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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

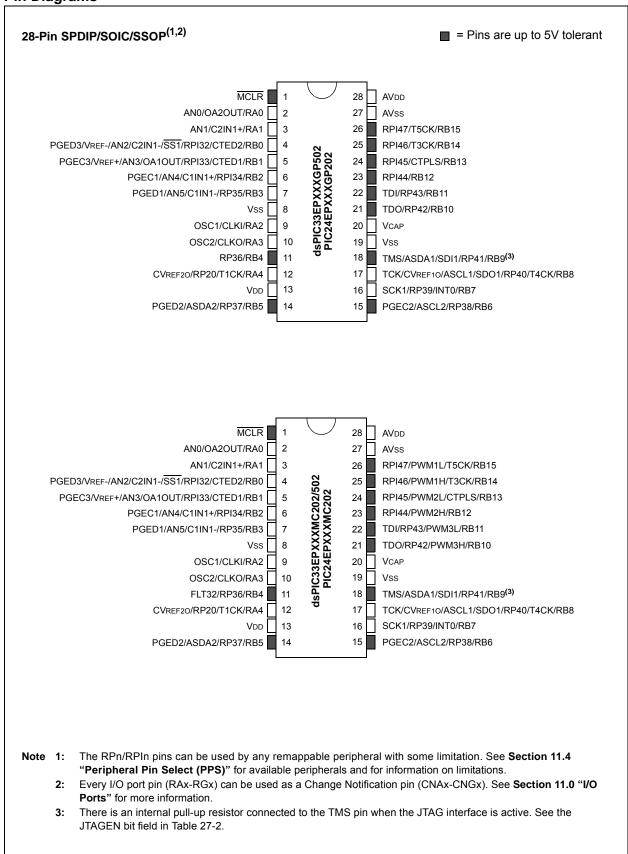
Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	21
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256gp502t-i-ss

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong





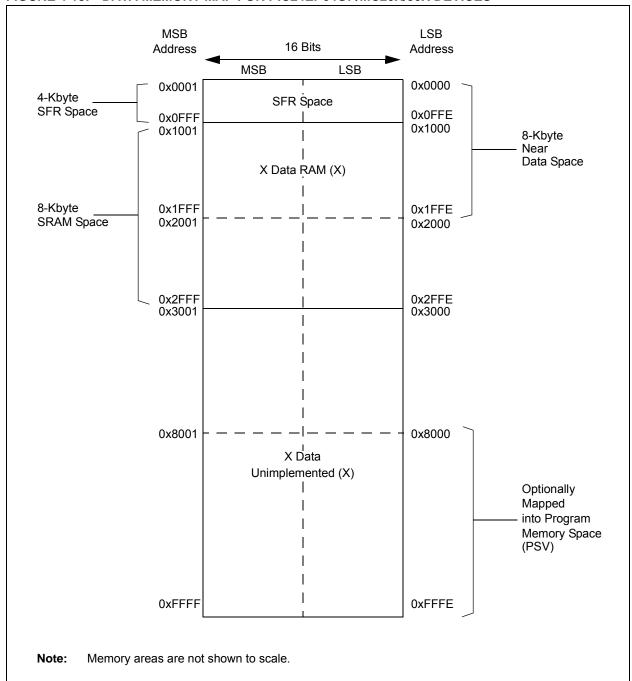


FIGURE 4-13: DATA MEMORY MAP FOR PIC24EP64GP/MC20X/50X DEVICES

TABLE 4-1: CPU CORE REGISTER MAP FOR dsPIC33EPXXXMC20X/50X AND dsPIC33EPXXXGP50X DEVICES ONLY (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	AII Resets
SR	0042	OA	ОВ	SA	SB	OAB	SAB	DA	DC	IPL2	IPL1	IPL0	RA	N	OV	Z	С	0000
CORCON	0044	VAR	_	US<	1:0>	EDT		DL<2:0>		SATA	SATB	SATDW	ACCSAT	IPL3	SFA	RND	IF	0020
MODCON	0046	XMODEN	YMODEN	-	-		BWM	<3:0>			YWM<	:3:0>			XWM<	<3:0>		0000
XMODSRT	0048			XMODSRT<15:0>							_	0000						
XMODEND	004A		XMODEND<15:0>								_	0001						
YMODSRT	004C							YMO	DSRT<15:0	>							_	0000
YMODEND	004E							YMO	DEND<15:0	>							_	0001
XBREV	0050	BREN							XBF	REV<14:0>								0000
DISICNT	0052	_	_							DISICNT<	13:0>							0000
TBLPAG	0054	_	TBLPAG<7:0>								0000							
MSTRPR	0058		MSTRPR<15:0>								0000							

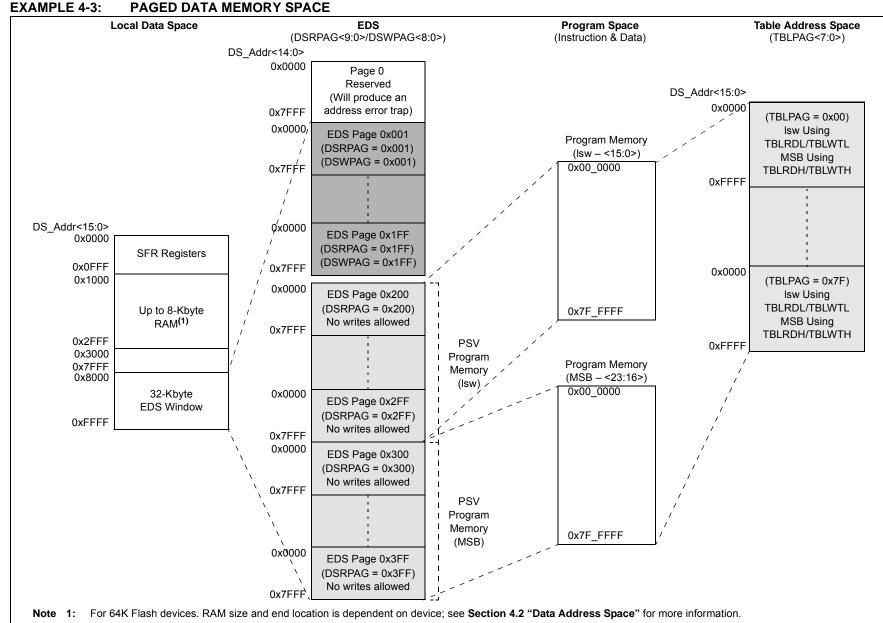
dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-6: INTERRUPT CONTROLLER REGISTER MAP FOR dsPIC33EPXXXMC20X DEVICES ONLY (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IPC35	0886	1	,	JTAGIP<2:0	)>	_		ICDIP<2:0	>	1	_	-	1	_	_	_	_	4400
IPC36	0888	-	ı	PTG0IP<2:0	)>	_	PT	GWDTIP<	2:0>	ı	P	TGSTEPIP<2	:0>	_	-	ı	-	4440
IPC37	088A	-	_	_	_	_	P	TG3IP<2:0	)>	ı		PTG2IP<2:0>	>	_	F	TG1IP<2:0>		0444
INTCON1	08C0	NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE	SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	ı	0000
INTCON2	08C2	GIE	DISI	SWTRAP	-	_	_	_	-	ı	_	_	ı	_	INT2EP	INT1EP	INT0EP	8000
INTCON3	08C4	ı	_	_	-	_	_	_	-	ı	_	DAE	DOOVR	_	-	ı	ı	0000
INTCON4	08C6	-	_	_	_	_	_	_	_	-	_	_		_	_	_	SGHT	0000
INTTREG	08C8	_	_	_	_		ILR<	3:0>		VECNUM<7:0>					0000			

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

Allocating different Page registers for read and write access allows the architecture to support data movement between different pages in data memory. This is accomplished by setting the DSRPAG register value to the page from which you want to read, and configuring the DSWPAG register to the page to which it needs to be written. Data can also be moved from different PSV to EDS pages, by configuring the DSRPAG and DSWPAG registers to address PSV and EDS space, respectively. The data can be moved between pages by a single instruction.

When an EDS or PSV page overflow or underflow occurs, EA<15> is cleared as a result of the register indirect EA calculation. An overflow or underflow of the EA in the EDS or PSV pages can occur at the page boundaries when:

- The initial address prior to modification addresses an EDS or PSV page
- The EA calculation uses Pre-Modified or Post-Modified Register Indirect Addressing; however, this does not include Register Offset Addressing

In general, when an overflow is detected, the DSxPAG register is incremented and the EA<15> bit is set to keep the base address within the EDS or PSV window. When an underflow is detected, the DSxPAG register is decremented and the EA<15> bit is set to keep the base address within the EDS or PSV window. This creates a linear EDS and PSV address space, but only when using Register Indirect Addressing modes.

Exceptions to the operation described above arise when entering and exiting the boundaries of Page 0, EDS and PSV spaces. Table 4-61 lists the effects of overflow and underflow scenarios at different boundaries.

In the following cases, when overflow or underflow occurs, the EA<15> bit is set and the DSxPAG is not modified; therefore, the EA will wrap to the beginning of the current page:

- · Register Indirect with Register Offset Addressing
- · Modulo Addressing
- Bit-Reversed Addressing

TABLE 4-61: OVERFLOW AND UNDERFLOW SCENARIOS AT PAGE 0, EDS and PSV SPACE BOUNDARIES<sup>(2,3,4)</sup>

	•	OV SI ACE BOOK	D/ (( ( ) = 0				
0/11			Before			After	
O/U, R/W	Operation	DSxPAG	DS EA<15>	Page Description	DSxPAG	DS EA<15>	Page Description
O, Read		DSRPAG = 0x1FF	1	EDS: Last page	DSRPAG = 0x1FF	0	See Note 1
O, Read	[++Wn]	DSRPAG = 0x2FF	1	PSV: Last Isw page	DSRPAG = 0x300	1	PSV: First MSB page
O, Read	or [Wn++]	DSRPAG = 0x3FF	1	PSV: Last MSB page	DSRPAG = 0x3FF	0	See Note 1
O, Write		DSWPAG = 0x1FF	1	EDS: Last page	DSWPAG = 0x1FF	0	See Note 1
U, Read		DSRPAG = 0x001	1	PSV page	DSRPAG = 0x001	0	See Note 1
U, Read	[Wn] <b>or</b> [Wn]	DSRPAG = 0x200	1	PSV: First Isw page	DSRPAG = 0x200	0	See Note 1
U, Read	[ [ ]	DSRPAG = 0x300	1	PSV: First MSB page	DSRPAG = 0x2FF	1	PSV: Last Isw page

**Legend:** O = Overflow, U = Underflow, R = Read, W = Write

- Note 1: The Register Indirect Addressing now addresses a location in the base Data Space (0x0000-0x8000).
  - 2: An EDS access with DSxPAG = 0x000 will generate an address error trap.
  - **3:** Only reads from PS are supported using DSRPAG. An attempt to write to PS using DSWPAG will generate an address error trap.
  - 4: Pseudo-Linear Addressing is not supported for large offsets.

#### REGISTER 8-1: DMAXCON: DMA CHANNEL x CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
CHEN	SIZE	DIR	HALF	NULLW	_	_	_
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
_	_	AMODE1	AMODE0	_	_	MODE1	MODE0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 CHEN: DMA Channel Enable bit

1 = Channel is enabled0 = Channel is disabled

bit 14 SIZE: DMA Data Transfer Size bit

1 = Byte0 = Word

bit 13 DIR: DMA Transfer Direction bit (source/destination bus select)

1 = Reads from RAM address, writes to peripheral address

0 = Reads from peripheral address, writes to RAM address

bit 12 HALF: DMA Block Transfer Interrupt Select bit

1 = Initiates interrupt when half of the data has been moved

0 = Initiates interrupt when all of the data has been moved

bit 11 NULLW: Null Data Peripheral Write Mode Select bit

1 = Null data write to peripheral in addition to RAM write (DIR bit must also be clear)

0 = Normal operation

bit 10-6 Unimplemented: Read as '0'

bit 5-4 AMODE<1:0>: DMA Channel Addressing Mode Select bits

11 = Reserved

10 = Peripheral Indirect Addressing mode

01 = Register Indirect without Post-Increment mode

00 = Register Indirect with Post-Increment mode

bit 3-2 **Unimplemented:** Read as '0'

bit 1-0 MODE<1:0>: DMA Channel Operating Mode Select bits

11 = One-Shot, Ping-Pong modes are enabled (one block transfer from/to each DMA buffer)

10 = Continuous, Ping-Pong modes are enabled

01 = One-Shot, Ping-Pong modes are disabled

00 = Continuous, Ping-Pong modes are disabled

sPIC33EPXXXG	P50X, dsPIC	33EPXXXM(	C20X/50X AI	ND PIC24EF	PXXXGP/M	C20X
OTES:						

## 18.3 SPIx Control Registers

#### REGISTER 18-1: SPIXSTAT: SPIX STATUS AND CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	
SPIEN	_	SPISIDL	_	_		SPIBEC<2:0>	1	
bit 15 b								

R/W-0	R/C-0, HS	R/W-0	R/W-0	R/W-0	R/W-0	R-0, HS, HC	R-0, HS, HC
SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF
bit 7						•	bit 0

Legend:	C = Clearable bit	HS = Hardware Settable bit	t HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ad as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 SPIEN: SPIx Enable bit

1 = Enables the module and configures SCKx, SDOx, SDIx and  $\overline{SSx}$  as serial port pins

0 = Disables the module

bit 14 **Unimplemented:** Read as '0'

bit 13 SPISIDL: SPIx Stop in Idle Mode bit

1 = Discontinues the module operation when device enters Idle mode

0 = Continues the module operation in Idle mode

bit 12-11 **Unimplemented:** Read as '0'

bit 10-8 SPIBEC<2:0>: SPIx Buffer Element Count bits (valid in Enhanced Buffer mode)

Master mode:

Number of SPIx transfers that are pending.

Slave mode:

Number of SPIx transfers that are unread.

bit 7 SRMPT: SPIx Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode)

1 = SPIx Shift register is empty and Ready-To-Send or receive the data

0 = SPIx Shift register is not empty

bit 6 SPIROV: SPIx Receive Overflow Flag bit

1 = A new byte/word is completely received and discarded; the user application has not read the previous data in the SPIxBUF register

0 = No overflow has occurred

bit 5 SRXMPT: SPIx Receive FIFO Empty bit (valid in Enhanced Buffer mode)

1 = RX FIFO is empty

0 = RX FIFO is not empty

bit 4-2 SISEL<2:0>: SPIx Buffer Interrupt Mode bits (valid in Enhanced Buffer mode)

111 = Interrupt when the SPIx transmit buffer is full (SPITBF bit is set)

110 = Interrupt when last bit is shifted into SPIxSR and as a result, the TX FIFO is empty

101 = Interrupt when the last bit is shifted out of SPIxSR and the transmit is complete

100 = Interrupt when one data is shifted into the SPIxSR and as a result, the TX FIFO has one open memory location

011 = Interrupt when the SPIx receive buffer is full (SPIRBF bit is set)

010 = Interrupt when the SPIx receive buffer is 3/4 or more full

001 = Interrupt when data is available in the receive buffer (SRMPT bit is set)

000 = Interrupt when the last data in the receive buffer is read and as a result, the buffer is empty (SRXMPT bit is set)

# 20.1 UART Helpful Tips

- 1. In multi-node, direct-connect UART networks, receive inputs react to complementary logic level defined by the URXINV bit (UxMODE<4>), which defines the Idle state, the default of which is logic high (i.e., URXINV = 0). Because remote devices do not initialize at the same time, it is likely that one of the devices, because the RX line is floating, will trigger a Start bit detection and will cause the first byte received, after the device has been initialized, to be invalid. To avoid this situation, the user should use a pull-up or pull-down resistor on the RX pin depending on the value of the URXINV bit.
  - a) If URXINV = 0, use a pull-up resistor on the RX pin.
  - b) If URXINV = 1, use a pull-down resistor on the RX pin.
- 2. The first character received on a wake-up from Sleep mode caused by activity on the UxRX pin of the UARTx module will be invalid. In Sleep mode, peripheral clocks are disabled. By the time the oscillator system has restarted and stabilized from Sleep mode, the baud rate bit sampling clock, relative to the incoming UxRX bit timing, is no longer synchronized, resulting in the first character being invalid; this is to be expected.

#### 20.2 UART Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser:
http://www.microchip.com/wwwproducts/
Devices.aspx?dDocName=en555464

#### 20.2.1 KEY RESOURCES

- "UART" (DS70582) in the "dsPIC33/PIC24 Family Reference Manual"
- · Code Samples
- · Application Notes
- · Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- · Development Tools

#### REGISTER 21-24: CxRXOVF1: ECANx RECEIVE BUFFER OVERFLOW REGISTER 1

R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0	R/C-0
RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8
bit 15							bit 8

| R/C-0  |
|--------|--------|--------|--------|--------|--------|--------|--------|
| RXOVF7 | RXOVF6 | RXOVF5 | RXOVF4 | RXOVF3 | RXOVF2 | RXOVF1 | RXOVF0 |
| bit 7  |        |        |        |        |        |        | bit 0  |

**Legend:** C = Writable bit, but only '0' can be written to clear the bit

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

#### bit 15-0 **RXOVF<15:0>:** Receive Buffer n Overflow bits

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition (cleared by user software)

#### REGISTER 21-25: CxRXOVF2: ECANx RECEIVE BUFFER OVERFLOW REGISTER 2

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXOVF31 | RXOVF30 | RXOVF29 | RXOVF28 | RXOVF27 | RXOVF26 | RXOVF25 | RXOVF24 |
| bit 15  |         |         |         |         |         |         | bit 8   |

| R/C-0   |
|---------|---------|---------|---------|---------|---------|---------|---------|
| RXOVF23 | RXOVF22 | RXOVF21 | RXOVF20 | RXOVF19 | RXOVF18 | RXOVF17 | RXOVF16 |
| bit 7   |         |         |         |         |         |         | bit 0   |

**Legend:** C = Writable bit, but only '0' can be written to clear the bit

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

## bit 15-0 **RXOVF<31:16>:** Receive Buffer n Overflow bits

1 = Module attempted to write to a full buffer (set by module)

0 = No overflow condition (cleared by user software)

#### REGISTER 22-3: CTMUICON: CTMU CURRENT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-10 ITRIM<5:0>: Current Source Trim bits

011111 = Maximum positive change from nominal current + 62%

011110 = Maximum positive change from nominal current + 60%

•

•

•

000010 = Minimum positive change from nominal current + 4%

000001 = Minimum positive change from nominal current + 2%

000000 = Nominal current output specified by IRNG<1:0>

111111 = Minimum negative change from nominal current – 2%

111110 = Minimum negative change from nominal current – 4%

•

•

•

100010 = Maximum negative change from nominal current – 60% 100001 = Maximum negative change from nominal current – 62%

bit 9-8 IRNG<1:0>: Current Source Range Select bits

11 = 100 × Base Current(2)

10 = 10 × Base Current(2)

01 = Base Current Level(2)

00 = 1000 × Base Current(1,2)

bit 7-0 **Unimplemented:** Read as '0'

- **Note 1:** This current range is not available to be used with the internal temperature measurement diode.
  - 2: Refer to the CTMU Current Source Specifications (Table 30-56) in **Section 30.0 "Electrical Characteristics"** for the current range selection values.

# REGISTER 23-5: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER (CONTINUED)

bit 0 CH123SA: Channel 1, 2, 3 Positive Input Select for Sample MUXA bit
In 12-bit mode (AD21B = 1), CH123SA is Unimplemented and is Read as '0':

Value	ADC Channel					
value	CH1	CH2	СНЗ			
<b>1</b> (2)	OA1/AN3	OA2/AN0	OA3/AN6			
0(1,2)	OA2/AN0	AN1	AN2			

- **Note 1:** AN0 through AN7 are repurposed when comparator and op amp functionality is enabled. See Figure 23-1 to determine how enabling a particular op amp or comparator affects selection choices for Channels 1, 2 and 3.
  - 2: The OAx input is used if the corresponding op amp is selected (OPMODE (CMxCON<10>) = 1); otherwise, the ANx input is used.

### REGISTER 23-6: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER (CONTINUED)

```
CH0SA<4:0>: Channel 0 Positive Input Select for Sample MUXA bits(1)
bit 4-0
              11111 = Open; use this selection with CTMU capacitive and time measurement
              11110 = Channel 0 positive input is connected to the CTMU temperature measurement diode (CTMU TEMP)
              11101 = Reserved
              11100 = Reserved
              11011 = Reserved
              11010 = Channel 0 positive input is the output of OA3/AN6<sup>(2,3)</sup>
              11001 = Channel 0 positive input is the output of OA2/AN0<sup>(2)</sup>
              11000 = Channel 0 positive input is the output of OA1/AN3<sup>(2)</sup>
              10110 = Reserved
              10000 = Reserved
              01111 = Channel 0 positive input is AN15<sup>(1,3)</sup>
              01110 = Channel 0 positive input is AN14<sup>(1,3)</sup>
              01101 = Channel 0 positive input is AN13<sup>(1,3)</sup>
              00010 = Channel 0 positive input is AN2(1,3)
              00001 = Channel 0 positive input is AN1<sup>(1,3)</sup>
              00000 = Channel 0 positive input is AN0^{(1,3)}
```

- Note 1: AN0 through AN7 are repurposed when comparator and op amp functionality is enabled. See Figure 23-1 to determine how enabling a particular op amp or comparator affects selection choices for Channels 1, 2 and 3.
  - 2: The OAx input is used if the corresponding op amp is selected (OPMODE (CMxCON<10>) = 1); otherwise, the ANx input is used.
  - **3:** See the "Pin Diagrams" section for the available analog channels for each device.

# 24.4 Step Commands and Format

TABLE 24-1: PTG STEP COMMAND FORMAT

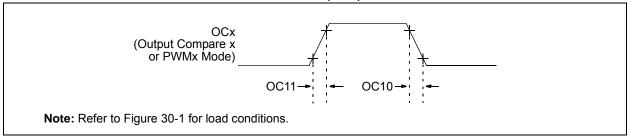
Step Command Byte:					
	STEP	<7:0>			
CMD<3:0>		OPTION<3:0>			
bit 7	bit 4	bit 3	bit 0		

bit 7-4	CMD<3:0>	Step Command	Command Description
	0000	PTGCTRL	Execute control command as described by OPTION<3:0>.
	0001	PTGADD	Add contents of PTGADJ register to target register as described by OPTION<3:0>.
		PTGCOPY	Copy contents of PTGHOLD register to target register as described by OPTION<3:0>.
	001x	PTGSTRB	Copy the value contained in CMD<0>:OPTION<3:0> to the CH0SA<4:0> bits (AD1CHS0<4:0>).
	0100	PTGWHI	Wait for a low-to-high edge input from the selected PTG trigger input as described by OPTION<3:0>.
	0101	PTGWLO	Wait for a high-to-low edge input from the selected PTG trigger input as described by OPTION<3:0>.
	0110	Reserved	Reserved.
	0111	PTGIRQ	Generate individual interrupt request as described by OPTION3<:0>.
	100x	PTGTRIG	Generate individual trigger output as described by < <cmd<0>:OPTION&lt;3:0&gt;&gt;.</cmd<0>
	101x	PTGJMP	Copy the value indicated in < <cmd<0>:OPTION&lt;3:0&gt;&gt; to the Queue Pointer (PTGQPTR) and jump to that Step queue.</cmd<0>
	110x	PTGJMPC0	PTGC0 = PTGC0LIM: Increment the Queue Pointer (PTGQPTR).
			PTGC0 ≠ PTGC0LIM: Increment Counter 0 (PTGC0) and copy the value indicated in < <cmd<0>:OPTION&lt;3:0&gt;&gt; to the Queue Pointer (PTGQPTR), and jump to that Step queue</cmd<0>
	111x	PTGJMPC1	PTGC1 = PTGC1LIM: Increment the Queue Pointer (PTGQPTR).
			PTGC1 ≠ PTGC1LIM: Increment Counter 1 (PTGC1) and copy the value indicated in < <cmd<0>:OPTION&lt;3:0&gt;&gt; to the Queue Pointer (PTGQPTR), and jump to that Step queue.</cmd<0>

Note 1: All reserved commands or options will execute but have no effect (i.e., execute as a NOP instruction).

- 2: Refer to Table 24-2 for the trigger output descriptions.
- 3: This feature is only available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices.

# FIGURE 30-7: OUTPUT COMPARE x MODULE (OCx) TIMING CHARACTERISTICS



#### TABLE 30-27: OUTPUT COMPARE x MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)  Operating temperature $-40^{\circ}\text{C} \le \text{Ta} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{Ta} \le +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур.	Max.	Units	Conditions	
OC10	TccF	OCx Output Fall Time	_	_	_	ns	See Parameter DO32	
OC11	TccR	OCx Output Rise Time		_	_	ns	See Parameter DO31	

Note 1: These parameters are characterized but not tested in manufacturing.

FIGURE 30-8: OCx/PWMx MODULE TIMING CHARACTERISTICS

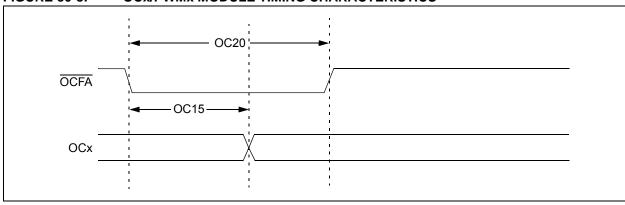


TABLE 30-28: OCx/PWMx MODE TIMING REQUIREMENTS

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур.	Max.	Units	Conditions
OC15	TFD	Fault Input to PWMx I/O Change		_	Tcy + 20	ns	
OC20	TFLT	Fault Input Pulse Width	Tcy + 20	_	_	ns	

Note 1: These parameters are characterized but not tested in manufacturing.

FIGURE 30-26: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS

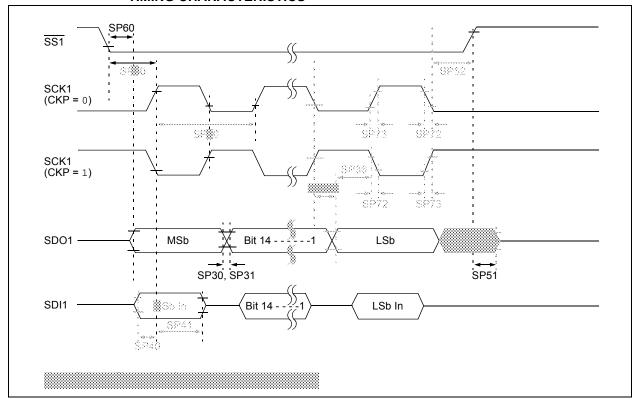
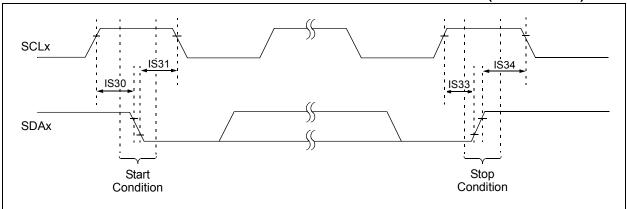
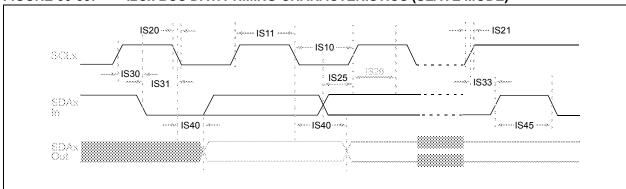


FIGURE 30-32: I2Cx BUS START/STOP BITS TIMING CHARACTERISTICS (SLAVE MODE)

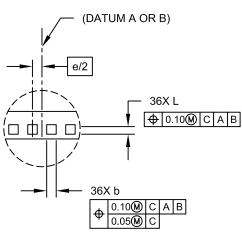


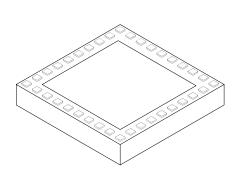
# FIGURE 30-33: I2Cx BUS DATA TIMING CHARACTERISTICS (SLAVE MODE)



# 36-Terminal Very Thin Thermal Leadless Array Package (TL) – 5x5x0.9 mm Body with Exposed Pad [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





**DETAIL A** 

	Units	N	1ILLIMETER	S
Dimension	Limits	MIN	NOM	MAX
Number of Pins	N		36	
Number of Pins per Side	ND		10	
Number of Pins per Side	NE		8	
Pitch	е		0.50 BSC	
Overall Height	Α	0.80	0.90	1.00
Standoff	A1	0.025	-	0.075
Overall Width	Е		5.00 BSC	
Exposed Pad Width	E2	3.60	3.75	3.90
Overall Length	D		5.00 BSC	
Exposed Pad Length	D2	3.60	3.75	3.90
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.20	0.25	0.30
Contact-to-Exposed Pad	K	0.20	-	-

#### Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated.
- 3. Dimensioning and tolerancing per ASME Y14.5M.
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-187C Sheet 2 of 2

TABLE A-5: MAJOR SECTION UPDATES (CONTINUED)

Section Name	Update Description
Section 30.0 "Electrical	Throughout: qualifies all footnotes relating to the operation of analog modules below
Characteristics"	VDDMIN (replaces "will have" with "may have")
	Throughout: changes all references of SPI timing parameter symbol "TscP" to "FscP"
	Table 30-1: changes VDD range to 3.0V to 3.6V
	Table 30-4: removes Parameter DC12 (RAM Retention Voltage)
	Table 30-7: updates Maximum values at 10 and 20 MIPS
	• Table 30-8: adds Maximum IPD values, and removes all ΔIWDT entries
	<ul> <li>Adds new Table 30-9 (Watchdog Timer Delta Current) with consolidated values removed from Table 30-8. All subsequent tables are renumbered accordingly.</li> </ul>
	<ul> <li>Table 30-10: adds footnote for all parameters for 1:2 Doze ratio</li> <li>Table 30-11:</li> </ul>
	- changes Minimum and Maximum values for D120 and D130
	- adds Minimum and Maximum values for D131
	<ul> <li>adds Minimum and Maximum values for D150 through D156, and removes</li> <li>Typical values</li> </ul>
	• Table 30-12:
	- reformats table for readability
	- changes IoL conditions for DO10
	Table 30-14: adds footnote to D135
	Table 30-17: changes Minimum and Maximum values for OS30  Table 30-17: changes Minimum and Maximum values for OS30  Table 30-17: changes Minimum and Maximum values for OS30  Table 30-17: changes Minimum and Maximum values for OS30  Table 30-17: changes Minimum and Maximum values for OS30  Table 30-17: changes Minimum and Maximum values for OS30
	• Table 30-19:
	- splits temperature range and adds new values for F20a
	<ul> <li>reduces temperature range for F20b to extended temperatures only</li> <li>Table 30-20:</li> </ul>
	- splits temperature range and adds new values for F21a
	- reduces temperature range for F20b to extended temperatures only
	• Table 30-53:
	- adds Maximum value to CM30
	- adds footnote ("Parameter characterized") to multiple parameters  Table 30.55; adds Minimum and Maximum values for all CTM II specifications, and
	<ul> <li>Table 30-55: adds Minimum and Maximum values for all CTMUI specifications, and removes Typical values</li> </ul>
	Table 30-57: adds new footnote to AD09
	• Table 30-58:
	<ul> <li>removes all specifications for accuracy with external voltage references</li> <li>removes Typical values for AD23a and AD24a</li> </ul>
	- replaces Minimum and Maximum values for AD21a, AD22a, AD23a and AD24a
	with new values, split by Industrial and Extended temperatures - removes Maximum value of AD30
	- removes Minimum values from AD31a and AD32a
	- adds or changes Typical values for AD30, AD31a, AD32a and AD33a
	Table 30-59:
	- removes all specifications for accuracy with external voltage references
	- removes Maximum value of AD30
	- removes Typical values for AD23b and AD24b
	- replaces Minimum and Maximum values for AD21b, AD22b, AD23b and AD24b
	with new values, split by Industrial and Extended temperatures
	- removes Minimum and Maximum values from AD31b, AD32b, AD33b and AD34b
	- adds or changes Typical values for AD30, AD31a, AD32a and AD33a
	Table 30-61: Adds footnote to AD51
Section 32.0 "DC and AC Device Characteristics Graphs"	<ul> <li>Updates Figure 32-6 (Typical IDD @ 3.3V) with individual current vs. processor speed curves for the different program memory sizes</li> </ul>
Section 33.0 "Packaging Information"	<ul> <li>Replaces drawing C04-149C (64-pin QFN, 7.15 x 7.15 exposed pad) with C04-154A (64-pin QFN, 5.4 x 5.4 exposed pad)</li> </ul>