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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

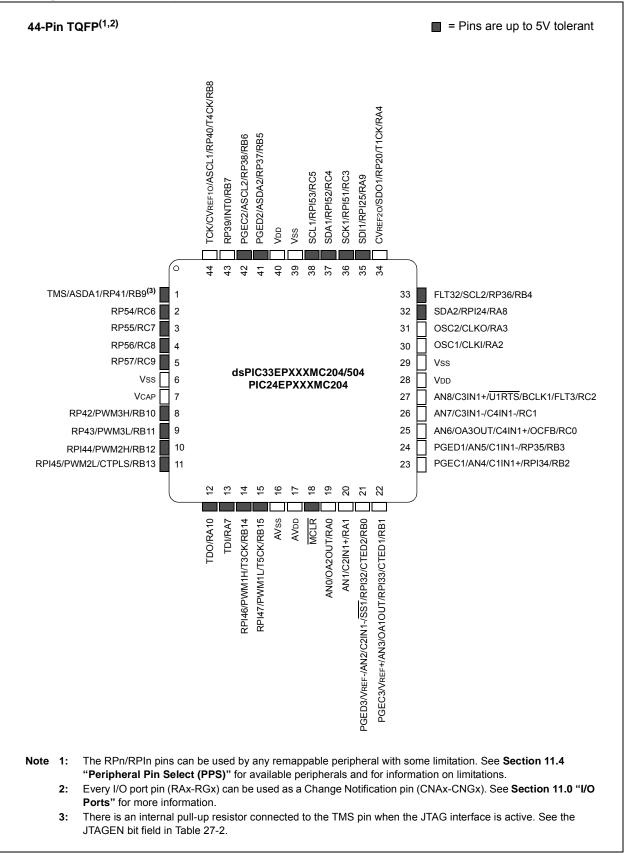
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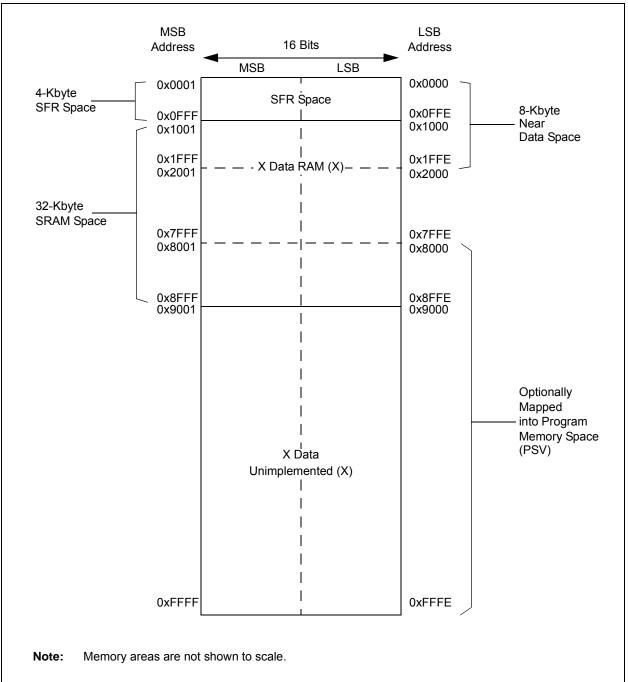
Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	70 MIPs
Connectivity	I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	· ·
RAM Size	8K x 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24ep128mc202t-i-ss

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## Pin Diagrams (Continued)







## TABLE 4-5: INTERRUPT CONTROLLER REGISTER MAP FOR dsPIC33EPXXXGP50X DEVICES ONLY (CONTINUED)

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	08C0	NSTDIS	OVAERR	OVBERR	COVAERR	COVBERR	OVATE	OVBTE	COVTE	SFTACERR	DIV0ERR	DMACERR	MATHERR	ADDRERR	STKERR	OSCFAIL		0000
INTCON2	08C2	GIE	DISI	SWTRAP	_	_	_	_	_	_	—	_	_	—	INT2EP	INT1EP	INT0EP	8000
INTCON3	08C4		_	_	—	_	_		_	_	—	DAE	DOOVR	—	_	_		0000
INTCON4	08C6		_				Ι	_			—	_		—			SGHT	0000
INTTREG	08C8	_	_	_	_		ILR<	3:0>					VECNU	M<7:0>				0000

**Legend:** — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

IABLE 4-2	1: E	ECANTI	REGIST		WHEN		TOTRE	1<0>) =	0 OR .	L FOR asi	PIC33E	PXXXIV	IC/GP5		ICES O	NLY		
File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
C1CTRL1	0400	_	—	CSIDL	ABAT	CANCKS	R	EQOP<2:0	>	OPM	/IODE<2:0	>	—	CANCAP	—	—	WIN	0480
C1CTRL2	0402	_	_	—	_	_	_	—	_	—	_	_		D	NCNT<4:0	>		0000
C1VEC	0404	_	—	—		F	ILHIT<4:0>			—			•	ICODE<6:0	>			0040
C1FCTRL	0406	C	DMABS<2:0	>		_	—	—	_	_	_	_			FSA<4:0>			0000
C1FIFO	0408		—			FBP<	5:0>			—	_			FNRB	<5:0>			0000
C1INTF	040A		—	TXBO	TXBP	RXBP	TXWAR	RXWAR	EWARN	IVRIF	WAKIF	ERRIF	_	FIFOIF	RBOVIF	RBIF	TBIF	0000
C1INTE	040C		—	—		_	—	—	_	IVRIE	WAKIE	ERRIE	_	FIFOIE	RBOVIE	RBIE	TBIE	0000
C1EC	040E				TERRCN	T<7:0>							RERRCN	NT<7:0>				0000
C1CFG1	0410	_	_	_	_	_	_	_	_	SJW<1	:0>			BRP	<5:0>			0000
C1CFG2	0412	_	WAKFIL	_	_	_	SI	=G2PH<2:(	)>	SEG2PHTS	SAM	S	EG1PH<2	:0>	Р	RSEG<2:0	>	0000
C1FEN1	0414	FLTEN15	FLTEN14	FLTEN13	FLTEN12	FLTEN11	FLTEN10	FLTEN9	FLTEN8	FLTEN7	FLTEN6	FLTEN5	FLTEN4	FLTEN3	FLTEN2	FLTEN1	FLTEN0	FFFF
C1FMSKSEL1	0418	F7MSł	<<1:0>	F6MSł	<<1:0>	F5MS	K<1:0>	F4MS	K<1:0>	F3MSK<	<1:0>	F2MS	K<1:0>	F1MSH	<<1:0>	F0MS	<<1:0>	0000
C1FMSKSEL2	041A	F15MS	K<1:0>	F14MS	K<1:0>	F13MS	K<1:0>	F12MS	K<1:0>	F11MSK	<1:0>	F10MS	K<1:0>	F9MSk	<<1:0>	F8MSI	<<1:0>	0000

#### TABLE 4-21: ECAN1 REGISTER MAP WHEN WIN (C1CTRL1<0>) = 0 OR 1 FOR dsPIC33EPXXXMC/GP50X DEVICES ONLY

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

## TABLE 4-22: ECAN1 REGISTER MAP WHEN WIN (C1CTRL1<0>) = 0 FOR dsPIC33EPXXXMC/GP50X DEVICES ONLY

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
	0400- 041E		See definition when WIN = x															
C1RXFUL1	0420	RXFUL15	5 RXFUL14 RXFUL13 RXFUL12 RXFUL11 RXFUL10 RXFUL9 RXFUL8 RXFUL7 RXFUL6 RXFUL5 RXFUL4 RXFUL3 RXFUL2 RXFUL1 RXFUL0 0000															
C1RXFUL2	0422	RXFUL31	RXFUL30	RXFUL29	RXFUL28	RXFUL27	RXFUL26	RXFUL25	RXFUL24	RXFUL23	RXFUL22	RXFUL21	RXFUL20	RXFUL19	RXFUL18	RXFUL17	RXFUL16	0000
C1RXOVF1	0428	RXOVF15	RXOVF14	RXOVF13	RXOVF12	RXOVF11	RXOVF10	RXOVF9	RXOVF8	RXOVF7	RXOVF6	RXOVF5	RXOVF4	RXOVF3	RXOVF2	RXOVF1	RXOVF0	0000
C1RXOVF2	042A	RXOVF31	RXOVF30	RXOVF29	RXOVF28	RXOVF27	RXOVF26	RXOVF25	RXOVF24	RXOVF23	RXOVF22	RXOVF21	RXOVF20	RXOVF19	RXOVF18	RXOVF17	RXOVF16	0000
C1TR01CON	0430	TXEN1	TXABT1	TXLARB1	TXERR1	TXREQ1	RTREN1	TX1PF	RI<1:0>	TXEN0	TXABAT0	TXLARB0	TXERR0	TXREQ0	RTREN0	TX0PF	RI<1:0>	0000
C1TR23CON	0432	TXEN3	TXABT3	TXLARB3	TXERR3	TXREQ3	RTREN3	TX3PF	RI<1:0>	TXEN2	TXABAT2	TXLARB2	TXERR2	TXREQ2	RTREN2	TX2PF	RI<1:0>	0000
C1TR45CON	0434	TXEN5	TXABT5	TXLARB5	TXERR5	TXREQ5	RTREN5	TX5PF	RI<1:0>	TXEN4	TXABAT4	TXLARB4	TXERR4	TXREQ4	RTREN4	TX4PF	RI<1:0>	0000
C1TR67CON	0436	TXEN7	TXABT7	TXLARB7	TXERR7	TXREQ7	RTREN7	TX7PF	RI<1:0>	TXEN6	TXABAT6	TXLARB6	TXERR6	TXREQ6	RTREN6	TX6PF	RI<1:0>	xxxx
C1RXD	0440							E	CAN1 Rece	eive Data Wo	ord							xxxx
C1TXD	0442							E	CAN1 Trans	smit Data Wo	ord							xxxx

Legend: x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0
VAR	—	US1	US0	EDT	DL2	DL1	DL0
bit 15	-	•					bit 8
R/W-0	R/W-0	R/W-1	R/W-0	R/C-0	R-0	R/W-0	R/W-0
SATA	SATB	SATDW	ACCSAT	IPL3 <sup>(2)</sup>	SFA	RND	IF
bit 7		•					bit 0

# **REGISTER 7-2:** CORCON: CORE CONTROL REGISTER<sup>(1)</sup>

Legend:	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bi	t, read as '0'
-n = Value at POR	'1'= Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit

VAR: Variable Exception Processing Latency Control
<ol> <li>1 = Variable exception processing is enabled</li> </ol>
0 = Fixed exception processing is enabled
IPL3: CPU Interrupt Priority Level Status bit 3 <sup>(2)</sup>
<ul> <li>1 = CPU Interrupt Priority Level is greater than 7</li> <li>0 = CPU Interrupt Priority Level is 7 or less</li> </ul>

**Note 1:** For complete register details, see Register 3-2.

2: The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ROON		ROSSLP	ROSEL	RODIV3 <sup>(1)</sup>	RODIV2 <sup>(1)</sup>	RODIV1 <sup>(1)</sup>	RODIV0 <sup>(1)</sup>
bit 15						•	bit
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	_	_		_		_	
bit 7							bit
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'	
-n = Value at		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	iown
bit 14	0 = Reference	e oscillator outp e oscillator outp i <b>ted:</b> Read as '	out is disabled		.K pin <sup>(2)</sup>		
bit 13	-	ference Oscilla		en hit			
	1 = Reference	e oscillator out e oscillator out	out continues	to run in Sleep			
bit 12	1 = Oscillator	erence Oscillato crystal is used lock is used as	as the refere	nce clock			
bit 11-8	1111 = Refer 1110 = Refer 1101 = Refer 1000 = Refer 1011 = Refer 1001 = Refer 1000 = Refer 0111 = Refer 0111 = Refer 0101 = Refer 0100 = Refer 0101 = Refer 0011 = Refer 0011 = Refer 0011 = Refer	Reference Os rence clock divi rence clock divi	ded by 32,763 ded by 16,384 ded by 8,192 ded by 4,096 ded by 2,048 ded by 1,024 ded by 512 ded by 512 ded by 256 ded by 128 ded by 64 ded by 32 ded by 16 ded by 8 ded by 4	8			
	0000 = Refer	ence clock	-				

#### REGISTER 9-5: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

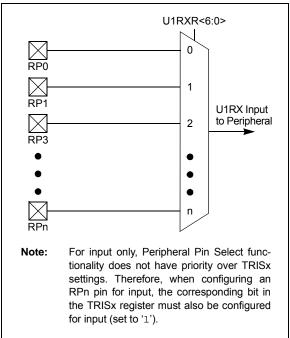
- **Note 1:** The reference oscillator output must be disabled (ROON = 0) before writing to these bits.
  - 2: This pin is remappable. See Section 11.4 "Peripheral Pin Select (PPS)" for more information.

#### 11.4.4 INPUT MAPPING

The inputs of the Peripheral Pin Select options are mapped on the basis of the peripheral. That is, a control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see Register 11-1 through Register 11-17). Each register contains sets of 7-bit fields, with each set associated with one of the remappable peripherals. Programming a given peripheral's bit field with an appropriate 7-bit value maps the RPn pin with the corresponding value to that peripheral. For any given device, the valid range of values for any bit field corresponds to the maximum number of Peripheral Pin Selections supported by the device.

For example, Figure 11-2 illustrates remappable pin selection for the U1RX input.

#### FIGURE 11-2: REMAPPABLE INPUT FOR U1RX



#### 11.4.4.1 Virtual Connections

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X devices support virtual (internal) connections to the output of the op amp/ comparator module (see Figure 25-1 in Section 25.0 "Op Amp/Comparator Module"), and the PTG module (see Section 24.0 "Peripheral Trigger Generator (PTG) Module").

In addition, dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X devices support virtual connections to the filtered QEI module inputs: FINDX1, FHOME1, FINDX2 and FHOME2 (see Figure 17-1 in Section 17.0 "Quadrature Encoder Interface (QEI) Module (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X Devices Only)".

Virtual connections provide a simple way of interperipheral connection without utilizing a physical pin. For example, by setting the FLT1R<6:0> bits of the RPINR12 register to the value of `b0000001, the output of the analog comparator, C1OUT, will be connected to the PWM Fault 1 input, which allows the analog comparator to trigger PWM Faults without the use of an actual physical pin on the device.

Virtual connection to the QEI module allows peripherals to be connected to the QEI digital filter input. To utilize this filter, the QEI module must be enabled and its inputs must be connected to a physical RPn pin. Example 11-2 illustrates how the input capture module can be connected to the QEI digital filter.

# EXAMPLE 11-2: CONNECTING IC1 TO THE HOME1 QEI1 DIGITAL FILTER INPUT ON PIN 43 OF THE dsPIC33EPXXXMC206 DEVICE

RPINR15 = 0x2500;	/* Connect the QEI1 HOME1 input to RP37 (pin 43) */
RPINR7 = 0x009;	/* Connect the IC1 input to the digital filter on the FHOME1 input */
QEI1IOC = 0x4000;	/* Enable the QEI digital filter */
QEI1CON = 0x8000;	/* Enable the QEI module */

- g) The TRISx registers control only the digital I/O output buffer. Any other dedicated or remappable active "output" will automatically override the TRIS setting. The TRISx register does not control the digital logic "input" buffer. Remappable digital "inputs" do not automatically override TRIS settings, which means that the TRISx bit must be set to input for pins with only remappable input function(s) assigned
- h) All analog pins are enabled by default after any Reset and the corresponding digital input buffer on the pin has been disabled. Only the Analog Pin Select registers control the digital input buffer, *not* the TRISx register. The user must disable the analog function on a pin using the Analog Pin Select registers in order to use any "digital input(s)" on a corresponding pin, no exceptions.

## 11.6 I/O Ports Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the product page using the link above, enter this URL in your browser:
	http://www.microchip.com/wwwproducts/ Devices.aspx?dDocName=en555464

#### 11.6.1 KEY RESOURCES

- "I/O Ports" (DS70598) in the "dsPIC33/PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related "dsPIC33/PIC24 Family Reference Manual" Sections
- Development Tools

NOTES:

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
			PTPE	R<15:8>			
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
			PTPE	R<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable bit	t	U = Unimpler	mented bit, read	l as '0'	

'0' = Bit is cleared

x = Bit is unknown

## REGISTER 16-3: PTPER: PWMx PRIMARY MASTER TIME BASE PERIOD REGISTER

bit 15-0 **PTPER<15:0>:** Primary Master Time Base (PMTMR) Period Value bits

'1' = Bit is set

#### REGISTER 16-4: SEVTCMP: PWMx PRIMARY SPECIAL EVENT COMPARE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			SEVTC	MP<15:8>			
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
			SEVT	CMP<7:0>			
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable bi	t	U = Unimplem	nented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is set '0' = Bit is cleared						x = Bit is unkr	nown

bit 15-0 SEVTCMP<15:0>: Special Event Compare Count Value bits

-n = Value at POR

#### 18.3 SPIx Control Registers

#### R/W-0 U-0 R/W-0 U-0 R/W-0 R/W-0 R/W-0 U-0 SPIEN SPISIDL SPIBEC<2:0> \_\_\_\_\_ bit 15 R/W-0 R/W-0 R/W-0 R/C-0, HS R/W-0 R/W-0 R-0, HS, HC R-0, HS, HC SRMPT SPIROV SRXMPT SISEL2 SISEL1 SISEL0 SPITBF SPIRBF bit 7 Legend: C = Clearable bit HS = Hardware Settable bit HC = Hardware Clearable bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15 SPIEN: SPIx Enable bit 1 = Enables the module and configures SCKx, SDOx, SDIx and $\overline{SSx}$ as serial port pins 0 = Disables the module bit 14 Unimplemented: Read as '0' bit 13 SPISIDL: SPIx Stop in Idle Mode bit 1 = Discontinues the module operation when device enters Idle mode 0 = Continues the module operation in Idle mode bit 12-11 Unimplemented: Read as '0' bit 10-8 SPIBEC<2:0>: SPIx Buffer Element Count bits (valid in Enhanced Buffer mode) Master mode: Number of SPIx transfers that are pending. Slave mode: Number of SPIx transfers that are unread. SRMPT: SPIx Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode) bit 7 1 = SPIx Shift register is empty and Ready-To-Send or receive the data 0 = SPIx Shift register is not empty bit 6 SPIROV: SPIx Receive Overflow Flag bit

#### REGISTER 18-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER

1 = A new byte/word is completely received and discarded; the user application has not read the previous data in the SPIxBUF register 0 = No overflow has occurred SRXMPT: SPIx Receive FIFO Empty bit (valid in Enhanced Buffer mode)

- 1 = RX FIFO is empty
- 0 = RX FIFO is not empty

#### bit 4-2 SISEL<2:0>: SPIx Buffer Interrupt Mode bits (valid in Enhanced Buffer mode)

- 111 = Interrupt when the SPIx transmit buffer is full (SPITBF bit is set)
  - 110 = Interrupt when last bit is shifted into SPIxSR and as a result, the TX FIFO is empty
  - 101 = Interrupt when the last bit is shifted out of SPIxSR and the transmit is complete
  - 100 = Interrupt when one data is shifted into the SPIxSR and as a result, the TX FIFO has one open memory location
  - 011 = Interrupt when the SPIx receive buffer is full (SPIRBF bit is set)
  - 010 = Interrupt when the SPIx receive buffer is 3/4 or more full
  - 001 = Interrupt when data is available in the receive buffer (SRMPT bit is set)
  - 000 = Interrupt when the last data in the receive buffer is read and as a result, the buffer is empty (SRXMPT bit is set)

bit 5

bit 8

bit 0

U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0		
_		FBP5	FBP4	FBP3	FBP2	FBP1	FBP0		
bit 15							bit 8		
U-0	U-0	R-0	R-0	R-0	R-0	R-0	R-0		
		FNRB5	FNRB4	FNRB3	FNRB2	FNRB1	FNRB0		
bit 7							bit (		
Legend:									
R = Readab	le bit	W = Writable	bit	bit 0 U = Unimplemented bit, read as '0' '0' = Bit is cleared x = Bit is unknown					
-n = Value a	t POR	'1' = Bit is set		-			iown		
bit 15-14	Unimpleme	ented: Read as '	0'						
bit 13-8	FBP<5:0>:	FIFO Buffer Poir	nter bits						
		RB31 buffer							
	011110 <b>= F</b>	RB30 buffer							
	•								
	•								
	•								
	000001 = TRB1 buffer 000000 = TRB0 buffer								
bit 7-6	Unimpleme	ented: Read as '	0'						
bit 5-0	FNRB<5:0	>: FIFO Next Rea	ad Buffer Poir	iter bits					
	011111 <b>= F</b>	RB31 buffer							
	011110 <b>= F</b>	RB30 buffer							
	•								
	•								
	•								
		FRB1 buffer FRB0 buffer							

#### REGISTER 21-5: CxFIFO: ECANx FIFO STATUS REGISTER

#### BUFFER 21-7: ECAN™ MESSAGE BUFFER WORD 6

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Ву	rte 7			
bit 15							bit 8
R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
			Ву	rte 6			
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit				U = Unimplen	nented bit, rea	d as '0'	
-n = Value at POR '1' = Bit is set				'0' = Bit is cleared x = Bit is unknown			

bit 15-8 Byte 7<15:8>: ECAN Message Byte 7 bits

bit 7-0 Byte 6<7:0>: ECAN Message Byte 6 bits

#### BUFFER 21-8: ECAN<sup>™</sup> MESSAGE BUFFER WORD 7

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	—	FILHIT4 <sup>(1)</sup>	FILHIT3 <sup>(1)</sup>	FILHIT2 <sup>(1)</sup>	FILHIT1 <sup>(1)</sup>	FILHITO <sup>(1)</sup>
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_		—				—
bit 7							bit 0
Legend:							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13	Unimplemented: Read as '0'
bit 12-8	FILHIT<4:0>: Filter Hit Code bits <sup>(1)</sup>
	Encodes number of filter that resulted in writing this buffer.
bit 7-0	Unimplemented: Read as '0'

Note 1: Only written by module for receive buffers, unused for transmit buffers.

## 22.0 CHARGE TIME MEASUREMENT UNIT (CTMU)

- Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X and PIC24EPXXXGP/MC20X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to "Charge Time Measurement Unit (CTMU)" (DS70661) in the "dsPIC33/PIC24 Family Reference Manual", which is available on the Microchip web site (www.microchip.com).
  - 2: Some registers and associated bits described in this section may not be available on all devices. Refer to Section 4.0 "Memory Organization" in this data sheet for device-specific register and bit information.

The Charge Time Measurement Unit is a flexible analog module that provides accurate differential time measurement between pulse sources, as well as asynchronous pulse generation. Its key features include:

- Four Edge Input Trigger Sources
- Polarity Control for Each Edge Source
- Control of Edge Sequence
- Control of Response to Edges
- · Precise Time Measurement Resolution of 1 ns
- Accurate Current Source Suitable for Capacitive Measurement
- On-Chip Temperature Measurement using a Built-in Diode

Together with other on-chip analog modules, the CTMU can be used to precisely measure time, measure capacitance, measure relative changes in capacitance or generate output pulses that are independent of the system clock.

The CTMU module is ideal for interfacing with capacitive-based sensors. The CTMU is controlled through three registers: CTMUCON1, CTMUCON2 and CTMUICON. CTMUCON1 and CTMUCON2 enable the module and control edge source selection, edge source polarity selection and edge sequencing. The CTMUICON register controls the selection and trim of the current source.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
EDG1MOD	EDG1POL	EDG1SEL3	EDG1SEL2	EDG1SEL1	EDG1SEL0	EDG2STAT	EDG1STAT			
bit 15		1		11			bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0			
EDG2MOD	EDG2POL	EDG2SEL3	EDG2SEL2	EDG2SEL1	EDG2SEL0	—	_			
bit 7										
Legend:										
R = Readabl	le bit	W = Writable	oit	U = Unimplem	ented bit, read	l as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	red	x = Bit is unkr	nown			
bit 15	EDG1MOD: E	Edge 1 Edge Sa	ampling Mode	Selection bit						
	1 = Edge 1 is edge-sensitive									
	•	s level-sensitive								
bit 14		dge 1 Polarity								
		s programmed f								
L:1 40 40	•	s programmed f	•	•						
bit 13-10		:0>: Edge 1 So	urce Select bits	5						
	1xxx = Reserved 01xx = Reserved									
	0011 = CTED1 pin									
	0010 = CTED2 pin									
	0001 = OC1									
hit O	0000 = Timer		:+							
bit 9		Edge 2 Status b		vritten to control	the odge cou	reo				
	1 = Edge 2 h				the edge sou	ice.				
		as not occurred	ł							
bit 8	EDG1STAT: E	Edge 1 Status b	it							
			1 and can be v	vritten to control	the edge sou	rce.				
	1 = Edge 1 h									
	-	as not occurred								
bit 7		Edge 2 Edge Sa		Selection bit						
		s edge-sensitive s level-sensitive								
bit 6	•	dge 2 Polarity								
Sit 0		s programmed f		dae response						
		s programmed f								
bit 5-2	EDG2SEL<3	:0>: Edge 2 So	urce Select bits	3						
	1111 <b>= Rese</b>	1111 = Reserved								
	01xx = Rese									
	0100 = CMP <sup>2</sup> 0011 = CTEE									
	0010 = CTEE									
		Ji pili								
	0001 = OC1	module								
		module								

#### REGISTER 22-2: CTMUCON2: CTMU CONTROL REGISTER 2

# dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
CH0NB	_	—	CH0SB4 <sup>(1)</sup>	CH0SB3 <sup>(1)</sup>	CH0SB2 <sup>(1)</sup>	CH0SB1 <sup>(1)</sup>	CH0SB0 <sup>(1)</sup>				
bit 15	•			•			bit 8				
R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
CH0NA			CH0SA4 <sup>(1)</sup>	CH0SA3 <sup>(1)</sup>	CH0SA2 <sup>(1)</sup>	CH0SA1 <sup>(1)</sup>	CH0SA0 <sup>(1)</sup>				
bit 7							bit (				
Legend:											
R = Read		W = Writable		•	nented bit, read						
-n = Value	e at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	iown				
bit 15		nannel 0 Negative	Input Soloot fo	r Samala MUV	'D hit						
DIL 15		el 0 negative input									
		el 0 negative input									
bit 14-13	Unimplem	ented: Read as 'o	)'								
bit 12-8	12-8 <b>CH0SB&lt;4:0&gt;:</b> Channel 0 Positive Input Select for Sample MUXB bits <sup>(1)</sup>										
		pen; use this sele				ement					
	11110 <b>= C</b>	11110 = Channel 0 positive input is connected to the CTMU temperature measurement diode (CTMU TEMP)									
	11101 <b>=</b> R										
	11100 = R 11011 = R										
		hannel 0 positive	input is the outr	out of OA3/AN6	<sub>)</sub> (2,3)						
		hannel 0 positive									
	11000 <b>= C</b>	hannel 0 positive	input is the outp	out of OA1/AN3	<sub>3</sub> (2)						
	10111 <b>= R</b>	eserved									
	•										
	•										
	10000 <b>= R</b>	eserved									
	01111 <b>= C</b>	hannel 0 positive	input is AN15 <sup>(3)</sup>								
	01110 = C	hannel 0 positive	input is AN14 <sup>(3)</sup>								
	01101 = C	hannel 0 positive	Input is AN130								
	•										
	•										
	00010 <b>= C</b>	00010 = Channel 0 positive input is AN2 <sup>(3)</sup>									
		00001 = Channel 0 positive input is AN1 <sup>(3)</sup>									
L:1 7	00000 = Channel 0 positive input is AN0 <sup>(3)</sup>										
DIT /	<ul> <li>it 7 CH0NA: Channel 0 Negative Input Select for Sample MUXA bit</li> <li>1 = Channel 0 negative input is AN1<sup>(1)</sup></li> </ul>										
		el 0 negative input									
bit 6-5		ented: Read as '									
Note 1:	to determine I	AN7 are repurpos now enabling a pa									
-	and 3.						- >				
2:		t is used if the co		amp is selecte	d (OPMODE (C	MxCON<10>) :	= 1);				

#### REGISTER 23-6: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER

3: See the "**Pin Diagrams**" section for the available analog channels for each device.

otherwise, the ANx input is used.

# TABLE 30-46:SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0)TIMING REQUIREMENTS

АС СНА	ARACTERIST	<b>FICS</b>	Standard Op (unless othe Operating ter	rwise st	<b>ated)</b> e -40°C	≤ Ta ≤ +8	<b>o 3.6V</b> 85°C for Industrial 125°C for Extended
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур. <sup>(2)</sup>	Max.	Units	Conditions
SP70	FscP	Maximum SCK1 Input Frequency	_		Lesser of FP or 11	MHz	(Note 3)
SP72	TscF	SCK1 Input Fall Time	_			ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK1 Input Rise Time	—			ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO1 Data Output Fall Time	—	_		ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO1 Data Output Rise Time				ns	See Parameter DO31 (Note 4)
SP35	TscH2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	_	_	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30		—	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	_	_	ns	
SP50	TssL2scH, TssL2scL	$\overline{SS1}$ ↓ to SCK1 ↑ or SCK1 ↓ Input	120	_	_	ns	
SP51	TssH2doZ	SS1 ↑ to SDO1 Output High-Impedance	10	_	50	ns	(Note 4)
SP52	TscH2ssH, TscL2ssH	SS1 ↑ after SCK1 Edge	1.5 Tcy + 40	_	_	ns	(Note 4)
SP60	TssL2doV	SDO1 Data Output Valid after SS1 Edge	—	_	50	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK1 is 91 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI1 pins.

AC CH	ARACTEI	RISTICS	Standard O (unless oth Operating te	erwise	ture -40°C	≤ Ta ≤ +	7 <b>to 3.6V</b> -85°C for Industrial -125°C for Extended
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions
			Devi	ce Sup	ply		
AD01	AVDD	Module VDD Supply	Greater of: VDD – 0.3 or 3.0		Lesser of: VDD + 0.3 or 3.6	V	
AD02	AVss	Module Vss Supply	Vss – 0.3		Vss + 0.3	V	
			Refere	ence In	puts		
AD05	Vrefh	Reference Voltage High	AVss + 2.5		AVDD	V	VREFH = VREF+ VREFL = VREF- <b>(Note 1)</b>
AD05a			3.0	_	3.6	V	VREFH = AVDD VREFL = AVSS = 0
AD06	VREFL	Reference Voltage Low	AVss		AVDD - 2.5	V	(Note 1)
AD06a			0	_	0	V	VREFH = AVDD VREFL = AVSS = 0
AD07	VREF	Absolute Reference Voltage	2.5	_	3.6	V	VREF = VREFH - VREFL
AD08	IREF	Current Drain	_		10 600	μΑ μΑ	ADC off ADC on
AD09	Iad	Operating Current <sup>(2)</sup>	—	5	—	mA	ADC operating in 10-bit mode (Note 1)
			—	2	—	mA	ADC operating in 12-bit mode (Note 1)
	•		Ana	log Inp	ut		
AD12	Vinh	Input Voltage Range VinH	VINL		Vrefh	V	This voltage reflects Sample-and- Hold Channels 0, 1, 2 and 3 (CH0-CH3), positive input
AD13	VINL	Input Voltage Range VINL	Vrefl	_	AVss + 1V	V	This voltage reflects Sample-and- Hold Channels 0, 1, 2 and 3 (CH0-CH3), negative input
AD17	Rin	Recommended Impedance of Analog Voltage Source	_	_	200	Ω	Impedance to achieve maximum performance of ADC

## TABLE 30-57: ADC MODULE SPECIFICATIONS

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

2: Parameter is characterized but not tested in manufacturing.

AC CHA	ARACTER	RISTICS	$ \begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(1)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array} $					
Param No.	Symbol	Characteristic	Min.	Тур.	Max.	Units	Conditions	
		Cloci	k Parame	eters				
AD50	TAD	ADC Clock Period	76	_	_	ns		
AD51	tRC	ADC Internal RC Oscillator Period <sup>(2)</sup>		250	_	ns		
		Conv	version F	Rate		•		
AD55	tCONV	Conversion Time		12 Tad	_			
AD56	FCNV	Throughput Rate	_	—	1.1	Msps	Using simultaneous sampling	
AD57a	TSAMP	Sample Time when Sampling any ANx Input	2 Tad	—	_	—		
AD57b	TSAMP	Sample Time when Sampling the Op Amp Outputs (Configuration A and Configuration B) <sup>(4,5)</sup>	4 Tad	_	—	—		
		Timin	g Param	eters				
AD60	tPCS	Conversion Start from Sample Trigger <sup>(2,3)</sup>	2 Tad	—	3 Tad	_	Auto-convert trigger is not selected	
AD61	tPSS	Sample Start from Setting Sample (SAMP) bit <sup>(2,3))</sup>	2 Tad	—	3 Tad	—		
AD62	tcss	Conversion Completion to Sample Start (ASAM = 1) <sup>(2,3)</sup>	_	0.5 Tad		—		
AD63	tdpu	Time to Stabilize Analog Stage from ADC Off to ADC On <sup>(2,3)</sup>		—	20	μs	(Note 6)	

#### TABLE 30-61: ADC CONVERSION (10-BIT MODE) TIMING REQUIREMENTS

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

- 2: Parameters are characterized but not tested in manufacturing.
- **3:** Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.
- 4: See Figure 25-6 for configuration information.
- 5: See Figure 25-7 for configuration information.
- 6: The parameter, tDPU, is the time required for the ADC module to stabilize at the appropriate level when the module is turned on (ADON (AD1CON1<15>) = 1). During this time, the ADC result is indeterminate.

### TABLE 30-62: DMA MODULE TIMING REQUIREMENTS

AC CH	ARACTERISTICS	$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param No.	Characteristic	Min.	Тур. <sup>(1)</sup>	Max.	Units	Conditions	
DM1	DMA Byte/Word Transfer Latency	1 TCY <sup>(2)</sup> — — ns					

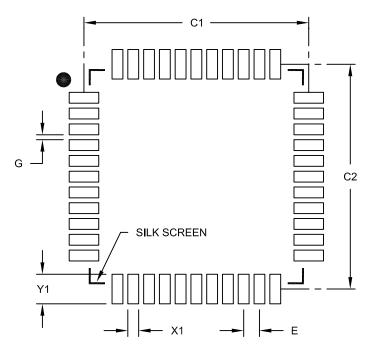
Note 1: These parameters are characterized, but not tested in manufacturing.

2: Because DMA transfers use the CPU data bus, this time is dependent on other functions on the bus.

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44-Lead Plastic Thin Quad Flatpack (PT) 10X10X1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



### **RECOMMENDED LAND PATTERN**

	N	MILLIMETERS			
Dimensior	MIN	NOM	MAX		
Contact Pitch	E		0.80 BSC		
Contact Pad Spacing	C1		11.40		
Contact Pad Spacing	C2		11.40		
Contact Pad Width (X44)	X1			0.55	
Contact Pad Length (X44)	Y1			1.50	
Distance Between Pads	G	0.25			

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076B