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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	64KB (22K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.300", 7.62mm)
Supplier Device Package	28-SPDIP
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep64mc502-i-sp">https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep64mc502-i-sp</a>

**3.5 Programmer’s Model**

The programmer’s model for the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X is shown in Figure 3-2. All registers in the programmer’s model are memory mapped and can be manipulated directly by instructions. Table 3-1 lists a description of each register.

In addition to the registers contained in the programmer’s model, the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/

MC20X devices contain control registers for Modulo Addressing (dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices only), Bit-Reversed Addressing (dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices only) and interrupts. These registers are described in subsequent sections of this document.

All registers associated with the programmer’s model are memory mapped, as shown in Table 4-1.

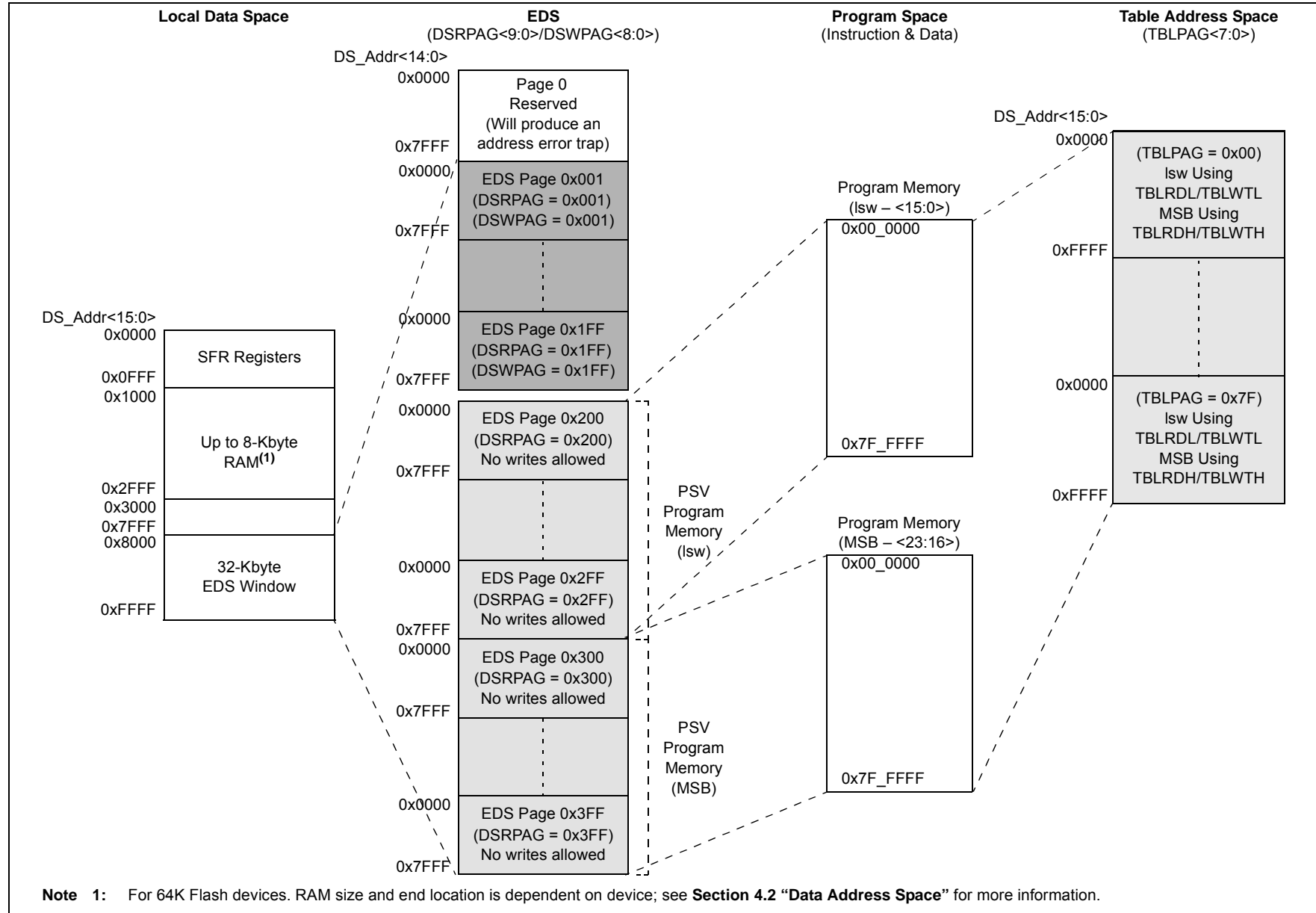
**TABLE 3-1: PROGRAMMER’S MODEL REGISTER DESCRIPTIONS**

Register(s) Name	Description
W0 through W15	Working Register Array
ACCA, ACCB	40-Bit DSP Accumulators
PC	23-Bit Program Counter
SR	ALU and DSP Engine STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
DSRPAG	Extended Data Space (EDS) Read Page Register
DSWPAG	Extended Data Space (EDS) Write Page Register
RCOUNT	REPEAT Loop Count Register
DCOUNT <sup>(1)</sup>	DO Loop Count Register
DOSTARTH <sup>(1,2)</sup> , DOSTARTL <sup>(1,2)</sup>	DO Loop Start Address Register (High and Low)
DOENDH <sup>(1)</sup> , DOENDL <sup>(1)</sup>	DO Loop End Address Register (High and Low)
CORCON	Contains DSP Engine, DO Loop Control and Trap Status bits

**Note 1:** This register is available on dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X devices only.

**2:** The DOSTARTH and DOSTARTL registers are read-only.

**EXAMPLE 4-3: PAGED DATA MEMORY SPACE**



**REGISTER 5-1: NVMCON: NONVOLATILE MEMORY (NVM) CONTROL REGISTER**

R/SO-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0	U-0	U-0	U-0	U-0	
WR	WREN	WRERR	NVMSIDL <sup>(2)</sup>	—	—	—	—	
bit 15								bit 8
U-0	U-0	U-0	U-0	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	R/W-0 <sup>(1)</sup>	
—	—	—	—	NVMOP3 <sup>(3,4)</sup>	NVMOP2 <sup>(3,4)</sup>	NVMOP1 <sup>(3,4)</sup>	NVMOP0 <sup>(3,4)</sup>	
bit 7								bit 0

<b>Legend:</b>	SO = Settable Only bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	U = Unimplemented bit, read as '0'
	'0' = Bit is cleared
	x = Bit is unknown

- bit 15      **WR:** Write Control bit<sup>(1)</sup>  
 1 = Initiates a Flash memory program or erase operation; the operation is self-timed and the bit is cleared by hardware once the operation is complete  
 0 = Program or erase operation is complete and inactive
- bit 14      **WREN:** Write Enable bit<sup>(1)</sup>  
 1 = Enables Flash program/erase operations  
 0 = Inhibits Flash program/erase operations
- bit 13      **WRERR:** Write Sequence Error Flag bit<sup>(1)</sup>  
 1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit)  
 0 = The program or erase operation completed normally
- bit 12      **NVMSIDL:** NVM Stop in Idle Control bit<sup>(2)</sup>  
 1 = Flash voltage regulator goes into Standby mode during Idle mode  
 0 = Flash voltage regulator is active during Idle mode
- bit 11-4    **Unimplemented:** Read as '0'
- bit 3-0     **NVMOP<3:0>:** NVM Operation Select bits<sup>(1,3,4)</sup>  
 1111 = Reserved  
 1110 = Reserved  
 1101 = Reserved  
 1100 = Reserved  
 1011 = Reserved  
 1010 = Reserved  
 0011 = Memory page erase operation  
 0010 = Reserved  
 0001 = Memory double-word program operation<sup>(5)</sup>  
 0000 = Reserved

- Note 1:** These bits can only be reset on a POR.
- 2:** If this bit is set, there will be minimal power savings (IDLE) and upon exiting Idle mode, there is a delay (TVREG) before Flash memory becomes operational.
- 3:** All other combinations of NVMOP<3:0> are unimplemented.
- 4:** Execution of the PWRSAV instruction is ignored while any of the NVM operations are in progress.
- 5:** Two adjacent words on a 4-word boundary are programmed during execution of this operation.

**REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1 (CONTINUED)**

bit 3	<b>SPI1MD:</b> SPI1 Module Disable bit 1 = SPI1 module is disabled 0 = SPI1 module is enabled
bit 2	<b>Unimplemented:</b> Read as '0'
bit 1	<b>C1MD:</b> ECAN1 Module Disable bit <sup>(2)</sup> 1 = ECAN1 module is disabled 0 = ECAN1 module is enabled
bit 0	<b>AD1MD:</b> ADC1 Module Disable bit 1 = ADC1 module is disabled 0 = ADC1 module is enabled

**Note 1:** This bit is available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

**2:** This bit is available on dsPIC33EPXXXGP50X and dsPIC33EPXXXMC50X devices only.

**REGISTER 11-8: RPINR14: PERIPHERAL PIN SELECT INPUT REGISTER 14**  
**(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	QEB1R<6:0>							
bit 15								bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
—	QEA1R<6:0>							
bit 7								bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15                      **Unimplemented:** Read as '0'

bit 14-8                      **QEB1R<6:0>:** Assign B (QEB) to the Corresponding RPN Pin bits  
(see Table 11-2 for input pin selection numbers)  
1111001 = Input tied to RPI121  
.  
.  
.  
0000001 = Input tied to CMP1  
0000000 = Input tied to Vss

bit 7                      **Unimplemented:** Read as '0'

bit 6-0                      **QEA1R<6:0>:** Assign A (QEA) to the Corresponding RPN Pin bits  
(see Table 11-2 for input pin selection numbers)  
1111001 = Input tied to RPI121  
.  
.  
.  
0000001 = Input tied to CMP1  
0000000 = Input tied to Vss

## 20.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

**Note 1:** This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “UART” (DS70582) in the “dsPIC33/PIC24 Family Reference Manual”, which is available from the Microchip web site (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X family of devices contains two UART modules.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X device family. The UART is a full-duplex, asynchronous system that can communicate with peripheral devices, such as personal computers, LIN/J2602, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins, and also includes an IrDA® encoder and decoder.

**Note:** Hardware flow control using  $\overline{UxRTS}$  and  $\overline{UxCTS}$  is not available on all pin count devices. See the “Pin Diagrams” section for availability.

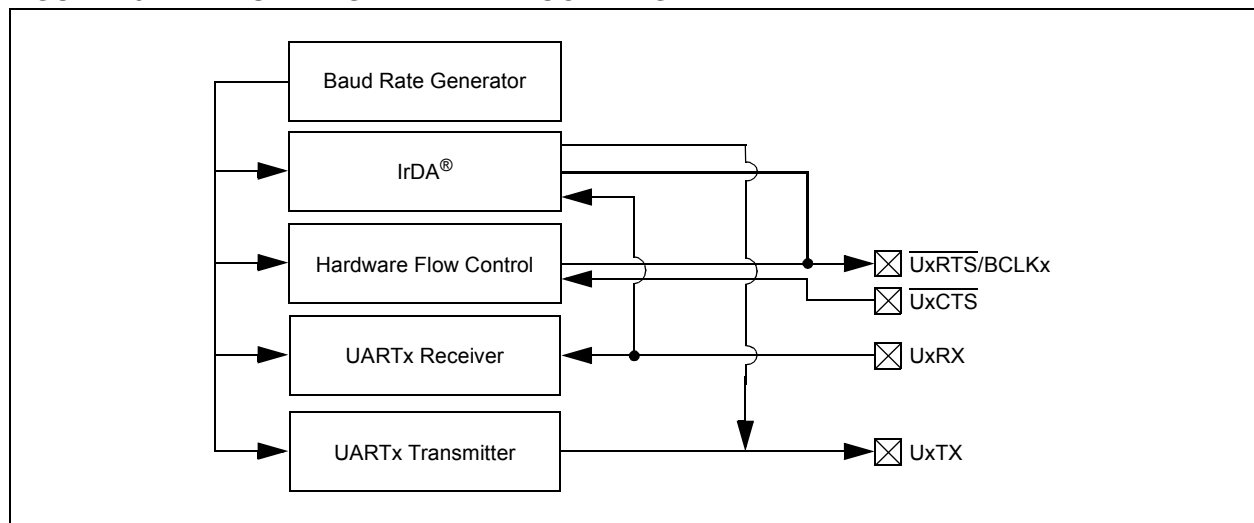
The primary features of the UARTx module are:

- Full-Duplex, 8 or 9-Bit Data Transmission through the UxTX and UxRX Pins
- Even, Odd or No Parity Options (for 8-bit data)
- One or Two Stop bits
- Hardware Flow Control Option with  $\overline{UxCTS}$  and  $\overline{UxRTS}$  Pins
- Fully Integrated Baud Rate Generator with 16-Bit Prescaler
- Baud Rates Ranging from 4.375 Mbps to 67 bps at 16x mode at 70 MIPS
- Baud Rates Ranging from 17.5 Mbps to 267 bps at 4x mode at 70 MIPS
- 4-Deep First-In First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- Transmit and Receive Interrupts
- A Separate Interrupt for all UARTx Error Conditions
- Loopback mode for Diagnostic Support
- Support for Sync and Break Characters
- Support for Automatic Baud Rate Detection
- IrDA® Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA Support

A simplified block diagram of the UARTx module is shown in Figure 20-1. The UARTx module consists of these key hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

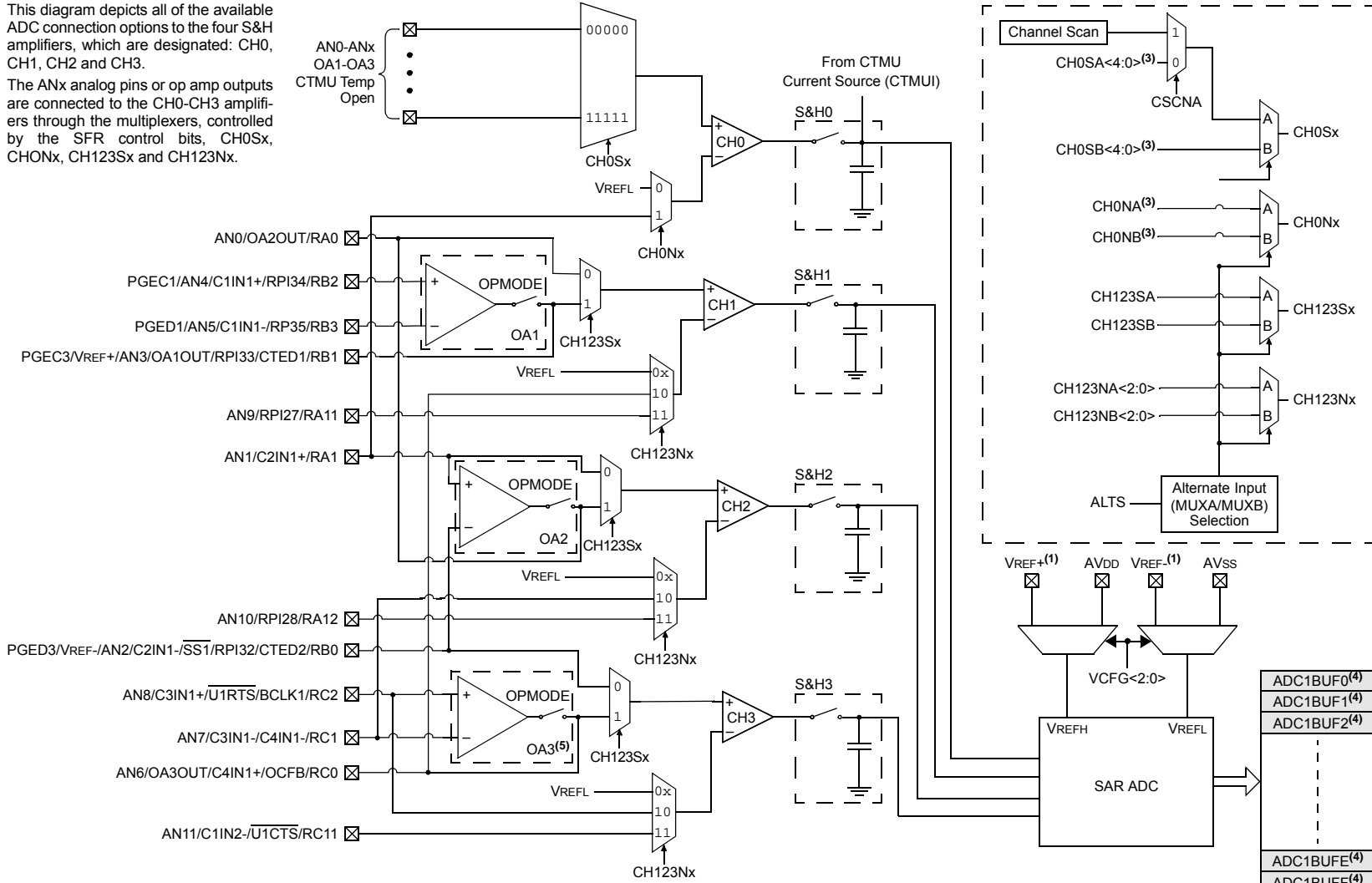
**FIGURE 20-1: UARTx SIMPLIFIED BLOCK DIAGRAM**



**FIGURE 23-1: ADC MODULE BLOCK DIAGRAM WITH CONNECTION OPTIONS FOR ANx PINS AND OP AMPS**

This diagram depicts all of the available ADC connection options to the four S&H amplifiers, which are designated: CH0, CH1, CH2 and CH3.

The ANx analog pins or op amp outputs are connected to the CH0-CH3 amplifiers through the multiplexers, controlled by the SFR control bits, CH0Sx, CH1Sx, CH2Sx and CH3Sx.



- Note**
- 1: VREF+, VREF- inputs can be multiplexed with other analog inputs.
  - 2: Channels 1, 2 and 3 are not applicable for the 12-bit mode of operation.
  - 3: These bits can be updated with Step commands from the PTG module. See Section 24.0 "Peripheral Trigger Generator (PTG) Module" for more information.
  - 4: When ADDMAEN (AD1CON4<8>) = 1, enabling DMA, only ADC1BUF0 is used.
  - 5: OA3 is not available for 28-pin devices.



TABLE 24-2: PTG OUTPUT DESCRIPTIONS

PTG Output Number	PTG Output Description
PTGO0	Trigger/Synchronization Source for OC1
PTGO1	Trigger/Synchronization Source for OC2
PTGO2	Trigger/Synchronization Source for OC3
PTGO3	Trigger/Synchronization Source for OC4
PTGO4	Clock Source for OC1
PTGO5	Clock Source for OC2
PTGO6	Clock Source for OC3
PTGO7	Clock Source for OC4
PTGO8	Trigger/Synchronization Source for IC1
PTGO9	Trigger/Synchronization Source for IC2
PTGO10	Trigger/Synchronization Source for IC3
PTGO11	Trigger/Synchronization Source for IC4
PTGO12	Sample Trigger for ADC
PTGO13	Sample Trigger for ADC
PTGO14	Sample Trigger for ADC
PTGO15	Sample Trigger for ADC
PTGO16	PWM Time Base Synchronous Source for PWM <sup>(1)</sup>
PTGO17	PWM Time Base Synchronous Source for PWM <sup>(1)</sup>
PTGO18	Mask Input Select for Op Amp/Comparator
PTGO19	Mask Input Select for Op Amp/Comparator
PTGO20	Reserved
PTGO21	Reserved
PTGO22	Reserved
PTGO23	Reserved
PTGO24	Reserved
PTGO25	Reserved
PTGO26	Reserved
PTGO27	Reserved
PTGO28	Reserved
PTGO29	Reserved
PTGO30	PTG Output to PPS Input Selection
PTGO31	PTG Output to PPS Input Selection

**Note 1:** This feature is only available on dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices.

**REGISTER 25-6: CM<sub>x</sub>FLTR: COMPARATOR x FILTER CONTROL REGISTER**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	CFSEL2	CFSEL1	CFSEL0	CFLTREN	CFDIV2	CFDIV1	CFDIV0
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15-7      **Unimplemented:** Read as '0'
- bit 6-4      **CFSEL<2:0>:** Comparator Filter Input Clock Select bits
  - 111 = T5CLK<sup>(1)</sup>
  - 110 = T4CLK<sup>(2)</sup>
  - 101 = T3CLK<sup>(1)</sup>
  - 100 = T2CLK<sup>(2)</sup>
  - 011 = Reserved
  - 010 = SYNCO1<sup>(3)</sup>
  - 001 = Fosc<sup>(4)</sup>
  - 000 = Fp<sup>(4)</sup>
- bit 3        **CFLTREN:** Comparator Filter Enable bit
  - 1 = Digital filter is enabled
  - 0 = Digital filter is disabled
- bit 2-0     **CFDIV<2:0>:** Comparator Filter Clock Divide Select bits
  - 111 = Clock Divide 1:128
  - 110 = Clock Divide 1:64
  - 101 = Clock Divide 1:32
  - 100 = Clock Divide 1:16
  - 011 = Clock Divide 1:8
  - 010 = Clock Divide 1:4
  - 001 = Clock Divide 1:2
  - 000 = Clock Divide 1:1

- Note 1:** See the Type C Timer Block Diagram (Figure 13-2).  
**Note 2:** See the Type B Timer Block Diagram (Figure 13-1).  
**Note 3:** See the High-Speed PWMx Module Register Interconnection Diagram (Figure 16-2).  
**Note 4:** See the Oscillator System Diagram (Figure 9-1).

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles <sup>(2)</sup>	Status Flags Affected
46	MOV	MOV $f, Wn$	Move $f$ to $Wn$	1	1	None
		MOV $f$	Move $f$ to $f$	1	1	None
		MOV $f, WREG$	Move $f$ to $WREG$	1	1	None
		MOV $\#lit16, Wn$	Move 16-bit literal to $Wn$	1	1	None
		MOV.b $\#lit8, Wn$	Move 8-bit literal to $Wn$	1	1	None
		MOV $Wn, f$	Move $Wn$ to $f$	1	1	None
		MOV $Wso, Wdo$	Move $Ws$ to $Wd$	1	1	None
		MOV $WREG, f$	Move $WREG$ to $f$	1	1	None
		MOV.D $Wns, Wd$	Move Double from $W(ns):W(ns + 1)$ to $Wd$	1	2	None
MOV.D $Ws, Wnd$	Move Double from $Ws$ to $W(nd + 1):W(nd)$	1	2	None		
47	MOVPAG	MOVPAG $\#lit10, DSRPAG$	Move 10-bit literal to $DSRPAG$	1	1	None
		MOVPAG $\#lit9, DSWPAG$	Move 9-bit literal to $DSWPAG$	1	1	None
		MOVPAG $\#lit8, TBLPAG$	Move 8-bit literal to $TBLPAG$	1	1	None
		MOVPAG $Ws, DSRPAG$	Move $Ws<9:0>$ to $DSRPAG$	1	1	None
		MOVPAG $Ws, DSWPAG$	Move $Ws<8:0>$ to $DSWPAG$	1	1	None
		MOVPAG $Ws, TBLPAG$	Move $Ws<7:0>$ to $TBLPAG$	1	1	None
48	MOVSAC	MOVSAC $Acc, Wx, Wxd, Wy, Wyd, AWB^{(1)}$	Prefetch and store accumulator	1	1	None
49	MPY	MPY $Wm*Wn, Acc, Wx, Wxd, Wy, Wyd^{(1)}$	Multiply $Wm$ by $Wn$ to Accumulator	1	1	OA,OB,OAB,SA,SB,SAB
		MPY $Wm*Wm, Acc, Wx, Wxd, Wy, Wyd^{(1)}$	Square $Wm$ to Accumulator	1	1	OA,OB,OAB,SA,SB,SAB
50	MPY.N	MPY.N $Wm*Wn, Acc, Wx, Wxd, Wy, Wyd^{(1)}$	-(Multiply $Wm$ by $Wn$ ) to Accumulator	1	1	None
51	MSC	MSC $Wm*Wm, Acc, Wx, Wxd, Wy, Wyd, AWB^{(1)}$	Multiply and Subtract from Accumulator	1	1	OA,OB,OAB,SA,SB,SAB

**Note 1:** These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

**2:** Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

TABLE 30-6: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended			
Parameter No.	Typ.	Max.	Units	Conditions		
<b>Operating Current (IDD)<sup>(1)</sup></b>						
DC20d	9	15	mA	-40°C	3.3V	10 MIPS
DC20a	9	15	mA	+25°C		
DC20b	9	15	mA	+85°C		
DC20c	9	15	mA	+125°C		
DC22d	16	25	mA	-40°C	3.3V	20 MIPS
DC22a	16	25	mA	+25°C		
DC22b	16	25	mA	+85°C		
DC22c	16	25	mA	+125°C		
DC24d	27	40	mA	-40°C	3.3V	40 MIPS
DC24a	27	40	mA	+25°C		
DC24b	27	40	mA	+85°C		
DC24c	27	40	mA	+125°C		
DC25d	36	55	mA	-40°C	3.3V	60 MIPS
DC25a	36	55	mA	+25°C		
DC25b	36	55	mA	+85°C		
DC25c	36	55	mA	+125°C		
DC26d	41	60	mA	-40°C	3.3V	70 MIPS
DC26a	41	60	mA	+25°C		
DC26b	41	60	mA	+85°C		

**Note 1:** IDD is primarily a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows:

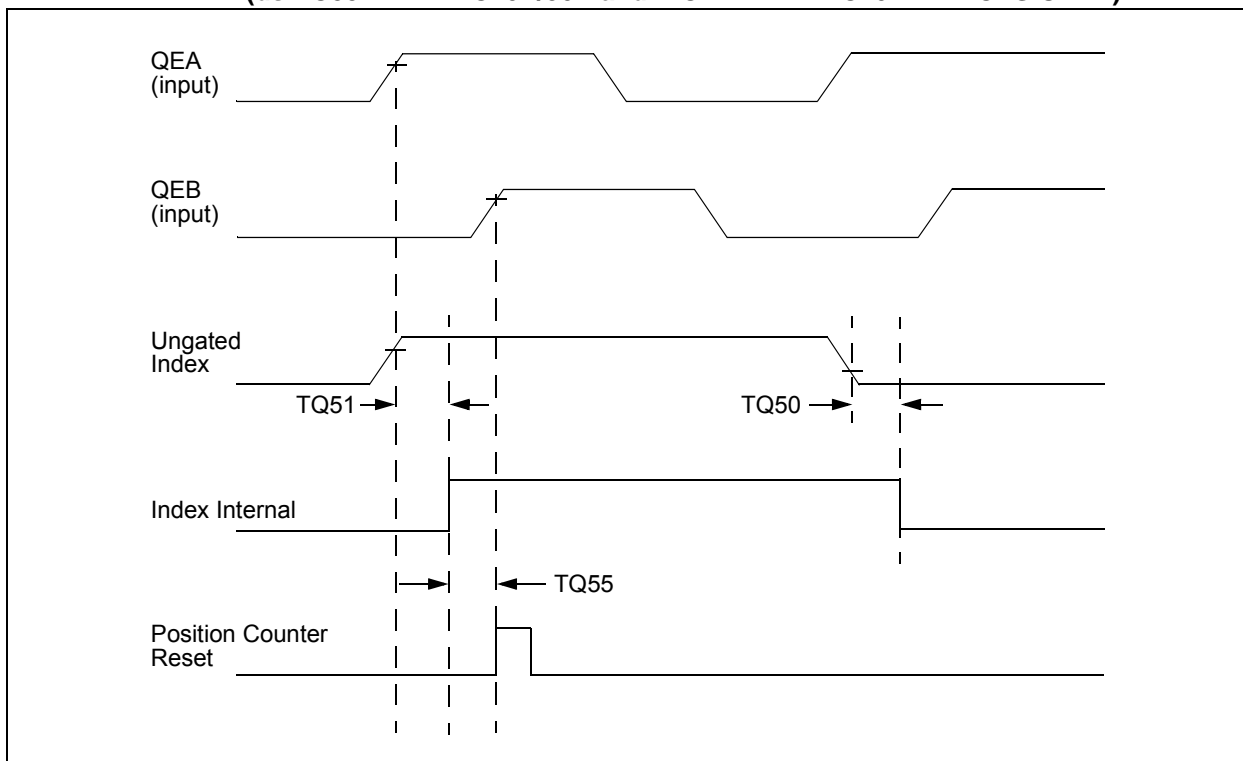
- Oscillator is configured in EC mode with PLL, OSC1 is driven with external square wave from rail-to-rail (EC clock overshoot/undershoot < 250 mV required)
- CLKO is configured as an I/O input pin in the Configuration Word
- All I/O pins are configured as inputs and pulled to Vss
- MCLR = VDD, WDT and FSCM are disabled
- CPU, SRAM, program memory and data memory are operational
- No peripheral modules are operating; however, every peripheral is being clocked (all PMDx bits are zeroed)
- CPU is executing `while(1){NOP();}` statement
- JTAG is disabled

TABLE 30-11: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
DI60a	I <sub>ICL</sub>	Input Low Injection Current	0	—	-5 <sup>(4,7)</sup>	mA	All pins except V <sub>DD</sub> , V <sub>SS</sub> , AV <sub>DD</sub> , AV <sub>SS</sub> , MCLR, V <sub>CAP</sub> and RB7
DI60b	I <sub>ICH</sub>	Input High Injection Current	0	—	+5 <sup>(5,6,7)</sup>	mA	All pins except V <sub>DD</sub> , V <sub>SS</sub> , AV <sub>DD</sub> , AV <sub>SS</sub> , MCLR, V <sub>CAP</sub> , RB7 and all 5V tolerant pins <sup>(6)</sup>
DI60c	$\Sigma I_{ICT}$	Total Input Injection Current (sum of all I/O and control pins)	-20 <sup>(8)</sup>	—	+20 <sup>(8)</sup>	mA	Absolute instantaneous sum of all $\pm$ input injection currents from all I/O pins ( $ I_{ICL}  +  I_{ICH} $ ) $\leq \Sigma I_{ICT}$

- Note 1:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 2:** Negative current is defined as current sourced by the pin.
- 3:** See the “Pin Diagrams” section for the 5V tolerant I/O pins.
- 4:** V<sub>IL</sub> source < (V<sub>SS</sub> – 0.3). Characterized but not tested.
- 5:** Non-5V tolerant pins V<sub>IH</sub> source > (V<sub>DD</sub> + 0.3), 5V tolerant pins V<sub>IH</sub> source > 5.5V. Characterized but not tested.
- 6:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 7:** Non-zero injection currents can affect the ADC results by approximately 4-6 counts.
- 8:** Any number and/or combination of I/O pins not excluded under I<sub>ICL</sub> or I<sub>ICH</sub> conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**FIGURE 30-13: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS**  
**(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**



**TABLE 30-32: QEI INDEX PULSE TIMING REQUIREMENTS**  
**(dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X DEVICES ONLY)**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended			
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Max.	Units	Conditions
TQ50	TqiL	Filter Time to Recognize Low, with Digital Filter	$3 * N * T_{CY}$	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 ( <b>Note 2</b> )
TQ51	TqiH	Filter Time to Recognize High, with Digital Filter	$3 * N * T_{CY}$	—	ns	N = 1, 2, 4, 16, 32, 64, 128 and 256 ( <b>Note 2</b> )
TQ55	Tqidxr	Index Pulse Recognized to Position Counter Reset (ungated index)	$3 T_{CY}$	—	ns	

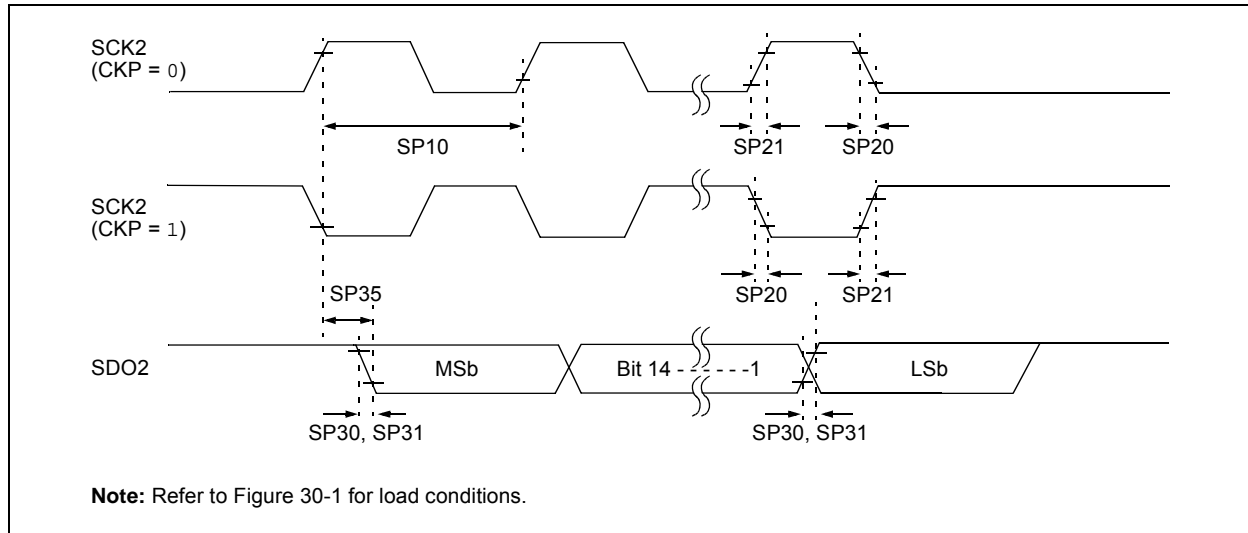
**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Alignment of index pulses to QEA and QEB is shown for position counter Reset timing only. Shown for forward direction only (QEA leads QEB). Same timing applies for reverse direction (QEA lags QEB) but index pulse recognition occurs on the falling edge.

TABLE 30-33: SPI2 MAXIMUM DATA/CLOCK RATE SUMMARY

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Maximum Data Rate	Master Transmit Only (Half-Duplex)	Master Transmit/Receive (Full-Duplex)	Slave Transmit/Receive (Full-Duplex)	CKE	CKP	SMP
15 MHz	Table 30-33	—	—	0,1	0,1	0,1
9 MHz	—	Table 30-34	—	1	0,1	1
9 MHz	—	Table 30-35	—	0	0,1	1
15 MHz	—	—	Table 30-36	1	0	0
11 MHz	—	—	Table 30-37	1	1	0
15 MHz	—	—	Table 30-38	0	1	0
11 MHz	—	—	Table 30-39	0	0	0

FIGURE 30-14: SPI2 MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS



**TABLE 30-47: SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)  
TIMING REQUIREMENTS**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP70	FscP	Maximum SCK1 Input Frequency	—	—	15	MHz	(Note 3)
SP72	TscF	SCK1 Input Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK1 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{\text{SS}}1 \downarrow$ to SCK1 $\uparrow$ or SCK1 $\downarrow$ Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{\text{SS}}1 \uparrow$ to SDO1 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	Tsch2ssH, TscL2ssH	$\overline{\text{SS}}1 \uparrow$ after SCK1 Edge	$1.5 T_{CY} + 40$	—	—	ns	(Note 4)

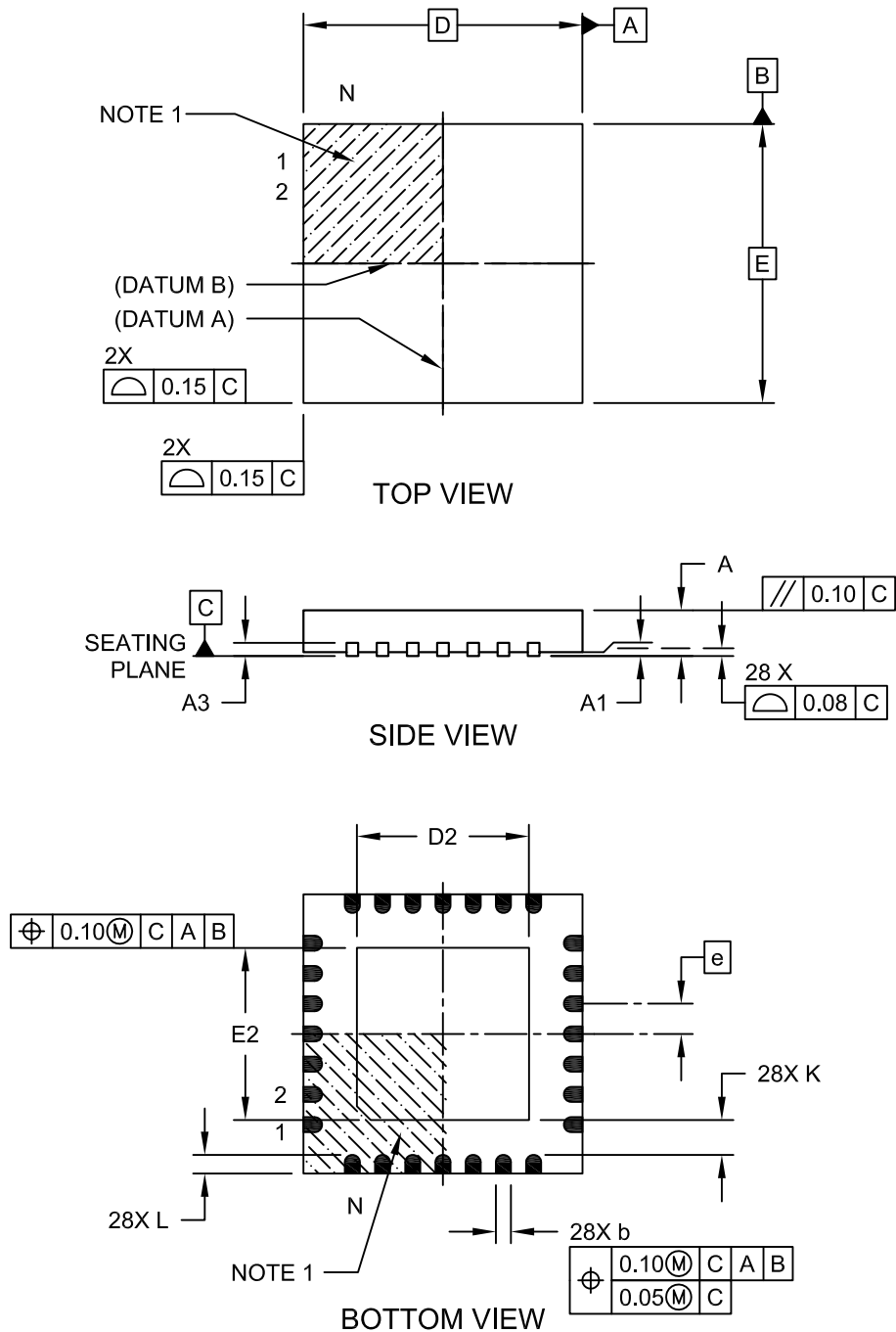
- Note 1:** These parameters are characterized, but are not tested in manufacturing.  
**Note 2:** Data in “Typical” column is at 3.3V, +25°C unless otherwise stated.  
**Note 3:** The minimum clock period for SCK1 is 66.7 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.  
**Note 4:** Assumes 50 pF load on all SPI1 pins.



NOTES:

**28-Lead Plastic Quad Flat, No Lead Package (MM) - 6x6x0.9mm Body [QFN-S]  
With 0.40 mm Terminal Length**

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

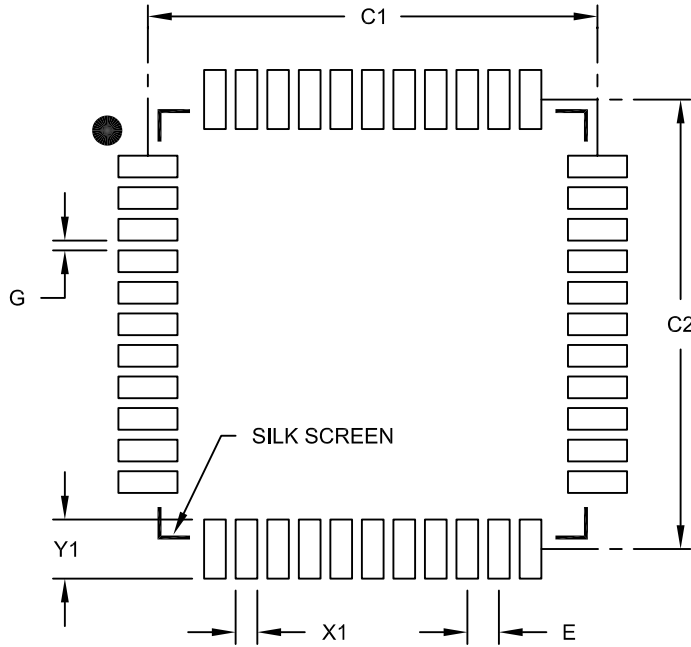


Microchip Technology Drawing C04-124C Sheet 1 of 2

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.80 BSC		
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B

PMD (PIC24EPXXXMC20X Devices).....	94	CmxMSKCON (Comparator x Mask Gating Control).....	368
PORTA (PIC24EPXXXGP/MC202, dsPIC33EPXXXGP/MC202/502 Devices) .....	104	CmxMSKSR (Comparator x Mask Source Select Control).....	366
PORTA (PIC24EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices) .....	103	CORCON (Core Control).....	42, 133
PORTA (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices) .....	102	CRCCON1 (CRC Control 1).....	375
PORTA (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	99	CRCCON2 (CRC Control 2).....	376
PORTB (PIC24EPXXXGP/MC202, dsPIC33EPXXXGP/MC202/502 Devices) .....	104	CRCXORH (CRC XOR Polynomial High) .....	377
PORTB (PIC24EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices) .....	103	CRCXORL (CRC XOR Polynomial Low).....	377
PORTB (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices) .....	102	CTMUCON1 (CTMU Control 1).....	317
PORTB (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	99	CTMUCON2 (CTMU Control 2).....	318
PORTC (PIC23EPXXXGP/MC203, dsPIC33EPXXXGP/MC203/503 Devices) .....	103	CTMUICON (CTMU Current Control).....	319
PORTC (PIC24EPXXXGP/MC204, dsPIC33EPXXXGP/MC204/504 Devices) .....	102	CVRCON (Comparator Voltage Reference Control).....	371
PORTC (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	99	CxBUFNT1 (ECANx Filter 0-3 Buffer Pointer 1) .....	300
PORTD (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	100	CxBUFNT2 (ECANx Filter 4-7 Buffer Pointer 2) .....	301
PORTE (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	100	CxBUFNT3 (ECANx Filter 8-11 Buffer Pointer 3) .....	301
PORTF (PIC24EPXXXGP/MC206, dsPIC33EPXXXGP/MC206/506 Devices) .....	100	CxBUFNT4 (ECANx Filter 12-15 Buffer Pointer 4) .....	302
PORTG (PIC24EPXXXGP/MC206 and dsPIC33EPXXXGP/MC206/506 Devices) .....	101	CxCFG1 (ECANx Baud Rate Configuration 1).....	298
PTG.....	78	CxCFG2 (ECANx Baud Rate Configuration 2).....	299
PWM (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	79	CxCTRL1 (ECANx Control 1).....	290
PWM Generator 1 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	79	CxCTRL2 (ECANx Control 2).....	291
PWM Generator 2 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	80	CxEC (ECANx Transmit/Receive Error Count) .....	298
PWM Generator 3 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	80	CxFCTRL (ECANx FIFO Control).....	293
QE11 (dsPIC33EPXXXMC20X/50X, PIC24EPXXXMC20X Devices).....	81	CxFEN1 (ECANx Acceptance Filter Enable 1).....	300
Reference Clock .....	93	CxFIFO (ECANx FIFO Status) .....	294
SPI1 and SPI2 .....	83	CxFMSKSEL1 (ECANx Filter 7-0 Mask Selection 1).....	304
System Control .....	93	CxFMSKSEL2 (ECANx Filter 15-8 Mask Selection 2).....	305
Time1 through Time5.....	75	CxINTE (ECANx Interrupt Enable) .....	297
UART1 and UART2 .....	82	CxINTF (ECANx Interrupt Flag).....	295
<b>Registers</b>		CxRXFnEID (ECANx Acceptance Filter n Extended Identifier) .....	304
AD1CHS0 (ADC1 Input Channel 0 Select) .....	333	CxRXFnSID (ECANx Acceptance Filter n Standard Identifier) .....	303
AD1CHS123 (ADC1 Input Channel 1, 2, 3 Select) .....	331	CxRXFUL1 (ECANx Receive Buffer Full 1).....	307
AD1CON1 (ADC1 Control 1) .....	325	CxRXFUL2 (ECANx Receive Buffer Full 2).....	307
AD1CON2 (ADC1 Control 2) .....	327	CxRXMnEID (ECANx Acceptance Filter Mask n Extended Identifier) .....	306
AD1CON3 (ADC1 Control 3) .....	329	CxRXMnSID (ECANx Acceptance Filter Mask n Standard Identifier) .....	306
AD1CON4 (ADC1 Control 4) .....	330	CxRXOVF1 (ECANx Receive Buffer Overflow 1).....	308
AD1CSSH (ADC1 Input Scan Select High) .....	335	CxRXOVF2 (ECANx Receive Buffer Overflow 2).....	308
AD1CSSL (ADC1 Input Scan Select Low).....	336	CxTRMnCON (ECANx TX/RX Buffer mn Control) .....	309
ALTDTRx (PWMx Alternate Dead-Time).....	238	CxVEC (ECANx Interrupt Code).....	292
AUXCONx (PWMx Auxiliary Control).....	247	DEVID (Device ID).....	383
CHOP (PWMx Chop Clock Generator).....	234	DEVREV (Device Revision).....	383
CLKDIV (Clock Divisor).....	158	DMALCA (DMA Last Channel Active Status) .....	150
CM4CON (Comparator 4 Control) .....	364	DMAPPS (DMA Ping-Pong Status).....	151
CMSTAT (Op Amp/Comparator Status) .....	360	DMAFWC (DMA Peripheral Write Collision Status).....	148
CMxCON (Comparator x Control, x = 1,2,3).....	362	DMARQC (DMA Request Collision Status).....	149
CMxFLTR (Comparator x Filter Control).....	370	DMAxCNT (DMA Channel x Transfer Count).....	146
		DMAxCON (DMA Channel x Control).....	142
		DMAxPAD (DMA Channel x Peripheral Address).....	146
		DMAxREQ (DMA Channel x IRQ Select).....	143

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