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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	3840
Number of Logic Elements/Cells	38400
Total RAM Bits	327680
Number of I/O	488
Number of Gates	1772000
Voltage - Supply	1.71V ~ 1.89V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	652-BGA
Supplier Device Package	652-BGA (45x45)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep20k1000cb652c8n

APEX 20KC devices include additional features such as enhanced I/O standard support, CAM, additional global clocks, and enhanced ClockLock clock circuitry. Table 7 shows the features included in APEX 20KC devices.

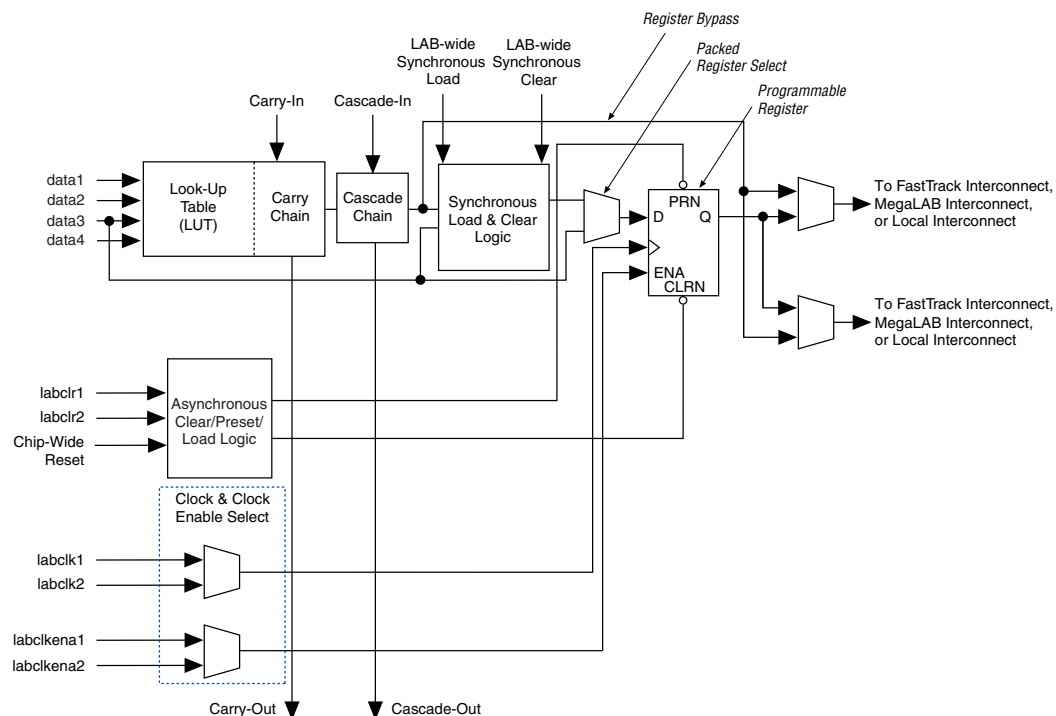
Table 7. APEX 20KC Device Features (Part 1 of 2)	
Feature	APEX 20KC Devices
MultiCore system integration	Full support
Hot-socketing support	Full support
SignalTap logic analysis	Full support
32-/64-bit, 33-MHz PCI	Full compliance
32-/64-bit, 66-MHz PCI	Full compliance in -7 and -8 speed grades in selected devices
MultiVolt I/O	1.8-V, 2.5-V, or 3.3-V V_{CCIO} V_{CCIO} selected bank by bank 5.0-V tolerant with use of external resistor
ClockLock support	Clock delay reduction $m/(n \times v)$ clock multiplication Drive ClockLock output off-chip External clock feedback ClockShift circuitry LVDS support Up to four PLLs ClockShift clock phase adjustment
Dedicated clock and input pins	Eight

Table 7. APEX 20KC Device Features (Part 2 of 2)

Feature	APEX 20KC Devices
I/O standard support	1.8-V, 2.5-V, 3.3-V, 5.0-V I/O 3.3-V PCI and PCI-X 3.3-V AGP CTT GTL+ LVCMOS LVTTTL True-LVDS™ and LVPECL data pins (in EP20K400C and larger devices) LVDS and LVPECL clock pins (in all devices) LVDS and LVPECL data pins up to 156 Mbps (in EP20K200C devices) HSTL Class I PCI-X SSTL-2 Class I and II SSTL-3 Class I and II
Memory support	CAM Dual-port RAM FIFO RAM ROM

All APEX 20KC devices are reconfigurable and are 100% tested prior to shipment. As a result, test vectors do not have to be generated for fault-coverage purposes. Instead, the designer can focus on simulation and design verification. In addition, the designer does not need to manage inventories of different application-specific integrated circuit (ASIC) designs; APEX 20KC devices can be configured on the board for the specific functionality required.

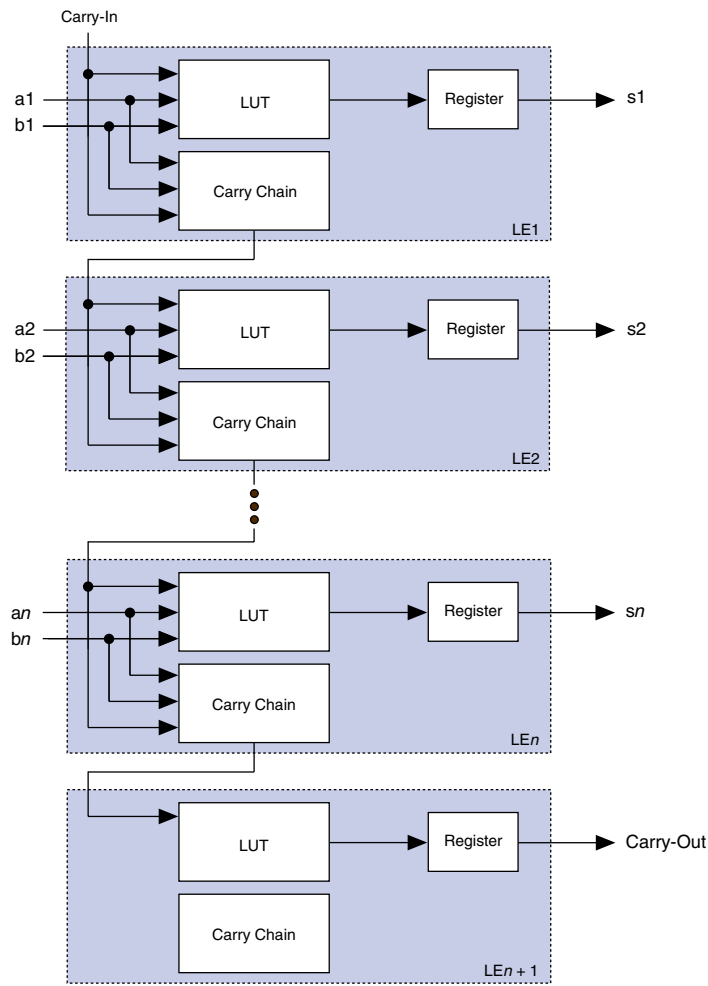
APEX 20KC devices are configured at system power-up with data stored in an Altera serial configuration device or provided by a system controller. Altera offers in-system programmability (ISP)-capable EPC16, EPC8, EPC4, EPC2, and EPC1 configuration devices and one-time programmable (OTP) EPC1 configuration devices, which configure APEX 20KC devices via a serial data stream. Moreover, APEX 20KC devices contain an optimized interface that permits microprocessors to configure APEX 20KC devices serially or in parallel, and synchronously or asynchronously. The interface also enables microprocessors to treat APEX 20KC devices as memory and configure the device by writing to a virtual memory location, making reconfiguration easy.

Figure 5. APEX 20KC Logic Element


Each LE's programmable register can be configured for D, T, JK, or SR operation. The register's clock and clear control signals can be driven by global signals, general-purpose I/O pins, or any internal logic. For combinational functions, the register is bypassed and the output of the LUT drives the outputs of the LE.

Each LE has two outputs that drive the local, MegaLAB, or FastTrack interconnect routing structure. Each output can be driven independently by the LUT's or register's output. For example, the LUT can drive one output while the register drives the other output. This feature, called register packing, improves device utilization because the register and the LUT can be used for unrelated functions. The LE can also drive out registered and unregistered versions of the LUT output.

Figure 6. APEX 20KC Carry Chain



LE Operating Modes

The APEX 20KC LE can operate in one of the following three modes:

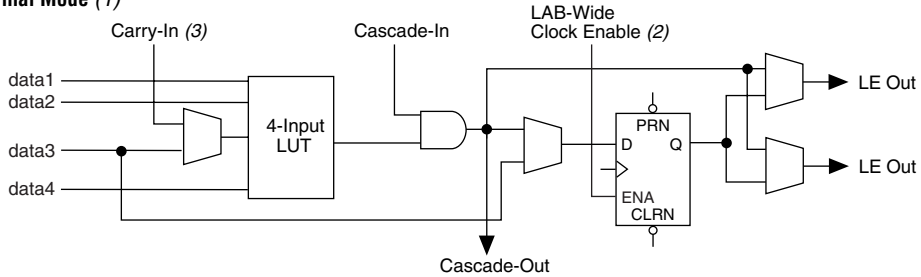
- Normal mode
- Arithmetic mode
- Counter mode

Each mode uses LE resources differently. In each mode, seven available inputs to the LE—the four data inputs from the LAB local interconnect, the feedback from the programmable register, and the carry-in and cascade-in from the previous LE—are directed to different destinations to implement the desired logic function. LAB-wide signals provide clock, asynchronous clear, asynchronous preset, asynchronous load, synchronous clear, synchronous load, and clock enable control for the register. These LAB-wide signals are available in all LE modes.

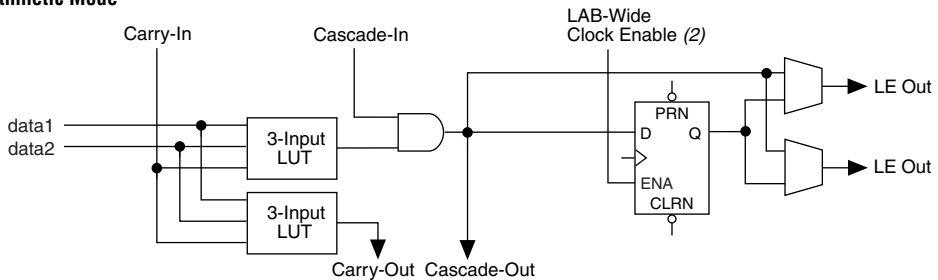
The Quartus II software, in conjunction with parameterized functions such as LPM and DesignWare functions, automatically chooses the appropriate mode for common functions such as counters, adders, and multipliers. If required, the designer can also create special-purpose functions that specify which LE operating mode to use for optimal performance. [Figure 8](#) shows the LE operating modes.

Figure 8. APEX 20KC LE Operating Modes

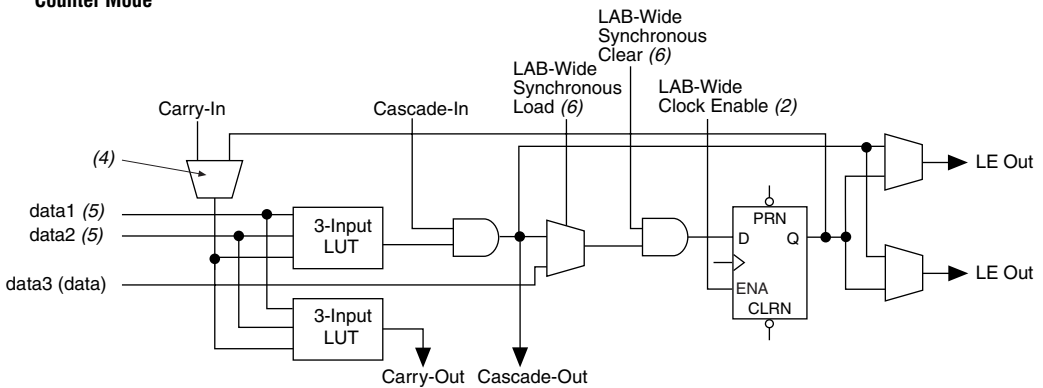
Normal Mode (1)



Arithmetic Mode



Counter Mode

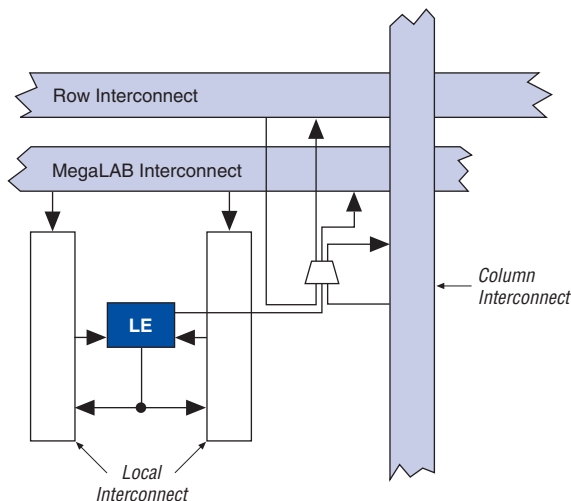


Notes to Figure 8:

- (1) LEs in normal mode support register packing.
- (2) There are two LAB-wide clock enables per LAB.
- (3) When using the carry-in in normal mode, the packed register feature is unavailable.
- (4) A register feedback multiplexer is available on LE1 of each LAB.
- (5) The DATA1 and DATA2 input signals can supply counter enable, up or down control, or register feedback signals for LEs other than the second LE in an LAB.
- (6) The LAB-wide synchronous clear and LAB wide synchronous load affect all registers in an LAB.

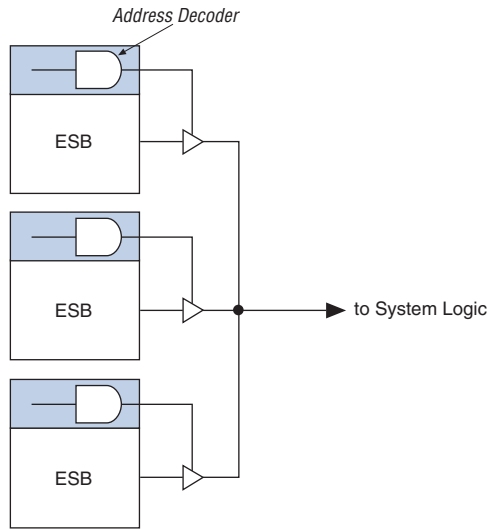
Figure 11 shows the intersection of a row and column interconnect, and how these forms of interconnects and LEs drive each other.

Figure 11. Driving the FastTrack Interconnect



APEX 20KC devices include an enhanced interconnect structure for faster routing of input signals with high fan-out. Column I/O pins can drive the FastRow™ interconnect, which routes signals directly into the local interconnect without having to drive through the MegaLAB interconnect. The FastRow lines traverse two MegaLAB structures. Also, these pins can drive the local interconnect directly for fast setup times. On EP20K400C and larger devices, the FastRow interconnect drives the two MegaLAB structures in the top left corner, the two MegaLAB structures in the two right corner, the two MegaLAB structures in the bottom left corner, and the two MegaLAB structures in the bottom right corner. On EP20K200C and smaller devices, FastRow interconnect drives the two MegaLAB structures on the top and the two MegaLAB structures on the bottom of the device. On all devices, the FastRow interconnect drives all local interconnect in the appropriate MegaLAB structures except the end local interconnect on the side of the MegaLAB opposite the ESB. Pins using the FastRow interconnect achieve a faster set-up time, as the signal does not need to use a MegaLAB interconnect line to reach the destination LE. Figure 12 shows the FastRow interconnect.

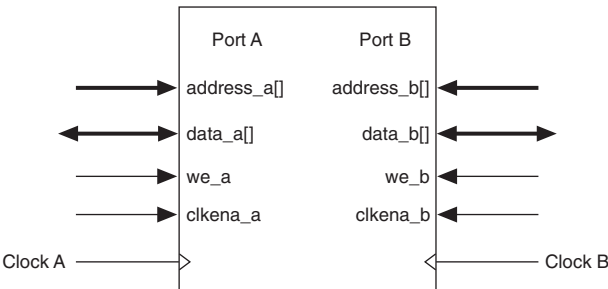
Figure 18. Deep Memory Block Implemented with Multiple ESBs



The ESB implements two forms of dual-port memory: read/write clock mode and input/output clock mode. The ESB can also be used for bidirectional, dual-port memory applications in which two ports read or write simultaneously. To implement this type of dual-port memory, two ESBs are used to support two simultaneous reads or writes.

The ESB can also use Altera megafunctions to implement dual-port RAM applications where both ports can read or write, as shown in [Figure 19](#).

Figure 19. APEX 20KC ESB Implementing Dual-Port RAM



Advanced I/O Standard Support

APEX 20KC IOEs support the following I/O standards: LVTTTL, LVCMOS, 1.8-V I/O, 2.5-V I/O, 3.3-V PCI, PCI-X, 3.3-V AGP, LVDS, LVPECL, GTL+, CTT, HSTL Class I, SSTL-3 Class I and II, and SSTL-2 Class I and II.



For more information on I/O standards supported by APEX 20KC devices, see *Application Note 117 (Using Selectable I/O Standards in Altera Devices)*.

The APEX 20KC device contains eight I/O banks. In QFP packages, the banks are linked to form four I/O banks. The I/O banks directly support all standards except LVDS and LVPECL. All I/O banks can support LVDS and LVPECL at up to 156 Mbps per channel with the addition of external resistors. In addition, one block within a bank contains circuitry to support high-speed True-LVDS and LVPECL inputs, and another block within a bank supports high-speed True-LVDS and LVPECL outputs. The LVDS blocks support all of the I/O standards. Each I/O bank has its own VCCIO pins. A single device can support 1.8-V, 2.5-V, and 3.3-V interfaces; each bank can support a different standard independently. Each bank can also use a separate V_{REF} level so that each bank can support any of the terminated standards (such as SSTL-3) independently. Within a bank, any one of the terminated standards can be supported. EP20K400C and larger APEX 20KC devices support the LVDS interface for data pins (EP20K200C devices support LVDS clock pins, but not data pins). EP20K400C and EP20K600C devices support LVDS for data pins at up to 840 Mbps per channel. EP20K1000C devices support LVDS on 16 channels at up to 750 Mbps.

Each bank can support multiple standards with the same VCCIO for output pins. Each bank can support one voltage-referenced I/O standard, but it can support multiple I/O standards with the same VCCIO voltage level. For example, when VCCIO is 3.3 V, a bank can support LVTTTL, LVCMOS, 3.3-V PCI, and SSTL-3 for inputs and outputs.

When the LVDS banks are not used for the LVDS I/O standard, they support all of the other I/O standards. [Figure 28](#) shows the arrangement of the APEX 20KC I/O banks.

ClockLock & ClockBoost Features

Open-drain output pins on APEX 20KC devices (with a series resistor and a pull-up resistor to the 5.0-V supply) can drive 5.0-V CMOS input pins that require a V_{IH} of 3.5 V. When the pin is inactive, the trace will be pulled up to 5.0 V by the resistor. The open-drain pin will only drive low or tri-state; it will never drive high. The rise time is dependent on the value of the pull-up resistor and load impedance. The I_{OL} current specification should be considered when selecting a pull-up resistor.

APEX 20KC devices support the ClockLock and ClockBoost clock management features, which are implemented with PLLs. The ClockLock circuitry uses a synchronizing PLL that reduces the clock delay and skew within a device. This reduction minimizes clock-to-output and setup times while maintaining zero hold times. The ClockBoost circuitry, which provides a clock multiplier, allows the designer to enhance device area efficiency by sharing resources within the device. The ClockBoost circuitry allows the designer to distribute a low-speed clock and multiply that clock on-device. APEX 20KC devices include a high-speed clock tree; unlike ASICs, the user does not have to design and optimize the clock tree. The ClockLock and ClockBoost features work in conjunction with the APEX 20KC device's high-speed clock to provide significant improvements in system performance and bandwidth. APEX 20KC devices in -7 and -8 speed grades have PLLs and support the ClockLock and ClockBoost features.

The ClockLock and ClockBoost features in APEX 20KC devices are enabled through the Quartus II software. External devices are not required to use these features.

APEX 20KC ClockLock Feature

APEX 20KC devices include up to four PLLs, which can be used independently. Two PLLs are designed for either general-purpose use or LVDS use (on devices that support LVDS I/O pins). The remaining two PLLs are designed for general-purpose use. The EP20K200C devices have two PLLs; the EP20K400C and larger devices have four PLLs.

The following sections describe some of the features offered by the APEX 20KC PLLs.

External PLL Feedback

The ClockLock circuit's output can be driven off-chip to clock other devices in the system; further, the feedback loop of the PLL can be routed off-chip. This feature allows the designer to exercise fine control over the I/O interface between the APEX 20KC device and another high-speed device, such as SDRAM.

Clock Multiplication

The APEX 20KC ClockBoost circuit can multiply or divide clocks by a programmable number. The clock can be multiplied by $m/(n \times k)$, where m and k range from 2 to 160 and n ranges from 1 to 16. Clock multiplication and division can be used for time-domain multiplexing and other functions, which can reduce design LE requirements.

Clock Phase & Delay Adjustment

The APEX 20KC ClockShift feature allows the clock phase and delay to be adjusted. The clock phase can be adjusted by 90° steps. The clock delay can be adjusted to increase or decrease the clock delay by an arbitrary amount, up to one clock period.

LVDS Support

All APEX 20KC devices support differential LVDS buffers on the input and output clock signals that interface with external devices. This is controlled in the Quartus II software by assigning the clock pins with an LVDS I/O standard assignment.

Two high-speed PLLs are designed to support the LVDS interface. When using LVDS, the I/O clock runs at a slower rate than the data transfer rate. Thus, PLLs are used to multiply the I/O clock internally to capture the LVDS data. For example, an I/O clock may run at 105 MHz to support 840 Mbps LVDS data transfer. In this example, the PLL multiplies the incoming clock by eight to support the high-speed data transfer. You can use PLLs in EP20K400C and larger devices for high-speed LVDS interfacing.

Lock Signals

The APEX 20KC ClockLock circuitry supports individual LOCK signals. The LOCK signal drives high when the ClockLock circuit has locked onto the input clock. The LOCK signals are optional for each ClockLock circuit; when not used, they are I/O pins.

IEEE Std. 1149.1 (JTAG) Boundary-Scan Support

All APEX 20KC devices provide JTAG BST circuitry that complies with the IEEE Std. 1149.1-1990 specification. JTAG boundary-scan testing can be performed before or after configuration, but not during configuration. APEX 20KC devices can also use the JTAG port for configuration with the Quartus II software or with hardware using either Jam Files (.jam) or Jam Byte-Code Files (.jbc). Finally, APEX 20KC devices use the JTAG port to monitor the logic operation of the device with the SignalTap embedded logic analyzer. APEX 20KC devices support the JTAG instructions shown in [Table 13](#).

Table 13. APEX 20KC JTAG Instructions

JTAG Instruction	Description
SAMPLE/PRELOAD	Allows a snapshot of signals at the device pins to be captured and examined during normal device operation, and permits an initial data pattern to be output at the device pins. Also used by the SignalTap embedded logic analyzer.
EXTEST	Allows the external circuitry and board-level interconnections to be tested by forcing a test pattern at the output pins and capturing test results at the input pins.
BYPASS	Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through selected devices to adjacent devices during normal device operation.
USERCODE	Selects the 32-bit USERCODE register and places it between the TDI and TDO pins, allowing the USERCODE to be serially shifted out of TDO.
IDCODE	Selects the IDCODE register and places it between TDI and TDO, allowing the IDCODE to be serially shifted out of TDO.
ICR Instructions	Used when configuring an APEX 20KC device via the JTAG port with a MasterBlaster™ or ByteBlasterMV™ download cable, or when using a Jam File or Jam Byte-Code File via an embedded processor.
SignalTap Instructions	Monitors internal device operation with the SignalTap embedded logic analyzer.

The APEX 20KC device instruction register length is 10 bits. The APEX 20KC device USERCODE register length is 32 bits. [Tables 14 and 15](#) show the boundary-scan register length and device IDCODE information for APEX 20KC devices.

Table 14. APEX 20KC Boundary-Scan Register Length

Device	Boundary-Scan Register Length
EP20K200C	1,164
EP20K400C	1,506
EP20K600C	1,806
EP20K1000C	2,190

Table 15. 32-Bit APEX 20KC Device IDCODE

Device	IDCODE (32 Bits) ⁽¹⁾			
	Version (4 Bits)	Part Number (16 Bits)	Manufacturer Identity (11 Bits)	1 (1 Bit) ⁽²⁾
EP20K200C	0000	1000 0010 0000 0000	000 0110 1110	1
EP20K400C	0000	1000 0100 0000 0000	000 0110 1110	1
EP20K600C	0000	1000 0110 0000 0000	000 0110 1110	1
EP20K1000C	0000	1001 0000 0000 0000	000 0110 1110	1

Notes to Table 15:

- (1) The most significant bit (MSB) is on the left.
- (2) The IDCODE's least significant bit (LSB) is always 1.

[Figure 30](#) shows the timing requirements for the JTAG signals.

Table 18. APEX 20KC Device Recommended Operating Conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V_{CCINT}	Supply voltage for internal logic and input buffers	(3), (4)	1.71 (1.71)	1.89 (1.89)	V
V_{CCIO}	Supply voltage for output buffers, 3.3-V operation	(3), (4)	3.00 (3.00)	3.60 (3.60)	V
	Supply voltage for output buffers, 2.5-V operation	(3), (4)	2.375 (2.375)	2.625 (2.625)	V
	Supply voltage for output buffers, 1.8-V operation	(3), (4)	1.71 (1.71)	1.89 (1.89)	V
V_I	Input voltage	(2), (5)	-0.5	4.1	V
V_O	Output voltage		0	V_{CCIO}	V
T_J	Operating junction temperature	For commercial use	0	85	° C
		For industrial use	-40	100	° C
t_R	Input rise time (10% to 90%)			40	ns
t_F	Input fall time (90% to 10%)			40	ns

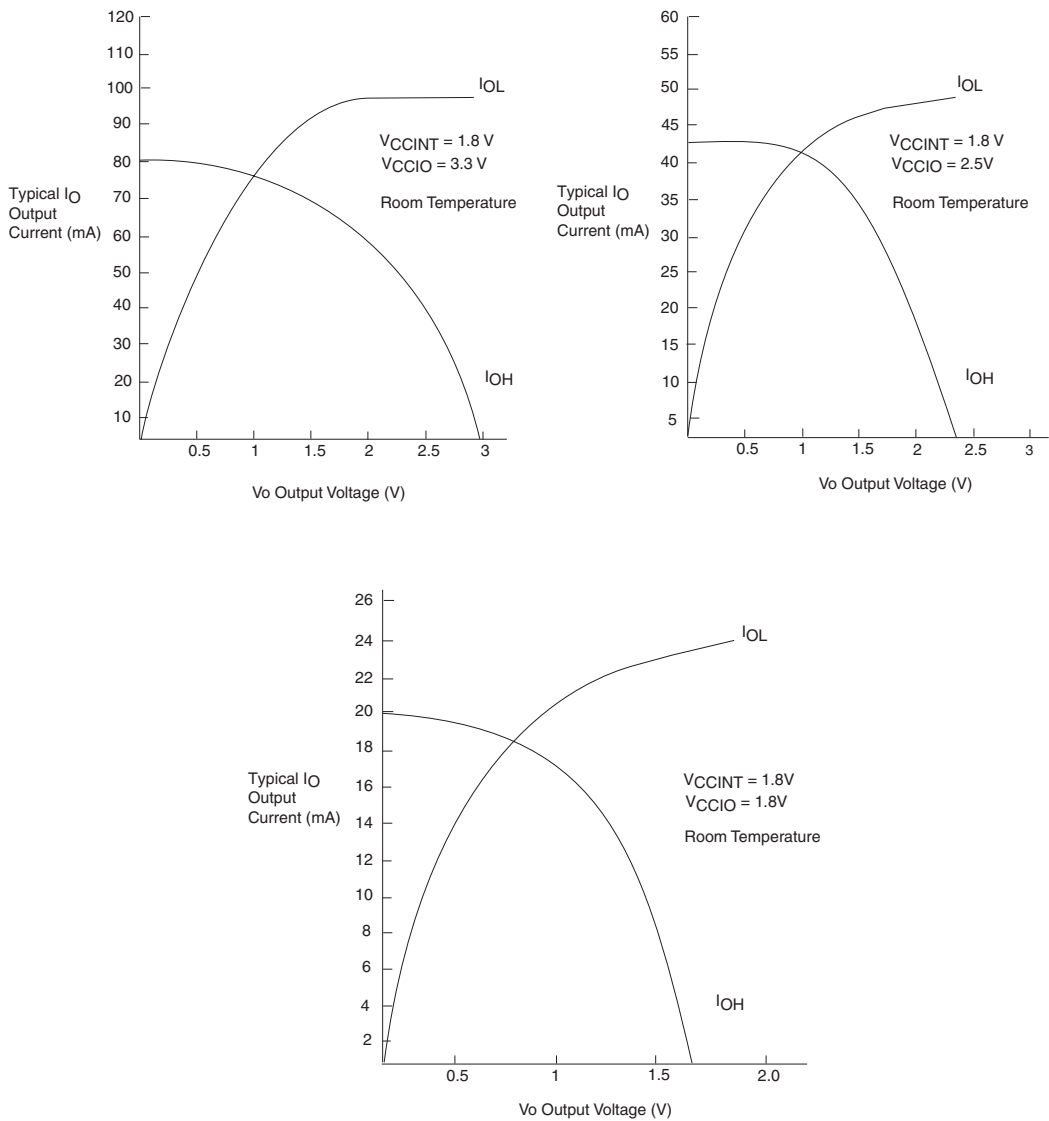
Table 19. APEX 20KC Device DC Operating Conditions Notes (6), (7)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_I	Input pin leakage current (8)	$V_I = 3.6$ to 0.0 V	-10		10	μ A
I_{OZ}	Tri-stated I/O pin leakage current (8)	$V_O = 4.1$ to -0.5 V	-10		10	μ A
I_{CC0}	V_{CC} supply current (standby) (All ESBs in power-down mode)	$V_I =$ ground, no load, no toggling inputs, -7 speed grade		10		mA
		$V_I =$ ground, no load, no toggling inputs, -8, -9 speed grades		5		mA
R_{CONF}	Value of I/O pin pull-up resistor before and during configuration	$V_{CCIO} = 3.0$ V (9)	20		50	k Ω
		$V_{CCIO} = 2.375$ V (9)	30		80	k Ω
		$V_{CCIO} = 1.71$ V (9)	60		150	k Ω



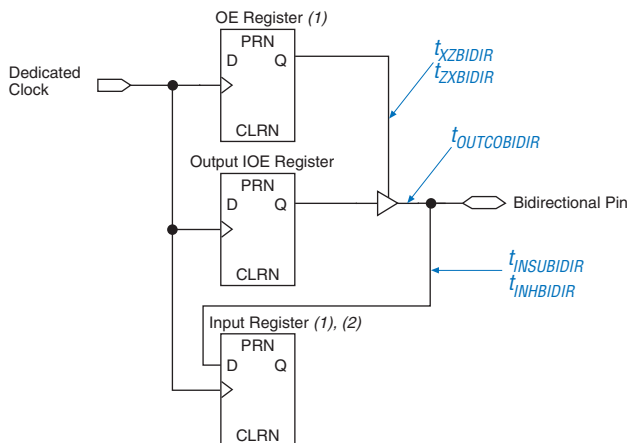
DC operating specifications on APEX 20KC I/O standards are listed in Tables 21 to 35.

Figure 31. Output Drive Characteristics of APEX 20KC Devices *Note (1)*



Note to Figure 31:
(1) These are transient (AC) currents.

Figure 35. Synchronous Bidirectional Pin External Timing



Notes to Figure 35:

- (1) The output enable and input registers are LE registers in the LAB adjacent to the bidirectional pin. Use the “Output Enable Routing = Single-Pin” option in the Quartus II software to set the output enable register.
- (2) Use the “Decrease Input Delay to Internal Cells = OFF” option in the Quartus II software to set the LAB-adjacent input register. This maintains a zero hold time for LAB-adjacent registers while giving a fast, position-independent setup time. Set “Decrease Input Delay to Internal Cells = ON” and move the input register farther away from the bidirectional pin for a faster setup time with zero hold time. The exact position where zero hold occurs with the minimum setup time varies with device density and speed grade.

Tables 36 to 38 describes the f_{MAX} timing parameters shown in Figure 32. Table 39 describes the functional timing parameters.

Table 36. APEX 20KC t_{MAX} LE Timing Parameters

Symbol	Parameter
t_{SU}	LE register setup time before clock
t_H	LE register hold time before clock
t_{CO}	LE register clock-to-output delay
t_{LUT}	LUT delay for data-in to data-out

Table 41. APEX 20KC External Bidirectional Timing Parameters *Note (1)*

Symbol	Parameter	Condition
$t_{\text{INSUBIDIR}}$	Setup time for bidirectional pins with global clock at LAB-adjacent input register	
t_{INHBIDIR}	Hold time for bidirectional pins with global clock at LAB-adjacent input register	
$t_{\text{OUTCOBIDIR}}$	Clock-to-output delay for bidirectional pins with global clock at IOE register	(2)
t_{XZBIDIR}	Synchronous output enable register to output buffer disable delay	(2)
t_{ZXBIDIR}	Synchronous output enable register to output buffer enable delay	(2)
$t_{\text{INSUBIDIRPLL}}$	Setup time for bidirectional pins with PLL clock at LAB-adjacent input register	
$t_{\text{INHBIDIRPLL}}$	Hold time for bidirectional pins with PLL clock at LAB-adjacent input register	
$t_{\text{OUTCOBIDIRPLL}}$	Clock-to-output delay for bidirectional pins with PLL clock at IOE register	(2)
$t_{\text{XZBIDIRPLL}}$	Synchronous output enable register to output buffer disable delay with PLL	(2)
$t_{\text{ZXBIDIRPLL}}$	Synchronous output enable register to output buffer enable delay with PLL	(2)

Notes to Tables 40 and 41:

- (1) These timing parameters are sample-tested only.
(2) For more information, refer to Table 43.

Tables 42 and 43 define the timing delays for each I/O standard. Some output standards require test load circuits for AC timing measurements as shown in Figures 36 through 38.

Table 42. APEX 20KC Selectable I/O Standard Input Adder Delays (Part 1 of 2) *Note (1)*

Symbol	Parameter	Condition
LVC MOS	Input adder delay for the LVC MOS I/O standard	
LVTTL	Input adder delay for the LVTTL I/O standard	
2.5 V	Input adder delay for the 2.5-V I/O standard	
1.8 V	Input adder delay for the 1.8-V I/O standard	
PCI	Input adder delay for the PCI I/O standard	
GTI+	Input adder delay for the GTI+ I/O standard	
SSTL-3 Class I	Input adder delay for the SSTL-3 Class I I/O standard	
SSTL-3 Class II	Input adder delay for the SSTL-3 Class II I/O standard	
SSTL-2 Class I	Input adder delay for the SSTL-2 Class I I/O standard	
SSTL-2 Class II	Input adder delay for the SSTL-2 Class II I/O standard	

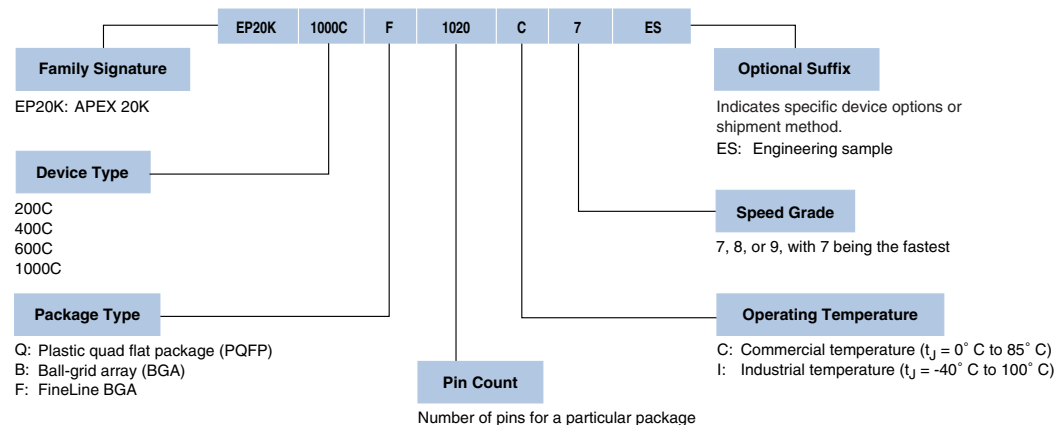
Table 61. EP20K600C External Bidirectional Timing Parameters

Symbol	-7 Speed Grade		-8 Speed Grade		-9 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{\text{INSUBIDIR}}$	2.03		2.57		2.97		ns
t_{INHBIDIR}	0.00		0.00		0.00		ns
$t_{\text{OUTCOBIDIR}}$	2.00	4.29	2.00	4.77	2.00	5.11	ns
t_{XZBIDIR}		8.31		9.14		9.76	ns
t_{ZXBIDIR}		8.31		9.14		9.76	ns
$t_{\text{INSUBIDIRPLL}}$	3.99		4.77		-		ns
$t_{\text{INHBIDIRPLL}}$	0.00		0.00		-		ns
$t_{\text{OUTCOBIDIRPLL}}$	0.50	2.37	0.50	2.63	-	-	ns
$t_{\text{XZBIDIRPLL}}$		6.35		6.94		-	ns
$t_{\text{ZXBIDIRPLL}}$		6.35		6.94		-	ns

Table 62. EP20K1000C t_{MAX} LE Timing Microparameters

Symbol	-7 Speed Grade		-8 Speed Grade		-9 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t_{SU}	0.01		0.01		0.01		ns
t_{H}	0.10		0.10		0.10		ns
t_{CO}		0.27		0.30		0.32	ns
t_{LUT}		0.66		0.79		0.92	ns

Figure 39. APEX 20KC Device Packaging Ordering Information



Revision History

The information contained in the *APEX 20KC Programmable Logic Device Data Sheet* version 2.2 supersedes information published in previous versions.

Version 2.2

The following changes were made to the *APEX 20KC Programmable Logic Device Data Sheet* version 2.2:

- Updated [Tables 1](#).
- Updated notes in [Tables 20](#).

Version 2.1

The following changes were made to the *APEX 20KC Programmable Logic Device Data Sheet* version 2.1:

- Removed figure on AC Test Conditions.
- Updated conditions in [Tables 40](#) and [41](#).
- Added [Tables 42](#) and [43](#).
- Updated V_{OD} in [Table 27](#).
- Added [Figures 36](#) through [38](#).
- Updated [Tables 44](#) through [49](#).
- Updated [Tables 62](#) through [67](#).
- Removed notes in [Tables 44](#) through [67](#).
- Various textual changes throughout the document.

