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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I ² C, IrDA, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	56
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.98V ~ 3.8V
Data Converters	A/D 8x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32g840f32g-e-qfn64

- Supply Voltage Comparator
- · Ultra efficient Power-on Reset and Brown-Out Detector
- · 2-pin Serial Wire Debug Interface
 - 1-pin Serial Wire Viewer
- Pre-Programmed USB/UART Bootloader
- Temperature range -40 to 85 °C
- Single power supply 1.98 to 3.8 V
- Packages
 - BGA112
 - LQFP100
 - TQFP64
 - TQFP48
 - QFN64
 - QFN32

3. System Overview

3.1 System Introduction

The EFM32 MCUs are the world's most energy friendly microcontrollers. With a unique combination of the powerful 32-bit ARM Cortex-M3, innovative low energy techniques, short wake-up time from energy saving modes, and a wide selection of peripherals, the EFM32G microcontroller is well suited for any battery operated application as well as other systems requiring high performance and low-energy consumption. This section gives a short introduction to each of the modules in general terms and also shows a summary of the configuration for the EFM32G devices. For a complete feature set and in-depth information on the modules, the reader is referred to the EFM32G Reference Manual.

The diagram shows a superset of features available on the family, which vary by OPN. For more information about specific device features, consult Ordering Information.

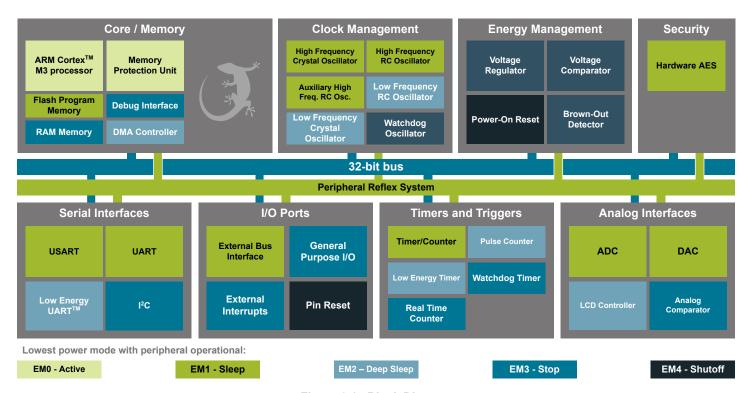


Figure 3.1. Block Diagram

3.1.1 ARM Cortex-M3 Core

The ARM Cortex-M3 includes a 32-bit RISC processor which can achieve as much as 1.25 Dhrystone MIPS/MHz. A Memory Protection Unit with support for up to 8 memory segments is included, as well as a Wake-up Interrupt Controller handling interrupts triggered while the CPU is asleep. The EFM32 implementation of the Cortex-M3 is described in detail in EFM32G Reference Manual.

3.1.2 Debug Interface (DBG)

This device includes hardware debug support through a 2-pin serial-wire debug interface. In addition there is also a 1-wire Serial Wire Viewer pin which can be used to output profiling information, data trace and software-generated messages.

3.1.3 Memory System Controller (MSC)

The Memory System Controller (MSC) is the program memory unit of the EFM32G microcontroller. The flash memory is readable and writable from both the Cortex-M3 and DMA. The flash memory is divided into two blocks; the main block and the information block. Program code is normally written to the main block. Additionally, the information block is available for special user data and flash lock bits. There is also a read-only page in the information block containing system and device calibration data. Read and write operations are supported in the energy modes EM0 and EM1.

3.1.14 Universal Asynchronous Receiver/Transmitter (UART)

The Universal Asynchronous serial Receiver and Transmitter (UART) is a very flexible serial I/O module. It supports full- and half-duplex asynchronous UART communication.

3.1.15 Low Energy Universal Asynchronous Receiver/Transmitter (LEUART)

The unique LEUARTTM, the Low Energy UART, is a UART that allows two-way UART communication on a strict power budget. Only a 32.768 kHz clock is needed to allow UART communication up to 9600 baud/ s. The LEUART includes all necessary hardware support to make asynchronous serial communication possible with minimum of software intervention and energy consumption.

3.1.16 Timer/Counter (TIMER)

The 16-bit general purpose Timer has 3 compare/capture channels for input capture and compare/Pulse-Width Modulation (PWM) output. TIMER0 also includes a Dead-Time Insertion module suitable for motor control applications.

3.1.17 Real Time Counter (RTC)

The Real Time Counter (RTC) contains a 24-bit counter and is clocked either by a 32.768 kHz crystal oscillator, or a 32.768 kHz RC oscillator. In addition to energy modes EM0 and EM1, the RTC is also available in EM2. This makes it ideal for keeping track of time since the RTC is enabled in EM2 where most of the device is powered down.

3.1.18 Low Energy Timer (LETIMER)

The unique LETIMERTM, the Low Energy Timer, is a 16-bit timer that is available in energy mode EM2 in addition to EM1 and EM0. Because of this, it can be used for timing and output generation when most of the device is powered down, allowing simple tasks to be performed while the power consumption of the system is kept at an absolute minimum. The LETIMER can be used to output a variety of waveforms with minimal software intervention. It is also connected to the Real Time Counter (RTC), and can be configured to start counting on compare matches from the RTC.

3.1.19 Pulse Counter (PCNT)

The Pulse Counter (PCNT) can be used for counting pulses on a single input or to decode quadrature encoded inputs. It runs off either the internal LFACLK or the PCNTn S0IN pin as external clock source. The module may operate in energy mode EM0 - EM3.

3.1.20 Analog Comparator (ACMP)

The Analog Comparator is used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. Inputs can either be one of the selectable internal references or from external pins. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

3.1.21 Voltage Comparator (VCMP)

The Voltage Supply Comparator is used to monitor the supply voltage from software. An interrupt can be generated when the supply falls below or rises above a programmable threshold. Response time and thereby also the current consumption can be configured by altering the current supply to the comparator.

3.1.22 Analog to Digital Converter (ADC)

The ADC is a Successive Approximation Register (SAR) architecture, with a resolution of up to 12 bits at up to one million samples per second. The integrated input mux can select inputs from 8 external pins and 6 internal signals.

3.1.23 Digital to Analog Converter (DAC)

The Digital to Analog Converter (DAC) can convert a digital value to an analog output voltage. The DAC is fully differential rail-to-rail, with 12-bit resolution. It has two single-ended output buffers which can be combined into one differential output. The DAC may be used for a number of different applications such as sensor interfaces or sound output.

3.1.24 Advanced Encryption Standard Accelerator (AES)

The AES accelerator performs AES encryption and decryption with 128-bit or 256-bit keys. Encrypting or decrypting one 128-bit data block takes 52 HFCORECLK cycles with 128-bit keys and 75 HFCORECLK cycles with 256-bit keys. The AES module is an AHB slave which enables efficient access to the data and key registers. All write accesses to the AES module must be 32-bit operations, i.e. 8- or 16-bit operations are not supported.

3.1.25 General Purpose Input/Output (GPIO)

General Purpose Input/Output (GPIO) pins are organized into ports with up to 16 pins each. These pins can individually be configured as either an output or input. More advanced configurations like open-drain, filtering and drive strength can also be configured individually for the pins. The GPIO pins can also be overridden by peripheral pin connections, like Timer PWM outputs or USART communication, which can be routed to several locations on the device. The GPIO supports up to 16 asynchronous external pin interrupts, which enables interrupts from any pin on the device. Also, the input value of a pin can be routed through the Peripheral Reflex System to other peripherals.

3.1.26 Liquid Crystal Display Driver (LCD)

The LCD driver is capable of driving a segmented LCD display with up to 4x40 segments. A voltage boost function enables it to provide the LCD display with higher voltage than the supply voltage for the device. In addition, an animation feature can run custom animations on the LCD display without any CPU intervention. The LCD driver can also remain active even in Energy Mode 2 and provides a Frame Counter interrupt that can wake-up the device on a regular basis for updating data.

3.2.10 EFM32G880

The features of the EFM32G880 is a subset of the feature set described in the EFM32G Reference Manual. The following table describes device specific implementation of the features.

Table 3.10. EFM32G880 Configuration Summary

Module	Module	Module
Cortex-M3	Full configuration	NA
DBG	Full configuration	DBG_SWCLK, DBG_SWDIO, DBG_SWO
MSC	Full configuration	NA
DMA	Full configuration	NA
RMU	Full configuration	NA
EMU	Full configuration	NA
СМИ	Full configuration	CMU_OUT0, CMU_OUT1
WDOG	Full configuration	NA
PRS	Full configuration	NA
ЕВІ	Full configuration	EBI_ARDY, EBI_ALE, EBI_WEn, EBI_REn, EBI_CS[3:0], EBI_AD[15:0]
I2C0	Full configuration	I2C0_SDA, I2C0_SCL
USART0	Full configuration with IrDA	US0_TX, US0_RX. US0_CLK, US0_CS
USART1	Full configuration	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	Full configuration	US2_TX, US2_RX, US2_CLK, US2_CS
UART0	Full configuration	U0_TX, U0_RX
LEUART0	Full configuration	LEU0_TX, LEU0_RX
LEUART1	Full configuration	LEU1_TX, LEU1_RX
TIMER0	Full configuration with DTI	TIM0_CC[2:0], TIM0_CDTI[2:0]
TIMER1	Full configuration	TIM1_CC[2:0]
TIMER2	Full configuration	TIM2_CC[2:0]
RTC	Full configuration	NA
LETIMER0	Full configuration	LET0_O[1:0]
PCNT0	Full configuration, 8-bit count register	PCNT0_S[1:0]
PCNT1	Full configuration, 8-bit count register	PCNT1_S[1:0]
PCNT2	Full configuration, 8-bit count register	PCNT2_S[1:0]
ACMP0	Full configuration	ACMP0_CH[7:0], ACMP0_O
ACMP1	Full configuration	ACMP1_CH[7:0], ACMP1_O
VCMP	Full configuration	NA
ADC0	Full configuration	ADC0_CH[7:0]
DAC0	Full configuration	DAC0_OUT[1:0]
AES	Full configuration	NA
GPIO	86 pins	Available pins are shown in Table 4.3 (p. 57)

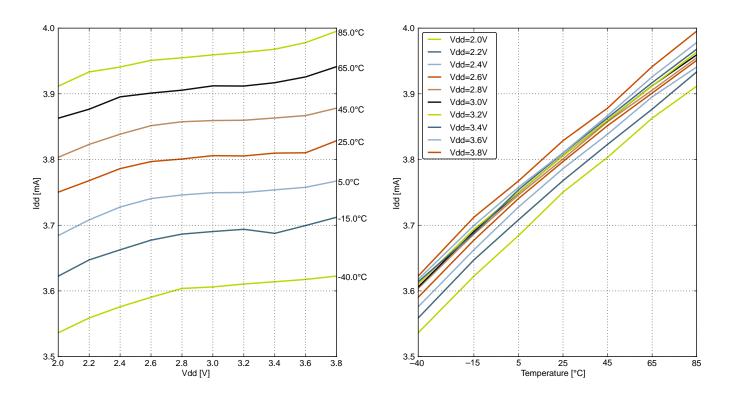


Figure 4.2. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 21 MHz

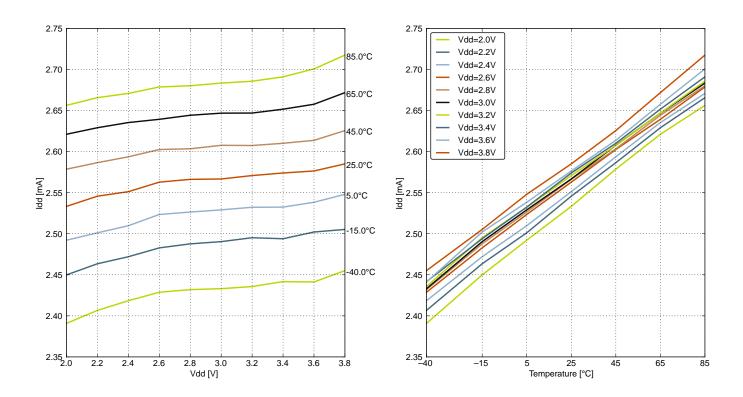


Figure 4.3. EM0 Current consumption while executing prime number calculation code from flash with HFRCO running at 14 MHz

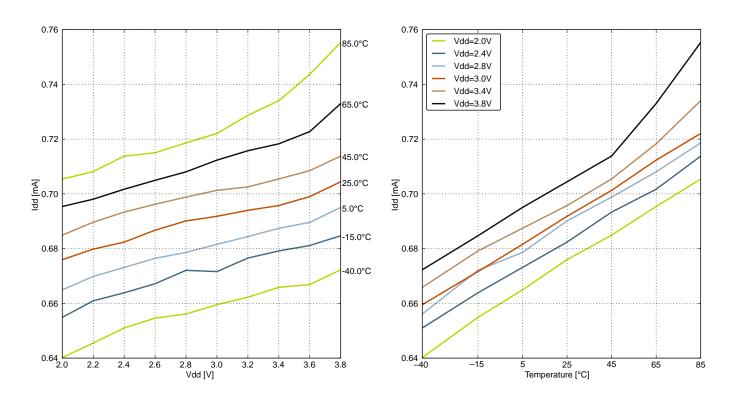


Figure 4.8. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 14 MHz

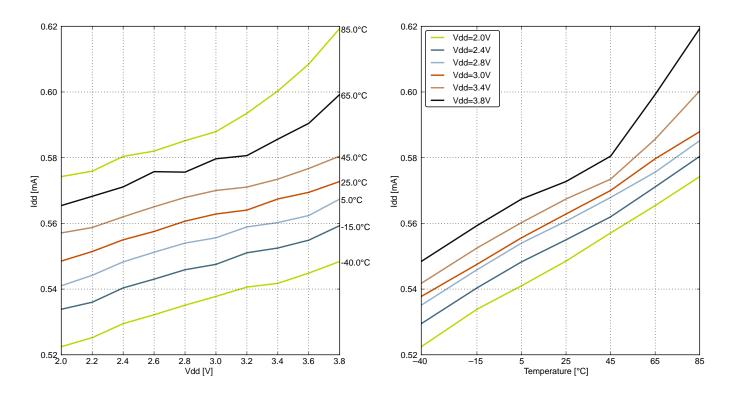


Figure 4.9. EM1 Current consumption with all peripheral clocks disabled and HFRCO running at 11 MHz

4.4.4 EM3 Current Consumption

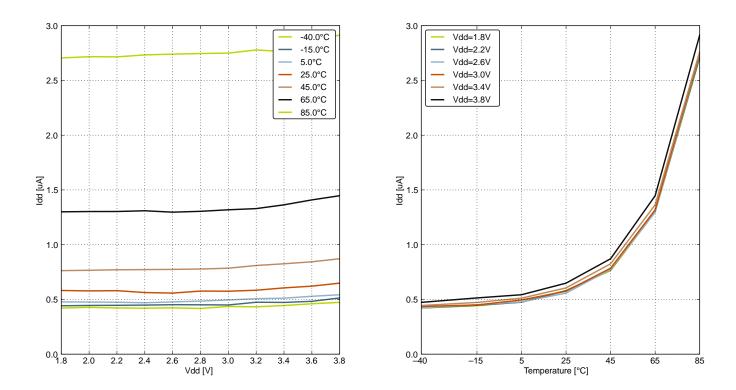


Figure 4.12. EM3 Current Consumption

4.9 Oscillators

4.9.1 LFXO

Table 4.8. LFXO

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Supported nominal crystal frequency	f _{LFXO}		_	32.768	_	kHz
Supported crystal equivalent series resistance (ESR)	ESR _{LFXO}		_	30	120	kOhm
Supported crystal external load range	C _{LFXOL}		X ¹	_	25	pF
Current consumption for core and buffer after startup	I _{LFXO}	ESR=30 kΩ, C _L =10 pF, LFXO- BOOST in CMU_CTRL is 1	_	190	_	nA
Start-up time	t _{LFXO}	ESR=30 kΩ, C _L =10 pF, 40% - 60% duty cycle has been reached, LFXOBOOST in CMU_CTRL is 1	_	400	_	ms

Note:

For safe startup of a given crystal, the Configurator tool in Simplicity Studio contains a tool to help users configure both load capacitance and software settings for using the LFXO. For details regarding the crystal configuration, the reader is referred to application note "AN0016 EFM32 Oscillator Design Consideration".

 $^{1.\,}See\,\,Minimum\,\,Load\,\,Capacitance\,\,(C_{LFXOL})\,\,Requirement\,\,For\,\,Safe\,\,Crystal\,\,Startup\,\,in\,\,Configurator\,\,in\,\,Simplicity\,\,Studio.$

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Signal-to-Noise Ratio (SNR)	SNR _{ADC}	1 MSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 13 MHz, BIASPROG = 0xF4B	_	59	_	dB
		1 MSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	63	_	dB
		1 MSamples/s, 12 bit, single- ended, V _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	67	_	dB
		1 MSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	63	_	dB
		1 MSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	66	_	dB
		1 MSamples/s, 12 bit, differential, 5 V reference, ADC_CLK =13 MHz, BIASPROG = 0xF4B	_	66	_	dB
		1 MSamples/s, 12 bit, differential, V _{DD} reference, ADC_CLK= 13 MHz, BIASPROG =0xF4B	63	69	_	dB
		1 MSamples/s, 12 bit, differential, 2xV _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	70	_	dB
		200 kSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	62	_	dB
		200 kSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	63	_	dB
		200 kSamples/s, 12 bit, single- ended, V _{DD} reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	67	_	dB
		200 kSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	63	_	dB
		200 kSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	66	_	dB
		200 kSamples/s, 12 bit, differential, 5 V reference, ADC_CLK = 7 MHz, BIASPROG = 0x747	_	66	_	dB

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Signal-to-Noise And Distortion Ratio (SINAD)	SINAD _{ADC}	1 MSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 13 MHz, BIASPROG = 0xF4B	_	58	_	dB
		1 MSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	62	_	dB
		1 MSamples/s, 12 bit, single- ended, V _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	66	_	dB
		1 MSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	63	_	dB
		1 MSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	66	_	dB
		1 MSamples/s, 12 bit, differential, 5 V reference, ADC_CLK = 13 MHz, BIASPROG = 0xF4B	_	66	_	dB
		1 MSamples/s, 12 bit, differential, V _{DD} reference, ADC_CLK = 13 MHz, BIASPROG = 0xF4B	62	68	_	dB
		1 MSamples/s, 12 bit, differential, 2xV _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	68	_	dB
		200 kSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	61	_	dB
		200 kSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	62	_	dB
		200 kSamples/s, 12 bit, single- ended, VDD reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	66	_	dB
		200 kSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	63	_	dB
		200 kSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	66	_	dB
		200 kSamples/s, 12 bit, differential, 5V reference, ADC_CLK= 7 MHz, BIASPROG = 0x747	_	66	_	dB

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Spurious-Free Dynamic Range (SFDR)	SFDR _{ADC}	1 MSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 13 MHz, BIASPROG = 0xF4B	_	75	_	dBc
		1 MSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	76	_	dBc
		1 MSamples/s, 12 bit, single- ended, V _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	_	76	_	dBc
		1 MSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	78	_	dBc
		1 MSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 13 MHz, BIA-SPROG = 0xF4B	_	77		dBc
		1 MSamples/s, 12 bit, differential, V _{DD} reference, ADC_CLK= 13 MHz, BIASPROG = 0xF4B	_	76	_	dBc
		1 MSamples/s, 12 bit, differential, 2xV _{DD} reference, ADC_CLK = 13 MHz, BIA- SPROG = 0xF4B	68	79	_	dBc
		1 MSamples/s, 12 bit, differential, 5 V reference, ADC_CLK =13 MHz, BIASPROG = 0xF4B	_	79	_	dBc
		200 kSamples/s, 12 bit, single- ended, internal 1.25 V refer- ence, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	75	_	dBc
		200 kSamples/s, 12 bit, single- ended, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	75	_	dBc
		200 kSamples/s, 12 bit, single- ended, V _{DD} reference, ADC_CLK = 7 MHz, BIA- SPROG = 0x747	_	76	_	dBc
		200 kSamples/s, 12 bit, differential, internal 1.25 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	79	_	dBc
		200 kSamples/s, 12 bit, differential, internal 2.5 V reference, ADC_CLK = 7 MHz, BIA-SPROG = 0x747	_	79	_	dBc
		200 kSamples/s, 12 bit, differential, 5 V reference, ADC_CLK = 7 MHz, BIASPROG = 0x747	_	78	_	dBc

5.2 EFM32G222 (TQFP48)

5.2.1 Pinout

The EFM32G222 pinout is shown in the following figure and table. Alternate locations are denoted by "#" followed by the location number (Multiple locations on the same pin are split with "/"). Alternate locations can be configured in the LOCATION bitfield in the *_ROUTE register in the module in question.

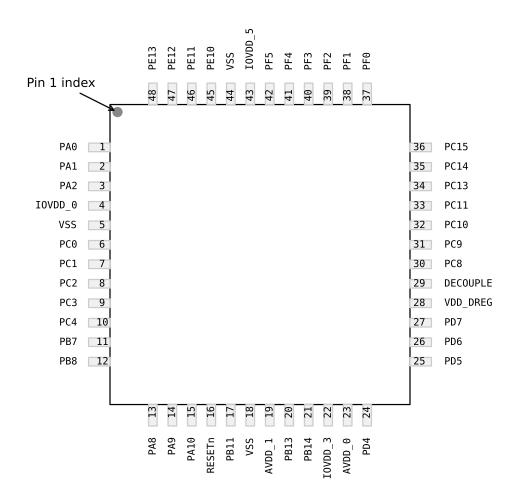


Figure 5.2. EFM32G222 Pinout (top view, not to scale)

Table 5.4. Device Pinout

	48 Pin# and Name		Pin Alternate Functionality / Description								
Pin#	Pin Name	Analog	Timers	Communication	Other						
1	PA0		TIM0_CC0 #0/1	I2C0_SDA #0							
2	PA1		TIM0_CC1 #0/1	I2C0_SCL #0	CMU_CLK1 #0						
3	PA2		TIM0_CC2 #0/1		CMU_CLK0 #0						
4	IOVDD_0	Digital IO power	Digital IO power supply 0.								
5	VSS	Ground.	Ground.								

Alternate	LOCATION				LOCATION
Functionality	0	1	2	3	Description
US0_TX	PE10		PC11		USART0 Asynchronous Transmit.Also used as receive input in half duplex communication. USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	PB7				USART1 clock input / output.
US1_CS	PB8				USART1 chip select input / output.
US1_RX	PC1				USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MI-SO).
US1_TX	PC0				USART1 Asynchronous Transmit.Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).

5.2.3 GPIO Pinout Overview

The specific GPIO pins available in EFM32G222 is shown in the following table. Each GPIO port is organized as 16-bit ports indicated by letters A through F, and the individual pin on this port is indicated by a number from 15 down to 0.

Table 5.6. GPIO Pinout

Port	Pin 15	Pin 14	Pin 13	Pin 12	Pin 11	Pin 10	Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2	Pin 1	Pin 0
Port A	_	_	_	_	_	PA10	PA9	PA8	_	_	_	_	_	PA2	PA1	PA0
Port B	_	PB14	PB13	_	PB11	_	_	PB8	PB7	_	_	_	_	_	_	_
Port C	PC15	PC14	PC13	_	PC11	PC10	PC9	PC8	_	_	_	PC4	PC3	PC2	PC1	PC0
Port D	_	_	_	_	_	_	_	_	PD7	PD6	PD5	PD4	_	_	_	_
Port E	_	_	PE13	PE12	PE11	PE10	_	_	_	_	_	_	_	_	_	
Port F	_	_	_	_	_	_	_	_	_	_	PF5	PF4	PF3	PF2	PF1	PF0

Alternate					LOCATION	
Functionality	0	1	2	3	Description	
TIM2_CC0	PA8	PA12	PC8		Timer 2 Capture Compare input / output channel 0.	
TIM2_CC1	PA9	PA13	PC9		Timer 2 Capture Compare input / output channel 1.	
TIM2_CC2	PA10	PA14	PC10		Timer 2 Capture Compare input / output channel 2.	
U0_RX	PF7	PE1	PA4	PC15	UART0 Receive input.	
U0_TX	PF6	PE0	PA3	PC14	UART0 Transmit output. Also used as receive input in half duplex communication.	
US0_CLK	PE12	PE5	PC9		USART0 clock input / output.	
US0_CS	PE13	PE4	PC8		USART0 chip select input / output.	
					USART0 Asynchronous Receive.	
US0_RX	PE11	PE6	PC10		USART0 Synchronous mode Master Input / Slave Output (MISO).	
US0_TX	5-10	DE 10	DEZ	D044		USART0 Asynchronous Transmit.Also used as receive input in half duplex communication.
	PE10	PE7	PC11		USART0 Synchronous mode Master Output / Slave Input (MOSI).	
US1_CLK	PB7	PD2			USART1 clock input / output.	
US1_CS	PB8	PD3			USART1 chip select input / output.	
					USART1 Asynchronous Receive.	
US1_RX	PC1	PD1			USART1 Synchronous mode Master Input / Slave Output (MISO).	
LIGA TV	DOG	DDG			USART1 Asynchronous Transmit.Also used as receive input in half duplex communication.	
US1_TX	PC0	PD0			USART1 Synchronous mode Master Output / Slave Input (MOSI).	
US2_CLK	PC4	PB5			USART2 clock input / output.	
US2_CS	PC5	PB6			USART2 chip select input / output.	
					USART2 Asynchronous Receive.	
US2_RX	PC3	PB4			USART2 Synchronous mode Master Input / Slave Output (MISO).	
US2_TX	DC2				USART2 Asynchronous Transmit.Also used as receive input in half duplex communication.	
	PC2	PB3			USART2 Synchronous mode Master Output / Slave Input (MOSI).	

Alternate					LOCATION
Functionality	0	1	2	3	Description
EBI_ARDY	PF2				External Bus Interface (EBI) Hardware Ready Control input.
EBI_CS0	PD9				External Bus Interface (EBI) Chip Select output 0.
EBI_CS1	PD10				External Bus Interface (EBI) Chip Select output 1.
EBI_CS2	PD11				External Bus Interface (EBI) Chip Select output 2.
EBI_CS3	PD12				External Bus Interface (EBI) Chip Select output 3.
EBI_REn	PF5				External Bus Interface (EBI) Read Enable output.
EBI_WEn	PF4				External Bus Interface (EBI) Write Enable output.
HFXTAL_N	PB14				High Frequency Crystal negative pin. Also used as external optional clock input pin.
HFXTAL_P	PB13				High Frequency Crystal positive pin.
I2C0_SCL	PA1	PD7	PC7		I2C0 Serial Clock Line input / output.
I2C0_SDA	PA0	PD6	PC6		I2C0 Serial Data input / output.
LCD_BCAP_N	PA13				LCD voltage booster (optional), boost capacitor, negative pin. If using the LCD voltage booster, connect a 22 nF capacitor between LCD_BCAP_N and LCD_BCAP_P.
LCD_BCAP_P	PA12				LCD voltage booster (optional), boost capacitor, positive pin. If using the LCD voltage booster, connect a 22 nF capacitor between LCD_BCAP_N and LCD_BCAP_P.
LCD_BEXT	PA14				LCD voltage booster (optional), boost output. If using the LCD voltage booster, connect a 1 uF capacitor between this pin and VSS. An external LCD voltage may also be applied to this pin if the booster is not enabled. If AVDD is used directly as the LCD supply voltage, this pin may be left unconnected or used as a GPIO.
LCD_COM0	PE4				LCD driver common line number 0.
LCD_COM1	PE5				LCD driver common line number 1.
LCD_COM2	PE6				LCD driver common line number 2.
LCD_COM3	PE7				LCD driver common line number 3.
LCD_SEG0	PF2				LCD segment line 0. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG1	PF3				LCD segment line 1. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG2	PF4				LCD segment line 2. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG3	PF5				LCD segment line 3. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG4	PE8				LCD segment line 4. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG5	PE9				LCD segment line 5. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG6	PE10				LCD segment line 6. Segments 4, 5, 6 and 7 are controlled by SEGEN1.

Alternate					LOCATION
Functionality	0	1	2	3	Description
LCD_SEG30	PD11				LCD segment line 30. Segments 28, 29, 30 and 31 are controlled by SEGEN7.
LCD_SEG31	PD12				LCD segment line 31. Segments 28, 29, 30 and 31 are controlled by SEGEN7.
LCD_SEG32	РВ0				LCD segment line 32. Segments 32, 33, 34 and 35 are controlled by SEGEN8.
LCD_SEG33	PB1				LCD segment line 33. Segments 32, 33, 34 and 35 are controlled by SEGEN8.
LCD_SEG34	PB2				LCD segment line 34. Segments 32, 33, 34 and 35 are controlled by SEGEN8.
LCD_SEG35	PA7				LCD segment line 35. Segments 32, 33, 34 and 35 are controlled by SEGEN8.
LCD_SEG36	PA8				LCD segment line 36. Segments 36, 37, 38 and 39 are controlled by SEGEN9.
LCD_SEG37	PA9				LCD segment line 37. Segments 36, 37, 38 and 39 are controlled by SEGEN9.
LCD_SEG38	PA10				LCD segment line 38. Segments 36, 37, 38 and 39 are controlled by SEGEN9.
LCD_SEG39	PA11				LCD segment line 39. Segments 36, 37, 38 and 39 are controlled by SEGEN9.
LETIMO_OUT0	PD6	PB11	PF0	PC4	Low Energy Timer LETIM0, output channel 0.
LETIM0_OUT1	PD7	PB12	PF1	PC5	Low Energy Timer LETIM0, output channel 1.
LEU0_RX	PD5	PB14	PE15		LEUART0 Receive input.
LEU0_TX	PD4	PB13	PE14		LEUART0 Transmit output. Also used as receive input in half duplex communication.
LEU1_RX	PC7	PA6			LEUART1 Receive input.
LEU1_TX	PC6	PA5			LEUART1 Transmit output. Also used as receive input in half duplex communication.
LFXTAL_N	PB8				Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	PB7				Low Frequency Crystal (typically 32.768 kHz) positive pin.
PCNT0_S0IN	PC13	PE0	PC0		Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	PC14	PE1	PC1		Pulse Counter PCNT0 input number 1.
PCNT1_S0IN	PC4	PB3			Pulse Counter PCNT1 input number 0.
PCNT1_S1IN	PC5	PB4			Pulse Counter PCNT1 input number 1.
PCNT2_S0IN	PD0	PE8			Pulse Counter PCNT2 input number 0.
PCNT2_S1IN	PD1	PE9			Pulse Counter PCNT2 input number 1.
TIM0_CC0	PA0	PA0	PF6	PD1	Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	PA1	PA1	PF7	PD2	Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	PA2	PA2	PF8	PD3	Timer 0 Capture Compare input / output channel 2.
TIM0_CDTI0	PA3	PC13	PF3	PC13	Timer 0 Complimentary Deat Time Insertion channel 0.

Alternate					LOCATION
Functionality	0	1	2	3	Description
EBI_ARDY	PF2				External Bus Interface (EBI) Hardware Ready Control input.
EBI_CS0	PD9				External Bus Interface (EBI) Chip Select output 0.
EBI_CS1	PD10				External Bus Interface (EBI) Chip Select output 1.
EBI_CS2	PD11				External Bus Interface (EBI) Chip Select output 2.
EBI_CS3	PD12				External Bus Interface (EBI) Chip Select output 3.
EBI_REn	PF5				External Bus Interface (EBI) Read Enable output.
EBI_WEn	PF4				External Bus Interface (EBI) Write Enable output.
HFXTAL_N	PB14				High Frequency Crystal negative pin. Also used as external optional clock input pin.
HFXTAL_P	PB13				High Frequency Crystal positive pin.
I2C0_SCL	PA1	PD7	PC7	PD15	I2C0 Serial Clock Line input / output.
I2C0_SDA	PA0	PD6	PC6	PD14	I2C0 Serial Data input / output.
LCD_BCAP_N	PA13				LCD voltage booster (optional), boost capacitor, negative pin. If using the LCD voltage booster, connect a 22 nF capacitor between LCD_BCAP_N and LCD_BCAP_P.
LCD_BCAP_P	PA12				LCD voltage booster (optional), boost capacitor, positive pin. If using the LCD voltage booster, connect a 22 nF capacitor between LCD_BCAP_N and LCD_BCAP_P.
LCD_BEXT	PA14				LCD voltage booster (optional), boost output. If using the LCD voltage booster, connect a 1 uF capacitor between this pin and VSS. An external LCD voltage may also be applied to this pin if the booster is not enabled. If AVDD is used directly as the LCD supply voltage, this pin may be left unconnected or used as a GPIO.
LCD_COM0	PE4				LCD driver common line number 0.
LCD_COM1	PE5				LCD driver common line number 1.
LCD_COM2	PE6				LCD driver common line number 2.
LCD_COM3	PE7				LCD driver common line number 3.
LCD_SEG0	PF2				LCD segment line 0. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG1	PF3				LCD segment line 1. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG2	PF4				LCD segment line 2. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG3	PF5				LCD segment line 3. Segments 0, 1, 2 and 3 are controlled by SEGEN0.
LCD_SEG4	PE8				LCD segment line 4. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG5	PE9				LCD segment line 5. Segments 4, 5, 6 and 7 are controlled by SEGEN1.
LCD_SEG6	PE10				LCD segment line 6. Segments 4, 5, 6 and 7 are controlled by SEGEN1.

7. LQFP100 Package Specifications

7.1 LQFP100 Package Dimensions

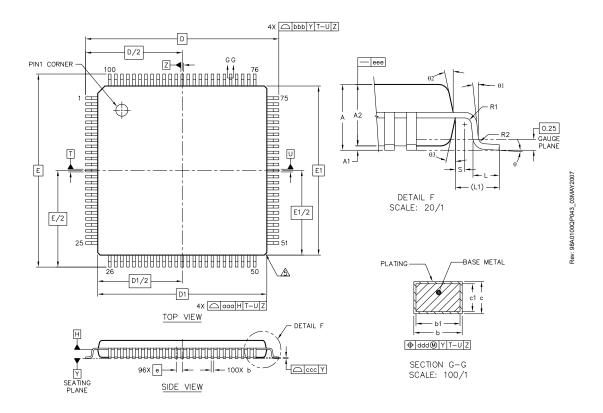


Figure 7.1. LQFP100

Note:

- 1. Datum 'T', 'U' and 'Z' to be determined at datum plane 'H'
- 2. Datum 'D' and 'E' to be determined at seating plane datum 'Y'.
- 3. Dimension 'D1' and 'E1' do not include mold protrusions. Allowable protrusion is 0.25 per side. Dimensions 'D1' and 'E1' do include mold mismatch and are determined at datum plane datum 'H'.
- 4. Dimension 'b' does not include dambar protrusion. Allowable dambar protrusion shall not cause thelead width to exceed the maximum 'b' dimension by more than 0.08 mm. Dambar can not be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm.
- 5. Exact shape of each corner is optional.

Table 7.1. LQFP100 (Dimensions in mm)

	SYMBOL	MIN	NOM	MAX
total thickness	A	_	_	1.6
stand off	A1	0.05	_	0.15
mold thickness	A2	1.35	1.4	1.45
lead width (plating)	b	0.17	0.2	0.27
lead width	b1	0.17	_	0.23
L/F thickness (plating)	С	0.09	_	0.2
lead thickness	c1	0.09	_	0.16

DIM	MIN	NOM	MAX	DIM	MIN	NOM	MAX
b	0.17	0.22	0.27	S	0.20	_	_
b1	0.17	0.20	0.23	θ	0°	3.5°	7°
С	0.09	_	0.20	θ1	0°	_	_
C1	0.09	_	0.16	θ2	11°	12°	13°
D		12.0 BS	C	θ3	11°	12°	13°
D1		10.0 BS	C				
е		0.50 BS	<u> </u>				
Е		12.0 BS	C				
E1	10.0 BSC						
L	0.45 0.60		0.75				

The TQFP64 Package is 10 by 10 mm in size and has a 0.5 mm pin pitch.

The TQFP64 Package uses Nickel-Palladium-Gold preplated leadframe.

All EFM32 packages are RoHS compliant and free of Bromine (Br) and Antimony (Sb).

For additional Quality and Environmental information, please see: http://www.silabs.com/support/quality/pages/default.aspx.