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Details

Product Status	Obsolete
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	53
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 16x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 150°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256mc206-h-pt

TABLE 2: dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X MOTOR CONTROL FAMILIES

Device	Page Erase Size (Instructions)	Program Flash Memory (Kbytes)	RAM (Kbytes)	Remappable Peripherals								I ² C™	CRC Generator	10-Bit/12-Bit ADC (Channels)	Op Amps/Comparators	CTMU	PTG	I/O Pins	Pins	Packages	
				16-Bit/32-Bit Timers	Input Capture	Output Compare	Motor Control PWM ⁽⁴⁾ (Channels)	Quadrature Encoder Interface	UART	SP ⁽²⁾	ECAN™ Technology										External Interrupts ⁽³⁾
PIC24EP32MC202	512	32	4	5	4	4	6	1	2	2	—	3	2	1	6	2/3 ⁽¹⁾	Yes	Yes	21	28	SPDIP, SOIC, SSOP ⁽⁵⁾ , QFN-S
PIC24EP64MC202	1024	64	8																		
PIC24EP128MC202	1024	128	16																		
PIC24EP256MC202	1024	256	32																		
PIC24EP512MC202	1024	512	48	5	4	4	6	1	2	2	—	3	2	1	8	3/4	Yes	Yes	25	36	VTLA
PIC24EP32MC203	512	32	4																		
PIC24EP64MC203	1024	64	8																		
PIC24EP32MC204	512	32	4																		
PIC24EP64MC204	1024	64	8	5	4	4	6	1	2	2	—	3	2	1	9	3/4	Yes	Yes	35	44/ 48	VTLA ⁽⁵⁾ , TQFP, QFN, UQFN
PIC24EP128MC204	1024	128	16																		
PIC24EP256MC204	1024	256	32																		
PIC24EP512MC204	1024	512	48																		
PIC24EP64MC206	1024	64	8	5	4	4	6	1	2	2	—	3	2	1	16	3/4	Yes	Yes	53	64	TQFP, QFN
PIC24EP128MC206	1024	128	16																		
PIC24EP256MC206	1024	256	32																		
PIC24EP512MC206	1024	512	48																		
dsPIC33EP32MC202	512	32	4	5	4	4	6	1	2	2	—	3	2	1	6	2/3 ⁽¹⁾	Yes	Yes	21	28	SPDIP, SOIC, SSOP ⁽⁵⁾ , QFN-S
dsPIC33EP64MC202	1024	64	8																		
dsPIC33EP128MC202	1024	128	16																		
dsPIC33EP256MC202	1024	256	32																		
dsPIC33EP512MC202	1024	512	48	5	4	4	6	1	2	2	—	3	2	1	8	3/4	Yes	Yes	25	36	VTLA
dsPIC33EP32MC203	512	32	4																		
dsPIC33EP64MC203	1024	64	8																		
dsPIC33EP32MC204	512	32	4																		
dsPIC33EP64MC204	1024	64	8	5	4	4	6	1	2	2	—	3	2	1	9	3/4	Yes	Yes	35	44/ 48	VTLA ⁽⁵⁾ , TQFP, QFN, UQFN
dsPIC33EP128MC204	1024	128	16																		
dsPIC33EP256MC204	1024	256	32																		
dsPIC33EP512MC204	1024	512	48																		
dsPIC33EP64MC206	1024	64	8	5	4	4	6	1	2	2	—	3	2	1	16	3/4	Yes	Yes	53	64	TQFP, QFN
dsPIC33EP128MC206	1024	128	16																		
dsPIC33EP256MC206	1024	256	32																		
dsPIC33EP512MC206	1024	512	48																		
dsPIC33EP32MC502	512	32	4	5	4	4	6	1	2	2	1	3	2	1	6	2/3 ⁽¹⁾	Yes	Yes	21	28	SPDIP, SOIC, SSOP ⁽⁵⁾ , QFN-S
dsPIC33EP64MC502	1024	64	8																		
dsPIC33EP128MC502	1024	128	16																		
dsPIC33EP256MC502	1024	256	32																		
dsPIC33EP512MC502	1024	512	48	5	4	4	6	1	2	2	1	3	2	1	8	3/4	Yes	Yes	25	36	VTLA
dsPIC33EP32MC503	512	32	4																		
dsPIC33EP64MC503	1024	64	8																		

- Note 1:** On 28-pin devices, Comparator 4 does not have external connections. Refer to **Section 25.0 “Op Amp/Comparator Module”** for details.
2: Only SPI2 is remappable.
3: INT0 is not remappable.
4: Only the PWM Faults are remappable.
5: The SSOP and VTLA packages are not available for devices with 512 Kbytes of memory.

TABLE 4-41: PMD REGISTER MAP FOR dsPIC33EPXXXMC20X DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0760	T5MD	T4MD	T3MD	T2MD	T1MD	QE1MD	PWMMD	—	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	AD1MD	0000
PMD2	0762	—	—	—	—	IC4MD	IC3MD	IC2MD	IC1MD	—	—	—	—	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0764	—	—	—	—	—	CMPMD	—	—	CRCMD	—	—	—	—	—	I2C2MD	—	0000
PMD4	0766	—	—	—	—	—	—	—	—	—	—	—	—	REFOMD	CTMUMD	—	—	0000
PMD6	076A	—	—	—	—	—	PWM3MD	PWM2MD	PWM1MD	—	—	—	—	—	—	—	—	0000
PMD7	076C	—	—	—	—	—	—	—	—	—	—	—	DMA0MD	PTGMD	—	—	—	0000
													DMA1MD					
													DMA2MD					
													DMA3MD					

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

NOTES:

12.2 Timer1 Control Register

REGISTER 12-1: T1CON: TIMER1 CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON ⁽¹⁾	—	TSIDL	—	—	—	—	—
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
—	TGATE	TCKPS1	TCKPS0	—	TSYNC ⁽¹⁾	TCS ⁽¹⁾	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **TON:** Timer1 On bit⁽¹⁾
 1 = Starts 16-bit Timer1
 0 = Stops 16-bit Timer1
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **TSIDL:** Timer1 Stop in Idle Mode bit
 1 = Discontinues module operation when device enters Idle mode
 0 = Continues module operation in Idle mode
- bit 12-7 **Unimplemented:** Read as '0'
- bit 6 **TGATE:** Timer1 Gated Time Accumulation Enable bit
 When TCS = 1:
 This bit is ignored.
 When TCS = 0:
 1 = Gated time accumulation is enabled
 0 = Gated time accumulation is disabled
- bit 5-4 **TCKPS<1:0>:** Timer1 Input Clock Prescale Select bits
 11 = 1:256
 10 = 1:64
 01 = 1:8
 00 = 1:1
- bit 3 **Unimplemented:** Read as '0'
- bit 2 **TSYNC:** Timer1 External Clock Input Synchronization Select bit⁽¹⁾
 When TCS = 1:
 1 = Synchronizes external clock input
 0 = Does not synchronize external clock input
 When TCS = 0:
 This bit is ignored.
- bit 1 **TCS:** Timer1 Clock Source Select bit⁽¹⁾
 1 = External clock is from pin, T1CK (on the rising edge)
 0 = Internal clock (Fp)
- bit 0 **Unimplemented:** Read as '0'

Note 1: When Timer1 is enabled in External Synchronous Counter mode (TCS = 1, TSYNC = 1, TON = 1), any attempts by user software to write to the TMR1 register are ignored.

17.0 QUADRATURE ENCODER INTERFACE (QEI) MODULE (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Quadrature Encoder Interface (QEI)**” (DS70601) in the “*dsPIC33/PIC24 Family Reference Manual*”, which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

This chapter describes the Quadrature Encoder Interface (QEI) module and associated operational modes. The QEI module provides the interface to incremental encoders for obtaining mechanical position data.

The operational features of the QEI module include:

- 32-Bit Position Counter
- 32-Bit Index Pulse Counter
- 32-Bit Interval Timer
- 16-Bit Velocity Counter
- 32-Bit Position Initialization/Capture/Compare High register
- 32-Bit Position Compare Low register
- x4 Quadrature Count mode
- External Up/Down Count mode
- External Gated Count mode
- External Gated Timer mode
- Internal Timer mode

Figure 17-1 illustrates the QEI block diagram.

REGISTER 17-2: QE1IOC: QE1 I/O CONTROL REGISTER (CONTINUED)

bit 2	INDEX: Status of INDXx Input Pin After Polarity Control 1 = Pin is at logic '1' 0 = Pin is at logic '0'
bit 1	QEB: Status of QEBx Input Pin After Polarity Control And SWPAB Pin Swapping 1 = Pin is at logic '1' 0 = Pin is at logic '0'
bit 0	QEA: Status of QEAx Input Pin After Polarity Control And SWPAB Pin Swapping 1 = Pin is at logic '1' 0 = Pin is at logic '0'

REGISTER 17-17: INT1TMRH: INTERVAL 1 TIMER HIGH WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
INTTMR<31:24>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
INTTMR<23:16>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **INTTMR<31:16>**: High Word Used to Form 32-Bit Interval Timer Register (INT1TMR) bits

REGISTER 17-18: INT1TMRL: INTERVAL 1 TIMER LOW WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
INTTMR<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
INTTMR<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **INTTMR<15:0>**: Low Word Used to Form 32-Bit Interval Timer Register (INT1TMR) bits

REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

- bit 3 **S:** Start bit
1 = Indicates that a Start (or Repeated Start) bit has been detected last
0 = Start bit was not detected last
Hardware is set or clear when a Start, Repeated Start or Stop is detected.
- bit 2 **R_W:** Read/Write Information bit (when operating as I²C slave)
1 = Read – Indicates data transfer is output from the slave
0 = Write – Indicates data transfer is input to the slave
Hardware is set or clear after reception of an I²C device address byte.
- bit 1 **RBF:** Receive Buffer Full Status bit
1 = Receive is complete, I2CxRCV is full
0 = Receive is not complete, I2CxRCV is empty
Hardware is set when I2CxRCV is written with a received byte. Hardware is clear when software reads I2CxRCV.
- bit 0 **TBF:** Transmit Buffer Full Status bit
1 = Transmit in progress, I2CxTRN is full
0 = Transmit is complete, I2CxTRN is empty
Hardware is set when software writes to I2CxTRN. Hardware is clear at completion of a data transmission.

20.3 UARTx Control Registers

REGISTER 20-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾	—	USIDL	IREN ⁽²⁾	RTSMD	—	UEN1	UEN0
bit 15						bit 8	

R/W-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7						bit 0	

Legend:	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **UARTEN:** UARTx Enable bit⁽¹⁾
 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
 0 = UARTx is disabled; all UARTx pins are controlled by PORT latches; UARTx power consumption is minimal
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **USIDL:** UARTx Stop in Idle Mode bit
 1 = Discontinues module operation when device enters Idle mode
 0 = Continues module operation in Idle mode
- bit 12 **IREN:** IrDA[®] Encoder and Decoder Enable bit⁽²⁾
 1 = IrDA encoder and decoder are enabled
 0 = IrDA encoder and decoder are disabled
- bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
 1 = $\overline{\text{UxRTS}}$ pin is in Simplex mode
 0 = $\overline{\text{UxRTS}}$ pin is in Flow Control mode
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **UEN<1:0>:** UARTx Pin Enable bits
 11 = UxTX, UxRX and BCLKx pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by PORT latches⁽³⁾
 10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used⁽⁴⁾
 01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin is controlled by PORT latches⁽⁴⁾
 00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ /BCLKx pins are controlled by PORT latches
- bit 7 **WAKE:** Wake-up on Start bit Detect During Sleep Mode Enable bit
 1 = UARTx continues to sample the UxRX pin; interrupt is generated on the falling edge; bit is cleared in hardware on the following rising edge
 0 = No wake-up is enabled
- bit 6 **LPBACK:** UARTx Loopback Mode Select bit
 1 = Enables Loopback mode
 0 = Loopback mode is disabled

- Note 1:** Refer to the “UART” (DS70582) section in the “dsPIC33/PIC24 Family Reference Manual” for information on enabling the UARTx module for receive or transmit operation.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).
- 3:** This feature is only available on 44-pin and 64-pin devices.
- 4:** This feature is only available on 64-pin devices.

REGISTER 21-5: CxFIFO: ECANx FIFO STATUS REGISTER

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FBP5	FBP4	FBP3	FBP2	FBP1	FBP0
bit 15							bit 8

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0
—	—	FNRB5	FNRB4	FNRB3	FNRB2	FNRB1	FNRB0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **FBP<5:0>:** FIFO Buffer Pointer bits

011111 = RB31 buffer

011110 = RB30 buffer

•
•
•

000001 = TRB1 buffer

000000 = TRB0 buffer

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **FNRB<5:0>:** FIFO Next Read Buffer Pointer bits

011111 = RB31 buffer

011110 = RB30 buffer

•
•
•

000001 = TRB1 buffer

000000 = TRB0 buffer

REGISTER 22-3: CTMUICON: CTMU CURRENT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-10 **ITRIM<5:0>**: Current Source Trim bits

011111 = Maximum positive change from nominal current + 62%

011110 = Maximum positive change from nominal current + 60%

•

•

•

000010 = Minimum positive change from nominal current + 4%

000001 = Minimum positive change from nominal current + 2%

000000 = Nominal current output specified by IRNG<1:0>

111111 = Minimum negative change from nominal current – 2%

111110 = Minimum negative change from nominal current – 4%

•

•

•

100010 = Maximum negative change from nominal current – 60%

100001 = Maximum negative change from nominal current – 62%

bit 9-8 **IRNG<1:0>**: Current Source Range Select bits11 = 100 × Base Current⁽²⁾10 = 10 × Base Current⁽²⁾01 = Base Current Level⁽²⁾00 = 1000 × Base Current^(1,2)bit 7-0 **Unimplemented**: Read as '0'**Note 1:** This current range is not available to be used with the internal temperature measurement diode.**Note 2:** Refer to the CTMU Current Source Specifications (Table 30-56) in **Section 30.0 “Electrical Characteristics”** for the current range selection values.

REGISTER 24-4: PTGT0LIM: PTG TIMER0 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGT0LIM<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGT0LIM<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **PTGT0LIM<15:0>**: PTG Timer0 Limit Register bits
 General Purpose Timer0 Limit register (effective only with a PTGT0 Step command).

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 24-5: PTGT1LIM: PTG TIMER1 LIMIT REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGT1LIM<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGT1LIM<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **PTGT1LIM<15:0>**: PTG Timer1 Limit Register bits
 General Purpose Timer1 Limit register (effective only with a PTGT1 Step command).

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

29.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16 and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

29.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

29.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

29.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

TABLE 30-6: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	Typ.	Max.	Units	Conditions		
Operating Current (IDD) ⁽¹⁾						
DC20d	9	15	mA	-40°C	3.3V	10 MIPS
DC20a	9	15	mA	+25°C		
DC20b	9	15	mA	+85°C		
DC20c	9	15	mA	+125°C		
DC22d	16	25	mA	-40°C	3.3V	20 MIPS
DC22a	16	25	mA	+25°C		
DC22b	16	25	mA	+85°C		
DC22c	16	25	mA	+125°C		
DC24d	27	40	mA	-40°C	3.3V	40 MIPS
DC24a	27	40	mA	+25°C		
DC24b	27	40	mA	+85°C		
DC24c	27	40	mA	+125°C		
DC25d	36	55	mA	-40°C	3.3V	60 MIPS
DC25a	36	55	mA	+25°C		
DC25b	36	55	mA	+85°C		
DC25c	36	55	mA	+125°C		
DC26d	41	60	mA	-40°C	3.3V	70 MIPS
DC26a	41	60	mA	+25°C		
DC26b	41	60	mA	+85°C		

Note 1: IDD is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows:

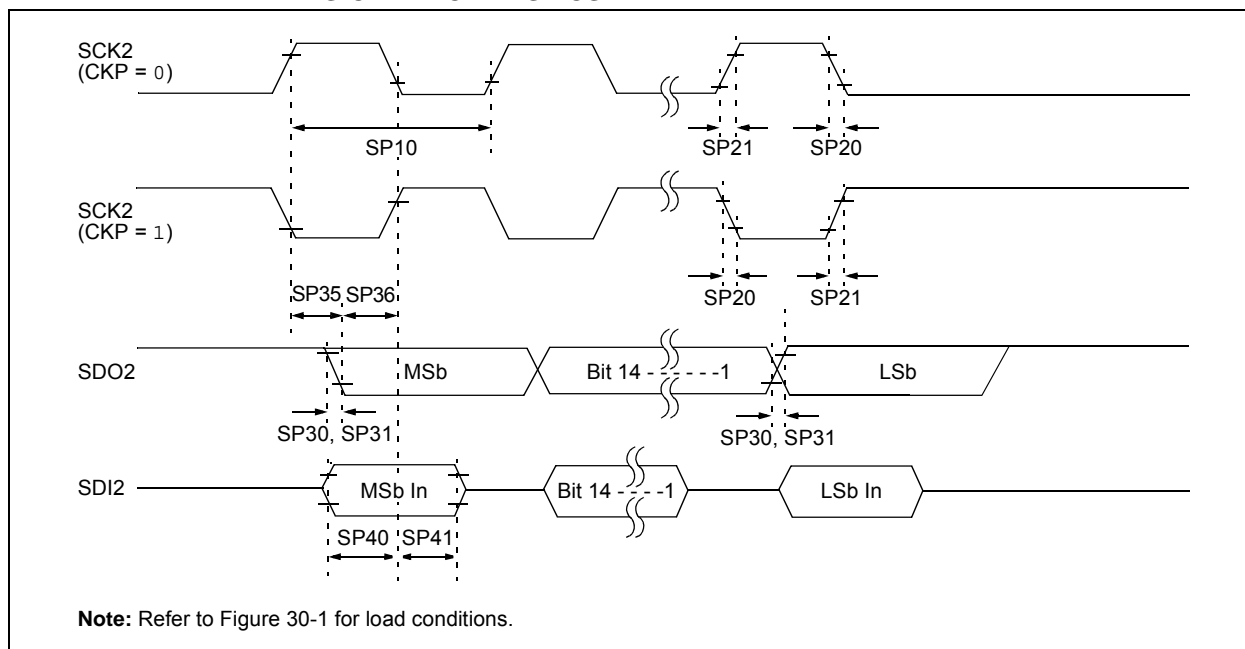
- Oscillator is configured in EC mode with PLL, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)
- CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to VSS
- $\overline{\text{MCLR}} = V_{DD}$, WDT and FSCM are disabled
- CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating; however, every peripheral is being clocked (all PMDx bits are zeroed)
- CPU is executing `while(1){NOP();}` statement
- JTAG is disabled

TABLE 30-11: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
DI60a	I _{ICL}	Input Low Injection Current	0	—	-5 ^(4,7)	mA	All pins except V _{DD} , V _{SS} , AV _{DD} , AV _{SS} , MCLR, VCAP and RB7
DI60b	I _{ICH}	Input High Injection Current	0	—	+5 ^(5,6,7)	mA	All pins except V _{DD} , V _{SS} , AV _{DD} , AV _{SS} , MCLR, VCAP, RB7 and all 5V tolerant pins ⁽⁶⁾
DI60c	ΣI_{ICT}	Total Input Injection Current (sum of all I/O and control pins)	-20 ⁽⁸⁾	—	+20 ⁽⁸⁾	mA	Absolute instantaneous sum of all \pm input injection currents from all I/O pins ($ I_{ICL} + I_{ICH} $) $\leq \Sigma I_{ICT}$

- Note 1:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 2:** Negative current is defined as current sourced by the pin.
- 3:** See the “Pin Diagrams” section for the 5V tolerant I/O pins.
- 4:** V_{IL} source < (V_{SS} – 0.3). Characterized but not tested.
- 5:** Non-5V tolerant pins V_{IH} source > (V_{DD} + 0.3), 5V tolerant pins V_{IH} source > 5.5V. Characterized but not tested.
- 6:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 7:** Non-zero injection currents can affect the ADC results by approximately 4-6 counts.
- 8:** Any number and/or combination of I/O pins not excluded under I_{ICL} or I_{ICH} conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**FIGURE 30-17: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)
TIMING CHARACTERISTICS**



**TABLE 30-36: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)
TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP10	FscP	Maximum SCK2 Frequency	—	—	9	MHz	-40°C to +125°C (Note 3)
SP20	TscF	SCK2 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK2 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO2 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO2 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO2 Data Output Valid after SCK2 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO2 Data Output Setup to First SCK2 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK2 is 111 ns. The clock generated in Master mode must not violate this specification.

4: Assumes 50 pF load on all SPI2 pins.

TABLE 31-8: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$				
Param.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
HDO10	VOL	Output Low Voltage 4x Sink Driver Pins ⁽²⁾	—	—	0.4	V	$I_{OL} \leq 5 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
		Output Low Voltage 8x Sink Driver Pins ⁽³⁾	—	—	0.4	V	$I_{OL} \leq 8 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
HDO20	VOH	Output High Voltage 4x Source Driver Pins ⁽²⁾	2.4	—	—	V	$I_{OH} \geq -10 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
		Output High Voltage 8x Source Driver Pins ⁽³⁾	2.4	—	—	V	$I_{OH} \geq 15 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
HDO20A	VOH1	Output High Voltage 4x Source Driver Pins ⁽²⁾	1.5	—	—	V	$I_{OH} \geq -3.9 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
			2.0	—	—		$I_{OH} \geq -3.7 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
			3.0	—	—		$I_{OH} \geq -2 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
		Output High Voltage 8x Source Driver Pins ⁽³⁾	1.5	—	—	V	$I_{OH} \geq -7.5 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
			2.0	—	—		$I_{OH} \geq -6.8 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)
			3.0	—	—		$I_{OH} \geq -3 \text{ mA}$, $V_{DD} = 3.3\text{V}$ (Note 1)

Note 1: Parameters are characterized, but not tested.

2: Includes all I/O pins that are not 8x Sink Driver pins (see below).

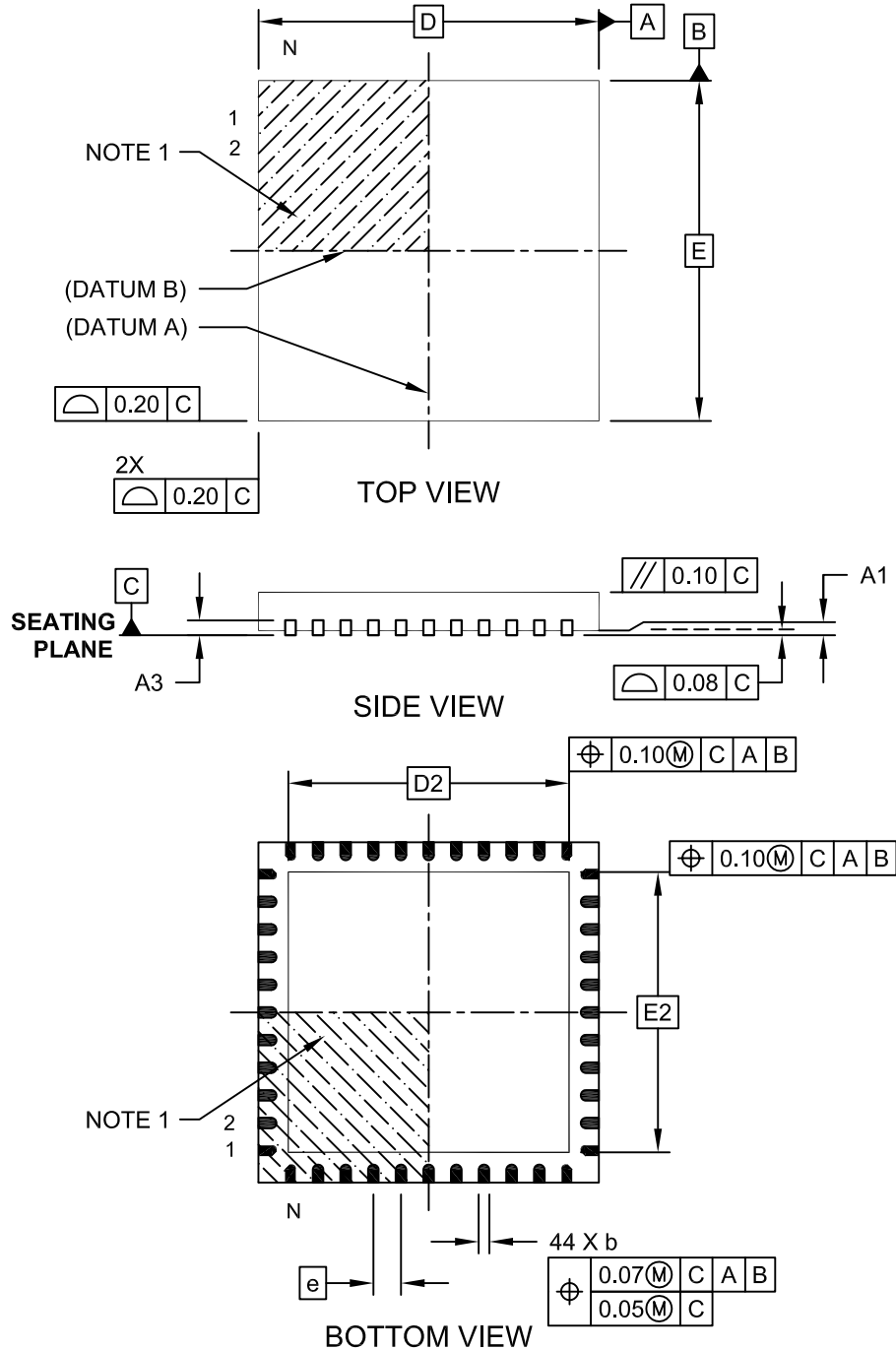
3: Includes the following pins:

For devices with less than 64 pins: RA3, RA4, RA9, RB<15:7> and RC3

For 64-pin devices: RA4, RA9, RB<15:7>, RC3 and RC15

44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN]

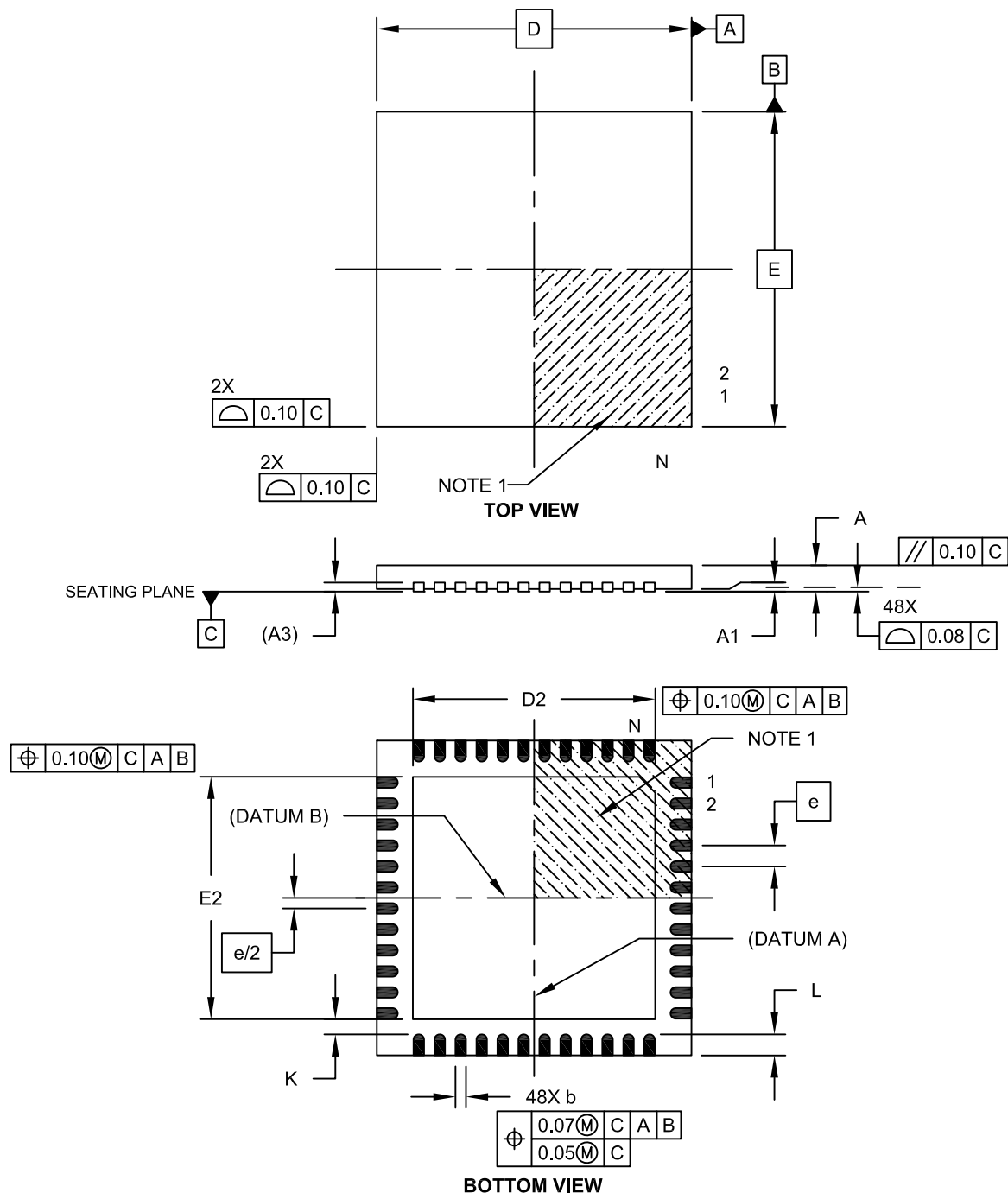
Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-103C Sheet 1 of 2

48-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) – 6x6x0.5 mm Body [UQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-153A Sheet 1 of 2

PMD (PIC24EPXXXMC20X Devices).....	94	CMxMSKCON (Comparator x Mask Gating Control).....	368
PORTA (PIC24EPXXXGP/MC202, dsPIC33EPXXXGP/MC202/502 Devices)	104	CMxMSKSR (Comparator x Mask Source Select Control).....	366
PORTA (PIC24EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices)	103	CORCON (Core Control).....	42, 133
PORTA (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices)	102	CRCCON1 (CRC Control 1).....	375
PORTA (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	99	CRCCON2 (CRC Control 2).....	376
PORTB (PIC24EPXXXGP/MC202, dsPIC33EPXXXGP/MC202/502 Devices)	104	CRCXORH (CRC XOR Polynomial High)	377
PORTB (PIC24EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices)	103	CRCXORL (CRC XOR Polynomial Low).....	377
PORTB (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices)	102	CTMUCON1 (CTMU Control 1).....	317
PORTB (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	99	CTMUCON2 (CTMU Control 2).....	318
PORTC (PIC24EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices)	103	CTMUICON (CTMU Current Control).....	319
PORTC (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices)	102	CVRCON (Comparator Voltage Reference Control).....	371
PORTC (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	99	CxBUFPNT1 (ECANx Filter 0-3 Buffer Pointer 1)	300
PORTD (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	100	CxBUFPNT2 (ECANx Filter 4-7 Buffer Pointer 2)	301
PORTE (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	100	CxBUFPNT3 (ECANx Filter 8-11 Buffer Pointer 3)	301
PORTF (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices)	100	CxBUFPNT4 (ECANx Filter 12-15 Buffer Pointer 4)	302
PORTG (PIC24EPXXXGP/MC206 and dsPIC33EPXXXGP/MC206/506 Devices)	101	CxCFG1 (ECANx Baud Rate Configuration 1).....	298
PTG.....	78	CxCFG2 (ECANx Baud Rate Configuration 2).....	299
PWM (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	79	CxCTRL1 (ECANx Control 1).....	290
PWM Generator 1 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	79	CxCTRL2 (ECANx Control 2).....	291
PWM Generator 2 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	80	CxEC (ECANx Transmit/Receive Error Count)	298
PWM Generator 3 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	80	CxFCTRL (ECANx FIFO Control).....	293
QE11 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	81	CxFEN1 (ECANx Acceptance Filter Enable 1).....	300
Reference Clock	93	CxFIFO (ECANx FIFO Status)	294
SPI1 and SPI2	83	CxFMSKSEL1 (ECANx Filter 7-0 Mask Selection 1).....	304
System Control	93	CxFMSKSEL2 (ECANx Filter 15-8 Mask Selection 2).....	305
Time1 through Time5.....	75	CxINTE (ECANx Interrupt Enable)	297
UART1 and UART2	82	CxINTF (ECANx Interrupt Flag).....	295
Registers		CxRXFnEID (ECANx Acceptance Filter n Extended Identifier)	304
AD1CHS0 (ADC1 Input Channel 0 Select)	333	CxRXFnSID (ECANx Acceptance Filter n Standard Identifier)	303
AD1CHS123 (ADC1 Input Channel 1, 2, 3 Select)	331	CxRXFUL1 (ECANx Receive Buffer Full 1).....	307
AD1CON1 (ADC1 Control 1)	325	CxRXFUL2 (ECANx Receive Buffer Full 2).....	307
AD1CON2 (ADC1 Control 2)	327	CxRXMnEID (ECANx Acceptance Filter Mask n Extended Identifier)	306
AD1CON3 (ADC1 Control 3)	329	CxRXMnSID (ECANx Acceptance Filter Mask n Standard Identifier)	306
AD1CON4 (ADC1 Control 4)	330	CxRXOVF1 (ECANx Receive Buffer Overflow 1).....	308
AD1CSSH (ADC1 Input Scan Select High)	335	CxRXOVF2 (ECANx Receive Buffer Overflow 2).....	308
AD1CSSL (ADC1 Input Scan Select Low).....	336	CxTRMnCON (ECANx TX/RX Buffer mn Control)	309
ALTDTRx (PWMx Alternate Dead-Time)	238	CxVEC (ECANx Interrupt Code).....	292
AUXCONx (PWMx Auxiliary Control).....	247	DEVID (Device ID).....	383
CHOP (PWMx Chop Clock Generator).....	234	DEVREV (Device Revision).....	383
CLKDIV (Clock Divisor).....	158	DMALCA (DMA Last Channel Active Status)	150
CM4CON (Comparator 4 Control)	364	DMAPPS (DMA Ping-Pong Status)	151
CMSTAT (Op Amp/Comparator Status)	360	DMAPOC (DMA Peripheral Write Collision Status).....	148
CMxCON (Comparator x Control, x = 1,2,3).....	362	DMARQC (DMA Request Collision Status).....	149
CMxFLTR (Comparator x Filter Control).....	370	DMAxCNT (DMA Channel x Transfer Count).....	146
		DMAxCON (DMA Channel x Control).....	142
		DMAxPAD (DMA Channel x Peripheral Address).....	146
		DMAxREQ (DMA Channel x IRQ Select).....	143