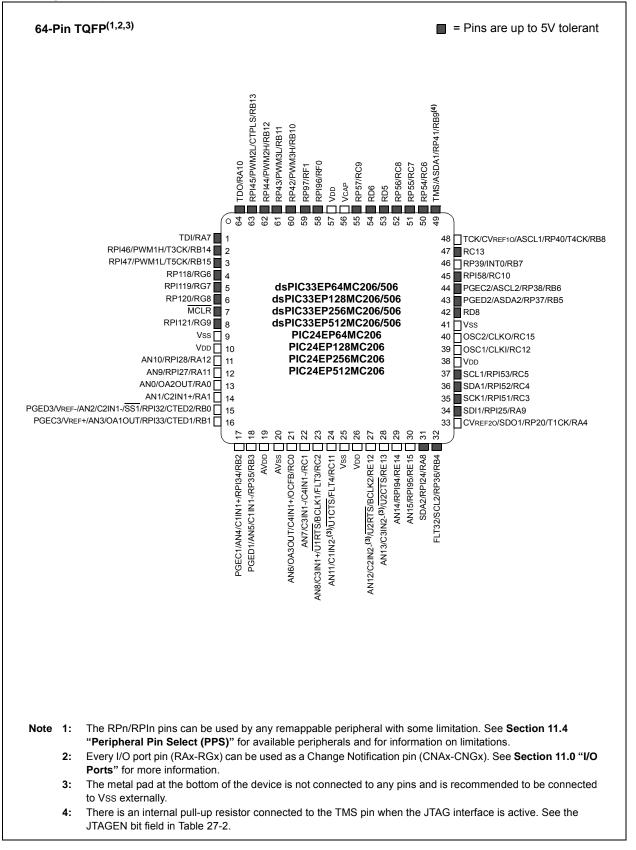
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Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-UFQFN Exposed Pad
Supplier Device Package	48-UQFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep128mc204t-i-mv

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Pin Diagrams (Continued)



3.6 CPU Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter
	this URL in your browser:
	http://www.microchip.com/wwwproducts/
	Devices.aspx?dDocName=en555464

3.6.1 KEY RESOURCES

- "CPU" (DS70359) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools



FIGURE 4-5: PROGRAM MEMORY MAP FOR dsPIC33EP512GP50X, dsPIC33EP512MC20X/50X AND PIC24EP512GP/MC20X DEVICES

TABLE 4-3: INTERRUPT CONTROLLER REGISTER MAP FOR PIC24EPXXXGP20X DEVICES ONLY

TADLL	τу.				VELEN							DEVICE						
File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IFS0	0800		DMA1IF	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPI1EIF	T3IF	T2IF	OC2IF	IC2IF	DMA0IF	T1IF	OC1IF	IC1IF	INTOIF	0000
IFS1	0802	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA2IF	_	_	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF	0000
IFS2	0804		_	_	-		_	—	_	_	IC4IF	IC3IF	DMA3IF	_	—	SPI2IF	SPI2EIF	0000
IFS3	0806	_	_	_	_	_	_	_	_	_	_	_	_	_	MI2C2IF	SI2C2IF	_	0000
IFS4	0808	_	_	CTMUIF	_	_	_	_	_	_	_	_	_	CRCIF	U2EIF	U1EIF	_	0000
IFS8	0810	JTAGIF	ICDIF		_	_	_	_	—	_	_	_	_	_	—	—	—	0000
IFS9	0812	_	_	_	_	_	_	_	—	_	PTG3IF	PTG2IF	PTG1IF	PTG0IF	PTGWDTIF	PTGSTEPIF	—	0000
IEC0	0820	_	DMA1IE	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPI1EIE	T3IE	T2IE	OC2IE	IC2IE	DMA0IE	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0822	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	DMA2IE	_	_	_	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE	0000
IEC2	0824	_	_	_	_	_	_	_	_	_	IC4IE	IC3IE	DMA3IE	_	_	SPI2IE	SPI2EIE	0000
IEC3	0826	_	_	_	_	_	_	_	—	_	_	_	_	_	MI2C2IE	SI2C2IE	—	0000
IEC4	0828	_	_	CTMUIE	_	_	_	_	_	_	_	_	_	CRCIE	U2EIE	U1EIE	_	0000
IEC8	0830	JTAGIE	ICDIE	_	_	_	_	_	_	_	_	_	_	_	_	_	_	0000
IEC9	0832	_	_	_	_	_	_	_	—	_	PTG3IE	PTG2IE	PTG1IE	PTG0IE	PTGWDTIE	PTGSTEPIE	_	0000
IPC0	0840	_		T1IP<2:0>		_	(OC1IP<2:0	>	_		IC1IP<2:0>		—		INT0IP<2:0>		4444
IPC1	0842	_		T2IP<2:0>		_	(OC2IP<2:0	>	_		IC2IP<2:0>		_	C	0MA0IP<2:0>		4444
IPC2	0844	_	U	J1RXIP<2:0	>	_	;	SPI1IP<2:0	>	_		SPI1EIP<2:0	>	_		T3IP<2:0>		4444
IPC3	0846	_	_	_	_	_	D)MA1IP<2:	0>	_		AD1IP<2:0>		_	ι	J1TXIP<2:0>		0444
IPC4	0848			CNIP<2:0>				CMIP<2:0	>	_		MI2C1IP<2:0	>	_	S	SI2C1IP<2:0>		4444
IPC5	084A	_	_	_	_	_	_	_	_	_	_	—	_	_	I	INT1IP<2:0>		0004
IPC6	084C	_		T4IP<2:0>		_	(OC4IP<2:0	>	_		OC3IP<2:0>		_	C)ma2IP<2:0>		4444
IPC7	084E		1	U2TXIP<2:0	>		L	J2RXIP<2:)>	_		INT2IP<2:0>		_		T5IP<2:0>		4444
IPC8	0850		_	_	_		_	—	—	_		SPI2IP<2:0>		_	S	SPI2EIP<2:0>		0044
IPC9	0852		_	_				IC4IP<2:0	>	_		IC3IP<2:0>		_	C	0MA3IP<2:0>		0444
IPC12	0858		_	_			N	112C2IP<2:	0>	_		SI2C2IP<2:0	>	_	_	_	_	0440
IPC16	0860			CRCIP<2:0>	>			U2EIP<2:0	>	_		U1EIP<2:0>		_	_	_	_	4440
IPC19	0866		_	_	_	_	_	_	_	_		CTMUIP<2:0	>	_	_	_	_	0040
IPC35	0886			JTAGIP<2:0	>	_		ICDIP<2:0	>	_	_	_	_	_	_	_	_	4400
IPC36	0888	_		PTG0IP<2:0	>	_	PT	GWDTIP<	2:0>	_	P	TGSTEPIP<2	:0>	_	_	—	_	4440
IPC37	088A	_	_	_	_	_	F	PTG3IP<2:)>	_		PTG2IP<2:0	>	_	F	PTG1IP<2:0>		0444
INTCON1	08C0	NSTDIS	OVAERR	OVBERR	_				—	_	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL		0000
INTCON2	08C2	GIE	DISI	SWTRAP	_				_	_		—	—	_	INT2EP	INT1EP	INT0EP	8000
INTCON3	08C4	_	_		_			_	_	_	_	DAE	DOOVR	_	_	—		0000
INTCON4	08C6		_	_	_	_	_	—	_	_	_	_	_	_	_		SGHT	0000
INTTREG	08C8	_			_		ILR<	3:0>					VECN	UM<7:0>				0000

- = unimplemented, read as '0'. Reset values are shown in hexadecimal. Legend:

TABLE 4-45: DMAC REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
DMA0CON	0B00	CHEN	SIZE	DIR	HALF	NULLW		_	_	_	_	AMOD	E<1:0>	_	_	MODE	<1:0>	0000
DMA0REQ	0B02	FORCE	_	_		_	_	_	_				IRQSE	_<7:0>	•			00FF
DMA0STAL	0B04								STA<15	5:0>								0000
DMA0STAH	0B06	_	_	_	_	_	_	_	_				STA<2	3:16>				0000
DMA0STBL	0B08								STB<1	5:0>								0000
DMA0STBH	0B0A	_	—	_	_	_	—	—	—				STB<2	3:16>				0000
DMA0PAD	0B0C								PAD<1	5:0>								0000
DMA0CNT	0B0E	_	_							CNT<1	3:0>							0000
DMA1CON	0B10	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	_	—	AMOD	E<1:0>	—	—	MODE	<1:0>	0000
DMA1REQ	0B12	FORCE	_	_		_	_	_	_				IRQSE	_<7:0>	•			00FF
DMA1STAL	0B14								STA<15	5:0>								0000
DMA1STAH	0B16	_	—	_	_	_	—	—	—				STA<2	3:16>				0000
DMA1STBL	0B18								STB<1	5:0>								0000
DMA1STBH	0B1A	_	—	_	_		—	_	_				STB<2	3:16>				0000
DMA1PAD	0B1C								PAD<1	5:0>								0000
DMA1CNT	0B1E	_	—							CNT<1	3:0>							0000
DMA2CON	0B20	CHEN	SIZE	DIR	HALF	NULLW	_	_	_	_	_	AMOD	E<1:0>		—	MODE	<1:0>	0000
DMA2REQ	0B22	FORCE	_	_		_	_	_	_				IRQSE	_<7:0>	•			00FF
DMA2STAL	0B24								STA<18	5:0>								0000
DMA2STAH	0B26	_	_	_	_	_	_	_	_				STA<2	3:16>				0000
DMA2STBL	0B28								STB<1	5:0>								0000
DMA2STBH	0B2A	_	_	_	_	_	_	_	_				STB<2	3:16>				0000
DMA2PAD	0B2C								PAD<1	5:0>								0000
DMA2CNT	0B2E	_	_							CNT<1	3:0>							0000
DMA3CON	0B30	CHEN	SIZE	DIR	HALF	NULLW	_	_	_	_	_	AMOD	E<1:0>	-	—	MODE	<1:0>	0000
DMA3REQ	0B32	FORCE	_	_	_	_	_	_	_				IRQSE	L<7:0>				00FF
DMA3STAL	0B34								STA<18	5:0>								0000
DMA3STAH	0B36	_	_	_	_	_	_	_	_				STA<2	3:16>				0000
DMA3STBL	0B38								STB<1	5:0>								0000
DMA3STBH	0B3A	_	_	_	_	_	_	_	_				STB<2	3:16>				0000
DMA3PAD	0B3C								PAD<1	5:0>								0000
DMA3CNT	0B3E	_	_							CNT<1	3:0>							0000
DMAPWC	0BF0	_	—	—	—	—	—		_	—	—		—	PWCOL3	PWCOL2	PWCOL1	PWCOL0	0000
DMARQC	0BF2	_	—	_	_	_	_	_	_	_	_	_	_	RQCOL3	RQCOL2	RQCOL1	RQCOL0	0000
DMAPPS	0BF4	_	—	_	_	_	_	_	_	_	_	_	_	PPST3	PPST2	PPST1	PPST0	0000
DMALCA	0BF6	_	_	_	_	_	_	_	_	_	_	_	_		LSTCH	1<3:0>		000F
DSADRL	0BF8								DSADR<	15:0>								0000
DSADRH	0BFA	_	—	—	—	—	—	—	—				DSADR•	<23:16>				0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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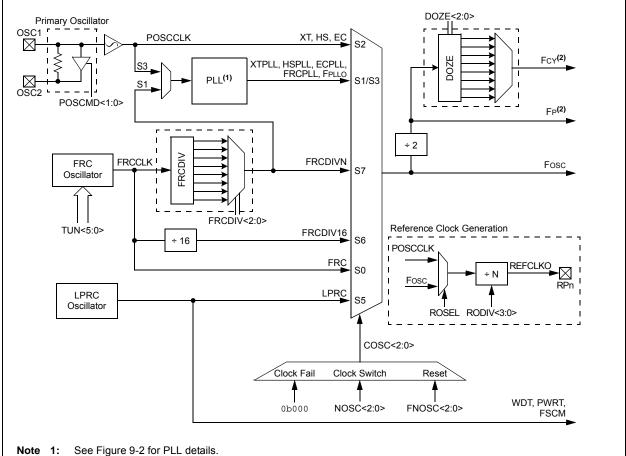
9.0 OSCILLATOR CONFIGURATION

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Oscillator" (DS70580) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip web site (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/ 50X and PIC24EPXXXGP/MC20X oscillator system provides:

- On-chip Phase-Locked Loop (PLL) to boost internal operating frequency on select internal and external oscillator sources
- On-the-fly clock switching between various clock sources
- · Doze mode for system power savings
- Fail-Safe Clock Monitor (FSCM) that detects clock failure and permits safe application recovery or shutdown
- Configuration bits for clock source selection
- A simplified diagram of the oscillator system is shown in Figure 9-1.

FIGURE 9-1: OSCILLATOR SYSTEM DIAGRAM



2: The term, FP, refers to the clock source for all peripherals, while FCY refers to the clock source for the CPU. Throughout this document, FCY and FP are used interchangeably, except in the case of Doze mode. FP and FCY will be different when Doze mode is used with a doze ratio of 1:2 or lower.

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			IC2R<6:0>			
·						bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			IC1R<6:0>			
						bit C
e bit	W = Writable b	it	U = Unimplem	nented bit, rea	d as '0'	
POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
•			nbers)			
		1				
Unimplemer	nted: Read as '0					
(see Table 11 1111001 = I	I-2 for input pin's nput tied to RPI1	election num 21		onding RPn Pi	n bits	
	e bit POR Unimplemen IC2R<6:0>: / (see Table 11 1111001 = I 0000001 = I 0000000 = I Unimplemen IC1R<6:0>: / (see Table 11 1111001 = I	e bit W = Writable b POR '1' = Bit is set Unimplemented: Read as '0 IC2R<6:0>: Assign Input Cap (see Table 11-2 for input pin s 1111001 = Input tied to RPI1 0000001 = Input tied to CMP 0000000 = Input tied to Vss Unimplemented: Read as '0 IC1R<6:0>: Assign Input Cap (see Table 11-2 for input pin s	e bit W = Writable bit POR '1' = Bit is set Unimplemented: Read as '0' IC2R<6:0>: Assign Input Capture 2 (IC2) (see Table 11-2 for input pin selection num 1111001 = Input tied to RPI121	R/W-0 R/W-0 R/W-0 R/W-0 IC1R<6:0> IC1R<6:0> e bit W = Writable bit U = Unimplem POR '1' = Bit is set '0' = Bit is clear Unimplemented: Read as '0' IC2R<6:0>: Assign Input Capture 2 (IC2) to the Correspond (see Table 11-2 for input pin selection numbers) 1111001 = Input tied to RPI121 . . 0000001 = Input tied to CMP1 0000000 = Input tied to Vss Unimplemented: Read as '0' IC1R<6:0>: Assign Input Capture 1 (IC1) to the Correspond (see Table 11-2 for input pin selection numbers) 1111001 = Input tied to RPI121 .	R/W-0 R/W-0 R/W-0 R/W-0 IC1R<6:0> e bit W = Writable bit U = Unimplemented bit, real POR '1' = Bit is set '0' = Bit is cleared Unimplemented: Read as '0' IC2R<6:0>: Assign Input Capture 2 (IC2) to the Corresponding RPn Pi (see Table 11-2 for input pin selection numbers) 1111001 = Input tied to RPI121 . . . 0000001 = Input tied to CMP1 0000000 = Input tied to Vss Unimplemented: Read as '0' IC1R<6:0>: Assign Input Capture 1 (IC1) to the Corresponding RPn Pi (see Table 11-2 for input pin selection numbers) 1111001 = Input tied to RPI121 .	R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 IC1R<6:0> e bit W = Writable bit U = Unimplemented bit, read as '0' POR '1' = Bit is set '0' = Bit is cleared x = Bit is unkr Unimplemented: Read as '0' IC2R<6:0>: Assign Input Capture 2 (IC2) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers) 1111001 = Input tied to RPI121 <p< td=""></p<>

REGISTER 11-4: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7

15.2 Output Compare Control Registers

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0				
	0-0	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0		ENFLTB				
 bit 15		COOIDE		OUTOLLI	OUTOLLU		bit 8				
Sit 10							bit 0				
R/W-0	U-0	R/W-0, HSC	R/W-0, HSC	R/W-0	R/W-0	R/W-0	R/W-0				
ENFLT		OCFLTB	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0				
bit 7							bit 0				
Legend:		HSC = Hardw	are Settable/Cl	earable bit							
R = Read	able bit	W = Writable I	oit	U = Unimplem	nented bit, read	as '0'					
-n = Value	e at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own				
bit 15-14	Unimplemen	ted: Read as '0)'								
bit 13	OCSIDL: Out	tput Compare x	Stop in Idle Mo	de Control bit							
		ompare x Halts									
	•	compare x conti	•		ode						
bit 12-10)>: Output Com	pare x Clock S	elect bits							
		111 = Peripheral clock (FP) 110 = Reserved									
	101 = PTGOx clock(2)										
		is the clock so			hronous clock	is supported)					
		is the clock so									
		(is the clock so (is the clock so									
		is the clock so									
bit 9	Unimplemen	ted: Read as '0)'								
bit 8	ENFLTB: Fau	ult B Input Enab	le bit								
		compare Fault B compare Fault B									
bit 7	-	ult A Input Enab									
	1 = Output C	ompare Fault A compare Fault A	input (OCFA)								
bit 6	•	ted: Read as '0	• • •								
bit 5	OCFLTB: PW	M Fault B Con	dition Status bit								
		ult B condition of Fault B condition									
bit 4		/M Fault A Cond	•								
	 1 = PWM Fault A condition on OCFA pin has occurred 0 = No PWM Fault A condition on OCFA pin has occurred 										
Note 1:	OCxR and OCxF	29 are double h	uffered in D\\//	/ mode only							
Note 1. 2:	Each Output Cor			-	irce. See Secti	on 24.0 "Perin	heral Trigger				
2.	Generator (PTG					5.1 2 7.0 1 611p					
	PTGO4 = OC1	-									
	PTGO5 = OC2										
	PTGO6 = OC3 PTGO7 = OC4										

19.0 INTER-INTEGRATED CIRCUIT[™] (I²C[™])

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXGP50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Inter-Integrated Circuit™ (I²C™)" (DS70330) in the "dsPIC33/ PIC24 Family Reference Manual", which is available from the Microchip web site (www.microchip.com).
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.
 - 3: There are minimum bit rates of approximately FCY/512. As a result, high processor speeds may not support 100 Kbit/second operation. See timing specifications, IM10 and IM11, and the "Baud Rate Generator" in the "dsPIC33/PIC24 Family Reference Manual".

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/ 50X and PIC24EPXXXGP/MC20X family of devices contains two Inter-Integrated Circuit (I²C) modules: I2C1 and I2C2.

The l^2C module provides complete hardware support for both Slave and Multi-Master modes of the l^2C serial communication standard, with a 16-bit interface.

The I^2C module has a 2-pin interface:

- · The SCLx pin is clock
- The SDAx pin is data

The I²C module offers the following key features:

- I²C interface supporting both Master and Slave modes of operation
- I²C Slave mode supports 7 and 10-bit addressing
- I²C Master mode supports 7 and 10-bit addressing
- I²C port allows bidirectional transfers between master and slaves
- Serial clock synchronization for I²C port can be used as a handshake mechanism to suspend and resume serial transfer (SCLREL control)
- I²C supports multi-master operation, detects bus collision and arbitrates accordingly
- Intelligent Platform Management Interface (IPMI)
 support
- System Management Bus (SMBus) support

20.3 UARTx Control Registers

REGISTER 20-1: UXMODE: UARTX MODE REGISTER

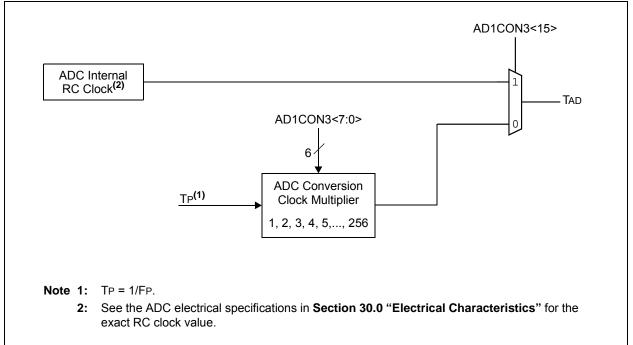
R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0				
UARTEN ⁽	¹⁾	USIDL	IREN ⁽²⁾	RTSMD	_	UEN1	UEN0				
bit 15				•			bit 8				
			D AMA	D 444 0	D 444 0	D 444.0	D 444 0				
R/W-0, H0		R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL				
bit 7							bit				
Legend:		HC = Hardwar	e Clearable b	it							
R = Reada	ble bit	W = Writable b	oit	U = Unimplem	ented bit, read	as '0'					
-n = Value	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown				
bit 15	1 = UARTx is	ARTx Enable bit ⁽ s enabled; all UA s disabled; all UA	ARTx pins are								
bit 14	Unimplemen	ted: Read as '0	,								
bit 13	USIDL: UAR	Tx Stop in Idle M	lode bit								
	1 = Discontinues module operation when device enters Idle mode0 = Continues module operation in Idle mode										
bit 12	1 = IrDA enc	IREN: IrDA [®] Encoder and Decoder Enable bit ⁽²⁾ 1 = IrDA encoder and decoder are enabled 0 = IrDA encoder and decoder are disabled									
bit 11	$1 = \overline{\text{UxRTS}} p$	le Selection for bin is in Simplex bin is in Flow Co	mode	t							
bit 10	Unimplemen	ted: Read as '0	,								
bit 9-8	11 = UxTX, U 10 = UxTX, U 01 = UxTX, U	IARTx Pin Enab JxRX and BCLK JxRX, UxCTS ar JxRX and UxRT nd UxRX pins a atches	x p <u>ins are</u> ena nd UxRTS pin S pins are ena	s are enabled a abled and used;	nd used ⁽⁴⁾ UxCT <u>S pin is</u> c	controlled by PC	ORT latches ⁽⁴				
bit 7	WAKE: Wake	e-up on Start bit	Detect During	Sleep Mode Ei	nable bit						
	in hardwa	ontinues to sam are on the follow -up is enabled			generated on t	the falling edge	; bit is cleare				
bit 6	1 = Enables	ARTx Loopback Loopback mode k mode is disab	:	bit							
2:	Refer to the " UAI enabling the UAR This feature is or	Tx module for realized for realized available for the second second second second second second second second s	eceive or trans the 16x BRG	mit operation. mode (BRGH =	-	ce Manual" for i	nformation or				
		his feature is only available on 44-pin and 64-pin devices.									
A-	i nie tooturo je or	ny available on l	al nin dovicos								

4: This feature is only available on 64-pin devices.

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
_		FBP5	FBP4	FBP3	FBP2	FBP1	FBP0
bit 15							bit 8
U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
		FNRB5	FNRB4	FNRB3	FNRB2	FNRB1	FNRB0
bit 7							bit (
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimplen	nented bit, read	d as '0'	
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkr	iown
bit 15-14	Unimpleme	ented: Read as '	0'				
bit 13-8	FBP<5:0>:	FIFO Buffer Poir	nter bits				
		RB31 buffer					
	011110 = F	RB30 buffer					
	•						
	•						
	•	TRB1 buffer					
		TRB0 buffer					
bit 7-6	Unimpleme	ented: Read as '	0'				
bit 5-0	FNRB<5:0	>: FIFO Next Rea	ad Buffer Poir	iter bits			
	011111 = F	RB31 buffer					
	011110 = F	RB30 buffer					
	•						
	•						
	•						
		FRB1 buffer FRB0 buffer					

REGISTER 21-5: CxFIFO: ECANx FIFO STATUS REGISTER





dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

	23-2: Al		CONTROL REG				
R/W-0	R/W-	-0 R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
VCFG2	VCFC	G1 VCFG0	—	—	CSCNA	CHPS1	CHPS0
bit 15							bit
R-0	R/W-	-0 R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BUFS	SMP		SMPI2	SMPI1	SMPI0	BUFM	ALTS
bit 7	Sivil		SIVILIZ			BOTIM	bit
Logondi							
Legend:	. hit	M = Mritable			montod hit roo		
R = Readable		W = Writable			mented bit, read		
-n = Value at	POR	'1' = Bit is se	et '()' = Bit is cle	eared	x = Bit is unkr	nown
bit 15-13	VCFG<2	2:0>: Converter Vol	tage Reference C	onfiguration	bits		
	Value	VREFH	VREFL				
	000	Avdd	Avss				
	001	External VREF+	Avss				
	010	Avdd	External VREF-				
	011	External VREF+	External VREF-				
	1xx	Avdd	Avss				
bit 12-11	Unimple	emented: Read as	'O'				
bit 10	-	: Input Scan Select					
		ns inputs for CH0+		JXA			
		s not scan inputs	5 1				
bit 9-8	CHPS<1	1:0>: Channel Sele	ct bits				
	<u>In 12-bit</u>	mode (AD21B = 1	<u>), the CHPS<1:0></u>	bits are Uni	mplemented an	d are Read as	<u>'0':</u>
		nverts CH0, CH1, (
		nverts CH0 and CH nverts CH0	11				
L:1 7							
bit 7		Buffer Fill Status bit C is currently filling t		-	o ucor opplicat	ion chould coor	oo data in t
		half of the buffer	the second hall of	line buller, li	ie user applicat		
		C is currently filling	the first half of the	e buffer; the	e user applicatio	on should acce	ss data in t
		ond half of the buffe					
bit 6-2	SMPI<4	:0>: Increment Rat	e bits				
		DDMAEN = 0:					
		Generates interru					
	x1110 =	Generates interru	pt after completion	of every 15	oth sample/conv	ersion operation	on
	•						
	•						
		Generates interru					n
		 Generates interru 	pt after completior	of every sa	ample/conversion	n operation	
		$\frac{\text{DDMAEN} = 1}{\text{Increments the DN}}$	11 address offer a	omplation of	four 20rd of	male (een verei	on onoratio
		Increments the DI Increments the DI					
	•			Simpletion	n every orac sa		
	•						
	•	- Increments the DI					

. . ACOND. ADCA CONTROL DECISTED 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
CSS15	CSS14	CSS13	CSS12	CSS11	CSS10	CSS9	CSS8	
bit 15				·	•	·	bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
CSS7	CSS6	CSS5	CSS4	CSS3	CSS2	CSS1	CSS0	
bit 7	-				•		bit (
Legend:								
R = Readable	bit	W = Writable	bit	U = Unimple	mented bit, rea	d as '0'		
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unknown		

REGISTER 23-8: AD1CSSL: ADC1 INPUT SCAN SELECT REGISTER LOW^(1,2)

bit 15-0 CSS<15:0>: ADC1 Input Scan Selection bits

1 = Selects ANx for input scan

0 = Skips ANx for input scan

Note 1: On devices with less than 16 analog inputs, all AD1CSSL bits can be selected by the user. However, inputs selected for scan, without a corresponding input on the device, convert VREFL.

2: CSSx = ANx, where x = 0-15.

28.0 INSTRUCTION SET SUMMARY

Note: This data sheet summarizes the features of the dsPIC33EPXXXGP50X. dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. То complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Familv Reference Manual', which is available from the Microchip web site (www.microchip.com).

The dsPIC33EP instruction set is almost identical to that of the dsPIC30F and dsPIC33F. The PIC24EP instruction set is almost identical to that of the PIC24F and PIC24H.

Most instructions are a single program memory word (24 bits). Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word, divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into five basic categories:

- · Word or byte-oriented operations
- · Bit-oriented operations
- · Literal operations
- DSP operations
- · Control operations

Table 28-1 lists the general symbols used in describing the instructions.

The dsPIC33E instruction set summary in Table 28-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand, which is typically a register 'Wb' without any address modifier
- The second source operand, which is typically a register 'Ws' with or without an address modifier
- The destination of the result, which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- · The file register specified by the value 'f'
- The destination, which could be either the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/ shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register 'Wb')

The literal instructions that involve data movement can use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand, which is a register 'Wb' without any address modifier
- The second source operand, which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register 'Wd' with or without an address modifier

The MAC class of DSP instructions can use some of the following operands:

- The accumulator (A or B) to be used (required operand)
- The W registers to be used as the two operands
- · The X and Y address space prefetch operations
- The X and Y address space prefetch destinations
- The accumulator write back destination

The other DSP instructions do not involve any multiplication and can include:

- The accumulator to be used (required)
- The source or destination operand (designated as Wso or Wdo, respectively) with or without an address modifier
- The amount of shift specified by a W register 'Wn' or a literal value

The control instructions can use some of the following operands:

- A program memory address
- The mode of the Table Read and Table Write instructions

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽²⁾	Status Flags Affected
46	MOV	MOV	f,Wn	Move f to Wn	1	1	None
		MOV	f	Move f to f	1	1	None
		MOV	f,WREG	Move f to WREG	1	1	None
		MOV	#litl6,Wn	Move 16-bit literal to Wn	1	1	None
		MOV.b	#lit8,Wn	Move 8-bit literal to Wn	1	1	None
		MOV	Wn,f	Move Wn to f	1	1	None
		MOV	Wso,Wdo	Move Ws to Wd	1	1	None
		MOV	WREG, f	Move WREG to f	1	1	None
		MOV.D	Wns,Wd	Move Double from W(ns):W(ns + 1) to Wd	1	2	None
		MOV.D	Ws , Wnd	Move Double from Ws to W(nd + 1):W(nd)	1	2	None
47	MOVPAG	MOVPAG	#lit10,DSRPAG	Move 10-bit literal to DSRPAG	1	1	None
		MOVPAG	#lit9,DSWPAG	Move 9-bit literal to DSWPAG	1	1	None
		MOVPAG	#lit8,TBLPAG	Move 8-bit literal to TBLPAG	1	1	None
		MOVPAG	Ws, DSRPAG	Move Ws<9:0> to DSRPAG	1	1	None
		MOVPAG	Ws, DSWPAG	Move Ws<8:0> to DSWPAG	1	1	None
		MOVPAG	Ws, TBLPAG	Move Ws<7:0> to TBLPAG	1	1	None
48	MOVSAC	MOVSAC	Acc,Wx,Wxd,Wy,Wyd,AWB ⁽¹⁾	Prefetch and store accumulator	1	1	None
49	MPY	MPY	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd(1)	Multiply Wm by Wn to Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
		MPY	Wm*Wm,Acc,Wx,Wxd,Wy,Wyd ⁽¹⁾	Square Wm to Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
50	MPY.N	MPY.N	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd(1)	-(Multiply Wm by Wn) to Accumulator	1	1	None
51	MSC	MSC	Wm*Wm, Acc, Wx, Wxd, Wy, Wyd, AWB ⁽¹⁾	Multiply and Subtract from Accumulator	1	1	OA,OB,OAB, SA,SB,SAB

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Note 1: These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

2: Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

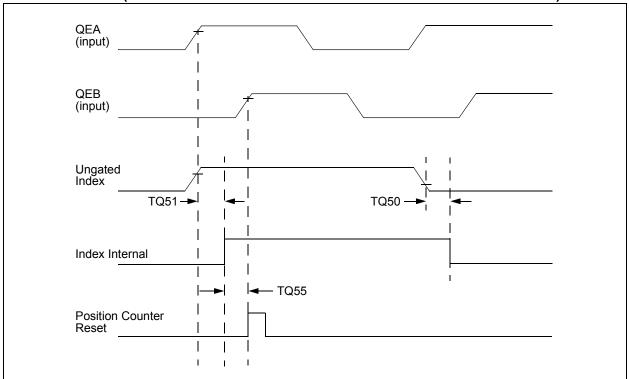


FIGURE 30-13: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

TABLE 30-32: QEI INDEX PULSE TIMING REQUIREMENTS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

АС СНА	RACTERI	STICS	$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$						
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Max.	Units	Conditions			
TQ50	TqiL	Filter Time to Recognize Low, with Digital Filter	3 * N * Tcy	_	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 (Note 2)			
TQ51	TqiH	Filter Time to Recognize High, with Digital Filter	3 * N * Tcy	_	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 (Note 2)			
TQ55	Tqidxr	Index Pulse Recognized to Position Counter Reset (ungated index)	3 TCY	—	ns				

Note 1: These parameters are characterized but not tested in manufacturing.

2: Alignment of index pulses to QEA and QEB is shown for position counter Reset timing only. Shown for forward direction only (QEA leads QEB). Same timing applies for reverse direction (QEA lags QEB) but index pulse recognition occurs on the falling edge.

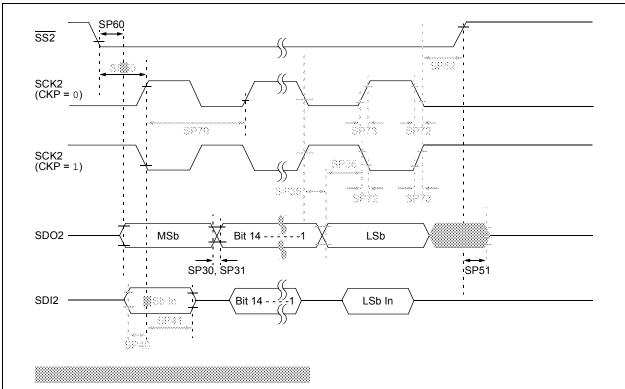
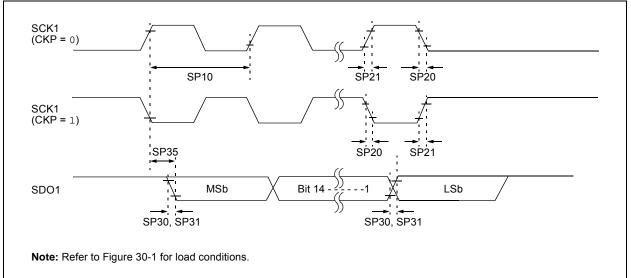


FIGURE 30-19: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS

AC CHARACTERISTICS			$\begin{tabular}{lllllllllllllllllllllllllllllllllll$				
Maximum Data Rate	Master Transmit Only (Half-Duplex)	Master Transmit/Receive (Full-Duplex)	Slave Transmit/Receive (Full-Duplex)	CKE	СКР	SMP	
15 MHz	Table 30-42	_	_	0,1	0,1	0,1	
10 MHz	_	Table 30-43	—	1	0,1	1	
10 MHz	—	Table 30-44	—	0	0,1	1	
15 MHz	—	—	Table 30-45	1	0	0	
11 MHz	—	—	Table 30-46	1	1	0	
15 MHz	_	—	Table 30-47	0	1	0	
11 MHz	_	_	Table 30-48	0	0	0	

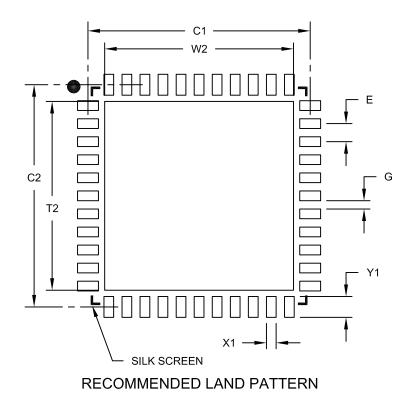
TABLE 30-41: SPI1 MAXIMUM DATA/CLOCK RATE SUMMARY

FIGURE 30-22: SPI1 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS



44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			6.60
Optional Center Pad Length	T2			6.60
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Width (X44)	X1			0.35
Contact Pad Length (X44)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2103B