Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	CANbus, I²C, SPI, UART/USART
Peripherals	LVD, PWM, WDT
Number of I/O	58
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 16x12b; D/A 2x6b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mke06z64vlh4

Table of Contents

1 Ordering parts

1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to **nxp.com** and perform a part number search for the following device numbers: KE06Z.

2 Part identification

2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

2.2 Format

Part numbers for this device have the following format:

Q KE## A FFF R T PP CC N

2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	• M = Fully qualified, general market flow • P = Prequalification
KE##	Kinetis family	• KE06
A	Key attribute	• Z = M0+ core
FFF	Program flash memory size	• 128 = 128 KB
R	Silicon revision	• (Blank) = Main • A = Revision after main
T	Temperature range (°C)	• V = –40 to 105
PP	Package identifier	• LD = 44 LQFP (10 mm x 10 mm)

Table continues on the next page...

4 Ratings

4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T_{STG}	Storage temperature	–55	150	°C	1
T_{SDR}	Solder temperature, lead-free	—	260	°C	2

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V_{HBM}	Electrostatic discharge voltage, human body model	–6000	+6000	V	1
V_{CDM}	Electrostatic discharge voltage, charged-device model	–500	+500	V	2
I_{LAT}	Latch-up current at ambient temperature of 125°C	–100	+100	mA	3

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.
3. Determined according to JEDEC Standard JESD78D, *IC Latch-up Test*.
   - Test was performed at 125 °C case temperature (Class II).
   - I/O pins pass ±100 mA I-test with I_{DD} current limit at 400 mA.
   - I/O pins pass +50/-100 mA I-test with I_{DD} current limit at 1000 mA.
   - Supply groups pass 1.5 V_{ccmax}.
   - $\overline{\text{RESET}}$ pin was only tested with negative I-test due to product conditioning requirement.

4.4 Voltage and current operating ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in the following table may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this document.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pullup resistor associated with the pin is enabled.

Table 2. Voltage and current operating ratings

Symbol	Description	Min.	Max.	Unit
V_{DD}	Digital supply voltage	–0.3	6.0	V
I_{DD}	Maximum current into V_{DD}	—	120	mA
V_{IN}	Input voltage except true open drain pins	–0.3	V_{DD} + 0.3[1]	V
	Input voltage of true open drain pins	–0.3	6	V
I_D	Instantaneous maximum current single pin limit (applies to all port pins)	–25	25	mA
V_{DDA}	Analog supply voltage	V_{DD} – 0.3	V_{DD} + 0.3	V

1. Maximum rating of V_{DD} also applies to V_{IN}.

5 General

5.1 Nonswitching electrical specifications

5.1.1 DC characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 3. DC characteristics

Symbol	C	Descriptions		Min	Typical[1]	Max	Unit
—	—	Operating voltage	—	2.7	—	5.5	V

Table continues on the next page...

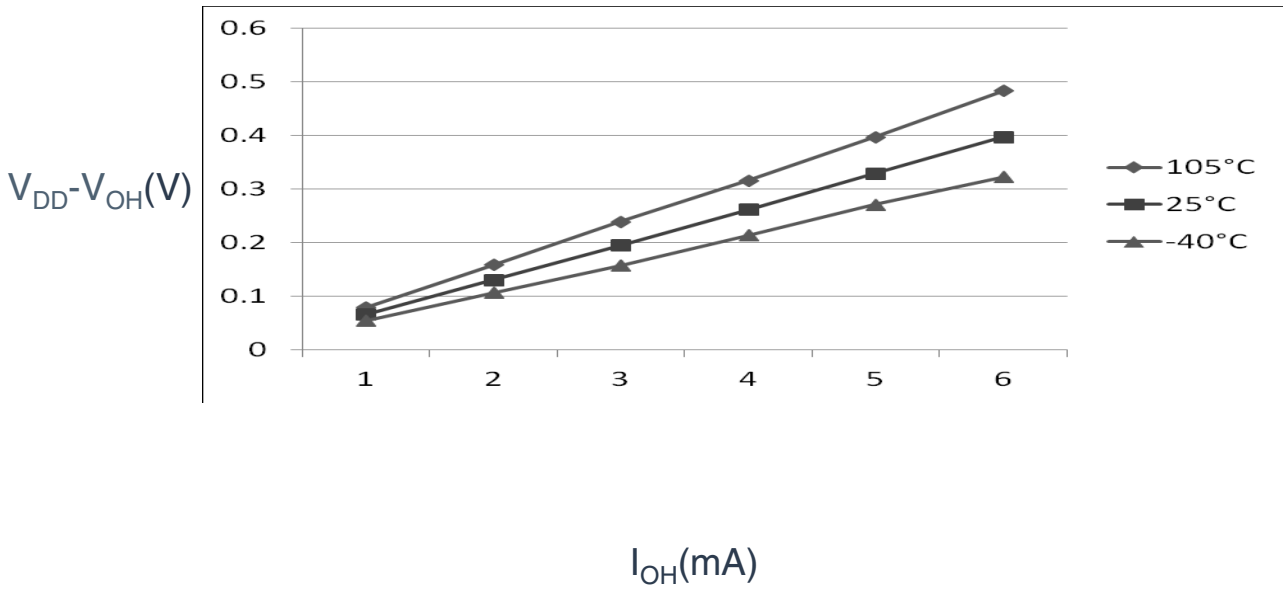


Figure 1. Typical V_{DD}-V_{OH} Vs. I_{OH} (standard drive strength) (V_{DD} = 5 V)

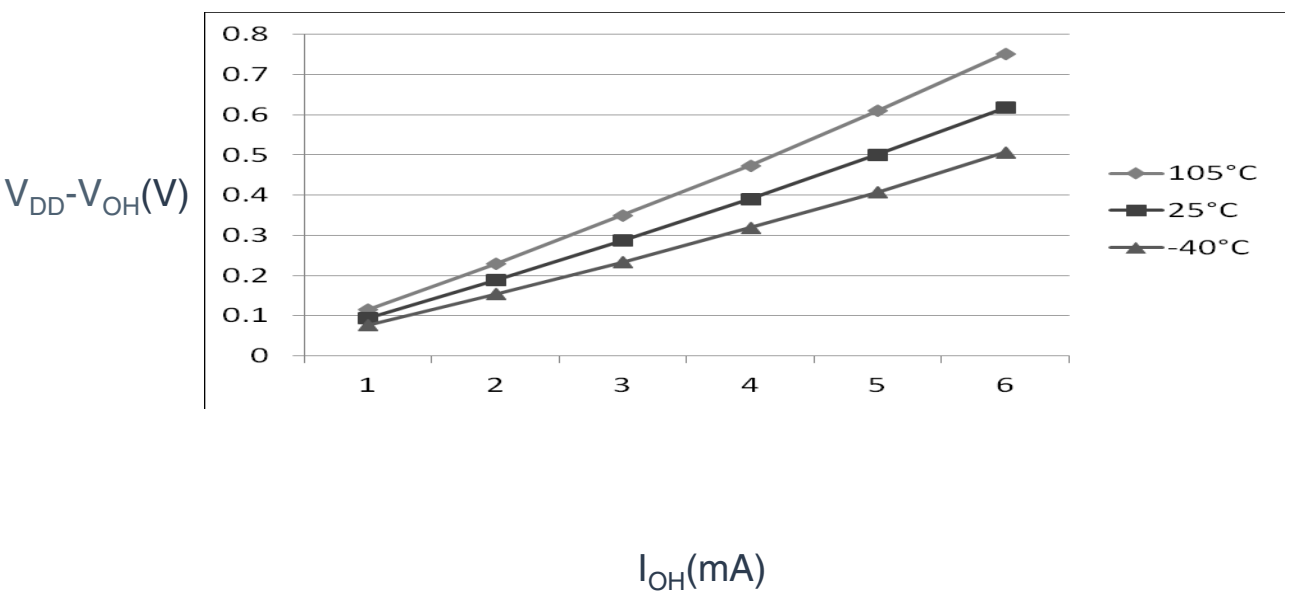


Figure 2. Typical V_{DD}-V_{OH} Vs. I_{OH} (standard drive strength) (V_{DD} = 3 V)

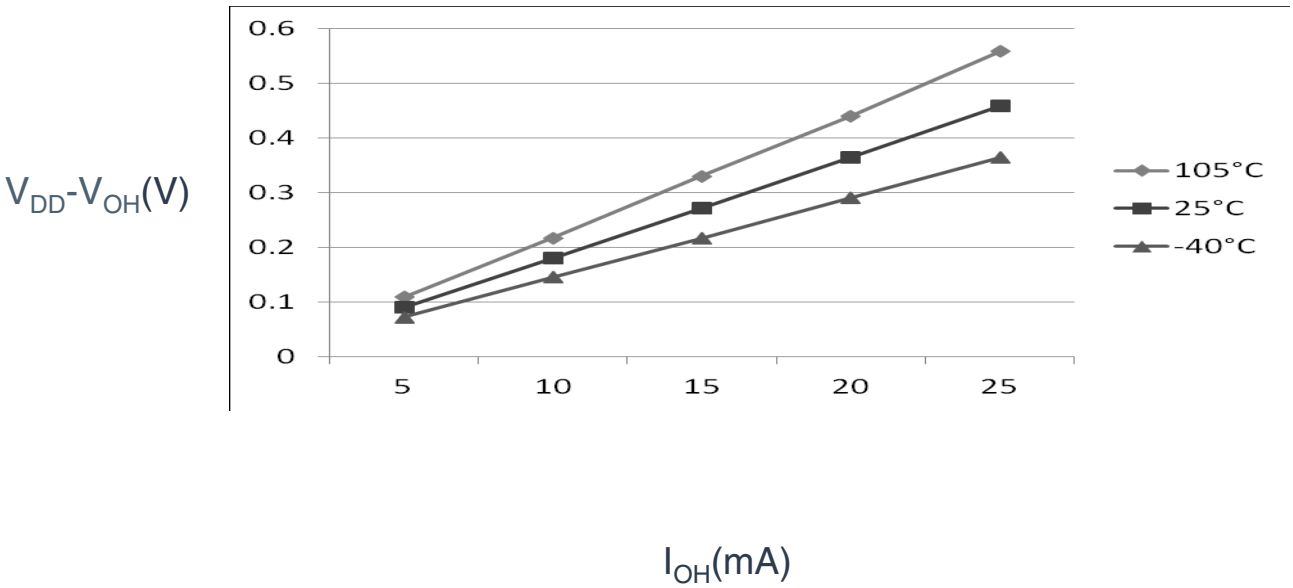


Figure 3. Typical V_{DD}-V_{OH} Vs. I_{OH} (high drive strength) (V_{DD} = 5 V)

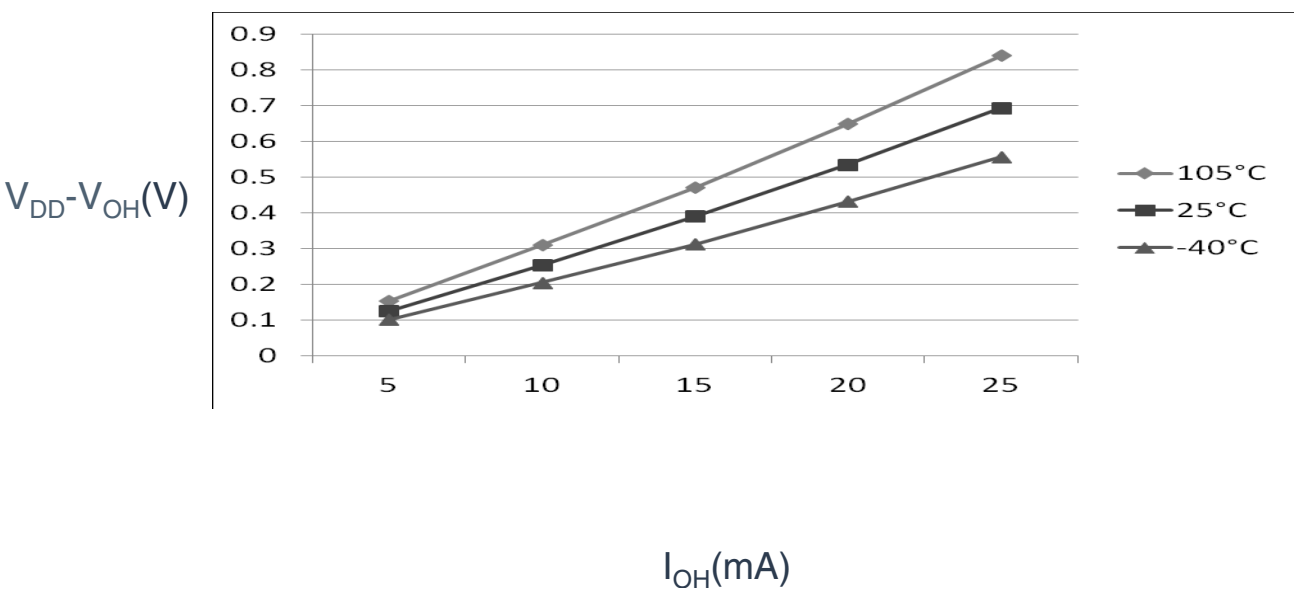


Figure 4. Typical V_{DD}-V_{OH} Vs. I_{OH} (high drive strength) (V_{DD} = 3 V)

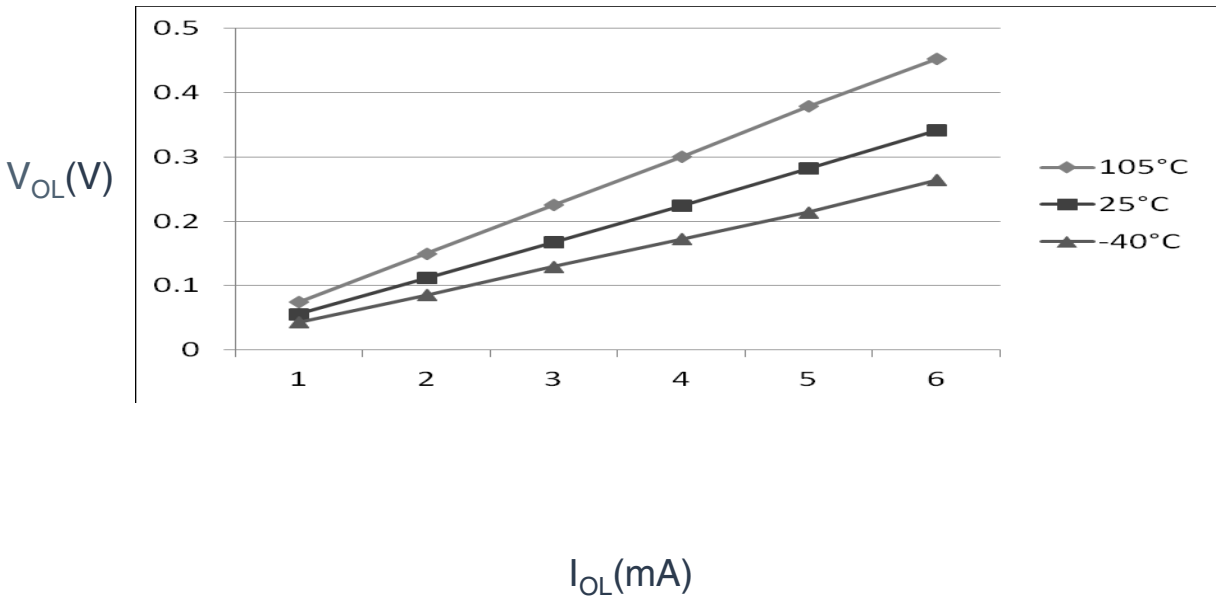


Figure 5. Typical V_{OL} Vs. I_{OL} (standard drive strength) (V_{DD} = 5 V)

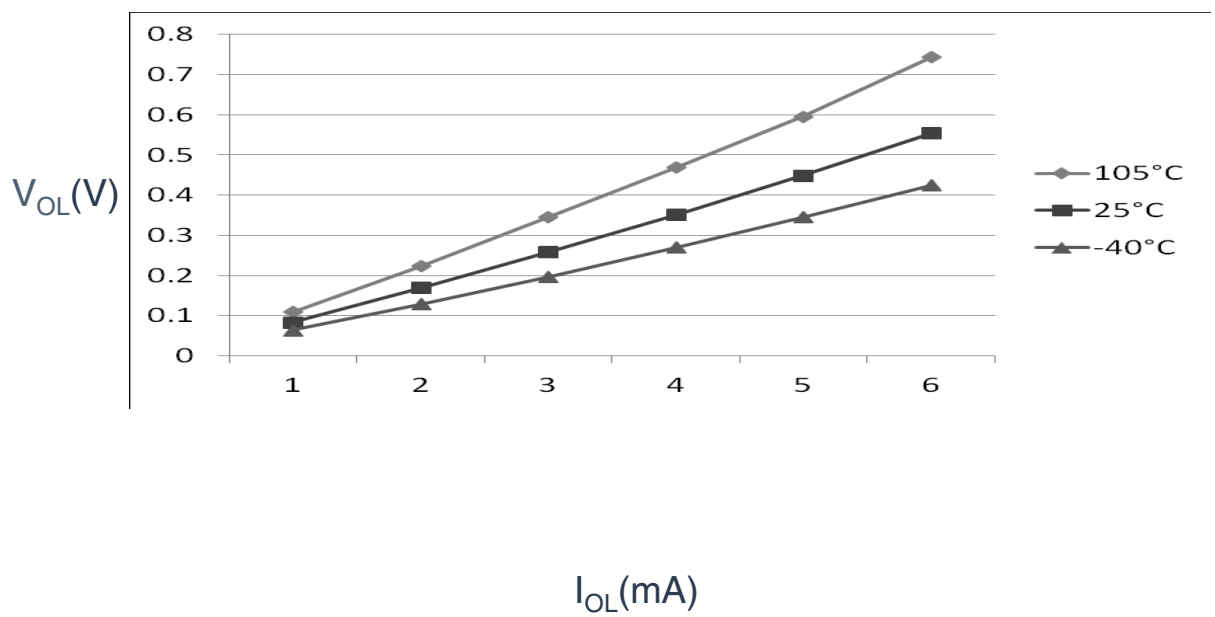


Figure 6. Typical V_{OL} Vs. I_{OL} (standard drive strength) (V_{DD} = 3 V)

5.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

Table 5. Supply current characteristics

C	Parameter	Symbol	Core/Bus Freq	V_{DD} (V)	Typical[1]	Max[2]	Unit	Temp
C	Run supply current FEI mode, all modules clocks enabled; run from flash	RI_{DD}	48/24 MHz	5	11.1	—	mA	-40 to 105 °C
C			24/24 MHz		8	—		
C			12/12 MHz		5	—		
C			1/1 MHz		2.4	—		
C			48/24 MHz	3	11	—		
C			24/24 MHz		7.9	—		
C			12/12 MHz		4.9	—		
			1/1 MHz		2.3	—		
C	Run supply current FEI mode, all modules clocks disabled and gated; run from flash	RI_{DD}	48/24 MHz	5	7.8	—	mA	-40 to 105 °C
C			24/24 MHz		5.5	—		
C			12/12 MHz		3.8	—		
C			1/1 MHz		2.3	—		
C			48/24 MHz	3	7.7	—		
C			24/24 MHz		5.4	—		
C			12/12 MHz		3.7	—		
C			1/1 MHz		2.2	—		
C	Run supply current FBE mode, all modules clocks enabled; run from RAM	RI_{DD}	48/24 MHz	5	14.7	—	mA	-40 to 105 °C
P			24/24 MHz		9.8	14.9		
C			12/12 MHz		6	—		
C			1/1 MHz		2.4	—		
C			48/24 MHz	3	14.6	—		
P			24/24 MHz		9.6	12.8		
C			12/12 MHz		5.9	—		
C			1/1 MHz		2.3	—		
C	Run supply current FBE mode, all modules clocks disabled and gated; run from RAM	RI_{DD}	48/24 MHz	5	11.4	—	mA	-40 to 105 °C
P			24/24 MHz		7.7	12.5		
C			12/12 MHz		4.7	—		
C			1/1 MHz		2.3	—		
C			48/24 MHz	3	11.3	—		
P			24/24 MHz		7.6	9.5		
C			12/12 MHz		4.6	—		
			1/1 MHz		2.2	—		

Table continues on the next page...

Table 12. OSC and ICS specifications (temperature range = -40 to 105 °C ambient) (continued)

Num	C	Characteristic		Symbol	Min	Typical[1]	Max	Unit
2	D	Load capacitors		C1, C2	See Note[2]			
3	D	Feedback resistor	Low Frequency, Low-Power Mode[3]	R_F	—	—	—	MΩ
			Low Frequency, High-Gain Mode		—	10	—	MΩ
			High Frequency, Low-Power Mode		—	1	—	MΩ
			High Frequency, High-Gain Mode		—	1	—	MΩ
4	D	Series resistor - Low Frequency	Low-Power Mode [3]	R_S	—	0	—	kΩ
			High-Gain Mode		—	200	—	kΩ
5	D	Series resistor - High Frequency	Low-Power Mode[3]	R_S	—	0	—	kΩ
	D	Series resistor - High Frequency, High-Gain Mode	4 MHz		—	0	—	kΩ
	D		8 MHz		—	0	—	kΩ
	D		16 MHz		—	0	—	kΩ
6	C	Crystal start-up time low range = 32.768 kHz crystal; High range = 20 MHz crystal[4,5]	Low range, low power	t_{CSTL}	—	1000	—	ms
	C		Low range, high gain		—	800	—	ms
	C		High range, low power	t_{CSTH}	—	3	—	ms
	C		High range, high gain		—	1.5	—	ms
7	T	Internal reference start-up time		t_{IRST}	—	20	50	µs
8	P	Internal reference clock (IRC) frequency trim range		f_{int_t}	31.25	—	39.0625	kHz
9	P	Internal reference clock frequency, factory trimmed	T = 25 °C, V_{DD} = 5 V	f_{int_ft}	—	37.5	—	kHz
10	P	DCO output frequency range	FLL reference = fint_t, flo, or fhi/RDIV	f_{dco}	40	—	50	MHz
11	P	Factory trimmed internal oscillator accuracy	T = 25 °C, V_{DD} = 5 V	Δf_{int_ft}	-0.5	—	0.5	%
12	C	Deviation of IRC over temperature when trimmed at T = 25 °C, V_{DD} = 5 V	Over temperature range from -40 °C to 105°C	Δf_{int_t}	-1	—	0.5	%
			Over temperature range from 0 °C to 105°C	Δf_{int_t}	-0.5	—	0.5	
13	C	Frequency accuracy of DCO output using factory trim value	Over temperature range from -40 °C to 105°C	Δf_{dco_ft}	-1.5	—	1	%
			Over temperature range from 0 °C to 105°C	Δf_{dco_ft}	-1	—	1	

Table continues on the next page...

Table 13. Flash characteristics (continued)

C	Characteristic	Symbol	Min[1]	Typical[2]	Max[3]	Unit[4]
D	NVM Bus frequency	f_{NVMBUS}	1	—	24	MHz
D	NVM Operating frequency	f_{NVMOP}	0.8	1	1.05	MHz
D	Erase Verify All Blocks	t_{VFYALL}	—	—	2605	t_{cyc}
D	Erase Verify Flash Block	t_{RD1BLK}	—	—	2579	t_{cyc}
D	Erase Verify Flash Section	t_{RD1SEC}	—	—	485	t_{cyc}
D	Read Once	t_{RDONCE}	—	—	464	t_{cyc}
D	Program Flash (2 word)	t_{PGM2}	0.12	0.13	0.31	ms
D	Program Flash (4 word)	t_{PGM4}	0.21	0.21	0.49	ms
D	Program Once	$t_{PGMONCE}$	0.20	0.21	0.21	ms
D	Erase All Blocks	t_{ERSALL}	95.42	100.18	100.30	ms
D	Erase Flash Block	t_{ERSBLK}	95.42	100.18	100.30	ms
D	Erase Flash Sector	t_{ERSPG}	19.10	20.05	20.09	ms
D	Unsecure Flash	t_{UNSECU}	95.42	100.19	100.31	ms
D	Verify Backdoor Access Key	t_{VFYKEY}	—	—	482	t_{cyc}
D	Set User Margin Level	t_{MLOADU}	—	—	415	t_{cyc}
C	FLASH Program/erase endurance T_L to T_H = -40 °C to 105 °C	n_{FLPE}	10 k	100 k	—	Cycles
C	Data retention at an average junction temperature of T_{Javg} = 85°C after up to 10,000 program/erase cycles	t_{D_ret}	15	100	—	years

1. Minimum times are based on maximum f_{NVMOP} and maximum f_{NVMBUS}
2. Typical times are based on typical f_{NVMOP} and maximum f_{NVMBUS}
3. Maximum times are based on typical f_{NVMOP} and typical f_{NVMBUS} plus aging
4. $t_{cyc} = 1 / f_{NVMBUS}$

Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see the Flash Memory Module section in the reference manual.

6.4 Analog

6.4.1 ADC characteristics

Table 14. 5 V 12-bit ADC operating conditions

Characteristic	Conditions	Symbol	Min	Typ[1]	Max	Unit	Comment
Reference potential	• Low • High	V_{REFL} V_{REFH}	V_{SSA} $V_{DDA}/2$	— —	$V_{DDA}/2$ V_{DDA}	V	—

Table continues on the next page...

Table 15. 12-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$)

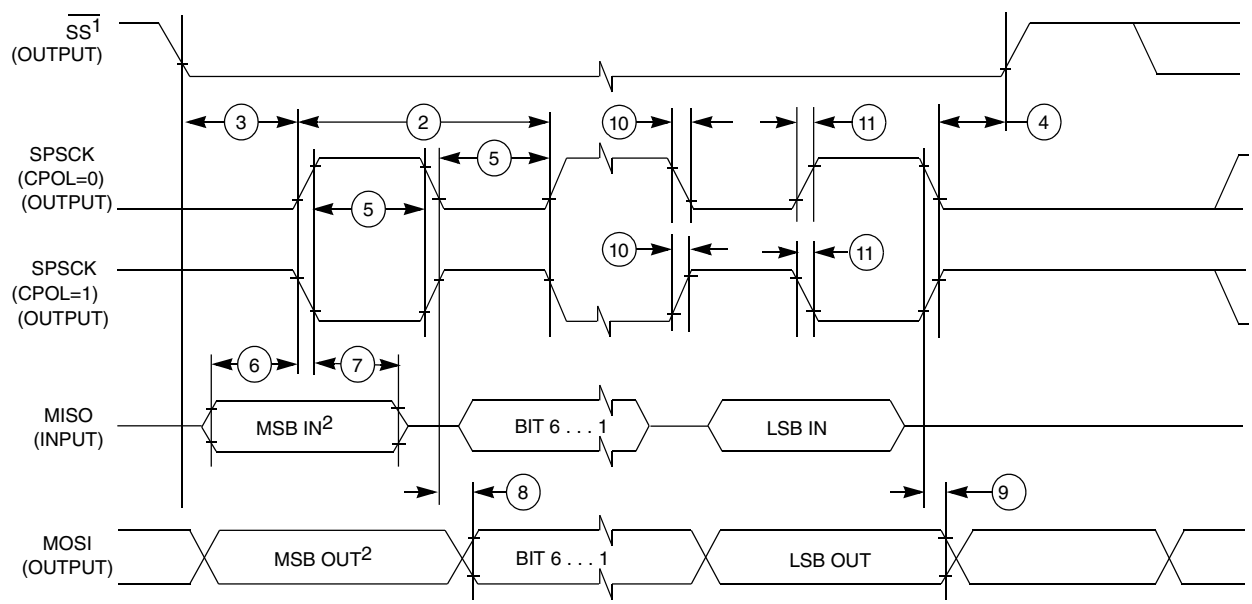
Characteristic	Conditions	C	Symbol	Min	Typ[1]	Max	Unit
Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		T	I_{DDA}	—	133	—	μA
Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		T	I_{DDA}	—	218	—	μA
Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		T	I_{DDA}	—	327	—	μA
Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		T	I_{DDA}	—	582	990	μA
Supply current	Stop, reset, module off	T	I_{DDA}	—	0.011	1	μA
ADC asynchronous clock source	High speed (ADLPC = 0)	P	f_{ADACK}	2	3.3	5	MHz
	Low power (ADLPC = 1)			1.25	2	3.3	
Conversion time (including sample time)	Short sample (ADLSMP = 0)	T	t_{ADC}	—	20	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	40	—	
Sample time	Short sample (ADLSMP = 0)	T	t_{ADS}	—	3.5	—	ADCK cycles
	Long sample (ADLSMP = 1)			—	23.5	—	
Total unadjusted Error[2]	12-bit mode	C	E_{TUE}	—	±5.0	—	LSB[3]
	10-bit mode	C		—	±1.5	—	
	8-bit mode	C		—	±0.8	—	
Differential Non-Liniarity	12-bit mode	C	DNL	—	±1.5	—	LSB[3]
	10-bit mode	C		—	±0.4	—	
	8-bit mode	C		—	±0.15	—	
Integral Non-Linearity	12-bit mode	C	INL	—	±1.5	—	LSB[3]
	10-bit mode	C		—	±0.4	—	
	8-bit mode	C		—	±0.15	—	
Zero-scale error[4]	12-bit mode	C	E_{ZS}	—	±1.0	—	LSB[3]
	10-bit mode	C		—	±0.2	—	

Table continues on the next page...

chip's reference manual for information about the modified transfer formats used for communicating with slower peripheral devices. All timing is shown with respect to 20% V_{DD} and 80% V_{DD}, unless noted, and 25 pF load on all SPI pins. All timing assumes slew rate control is disabled and high-drive strength is enabled for SPI output pins.

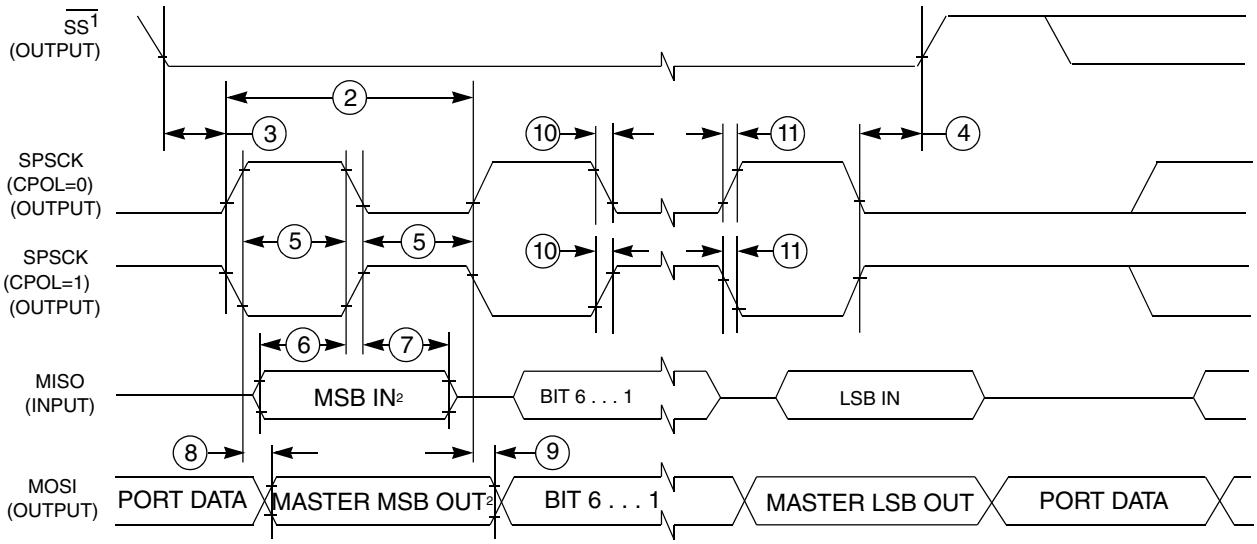
Table 17. SPI master mode timing

Num.	Symbol	Description	Min.	Max.	Unit	Comment
1	f_{op}	Frequency of operation	$f_{Bus}/2048$	$f_{Bus}/2$	Hz	f_{Bus} is the bus clock
2	t_{SPSCK}	SPSCK period	2 x t_{Bus}	2048 x t_{Bus}	ns	$t_{Bus} = 1/f_{Bus}$
3	t_{Lead}	Enable lead time	1/2	—	t_{SPSCK}	—
4	t_{Lag}	Enable lag time	1/2	—	t_{SPSCK}	—
5	t_{WSPSCK}	Clock (SPSCK) high or low time	t_{Bus} – 30	1024 x t_{Bus}	ns	—
6	t_{SU}	Data setup time (inputs)	8	—	ns	—
7	t_{HI}	Data hold time (inputs)	8	—	ns	—
8	t_v	Data valid (after SPSCK edge)	—	25	ns	—
9	t_{HO}	Data hold time (outputs)	20	—	ns	—
10	t_{RI}	Rise time input	—	t_{Bus} – 25	ns	—
	t_{FI}	Fall time input				
11	t_{RO}	Rise time output	—	25	ns	—
	t_{FO}	Fall time output				



1. If configured as an output.
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 17. SPI master mode timing (CPHA=0)



1.If configured as output

2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 18. SPI master mode timing (CPHA=1)

Table 18. SPI slave mode timing

Num.	Symbol	Description	Min.	Max.	Unit	Comment
1	f_{op}	Frequency of operation	0	$f_{Bus}/4$	Hz	f_{Bus} is the bus clock as defined in Control timing.
2	t_{SPSCK}	SPSCK period	4 x t_{Bus}	—	ns	$t_{Bus} = 1/f_{Bus}$
3	t_{Lead}	Enable lead time	1	—	t_{Bus}	—
4	t_{Lag}	Enable lag time	1	—	t_{Bus}	—
5	t_{WSPSCK}	Clock (SPSCK) high or low time	t_{Bus} - 30	—	ns	—
6	t_{SU}	Data setup time (inputs)	15	—	ns	—
7	t_{HI}	Data hold time (inputs)	25	—	ns	—
8	t_a	Slave access time	—	t_{Bus}	ns	Time to data active from high-impedance state
9	t_{dis}	Slave MISO disable time	—	t_{Bus}	ns	Hold time to high-impedance state
10	t_v	Data valid (after SPSCK edge)	—	25	ns	—
11	t_{HO}	Data hold time (outputs)	0	—	ns	—
12	t_{RI}	Rise time input	—	t_{Bus} - 25	ns	—
	t_{FI}	Fall time input				
13	t_{RO}	Rise time output	—	25	ns	—
	t_{FO}	Fall time output				

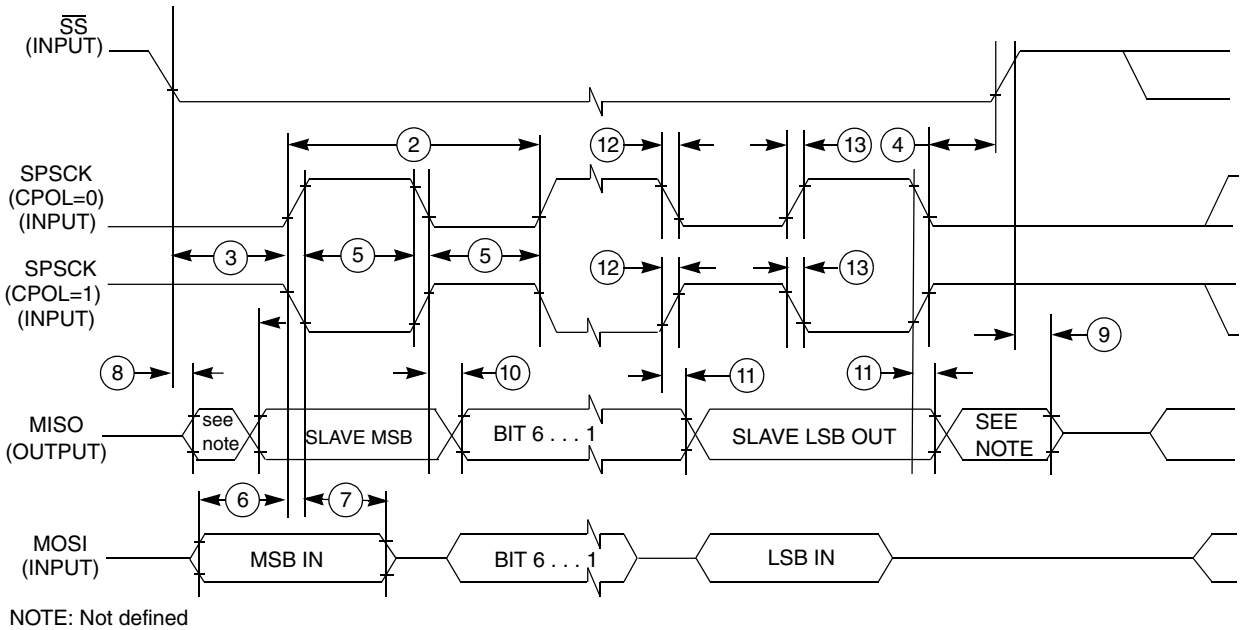


Figure 19. SPI slave mode timing (CPHA = 0)

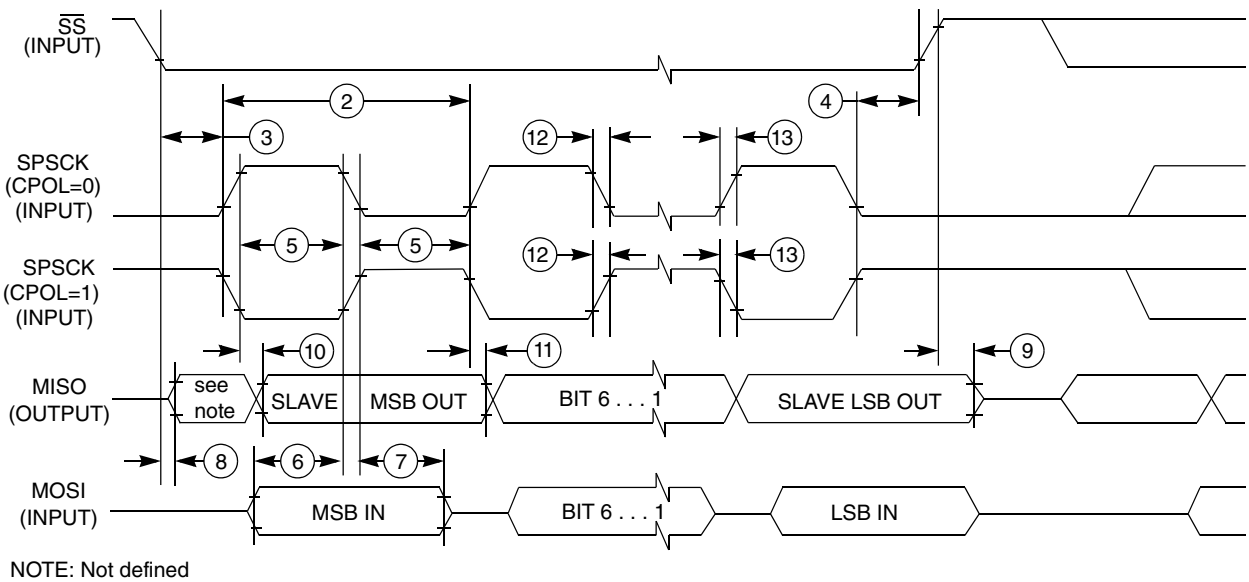


Figure 20. SPI slave mode timing (CPHA=1)

6.5.2 MSCAN

Table 19. MSCAN wake-up pulse characteristics

Parameter	Symbol	Min	Typ	Max	Unit
MSCAN wakeup dominant pulse filtered	t_{WUP}	-	-	1.5	µs
MSCAN wakeup dominant pulse pass	t_{WUP}	5	-	-	µs

80 LQFP	64 LQFP /QFP	44 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
1	1	1	PTD1	DISABLED	PTD1	KBI0_P25	FTM2_CH3	SPI1_MOSI				
2	2	2	PTD0	DISABLED	PTD0	KBI0_P24	FTM2_CH2	SPI1_SCK				
3	3	—	PTH7	DISABLED	PTH7	KBI1_P31	PWT_IN1					
4	4	—	PTH6	DISABLED	PTH6	KBI1_P30						
5	—	—	PTH5	DISABLED	PTH5	KBI1_P29						
6	5	3	PTE7	DISABLED	PTE7	KBI1_P7	TCLK2		FTM1_CH1	CAN0_TX		
7	6	4	PTH2	DISABLED	PTH2	KBI1_P26	BUSOUT		FTM1_CH0	CAN0_RX		
8	7	5	VDD	VDD							VDD	
9	8	6	VDDA	VDDA						VREFH	VDDA	
10	—	—	VREFH	VREFH							VREFH	
11	9	7	VREFL	VREFL							VREFL	
12	10	8	VSS/ VSSA	VSS/ VSSA						VSSA	VSS	
13	11	9	PTB7	EXTAL	PTB7	KBI0_P15	I2C0_SCL				EXTAL	
14	12	10	PTB6	XTAL	PTB6	KBI0_P14	I2C0_SDA				XTAL	
15	13	11	PTI4	DISABLED	PTI4		IRQ					
16	—	—	PTI1	DISABLED	PTI1		IRQ	UART2_TX				
17	—	—	PTI0	DISABLED	PTI0		IRQ	UART2_RX				
18	14	—	PTH1	DISABLED	PTH1	KBI1_P25	FTM2_CH1					
19	15	—	PTH0	DISABLED	PTH0	KBI1_P24	FTM2_CH0					
20	16	—	PTE6	DISABLED	PTE6	KBI1_P6						
21	17	—	PTE5	DISABLED	PTE5	KBI1_P5						
22	18	12	PTB5	DISABLED	PTB5	KBI0_P13	FTM2_CH5	SPI0_PCS	ACMP1_OUT			
23	19	13	PTB4	NMI_b	PTB4	KBI0_P12	FTM2_CH4	SPI0_MISO	ACMP1_IN2	NMI_b		
24	20	14	PTC3	ADC0_SE11	PTC3	KBI0_P19	FTM2_CH3		ADC0_SE11			
25	21	15	PTC2	ADC0_SE10	PTC2	KBI0_P18	FTM2_CH2		ADC0_SE10			
26	22	16	PTD7	DISABLED	PTD7	KBI0_P31	UART2_TX					
27	23	17	PTD6	DISABLED	PTD6	KBI0_P30	UART2_RX					
28	24	18	PTD5	DISABLED	PTD5	KBI0_P29	PWT_IN0					
29	—	—	PTI6	DISABLED	PTI6	IRQ						
30	—	—	PTI5	DISABLED	PTI5	IRQ						
31	25	19	PTC1	ADC0_SE9	PTC1	KBI0_P17	FTM2_CH1		ADC0_SE9			
32	26	20	PTC0	ADC0_SE8	PTC0	KBI0_P16	FTM2_CH0		ADC0_SE8			
33	—	—	PTH4	DISABLED	PTH4	KBI1_P28	I2C1_SCL					
34	—	—	PTH3	DISABLED	PTH3	KBI1_P27	I2C1_SDA					
35	27	—	PTF7	ADC0_SE15	PTF7	KBI1_P15			ADC0_SE15			
36	28	—	PTF6	ADC0_SE14	PTF6	KBI1_P14			ADC0_SE14			
37	29	—	PTF5	ADC0_SE13	PTF5	KBI1_P13			ADC0_SE13			
38	30	—	PTF4	ADC0_SE12	PTF4	KBI1_P12			ADC0_SE12			
39	31	21	PTB3	ADC0_SE7	PTB3	KBI0_P11	SPI0_MOSI	FTM0_CH1	ADC0_SE7			
40	32	22	PTB2	ADC0_SE6	PTB2	KBI0_P10	SPI0_SCK	FTM0_CH0	ADC0_SE6			

80 LQFP	64 LQFP /QFP	44 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
41	33	23	PTB1	ADC0_SE5	PTB1	KBI0_P9	UART0_TX		ADC0_SE5			
42	34	24	PTB0	ADC0_SE4	PTB0	KBI0_P8	UART0_RX	PWT_IN1	ADC0_SE4			
43	35	—	PTF3	DISABLED	PTF3	KBI1_P11	UART1_TX					
44	36	—	PTF2	DISABLED	PTF2	KBI1_P10	UART1_RX					
45	37	25	PTA7	ADC0_SE3	PTA7	KBI0_P7	FTM2_FLT2	ACMP1_IN1	ADC0_SE3			
46	38	26	PTA6	ADC0_SE2	PTA6	KBI0_P6	FTM2_FLT1	ACMP1_IN0	ADC0_SE2			
47	39	—	PTE4	DISABLED	PTE4	KBI1_P4						
48	40	27	VSS	VSS							VSS	
49	41	28	VDD	VDD							VDD	
50	—	—	PTG7	DISABLED	PTG7	KBI1_P23	FTM2_CH5	SPI1_PCS				
51	—	—	PTG6	DISABLED	PTG6	KBI1_P22	FTM2_CH4	SPI1_MISO				
52	—	—	PTG5	DISABLED	PTG5	KBI1_P21	FTM2_CH3	SPI1_MOSI				
53	—	—	PTG4	DISABLED	PTG4	KBI1_P20	FTM2_CH2	SPI1_SCK				
54	42	—	PTF1	DISABLED	PTF1	KBI1_P9	FTM2_CH1					
55	43	—	PTF0	DISABLED	PTF0	KBI1_P8	FTM2_CH0					
56	44	29	PTD4	DISABLED	PTD4	KBI0_P28						
57	45	30	PTD3	DISABLED	PTD3	KBI0_P27	SPI1_PCS					
58	46	31	PTD2	DISABLED	PTD2	KBI0_P26	SPI1_MISO					
59	47	32	PTA3	DISABLED	PTA3	KBI0_P3	UART0_TX	I2C0_SCL				
60	48	33	PTA2	DISABLED	PTA2	KBI0_P2	UART0_RX	I2C0_SDA				
61	49	34	PTA1	ADC0_SE1	PTA1	KBI0_P1	FTM0_CH1	I2C0_ 4WSDAOUT	ACMP0_IN1	ADC0_SE1		
62	50	35	PTA0	ADC0_SE0	PTA0	KBI0_P0	FTM0_CH0	I2C0_ 4WSCLOUT	ACMP0_IN0	ADC0_SE0		
63	51	36	PTC7	DISABLED	PTC7	KBI0_P23	UART1_TX			CAN0_TX		
64	52	37	PTC6	DISABLED	PTC6	KBI0_P22	UART1_RX			CAN0_RX		
65	—	—	PTI3	DISABLED	PTI3	IRQ						
66	—	—	PTI2	DISABLED	PTI2	IRQ						
67	53	—	PTE3	DISABLED	PTE3	KBI1_P3	SPI0_PCS					
68	54	38	PTE2	DISABLED	PTE2	KBI1_P2	SPI0_MISO	PWT_IN0				
69	—	—	VSS	VSS							VSS	
70	—	—	VDD	VDD							VDD	
71	55	—	PTG3	DISABLED	PTG3	KBI1_P19						
72	56	—	PTG2	DISABLED	PTG2	KBI1_P18						
73	57	—	PTG1	DISABLED	PTG1	KBI1_P17						
74	58	—	PTG0	DISABLED	PTG0	KBI1_P16						
75	59	39	PTE1	DISABLED	PTE1	KBI1_P1	SPI0_MOSI		I2C1_SCL			
76	60	40	PTE0	DISABLED	PTE0	KBI1_P0	SPI0_SCK	TCLK1	I2C1_SDA			
77	61	41	PTC5	DISABLED	PTC5	KBI0_P21		FTM1_CH1		RTC_ CLKOUT		

80 LQFP	64 LQFP /QFP	44 LQFP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7
78	62	42	PTC4	SWD_CLK	PTC4	KBI0_P20	RTC_ CLKOUT	FTM1_CH0	ACMP0_IN2	SWD_CLK		
79	63	43	PTA5	RESET_b	PTA5	KBI0_P5	IRQ	TCLK0	RESET_b			
80	64	44	PTA4	SWD_DIO	PTA4	KBI0_P4		ACMP0_OUT	SWD_DIO			

8.2 Device pin assignment

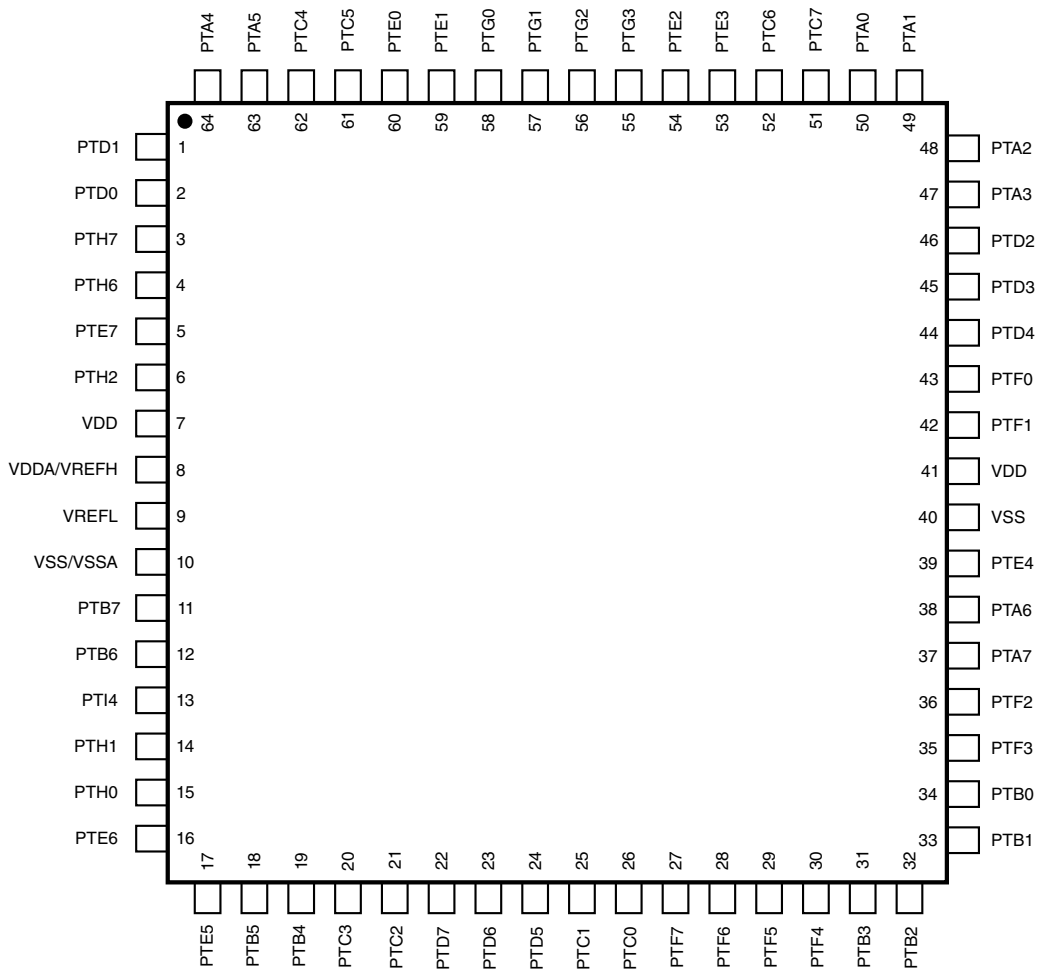


Figure 22. 64-pin QFP/LQFP packages

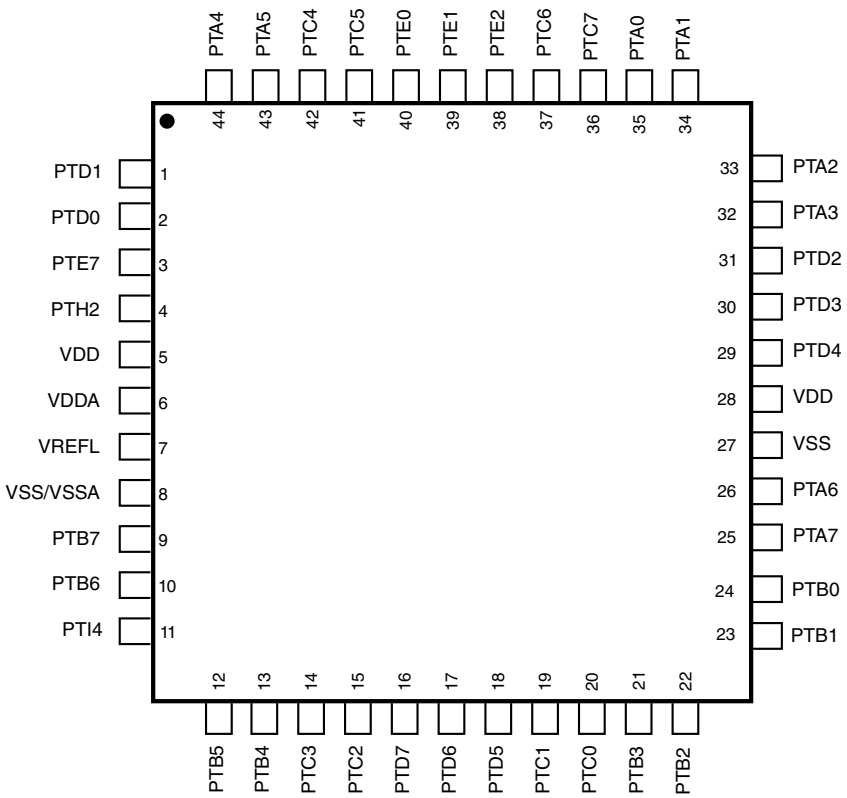


Figure 23. 44-pin LQFP package

9 Revision history

The following table provides a revision history for this document.

Table 20. Revision history

Rev. No.	Date	Substantial Changes
1	12/2013	Initial NDA release.
2	3/2014	Initial public release.
3	5/2014	• Updated the Max. of SI_{DD}. • Updated footnote to the V_{OH}. • Corrected Unit in the FTM input timing table.
4	07/2016	• Added a new section of Thermal operating requirements. • Corrected pinout diagram for 44-pin LQFP in the Device pin assignment.

How to Reach Us:

Home Page:
nxp.com

Web Support:
nxp.com/support

Document Number MKE06P80M48SF0
Revision 4, 07/2016