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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

|                            |   |
|----------------------------|---|
| Product Status             | Discontinued at Digi-Key  |
| Core Processor             | ARM® Cortex®-M0+  |
| Core Size                  | 32-Bit Single-Core  |
| Speed                      | 48MHz   |
| Connectivity               | I <sup>2</sup> C, LINbus, SCI, SPI, UART/USART, USB   |
| Peripherals                | DMA, POR, PWM, WDT  |
| Number of I/O              | 51  |
| Program Memory Size        | 256KB (256K x 8)  |
| Program Memory Type        | FLASH   |
| EEPROM Size                | -   |
| RAM Size                   | 32K x 8   |
| Voltage - Supply (Vcc/Vdd) | 1.62V ~ 3.63V   |
| Data Converters            | A/D 20x12b; D/A 2x12b   |
| Oscillator Type            | Internal  |
| Operating Temperature      | -40°C ~ 85°C (TA)   |
| Mounting Type              | Surface Mount   |
| Package / Case             | 64-TQFP   |
| Supplier Device Package    | 64-TQFP (10x10)   |
| Purchase URL               | <a href="https://www.e-xfl.com/product-detail/microchip-technology/atsaml21j18a-aut">https://www.e-xfl.com/product-detail/microchip-technology/atsaml21j18a-aut</a> |

- Static and Dynamic Power Gating Architecture
- Battery backup support
- Two Performance Levels
- Embedded Buck/LDO regulator supporting on-the-fly selection
- Peripherals
  - 16-channel Direct Memory Access Controller (DMAC)
  - 12-channel Event System
  - Up to five 16-bit Timer/Counters (TC) including one low-power TC, each configurable as:
    - 16-bit TC with two compare/capture channels
    - 8-bit TC with two compare/capture channels
    - 32-bit TC with two compare/capture channels, by using two TCs
  - Two 24-bit and one 16-bit Timer/Counters for Control (TCC), with extended functions:
    - Up to four compare channels with optional complementary output
    - Generation of synchronized pulse width modulation (PWM) pattern across port pins
    - Deterministic fault protection, fast decay and configurable dead-time between complementary output
    - Dithering that increase resolution with up to 5 bit and reduce quantization error
  - 32-bit Real Time Counter (RTC) with clock/calendar function
  - Watchdog Timer (WDT)
  - CRC-32 generator
  - One full-speed (12Mbps) Universal Serial Bus (USB) 2.0 interface
    - Embedded host and device function
    - Eight endpoints
  - Up to six Serial Communication Interfaces (SERCOM) including one low-power SERCOM, each configurable to operate as either:
    - USART with full-duplex and single-wire half-duplex configuration
    - I<sup>2</sup>C up to 3.4MHz
    - SPI
    - LIN slave
  - One AES encryption engine
  - One True Random Generator (TRNG)
  - One Configurable Custom Logic (CCL)
  - One 12-bit, 1MSPS Analog-to-Digital Converter (ADC) with up to 20 channels
    - Differential and single-ended input
    - Automatic offset and gain error compensation
    - Oversampling and decimation in hardware to support 13-, 14-, 15-, or 16-bit resolution
  - Two 12-bit, 1MSPS Dual Output Digital-to-Analog Converter (DAC)
  - Two Analog Comparators (AC) with window compare function
  - Three Operational Amplifiers (OPAMP)
  - Peripheral Touch Controller (PTC)
    - 169-Channel capacitive touch and proximity sensing
    - Wake-up on touch in standby mode
- Oscillators
  - 32.768kHz crystal oscillator (XOSC32K)

The Atmel SAM L21 devices are supported with a full suite of programs and system development tools, including C compilers, macro assemblers, program debugger/simulators, programmers and evaluation kits.

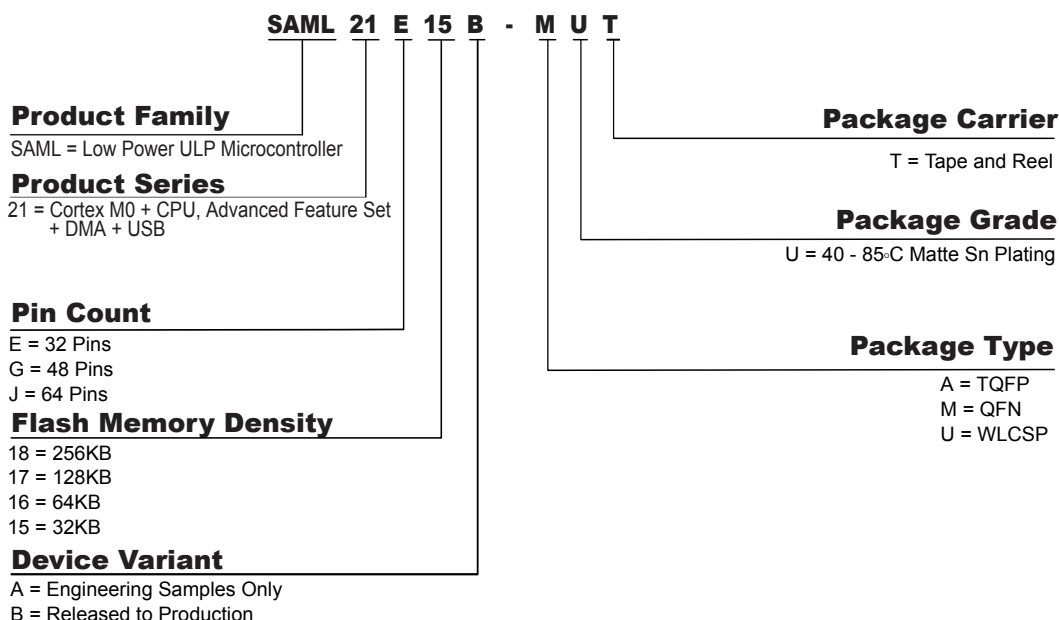
|   | SAM L21J   | SAM L21G                              | SAM L21E                              |
|---|--|---------------------------------------|---------------------------------------|
| Real-Time Counter (RTC)   | Yes  | Yes                                   | Yes                                   |
| RTC alarms  | 1  | 1                                     | 1                                     |
| RTC compare values  | One 32-bit value or two 16-bit values  | One 32-bit value or two 16-bit values | One 32-bit value or two 16-bit values |
| External Interrupt lines  | 16   | 16                                    | 16                                    |
| Peripheral Touch Controller (PTC) channels (X- x Y-Lines) for mutual capacitance <sup>(2)</sup> | 169 (13x13)  | 81 (9x9)                              | 42 (7x6)                              |
| Peripheral Touch Controller (PTC) channels for self capacitance (Y-Lines only) <sup>(3)</sup>   | 16   | 10                                    | 7                                     |
| Maximum CPU frequency   | 48MHz  |                                       |                                       |
| Packages  | QFN<br>TQFP<br>WLCSP <sup>(4)</sup>  | QFN<br>TQFP                           | QFN<br>TQFP                           |
| Oscillators   | 32.768kHz crystal oscillator (XOSC32K)<br>0.4-32MHz crystal oscillator (XOSC)<br>32.768kHz internal oscillator (OSC32K)<br>32KHz ultra-low-power internal oscillator (OSCULP32K)<br>16/12/8/4MHz high-accuracy internal oscillator (OSC16M)<br>48MHz Digital Frequency Locked Loop (DFLL48M)<br>96MHz Fractional Digital Phased Locked Loop (FDPLL96M) |                                       |                                       |
| Event System channels   | 12   | 12                                    | 12                                    |
| SW Debug Interface  | Yes  | Yes                                   | Yes                                   |
| Watchdog Timer (WDT)  | Yes  | Yes                                   | Yes                                   |

**Note:**

1. For SAM L21E and SAM L21G, only TC0, TC1 and TC4 are available.
2. The number of X- and Y-lines depends on the configuration of the device, as some I/O lines can be configured as either X-lines or Y-lines. Refer to *Multiplexed Signals* for details. The number in the Configuration Summary is the maximum number of channels that can be obtained.

3. The number of Y-lines depends on the configuration of the device, as some I/O lines can be configured as either X-lines or Y-lines. The number given here is the maximum number of Y-lines that can be obtained.
4. WLCSP parts are programmed with a specific SPI bootloader. Refer to Application Note AT09002 for details.

### 3. Ordering Information



**Note:** The device variant (last letter of the ordering number) is independent of the die revision (DSU.DID.REVISION): The device variant denotes functional differences, whereas the die revision marks evolution of the die.

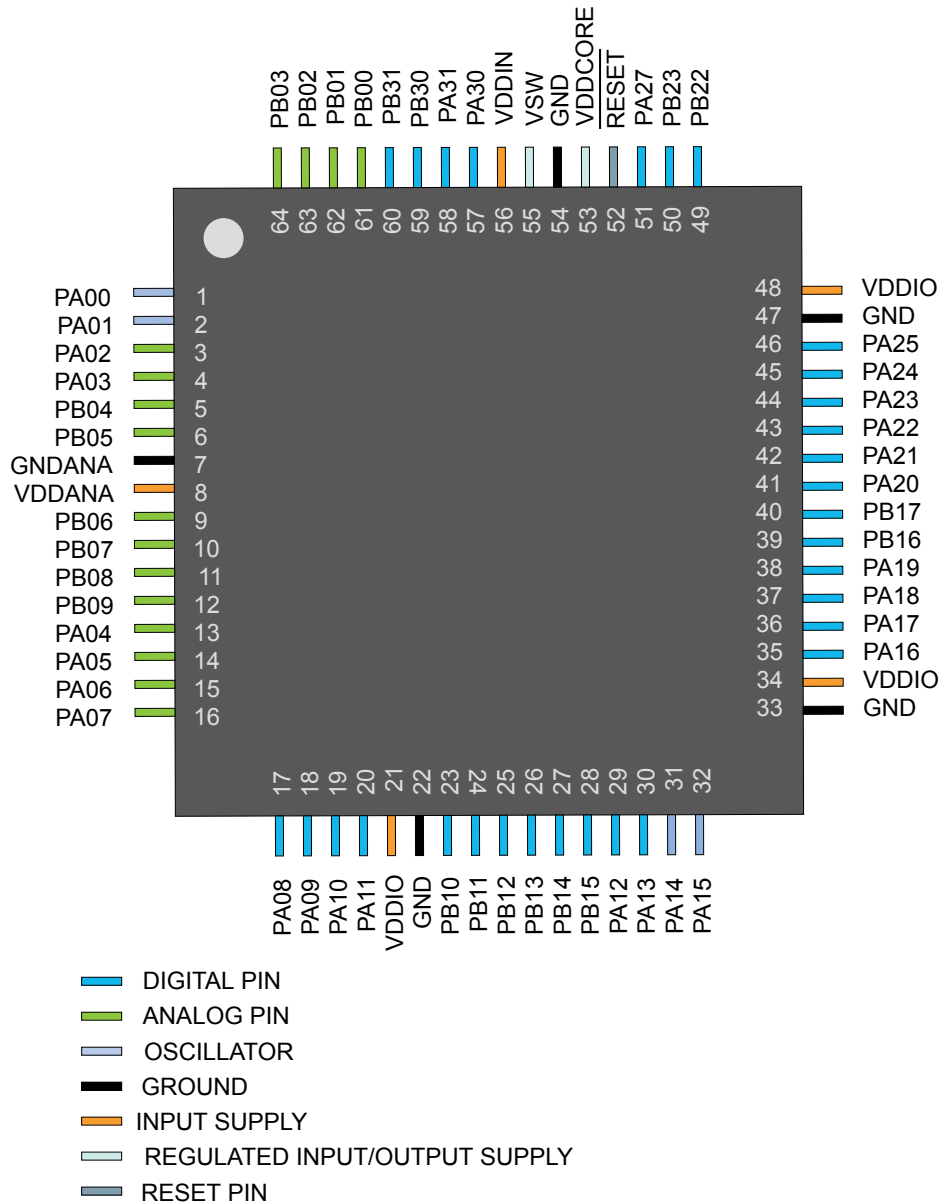
#### 3.1. SAM L21J

Table 3-1. SAM L21J Ordering Codes

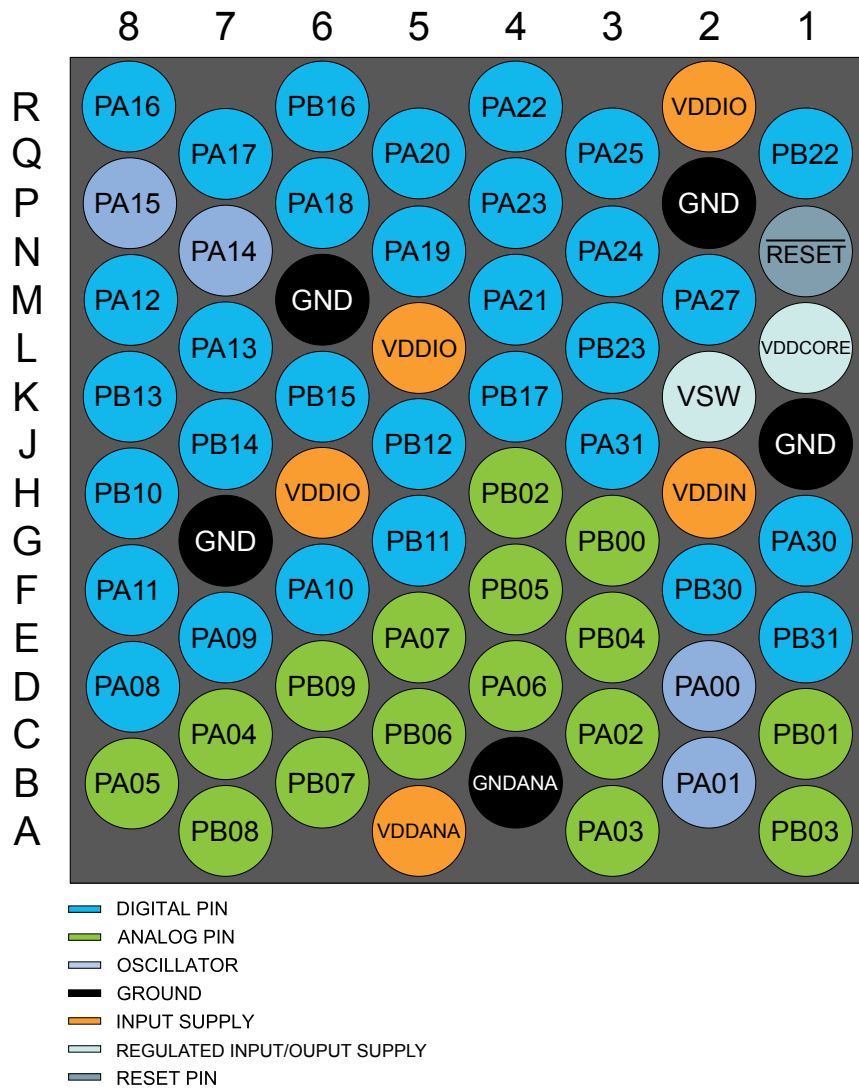
| Ordering Code    | FLASH (bytes) | SRAM (bytes) | Package | Carrier Type |
|------------------|---------------|--------------|---------|--------------|
| ATSAML21J16B-AUT | 64K           | 8K           | TQFP64  | Tape & Reel  |
| ATSAML21J16B-MUT |               |              | QFN64   |              |
| ATSAML21J17B-AUT | 128K          | 16K          | TQFP64  | Tape & Reel  |
| ATSAML21J17B-MUT |               |              | QFN64   |              |
| ATSAML21J17B-UUT |               |              | WLCSP64 |              |
| ATSAML21J18B-AUT | 256K          | 32K          | TQFP64  | Tape & Reel  |
| ATSAML21J18B-MUT |               |              | QFN64   |              |
| ATSAML21J18B-UUT |               |              | WLCSP64 |              |

## 5. Pinout

### 5.1. SAM L21J

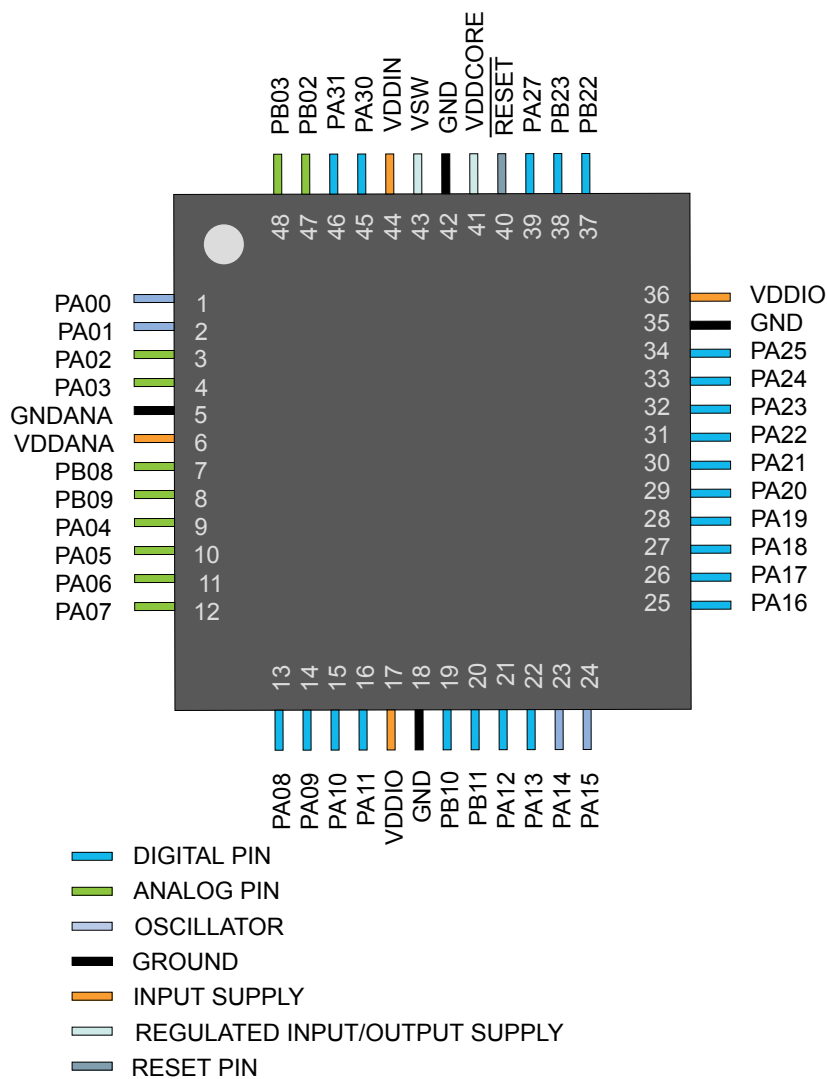


## 5.2. SAM L21J WLCSP64

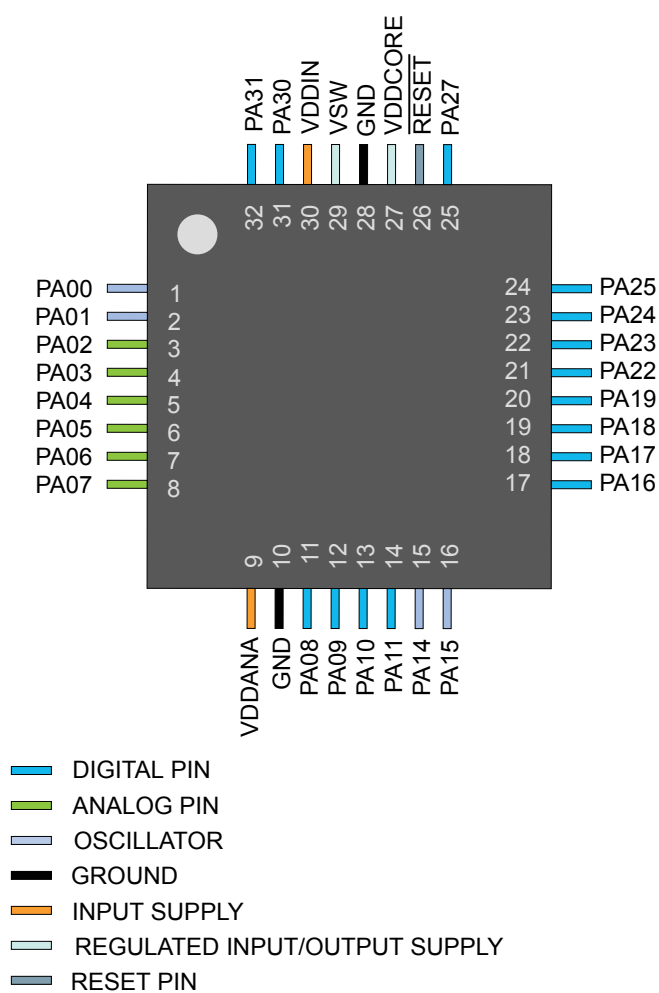




### 5.3. SAM L21G

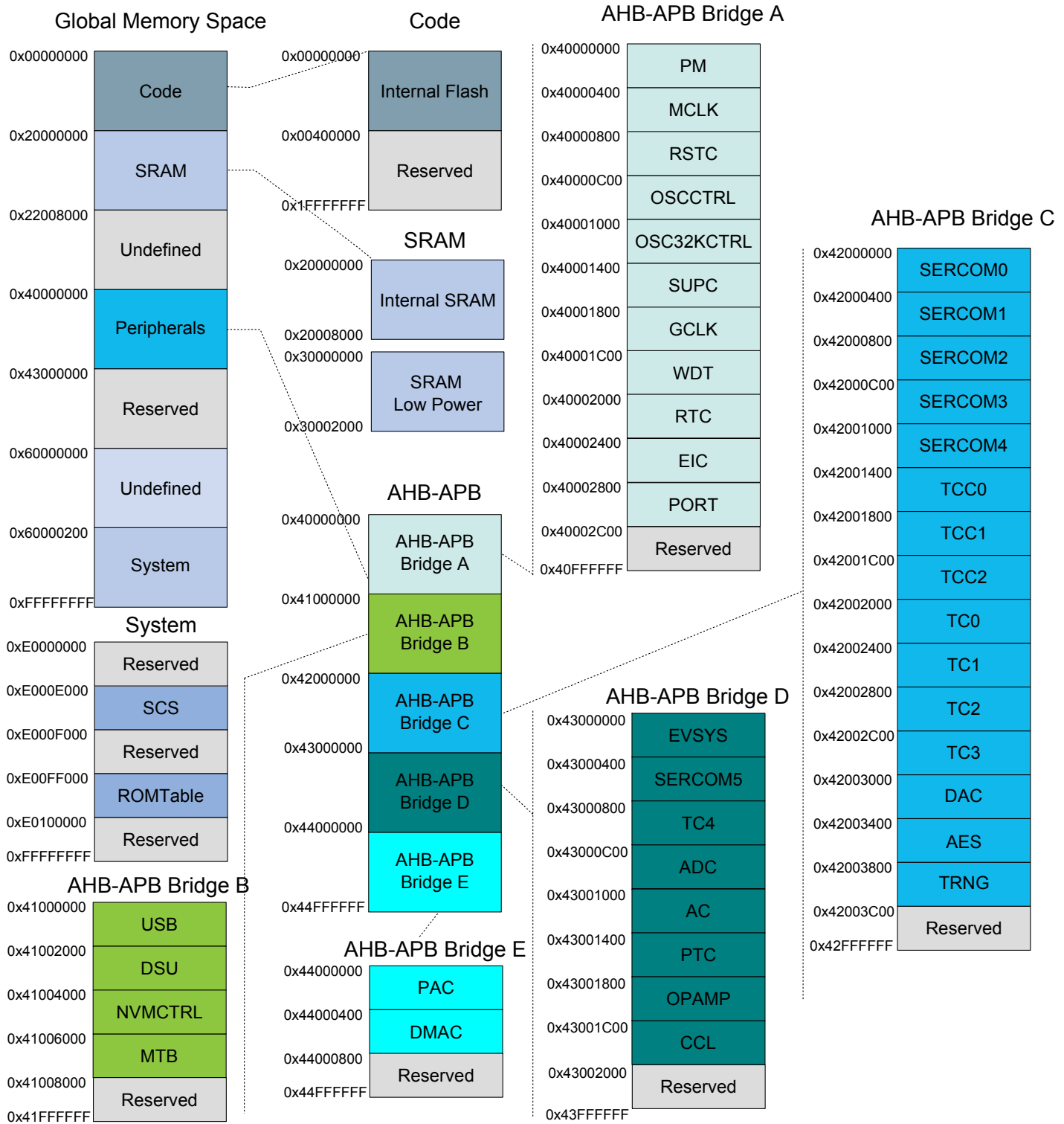


## 5.4. SAM L21E



## 6. Product Mapping

### Figure 6-1. Atmel SAM L21 Product Mapping



## 7. Processor and Architecture

### 7.1. Cortex M0+ Processor

The Atmel SAM L21 implements the ARM®Cortex™-M0+ processor, based on the ARMv6 Architecture and Thumb®-2 ISA. The Cortex M0+ is 100% instruction set compatible with its predecessor, the Cortex-M0 core, and upward compatible to Cortex-M3 and M4 cores. The implemented ARM Cortex-M0+ is revision r0p1. For more information refer to <http://www.arm.com>

#### 7.1.1. Cortex M0+ Configuration

Table 7-1. Cortex M0+ Configuration in Atmel SAM L21

| Features                         | Cortex M0+ options           | Atmel SAM L21 configuration                       |
|----------------------------------|------------------------------|---|
| Interrupts                       | External interrupts 0-32     | 29  |
| Data endianness                  | Little-endian or big-endian  | Little-endian                                     |
| SysTick timer                    | Present or absent            | Present   |
| Number of watchpoint comparators | 0, 1, 2                      | 2   |
| Number of breakpoint comparators | 0, 1, 2, 3, 4                | 4   |
| Halting debug support            | Present or absent            | Present   |
| Multiplier                       | Fast or small                | Fast (single cycle)                               |
| Single-cycle I/O port            | Present or absent            | Present   |
| Wake-up interrupt controller     | Supported or not supported   | Not supported                                     |
| Vector Table Offset Register     | Present or absent            | Present   |
| Unprivileged/Privileged support  | Present or absent            | Absent - All software run in privileged mode only |
| Memory Protection Unit           | Not present or 8-region      | Not present                                       |
| Reset all registers              | Present or absent            | Absent  |
| Instruction fetch width          | 16-bit only or mostly 32-bit | 32-bit  |

The ARM Cortex-M0+ core has two bus interfaces:

- Single 32-bit AMBA-3 AHB-Lite system interface that provides connections to peripherals and all system memory including Flash memory and RAM
- Single 32-bit I/O port bus interfacing to the PORT with 1-cycle loads and stores

##### 7.1.1.1. Cortex M0+ Peripherals

- System Control Space (SCS)
  - The processor provides debug through registers in the SCS. Refer to the Cortex-M0+ Technical Reference Manual for details (<http://www.arm.com>)
- Nested Vectored Interrupt Controller (NVIC)

- External interrupt signals connect to the NVIC, and the NVIC prioritizes the interrupts. Software can set the priority of each interrupt. The NVIC and the Cortex-M0+ processor core are closely coupled, providing low latency interrupt processing and efficient processing of late arriving interrupts. Refer to the Cortex-M0+ Technical Reference Manual for details (<http://www.arm.com>).
- Note:** When the CPU frequency is much higher than the APB frequency it is recommended to insert a memory read barrier after each CPU write to registers mapped on the APB. Failing to do so in such conditions may lead to unexpected behavior such as e.g. re-entering a peripheral interrupt handler just after leaving it.
- System Timer (SysTick)
  - The System Timer is a 24-bit timer clocked by CLK\_CPU that extends the functionality of both the processor and the NVIC. Refer to the Cortex-M0+ Technical Reference Manual for details (<http://www.arm.com>).
- System Control Block (SCB)
  - The System Control Block provides system implementation information, and system control. This includes configuration, control, and reporting of the system exceptions. Refer to the Cortex-M0+ Devices Generic User Guide for details (<http://www.arm.com>).
- Micro Trace Buffer (MTB)
  - The CoreSight MTB-M0+ (MTB) provides a simple execution trace capability to the Cortex-M0+ processor. Refer to section [MTB-Micro Trace Buffer](#) and the CoreSight MTB-M0+ Technical Reference Manual for details (<http://www.arm.com>).

## Related Links

[Nested Vector Interrupt Controller](#) on page 21

### 7.1.1.2. Cortex M0+ Address Map

Table 7-2. Cortex-M0+ Address Map

| Address    | Peripheral                                  |
|------------|---|
| 0xE000E000 | System Control Space (SCS)                  |
| 0xE000E010 | System Timer (SysTick)                      |
| 0xE000E100 | Nested Vectored Interrupt Controller (NVIC) |
| 0xE000ED00 | System Control Block (SCB)                  |
| 0x41006000 | Micro Trace Buffer (MTB)                    |

### 7.1.1.3. I/O Interface

The device allows direct access to PORT registers. Accesses to the AMBA<sup>®</sup> AHB-Lite<sup>™</sup> and the single cycle I/O interface can be made concurrently, so the Cortex M0+ processor can fetch the next instructions while accessing the I/Os. This enables single cycle I/O access to be sustained for as long as necessary.

## 7.2. Nested Vector Interrupt Controller

### 7.2.1. Overview

The Nested Vectored Interrupt Controller (NVIC) in the SAM L21 supports 32 interrupt lines with four different priority levels. For more details, refer to the Cortex-M0+ Technical Reference Manual (<http://www.arm.com>).

MASTER register. The MTB can be programmed to stop tracing automatically when the memory fills to a specified watermark level or to start or stop tracing by writing directly to the MASTER.EN bit. If the watermark mechanism is not being used and the trace buffer overflows, then the buffer wraps around overwriting previous trace packets.

The base address of the MTB registers is 0x41006000; this address is also written in the CoreSight ROM Table. The offset of each register from the base address is fixed and as defined by the CoreSight MTB-M0+ Technical Reference Manual. The MTB has four programmable registers to control the behavior of the trace features:

- POSITION: Contains the trace write pointer and the wrap bit
- MASTER: Contains the main trace enable bit and other trace control fields
- FLOW: Contains the WATERMARK address and the AUTOSTOP and AUTOHALT control bits
- BASE: Indicates where the SRAM is located in the processor memory map. This register is provided to enable auto discovery of the MTB SRAM location by a debug agent

See the CoreSight MTB-M0+ Technical Reference Manual for a detailed description of these registers.

## 7.4. High-Speed Bus System

### 7.4.1. Features

High-Speed Bus Matrix has the following features:

- Symmetric crossbar bus switch implementation
- Allows concurrent accesses from different masters to different slaves
- 32-bit data bus
- Operation at a one-to-one clock frequency with the bus masters

H2LBRIDGE has the following features:

- LP clock division support
- Write: Posted-write FIFO of 3 words, no bus stall until it is full
- Write: 1 cycle bus stall when full when LP clock is not divided
- 2 stall cycles on read when LP clock is not divided
- Ultra low latency mode:
  - Suitable when the HS clock frequency is not above half the maximum device clock frequency
  - Removes all intrinsic bridge stall cycles (except those needed for LP clock ratio adaptation)
  - Enabled by writing a '1' in 0x41008120 using a 32-bit write access

L2HBRIDGE has the following features:

- LP clock division support
- Write: Posted-write FIFO of 1 word, no bus stall until it is full
- Write: 1 cycle bus stall when full when LP clock is not divided
- 2 stall cycles on read when LP clock is not divided
- ultra low latency mode:
  - Suitable when the HS clock frequency is not above half the maximum device clock frequency
  - Removes all intrinsic bridge stall cycles (except those needed for LP clock ratio adaptation)
  - Enabled by writing a '1' in 0x41008120 using a 32-bit write access

The Quality of Service (QoS) level is independently selected for each master accessing the RAM. For any access to the RAM, the RAM also receives the QoS level. The QoS levels and their corresponding bit values for the QoS level configuration are shown in the following table.

**Table 7-8. Quality of Service**

| Value | Name    | Description                         |
|-------|---------|-------------------------------------|
| 0x0   | DISABLE | Background (no sensitive operation) |
| 0x1   | LOW     | Sensitive Bandwidth                 |
| 0x2   | MEDIUM  | Sensitive Latency                   |
| 0x3   | HIGH    | Critical Latency                    |

If a master is configured with QoS level DISABLE (0x0) or LOW (0x1) there will be a minimum latency of one cycle for the RAM access.

The priority order for concurrent accesses are decided by two factors. First, the QoS level for the master and second, a static priority given by the port ID. The lowest port ID has the highest static priority. See the tables below for details.

The MTB has a fixed QoS level HIGH (0x3).

The CPU QoS level can be written/read, using 32-bit access only, at address 0x41008114 bits [1:0]. Its reset value is 0x3.

Refer to different master QOSCTRL registers for configuring QoS for the other masters (USB, DMAC).

**Table 7-9. HS SRAM Port Connections QoS**

| HS SRAM Port Connection          | Port ID | Connection Type | QoS                                   | default QoS |
|----------------------------------|---------|-----------------|---------------------------------------|-------------|
| MTB - Micro Trace Buffer         | 4       | Direct          | STATIC-3                              | 0x3         |
| USB - Universal Serial Bus       | 3       | Direct          | IP-QOSCTRL                            | 0x3         |
| HMATRIXLP - Low-Power Bus Matrix | 2       | Bus Matrix      | 0x44000934 <sup>(1)</sup> , bits[1:0] | 0x2         |
| DSU - Device Service Unit        | 1       | Bus Matrix      | 0x4100201C <sup>(1)</sup>             | 0x2         |
| CM0+ - Cortex M0+ Processor      | 0       | Bus Matrix      | 0x41008114 <sup>(1)</sup> , bits[1:0] | 0x3         |

**Note:**

1. Using 32-bit access only.

**Table 7-10. LP SRAM Port Connections QoS**

| LP SRAM Port Connection                                    | Port ID | Connection Type | QoS               | default QoS |
|--|---------|-----------------|-------------------|-------------|
| DMAC - Direct Memory Access Controller - Write-Back Access | 5, 6    | Direct          | IP-QOSCTRL.WRBQOS | 0x2         |
| DMAC - Direct Memory Access Controller - Fetch Access      | 3, 4    | Direct          | IP-QOSCTRL.FQOS   | 0x2         |

## 8. Packaging Information

### 8.1. Thermal Considerations

#### 8.1.1. Thermal Resistance Data

The following table summarizes the thermal resistance data depending on the package.

**Table 8-1. Thermal Resistance Data**

| Package Type | $\theta_{JA}$ | $\theta_{JC}$ |
|--------------|---------------|---------------|
| 32-pin TQFP  | 68°C/W        | 25.8°C/W      |
| 48-pin TQFP  | 78.8°C/W      | 12.3°C/W      |
| 64-pin TQFP  | 66.7°C/W      | 11.9°C/W      |
| 32-pin QFN   | 37.2°C/W      | 3.1°C/W       |
| 48-pin QFN   | 31.6°C/W      | 10.3°C/W      |
| 64-pin QFN   | 32.2°C/W      | 10.1°C/W      |
| 64-pin WLCSP | 36.8°C/W      | 5.0°C/W       |

#### Related Links

[Junction Temperature](#) on page 29

#### 8.1.2. Junction Temperature

The average chip-junction temperature,  $T_J$ , in °C can be obtained from the following:

1.  $T_J = T_A + (P_D \times \theta_{JA})$
2.  $T_J = T_A + (P_D \times (\theta_{HEATSINK} + \theta_{JC}))$

where:

- $\theta_{JA}$  = Package thermal resistance, Junction-to-ambient (°C/W), see Thermal Resistance Data
- $\theta_{JC}$  = Package thermal resistance, Junction-to-case thermal resistance (°C/W), see Thermal Resistance Data
- $\theta_{HEATSINK}$  = Thermal resistance (°C/W) specification of the external cooling device
- $P_D$  = Device power consumption (W)
- $T_A$  = Ambient temperature (°C)

From the first equation, the user can derive the estimated lifetime of the chip and decide if a cooling device is necessary or not. If a cooling device is to be fitted on the chip, the second equation should be used to compute the resulting average chip-junction temperature  $T_J$  in °C.

#### Related Links

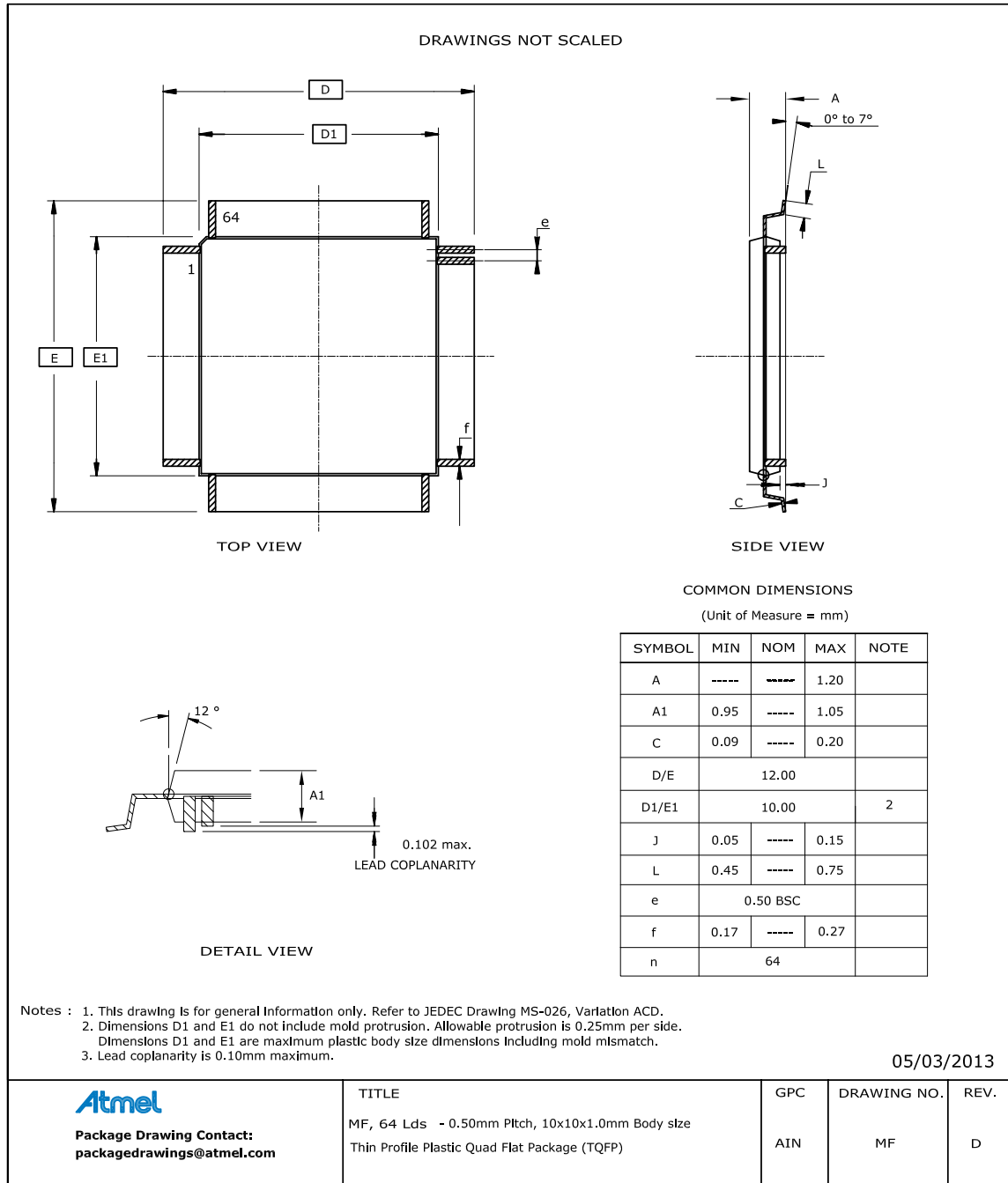
[Thermal Resistance Data](#) on page 29



**Table 8-4. Package Reference**

|                         |     |
|-------------------------|-----|
| JEDEC Drawing Reference | N/A |
| JESD97 Classification   | E1  |

### 8.2.2. 64 pin TQFP



**Table 8-5. Device and Package Maximum Weight**

|     |    |
|-----|----|
| 300 | mg |
|-----|----|

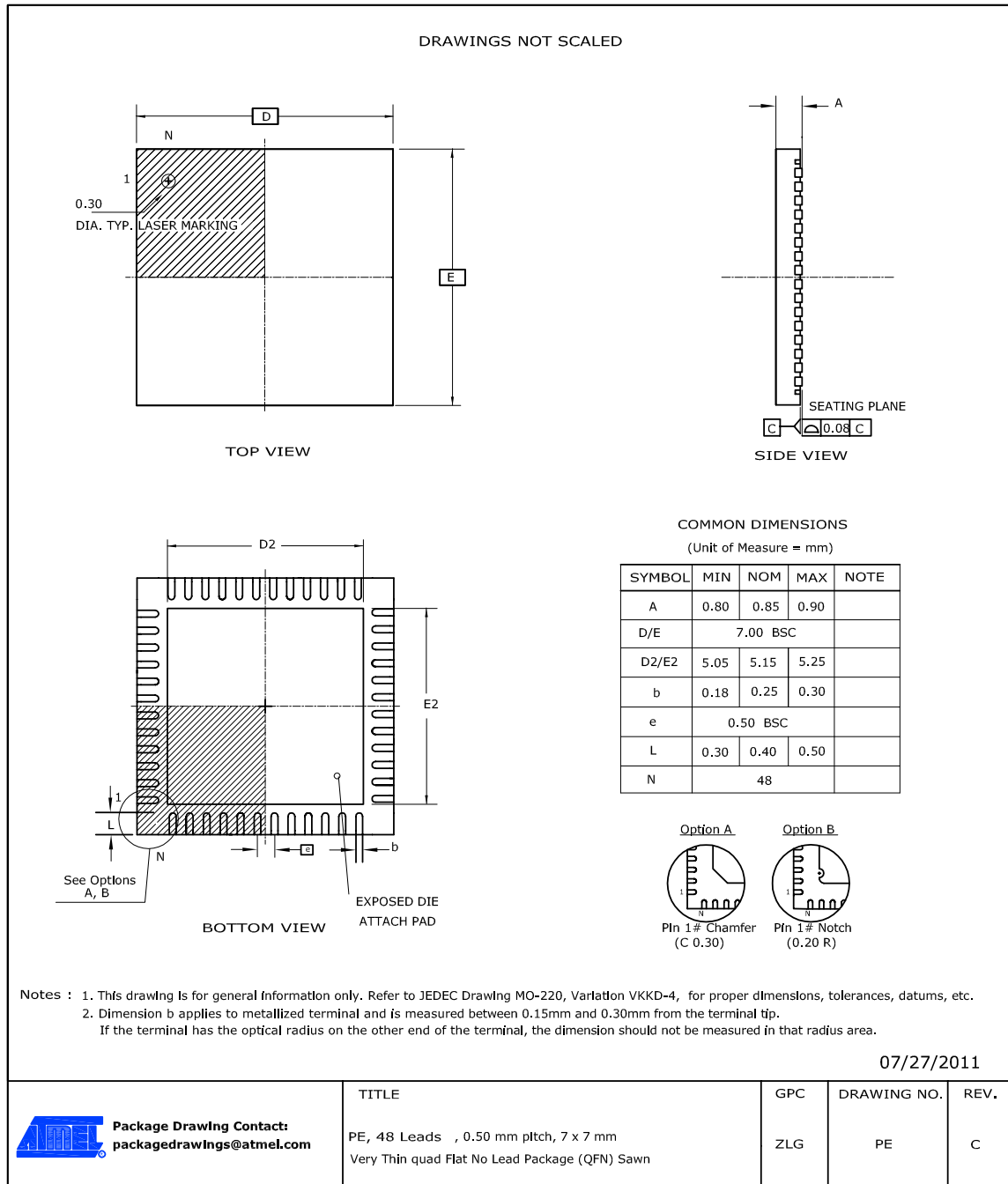
**Table 8-12. Package Characteristics**

|                            |      |
|----------------------------|------|
| Moisture Sensitivity Level | MSL3 |
|----------------------------|------|

**Table 8-13. Package Reference**

|                         |        |
|-------------------------|--------|
| JEDEC Drawing Reference | MS-026 |
| JESD97 Classification   | E3     |

### 8.2.5. 48 pin QFN



**Note:** The exposed die attach pad is not connected electrically inside the device.

**Table 8-14. Device and Package Maximum Weight**

|     |    |
|-----|----|
| 140 | mg |
|-----|----|

**Table 8-15. Package Characteristics**

|                            |      |
|----------------------------|------|
| Moisture Sensitivity Level | MSL3 |
|----------------------------|------|

**Table 8-16. Package Reference**

|                         |        |
|-------------------------|--------|
| JEDEC Drawing Reference | MO-220 |
| JESD97 Classification   | E3     |

8.2.6. 32 pin TQFP

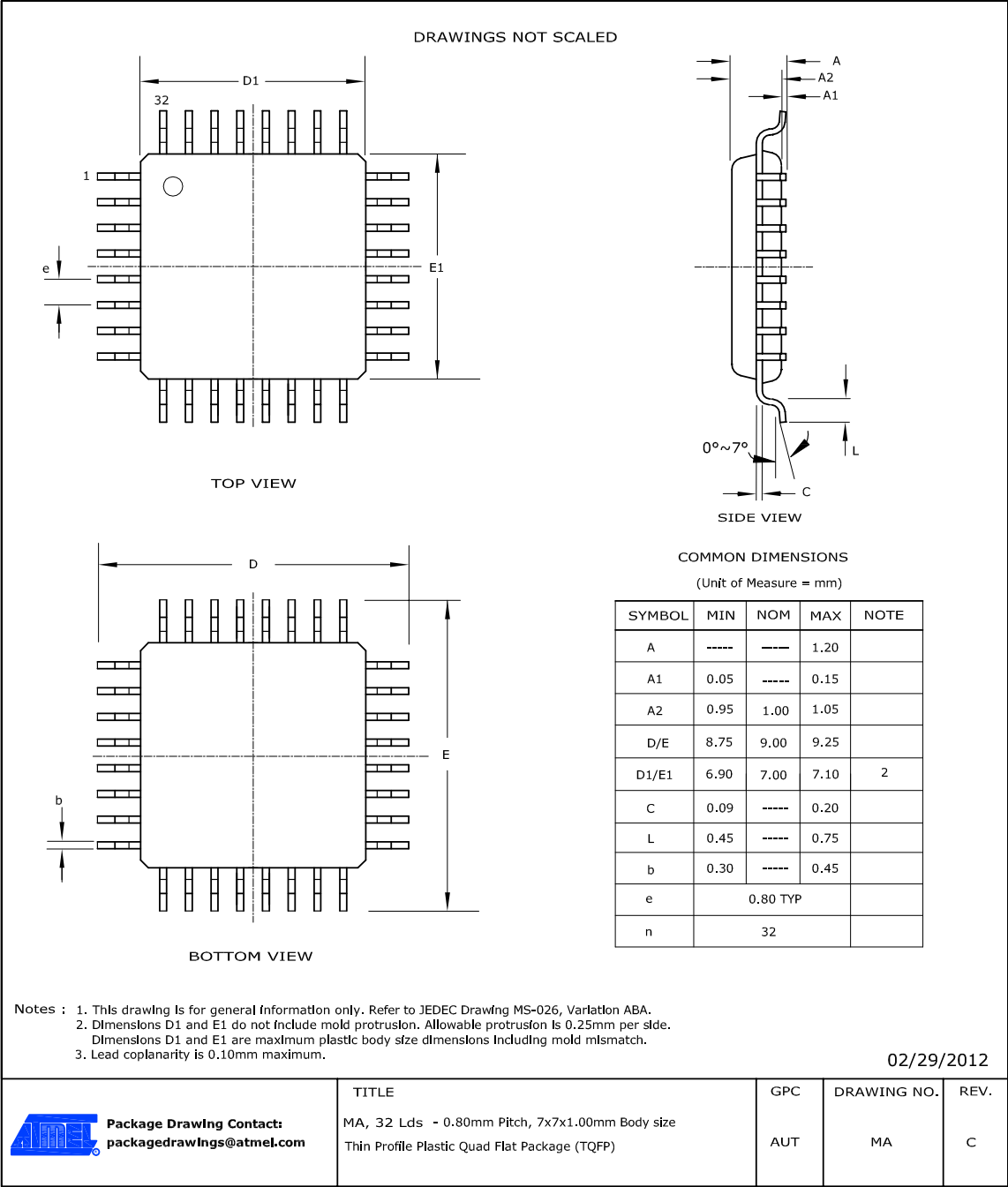


Table 8-17. Device and Package Maximum Weight

|     |    |
|-----|----|
| 100 | mg |
|-----|----|

Table 8-18. Package Characteristics

|                            |      |
|----------------------------|------|
| Moisture Sensitivity Level | MSL3 |
|----------------------------|------|

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