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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	64KB (22K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VFTLA Exposed Pad
Supplier Device Package	44-VTLA (6x6)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep64mc204t-e-tl">https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep64mc204t-e-tl</a>

### 3.0 CPU

**Note 1:** This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**CPU**” (DS70359) in the “*dsPIC33/PIC24 Family Reference Manual*”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for digital signal processing. The CPU has a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M x 24 bits of user program memory space.

An instruction prefetch mechanism helps maintain throughput and provides predictable execution. Most instructions execute in a single-cycle effective execution rate, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction, PSV accesses and the table instructions. Overhead-free program loop constructs are supported using the DO and REPEAT instructions, both of which are interruptible at any point.

#### 3.1 Registers

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X devices have sixteen, 16-bit working registers in the programmer's model. Each of the working registers can act as a data, address or address offset register. The 16th working register (W15) operates as a Software Stack Pointer for interrupts and calls.

#### 3.2 Instruction Set

The instruction set for dsPIC33EPXXXGP50X and dsPIC33EPXXXMC20X/50X devices has two classes of instructions: the MCU class of instructions and the DSP class of instructions. The instruction set for PIC24EPXXXGP/MC20X devices has the MCU class of instructions only and does not support DSP instructions. These two instruction classes are seamlessly integrated into the architecture and execute from a single execution unit. The instruction set includes many addressing modes and was designed for optimum C compiler efficiency.

### 3.3 Data Space Addressing

The base Data Space can be addressed as 64 Kbytes (32K words).

The Data Space includes two ranges of memory, referred to as X and Y data memory. Each memory range is accessible through its own independent Address Generation Unit (AGU). The MCU class of instructions operates solely through the X memory AGU, which accesses the entire memory map as one linear Data Space. On dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices, certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y Data Spaces have memory locations that are device-specific, and are described further in the data memory maps in **Section 4.2 “Data Address Space”**.

The upper 32 Kbytes of the Data Space memory map can optionally be mapped into Program Space (PS) at any 32-Kbyte aligned program word boundary. The Program-to-Data Space mapping feature, known as Program Space Visibility (PSV), lets any instruction access Program Space as if it were Data Space. Moreover, the Base Data Space address is used in conjunction with a Read or Write Page register (DSRPAG or DSWPAG) to form an Extended Data Space (EDS) address. The EDS can be addressed as 8M words or 16 Mbytes. Refer to the “**Data Memory**” (DS70595) and “**Program Memory**” (DS70613) sections in the “*dsPIC33/PIC24 Family Reference Manual*” for more details on EDS, PSV and table accesses.

On the dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices, overhead-free circular buffers (Modulo Addressing) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. The X AGU Circular Addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data re-ordering for radix-2 FFT algorithms. PIC24EPXXXGP/MC20X devices do not support Modulo and Bit-Reversed Addressing.

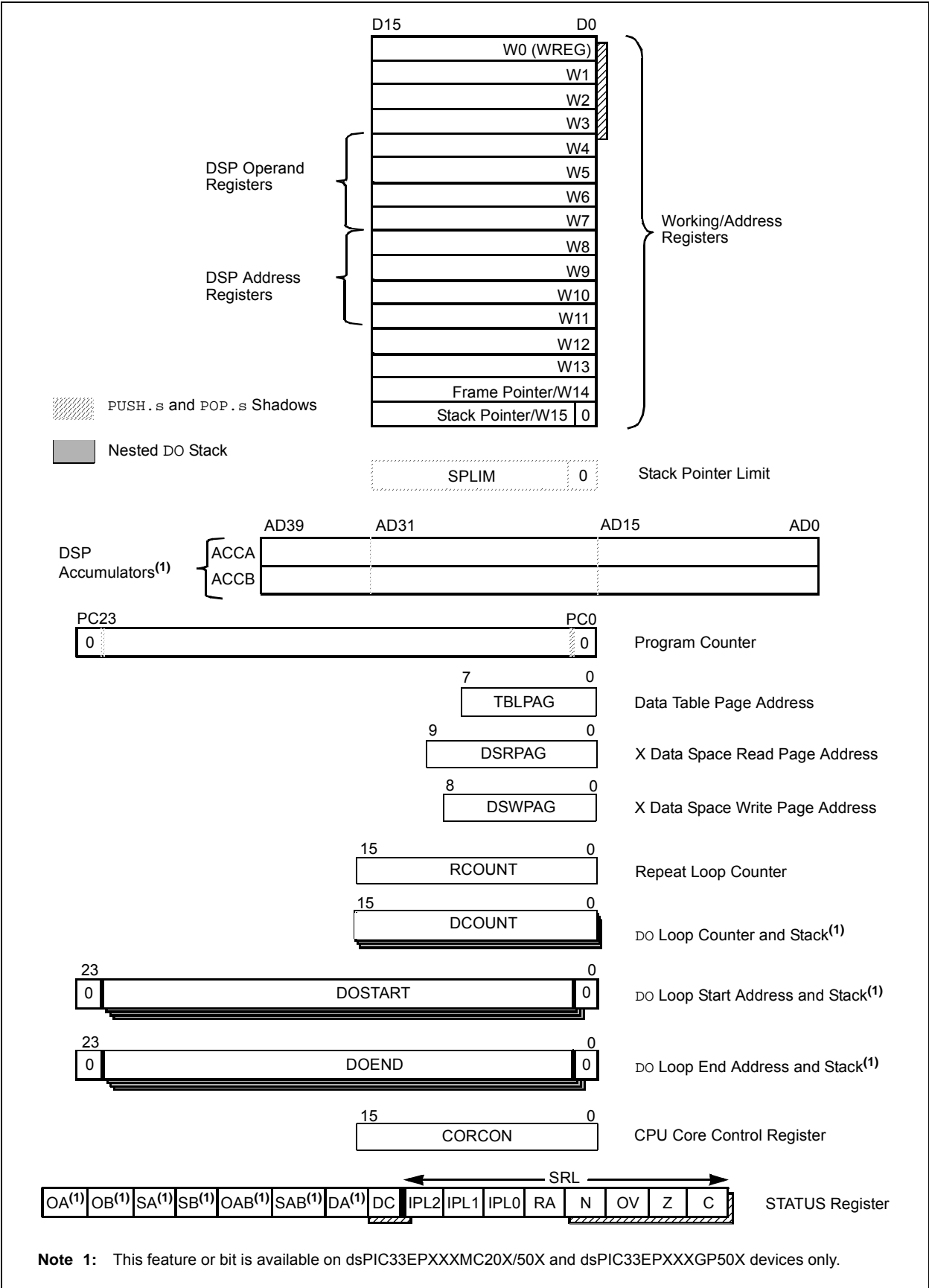
#### 3.4 Addressing Modes

The CPU supports these addressing modes:

- Inherent (no operand)
- Relative
- Literal
- Memory Direct
- Register Direct
- Register Indirect

Each instruction is associated with a predefined addressing mode group, depending upon its functional requirements. As many as six addressing modes are supported for each instruction.

FIGURE 3-2: PROGRAMMER'S MODEL



**REGISTER 3-2: CORCON: CORE CONTROL REGISTER (CONTINUED)**

- bit 2      **SFA:** Stack Frame Active Status bit  
1 = Stack frame is active; W14 and W15 address 0x0000 to 0xFFFF, regardless of DSRPAG and DSWPAG values  
0 = Stack frame is not active; W14 and W15 address of EDS or Base Data Space
- bit 1      **RND:** Rounding Mode Select bit<sup>(1)</sup>  
1 = Biased (conventional) rounding is enabled  
0 = Unbiased (convergent) rounding is enabled
- bit 0      **IF:** Integer or Fractional Multiplier Mode Select bit<sup>(1)</sup>  
1 = Integer mode is enabled for DSP multiply  
0 = Fractional mode is enabled for DSP multiply

- Note 1:** This bit is available on dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices only.  
**2:** This bit is always read as '0'.  
**3:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

**TABLE 4-45: DMAC REGISTER MAP**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
DMA0CON	0B00	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA0REQ	0B02	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>									00FF
DMA0STAL	0B04	STA<15:0>																	0000
DMA0STAH	0B06	—	—	—	—	—	—	—	—	STA<23:16>									0000
DMA0STBL	0B08	STB<15:0>																	0000
DMA0STBH	0B0A	—	—	—	—	—	—	—	—	STB<23:16>									0000
DMA0PAD	0B0C	PAD<15:0>																	0000
DMA0CNT	0B0E	—	—	CNT<13:0>															0000
DMA1CON	0B10	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA1REQ	0B12	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>									00FF
DMA1STAL	0B14	STA<15:0>																	0000
DMA1STAH	0B16	—	—	—	—	—	—	—	—	STA<23:16>									0000
DMA1STBL	0B18	STB<15:0>																	0000
DMA1STBH	0B1A	—	—	—	—	—	—	—	—	STB<23:16>									0000
DMA1PAD	0B1C	PAD<15:0>																	0000
DMA1CNT	0B1E	—	—	CNT<13:0>															0000
DMA2CON	0B20	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA2REQ	0B22	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>									00FF
DMA2STAL	0B24	STA<15:0>																	0000
DMA2STAH	0B26	—	—	—	—	—	—	—	—	STA<23:16>									0000
DMA2STBL	0B28	STB<15:0>																	0000
DMA2STBH	0B2A	—	—	—	—	—	—	—	—	STB<23:16>									0000
DMA2PAD	0B2C	PAD<15:0>																	0000
DMA2CNT	0B2E	—	—	CNT<13:0>															0000
DMA3CON	0B30	CHEN	SIZE	DIR	HALF	NULLW	—	—	—	—	—	AMODE<1:0>		—	—	MODE<1:0>		0000	
DMA3REQ	0B32	FORCE	—	—	—	—	—	—	—	IRQSEL<7:0>									00FF
DMA3STAL	0B34	STA<15:0>																	0000
DMA3STAH	0B36	—	—	—	—	—	—	—	—	STA<23:16>									0000
DMA3STBL	0B38	STB<15:0>																	0000
DMA3STBH	0B3A	—	—	—	—	—	—	—	—	STB<23:16>									0000
DMA3PAD	0B3C	PAD<15:0>																	0000
DMA3CNT	0B3E	—	—	CNT<13:0>															0000
DMA3PWC	0BF0	—	—	—	—	—	—	—	—	—	—	—	—	PWCOL3	PWCOL2	PWCOL1	PWCOL0	0000	
DMA3RQC	0BF2	—	—	—	—	—	—	—	—	—	—	—	—	RQCOL3	RQCOL2	RQCOL1	RQCOL0	0000	
DMA3PPS	0BF4	—	—	—	—	—	—	—	—	—	—	—	—	PPST3	PPST2	PPST1	PPST0	0000	
DMA3LCA	0BF6	—	—	—	—	—	—	—	—	—	—	—	—	LSTCH<3:0>				000F	
DSADRL	0BF8	DSADR<15:0>																	0000
DSADRH	0BFA	—	—	—	—	—	—	—	—	DSADR<23:16>									0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-59: PORTA REGISTER MAP FOR PIC24EPXXXGP/MC202 AND dsPIC33EPXXXGP/MC202/502 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	0E00	—	—	—	—	—	—	—	—	—	—	—	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	001F
PORTA	0E02	—	—	—	—	—	—	—	—	—	—	—	RA4	RA3	RA2	RA1	RA0	0000
LATA	0E04	—	—	—	—	—	—	—	—	—	—	—	LATA4	LATA3	LATA2	LA1TA1	LA0TA0	0000
ODCA	0E06	—	—	—	—	—	—	—	—	—	—	—	ODCA4	ODCA3	ODCA2	ODCA1	ODCA0	0000
CNENA	0E08	—	—	—	—	—	—	—	—	—	—	—	CNIEA4	CNIEA3	CNIEA2	CNIEA1	CNIEA0	0000
CNPUA	0E0A	—	—	—	—	—	—	—	—	—	—	—	CNPUA4	CNPUA3	CNPUA2	CNPUA1	CNPUA0	0000
CNPDA	0E0C	—	—	—	—	—	—	—	—	—	—	—	CNPDA4	CNPDA3	CNPDA2	CNPDA1	CNPDA0	0000
ANSELA	0E0E	—	—	—	—	—	—	—	—	—	—	—	ANSA4	—	—	ANSA1	ANSA0	0013

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-60: PORTB REGISTER MAP FOR PIC24EPXXXGP/MC202 AND dsPIC33EPXXXGP/MC202/502 DEVICES ONLY**

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	0E12	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	0E14	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	0E16	ODCB15	ODCB14	ODCB13	ODCB12	ODCB11	ODCB10	ODCB9	ODCB8	ODCB7	ODCB6	ODCB5	ODCB4	ODCB3	ODCB2	ODCB1	ODCB0	0000
CNENB	0E18	CNIEB15	CNIEB14	CNIEB13	CNIEB12	CNIEB11	CNIEB10	CNIEB9	CNIEB8	CNIEB7	CNIEB6	CNIEB5	CNIEB4	CNIEB3	CNIEB2	CNIEB1	CNIEB0	0000
CNPUB	0E1A	CNPUB15	CNPUB14	CNPUB13	CNPUB12	CNPUB11	CNPUB10	CNPUB9	CNPUB8	CNPUB7	CNPUB6	CNPUB5	CNPUB4	CNPUB3	CNPUB2	CNPUB1	CNPUB0	0000
CNPDB	0E1C	CNPDB15	CNPDB14	CNPDB13	CNPDB12	CNPDB11	CNPDB10	CNPDB9	CNPDB8	CNPDB7	CNPDB6	CNPDB5	CNPDB4	CNPDB3	CNPDB2	CNPDB1	CNPDB0	0000
ANSELB	0E1E	—	—	—	—	—	—	—	ANSB8	—	—	—	—	ANSB3	ANSB2	ANSB1	ANSB0	010F

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

## 4.5 Instruction Addressing Modes

The addressing modes shown in Table 4-63 form the basis of the addressing modes optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions differ from those in the other instruction types.

### 4.5.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (Near Data Space). Most file register instructions employ a working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file register or WREG (with the exception of the `MUL` instruction), which writes the result to a register or register pair. The `MOV` instruction allows additional flexibility and can access the entire Data Space.

### 4.5.2 MCU INSTRUCTIONS

The three-operand MCU instructions are of the form:

Operand 3 = Operand 1 <function> Operand 2

where Operand 1 is always a working register (that is, the addressing mode can only be Register Direct), which is referred to as Wb. Operand 2 can be a W register fetched from data memory or a 5-bit literal. The result location can either be a W register or a data memory location. The following addressing modes are supported by MCU instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-Modified
- Register Indirect Pre-Modified
- 5-Bit or 10-Bit Literal

**Note:** Not all instructions support all the addressing modes given above. Individual instructions can support different subsets of these addressing modes.

**TABLE 4-63: FUNDAMENTAL ADDRESSING MODES SUPPORTED**

Addressing Mode	Description
File Register Direct	The address of the file register is specified explicitly.
Register Direct	The contents of a register are accessed directly.
Register Indirect	The contents of Wn form the Effective Address (EA).
Register Indirect Post-Modified	The contents of Wn form the EA. Wn is post-modified (incremented or decremented) by a constant value.
Register Indirect Pre-Modified	Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA.
Register Indirect with Register Offset (Register Indexed)	The sum of Wn and Wb forms the EA.
Register Indirect with Literal Offset	The sum of Wn and a literal forms the EA.

**REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
NSTDIS	OVAERR <sup>(1)</sup>	OVBERR <sup>(1)</sup>	COVAERR <sup>(1)</sup>	COVBERR <sup>(1)</sup>	OVATE <sup>(1)</sup>	OVBTE <sup>(1)</sup>	COVTE <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
SFTACERR <sup>(1)</sup>	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFail	—
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15            **NSTDIS:** Interrupt Nesting Disable bit  
                   1 = Interrupt nesting is disabled  
                   0 = Interrupt nesting is enabled
- bit 14            **OVAERR:** Accumulator A Overflow Trap Flag bit<sup>(1)</sup>  
                   1 = Trap was caused by overflow of Accumulator A  
                   0 = Trap was not caused by overflow of Accumulator A
- bit 13            **OVBERR:** Accumulator B Overflow Trap Flag bit<sup>(1)</sup>  
                   1 = Trap was caused by overflow of Accumulator B  
                   0 = Trap was not caused by overflow of Accumulator B
- bit 12            **COVAERR:** Accumulator A Catastrophic Overflow Trap Flag bit<sup>(1)</sup>  
                   1 = Trap was caused by catastrophic overflow of Accumulator A  
                   0 = Trap was not caused by catastrophic overflow of Accumulator A
- bit 11            **COVBERR:** Accumulator B Catastrophic Overflow Trap Flag bit<sup>(1)</sup>  
                   1 = Trap was caused by catastrophic overflow of Accumulator B  
                   0 = Trap was not caused by catastrophic overflow of Accumulator B
- bit 10            **OVATE:** Accumulator A Overflow Trap Enable bit<sup>(1)</sup>  
                   1 = Trap overflow of Accumulator A  
                   0 = Trap is disabled
- bit 9             **OVBTE:** Accumulator B Overflow Trap Enable bit<sup>(1)</sup>  
                   1 = Trap overflow of Accumulator B  
                   0 = Trap is disabled
- bit 8             **COVTE:** Catastrophic Overflow Trap Enable bit<sup>(1)</sup>  
                   1 = Trap on catastrophic overflow of Accumulator A or B is enabled  
                   0 = Trap is disabled
- bit 7             **SFTACERR:** Shift Accumulator Error Status bit<sup>(1)</sup>  
                   1 = Math error trap was caused by an invalid accumulator shift  
                   0 = Math error trap was not caused by an invalid accumulator shift
- bit 6             **DIV0ERR:** Divide-by-Zero Error Status bit  
                   1 = Math error trap was caused by a divide-by-zero  
                   0 = Math error trap was not caused by a divide-by-zero
- bit 5             **DMACERR:** DMAC Trap Flag bit  
                   1 = DMAC trap has occurred  
                   0 = DMAC trap has not occurred

**Note 1:** These bits are available on dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices only.



### 10.2.1 SLEEP MODE

The following occurs in Sleep mode:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption is reduced to a minimum, provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor does not operate, since the system clock source is disabled.
- The LPRC clock continues to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals can continue to operate. This includes items such as the Input Change Notification (ICN) on the I/O ports or peripherals that use an external clock input.
- Any peripheral that requires the system clock source for its operation is disabled.

The device wakes up from Sleep mode on any of these events:

- Any interrupt source that is individually enabled
- Any form of device Reset
- A WDT time-out

On wake-up from Sleep mode, the processor restarts with the same clock source that was active when Sleep mode was entered.

For optimal power savings, the internal regulator and the Flash regulator can be configured to go into Standby when Sleep mode is entered by clearing the VREGS (RCON<8>) and VREGSF (RCON<11>) bits (default configuration).

If the application requires a faster wake-up time, and can accept higher current requirements, the VREGS (RCON<8>) and VREGSF (RCON<11>) bits can be set to keep the internal regulator and the Flash regulator active during Sleep mode.

### 10.2.2 IDLE MODE

The following occurs in Idle mode:

- The CPU stops executing instructions.
- The WDT is automatically cleared.
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see **Section 10.4 “Peripheral Module Disable”**).
- If the WDT or FSCM is enabled, the LPRC also remains active.

The device wakes from Idle mode on any of these events:

- Any interrupt that is individually enabled
- Any device Reset
- A WDT time-out

On wake-up from Idle mode, the clock is reapplied to the CPU and instruction execution will begin (2-4 clock cycles later), starting with the instruction following the `PWRSV` instruction or the first instruction in the Interrupt Service Routine (ISR).

All peripherals also have the option to discontinue operation when Idle mode is entered to allow for increased power savings. This option is selectable in the control register of each peripheral; for example, the `TSIDL` bit in the Timer1 Control register (`T1CON<13>`).

### 10.2.3 INTERRUPTS COINCIDENT WITH POWER SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a `PWRSV` instruction is held off until entry into Sleep or Idle mode has completed. The device then wakes up from Sleep or Idle mode.

**REGISTER 16-7: PWMCONx: PWMx CONTROL REGISTER**

HS/HC-0	HS/HC-0	HS/HC-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLTSTAT <sup>(1)</sup>	CLSTAT <sup>(1)</sup>	TRGSTAT	FLTIEEN	CLIEEN	TRGIEEN	ITB <sup>(2)</sup>	MDCS <sup>(2)</sup>
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
DTC1	DTC0	DTCP <sup>(3)</sup>	—	MTBS	CAM <sup>(2,4)</sup>	XPRES <sup>(5)</sup>	IUE <sup>(2)</sup>
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit	HS = Hardware Settable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **FLTSTAT:** Fault Interrupt Status bit<sup>(1)</sup>  
 1 = Fault interrupt is pending  
 0 = No Fault interrupt is pending  
 This bit is cleared by setting FLTIEEN = 0.
- bit 14 **CLSTAT:** Current-Limit Interrupt Status bit<sup>(1)</sup>  
 1 = Current-limit interrupt is pending  
 0 = No current-limit interrupt is pending  
 This bit is cleared by setting CLIEEN = 0.
- bit 13 **TRGSTAT:** Trigger Interrupt Status bit  
 1 = Trigger interrupt is pending  
 0 = No trigger interrupt is pending  
 This bit is cleared by setting TRGIEEN = 0.
- bit 12 **FLTIEEN:** Fault Interrupt Enable bit  
 1 = Fault interrupt is enabled  
 0 = Fault interrupt is disabled and the FLTSTAT bit is cleared
- bit 11 **CLIEEN:** Current-Limit Interrupt Enable bit  
 1 = Current-limit interrupt is enabled  
 0 = Current-limit interrupt is disabled and the CLSTAT bit is cleared
- bit 10 **TRGIEEN:** Trigger Interrupt Enable bit  
 1 = A trigger event generates an interrupt request  
 0 = Trigger event interrupts are disabled and the TRGSTAT bit is cleared
- bit 9 **ITB:** Independent Time Base Mode bit<sup>(2)</sup>  
 1 = PHASEx register provides time base period for this PWM generator  
 0 = PTPER register provides timing for this PWM generator
- bit 8 **MDCS:** Master Duty Cycle Register Select bit<sup>(2)</sup>  
 1 = MDC register provides duty cycle information for this PWM generator  
 0 = PDCx register provides duty cycle information for this PWM generator

- Note 1:** Software must clear the interrupt status here and in the corresponding IFSx bit in the interrupt controller.
- 2:** These bits should not be changed after the PWMx is enabled (PTEN = 1).
- 3:** DTC<1:0> = 11 for DTCP to be effective; otherwise, DTCP is ignored.
- 4:** The Independent Time Base (ITB = 1) mode must be enabled to use Center-Aligned mode. If ITB = 0, the CAM bit is ignored.
- 5:** To operate in External Period Reset mode, the ITB bit must be '1' and the CLMOD bit in the FCLCONx register must be '0'.

**REGISTER 17-3: QE1STAT: QE1 STATUS REGISTER**

U-0	U-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0
—	—	PCHEQIRQ	PCHEQIEN	PCLEQIRQ	PCLEQIEN	POSOVIRQ	POSOVIEN
bit 15						bit 8	

HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0	HS, R/C-0	R/W-0
PCIIRQ <sup>(1)</sup>	PCIEN	VELOVIRQ	VELOVIEN	HOMIRQ	HOMIEN	IDXIRQ	IDXIEN
bit 7						bit 0	

<b>Legend:</b>	HS = Hardware Settable bit	C = Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **PCHEQIRQ:** Position Counter Greater Than or Equal Compare Status bit  
1 = POS1CNT ≥ QE1GEC  
0 = POS1CNT < QE1GEC
- bit 12 **PCHEQIEN:** Position Counter Greater Than or Equal Compare Interrupt Enable bit  
1 = Interrupt is enabled  
0 = Interrupt is disabled
- bit 11 **PCLEQIRQ:** Position Counter Less Than or Equal Compare Status bit  
1 = POS1CNT ≤ QE1LEC  
0 = POS1CNT > QE1LEC
- bit 10 **PCLEQIEN:** Position Counter Less Than or Equal Compare Interrupt Enable bit  
1 = Interrupt is enabled  
0 = Interrupt is disabled
- bit 9 **POSOVIRQ:** Position Counter Overflow Status bit  
1 = Overflow has occurred  
0 = No overflow has occurred
- bit 8 **POSOVIEN:** Position Counter Overflow Interrupt Enable bit  
1 = Interrupt is enabled  
0 = Interrupt is disabled
- bit 7 **PCIIRQ:** Position Counter (Homing) Initialization Process Complete Status bit<sup>(1)</sup>  
1 = POS1CNT was reinitialized  
0 = POS1CNT was not reinitialized
- bit 6 **PCIEN:** Position Counter (Homing) Initialization Process Complete interrupt Enable bit  
1 = Interrupt is enabled  
0 = Interrupt is disabled
- bit 5 **VELOVIRQ:** Velocity Counter Overflow Status bit  
1 = Overflow has occurred  
0 = No overflow has not occurred
- bit 4 **VELOVIEN:** Velocity Counter Overflow Interrupt Enable bit  
1 = Interrupt is enabled  
0 = Interrupt is disabled
- bit 3 **HOMIRQ:** Status Flag for Home Event Status bit  
1 = Home event has occurred  
0 = No Home event has occurred

**Note 1:** This status bit is only applicable to PIMOD<2:0> modes, '011' and '100'.

**REGISTER 17-13: QE11LECH: QE11 LESS THAN OR EQUAL COMPARE HIGH WORD REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<31:24>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<23:16>							
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **QEILEC<31:16>**: High Word Used to Form 32-Bit Less Than or Equal Compare Register (QE11LEC) bits

**REGISTER 17-14: QE11LECL: QE11 LESS THAN OR EQUAL COMPARE LOW WORD REGISTER**

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-0                      **QEILEC<15:0>**: Low Word Used to Form 32-Bit Less Than or Equal Compare Register (QE11LEC) bits

## 19.2 I<sup>2</sup>C Control Registers

**REGISTER 19-1: I2CxCON: I2Cx CONTROL REGISTER**

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL	IPMIEN <sup>(1)</sup>	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **I2CEN:** I2Cx Enable bit  
 1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins  
 0 = Disables the I2Cx module; all I<sup>2</sup>C™ pins are controlled by port functions
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **I2CSIDL:** I2Cx Stop in Idle Mode bit  
 1 = Discontinues module operation when device enters an Idle mode  
 0 = Continues module operation in Idle mode
- bit 12      **SCLREL:** SCLx Release Control bit (when operating as I<sup>2</sup>C slave)  
 1 = Releases SCLx clock  
 0 = Holds SCLx clock low (clock stretch)  
If STREN = 1:  
 Bit is R/W (i.e., software can write '0' to initiate stretch and write '1' to release clock). Hardware is clear at the beginning of every slave data byte transmission. Hardware is clear at the end of every slave address byte reception. Hardware is clear at the end of every slave data byte reception.  
If STREN = 0:  
 Bit is R/S (i.e., software can only write '1' to release clock). Hardware is clear at the beginning of every slave data byte transmission. Hardware is clear at the end of every slave address byte reception.
- bit 11      **IPMIEN:** Intelligent Peripheral Management Interface (IPMI) Enable bit<sup>(1)</sup>  
 1 = IPMI mode is enabled; all addresses are Acknowledged  
 0 = IPMI mode disabled
- bit 10      **A10M:** 10-Bit Slave Address bit  
 1 = I2CxADD is a 10-bit slave address  
 0 = I2CxADD is a 7-bit slave address
- bit 9      **DISSLW:** Disable Slew Rate Control bit  
 1 = Slew rate control is disabled  
 0 = Slew rate control is enabled
- bit 8      **SMEN:** SMBus Input Levels bit  
 1 = Enables I/O pin thresholds compliant with SMBus specification  
 0 = Disables SMBus input thresholds
- bit 7      **GCEN:** General Call Enable bit (when operating as I<sup>2</sup>C slave)  
 1 = Enables interrupt when a general call address is received in I2CxRSR (module is enabled for reception)  
 0 = General call address disabled

**Note 1:** When performing master operations, ensure that the IPMIEN bit is set to '0'.

**REGISTER 20-2: UxSTA: UARTx STATUS AND CONTROL REGISTER**

R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV	UTXISEL0	—	UTXBRK	UTXEN <sup>(1)</sup>	UTXBF	TRMT
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7						bit 0	

<b>Legend:</b>	HC = Hardware Clearable bit	C = Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15,13 **UTXISEL<1:0>**: UARTx Transmission Interrupt Mode Selection bits  
 11 = Reserved; do not use  
 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR) and as a result, the transmit buffer becomes empty  
 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed  
 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 **UTXINV**: UARTx Transmit Polarity Inversion bit  
 If IREN = 0:  
 1 = UxTX Idle state is '0'  
 0 = UxTX Idle state is '1'  
 If IREN = 1:  
 1 = IrDA encoded, UxTX Idle state is '1'  
 0 = IrDA encoded, UxTX Idle state is '0'
- bit 12 **Unimplemented**: Read as '0'
- bit 11 **UTXBRK**: UARTx Transmit Break bit  
 1 = Sends Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion  
 0 = Sync Break transmission is disabled or completed
- bit 10 **UTXEN**: UARTx Transmit Enable bit<sup>(1)</sup>  
 1 = Transmit is enabled, UxTX pin is controlled by UARTx  
 0 = Transmit is disabled, any pending transmission is aborted and buffer is reset; UxTX pin is controlled by the PORT
- bit 9 **UTXBF**: UARTx Transmit Buffer Full Status bit (read-only)  
 1 = Transmit buffer is full  
 0 = Transmit buffer is not full, at least one more character can be written
- bit 8 **TRMT**: Transmit Shift Register Empty bit (read-only)  
 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)  
 0 = Transmit Shift Register is not empty, a transmission is in progress or queued
- bit 7-6 **URXISEL<1:0>**: UARTx Receive Interrupt Mode Selection bits  
 11 = Interrupt is set on UxRSR transfer, making the receive buffer full (i.e., has 4 data characters)  
 10 = Interrupt is set on UxRSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)  
 0x = Interrupt is set when any character is received and transferred from the UxRSR to the receive buffer; receive buffer has one or more characters

**Note 1:** Refer to the “UART” (DS70582) section in the “dsPIC33/PIC24 Family Reference Manual” for information on enabling the UARTx module for transmit operation.

**REGISTER 21-8: CxEC: ECANx TRANSMIT/RECEIVE ERROR COUNT REGISTER**

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
TERRCNT<7:0>							
bit 15							
bit 8							

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
RERRCNT<7:0>							
bit 7							
bit 0							

**Legend:**

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 15-8      **TERRCNT<7:0>**: Transmit Error Count bits  
 bit 7-0      **RERRCNT<7:0>**: Receive Error Count bits

**REGISTER 21-9: CxCFG1: ECANx BAUD RATE CONFIGURATION REGISTER 1**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							
bit 8							

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SJW1	SJW0	BRP5	BRP4	BRP3	BRP2	BRP1	BRP0
bit 7							
bit 0							

**Legend:**

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

bit 15-8      **Unimplemented:** Read as '0'  
 bit 7-6      **SJW<1:0>**: Synchronization Jump Width bits  
             11 = Length is 4 x T<sub>Q</sub>  
             10 = Length is 3 x T<sub>Q</sub>  
             01 = Length is 2 x T<sub>Q</sub>  
             00 = Length is 1 x T<sub>Q</sub>  
 bit 5-0      **BRP<5:0>**: Baud Rate Prescaler bits  
             11 1111 = T<sub>Q</sub> = 2 x 64 x 1/FCAN  
             •  
             •  
             •  
             00 0010 = T<sub>Q</sub> = 2 x 3 x 1/FCAN  
             00 0001 = T<sub>Q</sub> = 2 x 2 x 1/FCAN  
             00 0000 = T<sub>Q</sub> = 2 x 1 x 1/FCAN

**REGISTER 25-2: CMxCON: COMPARATOR x CONTROL REGISTER (x = 1, 2 OR 3)**

R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
CON	COE <sup>(2)</sup>	CPOL	—	—	OPMODE	CEVT	COUT
bit 15						bit 8	

R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0
EVPOL1	EVPOL0	—	CREF <sup>(1)</sup>	—	—	CCH1 <sup>(1)</sup>	CCH0 <sup>(1)</sup>
bit 7						bit 0	

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **CON:** Op Amp/Comparator Enable bit

1 = Op amp/comparator is enabled

0 = Op amp/comparator is disabled

bit 14 **COE:** Comparator Output Enable bit<sup>(2)</sup>

1 = Comparator output is present on the CxOUT pin

0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit

1 = Comparator output is inverted

0 = Comparator output is not inverted

bit 12-11 **Unimplemented:** Read as '0'

bit 10 **OPMODE:** Op Amp/Comparator Operation Mode Select bit

1 = Circuit operates as an op amp

0 = Circuit operates as a comparator

bit 9 **CEVT:** Comparator Event bit

1 = Comparator event according to the EVPOL<1:0> settings occurred; disables future triggers and interrupts until the bit is cleared

0 = Comparator event did not occur

bit 8 **COUT:** Comparator Output bit

When CPOL = 0 (non-inverted polarity):

1 = VIN+ > VIN-

0 = VIN+ < VIN-

When CPOL = 1 (inverted polarity):

1 = VIN+ < VIN-

0 = VIN+ > VIN-

**Note 1:** Inputs that are selected and not available will be tied to Vss. See the “Pin Diagrams” section for available inputs for each package.

**2:** This output is not available when OPMODE (CMxCON<10>) = 1.



**REGISTER 27-1: DEVID: DEVICE ID REGISTER**

R	R	R	R	R	R	R	R
DEVID<23:16> <sup>(1)</sup>							
bit 23				bit 16			

R	R	R	R	R	R	R	R
DEVID<15:8> <sup>(1)</sup>							
bit 15				bit 8			

R	R	R	R	R	R	R	R
DEVID<7:0> <sup>(1)</sup>							
bit 7				bit 0			

**Legend:** R = Read-Only bit U = Unimplemented bit

bit 23-0 **DEVID<23:0>:** Device Identifier bits<sup>(1)</sup>

**Note 1:** Refer to the “dsPIC33E/PIC24E Flash Programming Specification for Devices with Volatile Configuration Bits” (DS70663) for the list of device ID values.

**REGISTER 27-2: DEVREV: DEVICE REVISION REGISTER**

R	R	R	R	R	R	R	R
DEVREV<23:16> <sup>(1)</sup>							
bit 23				bit 16			

R	R	R	R	R	R	R	R
DEVREV<15:8> <sup>(1)</sup>							
bit 15				bit 8			

R	R	R	R	R	R	R	R
DEVREV<7:0> <sup>(1)</sup>							
bit 7				bit 0			

**Legend:** R = Read-only bit U = Unimplemented bit

bit 23-0 **DEVREV<23:0>:** Device Revision bits<sup>(1)</sup>

**Note 1:** Refer to the “dsPIC33E/PIC24E Flash Programming Specification for Devices with Volatile Configuration Bits” (DS70663) for the list of device revision values.

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles <sup>(2)</sup>	Status Flags Affected
9	BTG	BTG <i>f</i> ,#bit4	Bit Toggle <i>f</i>	1	1	None
		BTG <i>Ws</i> ,#bit4	Bit Toggle <i>Ws</i>	1	1	None
10	BTSC	BTSC <i>f</i> ,#bit4	Bit Test <i>f</i> , Skip if Clear	1	1 (2 or 3)	None
		BTSC <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> , Skip if Clear	1	1 (2 or 3)	None
11	BTSS	BTSS <i>f</i> ,#bit4	Bit Test <i>f</i> , Skip if Set	1	1 (2 or 3)	None
		BTSS <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> , Skip if Set	1	1 (2 or 3)	None
12	BTST	BTST <i>f</i> ,#bit4	Bit Test <i>f</i>	1	1	Z
		BTST.C <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to C	1	1	C
		BTST.Z <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to Z	1	1	Z
		BTST.C <i>Ws</i> , <i>Wb</i>	Bit Test <i>Ws</i> < <i>Wb</i> > to C	1	1	C
		BTST.Z <i>Ws</i> , <i>Wb</i>	Bit Test <i>Ws</i> < <i>Wb</i> > to Z	1	1	Z
13	BTSTS	BTSTS <i>f</i> ,#bit4	Bit Test then Set <i>f</i>	1	1	Z
		BTSTS.C <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to C, then Set	1	1	C
		BTSTS.Z <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to Z, then Set	1	1	Z
14	CALL	CALL <i>lit</i> 23	Call subroutine	2	4	SFA
		CALL <i>Wn</i>	Call indirect subroutine	1	4	SFA
		CALL.L <i>Wn</i>	Call indirect subroutine (long address)	1	4	SFA
15	CLR	CLR <i>f</i>	<i>f</i> = 0x0000	1	1	None
		CLR WREG	WREG = 0x0000	1	1	None
		CLR <i>Ws</i>	<i>Ws</i> = 0x0000	1	1	None
		CLR <i>Acc</i> , <i>Wx</i> , <i>Wxd</i> , <i>Wy</i> , <i>Wyd</i> ,AWB <sup>(1)</sup>	Clear Accumulator	1	1	OA,OB,SA,SB
16	CLRWDT	CLRWDT	Clear Watchdog Timer	1	1	WDTO,Sleep
17	COM	COM <i>f</i>	<i>f</i> = $\bar{f}$	1	1	N,Z
		COM <i>f</i> ,WREG	WREG = $\bar{f}$	1	1	N,Z
		COM <i>Ws</i> , <i>Wd</i>	<i>Wd</i> = $\overline{Ws}$	1	1	N,Z
18	CP	CP <i>f</i>	Compare <i>f</i> with WREG	1	1	C,DC,N,OV,Z
		CP <i>Wb</i> ,#lit8	Compare <i>Wb</i> with lit8	1	1	C,DC,N,OV,Z
		CP <i>Wb</i> , <i>Ws</i>	Compare <i>Wb</i> with <i>Ws</i> ( <i>Wb</i> – <i>Ws</i> )	1	1	C,DC,N,OV,Z
19	CP0	CP0 <i>f</i>	Compare <i>f</i> with 0x0000	1	1	C,DC,N,OV,Z
		CP0 <i>Ws</i>	Compare <i>Ws</i> with 0x0000	1	1	C,DC,N,OV,Z
20	CPB	CPB <i>f</i>	Compare <i>f</i> with WREG, with Borrow	1	1	C,DC,N,OV,Z
		CPB <i>Wb</i> ,#lit8	Compare <i>Wb</i> with lit8, with Borrow	1	1	C,DC,N,OV,Z
		CPB <i>Wb</i> , <i>Ws</i>	Compare <i>Wb</i> with <i>Ws</i> , with Borrow ( <i>Wb</i> – <i>Ws</i> – C)	1	1	C,DC,N,OV,Z
21	CPSEQ	CPSEQ <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if =	1	1 (2 or 3)	None
	CPBEQ	CPBEQ <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if =	1	1 (5)	None
22	CPSGT	CPSGT <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if >	1	1 (2 or 3)	None
	CPBGT	CPBGT <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if >	1	1 (5)	None
23	CPSLT	CPSLT <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if <	1	1 (2 or 3)	None
	CPBLT	CPBLT <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if <	1	1 (5)	None
24	CPSNE	CPSNE <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if ≠	1	1 (2 or 3)	None
	CPBNE	CPBNE <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if ≠	1	1 (5)	None

**Note 1:** These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

**2:** Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

FIGURE 30-5: TIMER1-TIMER5 EXTERNAL CLOCK TIMING CHARACTERISTICS

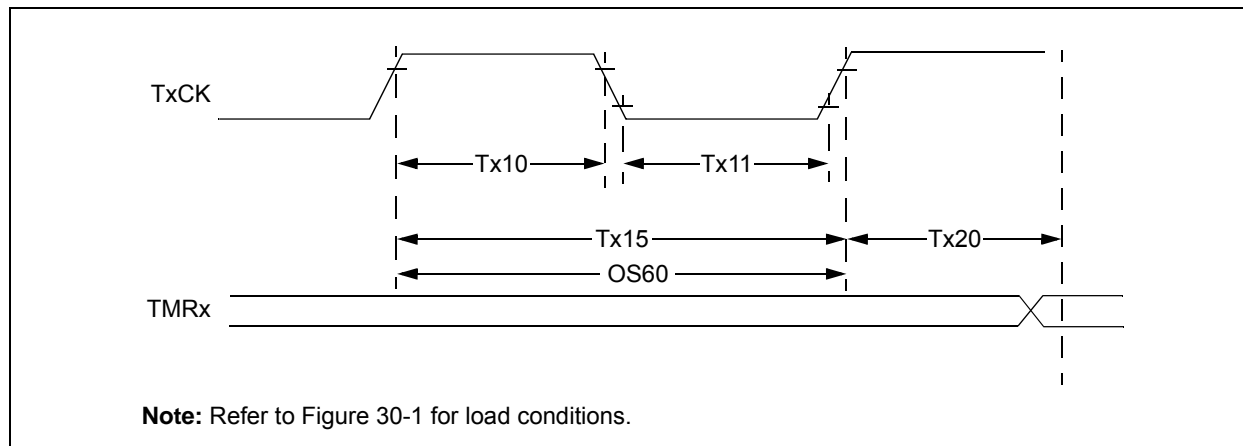


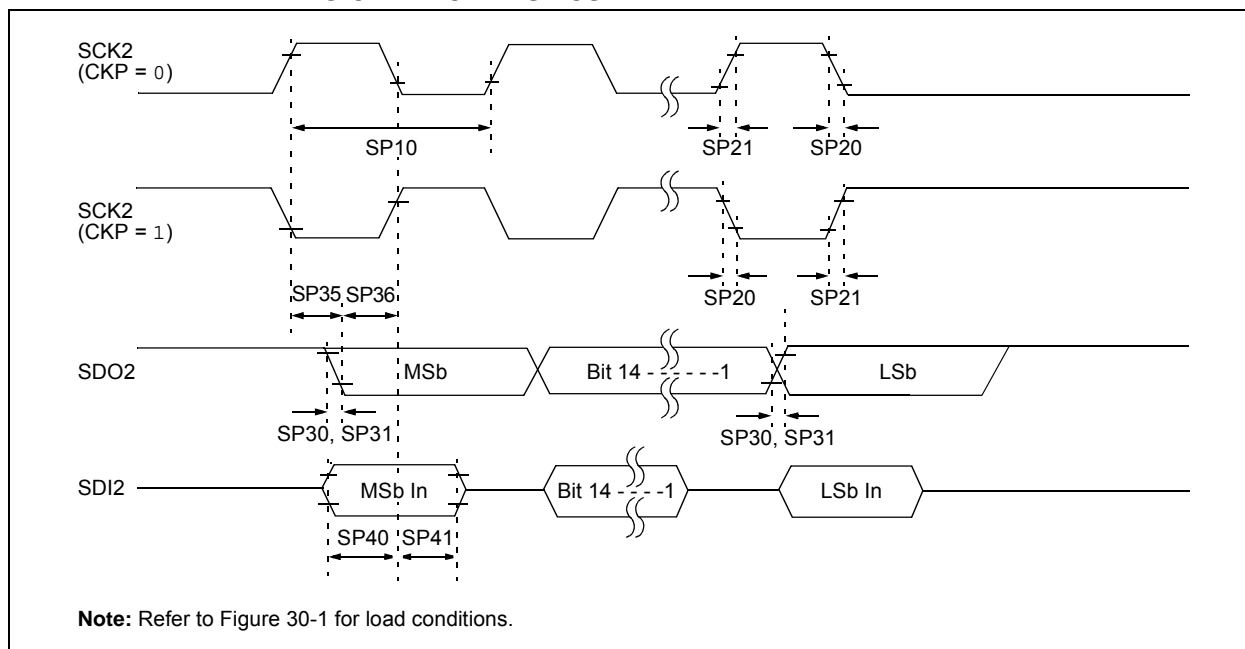
TABLE 30-23: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS<sup>(1)</sup>

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(2)</sup>		Min.	Typ.	Max.	Units	Conditions
TA10	TtxH	T1CK High Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet Parameter TA15, N = prescaler value (1, 8, 64, 256)
			Asynchronous	35	—	—	ns	
TA11	TtxL	T1CK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet Parameter TA15, N = prescaler value (1, 8, 64, 256)
			Asynchronous	10	—	—	ns	
TA15	TtxP	T1CK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	—	ns	N = prescale value (1, 8, 64, 256)
OS60	Ft1	T1CK Oscillator Input Frequency Range (oscillator enabled by setting bit, TCS (T1CON<1>))		DC	—	50	kHz	
TA20	TCKEXTMRL	Delay from External T1CK Clock Edge to Timer Increment		0.75 Tcy + 40	—	1.75 Tcy + 40	ns	

**Note 1:** Timer1 is a Type A.

**Note 2:** These parameters are characterized, but are not tested in manufacturing.

**FIGURE 30-17: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)  
TIMING CHARACTERISTICS**



**TABLE 30-36: SPI2 MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1)  
TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP10	FscP	Maximum SCK2 Frequency	—	—	9	MHz	-40°C to +125°C (Note 3)
SP20	TscF	SCK2 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK2 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO2 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO2 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO2 Data Output Valid after SCK2 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO2 Data Output Setup to First SCK2 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI2 Data Input to SCK2 Edge	30	—	—	ns	

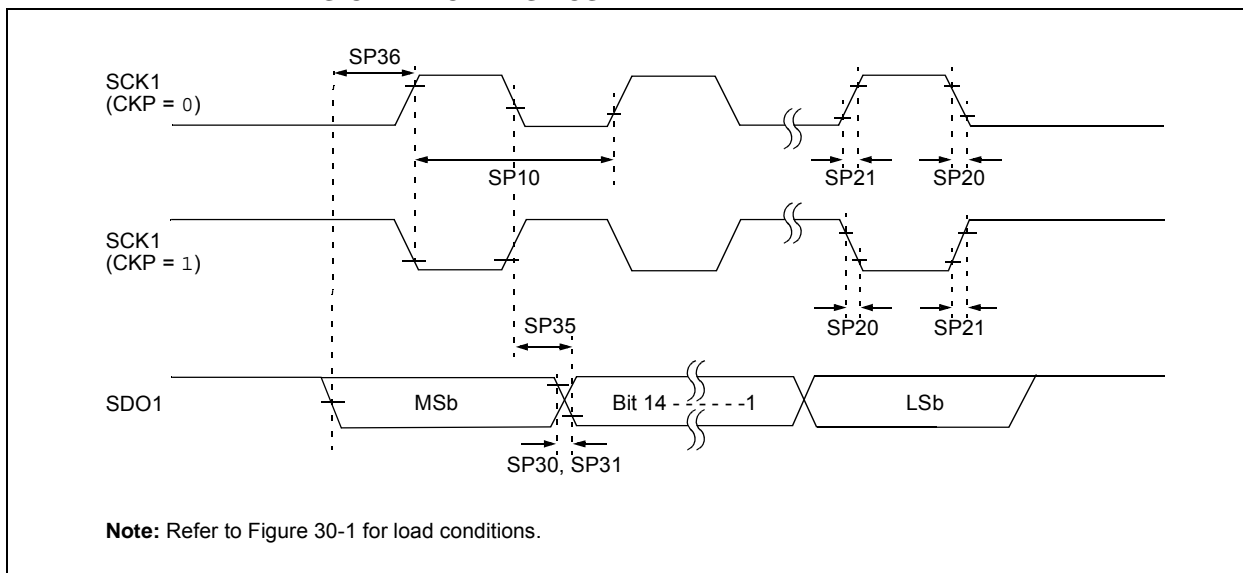
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK2 is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPI2 pins.

**FIGURE 30-23: SPI1 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 1) TIMING CHARACTERISTICS**



**TABLE 30-42: SPI1 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP10	FscP	Maximum SCK1 Frequency	—	—	15	MHz	(Note 3)
SP20	TscF	SCK1 Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP21	TscR	SCK1 Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdiV2scH, TdiV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**Note 2:** Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**Note 3:** The minimum clock period for SCK1 is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

**Note 4:** Assumes 50 pF load on all SPI1 pins.