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# What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

# Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

# Details

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Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	I <sup>2</sup> C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, Motor Control PWM, POR, PWM, WDT
Number of I/O	53
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K × 16
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 16x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 150°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24ep256mc206-h-pt

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# TABLE 2: dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X MOTOR CONTROL FAMILIES (CONTINUED)

	~	s)	-			Rer	nappa	ble P	eriphe	erals								1			
Device	Page Erase Size (Instructions)	Program Flash Memory (Kbyte	RAM (Kbytes)	16-Bit/32-Bit Timers	Input Capture	Output Compare	Motor Control PWM <sup>(4)</sup> (Channels)	Quadrature Encoder Interface	UART	SPI <sup>(2)</sup>	ECAN™ Technology	External Interrupts <sup>(3)</sup>	I <sup>2</sup> C <sup>TM</sup>	<b>CRC Generator</b>	10-Bit/12-Bit ADC (Channels)	Op Amps/Comparators	CTMU	PTG	I/O Pins	Pins	Packages
dsPIC33EP32MC504	512	32	4																		
dsPIC33EP64MC504	1024	64	8																		VTLA <sup>(5)</sup> ,
dsPIC33EP128MC504	1024	128	16	5	4	4	6	1	2	2	1	3	2	1	9	3/4	Yes	Yes	35	44/ 48	TQFP, OEN
dsPIC33EP256MC504	1024	256	32																	40	UQFN
dsPIC33EP512MC504	1024	512	48																		
dsPIC33EP64MC506	1024	64	8																		
dsPIC33EP128MC506	1024	128	16	5	4	4	6	1	2	2	1	2	2	1	16	2/4	Vaa	Voo	52	64	TQFP,
dsPIC33EP256MC506	1024	256	32	э	4	4	0	1	2	2	1	3	2		10	3/4	res	res	53	04	QFN
dsPIC33EP512MC506	1024	512	48																		

 Note 1:
 On 28-pin devices, Comparator 4 does not have external connections. Refer to Section 25.0 "Op Amp/Comparator Module" for details.

 2:
 Only SPI2 is remappable.

3: INT0 is not remappable.

4: Only the PWM Faults are remappable.

5: The SSOP and VTLA packages are not available for devices with 512 Kbytes of memory.

# 4.2.5 X AND Y DATA SPACES

# The dsPIC33EPXXXMC20X/50X and dsPIC33EPXXXGP50X core has two Data Spaces, X and Y. These Data Spaces can be considered either separate (for some DSP instructions) or as one unified linear address range (for MCU instructions). The Data Spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms, such as Finite Impulse Response (FIR) filtering and Fast Fourier Transform (FFT).

The X Data Space is used by all instructions and supports all addressing modes. X Data Space has separate read and write data buses. The X read data bus is the read data path for all instructions that view Data Space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y Data Space is used in concert with the X Data Space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSAC, MPY, MPY. N and MSC) to provide two concurrent data read paths.

Both the X and Y Data Spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X Data Space. Modulo Addressing and Bit-Reversed Addressing are not present in PIC24EPXXXGP/MC20X devices.

All data memory writes, including in DSP instructions, view Data Space as combined X and Y address space. The boundary between the X and Y Data Spaces is device-dependent and is not user-programmable.

# 4.3 Memory Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this link, contains the latest updates and additional information.

Note:	In the event you are not able to access the
	product page using the link above, enter
	this URL in your browser:
	http://www.microchip.com/wwwproducts/
	Devices.aspx?dDocName=en555464

# 4.3.1 KEY RESOURCES

- "Program Memory" (DS70613) in the "dsPIC33/ PIC24 Family Reference Manual"
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

File Name         Addr.         Bit 15         Bit 14         Bit 12         Bit 11         Bit 10         Bit 9         Bit 8         Bit 7         Bit 6         Bit 5         Bit 4         Bit 3         Bit 2         Bit 1         Bit 00         All Reset           OC1CON1         0900         —         —         OCSIDL         CCTSEL<2.0>         —         ENFLT8         ENFLT8         —         OCFIT8         OCFIT8<		+- I U.	001	FULC			CUGII	OUTFU			KE013		F							
OC1CON1         0900         —         —         ENFLTB         ENFLTB         ENFLTB         OCFLTB         OCFLTB         OCFLTA         TRIGMODE         OCM<2:0>         0000           OC1CON2         9902         FLTMD         FLTOUT         FLTRIEN         OCINV         —         —         —         OC32         OCTRIG         TRIGSTAT         OCFLTB         OCFLTA         TRIGMODE         OCM<2:0>         0000           OC100N2         9902         FLTMD         FLTRIEN         OCINV         —         —         —         OC32         OCTRIG         TRIGSTAT         OCTRIS         SYNCSEL-4:0>         0000           OC100N2         9906         —         —         OUDUT Compare 1 Register	File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
OC1CON2       0902       FLTMD       FLTNIEN       OCINV       —       —       OC22       OCTRIG       TRIGSTAT       OCTRIS       SYNCSEL4:0>       0000         OC1RN       0906	OC1CON1	0900	_	—	OCSIDL	C	CTSEL<2:	0>	—	ENFLTB	ENFLTA	_	OCFLTB	OCFLTA	TRIGMODE		OCM<2:0>	•	0000	
0C1RS       0904	OC1CON2	0902	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS		SYN	NCSEL<4:0	)>		000C	
OC1R       096	OC1RS	0904							Outp	out Compare	e 1 Seconda	ary Register							xxxx	
0C1TMR       0908	OC1R	0906								Output Co	mpare 1 Re	egister							xxxx	
OC2CON1         090A         —         OCSIDL         C_TSEL<2:>         —         ENFLTB         ENFLTB         M         OCFLTB         OCFLTA         TRIGMODE         OCM         000000000000000000000000000000000000	OC1TMR	0908								Timer V	alue 1 Regi	ster							xxxx	
OC2CON2       0900       FLTMU       FLTMU FLTNIEN       OCINV       -       -       OC32       OCTRIG       TRIGSTAT       OCTRIS       SYNCSEL4:0>       OOD         OC2R       0906       -       -       OC4       Corras       SYNCSEL4:0>       OOD       OOD       OC2R       OOD       Corras       SYNCSEL4:0>       OOD       OO	OC2CON1	090A		—	OCSIDL	0	CTSEL<2:	0>	—	ENFLTB	ENFLTA	_	OCFLTB	OCFLTA	TRIGMODE		OCM<2:0>		0000	
OC2RS       0906       Image: Second Windows Condows	OC2CON2	090C	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS		SYN	NCSEL<4:0	)>		000C	
OC2R       0910       UNIC UNIC UNIC UNIC UNIC UNIC UNIC UNIC	OC2RS	090E							Outp	out Compare	e 2 Seconda	ary Register								
OC2TMR       0912       Image: Second	OC2R	0910								Output Co	mpare 2 Re	egister							xxxx	
OC3CON1       0914       —       —       OCSIDL       OCTSEL<2:>       —       ENFLTB       ENFLTA       —       OCFLTB       OCFLTA       TRIGMODE       OCM<2:>>       000000000000000000000000000000000000	OC2TMR	0912								Timer V	alue 2 Regi	ster							xxxx	
OC3CON20916FLTMDFLTOUTFLTRIENOCINV———OC32OCTRIGTRIGSTATOCTRISSYNCSEL4:0>0000OC3RS09180918	OC3CON1	0914		—	OCSIDL	0	CTSEL<2:	0>	—	ENFLTB	ENFLTA	_	OCFLTB	OCFLTA	TRIGMODE		OCM<2:0>		0000	
OC3Rs       0918       Output Compare 3 Secondary Register       xxxx         OC3R       091A	OC3CON2	0916	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	—	—	OC32	OCTRIG	TRIGSTAT	OCTRIS		SYN	NCSEL<4:0	)>		000C	
OC3R       091A	OC3RS	0918							Outp	out Compare	e 3 Seconda	ary Register							xxxx	
OC3TMR       091C	OC3R	091A								Output Co	mpare 3 Re	egister							xxxx	
OC4CON1         091E         —         OCSIDL         OCTSEL<2:···         —         ENFLTB         ENFLTB         OCFLTB         OCFLTB         OCFLTA         TRIGMODE         OCM<2:0>         000000000000000000000000000000000000	OC3TMR	091C								Timer V	alue 3 Regi	ster							xxxx	
OC4CON2         0920         FLTMD         FLTRIEN         OCINV         —         —         OC32         OCTRIG         TRIGSTAT         OCTRIS         SYNCSEL<4:0>         000000000000000000000000000000000000	OC4CON1	091E	1E OCSIDL OCTSEL<2:0> - ENFLTB ENFLTA - OCFLTB OCFLTA TRIGMODE OCM<2:0> 000									0000								
OC4Rs0922Output Compare 4 Secondary RegisterxxxxOC4R0924Output Compare 4 RegisterxxxxOC4TMR0926Timer Value 4 Registerxxxx	OC4CON2	0920	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	_	_	OC32	OCTRIG	TRIGSTAT	OCTRIS		SYN	NCSEL<4:0	)>		000C	
OC4R         0924         Output Compare 4 Register         xxxx           OC4TMR         0926         Timer Value 4 Register         xxxx	OC4RS	0922							Outp	out Compare	e 4 Seconda	ary Register							xxxx	
OC4TMR 0926 Timer Value 4 Register xxxx	OC4R	0924								Output Co	mpare 4 Re	egister							xxxx	
	OC4TMR	0926								Timer V	alue 4 Regi	ster							xxxx	

# TABLE 4-10: OUTPUT COMPARE 1 THROUGH OUTPUT COMPARE 4 REGISTER MAP

Legend: x = unknown value on Reset, - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# TABLE 4-19: SPI1 AND SPI2 REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI1STAT	0240	SPIEN	—	SPISIDL	—	—	:	SPIBEC<2:0	>	SRMPT	SPIROV	SRXMPT		SISEL<2:0>		SPITBF	SPIRBF	0000
SPI1CON1	0242	_	_	_	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN		SPRE<2:0>		PPRE	<1:0>	0000
SPI1CON2	0244	FRMEN	SPIFSD	FRMPOL	_	_	_	_	_	_	_	—	_	_	_	FRMDLY	SPIBEN	0000
SPI1BUF	0248							SPI1 Tra	ansmit and F	Receive Buf	fer Registe	r						0000
SPI2STAT	0260	SPIEN	—	SPISIDL	—	—	:	SPIBEC<2:0	)>	SRMPT	SPIROV	SRXMPT		SISEL<2:0>		SPITBF	SPIRBF	0000
SPI2CON1	0262	_	—		DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN		SPRE<2:0>		PPRE	<1:0>	0000
SPI2CON2	0264	FRMEN	SPIFSD	FRMPOL	_	_	_	_	_	_	_	—	_	_	_	FRMDLY	SPIBEN	0000
SPI2BUF	0268							SPI2 Tra	ansmit and F	Receive Buf	fer Registe	r						0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# TABLE 4-42: OP AMP/COMPARATOR REGISTER MAP

File Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CMSTAT	0A80	PSIDL	—	—	—	C4EVT	C3EVT	C2EVT	C1EVT	—	-	—	—	C4OUT	C3OUT	C2OUT	C10UT	0000
CVRCON	0A82	_	CVR2OE	_	—	_	VREFSEL	_	—	CVREN	CVR10E	CVRR	CVRSS		CVR<	3:0>		0000
CM1CON	0A84	CON	COE	CPOL	—		OPMODE	CEVT	COUT	EVPO	_<1:0>	—	CREF		_	CCH	<1:0>	0000
CM1MSKSRC	0A86		—		—		SELSR	CC<3:0>		SELSRCB<3:0>					SELSRC	A<3:0>		0000
CM1MSKCON	0A88	HLMS	—	OCEN	OCNEN	OBEN	OBNEN	OAEN	OANEN	NAGS	PAGS	ACEN	ACNEN	ABEN	ABNEN	AAEN	AANEN	0000
CM1FLTR	0A8A		—		—		—		—		C	FSEL<2:0	>	CFLTREN	0	CFDIV<2:0	>	0000
CM2CON	0A8C	CON	COE	CPOL	—		OPMODE	CEVT	COUT	EVPO	_<1:0>	—	CREF		_	CCH	<1:0>	0000
CM2MSKSRC	0A8E		—		—		SELSR	CC<3:0>		SELSRCB<3:0>			SELSRCA<3:0>			0000		
CM2MSKCON	0A90	HLMS	—	OCEN	OCNEN	OBEN	OBNEN	OAEN	OANEN	NAGS	PAGS	ACEN	ACNEN	ABEN	ABNEN	AAEN	AANEN	0000
CM2FLTR	0A92		—		—		—		—		C	FSEL<2:0	>	CFLTREN	0	CFDIV<2:0	>	0000
CM3CON <sup>(1)</sup>	0A94	CON	COE	CPOL	—		OPMODE	CEVT	COUT	EVPO	_<1:0>	—	CREF		_	CCH	<1:0>	0000
CM3MSKSRC(1)	0A96		—		—		SELSR	CC<3:0>			SELSRC	B<3:0>			SELSRC	A<3:0>		0000
CM3MSKCON <sup>(1)</sup>	0A98	HLMS	—	OCEN	OCNEN	OBEN	OBNEN	OAEN	OANEN	NAGS	PAGS	ACEN	ACNEN	ABEN	ABNEN	AAEN	AANEN	0000
CM3FLTR <sup>(1)</sup>	0A9A	_	_	_	_	_	_	_	_	_	C	FSEL<2:0	>	CFLTREN	(	CFDIV<2:0	>	0000
CM4CON	0A9C	CON	COE	CPOL	_	_	_	CEVT	COUT	EVPO	_<1:0>	_	CREF	_	_	CCH	<1:0>	0000
CM4MSKSRC	0A9E		—		—		SELSR	CC<3:0>			SELSRC	B<3:0>			SELSRC	A<3:0>		0000
CM4MSKCON	0AA0	HLMS	_	OCEN	OCNEN	OBEN	OBNEN	OAEN	OANEN	NAGS	PAGS	ACEN	ACNEN	ABEN	ABNEN	AAEN	AANEN	0000
CM4FLTR	0AA2	_	—	—	—	—	-	—	_	—	C	FSEL<2:0	>	CFLTREN	(	CFDIV<2:0	>	0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: These registers are unavailable on dsPIC33EPXXXGP502/MC502/MC502/MC202 and PIC24EP256GP/MC202 (28-pin) devices.

# TABLE 4-43: CTMU REGISTER MAP

File	Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CTML	JCON1	033A	CTMUEN	-	CTMUSIDL	TGEN	EDGEN	EDGSEQEN	IDISSEN	CTTRIG	—	—	-	—			—	—	0000
CTML	JCON2	033C	EDG1MOD	EDG1POL		EDG1	SEL<3:0>		EDG2STAT	EDG1STAT	EDG2MOD	EDG2POL		EDG2S	EL<3:0>		_		0000
CTML	JICON	033E			ITRIM<5	5:0>			IRNG	6<1:0>	—	_		_	_	_			0000

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

# TABLE 4-44: JTAG INTERFACE REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
JDATAH	0FF0	—	_	—	—						JDATAH	<27:16>						xxxx
JDATAL	0FF2					JDATAL<15:0> 0000											0000	

Legend: x = unknown value on Reset, - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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# EXAMPLE 4-3: PAGED DATA MEMORY SPACE

dsPIC33EPXXXGP50X, dsPIC33EPXXXMC20X/50X AND PIC24EPXXXGP/MC20X

# 4.4.3 DATA MEMORY ARBITRATION AND BUS MASTER PRIORITY

EDS accesses from bus masters in the system are arbitrated.

The arbiter for data memory (including EDS) arbitrates between the CPU, the DMA and the ICD module. In the event of coincidental access to a bus by the bus masters, the arbiter determines which bus master access has the highest priority. The other bus masters are suspended and processed after the access of the bus by the bus master with the highest priority.

By default, the CPU is Bus Master 0 (M0) with the highest priority and the ICD is Bus Master 4 (M4) with the lowest priority. The remaining bus master (DMA Controller) is allocated to M3 (M1 and M2 are reserved and cannot be used). The user application may raise or lower the priority of the DMA Controller to be above that of the CPU by setting the appropriate bits in the EDS Bus Master Priority Control (MSTRPR) register. All bus masters with raised priorities will maintain the same priority relationship relative to each other (i.e., M1 being highest and M3 being lowest, with M2 in between). Also, all the bus masters with priorities below

# FIGURE 4-18: ARBITER ARCHITECTURE

that of the CPU maintain the same priority relationship relative to each other. The priority schemes for bus masters with different MSTRPR values are tabulated in Table 4-62.

This bus master priority control allows the user application to manipulate the real-time response of the system, either statically during initialization or dynamically in response to real-time events.

TABLE 4-62:	DATA MEMORY BUS
	ARBITER PRIORITY

Briority	MSTRPR<15:0	> Bit Setting <sup>(1)</sup>
Phoney	0x0000	0x0020
M0 (highest)	CPU	DMA
M1	Reserved	CPU
M2	Reserved	Reserved
M3	DMA	Reserved
M4 (lowest)	ICD	ICD

**Note 1:** All other values of MSTRPR<15:0> are reserved.





# FIGURE 16-2: HIGH-SPEED PWMx MODULE REGISTER INTERCONNECTION DIAGRAM

### 18.3 SPIx Control Registers

### R/W-0 U-0 R/W-0 U-0 R/W-0 R/W-0 R/W-0 U-0 SPIEN SPISIDL SPIBEC<2:0> \_\_\_\_\_ bit 15 R/W-0 R/W-0 R/W-0 R/C-0, HS R/W-0 R/W-0 R-0, HS, HC R-0, HS, HC SRMPT SPIROV SRXMPT SISEL2 SISEL1 SISEL0 SPITBF SPIRBF bit 7 bit 0 Legend: C = Clearable bit HS = Hardware Settable bit HC = Hardware Clearable bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15 SPIEN: SPIx Enable bit 1 = Enables the module and configures SCKx, SDOx, SDIx and $\overline{SSx}$ as serial port pins 0 = Disables the module bit 14 Unimplemented: Read as '0' bit 13 SPISIDL: SPIx Stop in Idle Mode bit 1 = Discontinues the module operation when device enters Idle mode 0 = Continues the module operation in Idle mode bit 12-11 Unimplemented: Read as '0' bit 10-8 SPIBEC<2:0>: SPIx Buffer Element Count bits (valid in Enhanced Buffer mode) Master mode: Number of SPIx transfers that are pending. Slave mode: Number of SPIx transfers that are unread. **SRMPT:** SPIx Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode) bit 7 1 = SPIx Shift register is empty and Ready-To-Send or receive the data 0 = SPIx Shift register is not empty bit 6 SPIROV: SPIx Receive Overflow Flag bit

### REGISTER 18-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER

1 = A new byte/word is completely received and discarded; the user application has not read the previous data in the SPIxBUF register 0 = No overflow has occurred SRXMPT: SPIx Receive FIFO Empty bit (valid in Enhanced Buffer mode) bit 5 1 = RX FIFO is empty 0 = RX FIFO is not empty bit 4-2 SISEL<2:0>: SPIx Buffer Interrupt Mode bits (valid in Enhanced Buffer mode) 111 = Interrupt when the SPIx transmit buffer is full (SPITBF bit is set) 110 = Interrupt when last bit is shifted into SPIxSR and as a result, the TX FIFO is empty 101 = Interrupt when the last bit is shifted out of SPIxSR and the transmit is complete 100 = Interrupt when one data is shifted into the SPIxSR and as a result, the TX FIFO has one open memory location 011 = Interrupt when the SPIx receive buffer is full (SPIRBF bit is set) 010 = Interrupt when the SPIx receive buffer is 3/4 or more full 001 = Interrupt when data is available in the receive buffer (SRMPT bit is set) 000 = Interrupt when the last data in the receive buffer is read and as a result, the buffer is empty

bit 8

# REGISTER 19-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

bit 3	S: Start bit
	1 = Indicates that a Start (or Repeated Start) bit has been detected last
	0 = Start bit was not detected last
	Hardware is set or clear when a Start, Repeated Start or Stop is detected.
bit 2	<b>R_W:</b> Read/Write Information bit (when operating as I <sup>2</sup> C slave)
	1 = Read – Indicates data transfer is output from the slave
	0 = Write – Indicates data transfer is input to the slave
	Hardware is set or clear after reception of an I <sup>2</sup> C device address byte.
bit 1	RBF: Receive Buffer Full Status bit
	1 = Receive is complete, I2CxRCV is full
	0 = Receive is not complete, I2CxRCV is empty
	Hardware is set when I2CxRCV is written with a received byte. Hardware is clear when software reads
	I2CxRCV.
bit 0	TBF: Transmit Buffer Full Status bit
	1 = Transmit in progress, I2CxTRN is full
	0 = Transmit is complete, I2CxTRN is empty
	Hardware is set when software writes to I2CxTRN. Hardware is clear at completion of a data transmission.

# 24.3 PTG Control Registers

# REGISTER 24-1: PTGCST: PTG CONTROL/STATUS REGISTER

R/W-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
PTGEN	_	PTGSIDL	PTGTOGL	—	PTGSWT <sup>(2)</sup>	PTGSSEN <sup>(3)</sup>	PTGIVIS
bit 15							bit 8
R/W-0	HS-0	U-0	U-0	U-0	U-0	R/W	/-0

R/W-0	HS-0	U-0	U-0	U-0	U-0	R/\	N-0
PTGSTRT	PTGWDTO		_	_	—	PTGITM1 <sup>(1)</sup>	PTGITM0 <sup>(1)</sup>
bit 7							bit 0

Legend:	HS = Hardware Settable bit					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	PTGEN: Module Enable bit
	1 = PTG module is enabled
	0 = PTG module is disabled
bit 14	Unimplemented: Read as '0'
bit 13	PTGSIDL: PTG Stop in Idle Mode bit
	<ul> <li>1 = Discontinues module operation when device enters Idle mode</li> <li>0 = Continues module operation in Idle mode</li> </ul>
bit 12	PTGTOGL: PTG TRIG Output Toggle Mode bit
	<ul> <li>1 = Toggle state of the PTGOx for each execution of the PTGTRIG command</li> <li>0 = Each execution of the PTGTRIG command will generate a single PTGOx pulse determined by the value in the PTGPWDx bits</li> </ul>
bit 11	Unimplemented: Read as '0'
bit 10	PTGSWT: PTG Software Trigger bit <sup>(2)</sup>
	<ul> <li>1 = Triggers the PTG module</li> <li>0 = No action (clearing this bit will have no effect)</li> </ul>
bit 9	PTGSSEN: PTG Enable Single-Step bit <sup>(3)</sup>
	1 = Enables Single-Step mode 0 = Disables Single-Step mode
bit 8	PTGIVIS: PTG Counter/Timer Visibility Control bit
	<ul> <li>1 = Reads of the PTGSDLIM, PTGCxLIM or PTGTxLIM registers return the current values of their corresponding counter/timer registers (PTGSD, PTGCx, PTGTx)</li> <li>0 = Reads of the PTGSDLIM, PTGCxLIM or PTGTxLIM registers return the value previously written to those limit registers</li> </ul>
bit 7	PTGSTRT: PTG Start Sequencer bit
	<ul><li>1 = Starts to sequentially execute commands (Continuous mode)</li><li>0 = Stops executing commands</li></ul>
bit 6	PTGWDTO: PTG Watchdog Timer Time-out Status bit
	<ul> <li>1 = PTG Watchdog Timer has timed out</li> <li>0 = PTG Watchdog Timer has not timed out.</li> </ul>
bit 5-2	Unimplemented: Read as '0'
Note 1:	These bits apply to the PTGWHI and PTGWLO commands only.
2:	This bit is only used with the PTGCTRL step command software trigger option.

3: Use of the PTG Single-Step mode is reserved for debugging tools only.

# FIGURE 30-7: OUTPUT COMPARE x MODULE (OCx) TIMING CHARACTERISTICS



# TABLE 30-27: OUTPUT COMPARE x MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{llllllllllllllllllllllllllllllllllll$					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур.	Max.	Units	Conditions	
OC10	TccF	OCx Output Fall Time	—			ns	See Parameter DO32	
OC11	TccR	OCx Output Rise Time	—	—	—	ns	See Parameter DO31	

Note 1: These parameters are characterized but not tested in manufacturing.

# FIGURE 30-8: OCx/PWMx MODULE TIMING CHARACTERISTICS



# TABLE 30-28: OCx/PWMx MODE TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min.	Тур.	Max.	Units	Conditions	
OC15	TFD	Fault Input to PWMx I/O Change	—	_	Tcy + 20	ns		
OC20	TFLT	Fault Input Pulse Width	Tcy + 20	_	—	ns		

**Note 1:** These parameters are characterized but not tested in manufacturing.

# TABLE 30-47:SPI1 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)TIMING REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)} \\ \mbox{Operating temperature} & -40^\circ C \leq TA \leq +85^\circ C \mbox{ for Industrial} \\ & -40^\circ C \leq TA \leq +125^\circ C \mbox{ for Extended} \end{array}$					
Param.	Symbol	Characteristic <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions	
SP70	FscP	Maximum SCK1 Input Frequency	—	—	15	MHz	(Note 3)	
SP72	TscF	SCK1 Input Fall Time	—	-	_	ns	See Parameter DO32 (Note 4)	
SP73	TscR	SCK1 Input Rise Time	_	—	—	ns	See Parameter DO31 (Note 4)	
SP30	TdoF	SDO1 Data Output Fall Time			_	ns	See Parameter DO32 (Note 4)	
SP31	TdoR	SDO1 Data Output Rise Time	—	-	_	ns	See Parameter DO31 (Note 4)	
SP35	TscH2doV, TscL2doV	SDO1 Data Output Valid after SCK1 Edge	—	6	20	ns		
SP36	TdoV2scH, TdoV2scL	SDO1 Data Output Setup to First SCK1 Edge	30	_	_	ns		
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI1 Data Input to SCK1 Edge	30	_	_	ns		
SP41	TscH2diL, TscL2diL	Hold Time of SDI1 Data Input to SCK1 Edge	30	—	_	ns		
SP50	TssL2scH, TssL2scL	$\overline{SS1}$ ↓ to SCK1 ↑ or SCK1 ↓ Input	120		—	ns		
SP51	TssH2doZ	SS1 ↑ to SDO1 Output High-Impedance	10	—	50	ns	(Note 4)	
SP52	TscH2ssH, TscL2ssH	SS1 ↑ after SCK1 Edge	1.5 Tcy + 40	—	_	ns	(Note 4)	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, +25°C unless otherwise stated.

**3:** The minimum clock period for SCK1 is 66.7 ns. Therefore, the SCK1 clock generated by the master must not violate this specification.

4: Assumes 50 pF load on all SPI1 pins.

	30-37.										
AC CHARACTERISTICS			$\begin{array}{l} \mbox{Standard Operating Conditions: 3.0V to 3.6V} \\ \mbox{(unless otherwise stated)}^{(1)} \\ \mbox{Operating temperature} & -40^{\circ}C \leq TA \leq +85^{\circ}C \mbox{ for Industrial} \\ & -40^{\circ}C \leq TA \leq +125^{\circ}C \mbox{ for Extended} \end{array}$								
Param No.	Symbol	Characteristic	Min.	Min. Typ. Max. Units Conditions							
	Device Supply										
AD01	AVDD	Module VDD Supply	Greater of: VDD – 0.3 or 3.0	—	Lesser of: VDD + 0.3 or 3.6	V					
AD02	AVss	Module Vss Supply	Vss – 0.3	_	Vss + 0.3	V					
		·	Refer	ence In	puts						
AD05	Vrefh	Reference Voltage High	AVss + 2.5	—	AVdd	V	VREFH = VREF+ VREFL = VREF- <b>(Note 1)</b>				
AD05a			3.0	—	3.6	V	VREFH = AVDD VREFL = AVSS = 0				
AD06	VREFL	Reference Voltage Low	AVss	_	AVDD – 2.5	V	(Note 1)				
AD06a	-		0	—	0	V	VREFH = AVDD VREFL = AVSS = 0				
AD07	Vref	Absolute Reference Voltage	2.5	—	3.6	V	VREF = VREFH - VREFL				
AD08	IREF	Current Drain	_	_	10 600	μΑ μΑ	ADC off ADC on				
AD09	IAD	Operating Current <sup>(2)</sup>	—	5	—	mA	ADC operating in 10-bit mode (Note 1)				
			—	2	—	mA	ADC operating in 12-bit mode (Note 1)				
			Ana	log Inp	out	•					
AD12	Vinh	Input Voltage Range Vinн	VINL	_	Vrefh	V	This voltage reflects Sample-and- Hold Channels 0, 1, 2 and 3 (CH0-CH3), positive input				
AD13	VINL	Input Voltage Range VINL	VREFL		AVss + 1V	V	This voltage reflects Sample-and- Hold Channels 0, 1, 2 and 3 (CH0-CH3), negative input				
AD17	Rin	Recommended Impedance of Analog Voltage Source	_		200	Ω	Impedance to achieve maximum performance of ADC				

# TABLE 30-57: ADC MODULE SPECIFICATIONS

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

2: Parameter is characterized but not tested in manufacturing.

AC CHARACTERISTICS		$\begin{tabular}{lllllllllllllllllllllllllllllllllll$					
Param No.	Symbol	Characteristic	Min.	Min. Typ. Max. U		Units	Conditions
		ADC /	Accuracy	/ (12-Bit	Mode)		
AD20a	Nr	Resolution	12	2 Data Bi	its	bits	
AD21a	INL	Integral Nonlinearity	-2.5		2.5	LSb	$-40^{\circ}C \le TA \le +85^{\circ}C$ (Note 2)
			-5.5	_	5.5	LSb	+85°C < TA $\leq$ +125°C (Note 2)
AD22a	DNL	Differential Nonlinearity	-1		1	LSb	$-40^{\circ}C \leq TA \leq +85^{\circ}C \text{ (Note 2)}$
			-1		1	LSb	+85°C < TA $\leq$ +125°C (Note 2)
AD23a	Gerr	Gain Error <sup>(3)</sup>	-10		10	LSb	-40°C $\leq$ TA $\leq$ +85°C (Note 2)
			-10		10	LSb	+85°C < TA $\leq$ +125°C (Note 2)
AD24a	EOFF	Offset Error	-5		5	LSb	$-40^{\circ}C \leq TA \leq +85^{\circ}C$ (Note 2)
			-5		5	LSb	$+85^{\circ}C < TA \le +125^{\circ}C$ (Note 2)
AD25a	—	Monotonicity	_			—	Guaranteed
		Dynamic	Performa	ance (12	Bit Mod	e)	
AD30a	THD	Total Harmonic Distortion <sup>(3)</sup>	_	75		dB	
AD31a	SINAD	Signal to Noise and Distortion <sup>(3)</sup>	_	68	_	dB	
AD32a	SFDR	Spurious Free Dynamic Range <sup>(3)</sup>		80	_	dB	
AD33a	Fnyq	Input Signal Bandwidth <sup>(3)</sup>	_	250		kHz	
AD34a	ENOB	Effective Number of Bits <sup>(3)</sup>	11.09	11.3	_	bits	

# TABLE 30-58: ADC MODULE SPECIFICATIONS (12-BIT MODE)

**Note 1:** Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules (ADC, op amp/comparator and comparator voltage reference) may have degraded performance. Refer to Parameter BO10 in Table 30-13 for the minimum and maximum BOR values.

2: For all accuracy specifications, VINL = AVSS = VREFL = 0V and AVDD = VREFH = 3.6V.

3: Parameters are characterized but not tested in manufacturing.

NOTES:

# 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





	MILLIMETERS					
Dimension	l Limits	MIN	NOM	MAX		
Number of Pins	Ν		28			
Pitch	е		1.27 BSC			
Overall Height	Α	-	-	2.65		
Molded Package Thickness	A2	2.05	-	-		
Standoff §	A1	0.10	-	0.30		
Overall Width	Width E 10.30 BSC					
Molded Package Width	E1	7.50 BSC				
Overall Length	D		17.90 BSC			
Chamfer (Optional)	h	0.25	-	0.75		
Foot Length	L	0.40	-	1.27		
Footprint	L1		1.40 REF			
Lead Angle	Θ	0°	-	-		
Foot Angle	φ	0°	-	8°		
Lead Thickness	С	0.18	-	0.33		
Lead Width	b	0.31	-	0.51		
Mold Draft Angle Top	α	5°	-	15°		
Mold Draft Angle Bottom	β	5°	-	15°		

## Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- 3. Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

48-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) – 6x6x0.5 mm Body [UQFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			S
Dimension	Limits	MIN	NOM	MAX
Number of Pins	N		48	
Pitch	е		0.40 BSC	
Overall Height	Α	0.45	0.50	0.55
Standoff	A1	0.00	0.02	0.05
Contact Thickness	A3	0.127 REF		
Overall Width	E	6.00 BSC		
Exposed Pad Width	E2	4.45	4.60	4.75
Overall Length	D		6.00 BSC	
Exposed Pad Length	D2	4.45	4.60	4.75
Contact Width	b	0.15	0.20	0.25
Contact Length	L	0.30	0.40	0.50
Contact-to-Exposed Pad	K	0.20	-	_

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Package is saw singulated.

3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-153A Sheet 2 of 2

# 64-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm Footprint [TQFP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS			
Dimensio	on Limits	MIN	NOM	MAX	
Number of Leads	Ν		64		
Lead Pitch	е		0.50 BSC		
Overall Height	А	_	-	1.20	
Molded Package Thickness	A2	0.95	1.00	1.05	
Standoff	A1	0.05	-	0.15	
Foot Length	L	0.45	0.60	0.75	
Footprint	L1		1.00 REF		
Foot Angle	φ	0°	3.5°	7°	
Overall Width	E		12.00 BSC		
Overall Length	D		12.00 BSC		
Molded Package Width	E1		10.00 BSC		
Molded Package Length	D1	10.00 BSC			
Lead Thickness	С	0.09	-	0.20	
Lead Width	b	0.17	0.22	0.27	
Mold Draft Angle Top	α	11°	12°	13°	
Mold Draft Angle Bottom	β	11°	12°	13°	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Chamfers at corners are optional; size may vary.

3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.

4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-085B

Section Name	Update Description
Section 16.0 "High-Speed PWM Module (dsPIC33EPXXXMC20X/50X and PIC24EPXXXMC20X Devices Only)"	Updated the High-Speed PWM Module Register Interconnection Diagram (see Figure 16-2). Added the TRGCONx and TRIGx registers (see Register 16-12 and Register 16-14, respectively).
Section 21.0 "Enhanced CAN (ECAN™) Module (dsPIC33EPXXXGP/MC50X Devices Only)"	Updated the CANCKS bit value definitions in CiCTRL1: ECAN Control Register 1 (see Register 21-1).
Section 22.0 "Charge Time Measurement Unit (CTMU)"	Updated the IRNG<1:0> bit value definitions and added Note 2 in the CTMU Current Control Register (see Register 22-3).
Section 25.0 "Op amp/ Comparator Module"	Updated the Op amp/Comparator I/O Operating Modes Diagram (see Figure 25-1). Updated the User-programmable Blanking Function Block Diagram (see Figure 25-3). Updated the Digital Filter Interconnect Block Diagram (see Figure 25-4). Added <b>Section 25.1 "Op amp Application Considerations"</b> . Added Note 2 to the Comparator Control Register (see Register 25-2). Updated the bit definitions in the Comparator Mask Gating Control Register (see Register 25-5).
Section 27.0 "Special Features"	Updated the FICD Configuration Register, updated Note 1, and added Note 3 in the Configuration Byte Register Map (see Table 27-1). Added <b>Section 27.2 "User ID Words"</b> .
Section 30.0 "Electrical Characteristics"	<ul> <li>Updated the following Absolute Maximum Ratings:</li> <li>Maximum current out of Vss pin</li> <li>Maximum current into VDD pin</li> <li>Added Note 1 to the Operating MIPS vs. Voltage (see Table 30-1).</li> </ul>
	Updated all Idle Current (IIDLE) Typical and Maximum DC Characteristics values (see Table 30-7).
	Updated all Doze Current (IDOZE) Typical and Maximum DC Characteristics values (see Table 30-9).
	Added Note 2, removed Parameter CM24, updated the Typical values Parameters CM10, CM20, CM21, CM32, CM41, CM44, and CM45, and updated the Minimum values for CM40 and CM41, and the Maximum value for CM40 in the AC/DC Characteristics: Op amp/Comparator (see Table 30-14).
	Updated Note 2 and the Typical value for Parameter VR310 in the Op amp/ Comparator Reference Voltage Settling Time Specifications (see Table 30-15).
	Added Note 1, removed Parameter VRD312, and added Parameter VRD314 to the Op amp/Comparator Voltage Reference DC Specifications (see Table 30-16).
	Updated the Minimum, Typical, and Maximum values for Internal LPRC Accuracy (see Table 30-22).
	Updated the Minimum, Typical, and Maximum values for Parameter SY37 in the Reset, Watchdog Timer, Oscillator Start-up Timer, Power-up Timer Timing Requirements (see Table 30-24).
	The Maximum Data Rate values were updated for the SPI2 Maximum Data/Clock Rate Summary (see Table 30-35)

# TABLE A-2: MAJOR SECTION UPDATES (CONTINUED)