



Welcome to [E-XFL.COM](https://www.e-xfl.com)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, Motor Control PWM, POR, PWM, WDT
Number of I/O	35
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 18x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep256gm604-i-ml

Table of Contents

dsPIC33EPXXXGM3XX/6XX/7XX Product Family	2
1.0 Device Overview	15
2.0 Guidelines for Getting Started with 16-Bit Digital Signal Controllers	21
3.0 CPU	27
4.0 Memory Organization	37
5.0 Flash Program Memory	103
6.0 Resets	111
7.0 Interrupt Controller	115
8.0 Direct Memory Access (DMA)	129
9.0 Oscillator Configuration	143
10.0 Power-Saving Features	153
11.0 I/O Ports	163
12.0 Timer1	211
13.0 Timer2/3, Timer4/5, Timer6/7 and Timer8/9	213
14.0 Input Capture	219
15.0 Output Compare	223
16.0 High-Speed PWM Module	229
17.0 Quadrature Encoder Interface (QEI) Module	257
18.0 Serial Peripheral Interface (SPI)	273
19.0 Inter-Integrated Circuit™ (I ² C™)	281
20.0 Universal Asynchronous Receiver Transmitter (UART)	289
21.0 Controller Area Network (CAN) Module (dsPIC33EPXXXGM6XX/7XX Devices Only)	295
22.0 Charge Time Measurement Unit (CTMU)	321
23.0 10-Bit/12-Bit Analog-to-Digital Converter (ADC)	327
24.0 Data Converter Interface (DCI) Module	343
25.0 Peripheral Trigger Generator (PTG) Module	349
26.0 Op Amp/Comparator Module	365
27.0 Real-Time Clock and Calendar (RTCC)	383
28.0 Parallel Master Port (PMP)	395
29.0 Programmable Cyclic Redundancy Check (CRC) Generator	405
30.0 Special Features	411
31.0 Instruction Set Summary	419
32.0 Development Support	429
33.0 Electrical Characteristics	433
34.0 High-Temperature Electrical Characteristics	499
35.0 Packaging Information	507
Appendix A: Revision History	527
Index	529
The Microchip Web Site	537
Customer Change Notification Service	537
Customer Support	537
Product Identification System	539

4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-4).

Program memory addresses are always word-aligned on the lower word and addresses are incremented or decremented by two during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

4.1.2 INTERRUPT AND TRAP VECTORS

All dsPIC33EPXXXGM3XX/6XX/7XX devices reserve the addresses between 0x000000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user application at address, 0x000000 of Flash memory, with the actual address for the start of code at address, 0x000002 of Flash memory.

A more detailed discussion of the interrupt vector tables is provided in **Section 7.1 “Interrupt Vector Table”**.

FIGURE 4-4: PROGRAM MEMORY ORGANIZATION

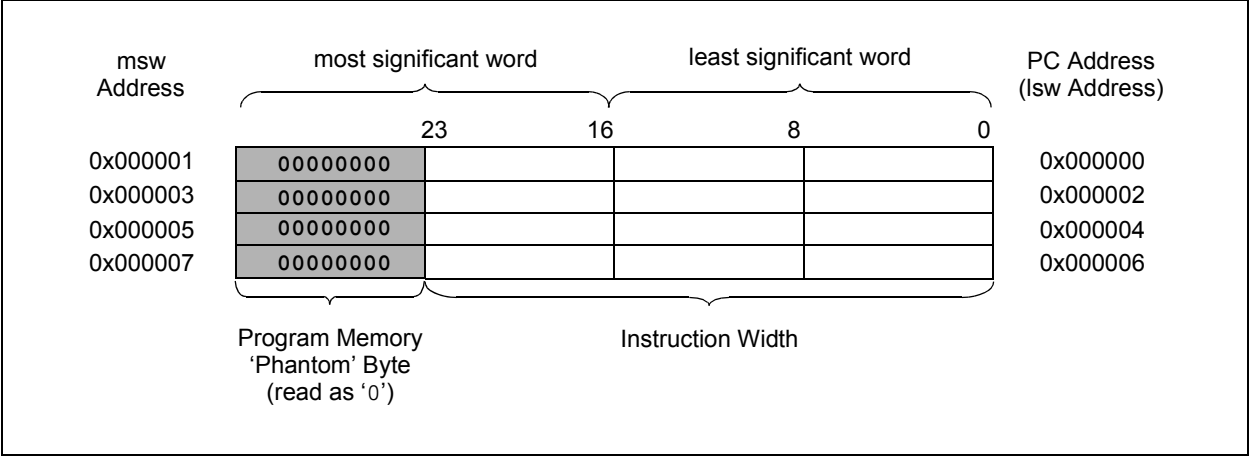


TABLE 4-55: PORTD REGISTER MAP FOR dsPIC33EPXXXGM310/710 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISD	0E30	TRISD<15:12>				—	—	—	TRISD8	—	TRISD<6:1>				—	—	—	0160
PORTD	0E32	RD<15:12>				—	—	—	RD8	—	RD<6:1>				—	—	—	xxxx
LATD	0E34	LATD<15:12>				—	—	—	LATD8	—	LATD<6:1>				—	—	—	xxxx
ODCD	0E36	ODCD<15:12>				—	—	—	ODCD8	—	ODCD<6:1>				—	—	—	0000
CNEND	0E38	CNIED<15:12>				—	—	—	CNIED8	—	CNIED<6:1>				—	—	—	0000
CNPUD	0E3A	CNPUD<15:12>				—	—	—	CNPUD8	—	CNPUD<6:1>				—	—	—	0000
CNPDD	0E3C	CNPDD<15:12>				—	—	—	CNPDD8	—	CNPDD<6:1>				—	—	—	0000
ANSELD	0E3E	ANS<15:14>		—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-56: PORTD REGISTER MAP FOR dsPIC33EPXXXGM306/706 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISD	0E30	—	—	—	—	—	—	—	TRISD8	—	TRISD<6:5>		—	—	—	—	—	0160
PORTD	0E32	—	—	—	—	—	—	—	RD8	—	RD<6:5>		—	—	—	—	—	xxxx
LATD	0E34	—	—	—	—	—	—	—	LATD8	—	LATD<6:5>		—	—	—	—	—	xxxx
ODCD	0E36	—	—	—	—	—	—	—	ODCD8	—	ODCD<6:5>		—	—	—	—	—	0000
CNEND	0E38	—	—	—	—	—	—	—	CNIED8	—	CNIED<6:5>		—	—	—	—	—	0000
CNPUD	0E3A	—	—	—	—	—	—	—	CNPUD8	—	CNPUD<6:5>		—	—	—	—	—	0000
CNPDD	0E3C	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-57: PORTE REGISTER MAP FOR dsPIC33EPXXXGM310/710 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISE	0E40	TRISE<15:12>				—	—	TRISE<9:8>		—	—	—	—	—	—	TRISE<1:0>		F303
PORTE	0E42	RE<15:12>				—	—	RE<9:8>		—	—	—	—	—	—	RE<1:0>		xxxx
LATE	0E44	LATE<15:12>				—	—	LATE<9:8>		—	—	—	—	—	—	LATE<1:0>		xxxx
ODCE	0E46	ODCE<15:12>				—	—	ODCE<9:8>		—	—	—	—	—	—	ODCE<1:0>		0000
CNENE	0E48	CNIEE<15:12>				—	—	CNIEE<9:8>		—	—	—	—	—	—	CNIEE<1:0>		0000
CNPUE	0E4A	CNPUE<15:12>				—	—	CNPUE<9:8>		—	—	—	—	—	—	CNPUE<1:0>		0000
CNPDE	0E4C	CNPDE<15:12>				—	—	CNPDE<9:8>		—	—	—	—	—	—	CNPDE<1:0>		0000
ANSELE	0E4E	ANSE<15:12>				—	—	ANSE<9:8>		—	—	—	—	—	—	ANSE<1:0>		0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 11-1: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION) (CONTINUED)

Input Name ⁽¹⁾	Function Name	Register	Configuration Bits
PWM Sync Input 1	SYNCI1	RPINR37	SYNCI1R<6:0>
PWM Dead-Time Compensation 1	DTCMP1	RPINR38	DTCMP1R<6:0>
PWM Dead-Time Compensation 2	DTCMP2	RPINR39	DTCMP2R<6:0>
PWM Dead-Time Compensation 3	DTCMP3	RPINR39	DTCMP3R<6:0>
PWM Dead-Time Compensation 4	DTCMP4	RPINR40	DTCMP4R<6:0>
PWM Dead-Time Compensation 5	DTCMP5	RPINR40	DTCMP5R<6:0>
PWM Dead-Time Compensation 6	DTCMP6	RPINR41	DTCMP6R<6:0>

Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger input buffers.

2: This input is available on dsPIC33EPXXXGM6XX/7XX devices only.

REGISTER 11-28: RPINR40: PERIPHERAL PIN SELECT INPUT REGISTER 40

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	DTCMP5R<6:0>						
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	DTCMP4R<6:0>						
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-8 **DTCMP5R<6:0>:** Assign PWM Dead-Time Compensation Input 5 to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)

1111100 = Input tied to RPI124

•

•

•

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **DTCMP4R<6:0>:** Assign PWM Dead-Time Compensation Input 4 to the Corresponding RPn Pin bits (see Table 11-2 for input pin selection numbers)

1111100 = Input tied to RPI124

•

•

•

0000001 = Input tied to CMP1

0000000 = Input tied to Vss

NOTES:

dsPIC33EPXXXGM3XX/6XX/7XX

15.1 Output Compare Control Registers

REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	—	ENFLTB
bit 15							bit 8

R/W-0	U-0	R/W-0, HSC	R/W-0, HSC	R/W-0	R/W-0	R/W-0	R/W-0
ENFLTA	—	OCFLTB	OCFLTA	TRIGMODE	OCM2	OCM1	OCM0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit						
R = Readable bit	W = Writable bit		U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **OCSIDL:** Output Compare x Stop in Idle Mode Control bit
1 = Output Compare x halts in CPU Idle mode
0 = Output Compare x continues to operate in CPU Idle mode
- bit 12-10 **OCTSEL<2:0>:** Output Compare x Clock Select bits
111 = Peripheral clock (FP)
110 = Reserved
101 = PTGOx clock⁽²⁾
100 = T1CLK is the clock source of OCx (only the synchronous clock is supported)
011 = T5CLK is the clock source of OCx
010 = T4CLK is the clock source of OCx
001 = T3CLK is the clock source of OCx
000 = T2CLK is the clock source of OCx
- bit 9 **Unimplemented:** Read as '0'
- bit 8 **ENFLTB:** Fault B Input Enable bit
1 = Output Compare x Fault B input (OCFB) is enabled
0 = Output Compare x Fault B input (OCFB) is disabled
- bit 7 **ENFLTA:** Fault A Input Enable bit
1 = Output Compare x Fault A input (OCFA) is enabled
0 = Output Compare x Fault A input (OCFA) is disabled
- bit 6 **Unimplemented:** Read as '0'
- bit 5 **OCFLTB:** PWM Fault B Condition Status bit
1 = PWM Fault B condition on OCFB pin has occurred
0 = No PWM Fault B condition on OCFB pin has occurred
- bit 4 **OCFLTA:** PWM Fault A Condition Status bit
1 = PWM Fault A condition on OCFA pin has occurred
0 = No PWM Fault A condition on OCFA pin has occurred

- Note 1:** OCxR and OCxRS are double-buffered in PWM mode only.
- Note 2:** Each Output Compare x module (OCx) has one PTG clock source. See **Section 25.0 “Peripheral Trigger Generator (PTG) Module”** for more information.
PTGO4 = OC1, OC5
PTGO5 = OC2, OC6
PTGO6 = OC3, OC7
PTGO7 = OC4, OC8

dsPIC33EPXXXGM3XX/6XX/7XX

REGISTER 16-7: STPER: PWMx SECONDARY MASTER TIME BASE PERIOD REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
STPER<15:8>							
bit 15				bit 8			

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0
STPER<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **STPER<15:0>**: PWMx Secondary Master Time Base (PMTMR) Period Value bits

REGISTER 16-8: SSEVTCMP: PWMx SECONDARY SPECIAL EVENT COMPARE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEVTCMP<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEVTCMP<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **SSEVTCMP<15:0>**: PWMx Secondary Special Event Compare Count Value bits

dsPIC33EPXXXGM3XX/6XX/7XX

REGISTER 16-11: PWMCONx: PWMx CONTROL REGISTER

HS/HC-0	HS/HC-0	HS/HC-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLTSTAT ⁽¹⁾	CLSTAT ⁽¹⁾	TRGSTAT	FLTIE	CLIE	TRGIE	ITB ⁽²⁾	MDCS ⁽²⁾
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
DTC1	DTC0	DTCP ⁽³⁾	—	MTBS	CAM ^(2,4)	XPRES ⁽⁵⁾	IUE ⁽²⁾
bit 7							bit 0

Legend:	HC = Hardware Clearable bit	HS = Hardware Settable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15 **FLTSTAT:** Fault Interrupt Status bit⁽¹⁾
 1 = Fault interrupt is pending
 0 = No Fault interrupt is pending
 This bit is cleared by setting: FLTIE = 0.
- bit 14 **CLSTAT:** Current-Limit Interrupt Status bit⁽¹⁾
 1 = Current-limit interrupt is pending
 0 = No current-limit interrupt is pending
 This bit is cleared by setting: CLIE = 0.
- bit 13 **TRGSTAT:** Trigger Interrupt Status bit
 1 = Trigger interrupt is pending
 0 = No trigger interrupt is pending
 This bit is cleared by setting: TRGIE = 0.
- bit 12 **FLTIE:** Fault Interrupt Enable bit
 1 = Fault interrupt is enabled
 0 = Fault interrupt is disabled and the FLTSTAT bit is cleared
- bit 11 **CLIE:** Current-Limit Interrupt Enable bit
 1 = Current-limit interrupt is enabled
 0 = Current-limit interrupt is disabled and the CLSTAT bit is cleared
- bit 10 **TRGIE:** Trigger Interrupt Enable bit
 1 = A trigger event generates an interrupt request
 0 = Trigger event interrupts are disabled and the TRGSTAT bit is cleared
- bit 9 **ITB:** Independent Time Base Mode bit⁽²⁾
 1 = PHASEx register provides the time base period for this PWMx generator
 0 = PTPER register provides timing for this PWMx generator
- bit 8 **MDCS:** Master Duty Cycle Register Select bit⁽²⁾
 1 = MDC register provides duty cycle information for this PWMx generator
 0 = PDCx register provides duty cycle information for this PWMx generator

- Note 1:** Software must clear the interrupt status here and in the corresponding IFSx bit in the interrupt controller.
- Note 2:** These bits should not be changed after the PWMx is enabled (PTEN = 1).
- Note 3:** DTC<1:0> = 11 for DTCP to be effective; otherwise, DTCP is ignored.
- Note 4:** The Independent Time Base (ITB = 1) mode must be enabled to use Center-Aligned mode. If ITB = 0, the CAM bit is ignored.
- Note 5:** To operate in External Period Reset mode, the ITB bit must be '1' and the CLMOD bit in the FCLCONx register must be '0'.

17.0 QUADRATURE ENCODER INTERFACE (QEI) MODULE

Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGM3XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “*dsPIC33/PIC24 Family Reference Manual*”, “**Quadrature Encoder Interface (QEI)**” (DS70601) which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

This chapter describes the Quadrature Encoder Interface (QEI) module and associated operational modes. The QEI module provides the interface to incremental encoders for obtaining mechanical position data.

The operational features of the QEI module include:

- 32-Bit Position Counter
- 32-Bit Index Pulse Counter
- 32-Bit Interval Timer
- 16-Bit Velocity Counter
- 32-Bit Position Initialization/Capture/Compare High Register
- 32-Bit Position Compare Low Register
- x4 Quadrature Count mode
- External Up/Down Count mode
- External Gated Count mode
- External Gated Timer mode
- Internal Timer mode

Figure 17-1 illustrates the QEIx block diagram.

REGISTER 17-13: QEIXLECH: QEIX LESS THAN OR EQUAL COMPARE HIGH WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<31:24>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<23:16>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **QEILEC<31:16>**: High Word Used to Form 32-Bit Less Than or Equal Compare Register (QEIXLEC) bits

REGISTER 17-14: QEIXLECL: QEIX LESS THAN OR EQUAL COMPARE LOW WORD REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<15:8>							
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
QEILEC<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-0 **QEILEC<15:0>**: Low Word Used to Form 32-Bit Less Than or Equal Compare Register (QEIXLEC) bits

REGISTER 24-2: DCICON2: DCI CONTROL REGISTER 2

r-0	r-0	r-0	r-0	R/W-0	R/W-0	r-0	R/W-0
r	r	r	r	BLen1	BLen0	r	COFSG3
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	r-0	R/W-0	R/W-0	R/W-0	R/W-0
COFSG2	COFSG1	COFSG0	r	WS3	WS2	WS1	WS0
bit 7						bit 0	

Legend:	r = Reserved bit	U = Unimplemented bit, read as '0'
R = Readable bit	W = Writable bit	'0' = Bit is cleared
-n = Value at POR	'1' = Bit is set	x = Bit is unknown

bit 15-12 **Reserved:** Read as '0'

bit 11-10 **BLen<1:0>:** Buffer Length Control bits
 11 = Four data words will be buffered between interrupts
 10 = Three data words will be buffered between interrupts
 01 = Two data words will be buffered between interrupts
 00 = One data word will be buffered between interrupts

bit 9 **Reserved:** Read as '0'

bit 8-5 **COFSG<3:0>:** Frame Sync Generator Control bits
 1111 = Data frame has 16 words
 •
 •
 •
 0010 = Data frame has 3 words
 0001 = Data frame has 2 words
 0000 = Data frame has 1 word

bit 4 **Reserved:** Read as '0'

bit 3-0 **WS<3:0>:** DCI Data Word Size bits
 1111 = Data word size is 16 bits
 •
 •
 •
 0100 = Data word size is 5 bits
 0011 = Data word size is 4 bits
 0010 = **Invalid Selection.** Do not use. Unexpected results may occur.
 0001 = **Invalid Selection.** Do not use. Unexpected results may occur.
 0000 = **Invalid Selection.** Do not use. Unexpected results may occur.

REGISTER 26-5: CMxMSKCON: COMPARATOR x MASK GATING CONTROL REGISTER (CONTINUED)

bit 3	ABEN: AND Gate B Input Enable bit 1 = MBI is connected to the AND gate 0 = MBI is not connected to the AND gate
bit 2	ABNEN: AND Gate B Input Inverted Enable bit 1 = Inverted MBI is connected to the AND gate 0 = Inverted MBI is not connected to the AND gate
bit 1	AAEN: AND Gate A Input Enable bit 1 = MAI is connected to the AND gate 0 = MAI is not connected to the AND gate
bit 0	AANEN: AND Gate A Input Inverted Enable bit 1 = Inverted MAI is connected to the AND gate 0 = Inverted MAI is not connected to the AND gate

REGISTER 26-8: CVR2CON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER 2

U-0	U-0	U-0	U-0	R/W-0	R/W-0	U-0	U-0
—	—	—	—	CVRR1	VREFSEL	—	—
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CVREN	CVROE	CVRR0	CVRSS	CVR3	CVR2	CVR1	CVR0
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-12 **Unimplemented:** Read as '0'
- bit 11 **CVRR1:** Comparator Voltage Reference Range Selection bit
See bit 5.
- bit 10 **VREFSEL:** Voltage Reference Select bit
1 = Reference source for inverting input is from CVR2
0 = Reference source for inverting input is from CVR1
- bit 9-8 **Unimplemented:** Read as '0'
- bit 7 **CVREN:** Comparator Voltage Reference Enable bit
1 = Comparator voltage reference circuit is powered on
0 = Comparator voltage reference circuit is powered down
- bit 6 **CVROE:** Comparator Voltage Reference Output Enable on CVREF2O Pin bit
1 = Voltage level is output on the CVREF2O pin
0 = Voltage level is disconnected from the CVREF2O pin
- bit 11, 5 **CVRR<1:0>:** Comparator Voltage Reference Range Selection bits
11 = 0.00 CVRSRC to 0.94, with CVRSRC/16 step-size
10 = 0.33 CVRSRC to 0.96, with CVRSRC/24 step-size
01 = 0.00 CVRSRC to 0.67, with CVRSRC/24 step-size
00 = 0.25 CVRSRC to 0.75, with CVRSRC/32 step-size
- bit 4 **CVRSS:** Comparator Voltage Reference Source Selection bit
1 = Comparator voltage reference source, CVRSRC = CVREF+ – AVSS
0 = Comparator voltage reference source, CVRSRC = AVDD – AVSS
- bit 3-0 **CVR<3:0>:** Comparator Voltage Reference Value Selection $0 \leq \text{CVR<3:0>} \leq 15$ bits
When CVRR<1:0> = 11:
 $\text{CVREF} = (\text{CVR<3:0>}/16) \bullet (\text{CVRSRC})$
When CVRR<1:0> = 10:
 $\text{CVREF} = (1/3) \bullet (\text{CVRSRC}) + (\text{CVR<3:0>}/24) \bullet (\text{CVRSRC})$
When CVRR<1:0> = 01:
 $\text{CVREF} = (\text{CVR<3:0>}/24) \bullet (\text{CVRSRC})$
When CVRR<1:0> = 00:
 $\text{CVREF} = (1/4) \bullet (\text{CVRSRC}) + (\text{CVR<3:0>}/32) \bullet (\text{CVRSRC})$

32.11 Demonstration/Development Boards, Evaluation Kits and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.

32.12 Third-Party Development Tools

Microchip also offers a great collection of tools from third-party vendors. These tools are carefully selected to offer good value and unique functionality.

- Device Programmers and Gang Programmers from companies, such as SoftLog and CCS
- Software Tools from companies, such as Gimpel and Trace Systems
- Protocol Analyzers from companies, such as Saleae and Total Phase
- Demonstration Boards from companies, such as MikroElektronika, Digilent® and Olimex
- Embedded Ethernet Solutions from companies, such as EZ Web Lynx, WIZnet and IPLogika®

TABLE 33-10: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
DI60a	I _{ICL}	Input Low Injection Current	0	—	-5 ^(4,7)	mA	All pins except V _{DD} , V _{SS} , AV _{DD} , AV _{SS} , MCLR, VCAP and RB7
DI60b	I _{ICH}	Input High Injection Current	0	—	+5 ^(5,6,7)	mA	All pins except V _{DD} , V _{SS} , AV _{DD} , AV _{SS} , MCLR, VCAP, RB7 and all 5V tolerant pins ⁽⁶⁾
DI60c	ΣI_{ICT}	Total Input Injection Current (sum of all I/O and control pins)	-20 ⁽⁸⁾	—	+20 ⁽⁸⁾	mA	Absolute instantaneous sum of all \pm input injection currents from all I/O pins: $(I_{ICL} + I_{ICH}) \leq \Sigma I_{ICT}$

- Note 1:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current can be measured at different input voltages.
- 2:** Negative current is defined as current sourced by the pin.
- 3:** See the “Pin Diagrams” section for the 5V tolerant I/O pins.
- 4:** V_{IL} source < (V_{SS} – 0.3). Characterized but not tested.
- 5:** Non-5V tolerant pins V_{IH} source > (V_{DD} + 0.3), 5V tolerant pins V_{IH} source > 5.5V. Characterized but not tested.
- 6:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.
- 7:** Non-zero injection currents can affect the ADC results by approximately 4-6 counts.
- 8:** Any number and/or combination of I/O pins not excluded under I_{ICL} or I_{ICH} conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

dsPIC33EPXXXGM3XX/6XX/7XX

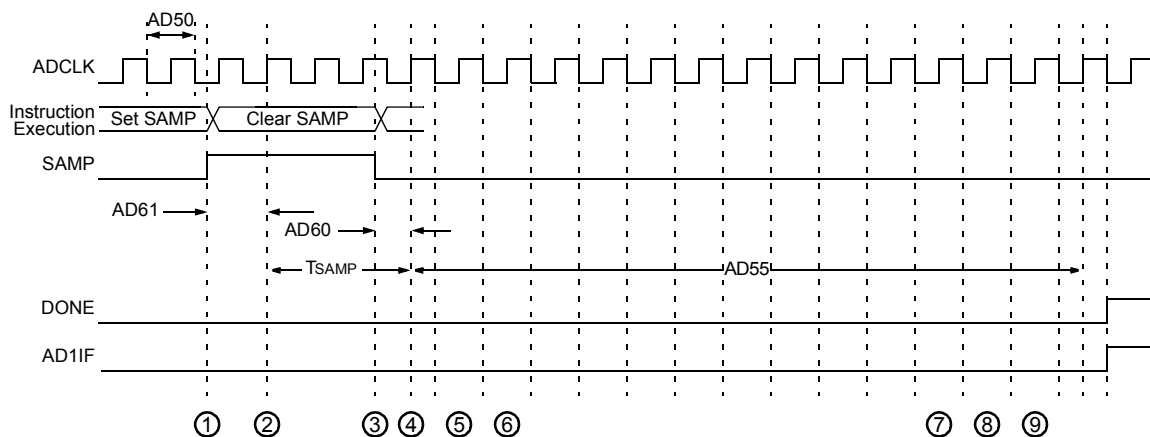
TABLE 33-57: ADCx MODULE SPECIFICATIONS (12-BIT MODE)

AC CHARACTERISTICS			Standard Operating Conditions (see Note 1): 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
ADC Accuracy (12-Bit Mode) – VREF-							
AD20a	Nr	Resolution	12 data bits			bits	
AD21a	INL	Integral Nonlinearity	-3	—	+3	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V (Note 2)
AD22a	DNL	Differential Nonlinearity	≥ 1	—	< 1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V (Note 2)
AD23a	GERR	Gain Error	-10	—	10	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V (Note 2)
AD24a	EOFF	Offset Error	-5	—	5	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V (Note 2)
AD25a	—	Monotonicity	—	—	—	—	Guaranteed
Dynamic Performance (12-Bit Mode)							
AD30a	THD	Total Harmonic Distortion	—	—	-75	dB	
AD31a	SINAD	Signal to Noise and Distortion	68.5	69.5	—	dB	
AD32a	SFDR	Spurious Free Dynamic Range	80	—	—	dB	
AD33a	FNYQ	Input Signal Bandwidth	—	—	250	kHz	
AD34a	ENOB	Effective Number of Bits	11.09	11.3	—	bits	

Note 1: Device is functional at VBORMIN < VDD < VDDMIN, but will have degraded performance. Device functionality is tested, but not characterized. Analog modules: ADC, op amp/comparator and comparator voltage reference, will have degraded performance. Refer to Parameter BO10 in Table 33-12 for the minimum and maximum BOR values.

2: For all accuracy specifications, VINL = AVSS = VREFL = 0V and AVDD = VREFH = 3.6V.

FIGURE 33-38: ADC1 CONVERSION (12-BIT MODE) TIMING CHARACTERISTICS
(ASAM = 0, SSRC<2:0> = 000, SSRCG = 0)



- | | |
|---|------------------------------------|
| ① – Software sets AD1CON1. SAMP to start sampling. | ⑤ – Convert bit 11. |
| ② – Sampling starts after discharge period. TSAMP is described in “Analog-to-Digital Converter (ADC)” (DS70621) of the “dsPIC33/PIC24 Family Reference Manual”. | ⑥ – Convert bit 10. |
| ③ – Software clears AD1CON1. SAMP to start conversion. | ⑦ – Convert bit 1. |
| ④ – Sampling ends, conversion sequence starts. | ⑧ – Convert bit 0. |
| | ⑨ – One TAD for end of conversion. |

34.0 HIGH-TEMPERATURE ELECTRICAL CHARACTERISTICS

This section provides an overview of dsPIC33EPXXXGM3XX/6XX/7XX electrical characteristics for devices operating in an ambient temperature range of -40°C to +150°C.

The specifications between -40°C to +150°C are identical to those shown in **Section 33.0 “Electrical Characteristics”** for operation between -40°C to +125°C, with the exception of the parameters listed in this section.

Parameters in this section begin with an H, which denotes High temperature. For example, Parameter DC10 in **Section 33.0 “Electrical Characteristics”** is the Industrial and Extended temperature equivalent of HDC10.

Absolute maximum ratings for the dsPIC33EPXXXGM3XX/6XX/7XX high-temperature devices are listed below. Exposure to these maximum rating conditions for extended periods can affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

Absolute Maximum Ratings⁽¹⁾

Ambient temperature under bias ⁽²⁾	-40°C to +150°C
Storage temperature	-65°C to +160°C
Voltage on VDD with respect to VSS	-0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to VSS ⁽³⁾	-0.3V to (VDD + 0.3V)
Voltage on any 5V tolerant pin with respect to VSS when VDD < 3.0V ⁽³⁾	-0.3V to 3.6V
Voltage on any 5V tolerant pin with respect to VSS when VDD ≥ 3.0V ⁽³⁾	-0.3V to 5.5V
Maximum current out of VSS pin	60 mA
Maximum current into VDD pin ⁽⁴⁾	60 mA
Maximum junction temperature	+155°C
Maximum current sourced/sunk by any 4x I/O pin	10 mA
Maximum current sourced/sunk by any 8x I/O pin	15 mA
Maximum current sunk by all ports combined	70 mA
Maximum current sourced by all ports combined ⁽⁴⁾	70 mA

Note 1: Stresses above those listed under “Absolute Maximum Ratings” can cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods can affect device reliability.

2: AEC-Q100 reliability testing for devices intended to operate at +150°C is 1,000 hours. Any design in which the total operating time from +125°C to +150°C will be greater than 1,000 hours is not warranted without prior written approval from Microchip Technology Inc.

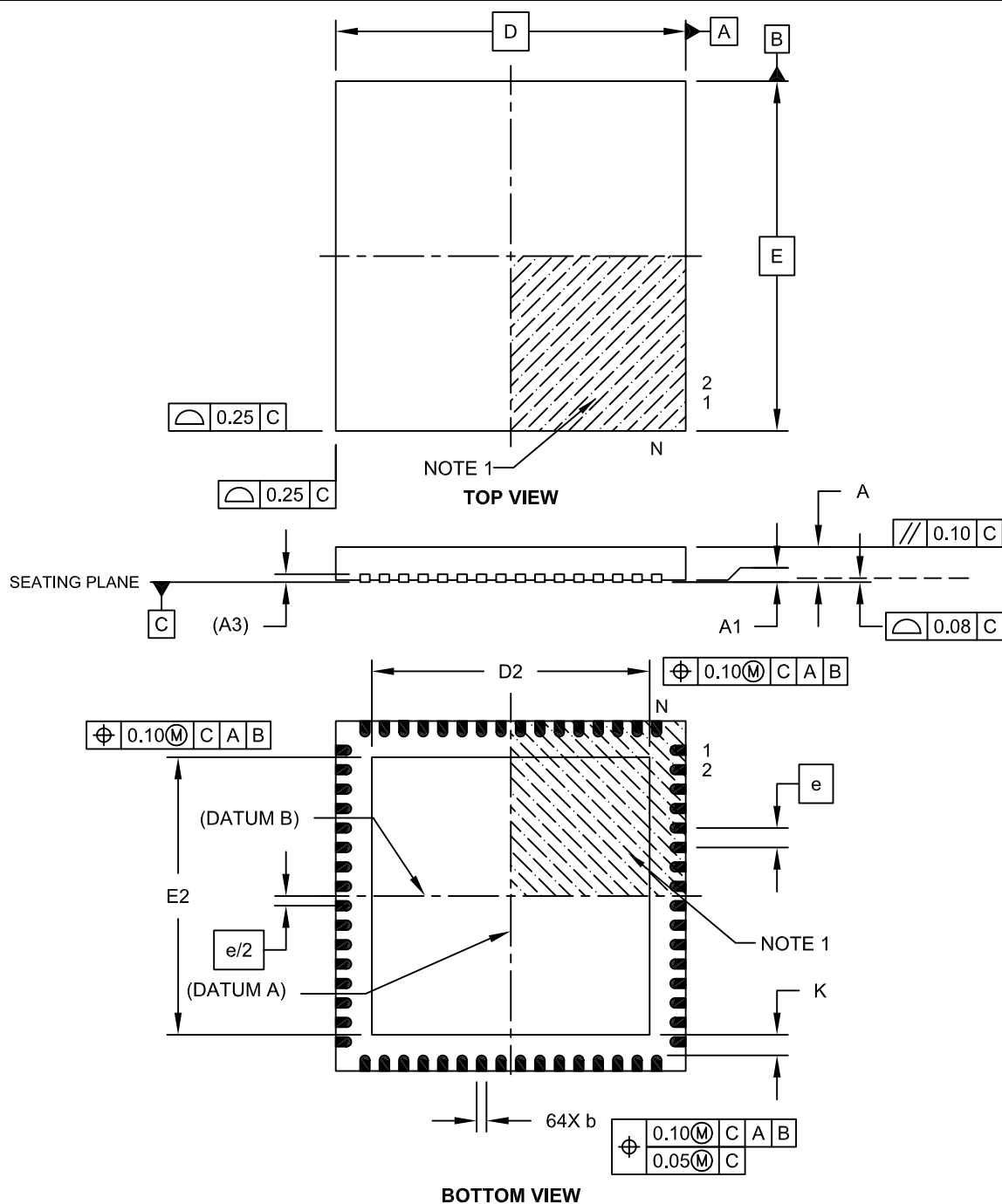
3: Refer to the “Pin Diagrams” section for 5V tolerant pins.

4: Maximum allowable current is a function of device maximum power dissipation (see Table 34-2).

dsPIC33EPXXXGM3XX/6XX/7XX

**64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]
With 7.15 x 7.15 Exposed Pad**

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-149C Sheet 1 of 2