What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	CANbus, I²C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	32KB (10.7K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 150°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32mc502-h-so

4.0   MEMORY ORGANIZATION

> **Note:** This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Program Memory"** (DS70613) in the "*dsPIC33/PIC24 Family Reference Manual*", which is available from the Microchip web site (www.microchip.com).

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X architecture features separate program and data memory spaces, and buses. This architecture also allows the direct access of program memory from the Data Space (DS) during code execution.

4.1   Program Address Space

The program address memory space of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X devices is 4M instructions. The space is addressable by a 24-bit value derived either from the 23-bit PC during program execution, or from table operation or Data Space remapping, as described in **Section 4.8 "Interfacing Program and Data Memory Spaces"**.

User application access to the program memory space is restricted to the lower half of the address range (0x000000 to 0x7FFFFF). The exception is the use of TBLRD operations, which use TBLPAG<7> to read Device ID sections of the configuration memory space.

The program memory maps, which are presented by device family and memory size, are shown in Figure 4-1 through Figure 4-5.

FIGURE 4-1:   PROGRAM MEMORY MAP FOR dsPIC33EP32GP50X, dsPIC33EP32MC20X/50X AND PIC24EP32GP/MC20X DEVICES
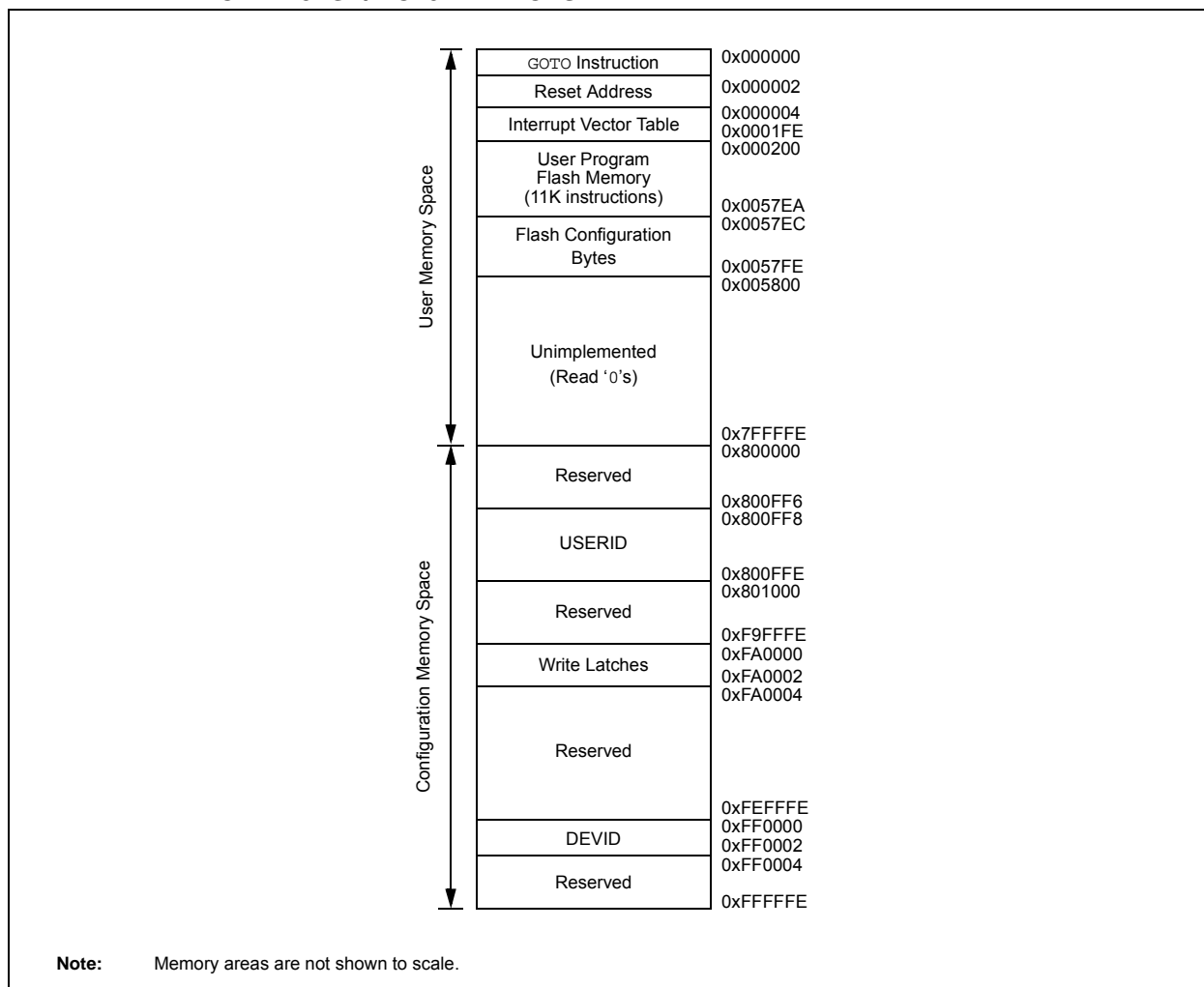

GOTO Instruction	0x000000
Reset Address	0x000002
Interrupt Vector Table	0x000004 / 0x0001FE
User Program Flash Memory (11K instructions)	0x000200 / 0x0057EA
Flash Configuration Bytes	0x0057EC / 0x0057FE
Unimplemented (Read '0's)	0x005800 / 0x7FFFFE
Reserved	0x800000 / 0x800FF6
USERID	0x800FF8 / 0x800FFE
Reserved	0x801000 / 0xF9FFFE
Write Latches	0xFA0000 / 0xFA0002
Reserved	0xFA0004 / 0xFEFFFE
DEVID	0xFF0000 / 0xFF0002
Reserved	0xFF0004 / 0xFFFFFE

User Memory Space / Configuration Memory Space

Note: Memory areas are not shown to scale.

TABLE 4-19:   SPI1 AND SPI2 REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI1STAT	0240	SPIEN	—	SPISIDL	—	—	SPIBEC<2:0>			SRMPT	SPIROV	SRXMPT	SISEL<2:0>			SPITBF	SPIRBF	0000
SPI1CON1	0242	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE<2:0>			PPRE<1:0>		0000
SPI1CON2	0244	FRMEN	SPIFSD	FRMPOL	—	—	—	—	—	—	—	—	—	—	—	FRMDLY	SPIBEN	0000
SPI1BUF	0248	SPI1 Transmit and Receive Buffer Register																0000
SPI2STAT	0260	SPIEN	—	SPISIDL	—	—	SPIBEC<2:0>			SRMPT	SPIROV	SRXMPT	SISEL<2:0>			SPITBF	SPIRBF	0000
SPI2CON1	0262	—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE<2:0>			PPRE<1:0>		0000
SPI2CON2	0264	FRMEN	SPIFSD	FRMPOL	—	—	—	—	—	—	—	—	—	—	—	FRMDLY	SPIBEN	0000
SPI2BUF	0268	SPI2 Transmit and Receive Buffer Register																0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

REGISTER 7-4: **INTCON2: INTERRUPT CONTROL REGISTER 2**

R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
GIE	DISI	SWTRAP	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	INT2EP	INT1EP	INT0EP
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15   **GIE:** Global Interrupt Enable bit
            1 = Interrupts and associated IE bits are enabled
            0 = Interrupts are disabled, but traps are still enabled

bit 14   **DISI:** DISI Instruction Status bit
            1 = DISI instruction is active
            0 = DISI instruction is not active

bit 13   **SWTRAP:** Software Trap Status bit
            1 = Software trap is enabled
            0 = Software trap is disabled

bit 12-3   **Unimplemented:** Read as '0'

bit 2   **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit
            1 = Interrupt on negative edge
            0 = Interrupt on positive edge

bit 1   **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit
            1 = Interrupt on negative edge
            0 = Interrupt on positive edge

bit 0   **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit
            1 = Interrupt on negative edge
            0 = Interrupt on positive edge

REGISTER 8-13:   DMALCA: DMA LAST CHANNEL ACTIVE STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R-1	R-1	R-1	R-1
—	—	—	—	LSTCH<3:0>			
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4 **Unimplemented:** Read as '0'

bit 3-0 **LSTCH<3:0>:** Last DMAC Channel Active Status bits

1111 = No DMA transfer has occurred since system Reset
1110 = Reserved
•
•
•
0100 = Reserved
0011 = Last data transfer was handled by Channel 3
0010 = Last data transfer was handled by Channel 2
0001 = Last data transfer was handled by Channel 1
0000 = Last data transfer was handled by Channel 0

g)   The TRISx registers control *only* the digital I/O output buffer. Any other dedicated or remappable active "output" will automatically override the TRIS setting. The TRISx register *does not* control the digital logic "input" buffer. Remappable digital "inputs" do not automatically override TRIS settings, which means that the TRISx bit must be set to input for pins with only remappable input function(s) assigned

h)   All analog pins are enabled by default after any Reset and the corresponding digital input buffer on the pin has been disabled. Only the Analog Pin Select registers control the digital input buffer, *not* the TRISx register. The user must disable the analog function on a pin using the Analog Pin Select registers in order to use any "digital input(s)" on a corresponding pin, no exceptions.

11.6   I/O Ports Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter this URL in your browser: http://www.microchip.com/wwwproducts/ Devices.aspx?dDocName=en555464

11.6.1   KEY RESOURCES

- **"I/O Ports"** (DS70598) in the *"dsPIC33/PIC24 Family Reference Manual"*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

REGISTER 14-2:   ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	IC32
bit 15							bit 8

R/W-0	R/W/HS-0	U-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-1
ICTRIG[2]	TRIGSTAT[3]	—	SYNCSEL4[4]	SYNCSEL3[4]	SYNCSEL2[4]	SYNCSEL1[4]	SYNCSEL0[4]
bit 7							bit 0

Legend:		HS = Hardware Settable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-9   **Unimplemented:** Read as '0'

bit 8   **IC32:** Input Capture 32-Bit Timer Mode Select bit (Cascade mode)

    1 = Odd IC and Even IC form a single 32-bit input capture module[1]
    0 = Cascade module operation is disabled

bit 7   **ICTRIG:** Input Capture Trigger Operation Select bit[2]

    1 = Input source used to trigger the input capture timer (Trigger mode)
    0 = Input source used to synchronize the input capture timer to a timer of another module (Synchronization mode)

bit 6   **TRIGSTAT:** Timer Trigger Status bit[3]

    1 = ICxTMR has been triggered and is running
    0 = ICxTMR has not been triggered and is being held clear

bit 5   **Unimplemented:** Read as '0'

Note 1:   The IC32 bit in both the Odd and Even IC must be set to enable Cascade mode.

    2:   The input source is selected by the SYNCSEL<4:0> bits of the ICxCON2 register.

    3:   This bit is set by the selected input source (selected by SYNCSEL<4:0> bits). It can be read, set and cleared in software.

    4:   Do not use the ICx module as its own Sync or Trigger source.

    5:   This option should only be selected as a trigger source and not as a synchronization source.

    6:   Each Input Capture x (ICx) module has one PTG input source. See **Section 24.0 "Peripheral Trigger Generator (PTG) Module"** for more information.
        PTGO8 = IC1
        PTGO9 = IC2
        PTGO10 = IC3
        PTGO11 = IC4

REGISTER 14-2:   ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0   **SYNCSEL<4:0>:** Input Source Select for Synchronization and Trigger Operation bits[4]

     11111 = No Sync or Trigger source for ICx
     11110 = Reserved
     11101 = Reserved
     11100 = CTMU module synchronizes or triggers ICx
     11011 = ADC1 module synchronizes or triggers ICx[5]
     11010 = CMP3 module synchronizes or triggers ICx[5]
     11001 = CMP2 module synchronizes or triggers ICx[5]
     11000 = CMP1 module synchronizes or triggers ICx[5]
     10111 = Reserved
     10110 = Reserved
     10101 = Reserved
     10100 = Reserved
     10011 = IC4 module synchronizes or triggers ICx
     10010 = IC3 module synchronizes or triggers ICx
     10001 = IC2 module synchronizes or triggers ICx
     10000 = IC1 module synchronizes or triggers ICx
     01111 = Timer5 synchronizes or triggers ICx
     01110 = Timer4 synchronizes or triggers ICx
     01101 = Timer3 synchronizes or triggers ICx **(default)**
     01100 = Timer2 synchronizes or triggers ICx
     01011 = Timer1 synchronizes or triggers ICx
     01010 = PTGOx module synchronizes or triggers ICx[6]
     01001 = Reserved
     01000 = Reserved
     00111 = Reserved
     00110 = Reserved
     00101 = Reserved
     00100 = OC4 module synchronizes or triggers ICx
     00011 = OC3 module synchronizes or triggers ICx
     00010 = OC2 module synchronizes or triggers ICx
     00001 = OC1 module synchronizes or triggers ICx
     00000 = No Sync or Trigger source for ICx

Note 1: The IC32 bit in both the Odd and Even IC must be set to enable Cascade mode.

2: The input source is selected by the SYNCSEL<4:0> bits of the ICxCON2 register.

3: This bit is set by the selected input source (selected by SYNCSEL<4:0> bits). It can be read, set and cleared in software.

4: Do not use the ICx module as its own Sync or Trigger source.

5: This option should only be selected as a trigger source and not as a synchronization source.

6: Each Input Capture x (ICx) module has one PTG input source. See **Section 24.0 "Peripheral Trigger Generator (PTG) Module"** for more information.
PTGO8 = IC1
PTGO9 = IC2
PTGO10 = IC3
PTGO11 = IC4

REGISTER 16-15: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER[(1)]

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	CLSRC4	CLSRC3	CLSRC2	CLSRC1	CLSRC0	CLPOL[(2)]	CLMOD
bit 15							bit 8

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
FLTSRC4	FLTSRC3	FLTSRC2	FLTSRC1	FLTSRC0	FLTPOL[(2)]	FLTMOD1	FLTMOD0
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-10 **CLSRC<4:0>:** Current-Limit Control Signal Source Select for PWM Generator # bits

11111 = Fault 32
11110 = Reserved
•
•
•
01100 = Reserved
01011 = Comparator 4
01010 = Op Amp/Comparator 3
01001 = Op Amp/Comparator 2
01000 = Op Amp/Comparator 1
00111 = Reserved
00110 = Reserved
00101 = Reserved
00100 = Reserved
00011 = Fault 4
00010 = Fault 3
00001 = Fault 2
00000 = Fault 1 **(default)**

bit 9 **CLPOL:** Current-Limit Polarity for PWM Generator # bit[(2)]

1 = The selected current-limit source is active-low
0 = The selected current-limit source is active-high

bit 8 **CLMOD:** Current-Limit Mode Enable for PWM Generator # bit

1 = Current-Limit mode is enabled
0 = Current-Limit mode is disabled

Note 1: If the PWMLOCK Configuration bit (FOSCSEL<6>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.

2: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER

R-0, HSC	R-0, HSC	U-0	U-0	U-0	R/C-0, HS	R-0, HSC	R-0, HSC
ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10
bit 15							bit 8

R/C-0, HS	R/C-0, HS	R-0, HSC	R/C-0, HSC	R/C-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF
bit 7							bit 0

Legend:	C = Clearable bit	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **ACKSTAT:** Acknowledge Status bit (when operating as I2C™ master, applicable to master transmit operation)
1 = NACK received from slave
0 = ACK received from slave
Hardware is set or clear at the end of slave Acknowledge.

bit 14 **TRSTAT:** Transmit Status bit (when operating as I2C master, applicable to master transmit operation)
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress
Hardware is set at the beginning of master transmission. Hardware is clear at the end of slave Acknowledge.

bit 13-11 **Unimplemented:** Read as '0'

bit 10 **BCL:** Master Bus Collision Detect bit
1 = A bus collision has been detected during a master operation
0 = No bus collision detected
Hardware is set at detection of a bus collision.

bit 9 **GCSTAT:** General Call Status bit
1 = General call address was received
0 = General call address was not received
Hardware is set when address matches general call address. Hardware is clear at Stop detection.

bit 8 **ADD10:** 10-Bit Address Status bit
1 = 10-bit address was matched
0 = 10-bit address was not matched
Hardware is set at the match of the 2nd byte of the matched 10-bit address. Hardware is clear at Stop detection.

bit 7 **IWCOL:** I2Cx Write Collision Detect bit
1 = An attempt to write to the I2CxTRN register failed because the I2C module is busy
0 = No collision
Hardware is set at the occurrence of a write to I2CxTRN while busy (cleared by software).

bit 6 **I2COV:** I2Cx Receive Overflow Flag bit
1 = A byte was received while the I2CxRCV register was still holding the previous byte
0 = No overflow
Hardware is set at an attempt to transfer I2CxRSR to I2CxRCV (cleared by software).

bit 5 **D_A:** Data/Address bit (when operating as I2C slave)
1 = Indicates that the last byte received was data
0 = Indicates that the last byte received was a device address
Hardware is clear at a device address match. Hardware is set by reception of a slave byte.

bit 4 **P:** Stop bit
1 = Indicates that a Stop bit has been detected last
0 = Stop bit was not detected last
Hardware is set or clear when a Start, Repeated Start or Stop is detected.

21.0 ENHANCED CAN (ECAN™) MODULE (dsPIC33EPXXXGP/ MC50X DEVICES ONLY)

> **Note 1:** This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Enhanced Controller Area Network (ECAN™)"** (DS70353) in the "*dsPIC33/PIC24 Family Reference Manual*", which is available from the Microchip web site (www.microchip.com).
>
> **2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

21.1 Overview

The Enhanced Controller Area Network (ECAN) module is a serial interface, useful for communicating with other CAN modules or microcontroller devices. This interface/protocol was designed to allow communications within noisy environments. The dsPIC33EPXXXGP/MC50X devices contain one ECAN module.

The ECAN module is a communication controller implementing the CAN 2.0 A/B protocol, as defined in the BOSCH CAN specification. The module supports CAN 1.2, CAN 2.0A, CAN 2.0B Passive and CAN 2.0B Active versions of the protocol. The module implementation is a full CAN system. The CAN specification is not covered within this data sheet. The reader can refer to the BOSCH CAN specification for further details.

The ECAN module features are as follows:

- Implementation of the CAN protocol, CAN 1.2, CAN 2.0A and CAN 2.0B
- Standard and extended data frames
- 0-8 bytes data length
- Programmable bit rate up to 1 Mbit/sec
- Automatic response to remote transmission requests
- Up to eight transmit buffers with application specified prioritization and abort capability (each buffer can contain up to 8 bytes of data)
- Up to 32 receive buffers (each buffer can contain up to 8 bytes of data)
- Up to 16 full (Standard/Extended Identifier) acceptance filters
- Three full acceptance filter masks
- DeviceNet™ addressing support
- Programmable wake-up functionality with integrated low-pass filter
- Programmable Loopback mode supports self-test operation
- Signaling via interrupt capabilities for all CAN receiver and transmitter error states
- Programmable clock source
- Programmable link to Input Capture (IC2) module for time-stamping and network synchronization
- Low-power Sleep and Idle mode

The CAN bus module consists of a protocol engine and message buffering/control. The CAN protocol engine handles all functions for receiving and transmitting messages on the CAN bus. Messages are transmitted by first loading the appropriate data registers. Status and errors can be checked by reading the appropriate registers. Any message detected on the CAN bus is checked for errors and then matched against filters to see if it should be received and stored in one of the receive registers.

REGISTER 21-6: CxINTF: ECANx INTERRUPT FLAG REGISTER (CONTINUED)

bit 1   **RBIF:** RX Buffer Interrupt Flag bit

1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 0   **TBIF:** TX Buffer Interrupt Flag bit

1 = Interrupt request has occurred
0 = Interrupt request has not occurred

BUFFER 21-5:   ECAN™ MESSAGE BUFFER WORD 4

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 3							

bit 15   bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 2							

bit 7   bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8   **Byte 3<15:8>:** ECAN Message Byte 3 bits
bit 7-0   **Byte 2<7:0>:** ECAN Message Byte 2 bits

BUFFER 21-6:   ECAN™ MESSAGE BUFFER WORD 5

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 5							

bit 15   bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
Byte 4							

bit 7   bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8   **Byte 5<15:8>:** ECAN Message Byte 5 bits
bit 7-0   **Byte 4<7:0>:** ECAN Message Byte 4 bits

NOTES:

REGISTER 23-6:   AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER (CONTINUED)

bit 4-0   **CH0SA<4:0>:** Channel 0 Positive Input Select for Sample MUXA bits[1]

11111 = Open; use this selection with CTMU capacitive and time measurement
11110 = Channel 0 positive input is connected to the CTMU temperature measurement diode (CTMU TEMP)
11101 = Reserved
11100 = Reserved
11011 = Reserved
11010 = Channel 0 positive input is the output of OA3/AN6[2,3]
11001 = Channel 0 positive input is the output of OA2/AN0[2]
11000 = Channel 0 positive input is the output of OA1/AN3[2]
10110 = Reserved
•
•
•
10000 = Reserved
01111 = Channel 0 positive input is AN15[1,3]
01110 = Channel 0 positive input is AN14[1,3]
01101 = Channel 0 positive input is AN13[1,3]
•
•
•
00010 = Channel 0 positive input is AN2[1,3]
00001 = Channel 0 positive input is AN1[1,3]
00000 = Channel 0 positive input is AN0[1,3]

Note 1: AN0 through AN7 are repurposed when comparator and op amp functionality is enabled. See Figure 23-1 to determine how enabling a particular op amp or comparator affects selection choices for Channels 1, 2 and 3.

2: The OAx input is used if the corresponding op amp is selected (OPMODE (CMxCON<10>) = 1); otherwise, the ANx input is used.

3: See the **"Pin Diagrams"** section for the available analog channels for each device.

FIGURE 30-12: **QEA/QEB INPUT CHARACTERISTICS
(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**
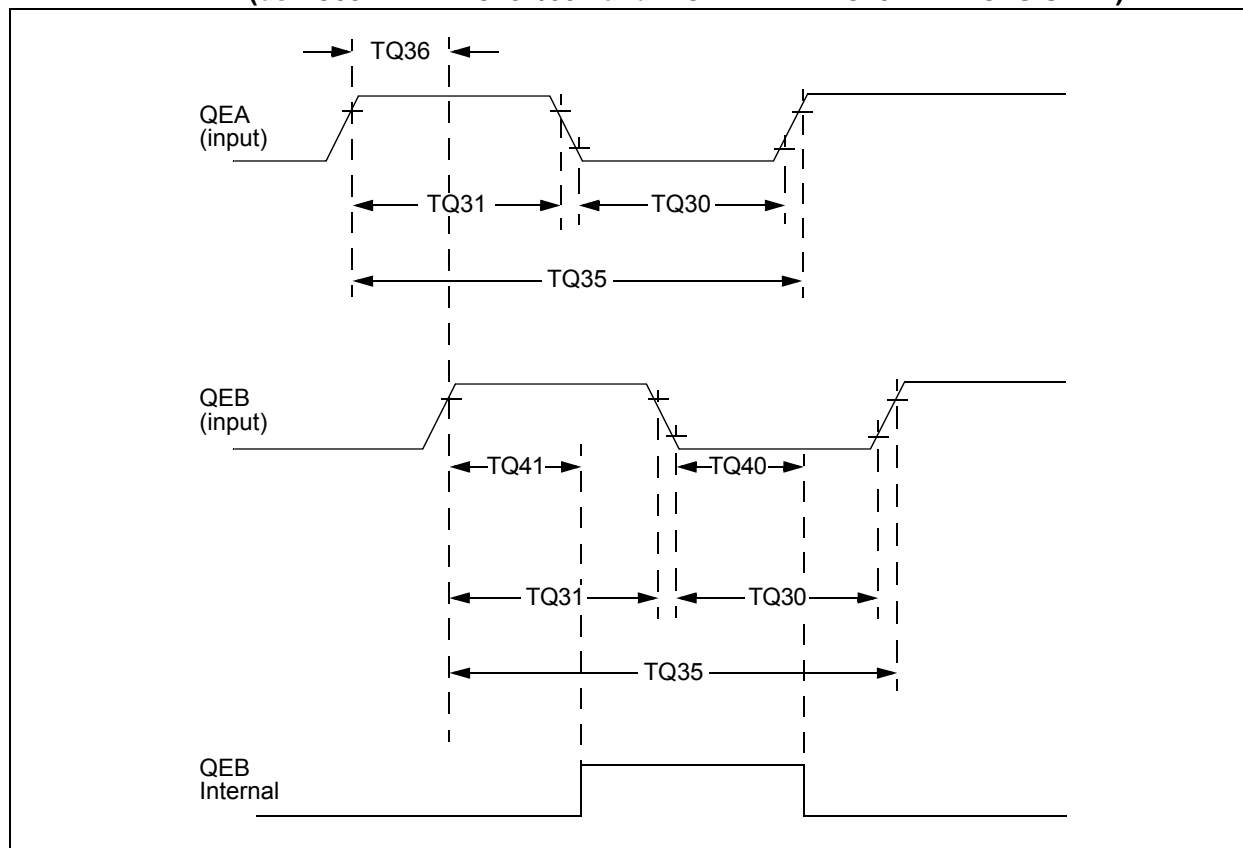

TABLE 30-31: **QUADRATURE DECODER TIMING REQUIREMENTS
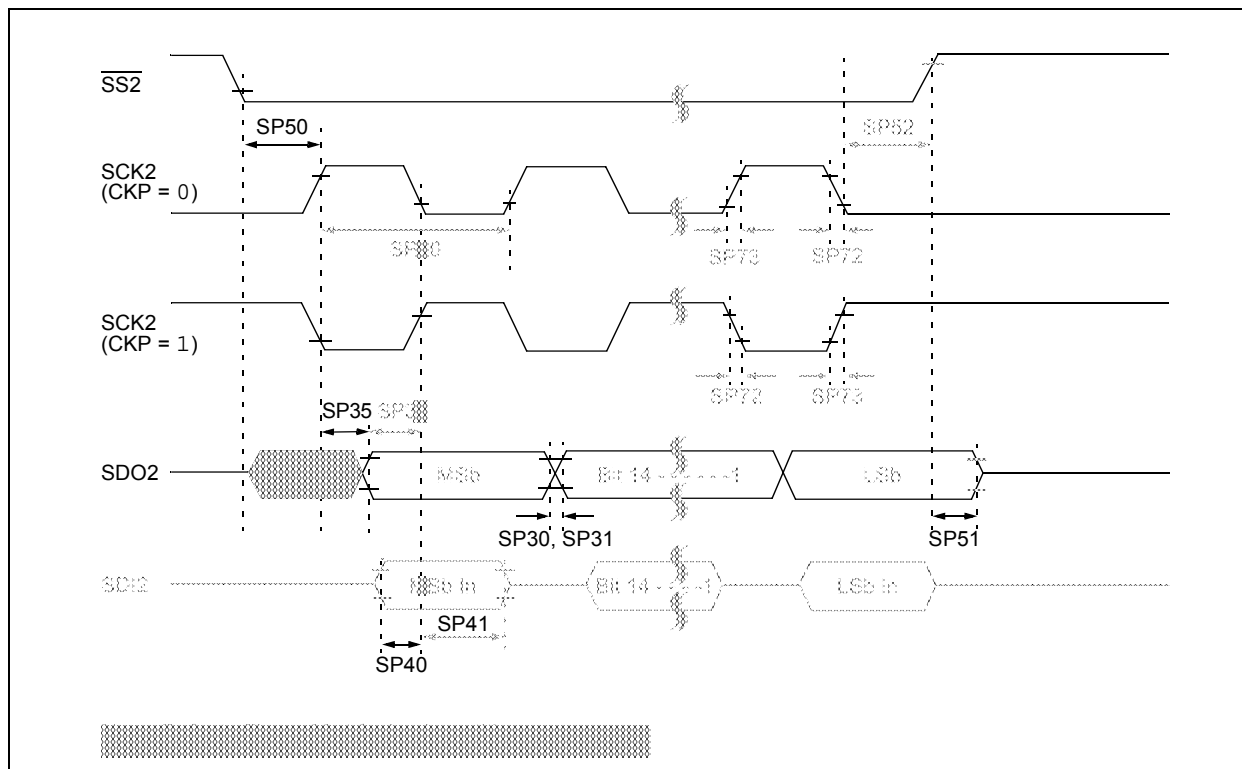(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param No.	Symbol	Characteristic[1]	Typ.[2]	Max.	Units	Conditions
TQ30	TQuL	Quadrature Input Low Time	6 TCY	—	ns	
TQ31	TQuH	Quadrature Input High Time	6 TCY	—	ns	
TQ35	TQuIN	Quadrature Input Period	12 TCY	—	ns	
TQ36	TQuP	Quadrature Phase Period	3 TCY	—	ns	
TQ40	TQuFL	Filter Time to Recognize Low, with Digital Filter	3 * N * TCY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)**
TQ41	TQuFH	Filter Time to Recognize High, with Digital Filter	3 * N * TCY	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)**

Note 1: These parameters are characterized but not tested in manufacturing.

   2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

   3: N = Index Channel Digital Filter Clock Divide Select bits. Refer to **"Quadrature Encoder Interface (QEI)"** (DS70601) in the "*dsPIC33/PIC24 Family Reference Manual*". Please see the Microchip web site for the latest family reference manual sections.

FIGURE 30-19: SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS
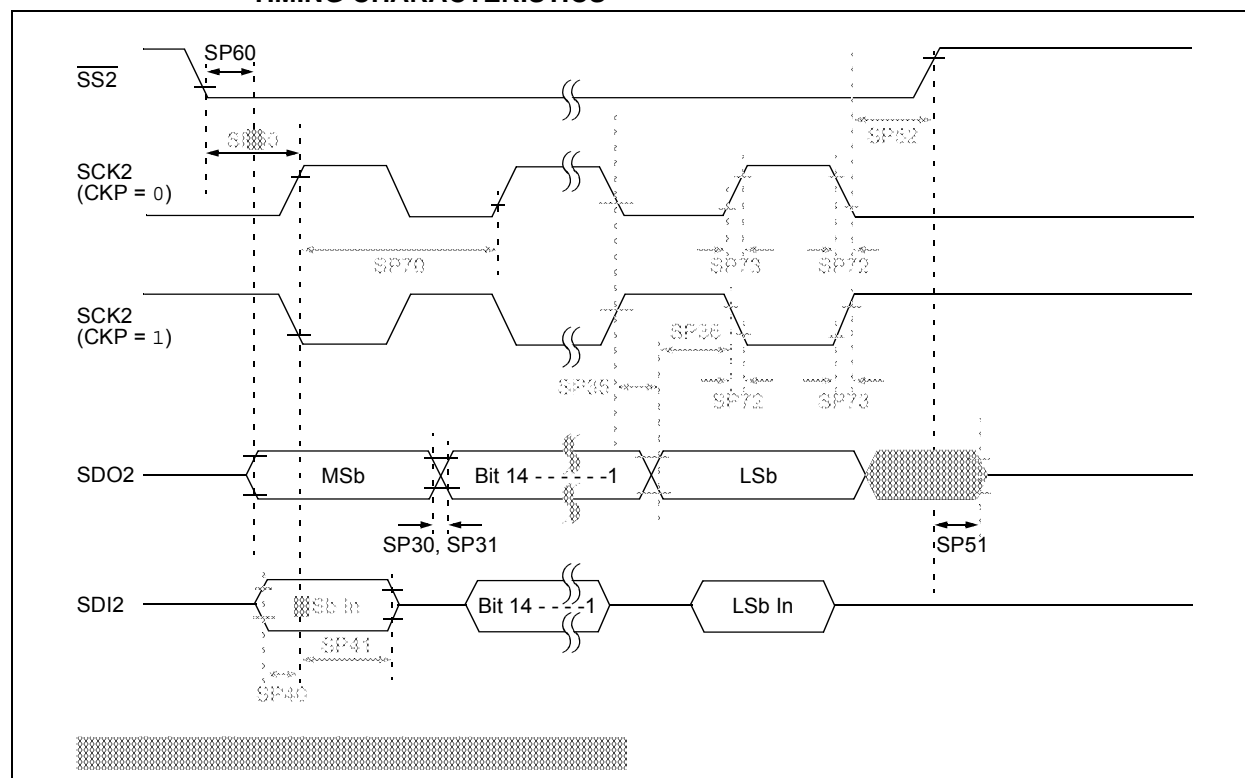
FIGURE 30-21:   **SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**

TABLE 30-46: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic[1]	Min.	Typ.[2]	Max.	Units	Conditions
SP70	FscP	Maximum SCK1 Input Frequency	—	—	Lesser of FP or 11	MHz	(Note 3)
SP72	TscF	SCK1 Input Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK1 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{SS1}$ ↓ to SCK1 ↑ or SCK1 ↓ Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{SS1}$ ↑ to SDO1 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	TscH2ssH, TscL2ssH	$\overline{SS1}$ ↑ after SCK1 Edge	1.5 TCY + 40	—	—	ns	(Note 4)
SP60	TssL2doV	SDO1 Data Output Valid after $\overline{SS1}$ Edge	—	—	50	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK1 is 91 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI1 pins.

TABLE 31-8: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C				
Param.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
HDO10	VOL	**Output Low Voltage** 4x Sink Driver Pins[2]	—	—	0.4	V	IOL ≤ 5 mA, VDD = 3.3V **(Note 1)**
		Output Low Voltage 8x Sink Driver Pins[3]	—	—	0.4	V	IOL ≤ 8 mA, VDD = 3.3V **(Note 1)**
HDO20	VOH	**Output High Voltage** 4x Source Driver Pins[2]	2.4	—	—	V	IOH ≥ -10 mA, VDD = 3.3V **(Note 1)**
		Output High Voltage 8x Source Driver Pins[3]	2.4	—	—	V	IOH ≥ 15 mA, VDD = 3.3V **(Note 1)**
HDO20A	VOH1	**Output High Voltage** 4x Source Driver Pins[2]	1.5	—	—	V	IOH ≥ -3.9 mA, VDD = 3.3V **(Note 1)**
			2.0	—	—		IOH ≥ -3.7 mA, VDD = 3.3V **(Note 1)**
			3.0	—	—		IOH ≥ -2 mA, VDD = 3.3V **(Note 1)**
		Output High Voltage 8x Source Driver Pins[3]	1.5	—	—	V	IOH ≥ -7.5 mA, VDD = 3.3V **(Note 1)**
			2.0	—	—		IOH ≥ -6.8 mA, VDD = 3.3V **(Note 1)**
			3.0	—	—		IOH ≥ -3 mA, VDD = 3.3V **(Note 1)**

Note 1:   Parameters are characterized, but not tested.

**2:**   Includes all I/O pins that are not 8x Sink Driver pins (see below).

3:   Includes the following pins:
For devices with less than 64 pins: RA3, RA4, RA9, RB<15:7> and RC3
For 64-pin devices: RA4, RA9, RB<15:7>, RC3 and RC15

36-Terminal Very Thin Thermal Leadless Array Package (TL) – 5x5x0.9 mm Body with Exposed Pad [VTLA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging
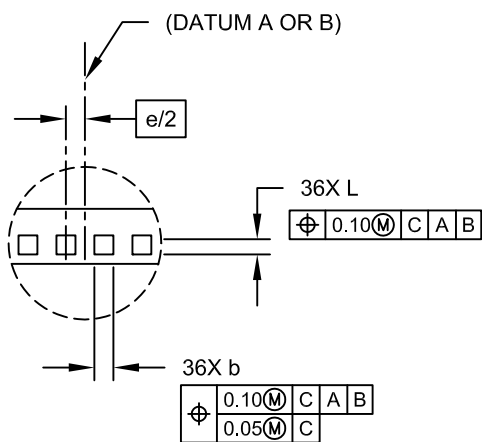
DETAIL A
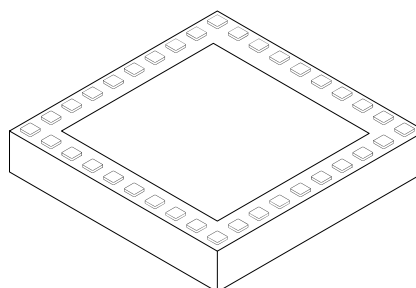
	Units	MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N		36	
Number of Pins per Side	ND		10	
Number of Pins per Side	NE		8	
Pitch	e		0.50 BSC	
Overall Height	A	0.80	0.90	1.00
Standoff	A1	0.025	-	0.075
Overall Width	E		5.00 BSC	
Exposed Pad Width	E2	3.60	3.75	3.90
Overall Length	D		5.00 BSC	
Exposed Pad Length	D2	3.60	3.75	3.90
Contact Width	b	0.20	0.25	0.30
Contact Length	L	0.20	0.25	0.30
Contact-to-Exposed Pad	K	0.20	-	-

Notes:
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.
   REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-187C Sheet 2 of 2