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### What is "[Embedded - Microcontrollers](#)"?

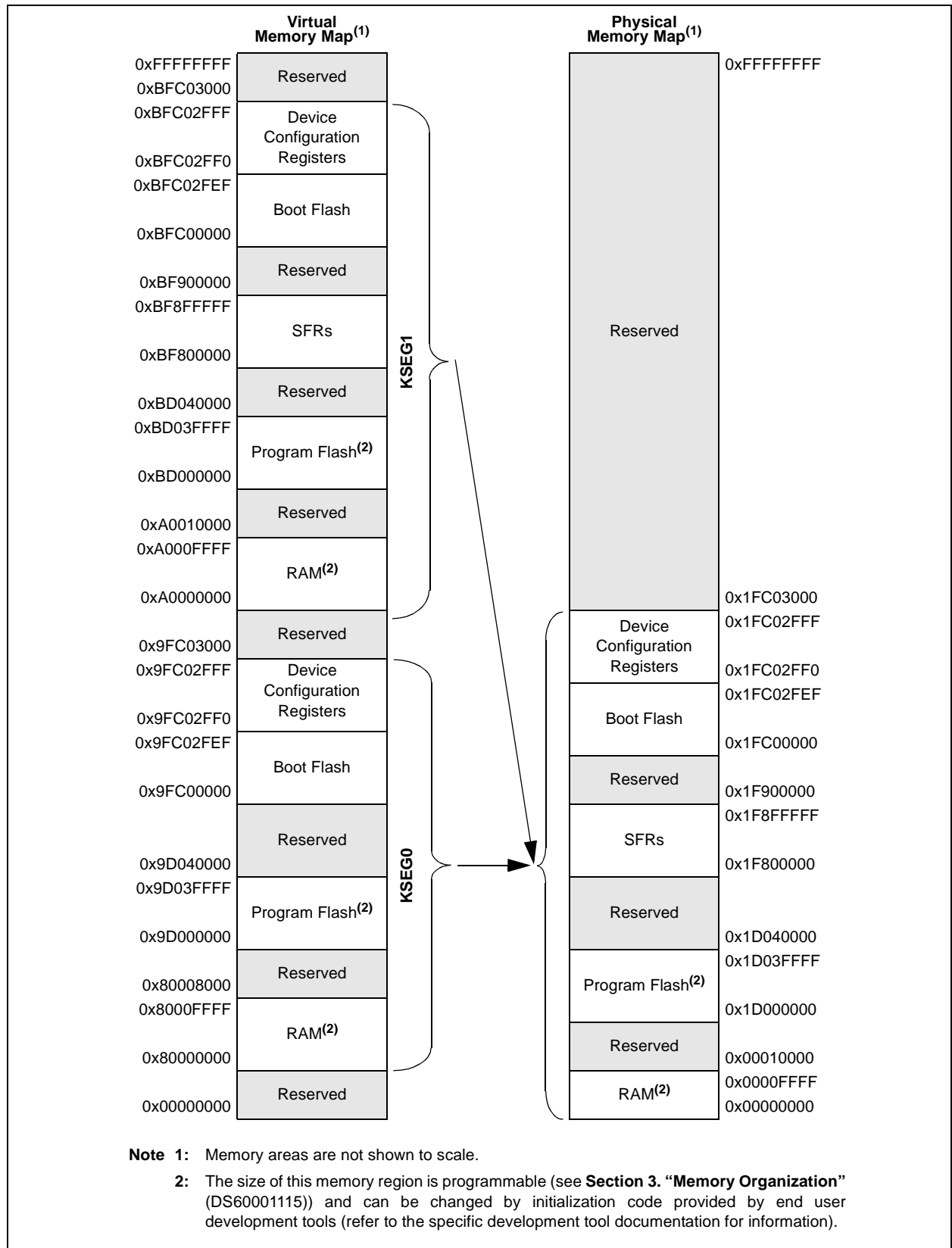
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, I <sup>2</sup> C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic32mx564f064l-i-pf">https://www.e-xfl.com/product-detail/microchip-technology/pic32mx564f064l-i-pf</a>

**FIGURE 4-4: MEMORY MAP ON RESET FOR PIC32MX575F256H, PIC32MX575F256L, PIC32MX675F256H, PIC32MX675F256L, PIC32MX775F256H AND PIC32MX775F256L DEVICES**



# PIC32MX5XX/6XX/7XX

**REGISTER 4-1: BMXCON: BUS MATRIX CONFIGURATION REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
23:16	U-0 —	U-0 —	U-0 —	R/W-1 BMX ERRIXI	R/W-1 BMX ERRICD	R/W-1 BMX ERRDMA	R/W-1 BMX ERRDS	R/W-1 BMX ERRIS
15:8	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
7:0	U-0 —	R/W-1 BMX WSDRM	U-0 —	U-0 —	U-0 —	R/W-0	R/W-0	R/W-1
BMXARB<2:0>								

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

bit 31-21 **Unimplemented:** Read as '0'

bit 20 **BMXERRIXI:** Enable Bus Error from IXI bit

1 = Enable bus error exceptions for unmapped address accesses initiated from IXI shared bus

0 = Disable bus error exceptions for unmapped address accesses initiated from IXI shared bus

bit 19 **BMXERRICD:** Enable Bus Error from ICD Debug Unit bit

1 = Enable bus error exceptions for unmapped address accesses initiated from ICD

0 = Disable bus error exceptions for unmapped address accesses initiated from ICD

bit 18 **BMXERRDMA:** Bus Error from DMA bit

1 = Enable bus error exceptions for unmapped address accesses initiated from DMA

0 = Disable bus error exceptions for unmapped address accesses initiated from DMA

bit 17 **BMXERRDS:** Bus Error from CPU Data Access bit (disabled in Debug mode)

1 = Enable bus error exceptions for unmapped address accesses initiated from CPU data access

0 = Disable bus error exceptions for unmapped address accesses initiated from CPU data access

bit 16 **BMXERRIS:** Bus Error from CPU Instruction Access bit (disabled in Debug mode)

1 = Enable bus error exceptions for unmapped address accesses initiated from CPU instruction access

0 = Disable bus error exceptions for unmapped address accesses initiated from CPU instruction access

bit 15-7 **Unimplemented:** Read as '0'

bit 6 **BMXWSDRM:** CPU Instruction or Data Access from Data RAM Wait State bit

1 = Data RAM accesses from CPU have one wait state for address setup

0 = Data RAM accesses from CPU have zero wait states for address setup

bit 5-3 **Unimplemented:** Read as '0'

bit 2-0 **BMXARB<2:0>:** Bus Matrix Arbitration Mode bits

111 = Reserved (using these Configuration modes will produce undefined behavior)

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011 = Reserved (using these Configuration modes will produce undefined behavior)

010 = Arbitration Mode 2

001 = Arbitration Mode 1 (default)

000 = Arbitration Mode 0

**REGISTER 4-2: BMXDKPBA: DATA RAM KERNEL PROGRAM BASE ADDRESS REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0
	BMXDKPBA<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	BMXDKPBA<7:0>							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-10 **BMXDKPBA<15:10>:** DRM Kernel Program Base Address bits

When non-zero, this value selects the relative base address for kernel program space in RAM

bit 9-0 **BMXDKPBA<9:0>:** DRM Kernel Program Base Address Read-Only bits

Value is always '0', which forces 1 KB increments

**Note 1:** At Reset, the value in this register is forced to zero, which causes all of the RAM to be allocated to Kernal mode data usage.

**2:** The value in this register must be less than or equal to BMXDRMSZ.

**TABLE 7-5: INTERRUPT REGISTER MAP FOR PIC32MX534F064L, PIC32MX564F064L, PIC32MX564F128L PIC32MX575F512L AND PIC32MX575F256L DEVICES (CONTINUED)**

Virtual Address (BF88_#)	Register Name <sup>(1)</sup>	Bit Range	Bits																All Resets		
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0			
10D0	IPC4	31:16	—	—	—	INT4IP<2:0>			INT4IS<1:0>			—	—	—	OC4IP<2:0>			OC4IS<1:0>		0000	
		15:0	—	—	—	IC4IP<2:0>			IC4IS<1:0>			—	—	—	T4IP<2:0>			T4IS<1:0>		0000	
10E0	IPC5	31:16	—	—	—	SPI1IP<2:0>			SPI1IS<1:0>			—	—	—	OC5IP<2:0>			OC5IS<1:0>		0000	
		15:0	—	—	—	IC5IP<2:0>			IC5IS<1:0>			—	—	—	T5IP<2:0>			T5IS<1:0>		0000	
10F0	IPC6	31:16	—	—	—	AD1IP<2:0>			AD1IS<1:0>			—	—	—	CNIP<2:0>			CNIS<1:0>		0000	
		15:0	—	—	—	I2C1IP<2:0>			I2C1IS<1:0>			—	—	—	U1IP<2:0>			U1IS<1:0>		0000	
															SPI3IP<2:0>			SPI3IS<1:0>			
															I2C3IP<2:0>			I2C3IS<1:0>			
1100	IPC7	31:16	—	—	—	U3IP<2:0>			U3IS<1:0>			—	—	—	CMP2IP<2:0>			CMP2IS<1:0>		0000	
						SPI2IP<2:0>			SPI2IS<1:0>												
						I2C4IP<2:0>			I2C4IS<1:0>												
		15:0	—	—	—	CMP1IP<2:0>			CMP1IS<1:0>			—	—	—	PMPIP<2:0>			PMPIS<1:0>		0000	
1110	IPC8	31:16	—	—	—	RTCCIP<2:0>			RTCCIS<1:0>			—	—	—	FSCMIP<2:0>			FSCMIS<1:0>		0000	
		15:0	—	—	—	I2C2IP<2:0>			I2C2IS<1:0>			—	—	—	U2IP<2:0>			U2IS<1:0>		0000	
															SPI4IP<2:0>			SPI4IS<1:0>			
															I2C5IP<2:0>			I2C5IS<1:0>			
1120	IPC9	31:16	—	—	—	DMA3IP<2:0>			DMA3IS<1:0>			—	—	—	DMA2IP<2:0>			DMA2IS<1:0>		0000	
		15:0	—	—	—	DMA1IP<2:0>			DMA1IS<1:0>			—	—	—	DMA0IP<2:0>			DMA0IS<1:0>		0000	
1130	IPC10	31:16	—	—	—	DMA7IP<2:0> <sup>(2)</sup>			DMA7IS<1:0> <sup>(2)</sup>			—	—	—	DMA6IP<2:0> <sup>(2)</sup>			DMA6IS<1:0> <sup>(2)</sup>		0000	
		15:0	—	—	—	DMA5IP<2:0> <sup>(2)</sup>			DMA5IS<1:0> <sup>(2)</sup>			—	—	—	DMA4IP<2:0> <sup>(2)</sup>			DMA4IS<1:0> <sup>(2)</sup>		0000	
1140	IPC11	31:16	—	—	—	—	—	—	—	—	—	—	—	—	CAN1IP<2:0>			CAN1IS<1:0>		0000	
		15:0	—	—	—	USBIP<2:0>			USBIS<1:0>			—	—	—	FCEIP<2:0>			FCEIS<1:0>		0000	
1150	IPC12	31:16	—	—	—	U5IP<2:0>			U5IS<1:0>			—	—	—	U6IP<2:0>			U6IS<1:0>		0000	
		15:0	—	—	—	U4IP<2:0>			U4IS<1:0>			—	—	—	—	—	—	—	—	0000	

**Legend:** x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** Except where noted, all registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

**2:** These bits are not available on PIC32MX534/564 devices.

**3:** This register does not have associated CLR, SET, and INV registers.

## 19.1 Control Registers

**TABLE 19-1: I2C1THROUGH I2C5 REGISTER MAP**

Virtual Address (BF80_#)	Register Name <sup>(1)</sup>	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
5000	I2C3CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	SCLREL	STRICT	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
5010	I2C3STAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	P	S	R/W	RBF	TBF	0000
5020	I2C3ADD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5030	I2C3MSK	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5040	I2C3BRG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5050	I2C3TRN	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5060	I2C3RCV	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5100	I2C4CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	SCLREL	STRICT	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
5110	I2C4STAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	P	S	R/W	RBF	TBF	0000
5120	I2C4ADD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5130	I2C4MSK	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5140	I2C4BRG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5150	I2C4TRN	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5160	I2C4RCV	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
5200	I2C5CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	SCLREL	STRICT	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
5210	I2C5STAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	P	S	R/W	RBF	TBF	0000
5220	I2C5ADD	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000

**Legend:** × = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**Note 1:** All registers in this table except I2CxRCV have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

**2:** This register is not available on 64-pin devices.

# PIC32MX5XX/6XX/7XX

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NOTES:

## 22.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

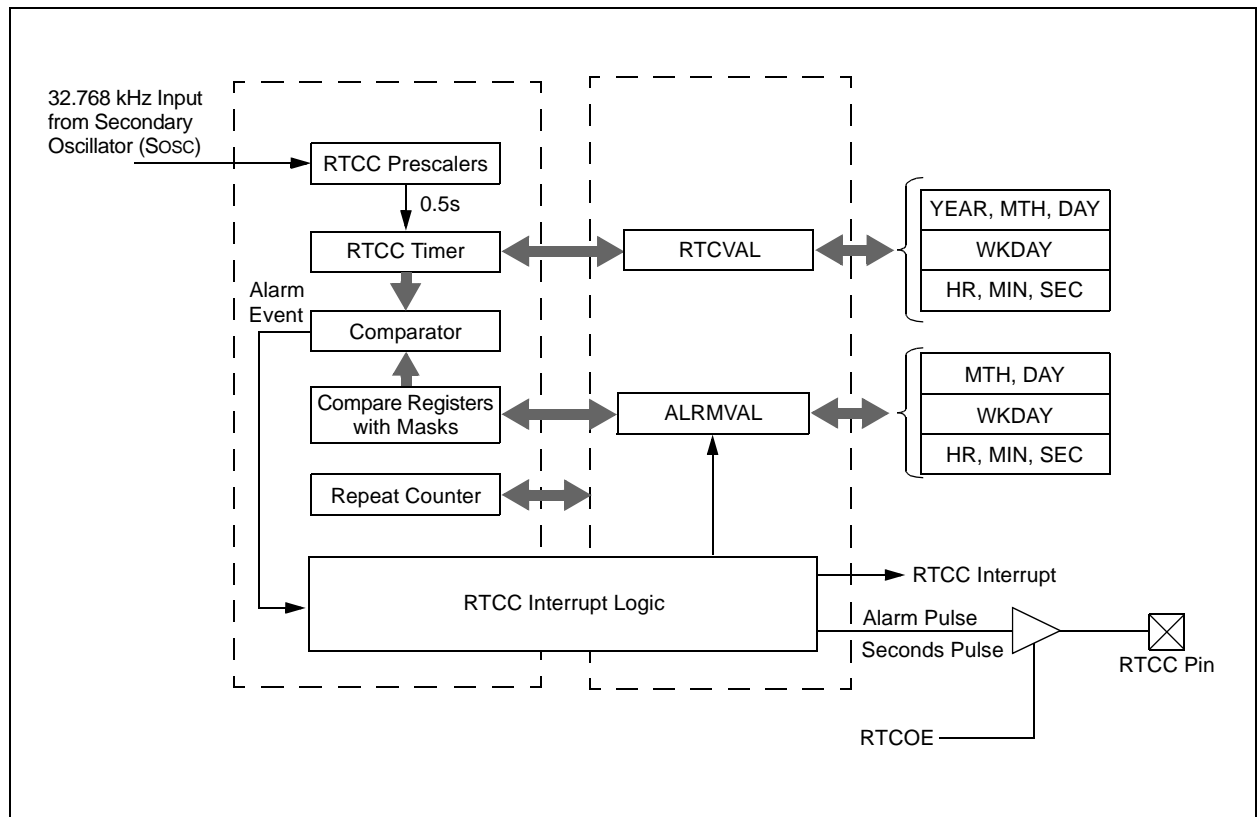
**Note:** This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 29. “Real-Time Clock and Calendar (RTCC)”** (DS60001125) in the “PIC32 Family Reference Manual”, which is available from the Microchip web site ([www.microchip.com/PIC32](http://www.microchip.com/PIC32)).

The PIC32 RTCC module is intended for applications in which accurate time must be maintained for extended periods of time with minimal or no CPU intervention. Low-power optimization provides extended battery lifetime while keeping track of time. A simplified block diagram of the RTCC module is illustrated in Figure 22-1.

Key features of the RTCC module include:

- Time: hours, minutes and seconds
- 24-hour format (military time)
- Visibility of one-half second period
- Provides calendar: Weekday, date, month and year
- Alarm intervals are configurable for half of a second, one second, 10 seconds, one minute, 10 minutes, one hour, one day, one week, one month and one year
- Alarm repeat with decrementing counter
- Alarm with indefinite repeat: Chime
- Year range: 2000 to 2099
- Leap year correction
- BCD format for smaller firmware overhead
- Optimized for long-term battery operation
- Fractional second synchronization
- User calibration of the clock crystal frequency with auto-adjust
- Calibration range:  $\pm 0.66$  seconds error per month
- Calibrates up to 260 ppm of crystal error
- Requirements: External 32.768 kHz clock crystal
- Alarm pulse or seconds clock output on RTCC pin

**FIGURE 22-1: RTCC BLOCK DIAGRAM**





## 24.0 CONTROLLER AREA NETWORK (CAN)

**Note:** This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 34. “Controller Area Network (CAN)”** (DS60001154) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site ([www.microchip.com/PIC32](http://www.microchip.com/PIC32)).

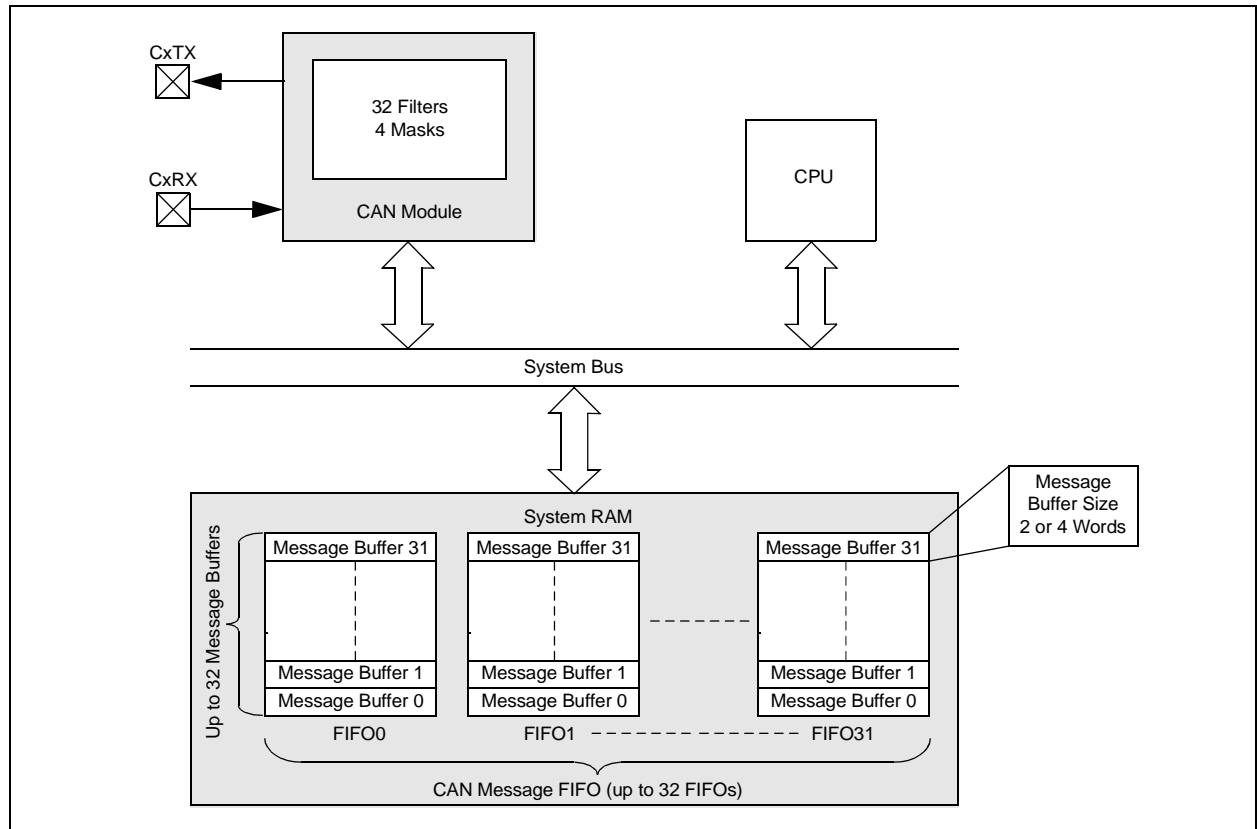
The Controller Area Network (CAN) module supports the following key features:

- Standards Compliance:
  - Full CAN 2.0B compliance
  - Programmable bit rate up to 1 Mbps
- Message Reception and Transmission:
  - 32 message FIFOs
  - Each FIFO can have up to 32 messages for a total of 1024 messages

- FIFO can be a transmit message FIFO or a receive message FIFO
- User-defined priority levels for message FIFOs used for transmission
- 32 acceptance filters for message filtering
- Four acceptance filter mask registers for message filtering
- Automatic response to remote transmit request
- DeviceNet™ addressing support
- Additional Features:
  - Loopback, Listen All Messages, and Listen Only modes for self-test, system diagnostics and bus monitoring
  - Low-power operating modes
  - CAN module is a bus master on the PIC32 system bus
  - Use of DMA is not required
  - Dedicated time-stamp timer
  - Dedicated DMA channels
  - Data-only Message Reception mode

Figure 24-1 illustrates the general structure of the CAN module.

**FIGURE 24-1: PIC32 CAN MODULE BLOCK DIAGRAM**



## REGISTER 24-14: CifLTCON4: CAN FILTER CONTROL REGISTER 4 (CONTINUED)

- bit 15     **FLTEN17**: Filter 13 Enable bit  
          1 = Filter is enabled  
          0 = Filter is disabled
- bit 14-13   **MSEL17<1:0>**: Filter 17 Mask Select bits  
          11 = Acceptance Mask 3 selected  
          10 = Acceptance Mask 2 selected  
          01 = Acceptance Mask 1 selected  
          00 = Acceptance Mask 0 selected
- bit 12-8   **FSEL17<4:0>**: FIFO Selection bits  
          11111 = Message matching filter is stored in FIFO buffer 31  
          11110 = Message matching filter is stored in FIFO buffer 30  
          •  
          •  
          •  
          00001 = Message matching filter is stored in FIFO buffer 1  
          00000 = Message matching filter is stored in FIFO buffer 0
- bit 7     **FLTEN16**: Filter 16 Enable bit  
          1 = Filter is enabled  
          0 = Filter is disabled
- bit 6-5   **MSEL16<1:0>**: Filter 16 Mask Select bits  
          11 = Acceptance Mask 3 selected  
          10 = Acceptance Mask 2 selected  
          01 = Acceptance Mask 1 selected  
          00 = Acceptance Mask 0 selected
- bit 4-0   **FSEL16<4:0>**: FIFO Selection bits  
          11111 = Message matching filter is stored in FIFO buffer 31  
          11110 = Message matching filter is stored in FIFO buffer 30  
          •  
          •  
          •  
          00001 = Message matching filter is stored in FIFO buffer 1  
          00000 = Message matching filter is stored in FIFO buffer 0

<b>Note:</b> The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.
---

## REGISTER 25-25: EMAC1IPGT: ETHERNET CONTROLLER MAC BACK-TO-BACK INTERPACKET GAP REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0
	—	B2BIPKTGP<6:0>						

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-7 **Unimplemented:** Read as '0'

bit 6-0 **B2BIPKTGP<6:0>:** Back-to-Back Interpacket Gap bits

This is a programmable field representing the nibble time offset of the minimum possible period between the end of any transmitted packet, to the beginning of the next. In Full-Duplex mode, the register value should be the desired period in nibble times minus 3. In Half-Duplex mode, the register value should be the desired period in nibble times minus 6. In Full-Duplex the recommended setting is 0x15 (21d), which represents the minimum IPG of 0.96  $\mu$ s (in 100 Mbps) or 9.6  $\mu$ s (in 10 Mbps). In Half-Duplex mode, the recommended setting is 0x12 (18d), which also represents the minimum IPG of 0.96  $\mu$ s (in 100 Mbps) or 9.6  $\mu$ s (in 10 Mbps).

**Note:** Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

**REGISTER 26-1: CMxCON: COMPARATOR 'x' CONTROL REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
23:16	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
15:8	R/W-0 ON <sup>(1)</sup>	R/W-0 COE	R/W-0 CPOL <sup>(2)</sup>	U-0 —	U-0 —	U-0 —	U-0 —	R-0 COUT
7:0	R/W-1 EVPOL<1:0>		U-0 —	R/W-0 CREF	U-0 —	U-0 —	R/W-1 CCH<1:0>	R/W-1

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Comparator ON bit<sup>(1)</sup>

Clearing this bit does not affect the other bits in this register.

1 = Module is enabled. Setting this bit does not affect the other bits in this register

0 = Module is disabled and does not consume current.

bit 14 **COE:** Comparator Output Enable bit

1 = Comparator output is driven on the output CxOUT pin

0 = Comparator output is not driven on the output CxOUT pin

bit 13 **CPOL:** Comparator Output Inversion bit<sup>(2)</sup>

1 = Output is inverted

0 = Output is not inverted

bit 12-9 **Unimplemented:** Read as '0'

bit 8 **COUT:** Comparator Output bit

1 = Output of the Comparator is a '1'

0 = Output of the Comparator is a '0'

bit 7-6 **EVPOL<1:0>:** Interrupt Event Polarity Select bits

11 = Comparator interrupt is generated on a low-to-high or high-to-low transition of the comparator output

10 = Comparator interrupt is generated on a high-to-low transition of the comparator output

01 = Comparator interrupt is generated on a low-to-high transition of the comparator output

00 = Comparator interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

bit 4 **CREF:** Comparator Positive Input Configure bit

1 = Comparator non-inverting input is connected to the internal CVREF

0 = Comparator non-inverting input is connected to the CxIN+ pin

bit 3-2 **Unimplemented:** Read as '0'

bit 1-0 **CCH<1:0>:** Comparator Negative Input Select bits for Comparator

11 = Comparator inverting input is connected to the IVREF

10 = Comparator inverting input is connected to the C2IN+ pin for C1 and C1IN+ pin for C2

01 = Comparator inverting input is connected to the C1IN+ pin for C1 and C2IN+ pin for C2

00 = Comparator inverting input is connected to the C1IN- pin for C1 and C2IN- pin for C2

**Note 1:** When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

**2:** Setting this bit will invert the signal to the comparator interrupt generator as well. This will result in an interrupt being generated on the opposite edge from the one selected by EVPOL<1:0>.

# PIC32MX5XX/6XX/7XX

**REGISTER 26-2: CMSTAT: COMPARATOR STATUS REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
	—	—	SIDL	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	R-0	R-0
	—	—	—	—	—	—	C2OUT	C1OUT

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-14 **Unimplemented:** Read as '0'

bit 13 **SIDL:** Stop in Idle Control bit

1 = All Comparator modules are disabled while in Idle mode

0 = All Comparator modules continue to operate while in Idle mode

bit 12-2 **Unimplemented:** Read as '0'

bit 1 **C2OUT:** Comparator Output bit

1 = Output of Comparator 2 is a '1'

0 = Output of Comparator 2 is a '0'

bit 0 **C1OUT:** Comparator Output bit

1 = Output of Comparator 1 is a '1'

0 = Output of Comparator 1 is a '0'

# PIC32MX5XX/6XX/7XX

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## REGISTER 29-2: DEVCFG1: DEVICE CONFIGURATION WORD 1 (CONTINUED)

- bit 13-12 **FPBDIV<1:0>**: Peripheral Bus Clock Divisor Default Value bits  
11 = PBCLK is SYSCLK divided by 8  
10 = PBCLK is SYSCLK divided by 4  
01 = PBCLK is SYSCLK divided by 2  
00 = PBCLK is SYSCLK divided by 1
- bit 11 **Reserved**: Write '1'
- bit 10 **OSCIOFNC**: CLKO Enable Configuration bit  
1 = CLKO output is disabled  
0 = CLKO output signal is active on the OSCO pin; the Primary Oscillator must be disabled or configured for External Clock mode (EC) for the CLKO to be active (POSCMOD<1:0> = 11 or 00)
- bit 9-8 **POSCMOD<1:0>**: Primary Oscillator Configuration bits  
11 = Primary Oscillator is disabled  
10 = HS Oscillator mode is selected  
01 = XT Oscillator mode is selected  
00 = External Clock mode is selected
- bit 7 **IESO**: Internal External Switchover bit  
1 = Internal External Switchover mode is enabled (Two-Speed Start-up is enabled)  
0 = Internal External Switchover mode is disabled (Two-Speed Start-up is disabled)
- bit 6 **Reserved**: Write '1'
- bit 5 **FSOSCEN**: Secondary Oscillator Enable bit  
1 = Enable the Secondary Oscillator  
0 = Disable the Secondary Oscillator
- bit 4-3 **Reserved**: Write '1'
- bit 2-0 **FNOSC<2:0>**: Oscillator Selection bits  
111 = Fast RC Oscillator with divide-by-N (FRCDIV)  
110 = FRCDIV16 Fast RC Oscillator with fixed divide-by-16 postscaler  
101 = Low-Power RC Oscillator (LPRC)  
100 = Secondary Oscillator (Sosc)  
011 = Primary Oscillator (Posc) with PLL module (XT+PLL, HS+PLL, EC+PLL)  
010 = Primary Oscillator (XT, HS, EC)<sup>(1)</sup>  
001 = Fast RC Oscillator with divide-by-N with PLL module (FRCDIV+PLL)  
000 = Fast RC Oscillator (FRC)

**Note 1:** Do not disable the Posc (POSCMOD = 11) when using this oscillator source.

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**REGISTER 29-5: DEVID: DEVICE AND REVISION ID REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R	R	R	R	R	R	R	R
	VER<3:0> <sup>(1)</sup>				DEVID<27:24> <sup>(1)</sup>			
23:16	R	R	R	R	R	R	R	R
	DEVID<23:16> <sup>(1)</sup>							
15:8	R	R	R	R	R	R	R	R
	DEVID<15:8> <sup>(1)</sup>							
7:0	R	R	R	R	R	R	R	R
	DEVID<7:0> <sup>(1)</sup>							

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-28 **VER<3:0>**: Revision Identifier bits<sup>(1)</sup>

bit 27-0 **DEVID<27:0>**: Device ID bits<sup>(1)</sup>

**Note 1:** See the "PIC32 Flash Programming Specification" (DS60001145) for a list of Revision and Device ID values.

**REGISTER 29-6: DDPCON: DEBUG DATA PORT CONTROL REGISTER**

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	U-0	R/W-0
	—	—	—	—	JTAGEN	TROEN	—	TDOEN

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-4 **Unimplemented:** Read as '0'

bit 3 **JTAGEN:** JTAG Port Enable bit

1 = Enable the JTAG port

0 = Disable the JTAG port

bit 2 **TROEN:** Trace Output Enable bit

1 = Enable the trace port

0 = Disable the trace port

bit 1 **Unimplemented:** Read as '0'

bit 0 **TDOEN:** TDO Enable for 2-Wire JTAG

1 = 2-wire JTAG protocol uses TDO

0 = 2-wire JTAG protocol does not use TDO

## 29.2 On-Chip Voltage Regulator

All PIC32MX5XX/6XX/7XX devices' core and digital logic are designed to operate at a nominal 1.8V. To simplify system designs, most devices in the PIC32MX-5XX/6XX/7XX family incorporate an on-chip regulator providing the required core logic voltage from VDD.

A low-ESR capacitor (such as tantalum) must be connected to the VCAP pin (see Figure 29-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in **Section 32.1 "DC Characteristics"**.

**Note:** It is important that the low-ESR capacitor is placed as close as possible to the VCAP pin.

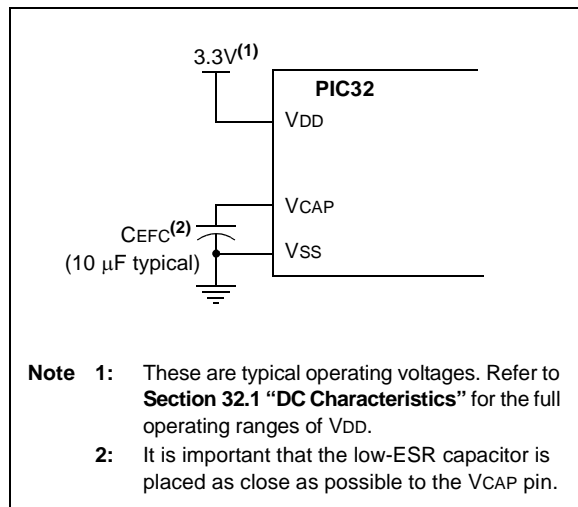
### 29.2.1 ON-CHIP REGULATOR AND POR

It takes a fixed delay for the on-chip regulator to generate an output. During this time, designated as TPU, code execution is disabled. TPU is applied every time the device resumes operation after any power-down, including Sleep mode.

### 29.2.2 ON-CHIP REGULATOR AND BOR

PIC32MX5XX/6XX/7XX devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain a regulated level, the regulator Reset circuitry will generate a Brown-out Reset (BOR). This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage levels are specified in **Section 32.1 "DC Characteristics"**.

**FIGURE 29-1: CONNECTIONS FOR THE ON-CHIP REGULATOR**



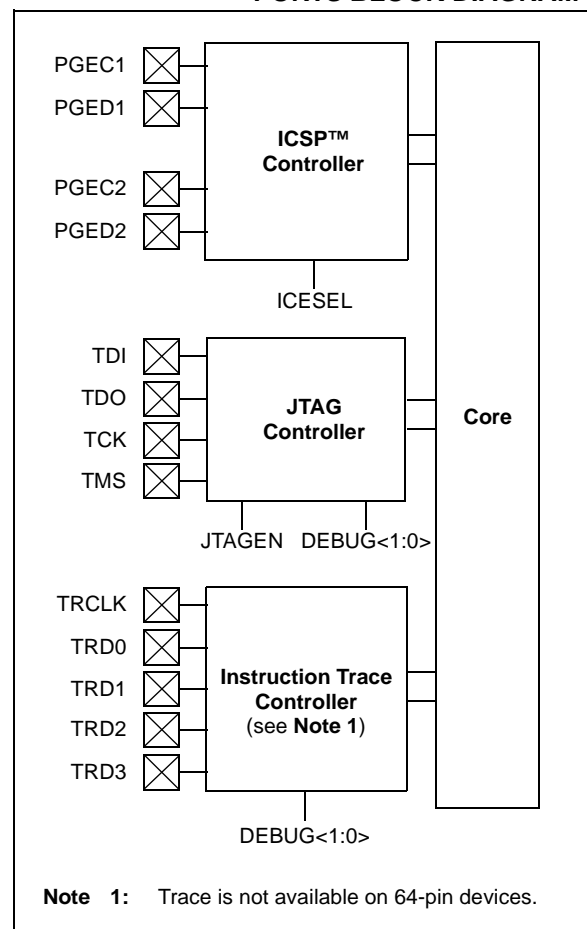
## 29.3 Programming and Diagnostics

PIC32MX5XX/6XX/7XX devices provide a complete range of programming and diagnostic features that can increase the flexibility of any application using them. These features allow system designers to include:

- Simplified field programmability using two-wire In-Circuit Serial Programming™ (ICSP™) interfaces
- Debugging using ICSP
- Programming and debugging capabilities using the EJTAG extension of JTAG
- JTAG boundary scan testing for device and board diagnostics

PIC32 devices incorporate two programming and diagnostic modules, and a trace controller, that provide a range of functions to the application developer.

**FIGURE 29-2: PROGRAMMING, DEBUGGING, AND TRACE PORTS BLOCK DIAGRAM**





# PIC32MX5XX/6XX/7XX

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NOTES:

# PIC32MX5XX/6XX/7XX

## 32.1 DC Characteristics

**TABLE 32-1: OPERATING MIPS VS. VOLTAGE**

Characteristic	VDD Range (in Volts) <sup>(1)</sup>	Temp. Range (in °C)	Max. Frequency
			PIC32MX5XX/6XX/7XX
DC5	2.3-3.6V	-40°C to +85°C	80 MHz
DC5b	2.3-3.6V	-40°C to +105°C	80 MHz

**Note 1:** Overall functional device operation at  $V_{BORMIN} < V_{DD} < V_{DDMIN}$  is tested, but not characterized. All device Analog modules, such as ADC, etc., will function, but with degraded performance below  $V_{DDMIN}$ . Refer to parameter BO10 in Table 32-10 for BOR values.

**TABLE 32-2: THERMAL OPERATING CONDITIONS**

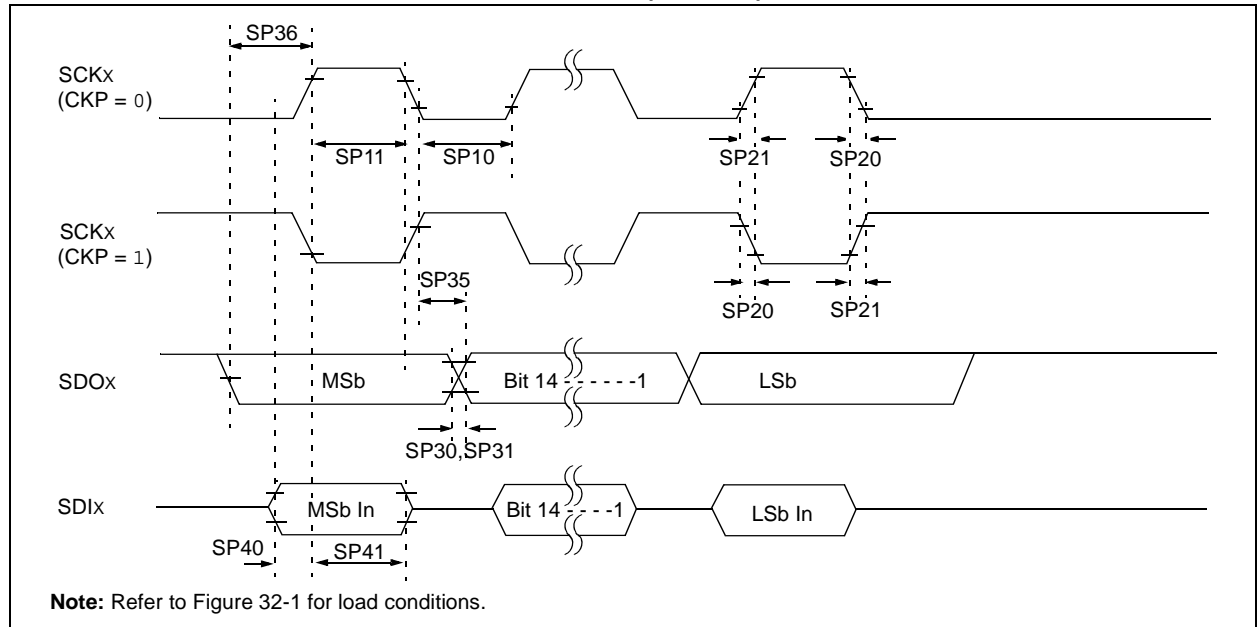
Rating	Symbol	Min.	Typical	Max.	Unit
<b>Industrial Temperature Devices</b>					
Operating Junction Temperature Range	TJ	-40	—	+125	°C
Operating Ambient Temperature Range	TA	-40	—	+85	°C
<b>V-Temp Temperature Devices</b>					
Operating Junction Temperature Range	TJ	-40	—	+140	°C
Operating Ambient Temperature Range	TA	-40	—	+105	°C
Power Dissipation: Internal Chip Power Dissipation: $P_{INT} = V_{DD} \times (I_{DD} - S \times I_{OH})$ I/O Pin Power Dissipation: $I/O = S \times ((V_{DD} - V_{OH}) \times I_{OH}) + S \times (V_{OL} \times I_{OL})$	PD	$P_{INT} + P_{I/O}$			W
Maximum Allowed Power Dissipation	PD <sub>MAX</sub>	$(T_J - T_A)/\theta_{JA}$			W

**TABLE 32-3: THERMAL PACKAGING CHARACTERISTICS**

Characteristics	Symbol	Typical	Max.	Unit	See Note
Package Thermal Resistance, 121-Pin TFBGA (10x10x1.1 mm)	$\theta_{JA}$	40	—	°C/W	1
Package Thermal Resistance, 100-Pin TQFP (14x14x1 mm)	$\theta_{JA}$	43	—	°C/W	1
Package Thermal Resistance, 100-Pin TQFP (12x12x1 mm)	$\theta_{JA}$	43	—	°C/W	1
Package Thermal Resistance, 64-Pin TQFP (10x10x1 mm)	$\theta_{JA}$	47	—	°C/W	1
Package Thermal Resistance, 64-Pin QFN (9x9x0.9 mm)	$\theta_{JA}$	28	—	°C/W	1
Package Thermal Resistance, 124-Pin VTLA (9x9x0.9 mm)	$\theta_{JA}$	21	—	°C/W	1

**Note 1:** Junction to ambient thermal resistance, Theta-JA ( $\theta_{JA}$ ) numbers are achieved by package simulations.

**FIGURE 32-11: SPIx MODULE MASTER MODE (CKE = 1) TIMING CHARACTERISTICS**



**TABLE 32-29: SPIx MODULE MASTER MODE (CKE = 1) TIMING REQUIREMENTS**

AC CHARACTERISTICS				Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp			
Param. No.	Symbol	Characteristics <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Units	Conditions
SP10	TsCL	SCKx Output Low Time <sup>(3)</sup>	TsCK/2	—	—	ns	—
SP11	TsCH	SCKx Output High Time <sup>(3)</sup>	TsCK/2	—	—	ns	—
SP20	TscF	SCKx Output Fall Time <sup>(4)</sup>	—	—	—	ns	See parameter DO32
SP21	TscR	SCKx Output Rise Time <sup>(4)</sup>	—	—	—	ns	See parameter DO31
SP30	TdOF	SDOx Data Output Fall Time <sup>(4)</sup>	—	—	—	ns	See parameter DO32
SP31	TdOR	SDOx Data Output Rise Time <sup>(4)</sup>	—	—	—	ns	See parameter DO31
SP35	Tsch2DoV, TsCL2DoV	SDOx Data Output Valid after SCKx Edge	—	—	15	ns	VDD > 2.7V
			—	—	20	ns	VDD < 2.7V
SP36	TdOV2sc, TdOV2sCL	SDOx Data Output Setup to First SCKx Edge	15	—	—	ns	—
SP40	TdIV2sch, TdIV2sCL	Setup Time of SDIx Data Input to SCKx Edge	15	—	—	ns	VDD > 2.7V
			20	—	—	ns	VDD < 2.7V
SP41	Tsch2DiL, TsCL2DiL	Hold Time of SDIx Data Input to SCKx Edge	15	—	—	ns	VDD > 2.7V
			20	—	—	ns	VDD < 2.7V

**Note 1:** These parameters are characterized, but not tested in manufacturing.

**2:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

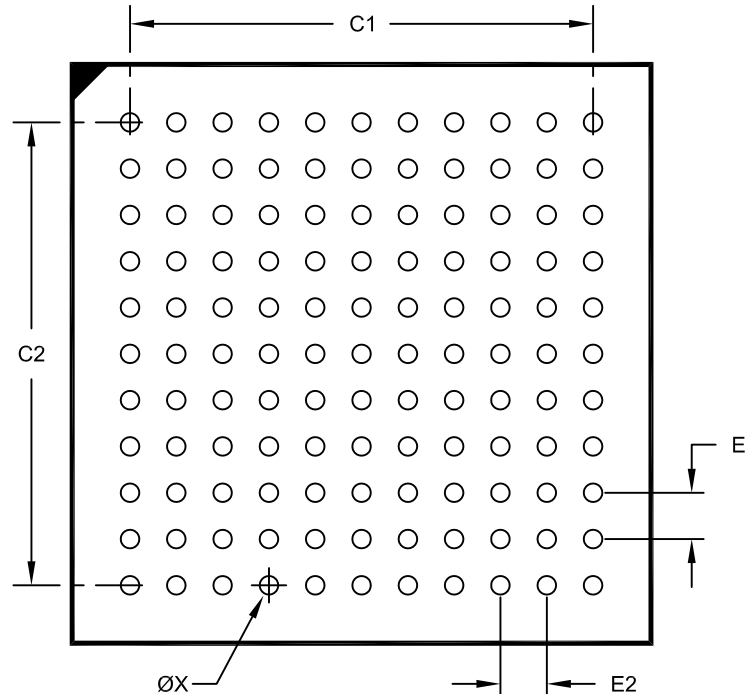
**3:** The minimum clock period for SCKx is 40 ns. Therefore, the clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

# PIC32MX5XX/6XX/7XX

## 121-Lead Plastic Thin Profile Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA--Formerly XBGA]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E1	0.80 BSC		
Contact Pitch	E2	0.80 BSC		
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Diameter (X121)	X			0.32

**Notes:**

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2148 Rev D

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