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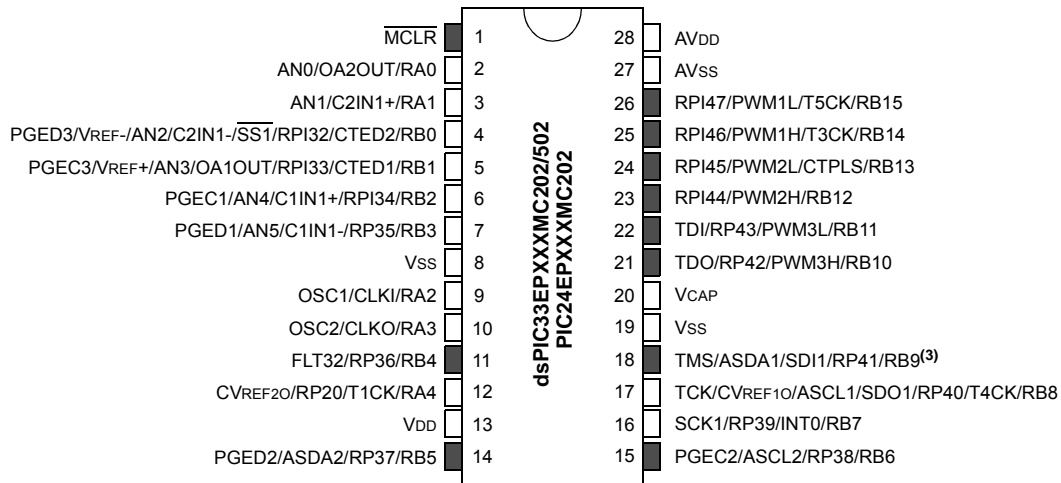
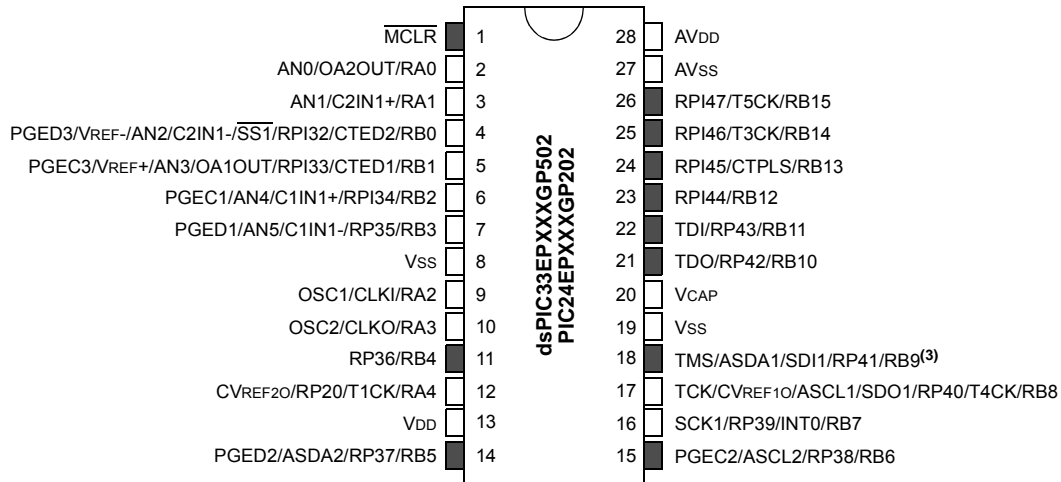
#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (10.7K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32gp502-i-ss">https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32gp502-i-ss</a>

## Pin Diagrams

### 28-Pin SPDIP/SOIC/SSOP<sup>(1,2)</sup>

■ = Pins are up to 5V tolerant



- Note 1:** The RPN/RPIn pins can be used by any remappable peripheral with some limitation. See **Section 11.4 “Peripheral Pin Select (PPS)”** for available peripherals and for information on limitations.
- Note 2:** Every I/O port pin (RAX-RGx) can be used as a Change Notification pin (CNAX-CNGx). See **Section 11.0 “I/O Ports”** for more information.
- Note 3:** There is an internal pull-up resistor connected to the TMS pin when the JTAG interface is active. See the JTAGEN bit field in Table 27-2.

## 4.4 Special Function Register Maps

**TABLE 4-1: CPU CORE REGISTER MAP FOR dsPIC33EPXXMC20X/50X AND dsPIC33EPXXGP50X DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
W0	0000	W0 (WREG)																xxxx	
W1	0002	W1																xxxx	
W2	0004	W2																xxxx	
W3	0006	W3																xxxx	
W4	0008	W4																xxxx	
W5	000A	W5																xxxx	
W6	000C	W6																xxxx	
W7	000E	W7																xxxx	
W8	0010	W8																xxxx	
W9	0012	W9																xxxx	
W10	0014	W10																xxxx	
W11	0016	W11																xxxx	
W12	0018	W12																xxxx	
W13	001A	W13																xxxx	
W14	001C	W14																xxxx	
W15	001E	W15																xxxx	
SPLIM	0020	SPLIM																0000	
ACCAL	0022	ACCAL																0000	
ACCAH	0024	ACCAH																0000	
ACCAU	0026	Sign Extension of ACCA<39>									ACCAU							0000	
ACCBH	0028	ACCBH																0000	
ACCBH	002A	ACCBH																0000	
ACCBU	002C	Sign Extension of ACCB<39>									ACCBU							0000	
PCL	002E	PCL<15:0>																—	0000
PCH	0030	—	—	—	—	—	—	—	—	—	PCH<6:0>							0000	
DSRPAG	0032	—	—	—	—	—	—	DSRPAG<9:0>										0001	
DSWPAG	0034	—	—	—	—	—	—	—	DSWPAG<8:0>										0001
RCOUNT	0036	RCOUNT<15:0>																0000	
DCOUNT	0038	DCOUNT<15:0>																0000	
DOSTARTL	003A	DOSTARTL<15:1>																—	0000
DOSTARTH	003C	—	—	—	—	—	—	—	—	—	—	DOSTARTH<5:0>					0000		
DOENDL	003E	DOENDL<15:1>																—	0000
DOENDH	0040	—	—	—	—	—	—	—	—	—	—	DOENDH<5:0>					0000		

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-49: PORTD REGISTER MAP FOR PIC24EPXXXGP/MC206 AND dsPIC33EPXXXGP/MC206/506 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISD	0E30	—	—	—	—	—	—	—	TRISD8	—	TRISD6	TRISD5	—	—	—	—	—	0160
PORTD	0E32	—	—	—	—	—	—	—	RD8	—	RD6	RD5	—	—	—	—	—	xxxx
LATD	0E34	—	—	—	—	—	—	—	LATD8	—	LATD6	LATD5	—	—	—	—	—	xxxx
ODCD	0E36	—	—	—	—	—	—	—	ODCD8	—	ODCD6	ODCD5	—	—	—	—	—	0000
CNEND	0E38	—	—	—	—	—	—	—	CNIED8	—	CNIED6	CNIED5	—	—	—	—	—	0000
CNPUD	0E3A	—	—	—	—	—	—	—	CNPUD8	—	CNPUD6	CNPUD5	—	—	—	—	—	0000
CNPDD	0E3C	—	—	—	—	—	—	—	CNPDD8	—	CNPDD6	CNPDD5	—	—	—	—	—	0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-50: PORTE REGISTER MAP FOR PIC24EPXXXGP/MC206 AND dsPIC33EPXXXGP/MC206/506 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISE	0E40	TRISE15	TRISE14	TRISE13	TRISE12	—	—	—	—	—	—	—	—	—	—	—	—	F000
PORTE	0E42	RE15	RE14	RE13	RE12	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
LATE	0E44	LATE15	LATE14	LATE13	LATE12	—	—	—	—	—	—	—	—	—	—	—	—	xxxx
ODCE	0E46	ODCE15	ODCE14	ODCE13	ODCE12	—	—	—	—	—	—	—	—	—	—	—	—	0000
CNENE	0E48	CNIEE15	CNIEE14	CNIEE13	CNIEE12	—	—	—	—	—	—	—	—	—	—	—	—	0000
CNPUE	0E4A	CNPUE15	CNPUE14	CNPUE13	CNPUE12	—	—	—	—	—	—	—	—	—	—	—	—	0000
CNPDE	0E4C	CNPDE15	CNPDE14	CNPDE13	CNPDE12	—	—	—	—	—	—	—	—	—	—	—	—	0000
ANSELE	0E4E	ANSE15	ANSE14	ANSE13	ANSE12	—	—	—	—	—	—	—	—	—	—	—	—	F000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-51: PORTF REGISTER MAP FOR PIC24EPXXXGP/MC206 AND dsPIC33EPXXXGP/MC206/506 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISF	0E50	—	—	—	—	—	—	—	—	—	—	—	—	—	—	TRISF1	TRISF0	0003
PORTF	0E52	—	—	—	—	—	—	—	—	—	—	—	—	—	—	RF1	RF0	xxxx
LATF	0E54	—	—	—	—	—	—	—	—	—	—	—	—	—	—	LATF1	LATF0	xxxx
ODCF	0E56	—	—	—	—	—	—	—	—	—	—	—	—	—	—	ODCF1	ODCF0	0000
CNENF	0E58	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CNIEF1	CNIEF0	0000
CNPUF	0E5A	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CNPUF1	CNPUF0	0000
CNPDF	0E5C	—	—	—	—	—	—	—	—	—	—	—	—	—	—	CNPDF1	CNPDF0	0000

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Allocating different Page registers for read and write access allows the architecture to support data movement between different pages in data memory. This is accomplished by setting the DSRPAG register value to the page from which you want to read, and configuring the DSWPAG register to the page to which it needs to be written. Data can also be moved from different PSV to EDS pages, by configuring the DSRPAG and DSWPAG registers to address PSV and EDS space, respectively. The data can be moved between pages by a single instruction.

When an EDS or PSV page overflow or underflow occurs, EA<15> is cleared as a result of the register indirect EA calculation. An overflow or underflow of the EA in the EDS or PSV pages can occur at the page boundaries when:

- The initial address prior to modification addresses an EDS or PSV page
- The EA calculation uses Pre-Modified or Post-Modified Register Indirect Addressing; however, this does not include Register Offset Addressing

In general, when an overflow is detected, the DSxPAG register is incremented and the EA<15> bit is set to keep the base address within the EDS or PSV window. When an underflow is detected, the DSxPAG register is decremented and the EA<15> bit is set to keep the base address within the EDS or PSV window. This creates a linear EDS and PSV address space, but only when using Register Indirect Addressing modes.

Exceptions to the operation described above arise when entering and exiting the boundaries of Page 0, EDS and PSV spaces. Table 4-61 lists the effects of overflow and underflow scenarios at different boundaries.

In the following cases, when overflow or underflow occurs, the EA<15> bit is set and the DSxPAG is not modified; therefore, the EA will wrap to the beginning of the current page:

- Register Indirect with Register Offset Addressing
- Modulo Addressing
- Bit-Reversed Addressing

**TABLE 4-61: OVERFLOW AND UNDERFLOW SCENARIOS AT PAGE 0, EDS and PSV SPACE BOUNDARIES<sup>(2,3,4)</sup>**

O/U, R/W	Operation	Before			After		
		DSxPAG	DS EA<15>	Page Description	DSxPAG	DS EA<15>	Page Description
O, Read	[ ++Wn ] or [ Wn++ ]	DSRPAG = 0x1FF	1	EDS: Last page	DSRPAG = 0x1FF	0	See <b>Note 1</b>
O, Read		DSRPAG = 0x2FF	1	PSV: Last lsw page	DSRPAG = 0x300	1	PSV: First MSB page
O, Read		DSRPAG = 0x3FF	1	PSV: Last MSB page	DSRPAG = 0x3FF	0	See <b>Note 1</b>
O, Write		DSWPAG = 0x1FF	1	EDS: Last page	DSWPAG = 0x1FF	0	See <b>Note 1</b>
U, Read	[ --Wn ] or [ Wn-- ]	DSRPAG = 0x001	1	PSV page	DSRPAG = 0x001	0	See <b>Note 1</b>
U, Read		DSRPAG = 0x200	1	PSV: First lsw page	DSRPAG = 0x200	0	See <b>Note 1</b>
U, Read		DSRPAG = 0x300	1	PSV: First MSB page	DSRPAG = 0x2FF	1	PSV: Last lsw page

**Legend:** O = Overflow, U = Underflow, R = Read, W = Write

**Note 1:** The Register Indirect Addressing now addresses a location in the base Data Space (0x0000-0x8000).

**2:** An EDS access with DSxPAG = 0x000 will generate an address error trap.

**3:** Only reads from PS are supported using DSRPAG. An attempt to write to PS using DSWPAG will generate an address error trap.

**4:** Pseudo-Linear Addressing is not supported for large offsets.

## 4.6 Modulo Addressing (dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X Devices Only)

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either Data or Program Space (since the Data Pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into Program Space) and Y Data Spaces. Modulo Addressing can operate on any W Register Pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing since these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction, as there are certain restrictions on the buffer start address (for incrementing buffers) or end address (for decrementing buffers), based upon the direction of the buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

### 4.6.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified, and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT and YMODEND (see Table 4-1).

**Note:** Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear).

The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

### 4.6.2 W ADDRESS REGISTER SELECTION

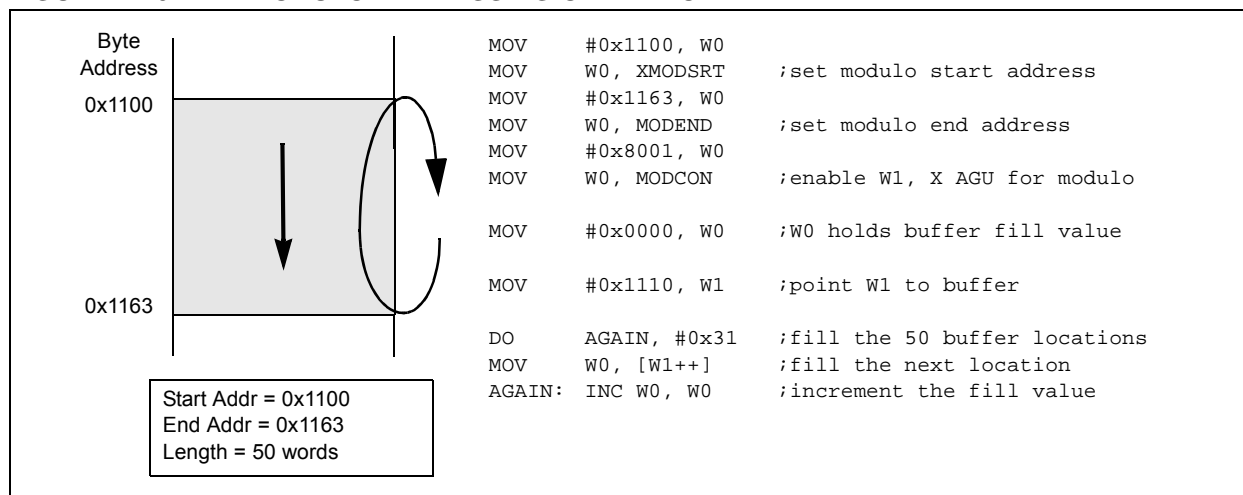
The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that operate with Modulo Addressing:

- If XWM = 1111, X RAGU and X WAGU Modulo Addressing is disabled
- If YWM = 1111, Y AGU Modulo Addressing is disabled

The X Address Space Pointer W register (XWM), to which Modulo Addressing is to be applied, is stored in MODCON<3:0> (see Table 4-1). Modulo Addressing is enabled for X Data Space when XWM is set to any value other than '1111' and the XMODEN bit is set (MODCON<15>).

The Y Address Space Pointer W register (YWM), to which Modulo Addressing is to be applied, is stored in MODCON<7:4>. Modulo Addressing is enabled for Y Data Space when YWM is set to any value other than '1111' and the YMODEN bit is set at MODCON<14>.

**FIGURE 4-20: MODULO ADDRESSING OPERATION EXAMPLE**



**FIGURE 7-1: dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X INTERRUPT VECTOR TABLE**

<div style="display: flex; align-items: center;"> <div style="writing-mode: vertical-rl; transform: rotate(180deg);">Decreasing Natural Order Priority</div> <div style="margin: 0 10px;"> <div style="height: 100px; border-left: 1px solid black; border-right: 1px solid black; position: relative;"> <div style="position: absolute; top: 0; left: -5px;">↑</div> <div style="position: absolute; bottom: 0; left: -5px;">↓</div> </div> <div style="writing-mode: vertical-rl; transform: rotate(180deg);">IVT</div> </div> </div>	Reset – GOTO Instruction	0x000000	<div style="display: flex; align-items: center;"> <div style="writing-mode: vertical-rl; transform: rotate(180deg);">See Table 7-1 for Interrupt Vector Details</div> <div style="margin: 0 10px;"> <div style="height: 100px; border-left: 1px solid black; border-right: 1px solid black; position: relative;"> <div style="position: absolute; top: 0; left: -5px;">↑</div> <div style="position: absolute; bottom: 0; left: -5px;">↓</div> </div> </div> </div>
	Reset – GOTO Address	0x000002	
	Oscillator Fail Trap Vector	0x000004	
	Address Error Trap Vector	0x000006	
	Generic Hard Trap Vector	0x000008	
	Stack Error Trap Vector	0x00000A	
	Math Error Trap Vector	0x00000C	
	DMAC Error Trap Vector	0x00000E	
	Generic Soft Trap Vector	0x000010	
	Reserved	0x000012	
	Interrupt Vector 0	0x000014	
	Interrupt Vector 1	0x000016	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 52	0x00007C	
	Interrupt Vector 53	0x00007E	
	Interrupt Vector 54	0x000080	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 116	0x0000FC	
	Interrupt Vector 117	0x0000FE	
	Interrupt Vector 118	0x000100	
	Interrupt Vector 119	0x000102	
	Interrupt Vector 120	0x000104	
	:	:	
	:	:	
	:	:	
	Interrupt Vector 244	0x0001FC	
	Interrupt Vector 245	0x0001FE	
	START OF CODE	0x000200	

**REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1 (CONTINUED)**

bit 3	<b>SPI1MD:</b> SPI1 Module Disable bit 1 = SPI1 module is disabled 0 = SPI1 module is enabled
bit 2	<b>Unimplemented:</b> Read as '0'
bit 1	<b>C1MD:</b> ECAN1 Module Disable bit <sup>(2)</sup> 1 = ECAN1 module is disabled 0 = ECAN1 module is enabled
bit 0	<b>AD1MD:</b> ADC1 Module Disable bit 1 = ADC1 module is disabled 0 = ADC1 module is enabled

**Note 1:** This bit is available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

**2:** This bit is available on dsPIC33EPXXXGP50X and dsPIC33EPXXXMC50X devices only.



## **15.1 Output Compare Resources**

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en555464>

### **15.1.1 KEY RESOURCES**

- **“Output Compare”** (DS70358) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools

## 15.2 Output Compare Control Registers

**REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1**

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	ENFLTB
bit 15				bit 8			

R/W-0	U-0	R/W-0, HSC	R/W-0, HSC	R/W-0	R/W-0	R/W-0	R/W-0
ENFLTA	—	OCFLTB	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0
bit 7				bit 0			

<b>Legend:</b>	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **OCSIDL:** Output Compare x Stop in Idle Mode Control bit  
 1 = Output Compare x Halts in CPU Idle mode  
 0 = Output Compare x continues to operate in CPU Idle mode

bit 12-10 **OCTSEL<2:0>:** Output Compare x Clock Select bits  
 111 = Peripheral clock (FP)  
 110 = Reserved  
 101 = PTGOx clock<sup>(2)</sup>  
 100 = T1CLK is the clock source of the OCx (only the synchronous clock is supported)  
 011 = T5CLK is the clock source of the OCx  
 010 = T4CLK is the clock source of the OCx  
 001 = T3CLK is the clock source of the OCx  
 000 = T2CLK is the clock source of the OCx

bit 9 **Unimplemented:** Read as '0'

bit 8 **ENFLTB:** Fault B Input Enable bit  
 1 = Output Compare Fault B input (OCFB) is enabled  
 0 = Output Compare Fault B input (OCFB) is disabled

bit 7 **ENFLTA:** Fault A Input Enable bit  
 1 = Output Compare Fault A input (OCFA) is enabled  
 0 = Output Compare Fault A input (OCFA) is disabled

bit 6 **Unimplemented:** Read as '0'

bit 5 **OCFLTB:** PWM Fault B Condition Status bit  
 1 = PWM Fault B condition on OCFB pin has occurred  
 0 = No PWM Fault B condition on OCFB pin has occurred

bit 4 **OCFLTA:** PWM Fault A Condition Status bit  
 1 = PWM Fault A condition on OCFA pin has occurred  
 0 = No PWM Fault A condition on OCFA pin has occurred

**Note 1:** OCxR and OCxRS are double-buffered in PWM mode only.

**2:** Each Output Compare x module (OCx) has one PTG clock source. See **Section 24.0 "Peripheral Trigger Generator (PTG) Module"** for more information.

PTGO4 = OC1

PTGO5 = OC2

PTGO6 = OC3

PTGO7 = OC4

**REGISTER 17-3: QE1STAT: QE1 STATUS REGISTER**

U-0	U-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0
—	—	PCHEQIRQ	PCHEQIEN	PCLEQIRQ	PCLEQIEN	POSOVIRQ	POSOVIEN
bit 15							bit 8

HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0
PCIIRQ <sup>(1)</sup>	PCIEN	VELOVIRQ	VELOVIEN	HOMIRQ	HOMIEN	IDXIRQ	IDXIEN
bit 7							bit 0

<b>Legend:</b>	HS = Hardware Settable bit	C = Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **PCHEQIRQ:** Position Counter Greater Than or Equal Compare Status bit  
 1 = POS1CNT ≥ QE1GEC  
 0 = POS1CNT < QE1GEC
- bit 12 **PCHEQIEN:** Position Counter Greater Than or Equal Compare Interrupt Enable bit  
 1 = Interrupt is enabled  
 0 = Interrupt is disabled
- bit 11 **PCLEQIRQ:** Position Counter Less Than or Equal Compare Status bit  
 1 = POS1CNT ≤ QE1LEC  
 0 = POS1CNT > QE1LEC
- bit 10 **PCLEQIEN:** Position Counter Less Than or Equal Compare Interrupt Enable bit  
 1 = Interrupt is enabled  
 0 = Interrupt is disabled
- bit 9 **POSOVIRQ:** Position Counter Overflow Status bit  
 1 = Overflow has occurred  
 0 = No overflow has occurred
- bit 8 **POSOVIEN:** Position Counter Overflow Interrupt Enable bit  
 1 = Interrupt is enabled  
 0 = Interrupt is disabled
- bit 7 **PCIIRQ:** Position Counter (Homing) Initialization Process Complete Status bit<sup>(1)</sup>  
 1 = POS1CNT was reinitialized  
 0 = POS1CNT was not reinitialized
- bit 6 **PCIEN:** Position Counter (Homing) Initialization Process Complete interrupt Enable bit  
 1 = Interrupt is enabled  
 0 = Interrupt is disabled
- bit 5 **VELOVIRQ:** Velocity Counter Overflow Status bit  
 1 = Overflow has occurred  
 0 = No overflow has not occurred
- bit 4 **VELOVIEN:** Velocity Counter Overflow Interrupt Enable bit  
 1 = Interrupt is enabled  
 0 = Interrupt is disabled
- bit 3 **HOMIRQ:** Status Flag for Home Event Status bit  
 1 = Home event has occurred  
 0 = No Home event has occurred

**Note 1:** This status bit is only applicable to PIMOD<2:0> modes, '011' and '100'.

## 19.1 I<sup>2</sup>C Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

<p><b>Note:</b> In the event you are not able to access the product page using the link above, enter this URL in your browser: <a href="http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en555464">http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en555464</a></p>
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### 19.1.1 KEY RESOURCES

- **“Inter-Integrated Circuit (I<sup>2</sup>C)”** (DS70330) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools

**REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)**

- bit 3      **S:** Start bit  
1 = Indicates that a Start (or Repeated Start) bit has been detected last  
0 = Start bit was not detected last  
Hardware is set or clear when a Start, Repeated Start or Stop is detected.
- bit 2      **R\_W:** Read/Write Information bit (when operating as I<sup>2</sup>C slave)  
1 = Read – Indicates data transfer is output from the slave  
0 = Write – Indicates data transfer is input to the slave  
Hardware is set or clear after reception of an I<sup>2</sup>C device address byte.
- bit 1      **RBF:** Receive Buffer Full Status bit  
1 = Receive is complete, I2CxRCV is full  
0 = Receive is not complete, I2CxRCV is empty  
Hardware is set when I2CxRCV is written with a received byte. Hardware is clear when software reads I2CxRCV.
- bit 0      **TBF:** Transmit Buffer Full Status bit  
1 = Transmit in progress, I2CxTRN is full  
0 = Transmit is complete, I2CxTRN is empty  
Hardware is set when software writes to I2CxTRN. Hardware is clear at completion of a data transmission.

**REGISTER 24-8: PTGC1LIM: PTG COUNTER 1 LIMIT REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGC1LIM<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGC1LIM<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **PTGC1LIM<15:0>**: PTG Counter 1 Limit Register bits

May be used to specify the loop count for the PTGJMPC1 Step command or as a limit register for the General Purpose Counter 1.

**Note 1:** This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).**REGISTER 24-9: PTGHOLD: PTG HOLD REGISTER<sup>(1)</sup>**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGHOLD<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGHOLD<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

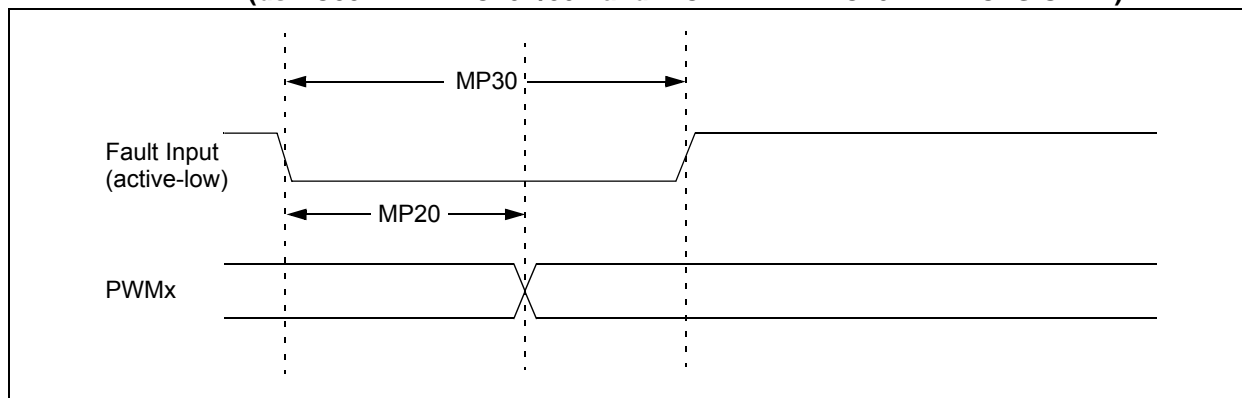
x = Bit is unknown

bit 15-0 **PTGHOLD<15:0>**: PTG General Purpose Hold Register bits

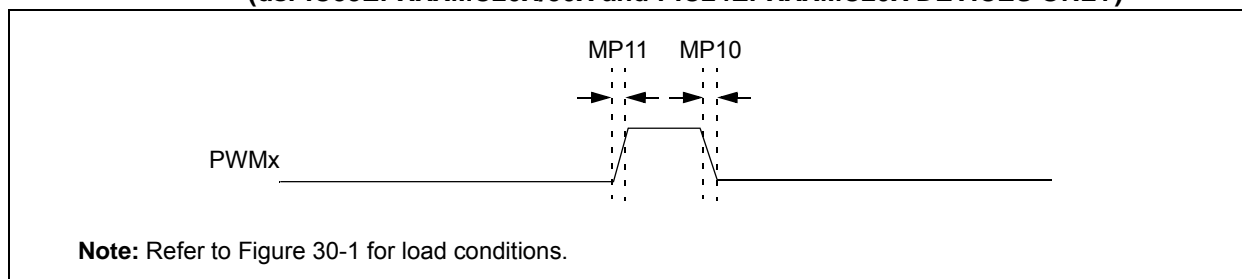
Holds user-supplied data to be copied to the PTGTxLIM, PTGCxLIM, PTGSDLIM or PTGL0 registers with the PTGCOPY command.

**Note 1:** This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

**FIGURE 30-9: HIGH-SPEED PWMx MODULE FAULT TIMING CHARACTERISTICS**  
(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)



**FIGURE 30-10: HIGH-SPEED PWMx MODULE TIMING CHARACTERISTICS**  
(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

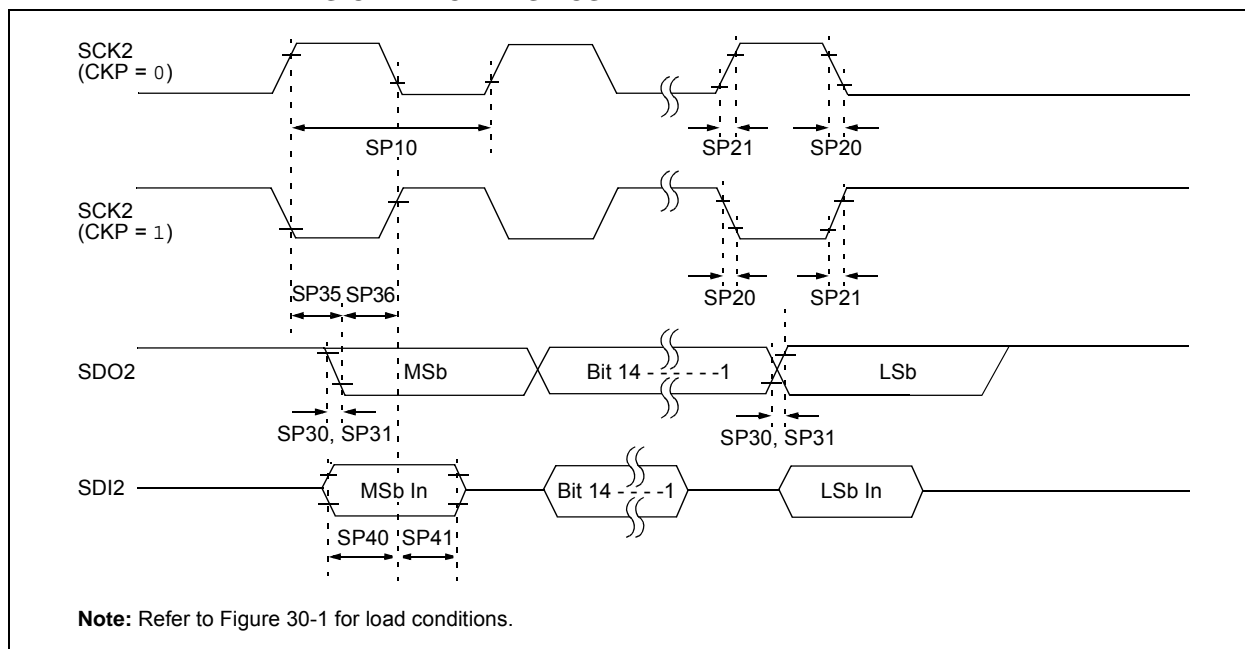


**TABLE 30-29: HIGH-SPEED PWMx MODULE TIMING REQUIREMENTS**  
(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ.	Max.	Units	Conditions
MP10	TFPWM	PWMx Output Fall Time	—	—	—	ns	See Parameter DO32
MP11	TRPWM	PWMx Output Rise Time	—	—	—	ns	See Parameter DO31
MP20	T <sub>FD</sub>	Fault Input ↓ to PWMx I/O Change	—	—	15	ns	
MP30	T <sub>FH</sub>	Fault Input Pulse Width	15	—	—	ns	

**Note 1:** These parameters are characterized but not tested in manufacturing.

**FIGURE 30-17: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)  
TIMING CHARACTERISTICS**



**TABLE 30-36: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)  
TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP10	FscP	Maximum SCK2 Frequency	—	—	9	MHz	-40°C to +125°C (Note 3)
SP20	TscF	SCK2 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK2 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO2 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO2 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO2 Data Output Valid after SCK2 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO2 Data Output Setup to First SCK2 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

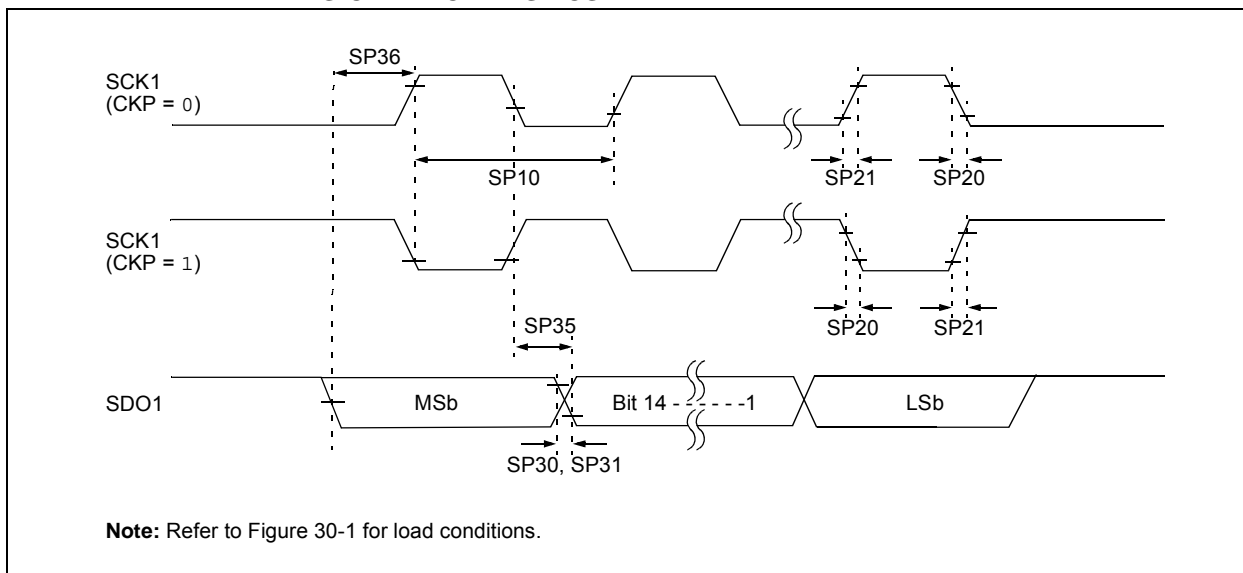
**2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK2 is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPI2 pins.



**FIGURE 30-23: SPI1 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 1) TIMING CHARACTERISTICS**



**TABLE 30-42: SPI1 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP10	FscP	Maximum SCK1 Frequency	—	—	15	MHz	(Note 3)
SP20	TscF	SCK1 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK1 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdiV2scH, TdiV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**Note 2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**Note 3:** The minimum clock period for SCK1 is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

**Note 4:** Assumes 50 pF load on all SPI1 pins.

**FIGURE 30-28: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)**  
**TIMING CHARACTERISTICS**

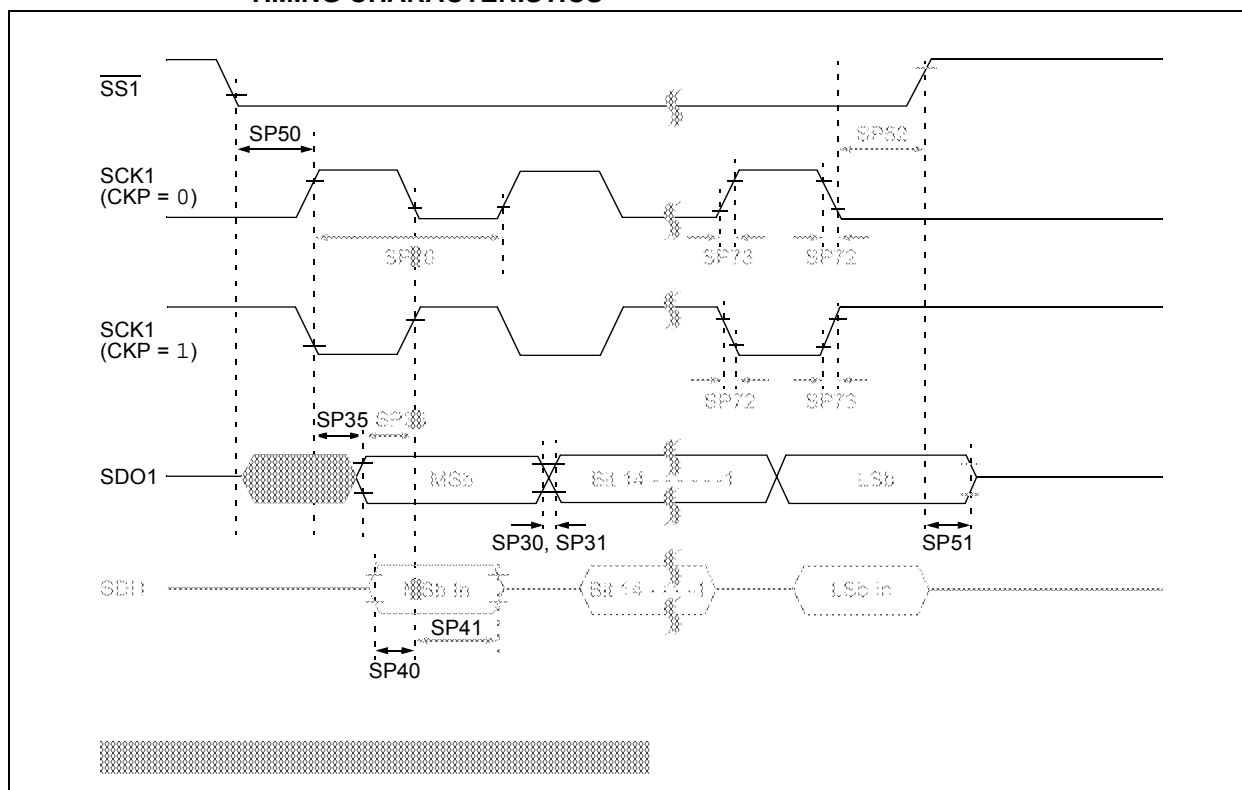


TABLE 31-11: INTERNAL RC ACCURACY

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$					
Param No.	Characteristic	Min	Typ	Max	Units	Conditions	
HF21	LPRC @ 32.768 kHz <sup>(1,2)</sup>						
	LPRC	-30	—	+30	%	$-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$	VDD = 3.0-3.6V

**Note 1:** Change of LPRC frequency as VDD changes.

**Note 2:** LPRC accuracy impacts the Watchdog Timer Time-out Period (TWDT). See **Section 27.5 “Watchdog Timer (WDT)”** for more information.

**Revision F (November 2012)**

Removed “Preliminary” from data sheet footer.

**Revision G (March 2013)**

This revision includes the following global changes:

- changes “ $\overline{\text{FLT}}\text{x}$ ” pin function to “FLT $\text{x}$ ” on all occurrences
- adds **Section 31.0 “High-Temperature Electrical Characteristics”** for high-temperature (+150°C) data

This revision also includes minor typographical and formatting changes throughout the text.

Other major changes are referenced by their respective section in Table A-5.

**TABLE A-5: MAJOR SECTION UPDATES**

Section Name	Update Description
<b>Cover Section</b>	<ul style="list-style-type: none"> <li>• Changes internal oscillator specification to 1.0%</li> <li>• Changes I/O sink/source values to 12 mA or 6 mA</li> <li>• Corrects 44-pin VTLA pin diagram (pin 32 now shows as 5V tolerant)</li> </ul>
<b>Section 4.0 “Memory Organization”</b>	<ul style="list-style-type: none"> <li>• Deletes references to Configuration Shadow registers</li> <li>• Corrects the spelling of the JTAGIP and PTGWDTIP bits throughout</li> <li>• Corrects the Reset value of all IOCON registers as C000h</li> <li>• Adds footnote to Table 4-42 to indicate the absence of Comparator 3 in 28-pin devices</li> </ul>
<b>Section 6.0 “Resets”</b>	<ul style="list-style-type: none"> <li>• Removes references to cold and warm Resets, and clarifies the initial configuration of the device clock source on all Resets</li> </ul>
<b>Section 7.0 “Interrupt Controller”</b>	<ul style="list-style-type: none"> <li>• Corrects the definition of GIE as “Global Interrupt Enable” (not “General”)</li> </ul>
<b>Section 9.0 “Oscillator Configuration”</b>	<ul style="list-style-type: none"> <li>• Clarifies the behavior of the CF bit when cleared in software</li> <li>• Removes POR behavior footnotes from all control registers</li> <li>• Corrects the tuning range of the TUN&lt;5:0&gt; bits in Register 9-4 to an overall range <math>\pm 1.5\%</math></li> </ul>
<b>Section 13.0 “Timer2/3 and Timer4/5”</b>	<ul style="list-style-type: none"> <li>• Clarifies the presence of the ADC Trigger in 16-bit Timer3 and Timer5, as well as the 32-bit timers</li> </ul>
<b>Section 15.0 “Output Compare”</b>	<ul style="list-style-type: none"> <li>• Corrects the first trigger source for SYNCSEL&lt;4:0&gt; (OCxCON2&lt;4:0&gt;) as OCxRS match</li> </ul>
<b>Section 16.0 “High-Speed PWM Module”</b>	<ul style="list-style-type: none"> <li>• Clarifies the source of the PWM interrupts in Figure 16-1</li> <li>• Corrects the Reset states of IOCONx&lt;15:14&gt; in Register 16-13 as ‘11’</li> </ul>
<b>Section 17.0 “Quadrature Encoder Interface (QEI) Module”</b>	<ul style="list-style-type: none"> <li>• Clarifies the operation of the IMV&lt;1:0&gt; bits (QEICON&lt;9:8&gt;) with updated text and additional notes</li> <li>• Corrects the first prescaler value for QFVDIV&lt;2:0&gt; (QE1IOC&lt;13:11&gt;), now 1:128</li> </ul>
<b>Section 23.0 “10-Bit/12-Bit Analog-to-Digital Converter (ADC)”</b>	<ul style="list-style-type: none"> <li>• Adds note to Figure 23-1 that Op Amp 3 is not available in 28-pin devices</li> <li>• Changes “sample clock” to “sample trigger” in AD1CON1 (Register 23-1)</li> <li>• Clarifies footnotes on op amp usage in Registers 23-5 and 23-6</li> </ul>
<b>Section 25.0 “Op Amp/Comparator Module”</b>	<ul style="list-style-type: none"> <li>• Adds Note text to indicate that Comparator 3 is unavailable in 28-pin devices</li> <li>• Splits Figure 25-1 into two figures for clearer presentation (Figure 25-1 for Op amp/Comparators 1 through 3, Figure 25-2 for Comparator 4). Subsequent figures are renumbered accordingly.</li> <li>• Corrects reference description in xxxxx (now (AVDD+AVSS)/2)</li> <li>• Changes CMSTAT&lt;15&gt; in Register 25-1 to “PSIDL”</li> </ul>
<b>Section 27.0 “Special Features”</b>	<ul style="list-style-type: none"> <li>• Corrects the addresses of all Configuration bytes for 512 Kbyte devices</li> </ul>

TABLE A-5: MAJOR SECTION UPDATES (CONTINUED)

Section Name	Update Description
<b>Section 30.0 “Electrical Characteristics”</b>	<ul style="list-style-type: none"> <li>• Throughout: qualifies all footnotes relating to the operation of analog modules below VDDMIN (replaces “will have” with “may have”)</li> <li>• Throughout: changes all references of SPI timing parameter symbol “TscP” to “FscP”</li> <li>• Table 30-1: changes VDD range to 3.0V to 3.6V</li> <li>• Table 30-4: removes Parameter DC12 (RAM Retention Voltage)</li> <li>• Table 30-7: updates Maximum values at 10 and 20 MIPS</li> <li>• Table 30-8: adds Maximum IPD values, and removes all <math>\Delta I_{WDT}</math> entries</li> <li>• Adds new Table 30-9 (Watchdog Timer Delta Current) with consolidated values removed from Table 30-8. All subsequent tables are renumbered accordingly.</li> <li>• Table 30-10: adds footnote for all parameters for 1:2 Doze ratio</li> <li>• Table 30-11: <ul style="list-style-type: none"> <li>- changes Minimum and Maximum values for D120 and D130</li> <li>- adds Minimum and Maximum values for D131</li> <li>- adds Minimum and Maximum values for D150 through D156, and removes Typical values</li> </ul> </li> <li>• Table 30-12: <ul style="list-style-type: none"> <li>- reformats table for readability</li> <li>- changes IOL conditions for DO10</li> </ul> </li> <li>• Table 30-14: adds footnote to D135</li> <li>• Table 30-17: changes Minimum and Maximum values for OS30</li> <li>• Table 30-19: <ul style="list-style-type: none"> <li>- splits temperature range and adds new values for F20a</li> <li>- reduces temperature range for F20b to extended temperatures only</li> </ul> </li> <li>• Table 30-20: <ul style="list-style-type: none"> <li>- splits temperature range and adds new values for F21a</li> <li>- reduces temperature range for F20b to extended temperatures only</li> </ul> </li> <li>• Table 30-53: <ul style="list-style-type: none"> <li>- adds Maximum value to CM30</li> <li>- adds footnote (“Parameter characterized...”) to multiple parameters</li> </ul> </li> <li>• Table 30-55: adds Minimum and Maximum values for all CTMUI specifications, and removes Typical values</li> <li>• Table 30-57: adds new footnote to AD09</li> <li>• Table 30-58: <ul style="list-style-type: none"> <li>- removes all specifications for accuracy with external voltage references</li> <li>- removes Typical values for AD23a and AD24a</li> <li>- replaces Minimum and Maximum values for AD21a, AD22a, AD23a and AD24a with new values, split by Industrial and Extended temperatures</li> <li>- removes Maximum value of AD30</li> <li>- removes Minimum values from AD31a and AD32a</li> <li>- adds or changes Typical values for AD30, AD31a, AD32a and AD33a</li> </ul> </li> <li>• Table 30-59: <ul style="list-style-type: none"> <li>- removes all specifications for accuracy with external voltage references</li> <li>- removes Maximum value of AD30</li> <li>- removes Typical values for AD23b and AD24b</li> <li>- replaces Minimum and Maximum values for AD21b, AD22b, AD23b and AD24b with new values, split by Industrial and Extended temperatures</li> <li>- removes Minimum and Maximum values from AD31b, AD32b, AD33b and AD34b</li> <li>- adds or changes Typical values for AD30, AD31a, AD32a and AD33a</li> </ul> </li> <li>• Table 30-61: Adds footnote to AD51</li> </ul>
<b>Section 32.0 “DC and AC Device Characteristics Graphs”</b>	<ul style="list-style-type: none"> <li>• Updates Figure 32-6 (Typical IDD @ 3.3V) with individual current vs. processor speed curves for the different program memory sizes</li> </ul>
<b>Section 33.0 “Packaging Information”</b>	<ul style="list-style-type: none"> <li>• Replaces drawing C04-149C (64-pin QFN, 7.15 x 7.15 exposed pad) with C04-154A (64-pin QFN, 5.4 x 5.4 exposed pad)</li> </ul>