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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I <sup>2</sup> C, PMP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	35
Program Memory Size	64KB (22K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 13x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24hj64gp204-i-ml">https://www.e-xfl.com/product-detail/microchip-technology/pic24hj64gp204-i-ml</a>

## Referenced Sources

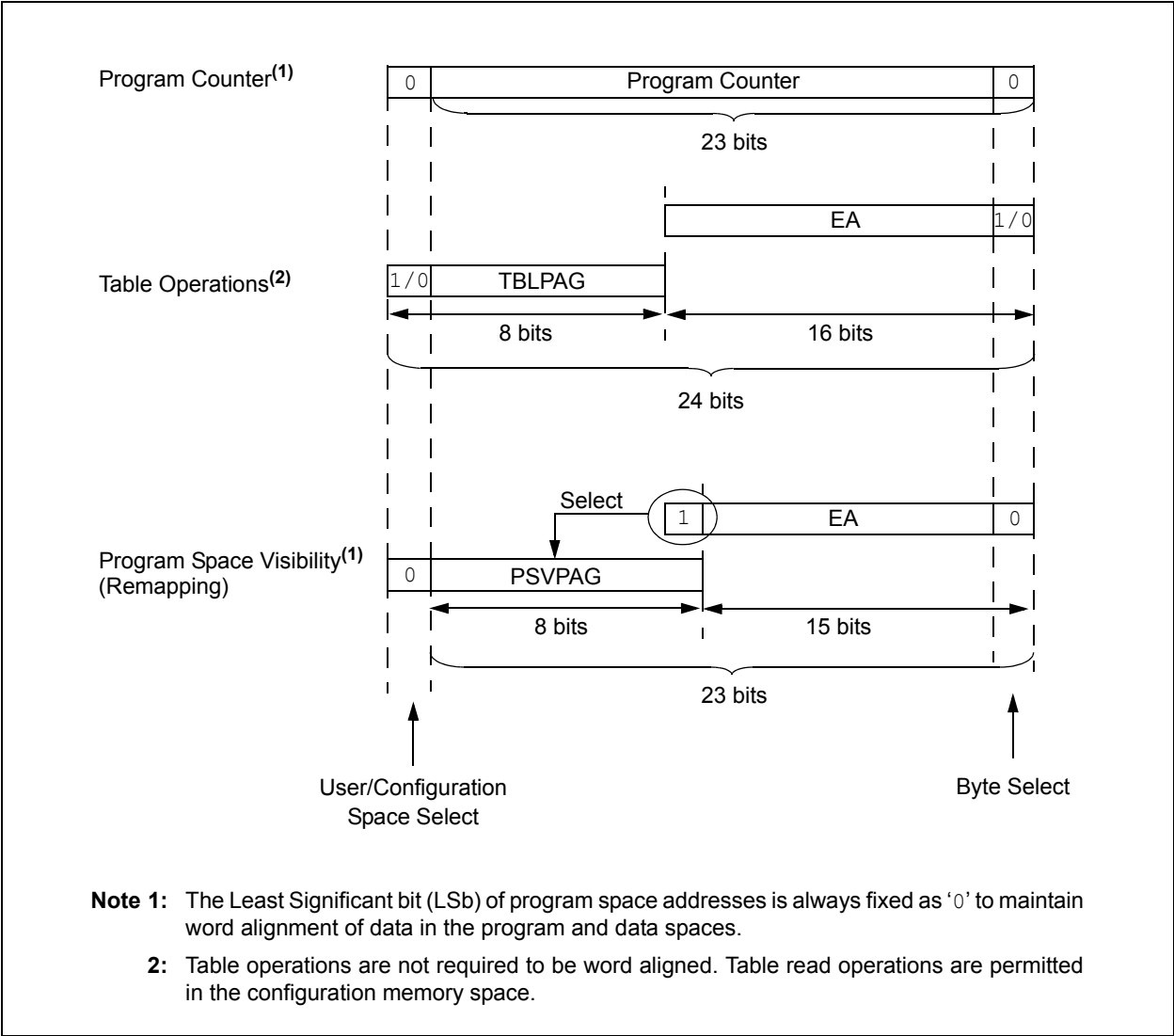
This device data sheet is based on the following individual chapters of the “*dsPIC33F/PIC24H Family Reference Manual*”. These documents should be considered as the general reference for the operation of a particular module or device feature.

**Note 1:** To access the documents listed below, browse to the documentation section of the [PIC24HJ64GP204](#) product page of the Microchip web site ([www.microchip.com](http://www.microchip.com)) or select a family reference manual section from the following list.

In addition to parameters, features, and other documentation, the resulting page provides links to the related family reference manual sections.

- **Section 1. “Introduction”** (DS70197)
- **Section 2. “CPU”** (DS70204)
- **Section 3. “Data Memory”** (DS70202)
- **Section 4. “Program Memory”** (DS70202)
- **Section 5. “Flash Programming”** (DS70191)
- **Section 8. “Reset”** (DS70192)
- **Section 9. “Watchdog Timer and Power-saving Modes”** (DS70196)
- **Section 11. “Timers”** (DS70205)
- **Section 12. “Input Capture”** (DS70198)
- **Section 13. “Output Compare”** (DS70209)
- **Section 16. “Analog-to-Digital Converter (ADC)”** (DS70183)
- **Section 17. “UART”** (DS70188)
- **Section 18. “Serial Peripheral Interface (SPI)”** (DS70206)
- **Section 19. “Inter-Integrated Circuit™ (I<sup>2</sup>C™)”** (DS70195)
- **Section 23. “CodeGuard™ Security”** (DS70199)
- **Section 24. “Programming and Diagnostics”** (DS70209)
- **Section 25. “Device Configuration”** (DS70194)
- **Section 30. “I/O Ports with Peripheral Pin Select (PPS)”** (DS70190)
- **Section 32. “Interrupts (Part III)”** (DS70214)
- **Section 33. “Audio Digital-to-Analog Converter (DAC)”** (DS70211)
- **Section 34. “Comparator”** (DS70212)
- **Section 35. “Parallel Master Port (PMP)”** (DS70299)
- **Section 36. “Programmable Cyclic Redundancy Check (CRC)”** (DS70298)
- **Section 37. “Real-Time Clock and Calendar (RTCC)”** (DS70301)
- **Section 38. “Direct Memory Access”** (DS70215)
- **Section 39. “Oscillator (Part III)”** (DS70216)

FIGURE 4-6: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION



## 6.1 Reset Resources

Many useful resources related to Resets are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](#), contains the latest updates and additional information.

**Note:** In the event you are not able to access the product page using the link above, enter this URL in your browser:  
<http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en534555>

### 6.1.1 KEY RESOURCES

- **Section 8. “Resets”** (DS70192)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

**REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2**

R/W-0	R-0	U-0	U-0	U-0	U-0	U-0	U-0
ALTIVT	DISI	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	INT2EP	INT1EP	INT0EP
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **ALTIVT:** Enable Alternate Interrupt Vector Table bit

1 = Use alternate vector table

0 = Use standard (default) vector table

bit 14 **DISI:** DISI Instruction Status bit

1 = DISI instruction is active

0 = DISI instruction is not active

bit 13-3 **Unimplemented:** Read as '0'

bit 2 **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

bit 1 **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

bit 0 **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit

1 = Interrupt on negative edge

0 = Interrupt on positive edge

### 9.3 Oscillator Control Registers

#### REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER<sup>(1,3)</sup>

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
—	COSC<2:0>			—	NOSC<2:0> <sup>(2)</sup>		
bit 15				bit 8			

R/W-0	R/W-0	R-0	U-0	R/C-0	U-0	R/W-0	R/W-0
CLKLOCK	IOLOCK	LOCK	—	CF	—	LPOSCEN	OSWEN
bit 7				bit 0			

<b>Legend:</b>	y = Value set from Configuration bits on POR	C = Clear only bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits (read-only)

- 111 = Fast RC oscillator (FRC) with Divide-by-n
- 110 = Fast RC oscillator (FRC) with Divide-by-16
- 101 = Low-Power RC oscillator (LPRC)
- 100 = Secondary oscillator (Sosc)
- 011 = Primary oscillator (XT, HS, EC) with PLL
- 010 = Primary oscillator (XT, HS, EC)
- 001 = Fast RC Oscillator (FRC) with divide-by-N and PLL (FRCDIVN + PLL)
- 000 = Fast RC oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits<sup>(2)</sup>

- 111 = Fast RC oscillator (FRC) with Divide-by-n
- 110 = Fast RC oscillator (FRC) with Divide-by-16
- 101 = Low-Power RC oscillator (LPRC)
- 100 = Secondary oscillator (Sosc)
- 011 = Primary oscillator (XT, HS, EC) with PLL
- 010 = Primary oscillator (XT, HS, EC)
- 001 = Fast RC Oscillator (FRC) with divide-by-N and PLL (FRCDIVN + PLL)
- 000 = Fast RC oscillator (FRC)

bit 7 **CLKLOCK:** Clock Lock Enable bit

If clock switching is enabled and FSCM is disabled, FCKSM<1:0>(FOSC<7:6>) = 0b01)

- 1 = Clock switching is disabled, system clock source is locked
- 0 = Clock switching is enabled, system clock source can be modified by clock switching

bit 6 **IOLOCK:** Peripheral Pin Select Lock bit

- 1 = Peripheral pin select is locked, write to peripheral pin select registers not allowed
- 0 = Peripheral pin select is not locked, write to peripheral pin select registers allowed

bit 5 **LOCK:** PLL Lock Status bit (read-only)

- 1 = Indicates that PLL is in lock, or PLL start-up timer is satisfied
- 0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled

bit 4 **Unimplemented:** Read as '0'

**Note 1:** Writes to this register require an unlock sequence. Refer to **Section 39. "Oscillator (Part III)"** (DS70308) in the *dsPIC33F/PIC24H Family Reference Manual* (available from the Microchip web site) for details.

**2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

**3:** This register is reset only on a Power-on Reset (POR).

**REGISTER 11-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3**

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T3CKR<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	T2CKR<4:0>				
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **T3CKR<4:0>:** Assign Timer3 External Clock (T3CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **T2CKR<4:0>:** Assign Timer2 External Clock (T2CK) to the corresponding RPn pin

11111 = Input tied to Vss

11001 = Input tied to RP25

•

•

•

00001 = Input tied to RP1

00000 = Input tied to RP0

**REGISTER 16-2: SPIxCON1: SPIx CONTROL REGISTER 1**

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	DISSCK	DISSDO	MODE16	SMP	CKE <sup>(1)</sup>
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEN <sup>(3)</sup>	CKP	MSTEN	SPRE<2:0> <sup>(2)</sup>			PPRE<1:0> <sup>(2)</sup>	
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **DISSCK:** Disable SCKx pin bit (SPI Master modes only)

1 = Internal SPI clock is disabled, pin functions as I/O

0 = Internal SPI clock is enabled

bit 11 **DISSDO:** Disable SDOx pin bit

1 = SDOx pin is not used by module; pin functions as I/O

0 = SDOx pin is controlled by the module

bit 10 **MODE16:** Word/Byte Communication Select bit

1 = Communication is word-wide (16 bits)

0 = Communication is byte-wide (8 bits)

bit 9 **SMP:** SPIx Data Input Sample Phase bit

Master mode:

1 = Input data sampled at end of data output time

0 = Input data sampled at middle of data output time

Slave mode:

SMP must be cleared when SPIx is used in Slave mode.

bit 8 **CKE:** SPIx Clock Edge Select bit<sup>(1)</sup>

1 = Serial output data changes on transition from active clock state to Idle clock state (see bit 6)

0 = Serial output data changes on transition from Idle clock state to active clock state (see bit 6)

bit 7 **SSEN:** Slave Select Enable bit (Slave mode)<sup>(3)</sup>

1 = SSx pin used for Slave mode

0 = SSx pin not used by module. Pin controlled by port function

bit 6 **CKP:** Clock Polarity Select bit

1 = Idle state for clock is a high level; active state is a low level

0 = Idle state for clock is a low level; active state is a high level

bit 5 **MSTEN:** Master Mode Enable bit

1 = Master mode

0 = Slave mode

**Note 1:** The CKE bit is not used in the Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).

**2:** Do not set both Primary and Secondary prescalers to a value of 1:1.

**3:** This bit must be cleared when FRMEN = 1.



**REGISTER 16-3: SPIxCON2: SPIx CONTROL REGISTER 2**

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0
FRMEN	SPIFSD	FRMPOL	—	—	—	—	—
bit 15			bit 8				

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0	
—	—	—	—	—	—	FRMDLY	—	
bit 7								bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15      **FRMEN:** Framed SPIx Support bit  
                  1 = Framed SPIx support enabled ( $\overline{\text{SSx}}$  pin used as frame sync pulse input/output)  
                  0 = Framed SPIx support disabled
- bit 14      **SPIFSD:** Frame Sync Pulse Direction Control bit  
                  1 = Frame sync pulse input (slave)  
                  0 = Frame sync pulse output (master)
- bit 13      **FRMPOL:** Frame Sync Pulse Polarity bit  
                  1 = Frame sync pulse is active-high  
                  0 = Frame sync pulse is active-low
- bit 12-2    **Unimplemented:** Read as '0'
- bit 1      **FRMDLY:** Frame Sync Pulse Edge Select bit  
                  1 = Frame sync pulse coincides with first bit clock  
                  0 = Frame sync pulse precedes first bit clock
- bit 0      **Unimplemented:** This bit must not be set to '1' by the user application

**REGISTER 19-8: CIEC: ECAN™ TRANSMIT/RECEIVE ERROR COUNT REGISTER**

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
TERRCNT<7:0>							
bit 15				bit 8			

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
RERRCNT<7:0>							
bit 7				bit 0			

**Legend:** C = Writeable bit, but only '0' can be written to clear the bit  
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'  
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **TERRCNT<7:0>**: Transmit Error Count bits

bit 7-0 **RERRCNT<7:0>**: Receive Error Count bits

**REGISTER 19-9: CIECFG1: ECAN™ BAUD RATE CONFIGURATION REGISTER 1**

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15				bit 8			

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SJW<1:0>		BRP<5:0>					
bit 7				bit 0			

**Legend:** R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'  
-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-6 **SJW<1:0>**: Synchronization Jump Width bits

11 = Length is 4 x T<sub>Q</sub>

10 = Length is 3 x T<sub>Q</sub>

01 = Length is 2 x T<sub>Q</sub>

00 = Length is 1 x T<sub>Q</sub>

bit 5-0 **BRP<5:0>**: Baud Rate Prescaler bits

11 1111 = T<sub>Q</sub> = 2 x 64 x 1/FCAN

•

•

•

00 0010 = T<sub>Q</sub> = 2 x 3 x 1/FCAN

00 0001 = T<sub>Q</sub> = 2 x 2 x 1/FCAN

00 0000 = T<sub>Q</sub> = 2 x 1 x 1/FCAN

## 20.0 10-BIT/12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC1)

**Note 1:** This data sheet summarizes the features of the PIC24HJ32GP302/304, PIC24HJ64GPX02/X04 and PIC24HJ128GPX02/X04 families of devices. It is not intended to be a comprehensive reference source. To complete the information in this data sheet, refer to **Section 16. “Analog-to-Digital Converter (ADC)”** (DS70183) of the “dsPIC33F/PIC24H Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The PIC24HJ32GP302/304, PIC24HJ64GPX02/X04 and PIC24HJ128GPX02/X04 devices have up to 13 ADC input channels.

The AD12B bit (AD1CON1<10>) allows each of the ADC modules to be configured by the user as either a 10-bit, 4-sample/hold ADC (default configuration) or a 12-bit, 1-sample/hold ADC.

**Note:** The ADC module needs to be disabled before modifying the AD12B bit.

### 20.1 Key Features

The 10-bit ADC configuration has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 1.1 Msps
- Up to 13 analog input pins
- External voltage reference input pins
- Simultaneous sampling of up to four analog input pins
- Automatic Channel Scan mode
- Selectable conversion trigger source
- Selectable Buffer Fill modes
- Operation during CPU Sleep and Idle modes

The 12-bit ADC configuration supports all the above features, except:

- In the 12-bit configuration, conversion speeds of up to 500 ksps are supported
- There is only one sample/hold amplifier in the 12-bit configuration, so simultaneous sampling of multiple channels is not supported.

Depending on the particular device pinout, the ADC can have up to 13 analog input pins, designated AN0 through AN12. In addition, there are two analog input pins for external voltage reference connections. These voltage reference inputs can be shared with other analog input pins. The actual number of analog input pins and external voltage reference input configuration depends on the specific device.

Block diagrams of the ADC module are shown in [Figure 20-1](#) and [Figure 20-2](#).

### 20.2 ADC Initialization

The following configuration steps should be performed.

1. Configure the ADC module:
  - a) Select port pins as analog inputs (AD1PCFGH<15:0> or AD1PCFGL<15:0>)
  - b) Select voltage reference source to match expected range on analog inputs (AD1CON2<15:13>)
  - c) Select the analog conversion clock to match desired data rate with processor clock (AD1CON3<7:0>)
  - d) Determine how many S/H channels are used (AD1CON2<9:8> and AD1PCFGH<15:0> or AD1PCFGL<15:0>)
  - e) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>)
  - f) Select how conversion results are presented in the buffer (AD1CON1<9:8>)
  - g) Turn on ADC module (AD1CON1<15>)
2. Configure ADC interrupt (if required):
  - a) Clear the AD1IF bit
  - b) Select ADC interrupt priority

### 20.3 ADC and DMA

If more than one conversion result needs to be buffered before triggering an interrupt, DMA data transfers can be used. ADC1 can trigger a DMA data transfer. If ADC1 is selected as the DMA IRQ source, a DMA transfer occurs when the AD1IF bit gets set as a result of an ADC1 sample conversion sequence.

The SMPI<3:0> bits (AD1CON2<5:2>) are used to select how often the DMA RAM buffer pointer is incremented.

The ADDMABM bit (AD1CON1<12>) determines how the conversion results are filled in the DMA RAM buffer area being used for ADC. If this bit is set, DMA buffers are written in the order of conversion. The module provides an address to the DMA channel that is the same as the address used for the non-DMA stand-alone buffer. If the ADDMABM bit is cleared, then DMA buffers are written in Scatter/Gather mode. The module provides a scatter/gather address to the DMA channel, based on the index of the analog input and the size of the DMA buffer.

**REGISTER 22-6: RTCVAL (WHEN RTCPTR<1:0> = 01): WKDYHR: WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>**

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY<2:0>		
bit 15					bit 8		

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN<1:0>		HRONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15-11                      **Unimplemented:** Read as '0'  
bit 10-8                      **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit; contains a value from 0 to 6  
bit 7-6                      **Unimplemented:** Read as '0'  
bit 5-4                      **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit; contains a value from 0 to 2  
bit 3-0                      **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit; contains a value from 0 to 9

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

**REGISTER 22-7: RTCVAL (WHEN RTCPTR<1:0> = 00): MINUTES AND SECONDS VALUE REGISTER**

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	MINTEN<2:0>			MINONE<3:0>			
bit 15							bit 8

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	SECTEN<2:0>			SECONE<3:0>			
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
-n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 15                      **Unimplemented:** Read as '0'  
bit 14-12                      **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit; contains a value from 0 to 5  
bit 11-8                      **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit; contains a value from 0 to 9  
bit 7                      **Unimplemented:** Read as '0'  
bit 6-4                      **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit; contains a value from 0 to 5  
bit 3-0                      **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit; contains a value from 0 to 9

## 23.0 PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

**Note 1:** This data sheet summarizes the features of the PIC24HJ32GP302/304, PIC24HJ64GPX02/X04 and PIC24HJ128GPX02/X04 families of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 36. “Programmable Cyclic Redundancy Check (CRC)”** (DS70298) of the “dsPIC33F/PIC24H Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The programmable CRC generator offers the following features:

- User-programmable polynomial CRC equation
- Interrupt output
- Data FIFO

## 23.1 Overview

The module implements a software configurable CRC generator. The terms of the polynomial and its length can be programmed using the CRCXOR bits ( $X<15:1>$ ) and the CRCCON bits ( $PLEN<3:0>$ ), respectively.

### EQUATION 23-1: CRC EQUATION

$$x^{16} + x^{12} + x^5 + 1$$

To program this polynomial into the CRC generator, the CRC register bits should be set as shown in **Table 23-1**.

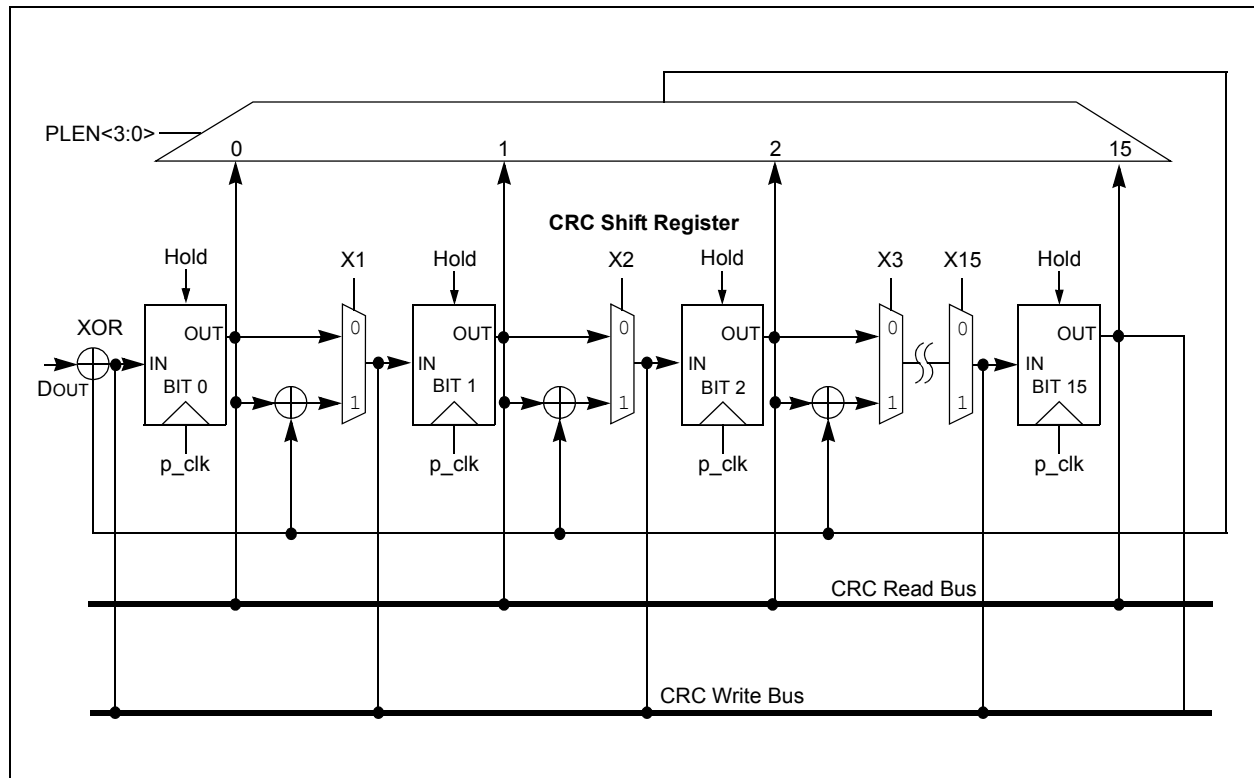
**TABLE 23-1: EXAMPLE CRC SETUP**

Bit Name	Bit Value
PLEN<3:0>	1111
X<15:1>	000100000010000

For the value of  $X<15:1>$ , the 12th bit and the 5th bit are set to ‘1’, as required by the CRC equation. The 0th bit required by the CRC equation is always XORed. For a 16-bit polynomial, the 16th bit is also always assumed to be XORed; therefore, the  $X<15:1>$  bits do not have the 0th bit or the 16th bit.

The topology of a standard CRC generator is shown in **Figure 23-2**.

**FIGURE 23-1: CRC SHIFTER DETAILS**



## 23.4 Programmable CRC Resources

Many useful resources related to Programmable CRC are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page, which can be accessed using this [link](http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en534555), contains the latest updates and additional information.

<p><b>Note:</b> In the event you are not able to access the product page using the link above, enter this URL in your browser: <a href="http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en534555">http://www.microchip.com/wwwproducts/Devices.aspx?dDocName=en534555</a></p>
--

### 23.4.1 KEY RESOURCES

- **Section 36. “Programmable Cyclic Redundancy Check CRC)”** (DS70298)
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All related dsPIC33F/PIC24H Family Reference Manuals Sections
- Development Tools

TABLE 26-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
69	ULNK	ULNK	Unlink Frame Pointer	1	1	None
70	XOR	XOR <i>f</i>	<i>f</i> = <i>f</i> .XOR. WREG	1	1	N,Z
		XOR <i>f</i> , WREG	WREG = <i>f</i> .XOR. WREG	1	1	N,Z
		XOR #lit10, <i>Wn</i>	<i>Wd</i> = lit10 .XOR. <i>Wd</i>	1	1	N,Z
		XOR <i>Wb</i> , <i>Ws</i> , <i>Wd</i>	<i>Wd</i> = <i>Wb</i> .XOR. <i>Ws</i>	1	1	N,Z
		XOR <i>Wb</i> , #lit5, <i>Wd</i>	<i>Wd</i> = <i>Wb</i> .XOR. lit5	1	1	N,Z
71	ZE	ZE <i>Ws</i> , <i>Wnd</i>	<i>Wnd</i> = Zero-extend <i>Ws</i>	1	1	C,Z,N

TABLE 28-10: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Conditions
DO10	VOL	<b>Output Low Voltage</b> I/O Pins: 2x Sink Driver Pins - RA2, RA7- RA10, RB10, RB11, RB7, RB4, RC3-RC9	—	—	0.4	V	IO <sub>L</sub> ≤ 3 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output Low Voltage</b> I/O Pins: 4x Sink Driver Pins - RA0, RA1, RB0-RB3, RB5, RB6, RB8, RB9, RB12-RB15, RC0-RC2	—	—	0.4	V	IO <sub>L</sub> ≤ 6 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output Low Voltage</b> I/O Pins: 8x Sink Driver Pins - RA3, RA4	—	—	0.4	V	IO <sub>L</sub> ≤ 10 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
DO20	VOH	<b>Output High Voltage</b> I/O Pins: 2x Source Driver Pins - RA2, RA7-RA10, RB4, RB7, RB10, RB11, RC3-RC9	2.4	—	—	V	IO <sub>H</sub> ≥ -3 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output High Voltage</b> I/O Pins: 4x Source Driver Pins - RA0, RA1, RB0-RB3, RB5, RB6, RB8, RB9, RB12-RB15, RC0-RC2	2.4	—	—	V	IO <sub>H</sub> ≥ -6 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output High Voltage</b> I/O Pins: 8x Source Driver Pins - RA4, RA3	2.4	—	—	V	IO <sub>H</sub> ≥ -10 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
DO20A	VOH1	<b>Output High Voltage</b> I/O Pins: 2x Source Driver Pins - RA2, RA7-RA10, RB4, RB7, RB10, RB11, RC3-RC9	1.5	—	—	V	IO <sub>H</sub> ≥ -6 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			2.0	—	—		IO <sub>H</sub> ≥ -5 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			3.0	—	—		IO <sub>H</sub> ≥ -2 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output High Voltage</b> 4x Source Driver Pins - RA0, RA1, RB0-RB3, RB5, RB6, RB8, RB9, RB12-RB15, RC0-RC2	1.5	—	—	V	IO <sub>H</sub> ≥ -12 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			2.0	—	—		IO <sub>H</sub> ≥ -11 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			3.0	—	—		IO <sub>H</sub> ≥ -3 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
		<b>Output High Voltage</b> I/O Pins: 8x Source Driver Pins - RA3, RA4	1.5	—	—	V	IO <sub>H</sub> ≥ -16 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			2.0	—	—		IO <sub>H</sub> ≥ -12 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>
			3.0	—	—		IO <sub>H</sub> ≥ -4 mA, V <sub>DD</sub> = 3.3V See <b>Note 1</b>

**Note 1:** Parameters are characterized, but not tested.



TABLE 28-11: ELECTRICAL CHARACTERISTICS: BOR

DC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Symbol	Characteristic	Min <sup>(1)</sup>	Typ	Max <sup>(1)</sup>	Units	Conditions
BO10	VBOR	BOR Event on VDD transition high-to-low	2.40	—	2.55	V	VDD

**Note 1:** Parameters are for design guidance only and are not tested in manufacturing.

TABLE 28-12: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
		<b>Program Flash Memory</b>					
D130a	EP	Cell Endurance	10,000	—	—	E/W	-40°C to +125°C
D131	VPR	VDD for Read	V <sub>MIN</sub>	—	3.6	V	V <sub>MIN</sub> = Minimum operating voltage
D132B	VPEW	VDD for Self-Timed Write	V <sub>MIN</sub>	—	3.6	V	V <sub>MIN</sub> = Minimum operating voltage
D134	TRETD	Characteristic Retention	20	—	—	Year	Provided no other specifications are violated
D135	IDDP	Supply Current during Programming	—	10	—	mA	—
D136a	TRW	Row Write Time	1.32	—	1.74	ms	TRW = 11064 FRC cycles, TA = +85°C, See <b>Note 2</b>
D136b	TRW	Row Write Time	1.28	—	1.79	ms	TRW = 11064 FRC cycles, TA = +125°C, See <b>Note 2</b>
D137a	TPE	Page Erase Time	20.1	—	26.5	ms	TPE = 168517 FRC cycles, TA = +85°C, See <b>Note 2</b>
D137b	TPE	Page Erase Time	19.5	—	27.3	ms	TPE = 168517 FRC cycles, TA = +125°C, See <b>Note 2</b>
D138a	TWW	Word Write Cycle Time	42.3	—	55.9	μs	TWW = 355 FRC cycles, TA = +85°C, See <b>Note 2</b>
D138b	TWW	Word Write Cycle Time	41.1	—	57.6	μs	TWW = 355 FRC cycles, TA = +125°C, See <b>Note 2</b>

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

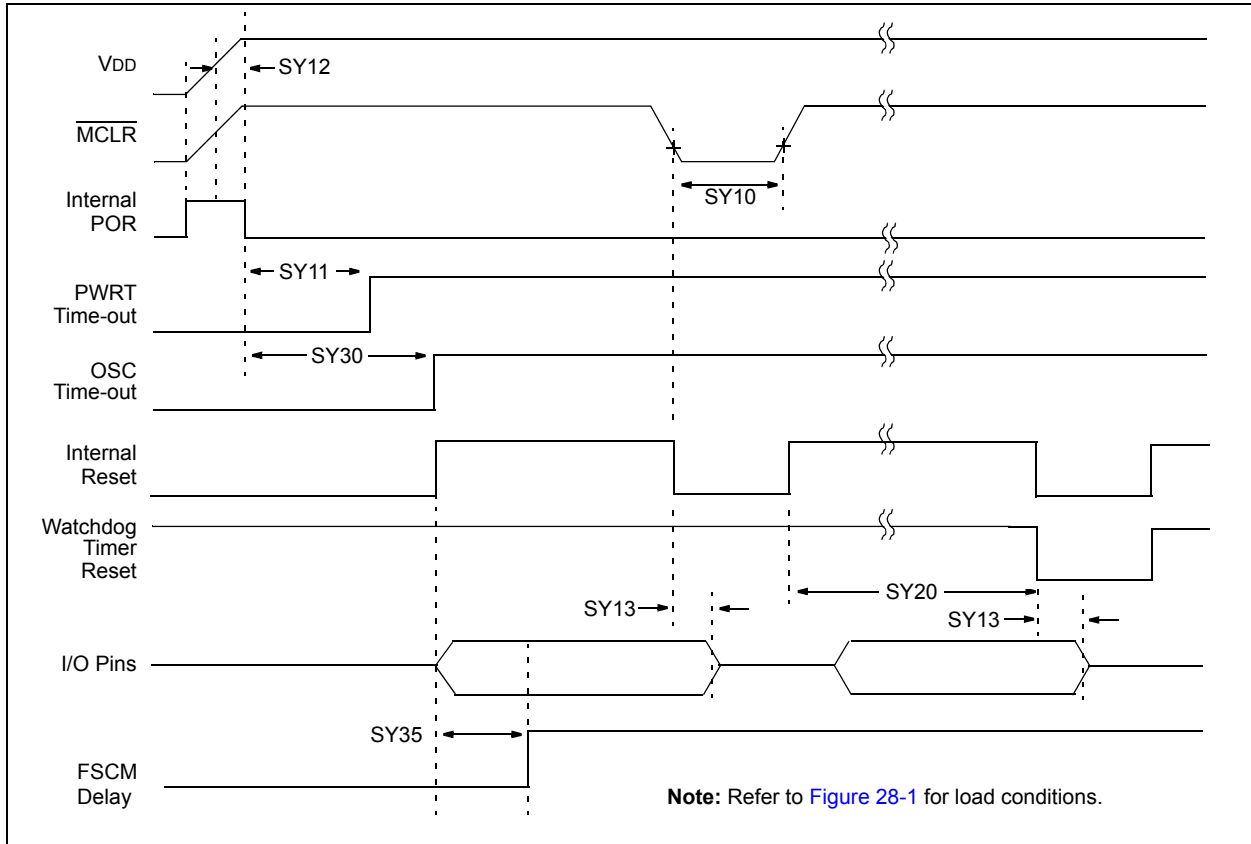
- 2:** Other conditions: FRC = 7.37 MHz, TUN<5:0> = b'011111 (for Min), TUN<5:0> = b'100000 (for Max). This parameter depends on the FRC accuracy (see [Table 28-19](#)) and the value of the FRC Oscillator Tuning register (see [Register 9-4](#)). For complete details on calculating the Minimum and Maximum time see [Section 5.3 “Programming Operations”](#).

TABLE 28-13: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS

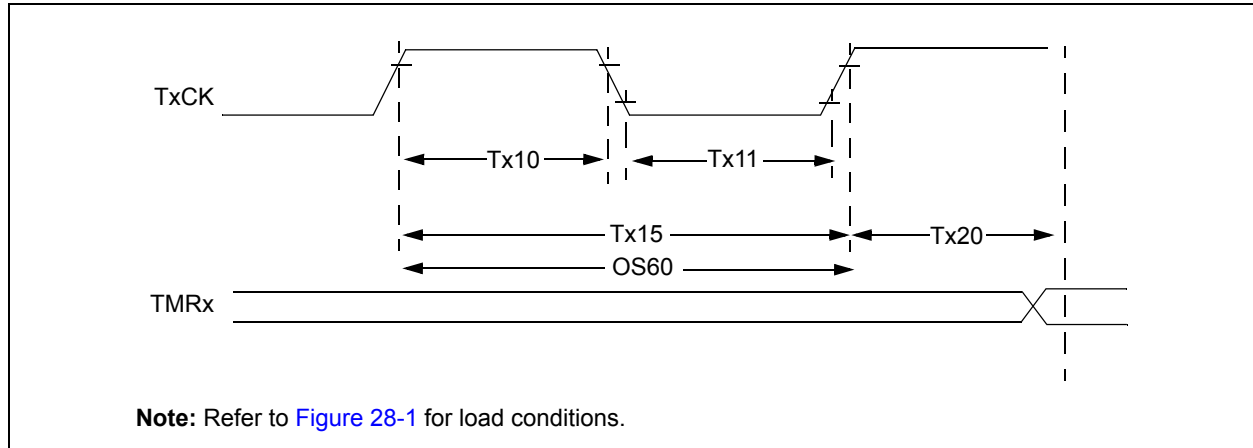
Standard Operating Conditions (unless otherwise stated): Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended							
Param No.	Symbol	Characteristics	Min	Typ	Max	Units	Comments
—	CEFC	External Filter Capacitor Value <sup>(1)</sup>	4.7	10	—	μF	Capacitor must be low series resistance (< 5 Ohms)

**Note 1:** Typical VCAP voltage = 2.5V when VDD ≥ VDDMIN.

**FIGURE 28-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS**



**FIGURE 28-5: TIMER1, 2, 3 AND 4 EXTERNAL CLOCK TIMING CHARACTERISTICS**



**TABLE 28-22: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS<sup>(1)</sup>**

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic		Min	Typ	Max	Units	Conditions
TA10	TtXH	TxCK High Time	Synchronous, no prescaler	T <sub>CY</sub> + 20	—	—	ns	Must also meet parameter TA15. N = prescale value (1, 8, 64, 256)
			Synchronous, with prescaler	(T <sub>CY</sub> + 20)/N	—	—	ns	
			Asynchronous	20	—	—	ns	
TA11	TtXL	TxCK Low Time	Synchronous, no prescaler	(T <sub>CY</sub> + 20)	—	—	ns	Must also meet parameter TA15. N = prescale value (1, 8, 64, 256)
			Synchronous, with prescaler	(T <sub>CY</sub> + 20)/N	—	—	ns	
			Asynchronous	20	—	—	ns	
TA15	TtXP	TxCK Input Period	Synchronous, no prescaler	2 T <sub>CY</sub> + 40	—	—	ns	—
			Synchronous, with prescaler	Greater of: 40 ns or (2 T <sub>CY</sub> + 40)/N	—	—	—	N = prescale value (1, 8, 64, 256)
			Asynchronous	40	—	—	ns	—
OS60	Ft1	SOSCI/T1CK Oscillator Input frequency Range (oscillator enabled by setting bit TCS (T1CON<1>))		DC	—	50	kHz	—
TA20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 T <sub>CY</sub> + 40	—	1.75 T <sub>CY</sub> + 40	—	—

**Note 1:** Timer1 is a Type A.

**TABLE 28-23: TIMER2 AND TIMER 4 EXTERNAL CLOCK TIMING REQUIREMENTS**

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TB10	TtxH	TxCK High Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB11	TtxL	TxCK Low Time	Synchronous mode	Greater of: 20 or (Tcy + 20)/N	—	—	ns	Must also meet parameter TB15 N = prescale value (1, 8, 64, 256)
TB15	TtxP	TxCK Input Period	Synchronous mode	Greater of: 40 or (2 Tcy + 40)/N	—	—	ns	N = prescale value (1, 8, 64, 256)
TB20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 Tcy + 40	—	1.75 Tcy + 40	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 28-24: TIMER3 AND TIMER5 EXTERNAL CLOCK TIMING REQUIREMENTS**

AC CHARACTERISTICS				Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤TA ≤+85°C for Industrial -40°C ≤TA ≤+125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Typ	Max	Units	Conditions
TC10	TtxH	TxCK High Time	Synchronous	Tcy + 20	—	—	ns	Must also meet parameter TC15
TC11	TtxL	TxCK Low Time	Synchronous	Tcy + 20	—	—	ns	Must also meet parameter TC15
TC15	TtxP	TxCK Input Period	Synchronous, with prescaler	2 Tcy + 40	—	—	ns	N = prescale value (1, 8, 64, 256)
TC20	TCKEXTMRL	Delay from External TxCK Clock Edge to Timer Increment		0.75 Tcy + 40	—	1.75 Tcy + 40	ns	

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

FIGURE 28-8: OC/PWM MODULE TIMING CHARACTERISTICS

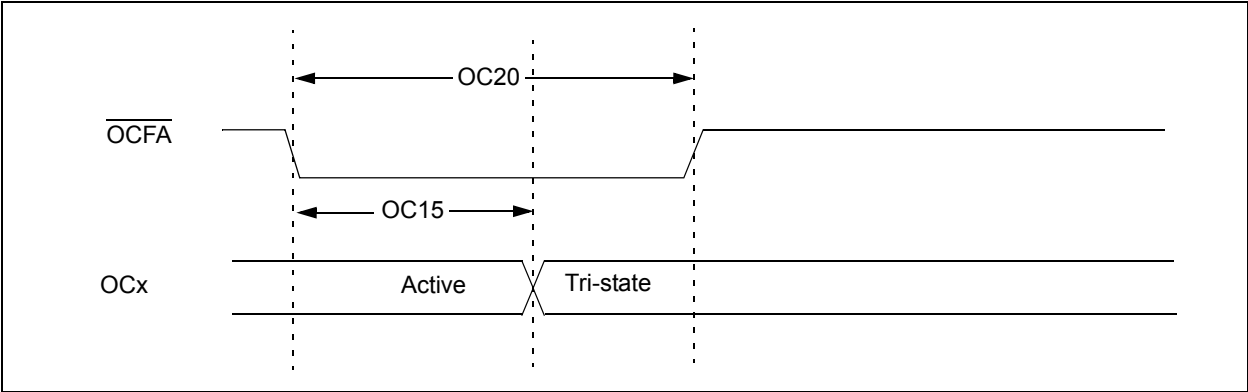


TABLE 28-27: SIMPLE OC/PWM MODE TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Typ	Max	Units	Conditions
OC15	TFD	Fault Input to PWM I/O Change	—	—	Tcy + 20	ns	—
OC20	TFLT	Fault Input Pulse Width	Tcy + 20	—	—	ns	—

**Note 1:** These parameters are characterized but not tested in manufacturing.