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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

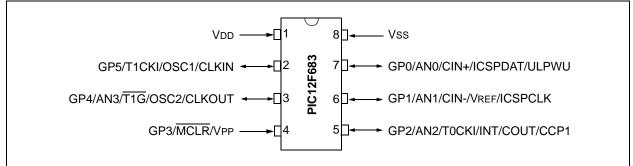
Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	5
Program Memory Size	3.5KB (2K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	128 x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 5.5V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	8-VDFN Exposed Pad
Supplier Device Package	8-DFN-S (6x5)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic12f683-e-mf

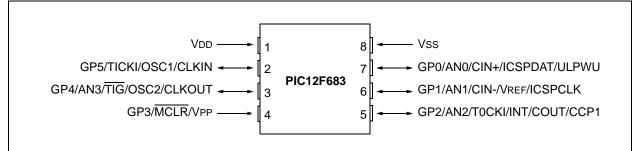
Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

8-Pin Diagram (PDIP, SOIC)



8-Pin Diagram (DFN)



8-Pin Diagram (DFN-S)

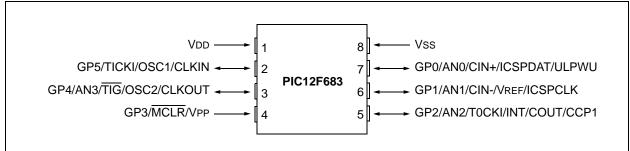


TABLE 1: 8-PIN SUMMARY

I/O	Pin	Analog	Comparators	Timer	ССР	Interrupts	Pull-ups	Basic
GP0	7	AN0	CIN+	_	_	IOC	Y	ICSPDAT/ULPWU
GP1	6	AN1/VREF	CIN-	—	—	IOC	Y	ICSPCLK
GP2	5	AN2	COUT	T0CKI	CCP1	INT/IOC	Y	—
GP3 ⁽¹⁾	4		—	_	_	IOC	Y(2)	MCLR/Vpp
GP4	3	AN3	—	T1G	-	IOC	Y	OSC2/CLKOUT
GP5	2	_	—	T1CKI		IOC	Y	OSC1/CLKIN
_	1		—		_	—	—	Vdd
	8	_		_	_	_	_	Vss

Note 1: Input only.

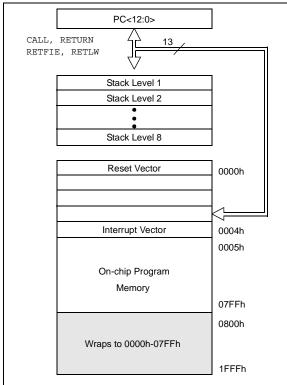
2: Only when pin is configured for external \overline{MCLR} .

2.0 MEMORY ORGANIZATION

2.1 Program Memory Organization

The PIC12F683 has a 13-bit program counter capable of addressing an $8k \times 14$ program memory space. Only the first $2k \times 14$ (0000h-07FFh) for the PIC12F683 is physically implemented. Accessing a location above these boundaries will cause a wraparound within the first $2K \times 14$ space. The Reset vector is at 0000h and the interrupt vector is at 0004h (see Figure 2-1).

FIGURE 2-1: PROGRAM MEMORY MAP AND STACK FOR THE PIC12F683



2.2 Data Memory Organization

The data memory (see Figure 2-2) is partitioned into two banks, which contain the General Purpose Registers (GPR) and the Special Function Registers (SFR). The Special Function Registers are located in the first 32 locations of each bank. Register locations 20h-7Fh in Bank 0 and A0h-BFh in Bank 1 are General Purpose Registers, implemented as static RAM. Register locations F0h-FFh in Bank 1 point to addresses 70h-7Fh in Bank 0. All other RAM is unimplemented and returns '0' when read. RP0 of the STATUS register is the bank select bit.

<u>RP0</u>

- $0 \rightarrow Bank 0 is selected$
- $1 \rightarrow Bank 1 is selected$

Note: The IRP and RP1 bits of the STATUS register are reserved and should always be maintained as '0's.

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Page	
Bank	Bank 1											
80h	INDF	Addressing	this location	uses conte	nts of FSR t	o address da	ata memory	(not a physi	cal register)	xxxx xxxx	17, 90	
81h	OPTION_REG	GPPU	INTEDG	TOCS	T0SE	PSA	PS2	PS1	PS0	1111 1111	12, 90	
82h	PCL	Program C	Program Counter's (PC) Least Significant Byte									
83h	STATUS	IRP ⁽¹⁾	RP1 ⁽¹⁾	RP0	TO	PD	Z	DC	С	0001 1xxx	11, 90	
84h	FSR	Indirect Da	ta Memory	Address Po	ointer					xxxx xxxx	17, 90	
85h	TRISIO	—	_	TRISIO5	TRISIO4	TRISIO3	TRISIO2	TRISIO1	TRISIO0	11 1111	32, 90	
86h	_	Unimpleme	ented							—	_	
87h	—	Unimpleme	ented							—	_	
88h	_	Unimpleme	ented							—	_	
89h	_	Unimpleme	ented							—	_	
8Ah	PCLATH	_	_		Write Buffe	r for upper	5 bits of Pro	ogram Cou	nter	0 0000	17, 90	
8Bh	INTCON	GIE	PEIE	TOIE	INTE	GPIE	TOIF	INTF	GPIF	0000 0000	13, 90	
8Ch	PIE1	EEIE	ADIE	CCP1IE	_	CMIE	OSFIE	TMR2IE	TMR1IE	000- 0000	14, 90	
8Dh		Unimpleme		—								
8Eh	PCON	_	_	ULPWUE	SBOREN	_	—	POR	BOR	01qq	16, 90	
8Fh	OSCCON		IRCF2	IRCF1	IRCF0	OSTS ⁽²⁾	HTS	LTS	SCS	-110 x000	20, 90	
90h	OSCTUNE	—	—	_	TUN4	TUN3	TUN2	TUN1	TUN0	0 0000	24, 90	
91h	_	Unimpleme	ented							—	—	
92h	PR2	Timer2 Mo	dule Period	Register						1111 1111	49, 90	
93h	_	Unimpleme	ented							—		
94h		Unimpleme	ented							—		
95h	WPU ⁽³⁾	—	—	WPU5	WPU4	_	WPU2	WPU1	WPU0	11 -111	34, 90	
96h	IOC	—	—	IOC5	IOC4	IOC3	IOC2	IOC1	IOC0	00 0000	34, 90	
97h	_	Unimpleme	ented							—		
98h	_	Unimpleme	ented							_	—	
99h	VRCON	VREN	—	VRR	—	VR3	VR2	VR1	VR0	0-0- 0000	58, 90	
9Ah	EEDAT	EEDAT7	EEDAT6	EEDAT5	EEDAT4	EEDAT3	EEDAT2	EEDAT1	EEDAT0	0000 0000	71, 90	
9Bh	EEADR	EEADR7	EEADR6	EEADR5	EEADR4	EEADR3	EEADR2	EEADR1	EEADR0	0000 0000	71, 90	
9Ch	EECON1	—	_	—	—	WRERR	WREN	WR	RD	x000	72, 91	
9Dh	EECON2				a physical						72, 91	
9Eh	ADRESL	Least Sign		s of the left	shifted resu	lt or 8 bits o	of the right s	shifted resu	lt	xxxx xxxx	66, 91	
9Fh	ANSEL	_	ADCS2	ADCS1	ADCS0	ANS3	ANS2	ANS1	ANS0	-000 1111	33, 91	

TABLE 2-2: PIC12F683 SPECIAL FUNCTION REGISTERS SUMMARY BANK 1

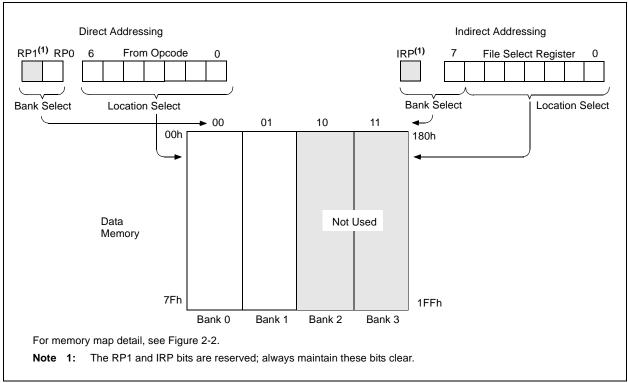
Legend: -= unimplemented locations read as '0', u = unchanged, x = unknown, q = value depends on condition, shaded = unimplemented

Note 1: IRP and RP1 bits are reserved, always maintain these bits clear.

2: OSTS bit of the OSCCON register reset to '0' with Dual Speed Start-up and LP, HS or XT selected as the oscillator.

3: GP3 pull-up is enabled when MCLRE is '1' in the Configuration Word register.





3.5.2.1 OSCTUNE Register

The HFINTOSC is factory calibrated but can be adjusted in software by writing to the OSCTUNE register (Register 3-2).

The default value of the OSCTUNE register is '0'. The value is a 5-bit two's complement number.

When the OSCTUNE register is modified, the HFINTOSC frequency will begin shifting to the new frequency. Code execution continues during this shift. There is no indication that the shift has occurred.

OSCTUNE does not affect the LFINTOSC frequency. Operation of features that depend on the LFINTOSC clock source frequency, such as the Power-up Timer (PWRT), Watchdog Timer (WDT), Fail-Safe Clock Monitor (FSCM) and peripherals, are *not* affected by the change in frequency.

REGISTER 3-2: OSCTUNE: OSCILLATOR TUNING REGISTER

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_	—	TUN4	TUN3	TUN3 TUN2		TUN0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5	Unimplemented: Read as '0'						
bit 4-0	TUN<4:0>: Frequency Tuning bits						
	01111 = Maximum frequency						
	01110 =						
	•						
	•						
	•						
	00001 =						
	00000 = Oscillator module is running at the calibrated frequency.						
	11111 =						
	•						
	•						
	•						
	10000 = Minimum frequency						

PIC12F683

4.2.5.6 GP5/T1CKI/OSC1/CLKIN

Figure 4-6 shows the diagram for this pin. The GP5 pin is configurable to function as one of the following:

- a general purpose I/O
- a Timer1 clock input
- a crystal/resonator connection
- a clock input

FIGURE 4-6:

BLOCK DIAGRAM OF GP5

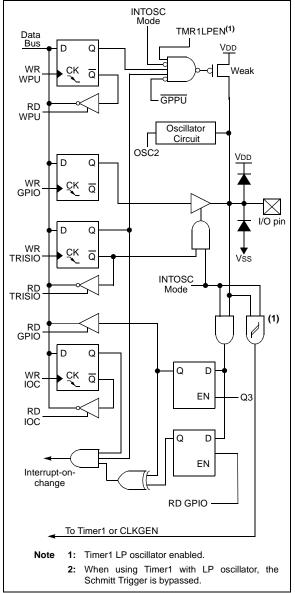


TABLE 4-1: SUMMARY OF REGISTERS ASSOCIATED WITH GPIO

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSEL	_	ADCS2	ADCS1	ADCS0	ANS3	ANS2	ANS1	ANS0	-000 1111	-000 1111
CCP1CON	_	_	DC1B1	DC1B0	CCP1M3	CCP1M2	CCP1M1	CCP1M0	00 0000	00 0000
CMCON0	_	COUT	_	CINV	CIS	CM2	CM1	CM0	-0-0 0000	-0-0 0000
PCON	_	_	ULPWUE	SBOREN	_	_	POR	BOR	01qq	0uuu
INTCON	GIE	PEIE	TOIE	INTE	GPIE	T0IF	INTF	GPIF	0000 0000	0000 000x
IOC	_	_	IOC5	IOC4	IOC3	IOC2	IOC1	IOC0	00 0000	00 0000
OPTION_REG	GPPU	INTEDG	TOCS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111
GPIO	_	_	GP5	GP4	GP3	GP2	GP1	GP0	xx xxxx	x0 x000
T1CON	T1GINV	TMR1GE	T1CKPS1	T1CKPS0	T1OSCEN	T1SYNC	TMR1CS	TMR10N	0000 0000	0000 0000
TRISIO	_	_	TRISIO5	TRISIO4	TRISIO3	TRISIO2	TRISIO1	TRISIO0	11 1111	11 1111
WPU	_	_	WPU5	WPU4	_	WPU2	WPU1	WPU0	11 -111	11 -111

Legend: x = unknown, u = unchanged, - = unimplemented locations read as '0'. Shaded cells are not used by GPIO.

6.0 TIMER1 MODULE WITH GATE CONTROL

The Timer1 module is a 16-bit timer/counter with the following features:

- 16-bit timer/counter register pair (TMR1H:TMR1L)
- · Programmable internal or external clock source
- 3-bit prescaler
- Optional LP oscillator
- · Synchronous or asynchronous operation
- Timer1 gate (count enable) via comparator or T1G pin
- Interrupt on overflow
- Wake-up on overflow (external clock, Asynchronous mode only)
- Special Event Trigger (with CCP)
- Comparator output synchronization to Timer1 clock

Figure 6-1 is a block diagram of the Timer1 module.

FIGURE 6-1: TIMER1 BLOCK DIAGRAM

6.1 Timer1 Operation

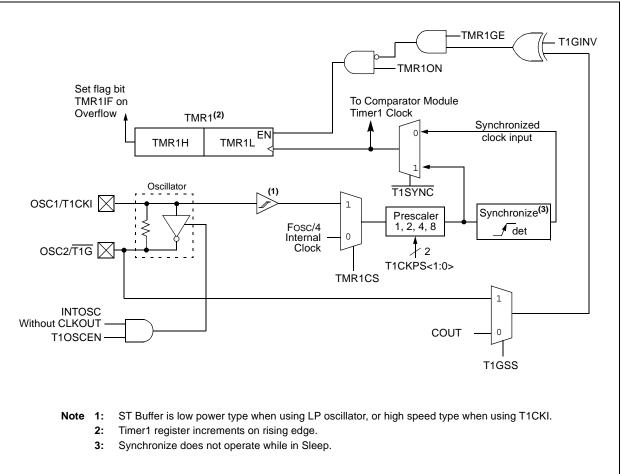
The Timer1 module is a 16-bit incrementing counter which is accessed through the TMR1H:TMR1L register pair. Writes to TMR1H or TMR1L directly update the counter.

When used with an internal clock source, the module is a timer. When used with an external clock source, the module can be used as either a timer or counter.

6.2 Clock Source Selection

The TMR1CS bit of the T1CON register is used to select the clock source. When TMR1CS = 0, the clock source is FOSC/4. When TMR1CS = 1, the clock source is supplied externally.

Clock Source	TMR1CS
Fosc/4	0
T1CKI pin	1



8.0 COMPARATOR MODULE

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. The comparators are very useful mixed signal building blocks because they provide analog functionality independent of the program execution. The analog comparator module includes the following features:

- Multiple comparator configurations
- · Comparator output is available internally/externally
- Programmable output polarity
- Interrupt-on-change
- Wake-up from Sleep
- Timer1 gate (count enable)
- Output synchronization to Timer1 clock input
- Programmable voltage reference

8.1 Comparator Overview

The comparator is shown in Figure 8-1 along with the relationship between the analog input levels and the digital output. When the analog voltage at VIN+ is less than the analog voltage at VIN-, the output of the comparator is a digital low level. When the analog voltage at VIN+ is greater than the analog voltage at VIN-, the output of the comparator is a digital high level.



SINGLE COMPARATOR

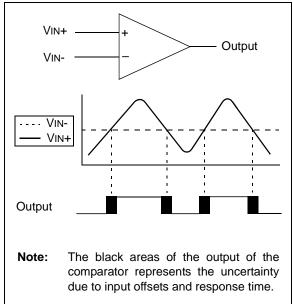
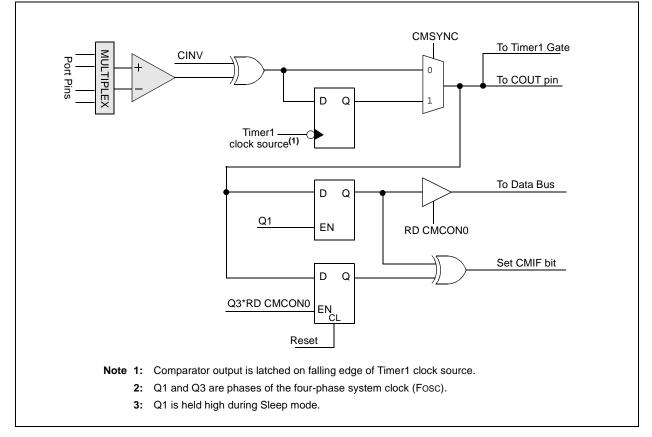


FIGURE 8-2: COMPARATOR OUTPUT BLOCK DIAGRAM



8.7 Operation During Sleep

The comparator, if enabled before entering Sleep mode, remains active during Sleep. The additional current consumed by the comparator is shown separately in **Section 15.0** "**Electrical Specifications**". If the comparator is not used to wake the device, power consumption can be minimized while in Sleep mode by turning off the comparator. The comparator is turned off by selecting mode CM<2:0> = 000 or CM<2:0> = 111 of the CMCON0 register.

A change to the comparator output can wake-up the device from Sleep. To enable the comparator to wake the device from Sleep, the CMIE bit of the PIE1 register and the PEIE bit of the INTCON register must be set. The instruction following the Sleep instruction always executes following a wake from Sleep. If the GIE bit of the INTCON register is also set, the device will then execute the Interrupt Service Routine.

8.8 Effects of a Reset

A device Reset forces the CMCON0 and CMCON1 registers to their Reset states. This forces the Comparator module to be in the Comparator Reset mode (CM<2:0> = 000). Thus, all comparator inputs are analog inputs with the comparator disabled to consume the smallest current possible.

REGISTER 8-1: CMCON0: COMPARATOR CONFIGURATION REGISTER

U-0	R-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
_	COUT	—	CINV	CIS	CM2	CM1	CM0				
bit 7							bit 0				
Legend:											
R = Readable		W = Writable bit	t	•	nted bit, read as						
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cleare	ed	x = Bit is unknow	wn				
bit 7	Unimplement	ed: Read as '0'									
bit 6	COUT: Compa When CINV = 1 = VIN+ > VIN 0 = VIN+ < VIN	- - <u>1:</u> -									
bit 5	Unimplement	Unimplemented: Read as '0'									
bit 4	CINV: Compar 1 = Output invo 0 = Output not		on bit								
bit 3	$\frac{\text{When CM} < 2:0}{1 = \text{CIN} + \text{conn}}$ $0 = \text{CIN} - \text{conn}$	ects to VIN- > = <u>0xx</u> or <u>100 or</u>									
bit 2-0	000 = CIN pins 001 = CIN pins 010 = CIN pins 011 = CIN- pin Compar 100 = CIN- pin available 101 = CIN pins Compar 110 = CIN pins Compar	nparator Mode bits s are configured as s are configured as n is configured as a ator output, CVREF n is configured as a e internally, CVREF s are configured as rator output, CVREF s are configured as rator output, CVREF s are configured as a as a configured as	analog, COUT p analog, COUT p analog, COUT p nalog, CIN+ pin is non-inverting nalog, CIN+ pin is non-inverting analog and mul- is non-inverting analog and mul- analog and mul-	bin configured as I/ bin configured as C bin configured as I/ is configured as I/C input is configured as I/C input tiplexed, COUT pir input tiplexed, COUT pir REF is non-inverting	Comparator outpu (O, Comparator o D, COUT pin conf D, COUT pin is co n is configured as n is configured as g input	t utput available inte igured as onfigured as I/O, Co I/O,	omparator output				



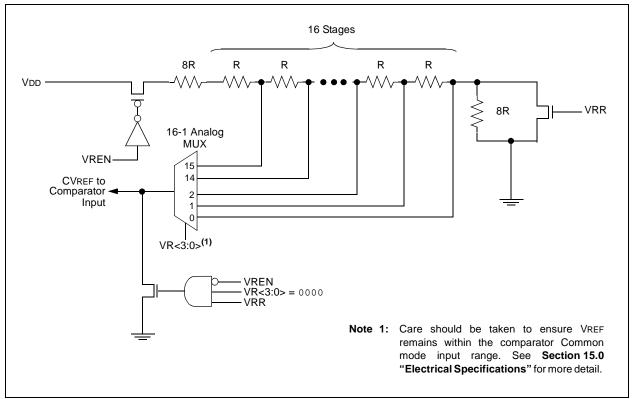


TABLE 8-2:SUMMARY OF REGISTERS ASSOCIATED WITH THE COMPARATOR AND VOLTAGE
REFERENCE MODULES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other Resets
ANSEL		ADCS2	ADCS1	ADCS0	ANS3	ANS2	ANS1	ANS0	-000 1111	-000 1111
CMCON0	_	COUT	—	CINV	CIS	CM2	CM1	CM0	-0-0 0000	-0-0 0000
CMCON1	_	_	—	—	—	_	T1GSS	CMSYNC	10	10
INTCON	GIE	PEIE	TOIE	INTE	GPIE	T0IF	INTF	GPIF	0000 0000	0000 000x
PIE1	EEIE	ADIE	CCP1IE	—	CMIE	OSFIE	TMR2IE	TMR1IE	000- 0000	0000 0000
PIR1	EEIF	ADIF	CCP1IF	—	CMIF	OSFIF	TMR2IF	TMR1IF	000- 0000	000- 0000
GPIO	_	_	GP5	GP4	GP3	GP2	GP1	GP0	xx xxxx	uu uuuu
TRISIO			TRISIO5	TRISIO4	TRISIO3	TRISIO2	TRISIO1	TRISIO0	11 1111	11 1111
VRCON	VREN		VRR	_	VR3	VR2	VR1	VR0	0-0- 0000	-0-0 0000

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0'. Shaded cells are not used for comparator.

R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0		
ADFM	VCFG	_	_	CHS1	CHS0	GO/DONE	ADON		
bit 7							bit 0		
Legend:									
R = Readable bit W = Writable bit				U = Unimpler	mented bit, read	d as '0'			
-n = Value at F	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown		
bit 7 ADFM: A/D Conversion Result Format Select bit 1 = Right justified 0 = Left justified									
bit 6	VCFG: Voltage Reference bit 1 = VREF pin 0 = VDD								
bit 5-4	Unimplemen	ted: Read as '	0'						
bit 3-2	CHS<1:0>: A	nalog Channe	el Select bits						
	00 = AN0 01 = AN1 10 = AN2 11 = AN3								
bit 1		/D Conversion							
	 1 = A/D conversion cycle in progress. Setting this bit starts an A/D conversion cycle. This bit is automatically cleared by hardware when the A/D conversion has completed. 0 = A/D conversion completed/not in progress 								
bit 0	 0 = A/D conversion completed/not in progress ADON: ADC Enable bit 1 = ADC is enabled 0 = ADC is disabled and consumes no operating current 								

REGISTER 9-1: ADCON0: A/D CONTROL REGISTER 0

12.3.1 POWER-ON RESET

The on-chip POR circuit holds the chip in Reset until VDD has reached a high enough level for proper operation. To take advantage of the POR, simply connect the MCLR pin through a resistor to VDD. This will eliminate external RC components usually needed to create Power-on Reset. A maximum rise time for VDD is required. See **Section 15.0** "**Electrical Specifications**" for details. If the BOR is enabled, the maximum rise time specification does not apply. The BOR circuitry will keep the device in Reset until VDD reaches VBOD (see **Section 12.3.4** "**Brown-Out Reset (BOR)**").

Note: The POR circuit does not produce an internal Reset when VDD declines. To re-enable the POR, VDD must reach Vss for a minimum of 100 μs.

When the device starts normal operation (exits the Reset condition), device operating parameters (i.e., voltage, frequency, temperature, etc.) must be met to ensure operation. If these conditions are not met, the device must be held in Reset until the operating conditions are met.

For additional information, refer to the Application Note *AN607, "Power-up Trouble Shooting"* (DS00607).

12.3.2 MCLR

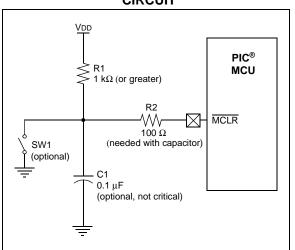
PIC12F683 has a noise filter in the $\overline{\text{MCLR}}$ Reset path. The filter will detect and ignore small pulses.

It should be noted that a WDT Reset does not drive $\overline{\text{MCLR}}$ pin low.

Voltages applied to the MCLR pin that exceed its specification can result in both MCLR Resets and excessive current beyond the device specification during the ESD event. For this reason, Microchip recommends that the MCLR pin no longer be tied directly to VDD. The use of an RC network, as shown in Figure 12-2, is suggested.

An internal $\overline{\text{MCLR}}$ option is enabled by clearing the $\overline{\text{MCLRE}}$ bit in the Configuration Word register. When $\overline{\text{MCLRE}} = 0$, the Reset signal to the chip is generated internally. When the $\overline{\text{MCLRE}} = 1$, the GP3/ $\overline{\text{MCLR}}$ pin becomes an external Reset input. In this mode, the GP3/ $\overline{\text{MCLR}}$ pin has a weak pull-up to VDD.

FIGURE 12-2: RECOMMENDED MCLR CIRCUIT



12.3.3 POWER-UP TIMER (PWRT)

The Power-up Timer provides a fixed 64 ms (nominal) time-out on power-up only, from POR or Brown-out Reset. The Power-up Timer operates from the 31 kHz LFINTOSC oscillator. For more information, see **Section 3.5 "Internal Clock Modes"**. The chip is kept in Reset as long as PWRT is active. The PWRT delay allows the VDD to rise to an acceptable level. A Configuration bit, PWRTE, can disable (if set) or enable (if cleared or programmed) the Power-up Timer. The Power-up Timer should be enabled when Brown-out Reset is enabled, although it is not required.

The Power-up Timer delay will vary from chip-to-chip due to:

- VDD variation
- Temperature variation
- Process variation

See DC parameters for details (Section 15.0 "Electrical Specifications").

Note: Voltage spikes below Vss at the $\overline{\text{MCLR}}$ pin, inducing currents greater than 80 mA, may cause latch-up. Thus, a series resistor of 50-100 Ω should be used when applying a "low" level to the $\overline{\text{MCLR}}$ pin, rather than pulling this pin directly to Vss.

14.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers are supported with a full range of hardware and software development tools:

- Integrated Development Environment
 - MPLAB[®] IDE Software
- Assemblers/Compilers/Linkers
 - MPASM[™] Assembler
 - MPLAB C18 and MPLAB C30 C Compilers
 - MPLINK[™] Object Linker/
 - MPLIB[™] Object Librarian
 - MPLAB ASM30 Assembler/Linker/Library
- Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB ICE 2000 In-Circuit Emulator
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debugger
 - MPLAB ICD 2
- Device Programmers
 - PICSTART[®] Plus Development Programmer
 - MPLAB PM3 Device Programmer
 - PICkit[™] 2 Development Programmer
- Low-Cost Demonstration and Development Boards and Evaluation Kits

14.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16-bit microcontroller market. The MPLAB IDE is a Windows[®] operating system-based application that contains:

- · A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- · A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Visual device initializer for easy register initialization
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as HI-TECH Software C Compilers and IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either assembly or C)
- One touch assemble (or compile) and download to PIC MCU emulator and simulator tools (automatically updates all project information)
- Debug using:
 - Source files (assembly or C)
 - Mixed assembly and C
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

15.2 DC Characteristics: PIC12F683-I (Industrial) PIC12F683-E (Extended)

DC CHA	ARACTERISTICS		ard Oper ing temp		-40°C ≤	≤ TA ≤ +8	s otherwise stated) 35°C for industrial 125°C for extended
Param	Device Characteristics	Min	Тур†	Max	Units		Conditions
No.			-71-1			Vdd	Note
D010	Supply Current (IDD) ^(1, 2)	_	11	16	μA	2.0	Fosc = 32 kHz
		_	18	28	μA	3.0	LP Oscillator mode
		_	35	54	μA	5.0	
D011*		_	140	240	μA	2.0	Fosc = 1 MHz
			220	380	μA	3.0	XT Oscillator mode
		_	380	550	μΑ	5.0	
D012		_	260	360	μA	2.0	Fosc = 4 MHz
			420	650	μA	3.0	XT Oscillator mode
		_	0.8	1.1	mA	5.0	
D013*		_	130	220	μA	2.0	Fosc = 1 MHz
		_	215	360	μA	3.0	EC Oscillator mode
		_	360	520	μA	5.0	
D014		_	220	340	μA	2.0	Fosc = 4 MHz
		_	375	550	μA	3.0	EC Oscillator mode
		_	0.65	1.0	mA	5.0	
D015		—	8	20	μA	2.0	Fosc = 31 kHz
		_	16	40	μA	3.0	LFINTOSC mode
		_	31	65	μA	5.0	
D016*		—	340	450	μΑ	2.0	Fosc = 4 MHz
		_	500	700	μΑ	3.0	HFINTOSC mode
		—	0.8	1.2	mA	5.0	
D017		—	410	650	μA	2.0	Fosc = 8 MHz
		—	700	950	μA	3.0	HFINTOSC mode
		_	1.30	1.65	mA	5.0	
D018		—	230	400	μA	2.0	FOSC = 4 MHz
		—	400	680	μA	3.0	EXTRC mode ⁽³⁾
			0.63	1.1	mA	5.0	
D019		—	2.6	3.25	mA	4.5	Fosc = 20 MHz
		—	2.8	3.35	mA	5.0	HS Oscillator mode

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: The test conditions for all IDD measurements in active operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to VDD; MCLR = VDD; WDT disabled.

2: The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.

3: For RC oscillator configurations, current through REXT is not included. The current through the resistor can be extended by the formula IR = VDD/2REXT (mA) with REXT in kΩ.

15.5	DC Characteristics:	PIC12F683-I (Industrial)		
		PIC12F683-E (Extended)		

DC CHARACTERISTICS			Standard Operating Conditions (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for extended						
Param No.	Sym Characteristic		Min	Тур†	Мах	Units	Conditions		
	VIL	Input Low Voltage							
		I/O Port:							
D030		with TTL buffer	Vss	—	0.8	V	$4.5V \le VDD \le 5.5V$		
D030A			Vss	—	0.15 Vdd	V	$2.0V \le VDD \le 4.5V$		
D031		with Schmitt Trigger buffer	Vss	—	0.2 Vdd	V	$2.0V \le VDD \le 5.5V$		
D032		MCLR, OSC1 (RC mode) ⁽¹⁾	Vss	—	0.2 Vdd	V			
D033		OSC1 (XT and LP modes)	Vss	—	0.3	V			
D033A		OSC1 (HS mode) Vss		—	0.3 Vdd	V			
	Vih	Input High Voltage							
		I/O ports:		—					
D040		with TTL buffer	2.0	—	Vdd	V	$4.5V \le VDD \le 5.5V$		
D040A			0.25 VDD + 0.8	—	Vdd	V	$2.0V \le VDD \le 4.5V$		
D041		with Schmitt Trigger buffer	0.8 Vdd	—	Vdd	V	$2.0V \le VDD \le 5.5V$		
D042		MCLR	0.8 Vdd	—	Vdd	V			
D043		OSC1 (XT and LP modes)	1.6	—	Vdd	V			
D043A		OSC1 (HS mode)	0.7 Vdd	—	Vdd	V			
D043B		OSC1 (RC mode)	0.9 Vdd	—	Vdd	V	(Note 1)		
	lı∟	Input Leakage Current ⁽²⁾							
D060		I/O ports	_	±0.1	± 1	μA	Vss ≤ VPIN ≤ VDD, Pin at high-impedance		
D061		MCLR ⁽³⁾	—	± 0.1	± 5	μA	$VSS \leq VPIN \leq VDD$		
D063		OSC1	—	± 0.1	± 5	μA	Vss \leq VPIN \leq VDD, XT, HS and LP oscillator configuration		
D070*	Ipur	GPIO Weak Pull-up Current	50	250	400	μA	VDD = 5.0V, VPIN = VSS		
VoL Outp		Output Low Voltage ⁽⁵⁾							
D080		I/O ports	—		0.6	V	IOL = 8.5 mA, VDD = 4.5V (Ind.)		
	Vон	Output High Voltage ⁽⁵⁾							
D090		I/O ports	Vdd - 0.7	—	—	V	IOH = -3.0 mA, VDD = 4.5V (Ind.)		

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.

2: Negative current is defined as current sourced by the pin.

3: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

4: See Section 10.4.1 "Using the Data EEPROM" for additional information.

5: Including OSC2 in CLKOUT mode.

15.5 DC Characteristics: PIC12F683-I (Industrial) PIC12F683-E (Extended) (Continued)

DC CH	ARACTE	RISTICS	Standard Operating Conditions (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for extended					
Param No.	Sym	Characteristic	Min	Тур†	Max	Units	Conditions	
D100	IULP	Ultra Low-Power Wake-Up Current	_	200	_	nA	See Application Note AN879, "Using the Microchip Ultra Low-Power Wake-up Module" (DS00879)	
		Capacitive Loading Specs on Output Pins						
D101*	COSC2	OSC2 pin	_	-	15	pF	In XT, HS and LP modes when external clock is used to drive OSC1	
D101A*	Сю	All I/O pins	_	—	50	pF		
		Data EEPROM Memory						
D120	ED	Byte Endurance	100K	1M	_	E/W	$-40^{\circ}C \le TA \le +85^{\circ}C$	
D120A	ED	Byte Endurance	10K	100K	_	E/W	+85°C ≤ TA ≤ +125°C	
D121	Vdrw	VDD for Read/Write	VMIN	-	5.5	V	Using EECON1 to read/write VMIN = Minimum operating voltage	
D122	TDEW	Erase/Write Cycle Time	_	5	6	ms		
D123	Tretd	Characteristic Retention	40	—	—	Year	Provided no other specifications are violated	
D124	Tref	Number of Total Erase/Write Cycles before Refresh ⁽⁴⁾	1M	10M	—	E/W	$-40^{\circ}C \le TA \le +85^{\circ}C$	
		Program Flash Memory						
D130	Eр	Cell Endurance	10K	100K	—	E/W	-40°C ≤ TA ≤ +85°C	
D130A	ED	Cell Endurance	1K	10K	—	E/W	+85°C ≤ TA ≤ +125°C	
D131	Vpr	VDD for Read	VMIN	-	5.5	V	VMIN = Minimum operating voltage	
D132	VPEW	VDD for Erase/Write	4.5		5.5	V		
D133	TPEW	Erase/Write cycle time	—	2	2.5	ms		
D134	Tretd	Characteristic Retention	40	—	—	Year	Provided no other specifications are violated	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: In RC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended to use an external clock in RC mode.

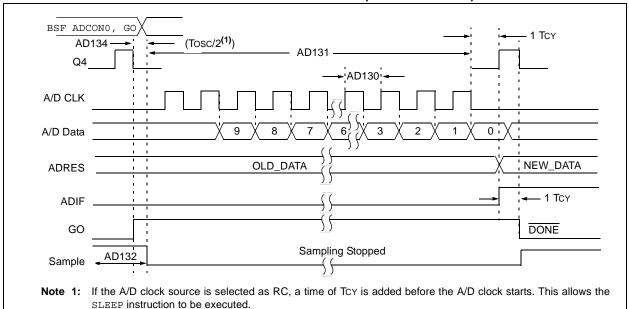
2: Negative current is defined as current sourced by the pin.

3: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

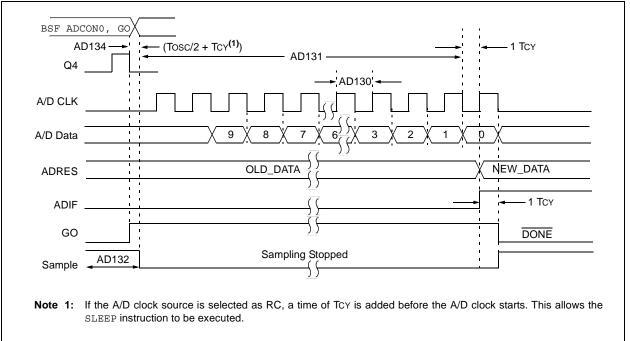
4: See Section 10.4.1 "Using the Data EEPROM" for additional information.

5: Including OSC2 in CLKOUT mode.









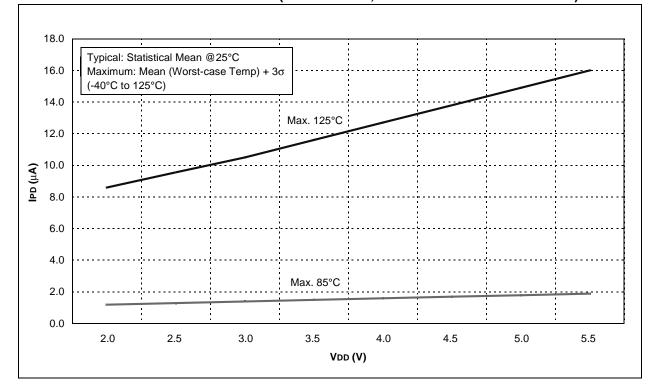
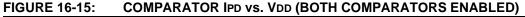
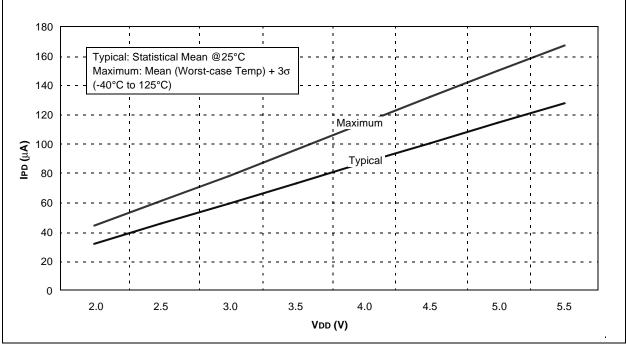


FIGURE 16-14: MAXIMUM IPD vs. VDD (SLEEP MODE, ALL PERIPHERALS DISABLED)





17.0 PACKAGING INFORMATION

17.1 Package Marking Information

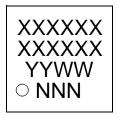
8-Lead PDIP



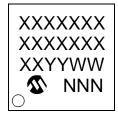
8-Lead SOIC (3.90 mm)



8-Lead DFN (4x4x0.9 mm)



8-Lead DFN-S (6x5 mm)



Example



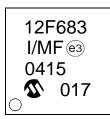
Example



Example



Example



Legend:	XXX Y YY WW NNN @3 *	Customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code Pb-free JEDEC designator for Matte Tin (Sn) This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.
	In the event the full Microchip part number cannot be marked on one line, it w be carried over to the next line, thus limiting the number of availab characters for customer-specific information.	

* Standard PIC[®] device marking consists of Microchip part number, year code, week code and traceability code. For PIC device marking beyond this, certain price adders apply. Please check with your Microchip Sales Office. For QTP devices, any special marking adders are included in QTP price.

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