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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	CANbus, I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	25
Program Memory Size	32KB (10.7K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 8x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	36-VFTLA Exposed Pad
Supplier Device Package	36-VTLA (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep32mc503-i-tl

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TABLE 2: dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X MOTOR CONTROL FAMILIES

		<u>~</u>				Re	mappa	ble P	eriphe	erals											
Device	Page Erase Size (Instructions)	Program Flash Memory (Kbyte	RAM (Kbytes)	16-Bit/32-Bit Timers	Input Capture	Output Compare	Motor Control PWM ⁽⁴⁾ (Channels)	Quadrature Encoder Interface	UART	SPI ⁽²⁾	ECAN™ Technology	External Interrupts ⁽³⁾	I²C™	CRC Generator	10-Bit/12-Bit ADC (Channels)	Op Amps/Comparators	СТМИ	PTG	l/O Pins	Pins	Packages
PIC24EP32MC202	512	32	4																		
PIC24EP64MC202	1024	64	8																		SPDIP,
PIC24EP128MC202	1024	128	16	5	4	4	6	1	2	2	_	3	2	1	6	2/3 ⁽¹⁾	Yes	Yes	21	28	SOIC,
PIC24EP256MC202	1024	256	32																		QFN-S
PIC24EP512MC202	1024	512	48																		
PIC24EP32MC203	512	32	4	-			_	4	0	0		0	0	4	•	2/4	V	Vee	05	20	
PIC24EP64MC203	1024	64	8	5	4	4	ю	1	2	2	_	3	2	1	8	3/4	res	res	25	30	VILA
PIC24EP32MC204	512	32	4																		
PIC24EP64MC204	1024	64	8																		VTLA ⁽⁵⁾ ,
PIC24EP128MC204	1024	128	16	5	4	4	6	1	2	2	_	3	2	1	9	3/4	Yes	Yes	35	44/	TQFP,
PIC24EP256MC204	1024	256	32																	40	QFN, UQFN
PIC24EP512MC204	1024	512	48																		
PIC24EP64MC206	1024	64	8																		
PIC24EP128MC206	1024	128	16	_								•									TQFP.
PIC24EP256MC206	1024	256	32	5	4	4	6	1	2	2	_	3	2	1	16	3/4	res	res	53	64	QFN
PIC24EP512MC206	1024	512	48																		
dsPIC33EP32MC202	512	32	4																		
dsPIC33EP64MC202	1024	64	8																		SPDIP,
dsPIC33EP128MC202	1024	128	16	5	4	4	6	1	2	2	_	3	2	1	6	2/3(1)	Yes	Yes	21	28	SOIC,
dsPIC33EP256MC202	1024	256	32																		QFN-S
dsPIC33EP512MC202	1024	512	48																		
dsPIC33EP32MC203	512	32	4	_		_			-	_		-	-		-						
dsPIC33EP64MC203	1024	64	8	5	4	4	6	1	2	2	—	3	2	1	8	3/4	Yes	Yes	25	36	VTLA
dsPIC33EP32MC204	512	32	4																		
dsPIC33EP64MC204	1024	64	8																		VTLA ⁽⁵⁾ ,
dsPIC33EP128MC204	1024	128	16	5	4	4	6	1	2	2	_	3	2	1	9	3/4	Yes	Yes	35	44/	TQFP,
dsPIC33EP256MC204	1024	256	32																	40	UQFN,
dsPIC33EP512MC204	1024	512	48																		
dsPIC33EP64MC206	1024	64	8																		
dsPIC33EP128MC206	1024	128	16	_					-			-	-								TOFP
dsPIC33EP256MC206	1024	256	32	5	4	4	6	1	2	2	—	3	2	1	16	3/4	Yes	Yes	53	64	QFN
dsPIC33EP512MC206	1024	512	48																		
dsPIC33EP32MC502	512	32	4																		
dsPIC33EP64MC502	1024	64	8																		SPDIP,
dsPIC33EP128MC502	1024	128	16	5	4	4	6	1	2	2	1	3	2	1	6	2/3(1)	Yes	Yes	21	28	SOIC,
dsPIC33EP256MC502	1024	256	32																		QFN-S
dsPIC33EP512MC502	1024	512	48																		_
dsPIC33EP32MC503	512	32	4	_			6		_	-			-		_	.		~	a-		
dsPIC33EP64MC503	1024	64	8	5	4	4	6	1	2	2	1	3	2	1	8	3/4	res	res	25	36	VILA

Note 1: On 28-pin devices, Comparator 4 does not have external connections. Refer to Section 25.0 "Op Amp/Comparator Module" for details. 2: Only SPI2 is remappable.

3: INTO is not remappable.

4: Only the PWM Faults are remappable.

5: The SSOP and VTLA packages are not available for devices with 512 Kbytes of memory.

Pin Diagrams (Continued)



Pin Diagrams (Continued)



TABLE 4-41: PMD REGISTER MAP FOR dsPIC33EPXXXMC20X DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0760	T5MD	T4MD	T3MD	T2MD	T1MD	QEI1MD	PWMMD	—	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	AD1MD	0000
PMD2	0762	_	_	_	_	IC4MD	IC3MD	IC2MD	IC1MD	_	_	_	_	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0764	_	_	_	_	_	CMPMD	_	_	CRCMD	_	_	_	_	_	I2C2MD	_	0000
PMD4	0766	_	_	_	_	_	_	_	_	_	_	_	_	REFOMD	CTMUMD	_	_	0000
PMD6	076A		_		_		PWM3MD	PWM2MD	PWM1MD			—	—	—	_	—		0000
													DMA0MD					
	0760												DMA1MD	DTOMD				0000
FINDT	0700	_	_	_	_	_	_	_	_	—	_	_	DMA2MD	FIGND	_	_	_	0000
													DMA3MD					

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

REGISTER 8-9: DSADRH: DMA MOST RECENT RAM HIGH ADDRESS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	—	—	_	—	—	—
bit 15							bit 8
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSADR	<23:16>			
bit 7							bit 0
Legend:							
R = Readable I	bit	W = Writable bi	t	U = Unimpler	mented bit, read	as '0'	

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 DSADR<23:16>: Most Recent DMA Address Accessed by DMA bits

REGISTER 8-10: DSADRL: DMA MOST RECENT RAM LOW ADDRESS REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSAI	DR<15:8>			
bit 15							bit 8
R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
			DSA	DR<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable bit		U = Unimplemer	nted bit, re	ad as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cleare	d	x = Bit is unknown	

bit 15-0 DSADR<15:0>: Most Recent DMA Address Accessed by DMA bits

REGISTER 14-2: ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2 (CONTINUED)

- bit 4-0 SYNCSEL<4:0>: Input Source Select for Synchronization and Trigger Operation bits⁽⁴⁾
 - 11111 = No Sync or Trigger source for ICx
 - 11110 = Reserved
 - 11101 = Reserved
 - 11100 = CTMU module synchronizes or triggers ICx
 - 11011 = ADC1 module synchronizes or triggers $ICx^{(5)}$
 - 11010 = CMP3 module synchronizes or triggers $ICx^{(5)}$
 - $11001 = CMP2 \text{ module synchronizes or triggers ICx}^{(5)}$
 - 11000 = CMP1 module synchronizes or triggers $ICx^{(5)}$
 - 10111 = Reserved
 - 10110 = Reserved
 - 10101 = Reserved
 - 10100 = Reserved
 - 10011 = IC4 module synchronizes or triggers ICx
 - 10010 = IC3 module synchronizes or triggers ICx
 - 10001 = IC2 module synchronizes or triggers ICx
 - 10000 = IC1 module synchronizes or triggers ICx
 - 01111 = Timer5 synchronizes or triggers ICx
 - 01110 = Timer4 synchronizes or triggers ICx
 - 01101 = Timer3 synchronizes or triggers ICx (default)
 - 01100 = Timer2 synchronizes or triggers ICx
 - 01011 = Timer1 synchronizes or triggers ICx
 - 01010 = PTGOx module synchronizes or triggers $ICx^{(6)}$
 - 01001 = Reserved
 - 01000 = Reserved
 - 00111 = Reserved
 - 00110 = Reserved
 - 00101 = Reserved
 - 00100 = OC4 module synchronizes or triggers ICx
 - 00011 = OC3 module synchronizes or triggers ICx
 - 00010 = OC2 module synchronizes or triggers ICx
 - 00001 = OC1 module synchronizes or triggers ICx
 - 00000 = No Sync or Trigger source for ICx
- **Note 1:** The IC32 bit in both the Odd and Even IC must be set to enable Cascade mode.
 - 2: The input source is selected by the SYNCSEL<4:0> bits of the ICxCON2 register.
 - **3:** This bit is set by the selected input source (selected by SYNCSEL<4:0> bits). It can be read, set and cleared in software.
 - 4: Do not use the ICx module as its own Sync or Trigger source.
 - 5: This option should only be selected as a trigger source and not as a synchronization source.
 - Each Input Capture x (ICx) module has one PTG input source. See Section 24.0 "Peripheral Trigger Generator (PTG) Module" for more information.
 PTGO8 = IC1

PTGO9 = IC2 PTGO10 = IC3 PTGO11 = IC4

15.2 Output Compare Control Registers

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0					
		OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	_	ENFLTB					
bit 15							bit 8					
R/W-0	U-0	R/W-0, HSC	R/W-0, HSC	R/W-0	R/W-0	R/W-0	R/W-0					
ENFLTA		OCFLTB	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0					
bit 7							bit 0					
Legend:		HSC = Hardw	are Settable/Cl	earable bit								
R = Reada	ible bit	W = Writable I	bit	U = Unimplem	nented bit, read	as '0'						
-n = Value	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown					
bit 15-14	Unimplemen	ted: Read as '0)'									
bit 13	OCSIDL: Out	tput Compare x	Stop in Idle Mo	de Control bit								
	1 = Output C	1 = Output Compare x Halts in CPU Idle mode										
bit 12 10		0 = Output Compare x continues to operate in CPU Idle mode										
DIL 12-10	111 = Perinh	111 = Perinheral clock (FP)										
	110 = Reserved											
	101 = PTGOx clock ⁽²⁾											
	100 = T1CLK	is the clock so	urce of the OC	k (only the sync	hronous clock	is supported)						
	011 = 15CLK	is the clock sou	urce of the OC	х ~								
	010 = T4CLK 001 = T3CLK	is the clock so	urce of the OC	x X								
	000 = T2CLK	is the clock so	urce of the OC	ĸ								
bit 9	Unimplemen	ted: Read as '0)'									
bit 8	ENFLTB: Fau	ult B Input Enab	le bit									
	1 = Output C 0 = Output C	compare Fault B compare Fault B	input (OCFB) input (OCFB)	is enabled is disabled								
bit 7	ENFLTA: Fau	ult A Input Enabl	le bit									
	1 = Output C	ompare Fault A	input (OCFA)	is enabled								
	0 = Output C	ompare Fault A	input (OCFA)	is disabled								
bit 6	Unimplemen	ted: Read as '0)'									
bit 5	OCFLTB: PW	M Fault B Cond	dition Status bit									
	1 = PWM Fa 0 = No PWM	ult B condition of Fault B condition	on OCFB pin ha on on OCFB pi	as occurred n has occurred								
bit 4	OCFLTA: PW	/M Fault A Cond	dition Status bit									
	1 = PWM Fa	ult A condition of	on OCFA pin ha	as occurred								
	0 = No PWM	I Fault A condition	on on OCFA pi	n has occurred								
Note 1:	OCxR and OCxF	RS are double-b	ouffered in PWN	A mode only.								
2:	Each Output Cor	mpare x module	(OCx) has one	PTG clock sou	urce. See Secti	on 24.0 "Perip	oheral Trigger					
	Generator (PTG PTGO4 = OC1) wodule" for r	nore informatio	n.								
	PTGO5 = OC2											
	PTGO6 = OC3											
	PTGO7 = OC4											

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

REGISTER 16-8: PDCx: PWMx GENERATOR DUTY CYCLE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PDC	x<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PDC	x<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimpler	mented bit, rea	id as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown

bit 15-0 **PDCx<15:0>:** PWMx Generator # Duty Cycle Value bits

REGISTER 16-9: PHASEx: PWMx PRIMARY PHASE-SHIFT REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PHAS	Ex<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			PHAS	SEx<7:0>			
bit 7							bit 0
Legend:							
R = Readable I	bit	W = Writable b	it	U = Unimpler	mented bit, rea	ad as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkı	nown

bit 15-0 PHASEx<15:0>: PWMx Phase-Shift Value or Independent Time Base Period for the PWM Generator bits

Note 1: If ITB (PWMCONx<9>) = 0, the following applies based on the mode of operation: Complementary, Redundant and Push-Pull Output mode (PMOD<1:0> (IOCON<11:10>) = 00, 01 or 10), PHASEx<15:0> = Phase-shift value for PWMxH and PWMxL outputs

 If ITB (PWMCONx<9>) = 1, the following applies based on the mode of operation: Complementary, Redundant and Push-Pull Output mode (PMOD<1:0> (IOCONx<11:10>) = 00, 01 or 10), PHASEx<15:0> = Independent time base period value for PWMxH and PWMxL

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	CLSRC4	CLSRC3	CLSRC2	CLSRC1	CLSRC0	CLPOL ⁽²⁾	CLMOD
bit 15			•				bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
FLTSRC4	FLTSRC3	FLTSRC2	FLTSRC1	FLTSRC0	FLTPOL ⁽²⁾	FLTMOD1	FLTMOD0
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable	bit	U = Unimple	mented bit, read	l as '0'	
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown
bit 15	Unimplemen	ted: Read as '	0'				
bit 14-10	CLSRC<4:0>	Current-Limit	Control Signa	al Source Sele	ct for PWM Ger	erator # bits	
	11111 = Fau	lt 32					
	11110 = Res	served					
	•						
	•	anyod					
	01100 = Res 01011 = Con	nparator 4					
	01010 = Op	Amp/Comparat	or 3				
	01001 = Op	Amp/Comparat	or 2				
	01000 = Op	Amp/Comparat	or 1				
	00111 = Res	erved					
	00101 = Res	erved					
	00100 = Res	erved					
	00011 = Fau	lt 4					
	00010 = Fau	lt 3 lt 2					
	00000 = Fau	It 1 (default)					
bit 9	CLPOL: Curr	ent-Limit Polar	ity for PWM G	enerator # bit	2)		
	1 = The selec	cted current-lim	it source is ac	tive-low			
	0 = The selec	cted current-lim	it source is ac	tive-high			
bit 8	CLMOD: Cur	rent-Limit Mode	e Enable for P	WM Generato	r # bit		
	1 = Current-L	imit mode is er	nabled				
	0 = Current-L	imit mode is di	sabled				
Note 1: If the	he PWMLOCK	Configuration b	it (FOSCSEL·	<6>) is a '1', th	ne IOCONx regi	ster can only be	e written after
the	unlock sequen	ice has been ex	cecuted.				

REGISTER 16-15: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER⁽¹⁾

2: These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.



FIGURE 18-1: SPIX MODULE BLOCK DIAGRAM

REGISTER 18-1: SPIx STAT: SPIx STATUS AND CONTROL REGISTER (CONTINUED)

- bit 1 SPITBF: SPIx Transmit Buffer Full Status bit
 - 1 = Transmit not yet started, SPIxTXB is full
 - 0 = Transmit started, SPIxTXB is empty

Standard Buffer mode:

Automatically set in hardware when core writes to the SPIxBUF location, loading SPIxTXB. Automatically cleared in hardware when SPIx module transfers data from SPIxTXB to SPIxSR.

Enhanced Buffer mode:

Automatically set in hardware when the CPU writes to the SPIxBUF location, loading the last available buffer location. Automatically cleared in hardware when a buffer location is available for a CPU write operation.

bit 0 SPIRBF: SPIx Receive Buffer Full Status bit

1 = Receive is complete, SPIxRXB is full

0 = Receive is incomplete, SPIxRXB is empty

Standard Buffer mode:

Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB. Automatically cleared in hardware when the core reads the SPIxBUF location, reading SPIxRXB.

Enhanced Buffer mode:

Automatically set in hardware when SPIx transfers data from SPIxSR to the buffer, filling the last unread buffer location. Automatically cleared in hardware when a buffer location is available for a transfer from SPIxSR.

						D 444 A					
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
-	—	—	DISSCK	DISSDO	MODE16	SMP	CKE				
bit 15							bit 8				
				DAMA		DAM 0					
	2) R/VV-U	R/W-U		R/W-U	R/W-0		R/W-0				
55EIN		MSTEN	SPRE2(*)	SPRET	SPREU	PPRET	PPREU				
DIL 7							DILU				
Legend:											
R = Read	able bit	W = Writable	bit	U = Unimpler	mented bit read	1 as '0'					
-n = Value	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown				
			•	0 2.1.10 0.10							
bit 15-13	Unimplemer	nted: Read as '	0'								
bit 12	DISSCK: Dis	able SCKx Pin	bit (SPIx Mas	ter modes only	<i>'</i>)						
	1 = Internal S	SPIx clock is dis	sabled, pin fun	ctions as I/O							
	0 = Internal S	SPIx clock is er	abled								
bit 11	DISSDO: Dis	able SDOx Pir	ı bit								
	1 = SDOx pir	n is not used by	the module; p	oin functions as	s I/O						
bit 10	0 = SDOx pin is controlled by the module MODE16: Word/Pyte Communication Select bit										
	1 = Commun	ication is word	wide (16 bits)								
	0 = Commun	ication is byte-	wide (8 bits)								
bit 9	SMP: SPIx D	ata Input Sam	ole Phase bit								
	Master mode	<u>):</u>									
	1 = Input dat	a is sampled at	end of data of	utput time							
	0 – Input data Slave mode:	a is sampled at		a output time							
	SMP must be	e cleared when	SPIx is used i	n Slave mode.							
bit 8	CKE: SPIx C	lock Edge Sele	ect bit ⁽¹⁾								
	1 = Serial ou	tput data chang	ges on transitio	on from active	clock state to Id	lle clock state (i	refer to bit 6)				
	0 = Serial ou	tput data chang	ges on transitio	on from Idle clo	ock state to activ	ve clock state (refer to bit 6)				
bit 7	SSEN: Slave	Select Enable	bit (Slave mo	de) ⁽²⁾							
	$1 = \frac{SSx}{SSx}$ pin is	s used for Slav	e mode he module: nir	is controlled h	ov port function						
bit 6	CKP: Clock F	Polarity Select	hit		by port function						
bito	1 = Idle state	for clock is a h	iiah level: activ	ve state is a low	v level						
	0 = Idle state	for clock is a l	ow level; active	e state is a higl	h level						
bit 5	MSTEN: Mas	ster Mode Enat	ole bit								
	1 = Master m	node									
	0 = Slave mo	ode									
Note 1:	The CKE bit is not	used in Frame	d SPI modes. I	Program this bi	t to '0' for Fram	ed SPI modes (FRMEN = 1).				
2:	This bit must be c	leared when FF	RMEN = 1.								

REGISTER 18-2: SPIXCON1: SPIX CONTROL REGISTER 1

- 3: Do not set both primary and secondary prescalers to the value of 1:1.





28.0 INSTRUCTION SET SUMMARY

Note: This data sheet summarizes the features of the dsPIC33EPXXXGP50X. dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. То complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Familv Reference Manual', which is available from the Microchip web site (www.microchip.com).

The dsPIC33EP instruction set is almost identical to that of the dsPIC30F and dsPIC33F. The PIC24EP instruction set is almost identical to that of the PIC24F and PIC24H.

Most instructions are a single program memory word (24 bits). Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word, divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into five basic categories:

- · Word or byte-oriented operations
- · Bit-oriented operations
- · Literal operations
- DSP operations
- · Control operations

Table 28-1 lists the general symbols used in describing the instructions.

The dsPIC33E instruction set summary in Table 28-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand, which is typically a register 'Wb' without any address modifier
- The second source operand, which is typically a register 'Ws' with or without an address modifier
- The destination of the result, which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- · The file register specified by the value 'f'
- The destination, which could be either the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/ shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register 'Wb')

The literal instructions that involve data movement can use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand, which is a register 'Wb' without any address modifier
- The second source operand, which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register 'Wd' with or without an address modifier

The MAC class of DSP instructions can use some of the following operands:

- The accumulator (A or B) to be used (required operand)
- The W registers to be used as the two operands
- · The X and Y address space prefetch operations
- The X and Y address space prefetch destinations
- The accumulator write back destination

The other DSP instructions do not involve any multiplication and can include:

- The accumulator to be used (required)
- The source or destination operand (designated as Wso or Wdo, respectively) with or without an address modifier
- The amount of shift specified by a W register 'Wn' or a literal value

The control instructions can use some of the following operands:

- A program memory address
- The mode of the Table Read and Table Write instructions



FIGURE 30-3: I/O TIMING CHARACTERISTICS

TABLE 30-21: I/O TIMING REQUIREMENTS

AC CHAR	ACTERISTI	CS	$\begin{tabular}{lllllllllllllllllllllllllllllllllll$						
Param No.	Symbol	Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Conditions		
DO31	TIOR	Port Output Rise Time	_	5	10	ns			
DO32	TIOF	Port Output Fall Time	—	5	10	ns			
DI35	TINP	INTx Pin High or Low Time (input)	20	_		ns			
DI40 TRBP CNx High or Low Time (input)			2		_	TCY			

Note 1: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

FIGURE 30-4: BOR AND MASTER CLEAR RESET TIMING CHARACTERISTICS





FIGURE 30-13: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

TABLE 30-32: QEI INDEX PULSE TIMING REQUIREMENTS (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$			
Param No.	Symbol	Characteristic ⁽¹⁾	Min.	Max.	Units	Conditions
TQ50	TqiL	Filter Time to Recognize Low, with Digital Filter	3 * N * Tcy	_	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 (Note 2)
TQ51	TqiH	Filter Time to Recognize High, with Digital Filter	3 * N * Tcy	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 (Note 2)
TQ55	Tqidxr	Index Pulse Recognized to Position Counter Reset (ungated index)	3 TCY	—	ns	

Note 1: These parameters are characterized but not tested in manufacturing.

2: Alignment of index pulses to QEA and QEB is shown for position counter Reset timing only. Shown for forward direction only (QEA leads QEB). Same timing applies for reverse direction (QEA lags QEB) but index pulse recognition occurs on the falling edge.

TABLE 30-40:SPI2 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0)TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP70	FscP	Maximum SCK2 Input Frequency	—	—	11	MHz	(Note 3)
SP72	TscF	SCK2 Input Fall Time	—	-	_	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK2 Input Rise Time	_	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO2 Data Output Fall Time			_	ns	See Parameter DO31 (Note 4)
SP31	TdoR	SDO2 Data Output Rise Time	—	_	_	ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDO2 Data Output Valid after SCK2 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO2 Data Output Setup to First SCK2 Edge	30	_	_	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI2 Data Input to SCK2 Edge	30	_	_	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDI2 Data Input to SCK2 Edge	30	—	_	ns	
SP50	TssL2scH, TssL2scL	$\overline{SS2}$ ↓ to SCK2 ↑ or SCK2 ↓ Input	120		—	ns	
SP51	TssH2doZ	SS2 ↑ to SDO2 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	TscH2ssH TscL2ssH	SS2 ↑ after SCK2 Edge	1.5 Tcy + 40	—		ns	(Note 4)

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCK2 is 91 ns. Therefore, the SCK2 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI2 pins.



FIGURE 30-24: SPI1 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING CHARACTERISTICS

TABLE 30-43:SPI1 MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1)TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP10	FscP	Maximum SCK1 Frequency	_		10	MHz	(Note 3)
SP20	TscF	SCK1 Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK1 Output Rise Time	—	—	_	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	_	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—		ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdoV2sc, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	_	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	—	_	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30			ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

- **3:** The minimum clock period for SCK1 is 100 ns. The clock generated in Master mode must not violate this specification.
- **4:** Assumes 50 pF load on all SPI1 pins.



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44-Terminal Very Thin Leadless Array Package (TL) – 6x6x0.9 mm Body With Exposed Pad [VTLA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



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