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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

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Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	53
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 16x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256mc206t-i-mr

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#### EXAMPLE 4-3: PAGED DATA MEMORY SPACE

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

## 5.2 RTSP Operation

RTSP allows the user application to erase a single page of memory and to program two instruction words at a time. See the General Purpose and Motor Control Family tables (Table 1 and Table 2, respectively) for the page sizes of each device.

For more information on erasing and programming Flash memory, refer to "Flash Programming" (DS70609) in the "dsPIC33/PIC24 Family Reference Manual".

## 5.3 **Programming Operations**

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. The processor stalls (waits) until the programming operation is finished.

For erase and program times, refer to Parameters D137a and D137b (Page Erase Time), and D138a and D138b (Word Write Cycle Time) in Table 30-14 in **Section 30.0 "Electrical Characteristics"**.

Setting the WR bit (NVMCON<15>) starts the operation and the WR bit is automatically cleared when the operation is finished.

#### 5.3.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program two adjacent words (24 bits x 2) of program Flash memory at a time on every other word address boundary (0x000002, 0x000006, 0x00000A, etc.). To do this, it is necessary to erase the page that contains the desired address of the location the user wants to change.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPS.

Refer to **Flash Programming**" (DS70609) in the "*dsPIC33/PIC24 Family Reference Manual*" for details and codes examples on programming using RTSP.

### 5.4 Flash Memory Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the
	product page using the link above, enter
	this URL in your browser:
	http://www.microchip.com/wwwproducts/
	Devices.aspx?dDocName=en555464

#### 5.4.1 KEY RESOURCES

- "Flash Programming" (DS70609) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

## 5.5 Control Registers

Four SFRs are used to erase and write the program Flash memory: NVMCON, NVMKEY, NVMADRH and NVMADRL.

The NVMCON register (Register 5-1) enables and initiates Flash memory erase and write operations.

NVMKEY (Register 5-4) is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register.

There are two NVM Address registers: NVMADRH and NVMADRL. These two registers, when concatenated, form the 24-bit Effective Address (EA) of the selected word for programming operations or the selected page for erase operations.

The NVMADRH register is used to hold the upper 8 bits of the EA, while the NVMADRL register is used to hold the lower 16 bits of the EA.

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	_	—	—	—	—
bit 15				·	- -		bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
				SS2R<6:0>			
bit 7	<u>.</u>						bit 0
Logondi							

## REGISTER 11-13: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-7	Unimplemented: Read as '0'
bit 6-0	<b>SS2R&lt;6:0&gt;:</b> Assign SPI2 Slave Select (SS2) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)
	1111001 = Input tied to RPI121
	•
	0000001 = Input tied to CMP1 0000000 = Input tied to Vss

#### REGISTER 11-14: RPINR26: PERIPHERAL PIN SELECT INPUT REGISTER 26 (dsPIC33EPXXXGP/MC50X DEVICES ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—				C1RXR<6:0>	>		
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-7	Unimplemented: Read as '0'
bit 6-0	<b>C1RXR&lt;6:0&gt;:</b> Assign CAN1 RX Input (CRX1) to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)
	1111001 = Input tied to RPI121
	•
	0000001 = Input tied to CMP1 0000000 = Input tied to Vss

#### REGISTER 16-1: PTCON: PWMx TIME BASE CONTROL REGISTER (CONTINUED)

bit 6-4	SYNCSRC<2:0>: Synchronous Source Selection bits <sup>(1)</sup> 111 = Reserved
	•
	• 100 = Reserved 011 = PTGO17 <sup>(2)</sup> 010 = PTGO16 <sup>(2)</sup> 001 = Reserved 000 = SYNCI1 input from PPS
bit 3-0	<pre>SEVTPS&lt;3:0&gt;: PWMx Special Event Trigger Output Postscaler Select bits<sup>(1)</sup> 1111 = 1:16 Postscaler generates Special Event Trigger on every sixteenth compare match event</pre>
	0001 = 1:2 Postscaler generates Special Event Trigger on every second compare match event 0000 = 1:1 Postscaler generates Special Event Trigger on every compare match event

- **Note 1:** These bits should be changed only when PTEN = 0. In addition, when using the SYNCI1 feature, the user application must program the period register with a value that is slightly larger than the expected period of the external synchronization input signal.
  - 2: See Section 24.0 "Peripheral Trigger Generator (PTG) Module" for information on this selection.

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0		
	TRGDI	V<3:0>		—	—	—	—		
bit 15							bit 8		
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
—	—			TRGSTF	RT<5:0>(1)				
bit 7							bit 0		
Legend:									
R = Readable	e bit	W = Writable	bit	U = Unimplen	nented bit, read	as '0'			
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own		
bit 15-12	TRGDIV<3:0	<b>)&gt;:</b> Trigger # Ou	tput Divider b	vits					
	1111 <b>= Trigg</b>	er output for ev	ery 16th trigg	er event					
	1110 = Trigger output for every 15th trigger event								
	1101 <b>= Trigg</b>	er output for ev	ery 14th trigg	er event					
	1100 = Trigg	er output for ev	ery 13th trigg	er event					
	1011 = Irigg	er output for ev	ery 12th trigg	er event					
	1010 = Trigg	per output for ev	ery 11th trigge	er event					
	1001 - Trigg	er output for ev	ery 9th triage	r event					
	0111 = Trigg	er output for ev	erv 8th triage	r event					
	0110 = Trigg	er output for ev	erv 7th triage	r event					
	0101 = Trigg	er output for ev	ery 6th trigge	r event					
	0100 = Trigg	jer output for ev	ery 5th trigge	r event					
	0011 = Trigg	er output for ev	ery 4th trigge	r event					
	0010 <b>= Trigg</b>	er output for ev	ery 3rd trigge	r event					
	0001 = Trigg	er output for ev	ery 2nd trigge	erevent					
	0000 = Trigg	ger output for ev	ery trigger ev	ent					
bit 11-6	Unimplemer	nted: Read as '	0'						
bit 5-0	TRGSTRT<5	5:0>: Trigger Po	stscaler Start	Enable Select	bits <sup>(1)</sup>				
	111111 <b>=</b> W	aits 63 PWM cy	cles before g	enerating the fir	rst trigger event	after the modu	le is enabled		
	•								
	•								
	•								
	000010 = W	aits 2 PWM cyc	les before ge	nerating the firs	t trigger event a	after the module	e is enabled		
	000001 = W	aits 1 PWM cyc	le before gen	erating the first	trigger event a	fter the module	is enabled		
	000000 = W	aits 0 PWM cyc	les before ge	nerating the firs	t trigger event a	after the module	e is enabled		

# REGISTER 16-12: TRGCONx: PWMx TRIGGER CONTROL REGISTER



# REGISTER 16-13: IOCONX: PWMx I/O CONTROL REGISTER<sup>(2)</sup> (CONTINUED)

- bit 1 SWAP: SWAP PWMxH and PWMxL Pins bit
   1 = PWMxH output signal is connected to PWMxL pins; PWMxL output signal is connected to PWMxH pins
   0 = PWMxH and PWMxL pins are mapped to their respective pins
   bit 0 OSYNC: Output Override Synchronization bit
   1 = Output overrides via the OVRDAT<1:0> bits are synchronized to the PWMx period boundary
  - 0 = Output overrides via the OVDDAT<1:0> bits occur on the next CPU clock boundary
- Note 1: These bits should not be changed after the PWMx module is enabled (PTEN = 1).
  - 2: If the PWMLOCK Configuration bit (FOSCSEL<6>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			TRGC	/IP<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			TRGC	MP<7:0>			
bit 7							bit 0
Legend:							
R = Readable I	bit	W = Writable bit U = Unimplemented bit, read as '0'					
-n = Value at POR '1' = Bit is set '0' = Bit is cleared		x = Bit is unkr	nown				

# REGISTER 16-14: TRIGX: PWMx PRIMARY TRIGGER COMPARE VALUE REGISTER

bit 15-0 TRGCMP<15:0>: Trigger Control Value bits

When the primary PWMx functions in local time base, this register contains the compare values that can trigger the ADC module.

#### FIGURE 17-1: QEI BLOCK DIAGRAM



#### REGISTER 17-2: QEI1IOC: QEI1 I/O CONTROL REGISTER (CONTINUED)

- bit 2 INDEX: Status of INDXx Input Pin After Polarity Control
  - 1 = Pin is at logic '1'
  - 0 = Pin is at logic '0'
- bit 1 QEB: Status of QEBx Input Pin After Polarity Control And SWPAB Pin Swapping 1 = Pin is at logic '1' 0 = Pin is at logic '0'
- bit 0 **QEA:** Status of QEAx Input Pin After Polarity Control And SWPAB Pin Swapping 1 = Pin is at logic '1'
  - 0 = Pin is at logic '0'

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

#### REGISTER 17-13: QEI1LECH: QEI1 LESS THAN OR EQUAL COMPARE HIGH WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
QEILEC<31:24>										
bit 15 bit 8										
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
			QEILE	C<23:16>						
bit 7							bit 0			
Legend:										
R = Readable I	bit	W = Writable bi	t	U = Unimplemented bit, read as '0'						
-n = Value at P	OR	'1' = Bit is set		0' = Bit is cleared x = Bit is unknown						

bit 15-0 **QEILEC<31:16>:** High Word Used to Form 32-Bit Less Than or Equal Compare Register (QEI1LEC) bits

# REGISTER 17-14: QEI1LECL: QEI1 LESS THAN OR EQUAL COMPARE LOW WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
	QEILEC<15:8>								
bit 15							bit 8		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
			QEIL	EC<7:0>					
bit 7							bit 0		
Legend:									
R = Readable	bit	W = Writable I	bit	U = Unimplemented bit, read as '0'					
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknow			nown		

bit 15-0 QEILEC<15:0>: Low Word Used to Form 32-Bit Less Than or Equal Compare Register (QEI1LEC) bits

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
FLTEN15	FLTEN14	FLTEN13	FLTEN12	FLTEN11	FLTEN10	FLTEN9	FLTEN8
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
FLTEN7	FLTEN6	FLTEN5	FLTEN4	FLTEN3	FLTEN2	FLTEN1	FLTEN0
bit 7							bit 0
Legend:							

#### REGISTER 21-11: CxFEN1: ECANx ACCEPTANCE FILTER ENABLE REGISTER 1

Legend				
R = Rea	dable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Valu	ue at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0

FLTEN<15:0>: Enable Filter n to Accept Messages bits

1 = Enables Filter n

0 = Disables Filter n

# REGISTER 21-12: CxBUFPNT1: ECANx FILTER 0-3 BUFFER POINTER REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
	F3BF	°<3:0>			F2B	P<3:0>		
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
	F1BP<3:0>				F0B	P<3:0>		
bit 7							bit 0	
Legend:								
R = Readable bit W = Writ			bit	U = Unimplen	nented bit, rea	id as '0'		
-n = Value at POR		'1' = Bit is set	'1' = Bit is set		$0^{\circ}$ = Bit is cleared $x = Bit is unknown$			
bit 15-12	F3BP<3:0>:	RX Buffer Mas	k for Filter 3 b	pits				
	1111 = Filte	r hits received ir	n RX FIFO bu	uffer				
	1110 <b>= Filte</b>	r hits received ir	n RX Buffer 1	4				
	•							
	•							
	0001 = Filte	r hits received ir	n RX Buffer 1					
	0000 = Filte	r hits received ir	n RX Buffer 0					
bit 11-8	F2BP<3:0>:	RX Buffer Mas	k for Filter 2 k	oits (same value	s as bits<15:1	2>)		
bit 7-4	F1BP<3:0>:	RX Buffer Mas	k for Filter 1 k	oits (same value	s as bits<15:1	2>)		
bit 3-0	F0BP<3:0>:	RX Buffer Mas	k for Filter 0 k	oits (same value	s as bits<15:1	2>)		

NOTES:

Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles <sup>(2)</sup>	Status Flags Affected
25	DAW	DAW	Wn	Wn = decimal adjust Wn	1	1	С
26	DEC	DEC	f	f = f - 1	1	1	C,DC,N,OV,Z
		DEC	f,WREG	WREG = f – 1	1	1	C,DC,N,OV,Z
		DEC	Ws,Wd	Wd = Ws - 1	1	1	C,DC,N,OV,Z
27	DEC2	DEC2	f	f = f – 2	1	1	C,DC,N,OV,Z
		DEC2	f,WREG	WREG = f – 2	1	1	C,DC,N,OV,Z
		DEC2	Ws,Wd	Wd = Ws - 2	1	1	C,DC,N,OV,Z
28	DISI	DISI	#lit14	Disable Interrupts for k instruction cycles	1	1	None
29	DIV	DIV.S	Wm,Wn	Signed 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.SD	Wm,Wn	Signed 32/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.U	Wm,Wn	Unsigned 16/16-bit Integer Divide	1	18	N,Z,C,OV
		DIV.UD	Wm,Wn	Unsigned 32/16-bit Integer Divide	1	18	N,Z,C,OV
30	DIVF	DIVF	Wm, Wn <sup>(1)</sup>	Signed 16/16-bit Fractional Divide	1	18	N,Z,C,OV
31	DO	DO	#lit15,Expr <sup>(1)</sup>	Do code to PC + Expr, lit15 + 1 times	2	2	None
		DO	Wn,Expr <sup>(1)</sup>	Do code to PC + Expr, (Wn) + 1 times	2	2	None
32	ED	ED	Wm*Wm,Acc,Wx,Wy,Wxd <sup>(1)</sup>	Euclidean Distance (no accumulate)	1	1	OA,OB,OAB, SA,SB,SAB
33	EDAC	EDAC	Wm*Wm,Acc,Wx,Wy,Wxd <sup>(1)</sup>	Euclidean Distance	1	1	OA,OB,OAB, SA,SB,SAB
34	EXCH	EXCH	Wns,Wnd	Swap Wns with Wnd	1	1	None
35	FBCL	FBCL	Ws,Wnd	Find Bit Change from Left (MSb) Side	1	1	С
36	FF1L	FF1L	Ws,Wnd	Find First One from Left (MSb) Side	1	1	С
37	FF1R	FF1R	Ws,Wnd	Find First One from Right (LSb) Side	1	1	С
38	GOTO	GOTO	Expr	Go to address	2	4	None
		GOTO	Wn	Go to indirect	1	4	None
		GOTO.L	Wn	Go to indirect (long address)	1	4	None
39	INC	INC	f	f = f + 1	1	1	C,DC,N,OV,Z
		INC	f,WREG	WREG = f + 1	1	1	C,DC,N,OV,Z
		INC	Ws,Wd	Wd = Ws + 1	1	1	C,DC,N,OV,Z
40	INC2	INC2	f	f = f + 2	1	1	C,DC,N,OV,Z
		INC2	f,WREG	WREG = f + 2	1	1	C,DC,N,OV,Z
		INC2	Ws,Wd	Wd = Ws + 2	1	1	C,DC,N,OV,Z
41	IOR	IOR	f	f = f .IOR. WREG	1	1	N,Z
		IOR	f,WREG	WREG = f.IOR. WREG	1	1	N,Z
		IOR	#lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N,Z
		IOR	Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N,Z
		IOR	Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N,Z
42	LAC	LAC	Wso,#Slit4,Acc	Load Accumulator	1	1	OA,OB,OAB, SA,SB,SAB
43	LNK	LNK	#lit14	Link Frame Pointer	1	1	SFA
44	LSR	LSR	f	f = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	f,WREG	WREG = Logical Right Shift f	1	1	C,N,OV,Z
		LSR	Ws,Wd	Wd = Logical Right Shift Ws	1	1	C,N,OV,Z
		LSR	Wb,Wns,Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N,Z
		LSR	Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N,Z
45	MAC	MAC	Wm*Wn,Acc,Wx,Wxd,Wy,Wyd,AWB <sup>(1)</sup>	Multiply and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB
		MAC	Wm*Wm,Acc,Wx,Wxd,Wy,Wyd <sup>(1)</sup>	Square and Accumulate	1	1	OA,OB,OAB, SA,SB,SAB

### TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Note 1: These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

2: Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.



АС СНА	AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$				
Param No.	Symb	Characteristic	Min.	Тур. <sup>(1)</sup>	Max.	Units	Conditions	
OS10	FIN	External CLKI Frequency (External clocks allowed only in EC and ECPLL modes)	DC	_	60	MHz	EC	
		Oscillator Crystal Frequency	3.5 10	—	10 25	MHz MHz	XT HS	
OS20	Tosc	10          25           Tosc = 1/Fosc         8.33          DC           Tosc = 1/Fosc         7.14          DC		DC	ns	+125°C		
		Tosc = 1/Fosc	7.14	—	DC	ns	+85°C	
OS25	TCY	Instruction Cycle Time <sup>(2)</sup>	16.67	—	DC	ns	+125°C	
		Instruction Cycle Time <sup>(2)</sup>	14.28	—	DC	ns	+85°C	
OS30	TosL, TosH	External Clock in (OSC1) High or Low Time	0.45 x Tosc	—	0.55 x Tosc	ns	EC	
OS31	TosR, TosF	External Clock in (OSC1) Rise or Fall Time	—	—	20	ns	EC	
OS40	TckR	CLKO Rise Time <sup>(3,4)</sup>	—	5.2	—	ns		
OS41	TckF	CLKO Fall Time <sup>(3,4)</sup>	—	5.2	—	ns		
OS42	Gм	External Oscillator Transconductance <sup>(4)</sup>	—	12	—	mA/V	HS, VDD = 3.3V, TA = +25°C	
			—	6	—	mA/V	XT, VDD = 3.3V, TA = +25°C	

#### TABLE 30-17: EXTERNAL CLOCK TIMING REQUIREMENTS

Note 1: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

- 2: Instruction cycle period (TCY) equals two times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "Minimum" values with an external clock applied to the OSC1 pin. When an external clock input is used, the "Maximum" cycle time limit is "DC" (no clock) for all devices.
- 3: Measurements are taken in EC mode. The CLKO signal is measured on the OSC2 pin.
- 4: This parameter is characterized, but not tested in manufacturing.

## FIGURE 30-7: OUTPUT COMPARE x MODULE (OCx) TIMING CHARACTERISTICS



#### TABLE 30-27: OUTPUT COMPARE x MODULE TIMING REQUIREMENTS

AC CHA	RACTER	ISTICS	<b>Standar</b> (unless Operatir	$\begin{array}{ll} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Min. Typ. Max. Units Conditions					
OC10	TccF	OCx Output Fall Time	—		— ns See Parameter DO32				
OC11	TccR	OCx Output Rise Time	— — ns See Parameter DO31						

Note 1: These parameters are characterized but not tested in manufacturing.

#### FIGURE 30-8: OCx/PWMx MODULE TIMING CHARACTERISTICS



#### TABLE 30-28: OCx/PWMx MODE TIMING REQUIREMENTS

AC CHAF	RACTERIS	<b>FICS</b>	Standard Operating Conditions: 3.0V to 3.6V(unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended						
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min. Typ. Max. Units Conditions						
OC15	TFD	Fault Input to PWMx I/O Change	—	_	Tcy + 20	ns			
OC20	TFLT	Fault Input Pulse Width	Tcy + 20	Tcy + 20 — — ns					

**Note 1:** These parameters are characterized but not tested in manufacturing.





#### FIGURE 30-10: HIGH-SPEED PWMx MODULE TIMING CHARACTERISTICS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)



#### TABLE 30-29: HIGH-SPEED PWMx MODULE TIMING REQUIREMENTS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

AC CHARACTERISTICS				rd Opera otherwis ng tempe	ting Con se stated rature	ditions: 3 ) -40°C ≤ T -40°C ≤ T	<b>3.0V to 3.6V</b> $A \le +85^{\circ}C$ for Industrial $A \le +125^{\circ}C$ for Extended	
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min. Typ. Max. Units Conditions					
MP10	TFPWM	PWMx Output Fall Time	—			ns	See Parameter DO32	
MP11	TRPWM	PWMx Output Rise Time	_	_		ns	See Parameter DO31	
MP20	TFD	Fault Input ↓ to PWMx I/O Change	_	_	15	ns		
MP30	Tfh	Fault Input Pulse Width	15 — — ns					

**Note 1:** These parameters are characterized but not tested in manufacturing.

# TABLE 30-48:SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0)TIMING REQUIREMENTS

АС СНА				$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур. <sup>(2)</sup>	Max.	Units	Conditions	
SP70	FscP	Maximum SCK1 Input Frequency		_	11	MHz	(Note 3)	
SP72	TscF	SCK1 Input Fall Time	_		_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCK1 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO1 Data Output Fall Time			_	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO1 Data Output Rise Time	—	_	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	_	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	_	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	_	_	ns		
SP50	TssL2scH, TssL2scL	$\overline{SS1}$ ↓ to SCK1 ↑ or SCK1 ↓ Input	120	Ι	—	ns		
SP51	TssH2doZ	SS1 ↑ to SDO1 Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH, TscL2ssH	SS1 ↑ after SCK1 Edge	1.5 Tcy + 40	—	_	ns	(Note 4)	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK1 is 91 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI1 pins.

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X



#### FIGURE 30-36: ADC CONVERSION (12-BIT MODE) TIMING CHARACTERISTICS (ASAM = 0, SSRC<2:0> = 000, SSRCG = 0)

## 44-Terminal Very Thin Leadless Array Package (TL) – 6x6x0.9 mm Body With Exposed Pad [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



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# 44-Terminal Very Thin Leadless Array Package (TL) – 6x6x0.9 mm Body With Exposed Pad [VTLA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





DETAIL A

	Units	N	MILLIMETERS			
Dimension	Limits	MIN	NOM	MAX		
Number of Pins	Ν		44			
Number of Pins per Side	ND		12			
Number of Pins per Side	NE		10			
Pitch	е	0.50 BSC				
Overall Height	А	0.80	0.90	1.00		
Standoff	A1	0.025	-	0.075		
Overall Width	Е		6.00 BSC			
Exposed Pad Width	E2	4.40	4.55	4.70		
Overall Length	D		6.00 BSC			
Exposed Pad Length	D2	4.40	4.55	4.70		
Contact Width	b	0.20	0.25	0.30		
Contact Length	L	0.20	0.25	0.30		
Contact-to-Exposed Pad	К	0.20	-	-		

#### Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

- 3. Dimensioning and tolerancing per ASME Y14.5M.
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

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