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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 150°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep512mc204-h-pt

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

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2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS AND MICROCONTROLLERS

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the related section of the "dsPIC33/PIC24 Family Reference Manual", which is available from the Microchip web site (www.microchip.com)
 - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

2.1 Basic Connection Requirements

Getting started with the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names, which must always be connected:

- All VDD and Vss pins (see Section 2.2 "Decoupling Capacitors")
- All AVDD and AVSS pins (regardless if ADC module is not used) (see Section 2.2 "Decoupling Capacitors")
- VCAP
 (see Section 2.3 "CPU Logic Filter Capacitor Connection (VCAP)")
- MCLR pin (see Section 2.4 "Master Clear (MCLR) Pin")
- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes (see Section 2.5 "ICSP Pins")
- OSC1 and OSC2 pins when external oscillator source is used (see Section 2.6 "External Oscillator Pins")

Additionally, the following pins may be required:

 VREF+/VREF- pins are used when external voltage reference for the ADC module is implemented

Note: The AVDD and AVSS pins must be connected, independent of the ADC voltage reference source.

2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- Value and type of capacitor: Recommendation of 0.1 μ F (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended to use ceramic capacitors.
- Placement on the printed circuit board: The
 decoupling capacitors should be placed as close
 to the pins as possible. It is recommended to
 place the capacitors on the same side of the
 board as the device. If space is constricted, the
 capacitor can be placed on another layer on the
 PCB using a via; however, ensure that the trace
 length from the pin to the capacitor is within
 one-quarter inch (6 mm) in length.
- Handling high-frequency noise: If the board is experiencing high-frequency noise, above tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μF to 0.001 μF. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1 μF in parallel with 0.001 μF.
- Maximizing performance: On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB track inductance.

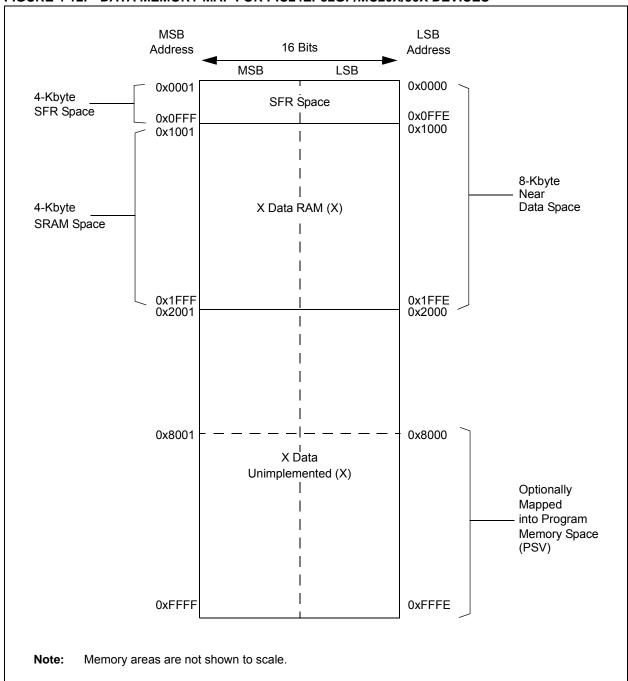


FIGURE 4-12: DATA MEMORY MAP FOR PIC24EP32GP/MC20X/50X DEVICES

TABLE 4-4: INTERRUPT CONTROLLER REGISTER MAP FOR PIC24EPXXXMC20X DEVICES ONLY (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IPC35	0886	_	,	JTAGIP<2:0	>	_		ICDIP<2:0	>	_	_	-	1	_	_	_	-	4400
IPC36	0888	_	F	PTG0IP<2:0	>	-	PT	GWDTIP<	2:0>	-	PT	GSTEPIP<2	:0>	_	-	_	ı	4440
IPC37	088A	_	_	_	_	-	F	PTG3IP<2:0	0>	-	l	PTG2IP<2:0>	>	_	I	PTG1IP<2:0>		0444
INTCON1	08C0	NSTDIS	OVAERR	OVBERR	-	-	1	-	_	_	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL	1	0000
INTCON2	08C2	GIE	DISI	SWTRAP	-	-	1	-	_	_	_	_	ı	_	INT2EP	INT1EP	INT0EP	8000
INTCON3	08C4	_	_	_	-	-	1	-	_	_	_	DAE	DOOVR	_	_	_	1	0000
INTCON4	08C6	_	_	_	_	_	ı	_	_	_	_	_	ı	_	_	_	SGHT	0000
INTTREG	08C8	_	_	_	-		ILR<	3:0>					VECN	UM<7:0>				0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-53: PORTA REGISTER MAP FOR PIC24EPXXXGP/MC204 AND dsPIC33EPXXXGP/MC204/504 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	0E00	_	1	_	1	_	TRISA10	TRISA9	TRISA8	TRISA7	-	-	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	079F
PORTA	0E02	1	-	_	_	_	RA10	RA9	RA8	RA7	_	_	RA4	RA3	RA2	RA1	RA0	0000
LATA	0E04	1	-	_	_	_	LATA10	LATA9	LATA8	LATA7	_	_	LATA4	LATA3	LATA2	LA1TA1	LA0TA0	0000
ODCA	0E06	1	-	_	_	_	ODCA10	ODCA9	ODCA8	ODCA7	_	_	ODCA4	ODCA3	ODCA2	ODCA1	ODCA0	0000
CNENA	0E08	1	-	_	_	_	CNIEA10	CNIEA9	CNIEA8	CNIEA7	_	_	CNIEA4	CNIEA3	CNIEA2	CNIEA1	CNIEA0	0000
CNPUA	0E0A	1	-	_	_	_	CNPUA10	CNPUA9	CNPUA8	CNPUA7	_	_	CNPUA4	CNPUA3	CNPUA2	CNPUA1	CNPUA0	0000
CNPDA	0E0C	1	-	_	_	_	CNPDA10	CNPDA9	CNPDA8	CNPDA7	_	_	CNPDA4	CNPDA3	CNPDA2	CNPDA1	CNPDA0	0000
ANSELA	0E0E	-	1	_	ı	1	_	_	_	_	ı	-	ANSA4	-	_	ANSA1	ANSA0	0013

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-54: PORTB REGISTER MAP FOR PIC24EPXXXGP/MC204 AND dsPIC33EPXXXGP/MC204/504 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	0E12	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	0E14	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	0E16	ODCB15	ODCB14	ODCB13	ODCB12	ODCB11	ODCB10	ODCB9	ODCB8	ODCB7	ODCB6	ODCB5	ODCB4	ODCB3	ODCB2	ODCB1	ODCB0	0000
CNENB	0E18	CNIEB15	CNIEB14	CNIEB13	CNIEB12	CNIEB11	CNIEB10	CNIEB9	CNIEB8	CNIEB7	CNIEB6	CNIEB5	CNIEB4	CNIEB3	CNIEB2	CNIEB1	CNIEB0	0000
CNPUB	0E1A	CNPUB15	CNPUB14	CNPUB13	CNPUB12	CNPUB11	CNPUB10	CNPUB9	CNPUB8	CNPUB7	CNPUB6	CNPUB5	CNPUB4	CNPUB3	CNPUB2	CNPUB1	CNPUB0	0000
CNPDB	0E1C	CNPDB15	CNPDB14	CNPDB13	CNPDB12	CNPDB11	CNPDB10	CNPDB9	CNPDB8	CNPDB7	CNPDB6	CNPDB5	CNPDB4	CNPDB3	CNPDB2	CNPDB1	CNPDB0	0000
ANSELB	0E1E	_	_	_	_	_	_	_	ANSB8	_	_	_	_	ANSB3	ANSB2	ANSB1	ANSB0	010F

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-55: PORTC REGISTER MAP FOR PIC24EPXXXGP/MC204 AND dsPIC33EPXXXGP/MC204/504 DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISC	0E20	_	_	_	_	_	-	TRISC9	TRISC8	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	03FF
PORTC	0E22	-	_		_		1	RC9	RC8	RC7	RC6	RC5	RC4	RC3	RC2	RC1	RC0	xxxx
LATC	0E24	-	_		_		1	LATC9	LATC8	LATC7	LATC6	LATC5	LATC4	LATC3	LATC2	LATC1	LATC0	xxxx
ODCC	0E26	_	_	ı		ı	-	ODCC9	ODCC8	ODCC7	ODCC6	ODCC5	ODCC4	ODCC3	ODCC2	ODCC1	ODCC0	0000
CNENC	0E28	-	_		_		1	CNIEC9	CNIEC8	CNIEC7	CNIEC6	CNIEC5	CNIEC4	CNIEC3	CNIEC2	CNIEC1	CNIEC0	0000
CNPUC	0E2A	-	_	-	-	-	_	CNPUC9	CNPUC8	CNPUC7	CNPUC6	CNPUC5	CNPUC4	CNPUC3	CNPUC2	CNPUC1	CNPUC0	0000
CNPDC	0E2C	-	_	-	_	_	_	CNPDC9	CNPDC8	CNPDC7	CNPDC6	CNPDC5	CNPDC4	CNPDC3	CNPDC2	CNPDC1	CNPDC0	0000
ANSELC	0E2E	_	_	_	_	_	_	_	_	_	_	_	_	_	ANSC2	ANSC1	ANSC0	0007

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

4.5 Instruction Addressing Modes

The addressing modes shown in Table 4-63 form the basis of the addressing modes optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions differ from those in the other instruction types.

4.5.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (Near Data Space). Most file register instructions employ a working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file register or WREG (with the exception of the MUL instruction), which writes the result to a register or register pair. The MOV instruction allows additional flexibility and can access the entire Data Space.

4.5.2 MCU INSTRUCTIONS

The three-operand MCU instructions are of the form:

Operand 3 = Operand 1 <function> Operand 2 where Operand 1 is always a working register (that is, the addressing mode can only be Register Direct), which is referred to as Wb. Operand 2 can be a W register fetched from data memory or a 5-bit literal. The result location can either be a W register or a data memory location. The following addressing modes are supported by MCU instructions:

- · Register Direct
- · Register Indirect
- · Register Indirect Post-Modified
- · Register Indirect Pre-Modified
- 5-Bit or 10-Bit Literal

Note: Not all instructions support all the addressing modes given above. Individual instructions can support different subsets of these addressing modes.

TABLE 4-63: FUNDAMENTAL ADDRESSING MODES SUPPORTED

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn form the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn form the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

5.2 RTSP Operation

RTSP allows the user application to erase a single page of memory and to program two instruction words at a time. See the General Purpose and Motor Control Family tables (Table 1 and Table 2, respectively) for the page sizes of each device.

For more information on erasing and programming Flash memory, refer to "Flash Programming" (DS70609) in the "dsPIC33/PIC24 Family Reference Manual".

5.3 Programming Operations

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. The processor stalls (waits) until the programming operation is finished.

For erase and program times, refer to Parameters D137a and D137b (Page Erase Time), and D138a and D138b (Word Write Cycle Time) in Table 30-14 in **Section 30.0 "Electrical Characteristics"**.

Setting the WR bit (NVMCON<15>) starts the operation and the WR bit is automatically cleared when the operation is finished.

5.3.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program two adjacent words (24 bits x 2) of program Flash memory at a time on every other word address boundary (0x000002, 0x000006, 0x000000A, etc.). To do this, it is necessary to erase the page that contains the desired address of the location the user wants to change.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPS

Refer to **Flash Programming**" (DS70609) in the "dsPIC33/PIC24 Family Reference Manual" for details and codes examples on programming using RTSP.

5.4 Flash Memory Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note: In the event you are not able to access the product page using the link above, enter this URL in your browser:
http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en555464

5.4.1 KEY RESOURCES

- "Flash Programming" (DS70609) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- · Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- · Development Tools

5.5 Control Registers

Four SFRs are used to erase and write the program Flash memory: NVMCON, NVMKEY, NVMADRH and NVMADRL.

The NVMCON register (Register 5-1) enables and initiates Flash memory erase and write operations.

NVMKEY (Register 5-4) is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register.

There are two NVM Address registers: NVMADRH and NVMADRL. These two registers, when concatenated, form the 24-bit Effective Address (EA) of the selected word for programming operations or the selected page for erase operations.

The NVMADRH register is used to hold the upper 8 bits of the EA, while the NVMADRL register is used to hold the lower 16 bits of the EA.

REGISTER 8-13: DMALCA: DMA LAST CHANNEL ACTIVE STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_		_		_		_
bit 15							bit 8

U-0	U-0	U-0	U-0	R-1	R-1	R-1	R-1
_	_	_	_		LSTCH	1<3:0>	
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-4 Unimplemented: Read as '0'

bit 3-0 LSTCH<3:0>: Last DMAC Channel Active Status bits

1111 = No DMA transfer has occurred since system Reset

1110 = Reserved

•

•

•

0100 = Reserved

0011 = Last data transfer was handled by Channel 3

0010 = Last data transfer was handled by Channel 2

0001 = Last data transfer was handled by Channel 1

0000 = Last data transfer was handled by Channel 0

9.1 CPU Clocking System

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X family of devices provides six system clock options:

- · Fast RC (FRC) Oscillator
- FRC Oscillator with Phase Locked Loop (PLL)
- · FRC Oscillator with Postscaler
- · Primary (XT, HS or EC) Oscillator
- · Primary Oscillator with PLL
- · Low-Power RC (LPRC) Oscillator

Instruction execution speed or device operating frequency, Fcy, is given by Equation 9-1.

EQUATION 9-1: DEVICE OPERATING FREQUENCY

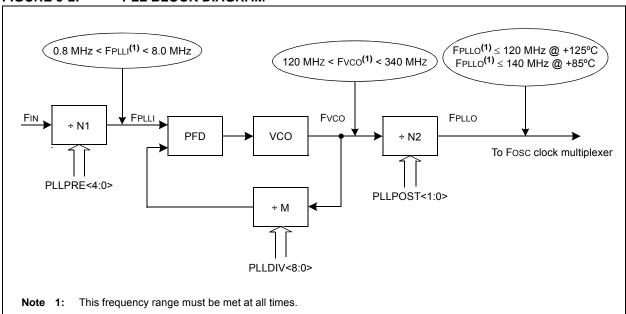
$$FCY = Fosc/2$$

Figure 9-2 is a block diagram of the PLL module.

Equation 9-2 provides the relationship between input frequency (FIN) and output frequency (FPLLO). In clock modes S1 and S3, when the PLL output is selected, FOSC = FPLLO.

Equation 9-3 provides the relationship between input frequency (FIN) and VCO frequency (FVCO).

FIGURE 9-2: PLL BLOCK DIAGRAM



EQUATION 9-2: FPLLO CALCULATION

$$FPLLO = FIN \times \left(\frac{M}{N1 \times N2}\right) = FIN \times \left(\frac{(PLLDIV + 2)}{(PLLPRE + 2) \times 2(PLLPOST + 1)}\right)$$

Where:

N1 = PLLPRE + 2

 $N2 = 2 \times (PLLPOST + 1)$

M = PLLDIV + 2

EQUATION 9-3: Fvco CALCULATION

$$Fvco = Fin \times \left(\frac{M}{N1}\right) = Fin \times \left(\frac{(PLLDIV + 2)}{(PLLPRE + 2)}\right)$$

REGISTER 11-9: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15 (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_				HOME1R<6:0)>		
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_				INDX1R<6:0	>		
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-8 **HOME1R<6:0>:** Assign QEI1 HOME1 (HOME1) to the Corresponding RPn Pin bits

(see Table 11-2 for input pin selection numbers)

1111001 = Input tied to RPI121

.

0000001 = Input tied to CMP1 0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'

bit 6-0 IND1XR<6:0>: Assign QEI1 INDEX1 (INDX1) to the Corresponding RPn Pin bits

(see Table 11-2 for input pin selection numbers)

1111001 = Input tied to RPI121

.

0000001 = Input tied to CMP1 0000000 = Input tied to Vss

21.4 ECAN Control Registers

REGISTER 21-1: CxCTRL1: ECANx CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0
_	_	CSIDL	ABAT	CANCKS	REQOP2	REQOP1	REQOP0
bit 15							bit 8

R-1	R-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0		
OPMODE2	OPMODE1	OPMODE0	_	CANCAP	_	_	WIN		
bit 7									

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 CSIDL: ECANx Stop in Idle Mode bit

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12 ABAT: Abort All Pending Transmissions bit

1 = Signals all transmit buffers to abort transmission

0 = Module will clear this bit when all transmissions are aborted

bit 11 CANCKS: ECANx Module Clock (FCAN) Source Select bit

1 = FCAN is equal to 2 * FP

0 = FCAN is equal to FP

bit 10-8 **REQOP<2:0>:** Request Operation Mode bits

111 = Set Listen All Messages mode

110 = Reserved

101 = Reserved

100 = Set Configuration mode

011 = Set Listen Only mode

010 = Set Loopback mode

001 = Set Disable mode

000 = Set Normal Operation mode

bit 7-5 **OPMODE<2:0>**: Operation Mode bits

111 = Module is in Listen All Messages mode

110 = Reserved

101 = Reserved

100 = Module is in Configuration mode

011 = Module is in Listen Only mode

010 = Module is in Loopback mode

001 = Module is in Disable mode

000 = Module is in Normal Operation mode

bit 4 Unimplemented: Read as '0'

bit 3 CANCAP: CAN Message Receive Timer Capture Event Enable bit

1 = Enables input capture based on CAN message receive

0 = Disables CAN capture

bit 2-1 **Unimplemented:** Read as '0'

bit 0 WIN: SFR Map Window Select bit

1 = Uses filter window

0 = Uses buffer window

REGISTER 21-17: CxRXFnEID: ECANx ACCEPTANCE FILTER n EXTENDED IDENTIFIER REGISTER (n = 0-15)

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
EID15	EID14	EID13	EID12	EID11	EID10	EID9	EID8
bit 15							bit 8

| R/W-x |
|-------|-------|-------|-------|-------|-------|-------|-------|
| EID7 | EID6 | EID5 | EID4 | EID3 | EID2 | EID1 | EID0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-0 **EID<15:0>:** Extended Identifier bits

1 = Message address bit, EIDx, must be '1' to match filter

0 = Message address bit, EIDx, must be '0' to match filter

REGISTER 21-18: CxFMSKSEL1: ECANx FILTER 7-0 MASK SELECTION REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F7MSK<1:0>		F6MSK<1:0>		F5MSK<1:0>		F4MSK<1:0>	
bit 15				•		•	bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
F3MSK<1:0>		F2MSK<1:0>		F1MSK<1:0>		F0MSK<1:0>	
bit 7							bit 0

Legend:

bit 3-2

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-14 F7MSK<1:0>: Mask Source for Filter 7 bits

11 = Reserved

10 = Acceptance Mask 2 registers contain mask

01 = Acceptance Mask 1 registers contain mask

00 = Acceptance Mask 0 registers contain mask

bit 13-12 **F6MSK<1:0>:** Mask Source for Filter 6 bits (same values as bits<15:14>)

bit 11-10 **F5MSK<1:0>:** Mask Source for Filter 5 bits (same values as bits<15:14>)

bit 9-8 **F4MSK<1:0>:** Mask Source for Filter 4 bits (same values as bits<15:14>)

bit 7-6 **F3MSK<1:0>:** Mask Source for Filter 3 bits (same values as bits<15:14>)

bit 5-4 **F2MSK<1:0>:** Mask Source for Filter 2 bits (same values as bits<15:14>)

F1MSK<1:0>: Mask Source for Filter 1 bits (same values as bits<15:14>)

bit 1-0 **F0MSK<1:0>:** Mask Source for Filter 0 bits (same values as bits<15:14>)

REGISTER 23-2: AD1CON2: ADC1 CONTROL REGISTER 2 (CONTINUED)

bit 1 BUFM: Buffer Fill Mode Select bit

- 1 = Starts the buffer filling the first half of the buffer on the first interrupt and the second half of the buffer on next interrupt
- 0 = Always starts filling the buffer from the start address.
- bit 0 ALTS: Alternate Input Sample Mode Select bit
 - 1 = Uses channel input selects for Sample MUXA on first sample and Sample MUXB on next sample
 - 0 = Always uses channel input selects for Sample MUXA

TABLE 24-1: PTG STEP COMMAND FORMAT (CONTINUED)

bit 3-0	Step Command	OPTION<3:0>	Option Description
	PTGCTRL(1)	0000	Reserved.
		0001	Reserved.
		0010	Disable Step Delay Timer (PTGSD).
		0011	Reserved.
		0100	Reserved.
		0101	Reserved.
		0110	Enable Step Delay Timer (PTGSD).
		0111	Reserved.
		1000	Start and wait for the PTG Timer0 to match the Timer0 Limit Register.
		1001	Start and wait for the PTG Timer1 to match the Timer1 Limit Register.
		1010	Reserved.
		1011	Wait for the software trigger bit transition from low-to-high before continuing (PTGSWT = 0 to 1).
		1100	Copy contents of the Counter 0 register to the AD1CHS0 register.
		1101	Copy contents of the Counter 1 register to the AD1CHS0 register.
		1110	Copy contents of the Literal 0 register to the AD1CHS0 register.
		1111	Generate triggers indicated in the Broadcast Trigger Enable register (PTGBTE).
	PTGADD(1)	0000	Add contents of the PTGADJ register to the Counter 0 Limit register (PTGC0LIM).
		0001	Add contents of the PTGADJ register to the Counter 1 Limit register (PTGC1LIM).
		0010	Add contents of the PTGADJ register to the Timer0 Limit register (PTGT0LIM).
		0011	Add contents of the PTGADJ register to the Timer1 Limit register (PTGT1LIM).
		0100	prop:prop:prop:prop:prop:prop:prop:prop
		0101	Add contents of the PTGADJ register to the Literal 0 register (PTGL0).
		0110	Reserved.
		0111	Reserved.
	PTGCOPY ⁽¹⁾	1000	Copy contents of the PTGHOLD register to the Counter 0 Limit register (PTGC0LIM).
		1001	Copy contents of the PTGHOLD register to the Counter 1 Limit register (PTGC1LIM).
		1010	Copy contents of the PTGHOLD register to the Timer0 Limit register (PTGT0LIM).
		1011	Copy contents of the PTGHOLD register to the Timer1 Limit register (PTGT1LIM).
		1100	Copy contents of the PTGHOLD register to the Step Delay Limit register (PTGSDLIM).
		1101	Copy contents of the PTGHOLD register to the Literal 0 register (PTGL0).
		1110	Reserved.
		1111	Reserved.

Note 1: All reserved commands or options will execute but have no effect (i.e., execute as a NOP instruction).

^{2:} Refer to Table 24-2 for the trigger output descriptions.

^{3:} This feature is only available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices.

TABLE 27-1: CONFIGURATION BYTE REGISTER MAP

File Name	Address	Device Memory Size (Kbytes)	Bits 23-8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	0057EC	32									
	00AFEC	64									
	0157EC	128	_	_	_	_	_	_	_	_	-
	02AFEC	256									
	0557EC	512									
Reserved	0057EE	32									
	00AFEE	64									
	0157EE	128	_	_	_	_	_	_	_	_	_
	02AFEE	256									
	0557EE	512									
FICD	0057F0	32									
	00AFF0	64									
	0157F0	128	i _	Reserved ⁽³⁾	_	JTAGEN	Reserved ⁽²⁾	Reserved ⁽³⁾	_	ICS<	:1:0>
	02AFF0	256						reserved			
	0557F0	512									
FPOR	0057F2	32									
	00AFF2	64									
	0157F2	128	_	WDTV	VIN<1:0>	ALTI2C2	ALTI2C1	Reserved ⁽³⁾) _ _		_
	02AFF2	256									
	0557F2	512									
FWDT	0057F4	32									
	00AFF4	64									
	0157F4	128	_	FWDTEN	WINDIS	PLLKEN	WDTPRE		WDTPOST<3:0>		
	02AFF4	256									
	0557F4	512									
FOSC	0057F6	32									
	00AFF6	64									
	0157F6	128	_	FCKS	SM<1:0>	IOL1WAY	_	_	OSCIOFNC	POSCM	ID<1:0>
	02AFF6	256				.02			000.01.110		
	0557F6	512									
FOSCSEL	0057F8	32									
	00AFF8	64									
	0157F8	128	_	IESO	PWMLOCK ⁽¹⁾	_	_	_	F	NOSC<2:0>	
	02AFF8	256									
	0557F8	512									
FGS	0057FA	32									
	00AFFA	64									
	0157FA	128	_	_	_	_	_	_	_	GCP	GWRP
	02AFFA	256									
	0557FA	512									
Reserved	0057FC	32									
	00AFFC	64									
	0157FC	128	_	_	_	_	_	_	_	_	_
	02AFFC	256									
	0557FC	512									
Reserved	057FFE	32									
	00AFFE	64									
	0157FE	128	_	_	_	_	_	_			_
	02AFFE	256									_
	0557FE	512									
l amandi			read as '1'.								

Legend: — = unimplemented, read as '1'.

Note 1: This bit is only available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices.

^{2:} This bit is reserved and must be programmed as '0'.

^{3:} These bits are reserved and must be programmed as '1'.

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

.,,,	_L Z0-Z.		COCTION SET OVERVIEW	(CONTINUED)						
Base Instr #	Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles ⁽²⁾	Status Flags Affected			
9	BTG	BTG	f,#bit4	Bit Toggle f	1	1	None			
		BTG	Ws,#bit4	Bit Toggle Ws	1	1	None			
10	BTSC	BTSC	f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None			
		BTSC	Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None			
11	BTSS	BTSS	f,#bit4	Bit Test f, Skip if Set	1	1 (2 or 3)	None			
		BTSS	Ws,#bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None			
12	BTST	BTST	f,#bit4	Bit Test f	1	1	Z			
		BTST.C	Ws,#bit4	Bit Test Ws to C	1	1	С			
		BTST.Z	Ws,#bit4	Bit Test Ws to Z	1	1	Z			
		BTST.C	Ws,Wb	Bit Test Ws <wb> to C</wb>	1	1	С			
		BTST.Z	Ws,Wb	Bit Test Ws <wb> to Z</wb>	1	1	Z			
13	BTSTS	BTSTS	f,#bit4	Bit Test then Set f	1	1	Z			
		BTSTS.C	Ws,#bit4	Bit Test Ws to C, then Set	1	1	С			
		BTSTS.Z	Ws,#bit4	Bit Test Ws to Z, then Set	1	1	Z			
14	CALL	CALL	lit23	Call subroutine	2	4	SFA			
		CALL	Wn	Call indirect subroutine	1	4	SFA			
		CALL.L	Wn	Call indirect subroutine (long address)	1	4	SFA			
15	CLR	CLR	f	f = 0x0000	1	1	None			
		CLR	WREG	WREG = 0x0000	1	1	None			
		CLR	Ws	Ws = 0x0000	1	1	None			
		CLR	Acc, Wx, Wxd, Wy, Wyd, AWB ⁽¹⁾	Clear Accumulator	1	1	OA,OB,SA,SB			
16	CLRWDT	CLRWDT		Clear Watchdog Timer	1	1	WDTO,Sleep			
17	COM	COM	f	f = Ī	1	1	N,Z			
		COM	f,WREG	WREG = f	1	1	N,Z			
		COM	Ws, Wd	Wd = Ws	1	1	N,Z			
18	CP	CP	f	Compare f with WREG	1	1	C,DC,N,OV,Z			
		CP	Wb,#lit8	Compare Wb with lit8	1	1	C,DC,N,OV,Z			
		CP	Wb,Ws	Compare Wb with Ws (Wb – Ws)	1	1	C,DC,N,OV,Z			
19	CP0	CP0	f	Compare f with 0x0000	1	1	C,DC,N,OV,Z			
		CP0	Ws	Compare Ws with 0x0000	1	1	C,DC,N,OV,Z			
20	CPB	CPB	f	Compare f with WREG, with Borrow	1	1	C,DC,N,OV,Z			
		CPB	Wb,#lit8	Compare Wb with lit8, with Borrow	1	1	C,DC,N,OV,Z			
		CPB	Wb,Ws	Compare Wb with Ws, with Borrow (Wb – Ws – C)	1	1	C,DC,N,OV,Z			
21	CPSEQ	CPSEQ	Wb,Wn	Compare Wb with Wn, skip if =	1	1 (2 or 3)	None			
	CPBEQ	CPBEQ	Wb,Wn,Expr	Compare Wb with Wn, branch if =	1	1 (5)	None			
22	CPSGT	CPSGT	Wb,Wn	Compare Wb with Wn, skip if >	1	1 (2 or 3)	None			
	CPBGT	CPBGT	Wb,Wn,Expr	Compare Wb with Wn, branch if >	1	1 (5)	None			
23	CPSLT	CPSLT	Wb,Wn	Compare Wb with Wn, skip if <	1	1 (2 or 3)	None			
	CPBLT	CPBLT	Wb,Wn,Expr	Compare Wb with Wn, branch if <	1	1 (5)	None			
24	CPSNE	CPSNE	Wb,Wn	Compare Wb with Wn, skip if ≠	1	1 (2 or 3)	None			
	CPBNE	CPBNE	Wb,Wn,Expr	Compare Wb with Wn, branch if ≠	1	1 (5)	None			

Note 1: These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

^{2:} Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

30.2 AC Characteristics and Timing Parameters

This section defines dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X AC characteristics and timing parameters.

TABLE 30-15: TEMPERATURE AND VOLTAGE SPECIFICATIONS - AC

	Standard Operating Conditions: 3.0V to 3.6V					
	(unless otherwise stated)					
AC CHARACTERISTICS	Operating temperature -40°C ≤ Ta ≤ +85°C for Industrial					
AC CHARACTERISTICS	-40°C ≤ Ta ≤ +125°C for Extended					
	Operating voltage VDD range as described in Section 30.1 "DC					
	Characteristics".					

FIGURE 30-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

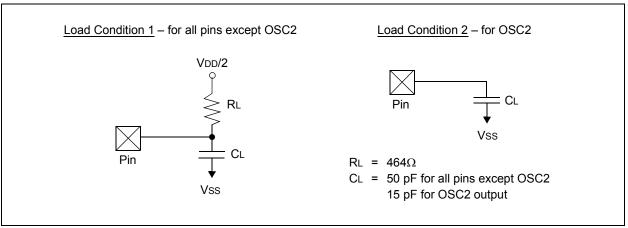
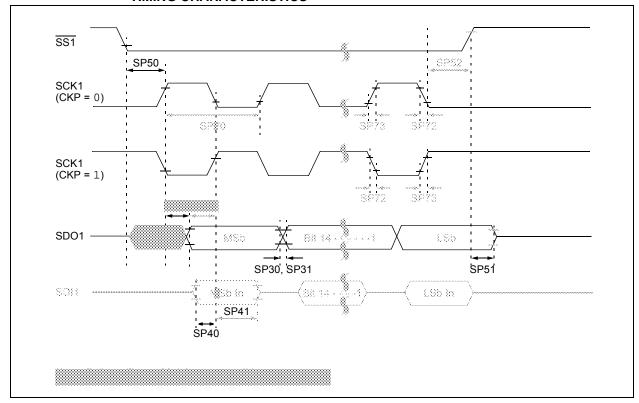


TABLE 30-16: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

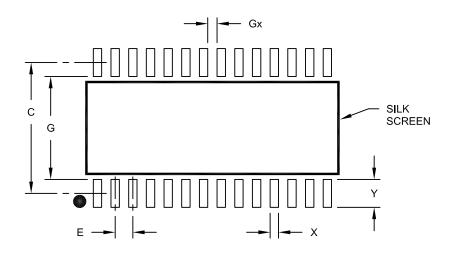
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions
DO50	Cosco	OSC2 Pin	_	_	15	pF	In XT and HS modes, when external clock is used to drive OSC1
DO56	Сю	All I/O Pins and OSC2	_	_	50	pF	EC mode
DO58	Св	SCLx, SDAx	_	_	400	pF	In I ² C™ mode

FIGURE 30-29: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS



28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	Е		1.27 BSC	
Contact Pad Spacing	С		9.40	
Contact Pad Width (X28)	Х			0.60
Contact Pad Length (X28)	Υ			2.00
Distance Between Pads	Gx	0.67		
Distance Between Pads	G	7.40		

Notes:

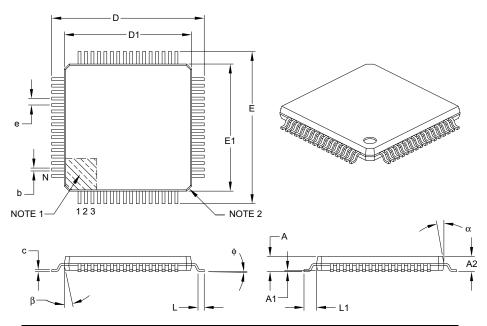
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A

64-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS			
	Dimension Limits	MIN	NOM	MAX	
Number of Leads	N		64		
Lead Pitch	е		0.50 BSC		
Overall Height	Α	_	-	1.20	
Molded Package Thickness	A2	0.95	1.00	1.05	
Standoff	A1	0.05	_	0.15	
Foot Length	L	0.45	0.60	0.75	
Footprint	L1	1.00 REF			
Foot Angle	ф	0°	3.5°	7°	
Overall Width	E		12.00 BSC		
Overall Length	D		12.00 BSC		
Molded Package Width	E1		10.00 BSC		
Molded Package Length	D1		10.00 BSC		
Lead Thickness	С	0.09	_	0.20	
Lead Width	b	0.17	0.22	0.27	
Mold Draft Angle Top	α	11°	12°	13°	
Mold Draft Angle Bottom	β	11°	12°	13°	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Chamfers at corners are optional; size may vary.
- 3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-085B