



Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	I ² C, IrDA, LINbus, QEI, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, Motor Control PWM, POR, PWM, WDT
Number of I/O	85
Program Memory Size	512KB (170K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	48K x 8
Voltage - Supply (Vcc/Vdd)	-
Data Converters	A/D 49x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep512gm310t-i-pt

Table of Contents

dsPIC33EPXXXGM3XX/6XX/7XX Product Family	2
1.0 Device Overview	15
2.0 Guidelines for Getting Started with 16-Bit Digital Signal Controllers	21
3.0 CPU	27
4.0 Memory Organization	37
5.0 Flash Program Memory	103
6.0 Resets	111
7.0 Interrupt Controller	115
8.0 Direct Memory Access (DMA)	129
9.0 Oscillator Configuration	143
10.0 Power-Saving Features	153
11.0 I/O Ports	163
12.0 Timer1	211
13.0 Timer2/3, Timer4/5, Timer6/7 and Timer8/9	213
14.0 Input Capture	219
15.0 Output Compare	223
16.0 High-Speed PWM Module	229
17.0 Quadrature Encoder Interface (QEI) Module	257
18.0 Serial Peripheral Interface (SPI)	273
19.0 Inter-Integrated Circuit™ (I ² C™)	281
20.0 Universal Asynchronous Receiver Transmitter (UART)	289
21.0 Controller Area Network (CAN) Module (dsPIC33EPXXXGM6XX/7XX Devices Only)	295
22.0 Charge Time Measurement Unit (CTMU)	321
23.0 10-Bit/12-Bit Analog-to-Digital Converter (ADC)	327
24.0 Data Converter Interface (DCI) Module	343
25.0 Peripheral Trigger Generator (PTG) Module	349
26.0 Op Amp/Comparator Module	365
27.0 Real-Time Clock and Calendar (RTCC)	383
28.0 Parallel Master Port (PMP)	395
29.0 Programmable Cyclic Redundancy Check (CRC) Generator	405
30.0 Special Features	411
31.0 Instruction Set Summary	419
32.0 Development Support	429
33.0 Electrical Characteristics	433
34.0 High-Temperature Electrical Characteristics	499
35.0 Packaging Information	507
Appendix A: Revision History	527
Index	529
The Microchip Web Site	537
Customer Change Notification Service	537
Customer Support	537
Product Identification System	539

FIGURE 2-5: SINGLE-PHASE SYNCHRONOUS BUCK CONVERTER

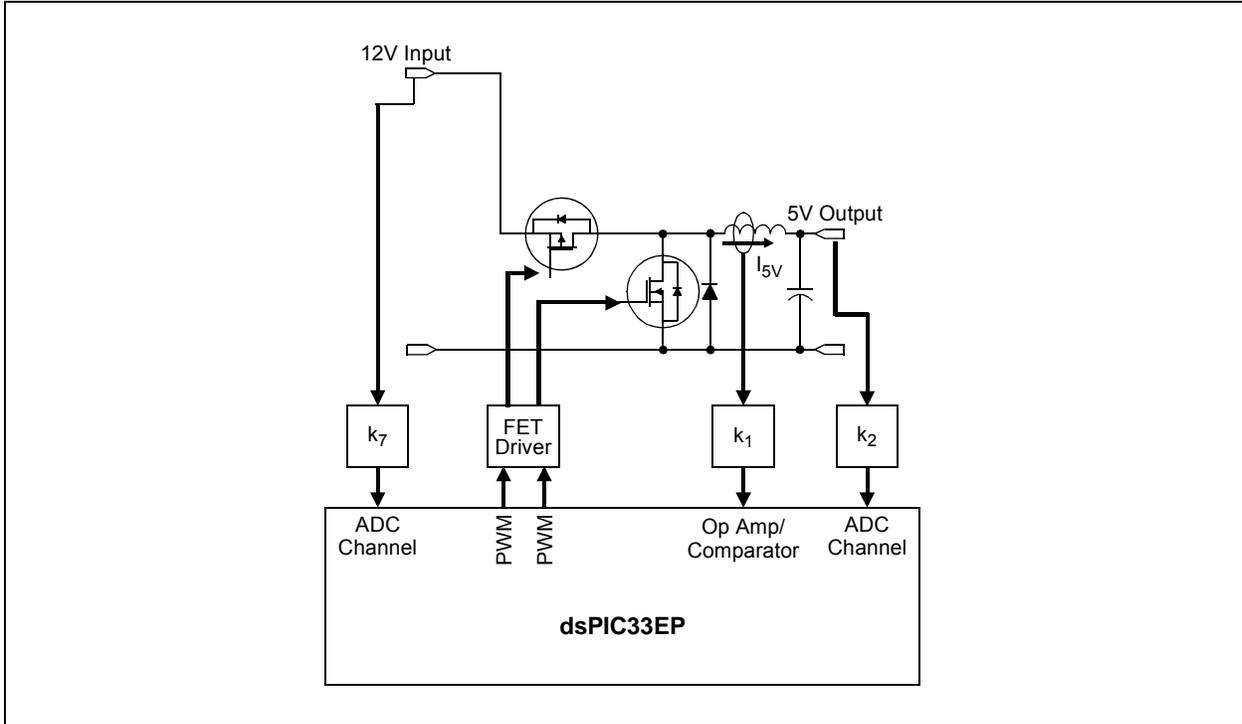


FIGURE 2-6: MULTIPHASE SYNCHRONOUS BUCK CONVERTER

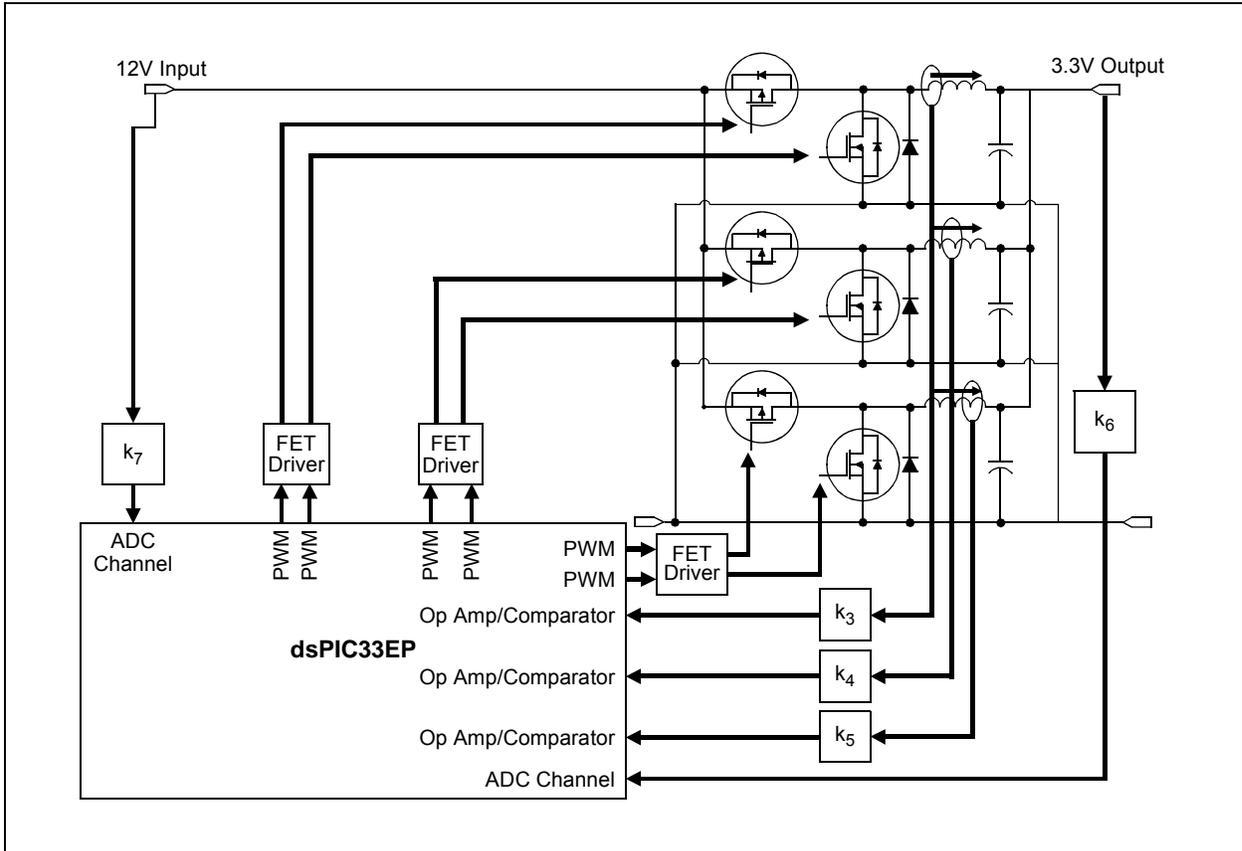


TABLE 4-49: PORTB REGISTER MAP FOR dsPIC33EPXXXGM310/710 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB<15:0>																DF9F
PORTB	0E12	RB<15:0>																xxxx
LATB	0E14	LATB<15:0>																xxxx
ODCB	0E16	ODCB<15:0>																0000
CNENB	0E18	CNIEB<15:0>																0000
CNPUB	0E1A	CNPUB<15:0>																0000
CNPDB	0E1C	CNPDB<15:0>																0000
ANSELB	0E1E	—	—	—	—	—	—	ANSB<9:7>				—	—	—	ANSB<3:0>			010F

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-50: PORTB REGISTER MAP FOR dsPIC33EPXXXGM306/706 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB<15:0>																DF9F
PORTB	0E12	RB<15:0>																xxxx
LATB	0E14	LATB<15:0>																xxxx
ODCB	0E16	ODCB<15:0>																0000
CNENB	0E18	CNIEB<15:0>																0000
CNPUB	0E1A	CNPUB<15:0>																0000
CNPDB	0E1C	CNPDB<15:0>																0000
ANSELB	0E1E	—	—	—	—	—	—	ANSB<9:7>				—	—	—	ANSB<3:0>			010F

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-51: PORTB REGISTER MAP FOR dsPIC33EPXXXGM304/604 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB<15:0>																FFFF
PORTB	0E12	RB<15:0>																xxxx
LATB	0E14	LATB<15:0>																xxxx
ODCB	0E16	ODCB<15:0>																0000
CNENB	0E18	CNIEB<15:0>																0000
CNPUB	0E1A	CNPUB<15:0>																0000
CNPDB	0E1C	CNPDB<15:0>																0000
ANSELB	0E1E	—	—	—	—	—	—	ANSB<9:7>				—	—	—	ANSB<3:0>			010F

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

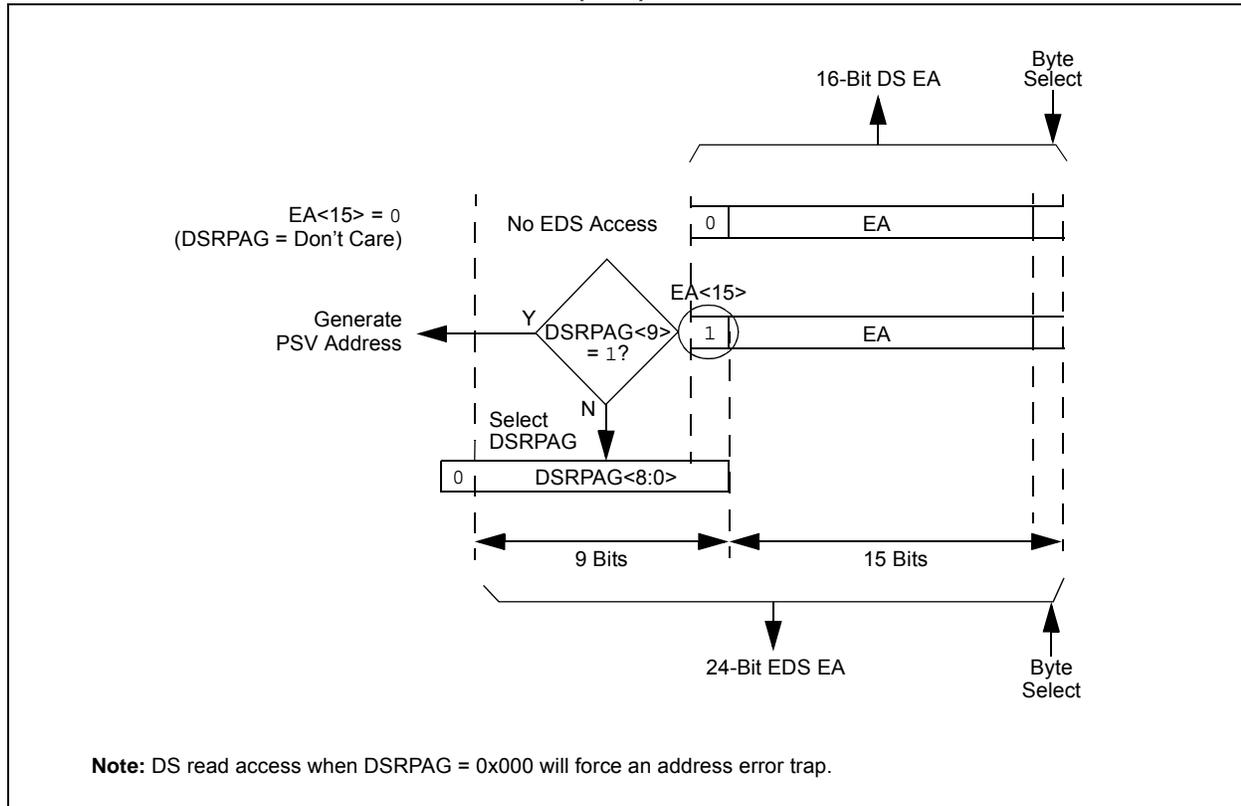
dsPIC33EPXXXGM3XX/6XX/7XX

4.3.1 PAGED MEMORY SCHEME

The dsPIC33EPXXXGM3XX/6XX/7XX architecture extends the available Data Space through a paging scheme, which allows the available Data Space to be accessed using MOV instructions in a linear fashion for pre- and post-modified Effective Addresses (EA). The upper half of the Base Data Space address is used in conjunction with the Data Space Page registers, the 10-bit Data Space Read Page register (DSRPAG) or the 9-bit Data Space Write Page register (DSWPAG), to form an Extended Data Space (EDS) address, or Program Space Visibility (PSV) address. The Data Space Page registers are located in the SFR space.

Construction of the EDS address is shown in Figure 4-8. When DSRPAG<9> = 0 and the base address bit, EA<15> = 1, the DSRPAG<8:0> bits are concatenated onto EA<14:0> to form the 24-bit EDS read address. Similarly, when the base address bit, EA<15> = 1, the DSWPAG<8:0> bits are concatenated onto EA<14:0> to form the 24-bit EDS write address.

FIGURE 4-8: EXTENDED DATA SPACE (EDS) READ ADDRESS GENERATION



dsPIC33EPXXXGM3XX/6XX/7XX

4.3.2 EXTENDED X DATA SPACE

The lower portion of the base address space range, between 0x0000 and 0x7FFF, is always accessible regardless of the contents of the Data Space Page registers. It is indirectly addressable through the register indirect instructions. It can be regarded as being located in the default EDS Page 0 (i.e., EDS address range of 0x000000 to 0x007FFF with the base address bit, EA<15> = 0, for this address range). However, Page 0 cannot be accessed through the upper 32 Kbytes, 0x8000 to 0xFFFF, of Base Data Space, in combination with DSRPAG = 0x000 or DSWPAG = 0x000. Consequently, DSRPAG and DSWPAG are initialized to 0x001 at Reset.

Note 1: DSxPAG should not be used to access Page 0. An EDS access with DSxPAG set to 0x000 will generate an address error trap.

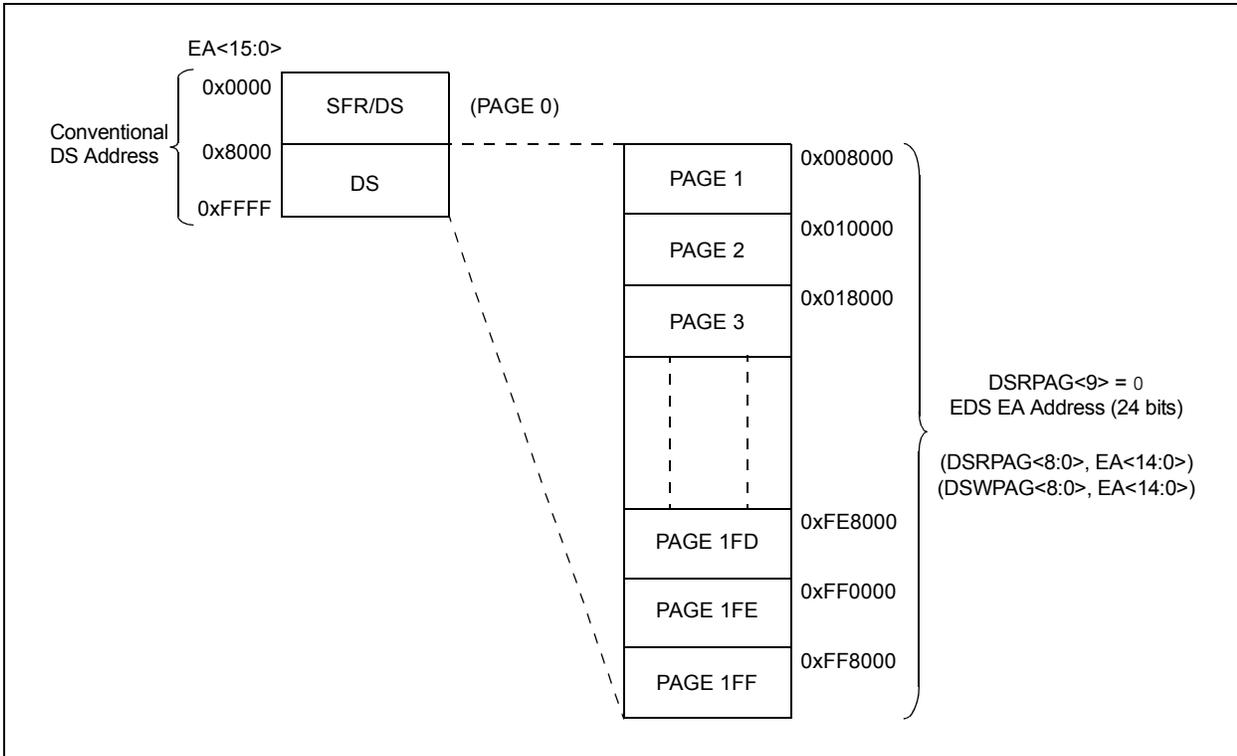
2: Clearing the DSxPAG in software has no effect.

The remaining pages, including both EDS and PSV pages, are only accessible using the DSRPAG or DSWPAG register, in combination with the upper 32 Kbytes, 0x8000 to 0xFFFF, of the base address, where the base address bit, EA<15> = 1.

For example, when DSRPAG = 0x001 or DSWPAG = 0x001, accesses to the upper 32 Kbytes, 0x8000 to 0xFFFF, of the Data Space will map to the EDS address range of 0x008000 to 0x00FFFF. When DSRPAG = 0x002 or DSWPAG = 0x002, accesses to the upper 32 Kbytes of the Data Space will map to the EDS address range of 0x010000 to 0x017FFF and so on, as shown in the EDS memory map in Figure 4-11.

For more information on the PSV page access, using Data Space Page registers, refer to the “**Program Space Visibility from Data Space**” section in “**Program Memory**” (DS70613) of the “*dsPIC33/PIC24 Family Reference Manual*”.

FIGURE 4-11: EDS MEMORY MAP



REGISTER 5-2: NVMADRU: NONVOLATILE MEMORY UPPER ADDRESS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADRU<23:16>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **NVMADRU<23:16>:** Nonvolatile Memory Upper Write Address bits
 Selects the upper 8 bits of the location to program or erase in program Flash memory. This register may be read or written to by the user application.

REGISTER 5-3: NVMADR: NONVOLATILE MEMORY LOWER ADDRESS REGISTER

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADR<15:8>							
bit 15							bit 8

R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
NVMADR<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **NVMADR<15:0>:** Nonvolatile Memory Lower Write Address bits
 Selects the lower 16 bits of the location to program or erase in program Flash memory. This register may be read or written to by the user application.

dsPIC33EPXXGM3XX/6XX/7XX

NOTES:

REGISTER 11-30: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP35R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP20R<5:0>					
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP35R<5:0>:** Peripheral Output Function is Assigned to RP35 Output Pin bits
(see Table 11-3 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP20R<5:0>:** Peripheral Output Function is Assigned to RP20 Output Pin bits
(see Table 11-3 for peripheral function numbers)

REGISTER 11-31: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP37R<5:0>					
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP36R<5:0>					
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP37R<5:0>:** Peripheral Output Function is Assigned to RP37 Output Pin bits
(see Table 11-3 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP36R<5:0>:** Peripheral Output Function is Assigned to RP36 Output Pin bits
(see Table 11-3 for peripheral function numbers)

dsPIC33EPXXGM3XX/6XX/7XX

NOTES:

dsPIC33EPXXXGM3XX/6XX/7XX

REGISTER 15-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0
FLTMD	FLTOUT	FLTRIEN	OCINV	—	—	—	OC32
bit 15							bit 8

R/W-0	R/W-0, HS	R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0
OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0
bit 7							bit 0

Legend:	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **FLTMD:** Fault Mode Select bit
 1 = Fault mode is maintained until the Fault source is removed; the corresponding OCFLTx bit is cleared in software and a new PWM period starts
 0 = Fault mode is maintained until the Fault source is removed and a new PWM period starts
- bit 14 **FLTOUT:** Fault Out bit
 1 = PWM output is driven high on a Fault
 0 = PWM output is driven low on a Fault
- bit 13 **FLTRIEN:** Fault Output State Select bit
 1 = OCx pin is tri-stated on a Fault condition
 0 = OCx pin I/O state is defined by the FLTOUT bit on a Fault condition
- bit 12 **OCINV:** OCx Invert bit
 1 = OCx output is inverted
 0 = OCx output is not inverted
- bit 11-9 **Unimplemented:** Read as '0'
- bit 8 **OC32:** Cascade Two OCx Modules Enable bit (32-bit operation)
 1 = Cascade module operation is enabled
 0 = Cascade module operation is disabled
- bit 7 **OCTRIG:** OCx Trigger/Sync Select bit
 1 = Triggers OCx from source designated by the SYNCSELx bits
 0 = Synchronizes OCx with source designated by the SYNCSELx bits
- bit 6 **TRIGSTAT:** Timer Trigger Status bit
 1 = Timer source has been triggered and is running
 0 = Timer source has not been triggered and is being held clear
- bit 5 **OCTRIS:** OCx Output Pin Direction Select bit
 1 = Output Compare x is tri-stated
 0 = Output Compare x module drives the OCx pin

- Note 1:** Do not use the OCx module as its own synchronization or trigger source.
- Note 2:** When the OCy module is turned off, it sends a trigger out signal. If the OCx module uses the OCy module as a trigger source, the OCy module must be unselected as a trigger source prior to disabling it.
- Note 3:** Each Output Compare x module (OCx) has one PTG Trigger/Sync source. See **Section 25.0 "Peripheral Trigger Generator (PTG) Module"** for more information.
 PTGO4 = OC1, OC5
 PTGO5 = OC2, OC6
 PTGO6 = OC3, OC7
 PTGO7 = OC4, OC8

REGISTER 16-23: LEBDLYx: LEADING-EDGE BLANKING DELAY REGISTER x

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	LEB<11:8>			
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
LEB<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-12 **Unimplemented:** Read as '0'
bit 11-0 **LEB<11:0>:** Leading-Edge Blanking Delay for Current-Limit and Fault Inputs bits

dsPIC33EPXXXGM3XX/6XX/7XX

REGISTER 17-1: QEIXCON: QEIX CONTROL REGISTER (CONTINUED)

- bit 6-4 **INTDIV<2:0>**: Timer Input Clock Prescale Select bits (interval timer, main timer (position counter), velocity counter and index counter internal clock divider select)⁽³⁾
- 111 = 1:128 prescale value
 - 110 = 1:64 prescale value
 - 101 = 1:32 prescale value
 - 100 = 1:16 prescale value
 - 011 = 1:8 prescale value
 - 010 = 1:4 prescale value
 - 001 = 1:2 prescale value
 - 000 = 1:1 prescale value
- bit 3 **CNTPOL**: Position and Index Counter/Timer Direction Select bit
- 1 = Counter direction is negative unless modified by external up/down signal
 - 0 = Counter direction is positive unless modified by external up/down signal
- bit 2 **GATEN**: External Count Gate Enable bit
- 1 = External gate signal controls position counter operation
 - 0 = External gate signal does not affect position counter/timer operation
- bit 1-0 **CCM<1:0>**: Counter Control Mode Selection bits
- 11 = Internal Timer mode with optional external count is selected
 - 10 = External clock count with optional external count is selected
 - 01 = External clock count with external up/down direction is selected
 - 00 = Quadrature Encoder Interface (x4 mode) Count mode is selected

- Note 1:** When CCM<1:0> = 10 or CCM<1:0> = 11, all of the QEI counters operate as timers and the PIMOD<2:0> bits are ignored.
- 2:** When CCM<1:0> = 00, and QEAX and QEBX values match the Index Match Value (IMV), the POSCNTNTH and POSCNTL registers are reset.
- 3:** The selected clock rate should be at least twice the expected maximum quadrature count rate.
- 4:** The match value applies to the A and B inputs after the swap and polarity bits have been applied.

dsPIC33EPXXGM3XX/6XX/7XX

NOTES:

REGISTER 21-3: CxVEC: CANx INTERRUPT CODE REGISTER

U-0	U-0	U-0	R-0	R-0	R-0	R-0	R-0
—	—	—	FILHIT4	FILHIT3	FILHIT2	FILHIT1	FILHIT0
bit 15							bit 8

U-0	R-1	R-0	R-0	R-0	R-0	R-0	R-0
—	ICODE6	ICODE5	ICODE4	ICODE3	ICODE2	ICODE1	ICODE0
bit 7							bit 0

Legend:
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-13 **Unimplemented:** Read as '0'
- bit 12-8 **FILHIT<4:0>:** Filter Hit Number bits
 - 10000-11111 = Reserved
 - 01111 = Filter 15
 -
 -
 -
 - 00001 = Filter 1
 - 00000 = Filter 0
- bit 7 **Unimplemented:** Read as '0'
- bit 6-0 **ICODE<6:0>:** Interrupt Flag Code bits
 - 1000101-1111111 = Reserved
 - 1000100 = FIFO almost full interrupt
 - 1000011 = Receiver overflow interrupt
 - 1000010 = Wake-up interrupt
 - 1000001 = Error interrupt
 - 1000000 = No interrupt
 -
 -
 -
 - 0010000-0111111 = Reserved
 - 0001111 = RB15 buffer interrupt
 -
 -
 -
 - 0001001 = RB9 buffer interrupt
 - 0001000 = RB8 buffer interrupt
 - 0000111 = TRB7 buffer interrupt
 - 0000110 = TRB6 buffer interrupt
 - 0000101 = TRB5 buffer interrupt
 - 0000100 = TRB4 buffer interrupt
 - 0000011 = TRB3 buffer interrupt
 - 0000010 = TRB2 buffer interrupt
 - 0000001 = TRB1 buffer interrupt
 - 0000000 = TRB0 buffer interrupt

REGISTER 26-3: CM4CON: OP AMP/COMPARATOR 4 CONTROL REGISTER (CONTINUED)

- bit 7-6 **EVPOL<1:0>**: Trigger/Event/Interrupt Polarity Select bits⁽²⁾
- 11 = Trigger/event/interrupt generated on any change of the comparator output (while CEVT = 0)
 - 10 = Trigger/event/interrupt generated only on high-to-low transition of the polarity selected comparator output (while CEVT = 0)
 - If CPOL = 1 (inverted polarity):
Low-to-high transition of the comparator output.
 - If CPOL = 0 (non-inverted polarity):
High-to-low transition of the comparator output.
 - 01 = Trigger/event/interrupt generated only on low-to-high transition of the polarity selected comparator output (while CEVT = 0)
 - If CPOL = 1 (inverted polarity):
High-to-low transition of the comparator output.
 - If CPOL = 0 (non-inverted polarity):
Low-to-high transition of the comparator output.
 - 00 = Trigger/event/interrupt generation is disabled
- bit 5 **Unimplemented**: Read as '0'
- bit 4 **CREF**: Comparator Reference Select bit (VIN+ input)⁽¹⁾
- 1 = VIN+ input connects to internal CVREFIN voltage
 - 0 = VIN+ input connects to C4IN1+ pin
- bit 3-2 **Unimplemented**: Read as '0'
- bit 1-0 **CCH<1:0>**: Comparator Channel Select bits⁽¹⁾
- 11 = VIN- input of comparator connects to OA3/AN6
 - 10 = VIN- input of comparator connects to OA2/AN0
 - 01 = VIN- input of comparator connects to OA1/AN3
 - 00 = VIN- input of comparator connects to C4IN1-

- Note 1:** Inputs that are selected and not available will be tied to VSS. See the “Pin Diagrams” section for available inputs for each package.
- 2:** After configuring the comparator, either for a high-to-low or low-to-high COUT transition (EVPOL<1:0> (CMxCON<7:6>) = 10 or 01), the Comparator Event bit, CEVT (CMxCON<9>), and the Comparator Combined Interrupt Flag, CMPIF (IFS1<2>), **must be cleared** before enabling the Comparator Interrupt Enable bit, CMPIE (IEC1<2>).

dsPIC33EPXXGM3XX/6XX/7XX

NOTES:

TABLE 31-1: SYMBOLS USED IN OPCODE DESCRIPTIONS (CONTINUED)

Field	Description
Wm*Wm	Multiplicand and Multiplier Working register pair for Square instructions $\in \{W4 * W4, W5 * W5, W6 * W6, W7 * W7\}$
Wm*Wn	Multiplicand and Multiplier Working register pair for DSP instructions $\in \{W4 * W5, W4 * W6, W4 * W7, W5 * W6, W5 * W7, W6 * W7\}$
Wn	One of 16 Working registers $\in \{W0...W15\}$
Wnd	One of 16 Destination Working registers $\in \{W0...W15\}$
Wns	One of 16 Source Working registers $\in \{W0...W15\}$
WREG	W0 (Working register used in File register instructions)
Ws	Source W register $\in \{Ws, [Ws], [Ws++] , [Ws--], [++Ws], [--Ws] \}$
Wso	Source W register $\in \{Wns, [Wns], [Wns++] , [Wns--], [++Wns], [--Wns], [Wns+Wb] \}$
Wx	X Data Space Prefetch Address register for DSP instructions $\in \{[W8] + = 6, [W8] + = 4, [W8] + = 2, [W8], [W8] - = 6, [W8] - = 4, [W8] - = 2, [W9] + = 6, [W9] + = 4, [W9] + = 2, [W9], [W9] - = 6, [W9] - = 4, [W9] - = 2, [W9 + W12], \text{none}\}$
Wxd	X Data Space Prefetch Destination register for DSP instructions $\in \{W4...W7\}$
Wy	Y Data Space Prefetch Address register for DSP instructions $\in \{[W10] + = 6, [W10] + = 4, [W10] + = 2, [W10], [W10] - = 6, [W10] - = 4, [W10] - = 2, [W11] + = 6, [W11] + = 4, [W11] + = 2, [W11], [W11] - = 6, [W11] - = 4, [W11] - = 2, [W11 + W12], \text{none}\}$
Wyd	Y Data Space Prefetch Destination register for DSP instructions $\in \{W4...W7\}$

dsPIC33EPXXXGM3XX/6XX/7XX

TABLE 33-49: I2Cx BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Param. No.	Symbol	Characteristic ⁽³⁾		Min.	Max.	Units	Conditions
IS10	TLO:SCL	Clock Low Time	100 kHz mode	4.7	—	μs	
			400 kHz mode	1.3	—	μs	
			1 MHz mode ⁽¹⁾	0.5	—	μs	
IS11	THI:SCL	Clock High Time	100 kHz mode	4.0	—	μs	Device must operate at a minimum of 1.5 MHz
			400 kHz mode	0.6	—	μs	Device must operate at a minimum of 10 MHz
			1 MHz mode ⁽¹⁾	0.5	—	μs	
IS20	TF:SCL	SDAx and SCLx Fall Time	100 kHz mode	—	300	ns	CB is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 CB	300	ns	
			1 MHz mode ⁽¹⁾	—	100	ns	
IS21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	—	1000	ns	CB is specified to be from 10 to 400 pF
			400 kHz mode	20 + 0.1 CB	300	ns	
			1 MHz mode ⁽¹⁾	—	300	ns	
IS25	TSU:DAT	Data Input Setup Time	100 kHz mode	250	—	ns	
			400 kHz mode	100	—	ns	
			1 MHz mode ⁽¹⁾	100	—	ns	
IS26	THD:DAT	Data Input Hold Time	100 kHz mode	0	—	μs	
			400 kHz mode	0	0.9	μs	
			1 MHz mode ⁽¹⁾	0	0.3	μs	
IS30	TSU:STA	Start Condition Setup Time	100 kHz mode	4.7	—	μs	Only relevant for Repeated Start condition
			400 kHz mode	0.6	—	μs	
			1 MHz mode ⁽¹⁾	0.25	—	μs	
IS31	THD:STA	Start Condition Hold Time	100 kHz mode	4.0	—	μs	After this period, the first clock pulse is generated
			400 kHz mode	0.6	—	μs	
			1 MHz mode ⁽¹⁾	0.25	—	μs	
IS33	TSU:STO	Stop Condition Setup Time	100 kHz mode	4.7	—	μs	
			400 kHz mode	0.6	—	μs	
			1 MHz mode ⁽¹⁾	0.6	—	μs	
IS34	THD:STO	Stop Condition Hold Time	100 kHz mode	4	—	μs	
			400 kHz mode	0.6	—	μs	
			1 MHz mode ⁽¹⁾	0.25	—	μs	
IS40	TAA:SCL	Output Valid From Clock	100 kHz mode	0	3500	ns	
			400 kHz mode	0	1000	ns	
			1 MHz mode ⁽¹⁾	0	350	ns	
IS45	TBF:SDA	Bus Free Time	100 kHz mode	4.7	—	μs	Time the bus must be free before a new transmission can start
			400 kHz mode	1.3	—	μs	
			1 MHz mode ⁽¹⁾	0.5	—	μs	
IS50	CB	Bus Capacitive Loading		—	400	pF	
IS51	TPGD	Pulse Gobbler Delay		65	390	ns	(Note 2)

Note 1: Maximum pin capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

2: The Typical value for this parameter is 130 ns.

3: These parameters are characterized, but not tested in manufacturing.

dsPIC33EPXXXGM3XX/6XX/7XX

TABLE 34-14: ADCx MODULE SPECIFICATIONS (12-BIT MODE)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
ADC Accuracy (12-Bit Mode)⁽¹⁾							
HAD20a	Nr	Resolution ⁽³⁾	12 Data Bits			bits	
HAD21a	INL	Integral Nonlinearity	-6	—	6	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD22a	DNL	Differential Nonlinearity	-1	—	1	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD23a	GERR	Gain Error	-10	—	10	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD24a	E _{OFF}	Offset Error	-5	—	5	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
Dynamic Performance (12-Bit Mode)⁽²⁾							
HAD33a	F _{NYQ}	Input Signal Bandwidth	—	—	200	kHz	

Note 1: These parameters are characterized, but are tested at 20 ksp/s only.

2: These parameters are characterized by similarity, but are not tested in manufacturing.

3: Injection currents $> |0|$ can affect the ADC results by approximately 4-6 counts.

TABLE 34-15: ADCx MODULE SPECIFICATIONS (10-BIT MODE)

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +150^{\circ}\text{C}$				
Param No.	Symbol	Characteristic	Min	Typ	Max	Units	Conditions
ADC Accuracy (10-Bit Mode)⁽¹⁾							
HAD20b	Nr	Resolution ⁽³⁾	10 Data Bits			bits	
HAD21b	INL	Integral Nonlinearity	-1.5	—	1.5	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD22b	DNL	Differential Nonlinearity	-0.25	—	0.25	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD23b	GERR	Gain Error	-2.5	—	2.5	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
HAD24b	E _{OFF}	Offset Error	-1.25	—	1.25	LSb	V _{INL} = AV _{SS} = V _{REFL} = 0V, AV _{DD} = V _{REFH} = 3.6V
Dynamic Performance (10-Bit Mode)⁽²⁾							
HAD33b	F _{NYQ}	Input Signal Bandwidth	—	—	400	kHz	

Note 1: These parameters are characterized, but are tested at 20 ksp/s only.

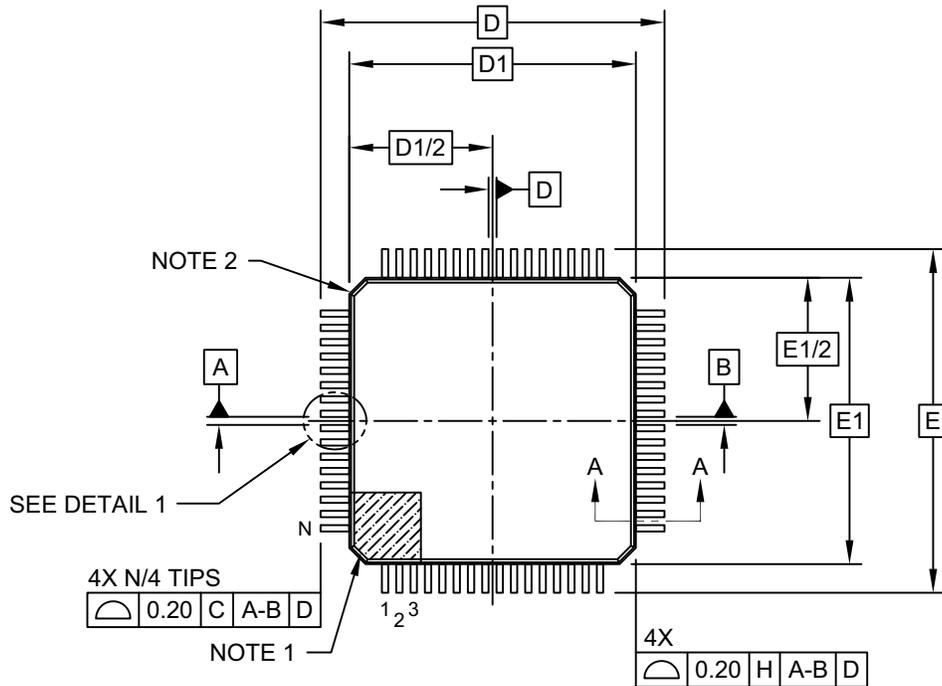
2: These parameters are characterized by similarity, but are not tested in manufacturing.

3: Injection currents $> |0|$ can affect the ADC results by approximately 4-6 counts.

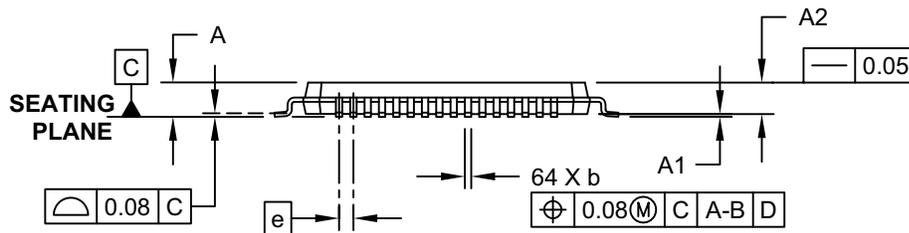
dsPIC33EPXXXGM3XX/6XX/7XX

64-Lead Plastic Thin Quad Flatpack (PT)-10x10x1 mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



TOP VIEW



SIDE VIEW

Microchip Technology Drawing C04-085C Sheet 1 of 2