

Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	64KB (22K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VFTLA Exposed Pad
Supplier Device Package	44-VTLA (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep64mc504t-i-tl

Pin Diagrams (Continued)

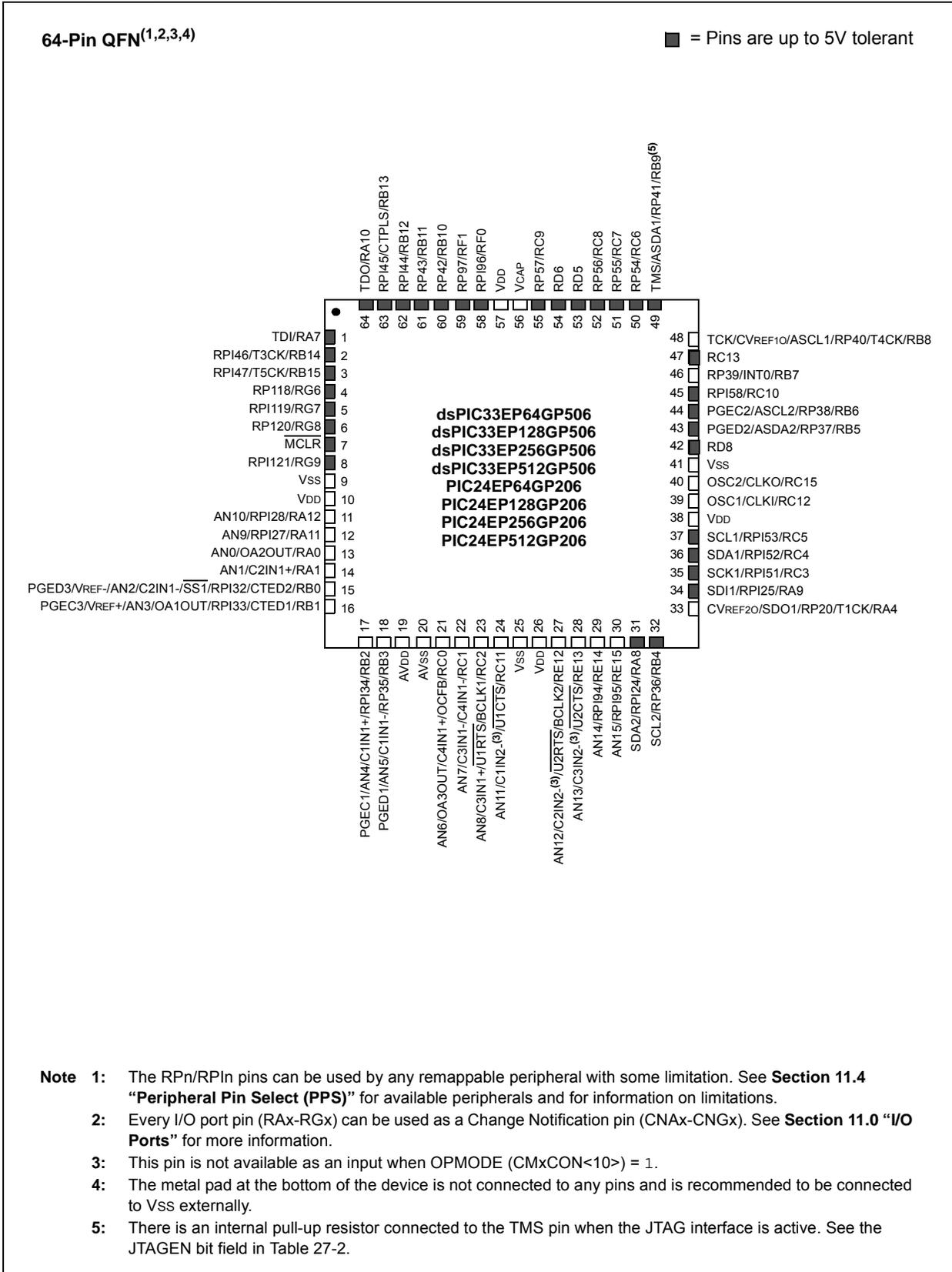


TABLE 4-7: INTERRUPT CONTROLLER REGISTER MAP FOR dsPIC33EPXXXMC50X DEVICES ONLY

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IFS0	0800	—	DMA1IF	AD1IF	U1TXIF	U1RXIF	SP11IF	SP11EIF	T3IF	T2IF	OC2IF	IC2IF	DMA0IF	T1IF	OC1IF	IC1IF	INT0IF	0000
IFS1	0802	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA2IF	—	—	—	INT1IF	CNIF	CMIF	M1C2IF	SI2C1IF	0000
IFS2	0804	—	—	—	—	—	—	—	—	—	IC4IF	IC3IF	DMA3IF	C1IF	C1RXIF	SPI2IF	SPI2EIF	0000
IFS3	0806	—	—	—	—	—	—	QE11IF	PSEMIF	—	—	—	—	—	M1C2IF	SI2C2IF	—	0000
IFS4	0808	—	—	CTMUIF	—	—	—	—	—	—	C1TXIF	—	—	CRCIF	U2EIF	U1EIF	—	0000
IFS5	080A	PWM2IF	PWM1IF	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IFS6	080C	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	PWM3IF	0000
IFS8	0810	JTAGIF	ICDIF	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IFS9	0812	—	—	—	—	—	—	—	—	—	PTG3IF	PTG2IF	PTG1IF	PTG0IF	PTGWDTIF	PTGSTEIF	—	0000
IEC0	0820	—	DMA1IE	AD1IE	U1TXIE	U1RXIE	SP11IE	SP11EIE	T3IE	T2IE	OC2IE	IC2IE	DMA0IE	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0822	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	DMA2IE	—	—	—	INT1IE	CNIE	CMIE	M1C2IE	SI2C1IE	0000
IEC2	0824	—	—	—	—	—	—	—	—	—	IC4IE	IC3IE	DMA3IE	C1IE	C1RXIE	SPI2IE	SPI2EIE	0000
IEC3	0826	—	—	—	—	—	—	QE11IE	PSEMIE	—	—	—	—	—	M1C2IE	SI2C2IE	—	0000
IEC4	0828	—	—	CTMUIE	—	—	—	—	—	—	C1TXIE	—	—	CRCIE	U2EIE	U1EIE	—	0000
IEC5	082A	PWM2IE	PWM1IE	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IEC6	082C	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	PWM3IE	0000
IEC7	082E	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IEC8	0830	JTAGIE	ICDIE	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
IEC9	0832	—	—	—	—	—	—	—	—	—	PTG3IE	PTG2IE	PTG1IE	PTG0IE	PTGWDTIE	PTGSTIE	—	0000
IPC0	0840	—	T1IP<2:0>			—	OC1IP<2:0>			—	IC1IP<2:0>			—	INT0IP<2:0>			4444
IPC1	0842	—	T2IP<2:0>			—	OC2IP<2:0>			—	IC2IP<2:0>			—	DMA0IP<2:0>			4444
IPC2	0844	—	U1RXIP<2:0>			—	SP11IP<2:0>			—	SP11EIP<2:0>			—	T3IP<2:0>			4444
IPC3	0846	—	—	—	—	—	DMA1IP<2:0>			—	AD1IP<2:0>			—	U1TXIP<2:0>			0444
IPC4	0848	—	CNIP<2:0>			—	CMIP<2:0>			—	M1C2IP<2:0>			—	SI2C1IP<2:0>			4444
IPC5	084A	—	—	—	—	—	—	—	—	—	—	—	—	—	INT1IP<2:0>			0004
IPC6	084C	—	T4IP<2:0>			—	OC4IP<2:0>			—	OC3IP<2:0>			—	DMA2IP<2:0>			4444
IPC7	084E	—	U2TXIP<2:0>			—	U2RXIP<2:0>			—	INT2IP<2:0>			—	T5IP<2:0>			4444
IPC8	0850	—	C1IP<2:0>			—	C1RXIP<2:0>			—	SPI2IP<2:0>			—	SPI2EIP<2:0>			4444
IPC9	0852	—	—	—	—	—	IC4IP<2:0>			—	IC3IP<2:0>			—	DMA3IP<2:0>			0444
IPC12	0858	—	—	—	—	—	M1C2IP<2:0>			—	SI2C2IP<2:0>			—	—	—	—	0440
IPC14	085C	—	—	—	—	—	QE11IP<2:0>			—	PSEMIP<2:0>			—	—	—	—	0440
IPC16	0860	—	CRCIP<2:0>			—	U2EIP<2:0>			—	U1EIP<2:0>			—	—	—	—	4440
IPC17	0862	—	—	—	—	—	C1TXIP<2:0>			—	—	—	—	—	—	—	—	0400
IPC19	0866	—	—	—	—	—	—	—	—	—	CTMUIP<2:0>			—	—	—	—	0040

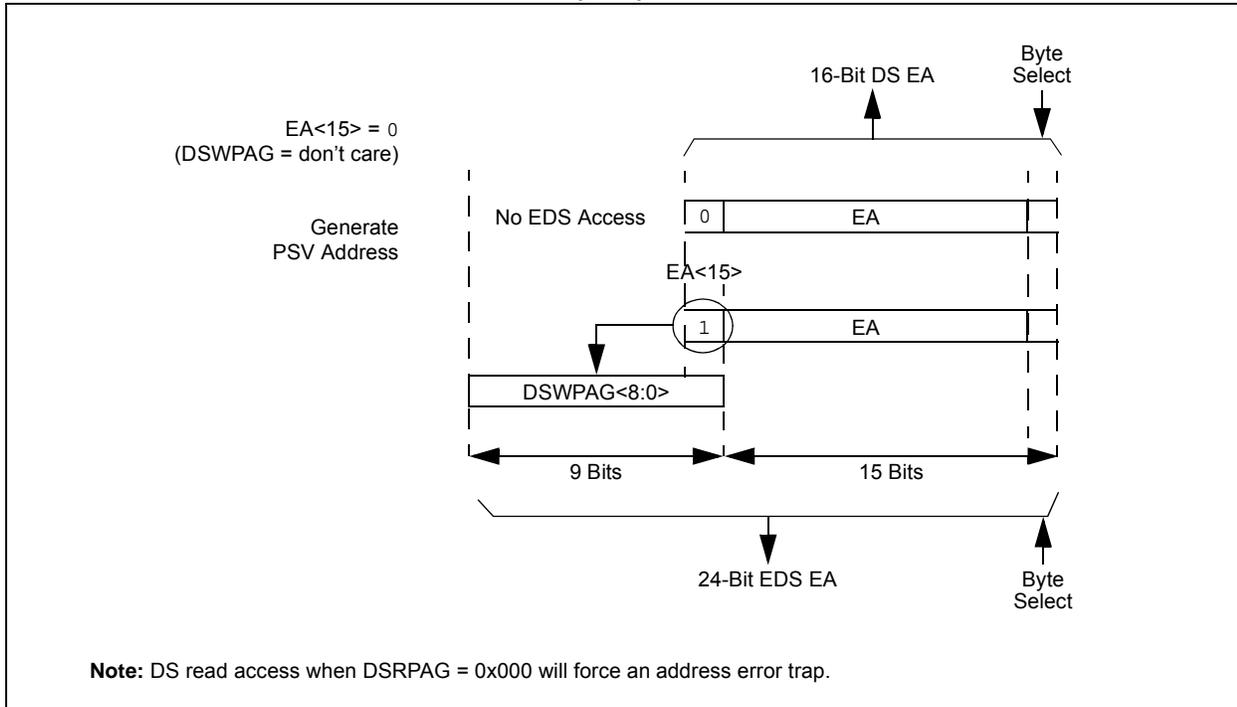
Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-8: TIMER1 THROUGH TIMER5 REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TMR1	0100	Timer1 Register																xxxx
PR1	0102	Period Register 1																FFFF
T1CON	0104	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	TSYNC	TCS	—	—	0000
TMR2	0106	Timer2 Register																xxxx
TMR3HLD	0108	Timer3 Holding Register (for 32-bit timer operations only)																xxxx
TMR3	010A	Timer3 Register																xxxx
PR2	010C	Period Register 2																FFFF
PR3	010E	Period Register 3																FFFF
T2CON	0110	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T3CON	0112	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000
TMR4	0114	Timer4 Register																xxxx
TMR5HLD	0116	Timer5 Holding Register (for 32-bit operations only)																xxxx
TMR5	0118	Timer5 Register																xxxx
PR4	011A	Period Register 4																FFFF
PR5	011C	Period Register 5																FFFF
T4CON	011E	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	T32	—	TCS	—	—	0000
T5CON	0120	TON	—	TSIDL	—	—	—	—	—	—	TGATE	TCKPS<1:0>	—	—	TCS	—	—	0000

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

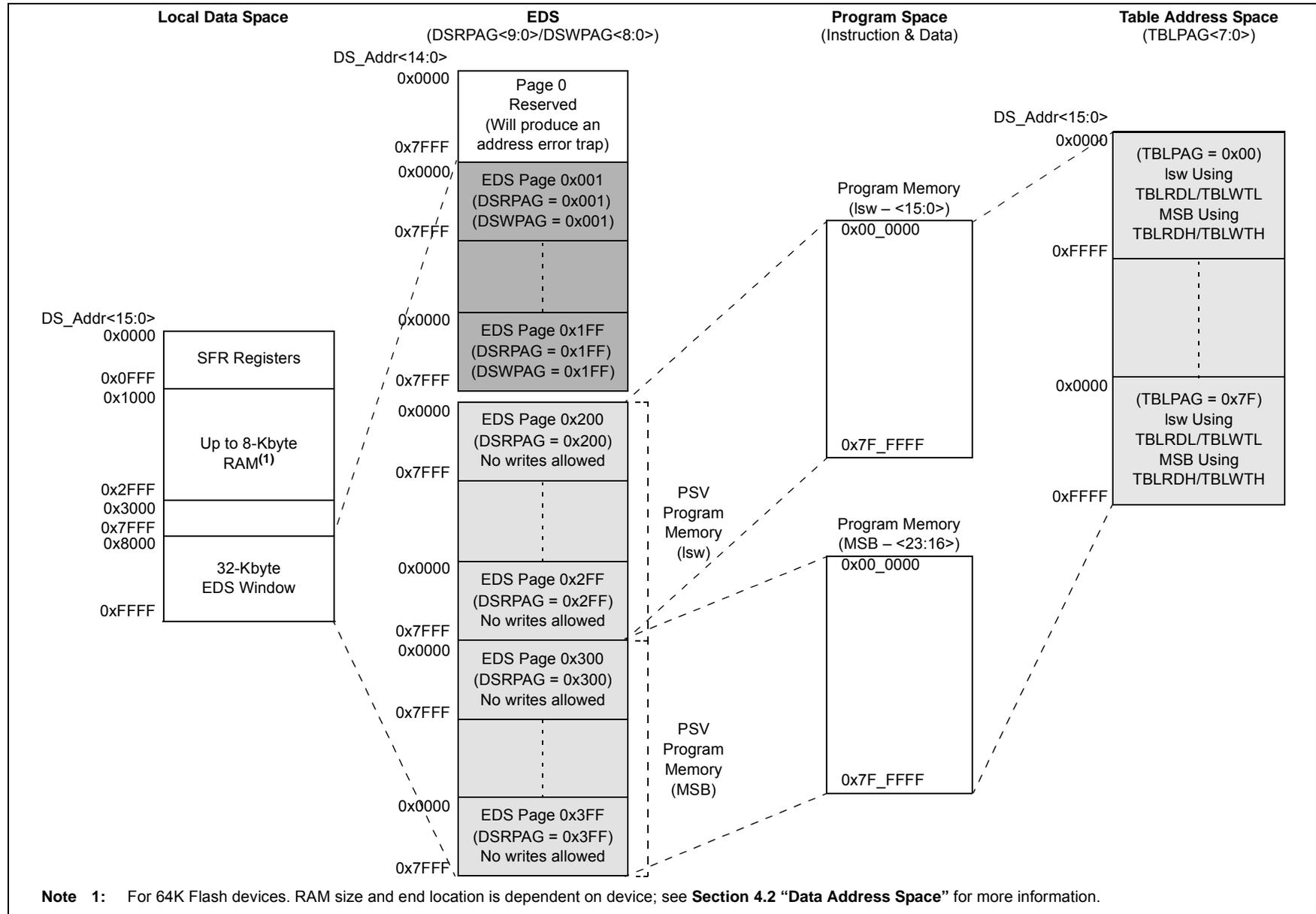
EXAMPLE 4-2: EXTENDED DATA SPACE (EDS) WRITE ADDRESS GENERATION



The paged memory scheme provides access to multiple 32-Kbyte windows in the EDS and PSV memory. The Data Space Page registers, DSxPAG, in combination with the upper half of the Data Space address, can provide up to 16 Mbytes of additional address space in the EDS and 8 Mbytes (DSRPAG only) of PSV address space. The paged data memory space is shown in Example 4-3.

The Program Space (PS) can be accessed with a DSRPAG of 0x200 or greater. Only reads from PS are supported using the DSRPAG. Writes to PS are not supported, so DSWPAG is dedicated to DS, including EDS only. The Data Space and EDS can be read from, and written to, using DSRPAG and DSWPAG, respectively.

EXAMPLE 4-3: PAGED DATA MEMORY SPACE



11.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. The challenge is even greater on low pin count devices. In an application where more than one peripheral needs to be assigned to a single pin, inconvenient work-arounds in application code, or a complete redesign, may be the only option.

Peripheral Pin Select configuration provides an alternative to these choices by enabling peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the device to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select configuration feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of most digital peripherals to any one of these I/O pins. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

11.4.1 AVAILABLE PINS

The number of available pins is dependent on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the label, “RPn” or “RPI n”, in their full pin designation, where “n” is the remappable pin number. “RP” is used to designate pins that support both remappable input and output functions, while “RPI” indicates pins that support remappable input functions only.

11.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the Peripheral Pin Select are all digital-only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer-related peripherals (input capture and output compare) and interrupt-on-change inputs.

In comparison, some digital-only peripheral modules are never included in the Peripheral Pin Select feature. This is because the peripheral’s function requires special I/O circuitry on a specific port and cannot be easily connected to multiple pins. These modules include I²C™ and the PWM. A similar requirement excludes all modules with analog inputs, such as the ADC Converter.

A key difference between remappable and non-remappable peripherals is that remappable peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non-remappable peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

When a remappable peripheral is active on a given I/O pin, it takes priority over all other digital I/O and digital communication peripherals associated with the pin. Priority is given regardless of the type of peripheral that is mapped. Remappable peripherals never take priority over any analog functions associated with the pin.

11.4.3 CONTROLLING PERIPHERAL PIN SELECT

Peripheral Pin Select features are controlled through two sets of SFRs: one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral’s input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1 (CONTINUED)

- bit 3 **TRIGMODE:** Trigger Status Mode Select bit
1 = TRIGSTAT (OCxCON2<6>) is cleared when OCxRS = OCxTMR or in software
0 = TRIGSTAT is cleared only by software
- bit 2-0 **OCM<2:0>:** Output Compare x Mode Select bits
111 = Center-Aligned PWM mode: Output set high when OCxTMR = OCxR and set low when OCxTMR = OCxRS⁽¹⁾
110 = Edge-Aligned PWM mode: Output set high when OCxTMR = 0 and set low when OCxTMR = OCxR⁽¹⁾
101 = Double Compare Continuous Pulse mode: Initializes OCx pin low, toggles OCx state continuously on alternate matches of OCxR and OCxRS
100 = Double Compare Single-Shot mode: Initializes OCx pin low, toggles OCx state on matches of OCxR and OCxRS for one cycle
011 = Single Compare mode: Compare event with OCxR, continuously toggles OCx pin
010 = Single Compare Single-Shot mode: Initializes OCx pin high, compare event with OCxR, forces OCx pin low
001 = Single Compare Single-Shot mode: Initializes OCx pin low, compare event with OCxR, forces OCx pin high
000 = Output compare channel is disabled

- Note 1:** OCxR and OCxRS are double-buffered in PWM mode only.
- 2:** Each Output Compare x module (OCx) has one PTG clock source. See **Section 24.0 “Peripheral Trigger Generator (PTG) Module”** for more information.
PTGO4 = OC1
PTGO5 = OC2
PTGO6 = OC3
PTGO7 = OC4

REGISTER 16-15: FCLCONx: PWMx FAULT CURRENT-LIMIT CONTROL REGISTER⁽¹⁾

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	CLSRC4	CLSRC3	CLSRC2	CLSRC1	CLSRC0	CLPOL ⁽²⁾	CLMOD
bit 15						bit 8	

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
FLTSRC4	FLTSRC3	FLTSRC2	FLTSRC1	FLTSRC0	FLTPOL ⁽²⁾	FLTMOD1	FLTMOD0
bit 7						bit 0	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **Unimplemented:** Read as '0'
- bit 14-10 **CLSRC<4:0>:** Current-Limit Control Signal Source Select for PWM Generator # bits
 - 11111 = Fault 32
 - 11110 = Reserved
 - .
 - .
 - .
 - 01100 = Reserved
 - 01011 = Comparator 4
 - 01010 = Op Amp/Comparator 3
 - 01001 = Op Amp/Comparator 2
 - 01000 = Op Amp/Comparator 1
 - 00111 = Reserved
 - 00110 = Reserved
 - 00101 = Reserved
 - 00100 = Reserved
 - 00011 = Fault 4
 - 00010 = Fault 3
 - 00001 = Fault 2
 - 00000 = Fault 1 (**default**)
- bit 9 **CLPOL:** Current-Limit Polarity for PWM Generator # bit⁽²⁾
 - 1 = The selected current-limit source is active-low
 - 0 = The selected current-limit source is active-high
- bit 8 **CLMOD:** Current-Limit Mode Enable for PWM Generator # bit
 - 1 = Current-Limit mode is enabled
 - 0 = Current-Limit mode is disabled

- Note 1:** If the PWMLOCK Configuration bit (FOSCSEL<6>) is a '1', the IOCONx register can only be written after the unlock sequence has been executed.
- 2:** These bits should be changed only when PTEN = 0. Changing the clock selection during operation will yield unpredictable results.

18.3 SPIx Control Registers

REGISTER 18-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
SPIEN	—	SPISIDL	—	—	SPIBEC<2:0>		
bit 15						bit 8	

R/W-0	R/C-0, HS	R/W-0	R/W-0	R/W-0	R/W-0	R-0, HS, HC	R-0, HS, HC
SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF
bit 7						bit 0	

Legend:	C = Clearable bit	HS = Hardware Settable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **SPIEN:** SPIx Enable bit
 1 = Enables the module and configures SCKx, SDOx, SDIx and \overline{SSx} as serial port pins
 0 = Disables the module
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **SPISIDL:** SPIx Stop in Idle Mode bit
 1 = Discontinues the module operation when device enters Idle mode
 0 = Continues the module operation in Idle mode
- bit 12-11 **Unimplemented:** Read as '0'
- bit 10-8 **SPIBEC<2:0>:** SPIx Buffer Element Count bits (valid in Enhanced Buffer mode)
Master mode:
 Number of SPIx transfers that are pending.
Slave mode:
 Number of SPIx transfers that are unread.
- bit 7 **SRMPT:** SPIx Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode)
 1 = SPIx Shift register is empty and Ready-To-Send or receive the data
 0 = SPIx Shift register is not empty
- bit 6 **SPIROV:** SPIx Receive Overflow Flag bit
 1 = A new byte/word is completely received and discarded; the user application has not read the previous data in the SPIxBUF register
 0 = No overflow has occurred
- bit 5 **SRXMPT:** SPIx Receive FIFO Empty bit (valid in Enhanced Buffer mode)
 1 = RX FIFO is empty
 0 = RX FIFO is not empty
- bit 4-2 **SISEL<2:0>:** SPIx Buffer Interrupt Mode bits (valid in Enhanced Buffer mode)
 111 = Interrupt when the SPIx transmit buffer is full (SPITBF bit is set)
 110 = Interrupt when last bit is shifted into SPIxSR and as a result, the TX FIFO is empty
 101 = Interrupt when the last bit is shifted out of SPIxSR and the transmit is complete
 100 = Interrupt when one data is shifted into the SPIxSR and as a result, the TX FIFO has one open memory location
 011 = Interrupt when the SPIx receive buffer is full (SPIRBF bit is set)
 010 = Interrupt when the SPIx receive buffer is 3/4 or more full
 001 = Interrupt when data is available in the receive buffer (SRMPT bit is set)
 000 = Interrupt when the last data in the receive buffer is read and as a result, the buffer is empty (SRXMPT bit is set)

REGISTER 22-3: CTMUICON: CTMU CURRENT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-10 **ITRIM<5:0>**: Current Source Trim bits

011111 = Maximum positive change from nominal current + 62%

011110 = Maximum positive change from nominal current + 60%

•

•

•

000010 = Minimum positive change from nominal current + 4%

000001 = Minimum positive change from nominal current + 2%

000000 = Nominal current output specified by IRNG<1:0>

111111 = Minimum negative change from nominal current – 2%

111110 = Minimum negative change from nominal current – 4%

•

•

•

100010 = Maximum negative change from nominal current – 60%

100001 = Maximum negative change from nominal current – 62%

bit 9-8 **IRNG<1:0>**: Current Source Range Select bits

11 = 100 × Base Current⁽²⁾

10 = 10 × Base Current⁽²⁾

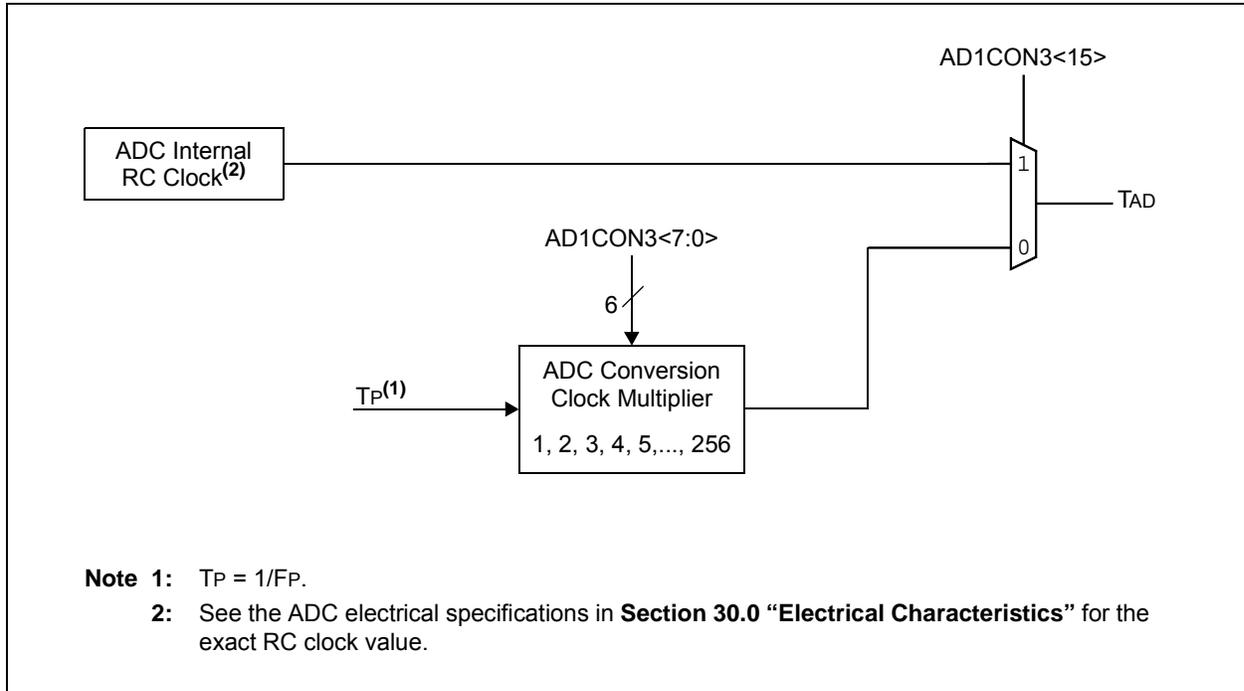
01 = Base Current Level⁽²⁾

00 = 1000 × Base Current^(1,2)

bit 7-0 **Unimplemented**: Read as '0'

- Note 1:** This current range is not available to be used with the internal temperature measurement diode.
- Note 2:** Refer to the CTMU Current Source Specifications (Table 30-56) in **Section 30.0 “Electrical Characteristics”** for the current range selection values.

FIGURE 23-2: ADC CONVERSION CLOCK PERIOD BLOCK DIAGRAM



REGISTER 24-10: PTGADJ: PTG ADJUST REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGADJ<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGADJ<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-0 **PTGADJ<15:0>**: PTG Adjust Register bits
 This register holds user-supplied data to be added to the PTGTxLIM, PTGCxLIM, PTGSDLIM or PTGL0 registers with the PTGADD command.

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

REGISTER 24-11: PTGL0: PTG LITERAL 0 REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGL0<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PTGL0<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-0 **PTGL0<15:0>**: PTG Literal 0 Register bits
 This register holds the 16-bit value to be written to the AD1CHS0 register with the PTGCTRL Step command.

Note 1: This register is read-only when the PTG module is executing Step commands (PTGEN = 1 and PTGSTRT = 1).

TABLE 28-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles ⁽²⁾	Status Flags Affected
9	BTG	BTG <i>f</i> ,#bit4	Bit Toggle <i>f</i>	1	1	None
		BTG <i>Ws</i> ,#bit4	Bit Toggle <i>Ws</i>	1	1	None
10	BTSC	BTSC <i>f</i> ,#bit4	Bit Test <i>f</i> , Skip if Clear	1	1 (2 or 3)	None
		BTSC <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> , Skip if Clear	1	1 (2 or 3)	None
11	BTSS	BTSS <i>f</i> ,#bit4	Bit Test <i>f</i> , Skip if Set	1	1 (2 or 3)	None
		BTSS <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> , Skip if Set	1	1 (2 or 3)	None
12	BTST	BTST <i>f</i> ,#bit4	Bit Test <i>f</i>	1	1	Z
		BTST.C <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to C	1	1	C
		BTST.Z <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to Z	1	1	Z
		BTST.C <i>Ws</i> , <i>Wb</i>	Bit Test <i>Ws</i> < <i>Wb</i> > to C	1	1	C
		BTST.Z <i>Ws</i> , <i>Wb</i>	Bit Test <i>Ws</i> < <i>Wb</i> > to Z	1	1	Z
13	BTSTS	BTSTS <i>f</i> ,#bit4	Bit Test then Set <i>f</i>	1	1	Z
		BTSTS.C <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to C, then Set	1	1	C
		BTSTS.Z <i>Ws</i> ,#bit4	Bit Test <i>Ws</i> to Z, then Set	1	1	Z
14	CALL	CALL <i>lit</i> 23	Call subroutine	2	4	SFA
		CALL <i>Wn</i>	Call indirect subroutine	1	4	SFA
		CALL.L <i>Wn</i>	Call indirect subroutine (long address)	1	4	SFA
15	CLR	CLR <i>f</i>	<i>f</i> = 0x0000	1	1	None
		CLR WREG	WREG = 0x0000	1	1	None
		CLR <i>Ws</i>	<i>Ws</i> = 0x0000	1	1	None
		CLR <i>Acc</i> , <i>Wx</i> , <i>Wxd</i> , <i>Wy</i> , <i>Wyd</i> , <i>AWB</i> ⁽¹⁾	Clear Accumulator	1	1	OA,OB,SA,SB
16	CLRWDT	CLRWDT	Clear Watchdog Timer	1	1	WDTO,Sleep
17	COM	COM <i>f</i>	<i>f</i> = \bar{f}	1	1	N,Z
		COM <i>f</i> ,WREG	WREG = \bar{f}	1	1	N,Z
		COM <i>Ws</i> , <i>Wd</i>	<i>Wd</i> = \overline{Ws}	1	1	N,Z
18	CP	CP <i>f</i>	Compare <i>f</i> with WREG	1	1	C,DC,N,OV,Z
		CP <i>Wb</i> ,#lit8	Compare <i>Wb</i> with lit8	1	1	C,DC,N,OV,Z
		CP <i>Wb</i> , <i>Ws</i>	Compare <i>Wb</i> with <i>Ws</i> (<i>Wb</i> – <i>Ws</i>)	1	1	C,DC,N,OV,Z
19	CP0	CP0 <i>f</i>	Compare <i>f</i> with 0x0000	1	1	C,DC,N,OV,Z
		CP0 <i>Ws</i>	Compare <i>Ws</i> with 0x0000	1	1	C,DC,N,OV,Z
20	CPB	CPB <i>f</i>	Compare <i>f</i> with WREG, with Borrow	1	1	C,DC,N,OV,Z
		CPB <i>Wb</i> ,#lit8	Compare <i>Wb</i> with lit8, with Borrow	1	1	C,DC,N,OV,Z
		CPB <i>Wb</i> , <i>Ws</i>	Compare <i>Wb</i> with <i>Ws</i> , with Borrow (<i>Wb</i> – <i>Ws</i> – C)	1	1	C,DC,N,OV,Z
21	CPSEQ	CPSEQ <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if =	1	1 (2 or 3)	None
	CPBEQ	CPBEQ <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if =	1	1 (5)	None
22	CPSGT	CPSGT <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if >	1	1 (2 or 3)	None
	CPBGT	CPBGT <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if >	1	1 (5)	None
23	CPSLT	CPSLT <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if <	1	1 (2 or 3)	None
	CPBLT	CPBLT <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if <	1	1 (5)	None
24	CPSNE	CPSNE <i>Wb</i> , <i>Wn</i>	Compare <i>Wb</i> with <i>Wn</i> , skip if ≠	1	1 (2 or 3)	None
	CPBNE	CPBNE <i>Wb</i> , <i>Wn</i> , <i>Expr</i>	Compare <i>Wb</i> with <i>Wn</i> , branch if ≠	1	1 (5)	None

Note 1: These instructions are available in dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices only.

2: Read and Read-Modify-Write (e.g., bit operations and logical operations) on non-CPU SFRs incur an additional instruction cycle.

TABLE 30-60: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) ⁽¹⁾ Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
Clock Parameters							
AD50	TAD	ADC Clock Period	117.6	—	—	ns	
AD51	tRC	ADC Internal RC Oscillator Period ⁽²⁾	—	250	—	ns	
Conversion Rate							
AD55	tCONV	Conversion Time	—	14 TAD	—	ns	
AD56	FCNV	Throughput Rate	—	—	500	ksps	
AD57a	TSAMP	Sample Time when Sampling any ANx Input	3 TAD	—	—	—	
AD57b	TSAMP	Sample Time when Sampling the Op Amp Outputs (Configuration A and Configuration B) ^(4,5)	3 TAD	—	—	—	
Timing Parameters							
AD60	tPCS	Conversion Start from Sample Trigger ^(2,3)	2 TAD	—	3 TAD	—	Auto-convert trigger is not selected
AD61	tPSS	Sample Start from Setting Sample (SAMP) bit ^(2,3)	2 TAD	—	3 TAD	—	
AD62	tCSS	Conversion Completion to Sample Start (ASAM = 1) ^(2,3)	—	0.5 TAD	—	—	
AD63	tDPU	Time to Stabilize Analog Stage from ADC Off to ADC On ^(2,3)	—	—	20	μs	(Note 6)

Note 1: Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

2: Parameters are characterized but not tested in manufacturing.

3: Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.

4: See Figure 25-6 for configuration information.

5: See Figure 25-7 for configuration information.

6: The parameter, tDPU, is the time required for the ADC module to stabilize at the appropriate level when the module is turned on (ADON (AD1CON1<15>) = 1). During this time, the ADC result is indeterminate.

TABLE 31-4: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$			
Parameter No.	Typical	Max	Units	Conditions		
Power-Down Current (IPD)						
HDC60e	1400	2500	μA	+150°C	3.3V	Base Power-Down Current (Notes 1, 3)
HDC61c	15	—	μA	+150°C	3.3V	Watchdog Timer Current: ΔIWDT (Notes 2, 4)

- Note 1:** Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to Vss. WDT, etc., are all switched off and VREGS (RCON<8>) = 1.
- Note 2:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.
- Note 3:** These currents are measured on the device containing the most memory in this family.
- Note 4:** These parameters are characterized, but are not tested in manufacturing.

TABLE 31-5: DC CHARACTERISTICS: IDLE CURRENT (IIDLE)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$			
Parameter No.	Typical	Max	Units	Conditions		
HDC44e	12	30	mA	+150°C	3.3V	40 MIPS

TABLE 31-6: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$			
Parameter No.	Typical	Max	Units	Conditions		
HDC20	9	15	mA	+150°C	3.3V	10 MIPS
HDC22	16	25	mA	+150°C	3.3V	20 MIPS
HDC23	30	50	mA	+150°C	3.3V	40 MIPS

TABLE 31-7: DC CHARACTERISTICS: DOZE CURRENT (IDOZE)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$			
Parameter No.	Typical	Max	Doze Ratio	Units	Conditions	
HDC72a	24	35	1:2	mA	+150°C	3.3V
HDC72f ⁽¹⁾	14	—	1:64	mA		
HDC72g ⁽¹⁾	12	—	1:128	mA		

- Note 1:** Parameters with Doze ratios of 1:64 and 1:128 are characterized, but are not tested in manufacturing.

31.2 AC Characteristics and Timing Parameters

The information contained in this section defines dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X AC characteristics and timing parameters for high-temperature devices. However, all AC timing specifications in this section are the same as those in Section 30.2 “AC Characteristics and Timing Parameters”, with the exception of the parameters listed in this section.

Parameters in this section begin with an H, which denotes High temperature. For example, Parameter OS53 in Section 30.2 “AC Characteristics and Timing Parameters” is the Industrial and Extended temperature equivalent of HOS53.

TABLE 31-9: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC

AC CHARACTERISTICS	Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$ Operating voltage VDD range as described in Table 31-1.
---------------------------	---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------

FIGURE 31-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

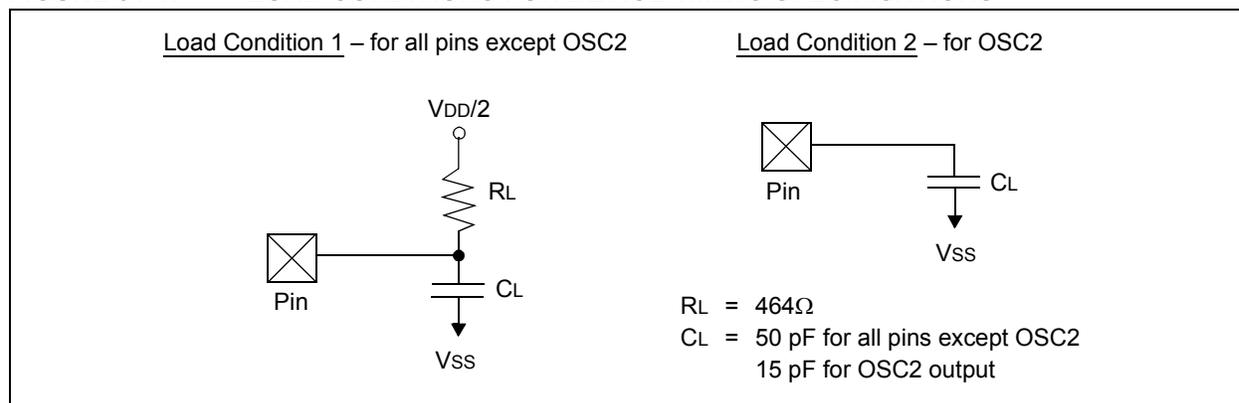


TABLE 31-10: PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
HOS53	DCLK	CLKO Stability (Jitter) ⁽¹⁾	-5	0.5	5	%	Measured over 100 ms period

Note 1: These parameters are characterized by similarity, but are not tested in manufacturing. This specification is based on clock cycle by clock cycle measurements. To calculate the effective jitter for individual time bases or communication clocks use this formula:

$$\text{Peripheral Clock Jitter} = \frac{DCLK}{\sqrt{\left(\frac{FOSC}{\text{Peripheral Bit Rate Clock}}\right)}}$$

For example: FOSC = 32 MHz, DCLK = 5%, SPIx bit rate clock (i.e., SCKx) is 2 MHz.

$$\text{SPI SCK Jitter} = \left[\frac{DCLK}{\sqrt{\left(\frac{32 \text{ MHz}}{2 \text{ MHz}}\right)}} \right] = \left[\frac{5\%}{\sqrt{16}} \right] = \left[\frac{5\%}{4} \right] = 1.25\%$$

33.1 Package Marking Information (Continued)

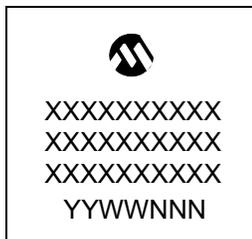
36-Lead VTLA (TLA)



Example



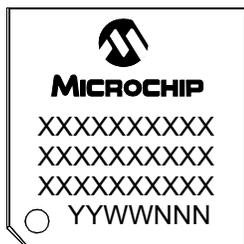
44-Lead VTLA (TLA)



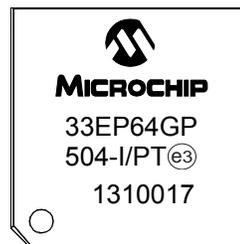
Example



44-Lead TQFP



Example



44-Lead QFN (8x8x0.9 mm)



Example



Revision F (November 2012)

Removed “Preliminary” from data sheet footer.

Revision G (March 2013)

This revision includes the following global changes:

- changes “ $\overline{\text{FLT}}_x$ ” pin function to “FLT_x” on all occurrences
- adds **Section 31.0 “High-Temperature Electrical Characteristics”** for high-temperature (+150°C) data

This revision also includes minor typographical and formatting changes throughout the text.

Other major changes are referenced by their respective section in Table A-5.

TABLE A-5: MAJOR SECTION UPDATES

Section Name	Update Description
Cover Section	<ul style="list-style-type: none"> • Changes internal oscillator specification to 1.0% • Changes I/O sink/source values to 12 mA or 6 mA • Corrects 44-pin VTLA pin diagram (pin 32 now shows as 5V tolerant)
Section 4.0 “Memory Organization”	<ul style="list-style-type: none"> • Deletes references to Configuration Shadow registers • Corrects the spelling of the JTAGIP and PTGWDTIP bits throughout • Corrects the Reset value of all IOCON registers as C000h • Adds footnote to Table 4-42 to indicate the absence of Comparator 3 in 28-pin devices
Section 6.0 “Resets”	<ul style="list-style-type: none"> • Removes references to cold and warm Resets, and clarifies the initial configuration of the device clock source on all Resets
Section 7.0 “Interrupt Controller”	<ul style="list-style-type: none"> • Corrects the definition of GIE as “Global Interrupt Enable” (not “General”)
Section 9.0 “Oscillator Configuration”	<ul style="list-style-type: none"> • Clarifies the behavior of the CF bit when cleared in software • Removes POR behavior footnotes from all control registers • Corrects the tuning range of the TUN<5:0> bits in Register 9-4 to an overall range ±1.5%
Section 13.0 “Timer2/3 and Timer4/5”	<ul style="list-style-type: none"> • Clarifies the presence of the ADC Trigger in 16-bit Timer3 and Timer5, as well as the 32-bit timers
Section 15.0 “Output Compare”	<ul style="list-style-type: none"> • Corrects the first trigger source for SYNCSEL<4:0> (OCxCON2<4:0>) as OCxRS match
Section 16.0 “High-Speed PWM Module”	<ul style="list-style-type: none"> • Clarifies the source of the PWM interrupts in Figure 16-1 • Corrects the Reset states of IOCONx<15:14> in Register 16-13 as ‘11’
Section 17.0 “Quadrature Encoder Interface (QEI) Module”	<ul style="list-style-type: none"> • Clarifies the operation of the IMV<1:0> bits (QEICON<9:8>) with updated text and additional notes • Corrects the first prescaler value for QFVDIV<2:0> (QEI1OC<13:11>), now 1:128
Section 23.0 “10-Bit/12-Bit Analog-to-Digital Converter (ADC)”	<ul style="list-style-type: none"> • Adds note to Figure 23-1 that Op Amp 3 is not available in 28-pin devices • Changes “sample clock” to “sample trigger” in AD1CON1 (Register 23-1) • Clarifies footnotes on op amp usage in Registers 23-5 and 23-6
Section 25.0 “Op Amp/Comparator Module”	<ul style="list-style-type: none"> • Adds Note text to indicate that Comparator 3 is unavailable in 28-pin devices • Splits Figure 25-1 into two figures for clearer presentation (Figure 25-1 for Op amp/Comparators 1 through 3, Figure 25-2 for Comparator 4). Subsequent figures are renumbered accordingly. • Corrects reference description in xxxxx (now (AVDD+AVSS)/2) • Changes CMSTAT<15> in Register 25-1 to “PSIDL”
Section 27.0 “Special Features”	<ul style="list-style-type: none"> • Corrects the addresses of all Configuration bytes for 512 Kbyte devices

INDEX

A

Absolute Maximum Ratings 401

AC Characteristics 413, 471

 10-Bit ADC Conversion Requirements 465

 12-Bit ADC Conversion Requirements 463

 ADC Module 459

 ADC Module (10-Bit Mode) 461, 473

 ADC Module (12-Bit Mode) 460, 473

 Capacitive Loading Requirements on

 Output Pins 413

 DMA Module Requirements 465

 ECANx I/O Requirements 454

 External Clock 414

 High-Speed PWMx Requirements 422

 I/O Timing Requirements 416

 I2Cx Bus Data Requirements (Master Mode) 451

 I2Cx Bus Data Requirements (Slave Mode) 453

 Input Capture x Requirements 420

 Internal FRC Accuracy 415

 Internal LPRC Accuracy 415

 Internal RC Accuracy 472

 Load Conditions 413, 471

 OCx/PWMx Mode Requirements 421

 Op Amp/Comparator Voltage Reference

 Settling Time Specifications 457

 Output Compare x Requirements 421

 PLL Clock 415, 471

 QEI External Clock Requirements 423

 QEI Index Pulse Requirements 425

 Quadrature Decoder Requirements 424

 Reset, Watchdog Timer, Oscillator Start-up Timer,

 Power-up Timer Requirements 417

 SPI1 Master Mode (Full-Duplex, CKE = 0, CKP = x,

 SMP = 1) Requirements 441

 SPI1 Master Mode (Full-Duplex, CKE = 1, CKP = x,

 SMP = 1) Requirements 440

 SPI1 Master Mode (Half-Duplex, Transmit Only)

 Requirements 439

 SPI1 Maximum Data/Clock Rate Summary 438

 SPI1 Slave Mode (Full-Duplex, CKE = 0,

 CKP = 0, SMP = 0) Requirements 449

 SPI1 Slave Mode (Full-Duplex, CKE = 0,

 CKP = 1, SMP = 0) Requirements 447

 SPI1 Slave Mode (Full-Duplex, CKE = 1,

 CKP = 0, SMP = 0) Requirements 443

 SPI1 Slave Mode (Full-Duplex, CKE = 1,

 CKP = 1, SMP = 0) Requirements 445

 SPI2 Master Mode (Full-Duplex, CKE = 0, CKP = x, SMP

 = 1) Requirements 429

 SPI2 Master Mode (Full-Duplex, CKE = 1,

 CKP = x, SMP = 1) Requirements 428

 SPI2 Master Mode (Half-Duplex, Transmit Only)

 Requirements 427

 SPI2 Maximum Data/Clock Rate Summary 426

 SPI2 Slave Mode (Full-Duplex, CKE = 0,

 CKP = 0, SMP = 0) Requirements 437

 SPI2 Slave Mode (Full-Duplex, CKE = 0, CKP = 1, SMP

 = 0) Requirements 435

 SPI2 Slave Mode (Full-Duplex, CKE = 1,

 CKP = 0, SMP = 0) Requirements 431

 SPI2 Slave Mode (Full-Duplex, CKE = 1,

 CKP = 1, SMP = 0) Requirements 433

 Timer1 External Clock Requirements 418

 Timer2/Timer4 External Clock Requirements 419

 Timer3/Timer5 External Clock Requirements 419

 UARTx I/O Requirements 454

ADC

 Control Registers 325

 Helpful Tips 324

 Key Features 321

 Resources 324

Arithmetic Logic Unit (ALU) 44

Assembler

 MPASM Assembler 398

B

Bit-Reversed Addressing 115

 Example 116

 Implementation 115

 Sequence Table (16-Entry) 116

Block Diagrams

 Data Access from Program Space

 Address Generation 117

 16-Bit Timer1 Module 203

 ADC Conversion Clock Period 323

 ADC with Connection Options for ANx Pins

 and Op Amps 322

 Arbiter Architecture 110

 BEMF Voltage Measurement Using ADC 34

 Boost Converter Implementation 32

 CALL Stack Frame 111

 Comparator (Module 4) 356

 Connections for On-Chip Voltage Regulator 384

 CPU Core 36

 CRC Module 373

 CRC Shift Engine 374

 CTMU Module 316

 Digital Filter Interconnect 357

 DMA Controller 141

 DMA Controller Module 139

 dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X

 and PIC24EPXXXGP/MC20X 25

 ECAN Module 288

 EDS Read Address Generation 105

 EDS Write Address Generation 106

 Example of MCLR Pin Connections 30

 High-Speed PWMx Architectural Overview 227

 High-Speed PWMx Register Interconnection 228

 I2Cx Module 274

 Input Capture x 213

 Interleaved PFC 34

 Multiphase Synchronous Buck Converter 33

 Multiplexing Remappable Output for RPN 180

 Op Amp Configuration A 358

 Op Amp Configuration B 359

 Op Amp/Comparator Voltage Reference Module 356

 Op Amp/Comparator x (Modules 1, 2, 3) 355

 Oscillator System 153

 Output Compare x Module 219

 PLL 154

 Programmer's Model 38

 PTG Module 338

 Quadrature Encoder Interface 250

 Recommended Minimum Connection 30

NOTES: