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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	64MHz
Connectivity	I ² C, MMC, SPI, SSC, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, I2S, POR, PWM, WDT
Number of I/O	34
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.6V
Data Converters	A/D 8x10/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsam3s2aa-mur



1. SAM3S Description

Atmel's SAM3S series is a member of a family of Flash microcontrollers based on the high performance 32-bit ARM Cortex-M3 RISC processor. It operates at a maximum speed of 64 MHz and features up to 256 Kbytes of Flash and up to 48 Kbytes of SRAM. The peripheral set includes a Full Speed USB Device port with embedded transceiver, a High Speed MCI for SDIO/SD/MMC, an External Bus Interface featuring a Static Memory Controller providing connection to SRAM, PSRAM, NOR Flash, LCD Module and NAND Flash, 2x USARTs, 2x UARTs, 2x TWIs, 3x SPI, an I2S, as well as 1 PWM timer, 6x general-purpose 16-bit timers, an RTC, an ADC, a 12-bit DAC and an analog comparator.

The SAM3S series is ready for capacitive touch thanks to the QTouch library, offering an easy way to implement buttons, wheels and sliders

The SAM3S device is a medium range general purpose microcontroller with the best ratio in terms of reduced power consumption, processing power and peripheral set. This enables the SAM3S to sustain a wide range of applications including consumer, industrial control, and PC peripherals.

It operates from 1.62V to 3.6V and is available in 48-, 64- and 100-pin QFP, 48- and 64-pin QFN, and 100-pin BGA packages.

The SAM3S series is the ideal migration path from the SAM7S series for applications that require more performance. The SAM3S series is pin-to-pin compatible with the SAM7Sseries.

1.1 Configuration Summary

The SAM3S series devices differ in memory size, package and features list. Table 1-1 below summarizes the configurations of the device family

Table 1-1. Configuration Summary

Device	Flash	SRAM	Timer Counter Channels	GPIOs	UART/ USARTs	ADC	12-bit DAC Output	External Bus Interface	нѕмсі	Package
SAM3S4C	256 Kbytes single plane	48 Kbytes	6	79	2/2 ⁽¹⁾	16 ch.	2	8-bit data, 4 chip selects, 24-bit address	1 port 4 bits	LQFP100 BGA100
SAM3S4B	256 Kbytes single plane	48 Kbytes	3	47	2/2	10 ch.	2	-	1 port 4 bits	LQFP64 QFN 64
SAM3S4A	256 Kbytes single plane	48 Kbytes	3	34	2/1	8 ch.	-	-	-	LQFP48 QFN 48
SAM3S2C	128 Kbytes single plane	32 Kbytes	6	79	2/2 ⁽¹⁾	16 ch.	2	8-bit data, 4 chip selects, 24-bit address	1 port 4 bits	LQFP100 BGA100
SAM3S2B	128 Kbytes single plane	32 Kbytes	3	47	2/2	10 ch.	2	-	1 port 4 bits	LQFP64 QFN 64
SAM3S2A	128 Kbytes single plane	32 Kbytes	3	34	2/1	8 ch.	-	-	-	LQFP48 QFN 48
SAM3S1C	64 Kbytes single plane	16 Kbytes	6	79	2/2 ⁽¹⁾	16 ch.	2	8-bit data, 4 chip selects, 24-bit address	1 port 4 bits	LQFP100 BGA100
SAM3S1B	64 Kbytes single plane	16 Kbytes	3	47	2/2	10 ch.	2	-	1 port 4 bits	LQFP64 QFN 64
SAM3S1A	64 Kbytes single plane	16 Kbytes	3	34	2/1	8 ch.	-	-	-	LQFP48 QFN 48

Note: 1. Full Modem support on USART1.

 Table 3-1.
 Signal Description List (Continued)

Signal Name	Function	Туре	Active Level	Voltage reference	Comments
	Universal Asynchronous	Receiver Trans	smitter - U	ARTx	
URXDx	UART Receive Data	Input			
UTXDx	UART Transmit Data	Output			
	PIO Controller -	PIOA - PIOB -	PIOC		
PA0 - PA31	Parallel IO Controller A	I/O			Reset State:
PB0 - PB14	Parallel IO Controller B	I/O		VDDIO - PIO or System IOs ⁽²	
PC0 - PC31	Parallel IO Controller C	I/O			 Internal pull-up enabled Schmitt Trigger enabled⁽¹⁾
	PIO Controller - Paralle	I Capture Mode	e (PIOA Oi	nly)	
PIODC0-PIODC7	Parallel Capture Mode Data	Input			
PIODCCLK	Parallel Capture Mode Clock	Input		VDDIO	
PIODCEN1-2	Parallel Capture Mode Enable	Input			
	External	Bus Interface			
D0 - D7	Data Bus	I/O			
A0 - A23	Address Bus	Output			
NWAIT	External Wait Signal	Input	Low		
	Static Memor	y Controller - S	МС		
NCS0 - NCS3	Chip Select Lines	Output	Low		
NRD	Read Signal	Output	Low		
NWE	Write Enable	Output	Low		
	NAND	Flash Logic			
NANDOE	NAND Flash Output Enable	Output	Low		
NANDWE	NAND Flash Write Enable	Output	Low		
	High Speed Multimed	lia Card Interfa	ce - HSMC	CI	
MCCK	Multimedia Card Clock	I/O			
MCCDA	Multimedia Card Slot A Command	I/O			
MCDA0 - MCDA3	Multimedia Card Slot A Data	I/O			
	Universal Synchronous Asynchi	onous Receive	er Transmi	tter USARTx	(
SCKx	USARTx Serial Clock	I/O			
TXDx	USARTx Transmit Data	I/O			
RXDx	USARTx Receive Data	Input			
RTSx	USARTx Request To Send	Output			
CTSx	USARTx Clear To Send	Input			
DTR1	USART1 Data Terminal Ready	I/O			
DSR1	USART1 Data Set Ready	Input			
DCD1	USART1 Data Carrier Detect	Input			
RI1	USART1 Ring Indicator	Input			



Table 3-1. Signal Description List (Continued)

Signal Name	Function	Туре	Active Level	Voltage reference	Comments		
	Fast Flash Programming Interface - FFPI						
PGMEN0-PGMEN2	Programming Enabling	Input		VDDIO			
PGMM0-PGMM3	Programming Mode	Input					
PGMD0-PGMD15	Programming Data	I/O					
PGMRDY	Programming Ready	Output	High				
PGMNVALID	Data Direction	Output	Low	VDDIO			
PGMNOE	Programming Read	Input	Low				
PGMCK	Programming Clock	Input					
PGMNCMD	Programming Command	Input	Low				
USB Full Speed Device							
DDM	USB Full Speed Data -	Analog			Reset State:		
DDP	USB Full Speed Data +	Analog, Digital		VDDIO	- USB Mode - Internal Pull-down ⁽³⁾		

- Notes: 1. Schmitt Triggers can be disabled through PIO registers.
 - 2. Some PIO lines are shared with System IOs.
 - 3. Refer to the USB sub section in the product Electrical Characteristics Section for Pull-down value in USB Mode.
 - 4. See Section 5.3 "Typical Powering Schematics" for restriction on voltage range of Analog Cells.



4.1.3 100-Lead LQFP Pinout

Table 4-1. 100-lead LQFP SAM3S4/2/1C Pinout

1	ADVREF
2	GND
3	PB0/AD4
4	PC29/AD13
5	PB1/AD5
6	PC30/AD14
7	PB2/AD6
8	PC31
9	PB3/AD7
10	VDDIN
11	VDDOUT
12	PA17/PGMD5/AD0
13	PC26
14	PA18/PGMD6/AD1
15	PA21/PGMD9/AD8
16	VDDCORE
17	PC27
18	PA19/PGMD7/AD2
19	PC15/AD11
20	PA22/PGMD10/AD9
21	PC13/AD10
22	PA23/PGMD1
23	PC12/AD12
24	PA20/PGMD8/AD3
25	PC0
	·

37 111100	.,_,		
26	GND		
27	VDDIO		
28	PA16/PGMD4		
29	PC7		
30	PA15/PGMD3		
31	PA14/PGMD2		
32	PC6		
33	PA13/PGMD1		
34	PA24/PGMD12		
35	PC5		
36	VDDCORE		
37	PC4		
38	PA25/PGMD13		
39	PA26/PGMD14		
40	PC3		
41	PA12/PGMD0		
42	PA11/PGMM3		
43	PC2		
44	PA10/PGMM2		
45	GND		
46	PA9/PGMM1		
47	PC1		
48	PA8/XOUT32/ PGMM0		
49	PA7/XIN32/ PGMNVALID		
50	VDDIO		
50	VDDIO		

51	TDI/PB4
52	PA6/PGMNOE
53	PA5/PGMRDY
54	PC28
55	PA4/PGMNCMD
56	VDDCORE
57	PA27/PGMD15
58	PC8
59	PA28
60	NRST
61	TST
62	PC9
63	PA29
64	PA30
65	PC10
66	PA3
67	PA2/PGMEN2
68	PC11
69	VDDIO
70	GND
71	PC14
72	PA1/PGMEN1
73	PC16
74	PA0/PGMEN0
75	PC17

76	TDO/TRACESWO/PB 5		
77	JTAGSEL		
78	PC18		
79	TMS/SWDIO/PB6		
80	PC19		
81	PA31		
82	PC20		
83	TCK/SWCLK/PB7		
84	PC21		
85	VDDCORE		
86	PC22		
87	ERASE/PB12		
88	DDM/PB10		
89	DDP/PB11		
90	PC23		
91	VDDIO		
92	PC24		
93	PB13/DAC0		
94	PC25		
95	GND		
96	PB8/XOUT		
97	PB9/PGMCK/XIN		
98	VDDIO		
99	PB14/DAC1		
100	VDDPLL		





4.1.4 100-ball LFBGA Pinout

Table 4-2. 100-ball LFBGA SAM3S4/2/1C Pinout

A1	PB1/AD5
A2	PC29
А3	VDDIO
A4	PB9/PGMCK/XIN
A 5	PB8/XOUT
A6	PB13/DAC0
A7	DDP/PB11
A8	DDM/PB10
A9	TMS/SWDIO/PB6
A10	JTAGSEL
B1	PC30
B2	ADVREF
В3	GNDANA
B4	PB14/DAC1
B5	PC21
В6	PC20
В7	PA31
В8	PC19
В9	PC18
B10	TDO/TRACESWO/ PB5
C1	PB2/AD6
C2	VDDPLL
C3	PC25
C4	PC23
C5	ERASE/PB12

C6	TCK/SWCLK/PB7		
C7	PC16		
C8	PA1/PGMEN1		
C9	PC17		
C10	PA0/PGMEN0		
D1	PB3/AD7		
D2	PB0/AD4		
D3	PC24		
D4	PC22		
D5	GND		
D6	GND		
D7	VDDCORE		
D8	PA2/PGMEN2		
D9	PC11		
D10	PC14		
E1	PA17/PGMD5/AD0		
E2	PC31		
E3	VDDIN		
E4	GND		
E5	GND		
E6	NRST		
E7	PA29/AD13		
E8	PA30/AD14		
E9	PC10		
E10	PA3		

F1	PA18/PGMD6/AD1
F2	PC26
F3	VDDOUT
F4	GND
F5	VDDIO
F6	PA27/PGMD15
F7	PC8
F8	PA28
F9	TST
F10	PC9
G1	PA21/PGMD9/AD8
G2	PC27
G3	PA15/PGMD3
G4	VDDCORE
G5	VDDCORE
G6	PA26/PGMD14
G7	PA12/PGMD0
G8	PC28
G9	PA4/PGMNCMD
G10	PA5/PGMRDY
H1	PA19/PGMD7/AD2
H2	PA23/PGMD11
НЗ	PC7
H4	PA14/PGMD2
H5	PA13/PGMD1

H6	PC4
H7	PA11/PGMM3
Н8	PC1
H9	PA6/PGMNOE
H10	TDI/PB4
J1	PC15/AD11
J2	PC0
J3	PA16/PGMD4
J4	PC6
J5	PA24/PGMD12
J6	PA25/PGMD13
J7	PA10/PGMM2
J8	GND
J9	VDDCORE
J10	VDDIO
K1	PA22/PGMD10/AD9
K2	PC13/AD10
КЗ	PC12/AD12
K4	PA20/PGMD8/AD3
K5	PC5
K6	PC3
K7	PC2
K8	PA9/PGMM1
K9	PA8/XOUT32/PGMM0
K10	PA7/XIN32/ PGMNVALID



4.2.1 64-Lead LQFP and QFN Pinout

64-pin version SAM3S devices are pin-to-pin compatible with AT91SAM7S legacy products. Furthermore, SAM3S products have new functionalities shown in italic in Table 4-3.

Table 4-3. 64-pin SAM3S4/2/1B Pinout

1	ADVREF	17	GND	33	TDI/PB4	49	TDO/TRACESWO/PB5
2	GND	18	VDDIO	34	PA6/PGMNOE	50	JTAGSEL
3	PB0/AD4	19	PA16/PGMD4	35	PA5/PGMRDY	51	TMS/SWDIO/PB6
4	PB1/AD5	20	PA15/PGMD3	36	PA4/PGMNCMD	52	PA31
5	PB2/AD6	21	PA14/PGMD2	37	PA27/PGMD15	53	TCK/SWCLK/PB7
6	PB3/AD7	22	PA13/PGMD1	38	PA28	54	VDDCORE
7	VDDIN	23	PA24/PGMD12	39	NRST	55	ERASE/PB12
8	VDDOUT	24	VDDCORE	40	TST	56	DDM/PB10
9	PA17/PGMD5/ AD <i>0</i>	25	PA25/PGMD13	41	PA29	57	DDP/PB11
10	PA18/PGMD6/ AD1	26	PA26/PGMD14	42	PA30	58	VDDIO
11	PA21/PGMD9/ AD8	27	PA12/PGMD0	43	PA3	59	PB13/DAC0
12	VDDCORE	28	PA11/PGMM3	44	PA2/PGMEN2	60	GND
13	PA19/PGMD7/ AD2	29	PA10/PGMM2	45	VDDIO	61	XOUT/PB8
14	PA22/PGMD10/ AD9	30	PA9/PGMM1	46	GND	62	XIN/PGMCK/PB9
15	PA23/PGMD11	31	PA8/ <i>XOUT32/</i> PGMM0	47	PA1/PGMEN1	63	PB14/DAC1
16	PA20/PGMD8/ AD3	32	PA7/ <i>XIN32/</i> PGMNVALID	48	PA0/PGMEN0	64	VDDPLL
Motor	T		and must be sennested to				

Note: The bottom pad of the QFN package must be connected to ground.



4.3.1 48-Lead LQFP and QFN Pinout

Table 4-4. 48-pin SAM3S4/2/1A Pinout

Iable	4-4. 40-pin 5Ai	1004/2/	•
1	ADVREF	1	3
2	GND	1	4
3	PB0/AD4	1	5
4	PB1/AD5	1	6
5	PB2/AD6	1	7
6	PB3/AD7	1	8
7	VDDIN	1	9
8	VDDOUT	2	20
9	PA17/PGMD5/ AD0	2	21
10	PA18/PGMD6/ AD1	2	22
11	PA19/PGMD7/ AD2	2	23
12	PA20/AD3	2	24

13	VDDIO			
14	PA16/PGMD4			
15	PA15/PGMD3			
16	PA14/PGMD2			
17	PA13/PGMD1			
18	VDDCORE			
19	PA12/PGMD0			
20	PA11/PGMM3			
21	PA10/PGMM2			
22	PA9/PGMM1			
23	PA8/XOUT32/			
	PGMM0			
24	PA7/XIN32/			
24	PGMNVALID			

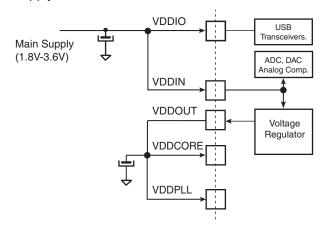
25	TDI/PB4	
26	PA6/PGMNOE	
27	PA5/PGMRDY	
28	PA4/PGMNCMD	
29	NRST	
30	TST	
31	PA3	
32	PA2/PGMEN2	
33	VDDIO	
34	GND	
35	PA1/PGMEN1	
36 PA0/PGMEN0		

37	TDO/TRACESWO/ PB5
38	JTAGSEL
39	TMS/SWDIO/PB6
40	TCK/SWCLK/PB7
41	VDDCORE
42	ERASE/PB12
43	DDM/PB10
44	DDP/PB11
45	XOUT/PB8
46	XIN/PB9/PGMCK
47	VDDIO
48	VDDPLL

Note: The bottom pad of the QFN package must be connected to ground.



Figure 5-1. Single Supply

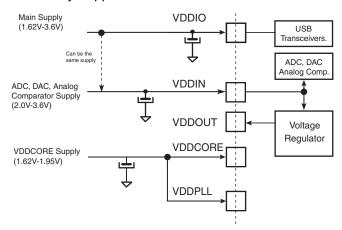


Note: Restrictions

With Main Supply < 2.0 V, USB and ADC/DAC and Analog comparator are not usable.

With Main Supply \geq 2.0V and < 3V, USB is not usable. With Main Supply \geq 3V, all peripherals are usable.

Figure 5-2. Core Externally Supplied



Note: Restrictions

With Main Supply < 2.0V, USB is not usable.

With VDDIN < 2.0V, ADC/DAC and Analog comparator are not usable.

With Main Supply \geq 2.0V and < 3V, USB is not usable.

With Main Supply and VDDIN ≥ 3V, all peripherals are usable.

Figure 5-3 below provides an example of the powering scheme when using a backup battery. Since the PIO state is preserved when in backup mode, any free PIO line can be used to switch off the external regulator by driving the PIO line at low level (PIO is input, pull-up enabled after backup reset). External wake-up of the system can be from a push button or any signal. See Section 5.6 "Wake-up Sources" for further details.

5.7 Fast Startup

The device allows the processor to restart in a few microseconds while the processor is in wait mode. A fast start up can occur upon detection of a low level on one of the 19 wake-up inputs (WKUP0 to 15 + SM + RTC + RTT).

The fast restart circuitry, as shown in Figure 5-5, is fully asynchronous and provides a fast start-up signal to the Power Management Controller. As soon as the fast start-up signal is asserted, the PMC automatically restarts the embedded 4/8/12 MHz fast RC oscillator, switches the master clock on this 4MHz clock and reenables the processor clock.

Figure 5-5. Fast Start-Up Circuitry

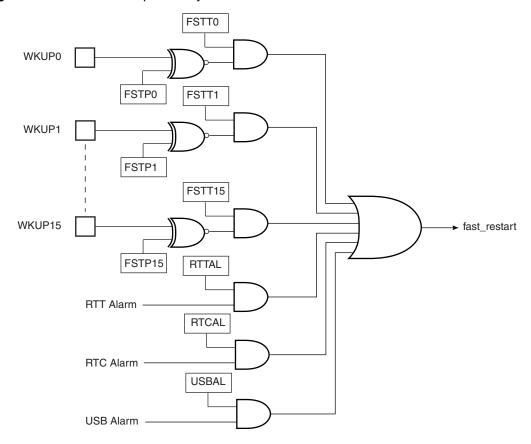




Table 6-1. System I/O Configuration Pin List.

SYSTEM_IO bit number	Default function after reset	Other function	Constraints for normal start	Configuration
12	ERASE	PB12	Low Level at startup ⁽¹⁾	
10	DDM	PB10	-	
11	DDP	PB11	-	In Matrix User Interface Registers
7	TCK/SWCLK	PB7	-	(Refer to the SystemIO Configuration Register in the Bus Matrix section of
6	TMS/SWDIO	PB6	-	the product datasheet.)
5	TDO/TRACESWO	PB5	-	
4	TDI	PB4	-	
-	PA7	XIN32	-	See footnote (2) below
-	PA8	XOUT32	-	See loothote - below
-	PB9	XIN	-	0 - 1 - 1 - 1 - (3) - 1 - 1
-	PB8	XOUT	-	See footnote ⁽³⁾ below

- Notes: 1. If PB12 is used as PIO input in user applications, a low level must be ensured at startup to prevent Flash erase before the user application sets PB12 into PIO mode,
 - 2. In the product Datasheet Refer to: Slow Clock Generator of the Supply Controller section.
 - 3. In the product Datasheet Refer to: 3 to 20 MHZ Crystal Oscillator information in PMC section.

6.2.1 Serial Wire JTAG Debug Port (SWJ-DP) Pins

The SWJ-DP pins are TCK/SWCLK, TMS/SWDIO, TDO/SWO, TDI and commonly provided on a standard 20-pin JTAG connector defined by ARM. For more details about voltage reference and reset state, refer to Table 3-1 on page 6.

At startup, SWJ-DP pins are configured in SWJ-DP mode to allow connection with debugging probe. Please refer to the Debug and Test Section of the product datasheet.

SWJ-DP pins can be used as standard I/Os to provide users more general input/output pins when the debug port is not needed in the end application. Mode selection between SWJ-DP mode (System IO mode) and general IO mode is performed through the AHB Matrix Special Function Registers (MATRIX SFR). Configuration of the pad for pull-up, triggers, debouncing and glitch filters is possible regardless of the mode.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level. It integrates a permanent pull-down resistor of about 15 $k\Omega$ to GND, so that it can be left unconnected for normal operations.

By default, the JTAG Debug Port is active. If the debugger host wants to switch to the Serial Wire Debug Port, it must provide a dedicated JTAG sequence on TMS/SWDIO and TCK/SWCLK which disables the JTAG-DP and enables the SW-DP. When the Serial Wire Debug Port is active, TDO/TRACESWO can be used for trace.

The asynchronous TRACE output (TRACESWO) is multiplexed with TDO. So the asynchronous trace can only be used with SW-DP, not JTAG-DP. For more information about SW-DP and JTAG-DP switching, please refer to the Debug and Test Section.



7. Processor and Architecture

7.1 ARM Cortex-M3 Processor

- Version 2.0
- Thumb-2 (ISA) subset consisting of all base Thumb-2 instructions, 16-bit and 32-bit
- · Harvard processor architecture enabling simultaneous instruction fetch with data load/store
- Three-stage pipeline
- Single cycle 32-bit multiply
- · Hardware divide
- Thumb and Debug states
- · Handler and Thread modes
- · Low latency ISR entry and exit

7.2 APB/AHB bridge

The SAM3S product embeds one peripheral bridge:

The peripherals of the bridge are clocked by MCK.

7.3 Matrix Masters

The Bus Matrix of the SAM3S product manages 4 masters, which means that each master can perform an access concurrently with others, to an available slave.

Each master has its own decoder, which is defined specifically for each master. In order to simplify the addressing, all the masters have the same decodings.

Table 7-1. List of Bus Matrix Masters

Master 0	Cortex-M3 Instruction/Data
Master 1	Cortex-M3 System
Master 2	Peripheral DMA Controller (PDC)
Master 3	CRC Calculation Unit

7.4 Matrix Slaves

The Bus Matrix of the SAM3S product manages 5 slaves. Each slave has its own arbiter, allowing a different arbitration per slave.

Table 7-2. List of Bus Matrix Slaves

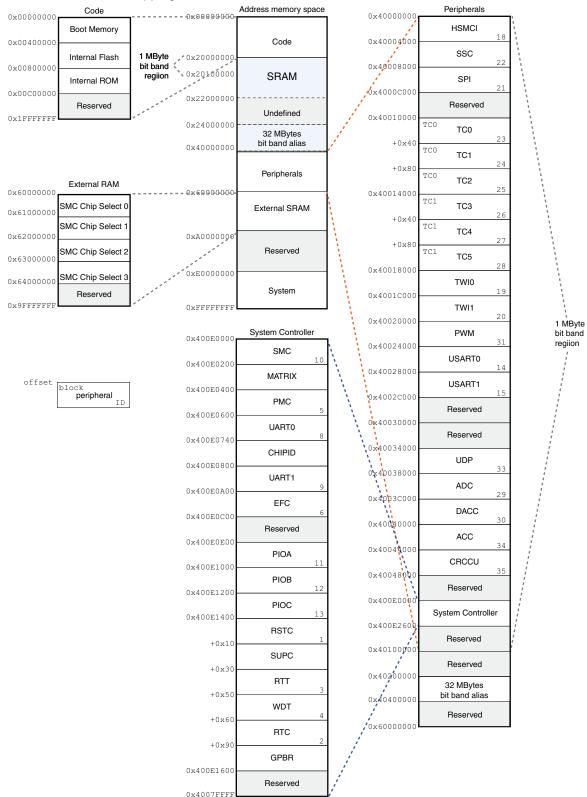
Slave 0	Internal SRAM
Slave 1	Internal ROM
Slave 2	Internal Flash
Slave 3	External Bus Interface
Slave 4	Peripheral Bridge





8. Product Mapping

Figure 8-1. SAM3S Product Mapping

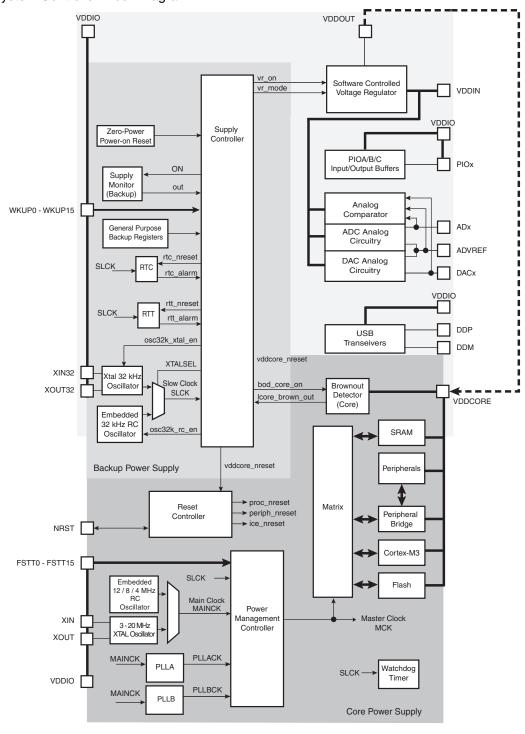


10. System Controller

The System Controller is a set of peripherals, which allow handling of key elements of the system, such as power, resets, clocks, time, interrupts, watchdog, etc...

See the system controller block diagram in Figure 10-1 on page 35.

Figure 10-1. System Controller Block Diagram



FSTT0 - FSTT15 are possible Fast Startup Sources, generated by WKUP0-WKUP15 Pins, but are not physical pins.



10.14 UART

- Two-pin UART
 - Implemented features are 100% compatible with the standard Atmel USART
 - Independent receiver and transmitter with a common programmable Baud Rate Generator
 - Even, Odd, Mark or Space Parity Generation
 - Parity, Framing and Overrun Error Detection
 - Automatic Echo, Local Loopback and Remote Loopback Channel Modes
 - Support for two PDC channels with connection to receiver and transmitter

10.15 PIO Controllers

- 3 PIO Controllers, PIOA, PIOB and PIOC (100-pin version only) controlling a maximum of 79 I/O Lines
- Fully programmable through Set/Clear Registers

Table 10-2. PIO available according to pin count

Version	48 pin	64 pin	100 pin	
PIOA	21	32	32	
PIOB	13	15	15	
PIOC	-	-	32	

- Multiplexing of four peripheral functions per I/O Line
- For each I/O Line (whether assigned to a peripheral or used as general purpose I/O)
 - Input change, rising edge, falling edge, low level and level interrupt
 - Debouncing and Glitch filter
 - Multi-drive option enables driving in open drain
 - Programmable pull-up or pull-down on each I/O line
 - Pin data status register, supplies visibility of the level on the pin at any time
- Synchronous output, provides Set and Clear of several I/O lines in a single write





11.2.3 PIO Controller C Multiplexing

Table 11-4. Multiplexing on PIO Controller C (PIOC)

I/O Line	Peripheral A	Peripheral B	Peripheral C	Extra Function	System Function	Comments
PC0	D0	PWML0				100-pin version
PC1	D1	PWML1				100-pin version
PC2	D2	PWML2				100-pin version
PC3	D3	PWML3				100-pin version
PC4	D4	NPCS1				100-pin version
PC5	D5					100-pin version
PC6	D6					100-pin version
PC7	D7					100-pin version
PC8	NWE					100-pin version
PC9	NANDOE					100-pin version
PC10	NANDWE					100-pin version
PC11	NRD					100-pin version
PC12	NCS3			AD12		100-pin version
PC13	NWAIT	PWML0		AD10		100-pin version
PC14	NCS0					100-pin version
PC15	NCS1	PWML1		AD11		100-pin version
PC16	A21/NANDALE					100-pin version
PC17	A22/NANDCLE					100-pin version
PC18	A0	PWMH0				100-pin version
PC19	A1	PWMH1				100-pin version
PC20	A2	PWMH2				100-pin version
PC21	А3	PWMH3				100-pin version
PC22	A4	PWML3				100-pin version
PC23	A5	TIOA3				100-pin version
PC24	A6	TIOB3				100-pin version
PC25	A7	TCLK3				100-pin version
PC26	A8	TIOA4				100-pin version
PC27	A9	TIOB4				100-pin version
PC28	A10	TCLK4				100-pin version
PC29	A11	TIOA5		AD13		100-pin version
PC30	A12	TIOB5		AD14		100-pin version
PC31	A13	TCLK5				100-pin version



12.4 Universal Synchronous Asynchronous Receiver Transceiver (USART)

- Programmable Baud Rate Generator with Fractional Baud rate support
- 5- to 9-bit full-duplex synchronous or asynchronous serial communications
 - 1, 1.5 or 2 stop bits in Asynchronous Mode or 1 or 2 stop bits in Synchronous Mode
 - Parity generation and error detection
 - Framing error detection, overrun error detection
 - MSB- or LSB-first
 - Optional break generation and detection
 - By 8 or by-16 over-sampling receiver frequency
 - Hardware handshaking RTS-CTS
 - Receiver time-out and transmitter timeguard
 - Optional Multi-drop Mode with address generation and detection
 - Optional Manchester Encoding
 - Full modem line support on USART1 (DCD-DSR-DTR-RI)
- RS485 with driver control signal
- ISO7816, T = 0 or T = 1 Protocols for interfacing with smart cards
 - NACK handling, error counter with repetition and iteration limit
- SPI Mode
 - Master or Slave
 - Serial Clock programmable Phase and Polarity
 - SPI Serial Clock (SCK) Frequency up to MCK/4
- · IrDA modulation and demodulation
 - Communication at up to 115.2 Kbps
- Test Modes
 - Remote Loopback, Local Loopback, Automatic Echo

12.5 Synchronous Serial Controller (SSC)

- Provides serial synchronous communication links used in audio and telecom applications (with CODECs in Master or Slave Modes, I²S, TDM Buses, Magnetic Card Reader)
- Contains an independent receiver and transmitter and a common clock divider
- Offers configurable frame sync and data length
- Receiver and transmitter can be programmed to start automatically or on detection of different event on the frame sync signal
- Receiver and transmitter include a data signal, a clock signal and a frame synchronization signal

12.6 Timer Counter (TC)

- Six 16-bit Timer Counter Channels
- Wide range of functions including:
 - Frequency Measurement
 - Event Counting

- Interval Measurement
- Pulse Generation
- Delay Timing
- Pulse Width Modulation
- Up/down Capabilities
- Each channel is user-configurable and contains:
 - Three external clock inputs
 - Five internal clock inputs
 - Two multi-purpose input/output signals
- Two global registers that act on all three TC Channels
- · Quadrature decoder
 - Advanced line filtering
 - Position / revolution / speed
- 2-bit Gray Up/Down Counter for Stepper Motor

12.7 Pulse Width Modulation Controller (PWM)

- One Four-channel 16-bit PWM Controller, 16-bit counter per channel
- Common clock generator, providing Thirteen Different Clocks
 - A Modulo n counter providing eleven clocks
 - Two independent Linear Dividers working on modulo n counter outputs
 - High Frequency Asynchronous clocking mode
- Independent channel programming
 - Independent Enable Disable Commands
 - Independent Clock Selection
 - Independent Period and Duty Cycle, with Double Buffering
 - Programmable selection of the output waveform polarity
 - Programmable center or left aligned output waveform
 - Independent Output Override for each channel
 - Independent complementary Outputs with 12-bit dead time generator for each channel
 - Independent Enable Disable Commands
 - Independent Clock Selection
 - Independent Period and Duty Cycle, with Double Buffering
- Synchronous Channel mode
 - Synchronous Channels share the same counter
 - Mode to update the synchronous channels registers after a programmable number of periods
- Connection to one PDC channel
 - Offers Buffer transfer without Processor Intervention, to update duty cycle of synchronous channels
- independent event lines which can send up to 4 triggers on ADC within a period



• Programmable gain: 1, 2, 4

12.11 Digital-to-Analog Converter (DAC)

- Up to 2 channel 12-bit DAC
- Up to 2 mega-samples conversion rate in single channel mode
- Flexible conversion range
- Multiple trigger sources for each channel
- 2 Sample/Hold (S/H) outputs
- Built-in offset and gain calibration
- · Possibility to drive output to ground
- Possibility to use as input to analog comparator or ADC (as an internal wire and without S/H stage)
- Two PDC channels
- · Power reduction mode

12.12 Static Memory Controller

- 16-Mbyte Address Space per Chip Select
- 8- bit Data Bus
- Word, Halfword, Byte Transfers
- Programmable Setup, Pulse And Hold Time for Read Signals per Chip Select
- Programmable Setup, Pulse And Hold Time for Write Signals per Chip Select
- Programmable Data Float Time per Chip Select
- External Wait Request
- Automatic Switch to Slow Clock Mode
- Asynchronous Read in Page Mode Supported: Page Size Ranges from 4 to 32 Bytes
- NAND FLASH additional logic supporting NAND Flash with Multiplexed Data/Address buses
- Hardware Configurable number of chip select from 1 to 4
- Programmable timing on a per chip select basis

12.13 Analog Comparator

- One analog comparator
- High speed option vs. low power option
- Selectable input hysteresis:
 - 0, 20 mV, 50 mV
- Minus input selection:
 - DAC outputs
 - Temperature Sensor
 - ADVREF
 - AD0 to AD3 ADC channels
- Plus input selection:
 - All analog inputs





Table 13-1. 48-lead LQFP Package Dimensions (in mm)

		Millimeter	,	Inch			
Symbol	Min	Nom	Max	Min	Nom	Max	
А	_	_	1.60	_	_	0.063	
A1	0.05	_	0.15	0.002	_	0.006	
A2	1.35	1.40	1.45	0.053	0.055	0.057	
D		9.00 BSC			0.354 BSC		
D1		7.00 BSC			0.276 BSC		
Е		9.00 BSC			0.354 BSC		
E1		7.00 BSC			0.276 BSC		
R2	0.08	_	0.20	0.003	_	0.008	
R1	0.08	_	_	0.003	_	_	
q	0°	3.5°	7°	0°	3.5°	7°	
θ_1	0°	_	_	0°	_	_	
θ_2	11°	12°	13°	11°	12°	13°	
θ_3	11°	12°	13°	11°	12°	13°	
С	0.09	_	0.20	0.004	_	0.008	
L	0.45	0.60	0.75	0.018	0.024	0.030	
L1		1.00 REF			0.039 REF		
S	0.20	_	-	0.008	_	-	
b	0.17	0.20	0.27	0.007	0.008	0.011	
е		0.50 BSC.			0.020 BSC.		
D2		5.50			0.217		
E2		5.50 0.217					
Tolerances of Form and Position							
aaa		0.20		0.008			
bbb		0.20		0.008			
ccc		0.08		0.003			
ddd		0.08			0.003		



Figure 13-5. 64-pad QFN Package Drawing

