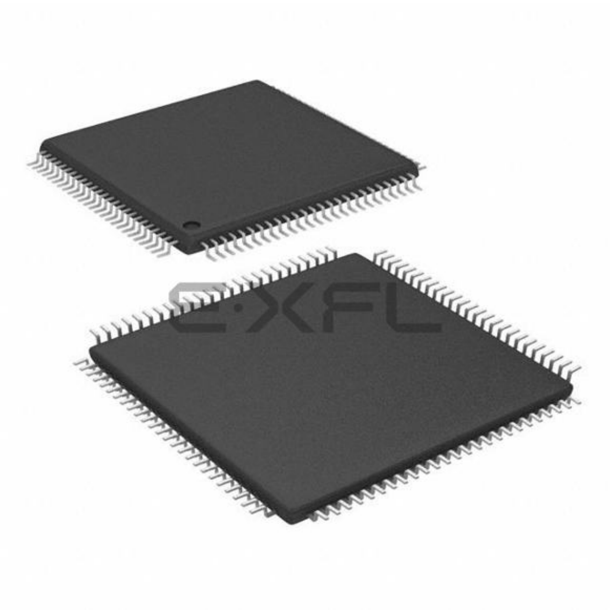

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Details	
Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, I²C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx564f064lt-v-pf

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

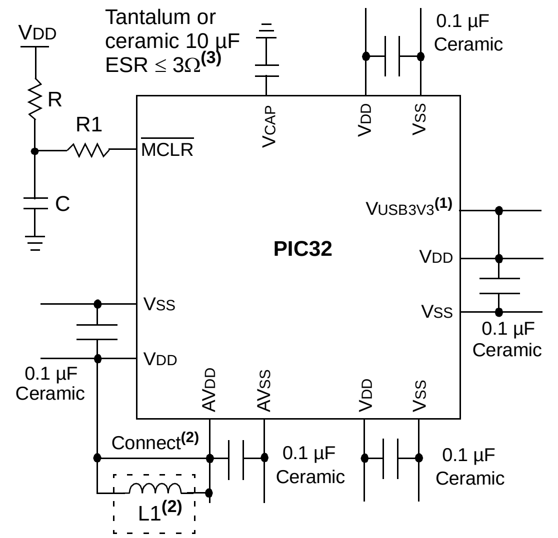
Pin Name	Pin Number[(1)]				Pin Type	Buffer Type	Description
	64-Pin QFN/TQFP	100-Pin TQFP	121-Pin TFBGA	124-pin VTLA			
TMS	23	17	G3	B9	I	ST	JTAG Test mode select pin
TCK	27	38	J6	A26	I	ST	JTAG test clock input pin
TDI	28	60	G11	A40	I	ST	JTAG test data input pin
TDO	24	61	G9	B33	O	—	JTAG test data output pin
RTCC	42	68	E9	B37	O	—	Real-Time Clock alarm output
CVREF-	15	28	L2	A21	I	Analog	Comparator Voltage Reference (low)
CVREF+	16	29	K3	B17	I	Analog	Comparator Voltage Reference (high)
CVREFOUT	23	34	L5	A24	O	Analog	Comparator Voltage Reference output
C1IN-	12	21	H2	B11	I	Analog	Comparator 1 negative input
C1IN+	11	20	H1	A12	I	Analog	Comparator 1 positive input
C1OUT	21	32	K4	A23	O	—	Comparator 1 output
C2IN-	14	23	J2	B13	I	Analog	Comparator 2 negative input
C2IN+	13	22	J1	A13	I	Analog	Comparator 2 positive input
C2OUT	22	33	L4	B19	O	—	Comparator 2 output
PMA0	30	44	L8	A29	I/O	TTL/ST	Parallel Master Port Address bit 0 input (Buffered Slave modes) and output (Master modes)
PMA1	29	43	K7	B24	I/O	TTL/ST	Parallel Master Port Address bit 1 input (Buffered Slave modes) and output (Master modes)
PMA2	8	14	F3	A9	O	—	Parallel Master Port address (Demultiplexed Master modes)
PMA3	6	12	F2	A8	O	—	
PMA4	5	11	F4	B6	O	—	
PMA5	4	10	E3	A7	O	—	
PMA6	16	29	K3	B17	O	—	
PMA7	22	28	L2	A21	O	—	
PMA8	32	50	L11	A32	O	—	
PMA9	31	49	L10	B27	O	—	
PMA10	28	42	L7	A28	O	—	
PMA11	27	41	J7	B23	O	—	
PMA12	24	35	J5	B20	O	—	
PMA13	23	34	L5	A24	O	—	
PMA14	45	71	C11	A46	O	—	
PMA15	44	70	D11	B38	O	—	
PMCS1	45	71	C11	A46	O	—	Parallel Master Port Chip Select 1 strobe
PMCS2	44	70	D11	B38	O	—	Parallel Master Port Chip Select 2 strobe

Legend: CMOS = CMOS compatible input or output; Analog = Analog input; P = Power
ST = Schmitt Trigger input with CMOS levels; O = Output; I = Input
TTL = TTL input buffer

Note 1: Pin numbers are only provided for reference. See the **"Device Pin Tables"** section for device pin availability.

2: See **25.0 "Ethernet Controller"** for more information.

FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION



Note 1: If the USB module is not used, this pin must be connected to VDD.

2: As an option, instead of a hard-wired connection, an inductor (L1) can be substituted between VDD and AVDD to improve ADC noise rejection. The inductor impedance should be less than 3Ω and the inductor capacity greater than 10 mA.

Where:

$$f = \frac{F_{CNV}}{2}$$ (i.e., ADC conversion rate/2)

$$f = \frac{1}{(2\pi\sqrt{LC})}$$

$$L = \left(\frac{1}{(2\pi f\sqrt{C})}\right)^2$$

3: Aluminum or electrolytic capacitors should not be used. ESR ≤ 3Ω from -40ºC to 125ºC @ SYSCLK frequency (i.e., MIPS).

2.2.1 BULK CAPACITORS

The use of a bulk capacitor is recommended to improve power supply stability. Typical values range from 4.7 µF to 47 µF. This capacitor should be located as close to the device as possible.

2.3 Capacitor on Internal Voltage Regulator (VCAP)

2.3.1 INTERNAL REGULATOR MODE

A low-ESR (1 ohm) capacitor is required on the VCAP pin, which is used to stabilize the internal voltage regulator output. The VCAP pin must not be connected to VDD, and must have a CEFC capacitor, with at least a 6V rating, connected to ground. The type can be ceramic or tantalum. Refer to **Section 32.0 "Electrical Characteristics"** for additional information on CEFC specifications.

2.4 Master Clear (MCLR) Pin

The MCLR pin provides two specific device functions:

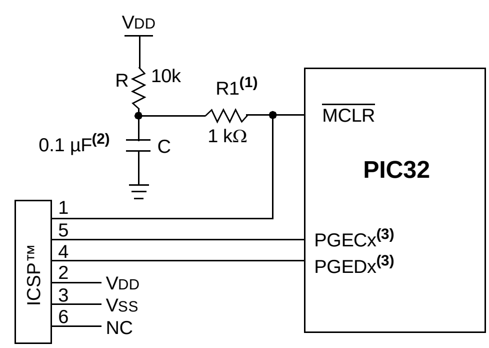
- Device Reset
- Device Programming and Debugging

Pulling The MCLR pin low generates a device Reset. Figure 2-2 illustrates a typical MCLR circuit. During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the MCLR pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as illustrated in Figure 2-2, it is recommended that the capacitor C, be isolated from the MCLR pin during programming and debugging operations.

Place the components illustrated in Figure 2-2 within one-quarter inch (6 mm) from the MCLR pin.

FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS



Note 1: 470Ω ≤ R1 ≤ 1kΩ will limit any current flowing into MCLR from the external capacitor C, in the event of MCLR pin breakdown, due to Electrostatic Discharge (ESD) or Electrical Overstress (EOS). Ensure that the MCLR pin VIH and VIL specifications are met without interfering with the Debug/Programmer tools.

2: The capacitor can be sized to prevent unintentional Resets from brief glitches or to extend the device Reset period during POR.

3: No pull-ups or bypass capacitors are allowed on active debug/program PGECx/PGEDx pins.

2.9 Configuration of Analog and Digital Pins During ICSP Operations

If MPLAB ICD 3 or REAL ICE is selected as a debugger, it automatically initializes all of the Analog-to-Digital input pins (ANx) as "digital" pins by setting all bits in the AD1PCFG register.

The bits in this register that correspond to the Analog-to-Digital pins that are initialized by MPLAB ICD 3 or REAL ICE, must not be cleared by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain ADC pins as analog input pins during the debug session, the user application must clear the corresponding bits in the AD1PCFG register during initialization of the ADC module.

When MPLAB ICD 3 or REAL ICE is used as a programmer, the user application firmware must correctly configure the AD1PCFG register. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all ADC pins being recognized as analog input pins, resulting in the port value being read as a logic '0', which may affect user application functionality.

2.10 Unused I/Os

Unused I/O pins should not be allowed to float as inputs. They can be configured as outputs and driven to a logic-low state.

Alternatively, inputs can be reserved by connecting the pin to Vss through a 1k to 10k resistor and configuring the pin as an input.

2.11 EMI/EMC/EFT (IEC 61000-4-4 and IEC 61000-4-2) Suppression Considerations

The use of LDO regulators is preferred to reduce overall system noise and provide a cleaner power source. However, when utilizing switching Buck/Boost regulators as the local power source for PIC32 devices, as well as in electrically noisy environments or test conditions required for IEC 61000-4-4 and IEC 61000-4-2, users should evaluate the use of T-Filters (i.e., L-C-L) on the power pins, as shown in Figure 2-4. In addition to a more stable power source, use of this type of T-Filter can greatly reduce susceptibility to EMI sources and events.

FIGURE 2-4: EMI/EMC/EFT SUPPRESSION CIRCUIT

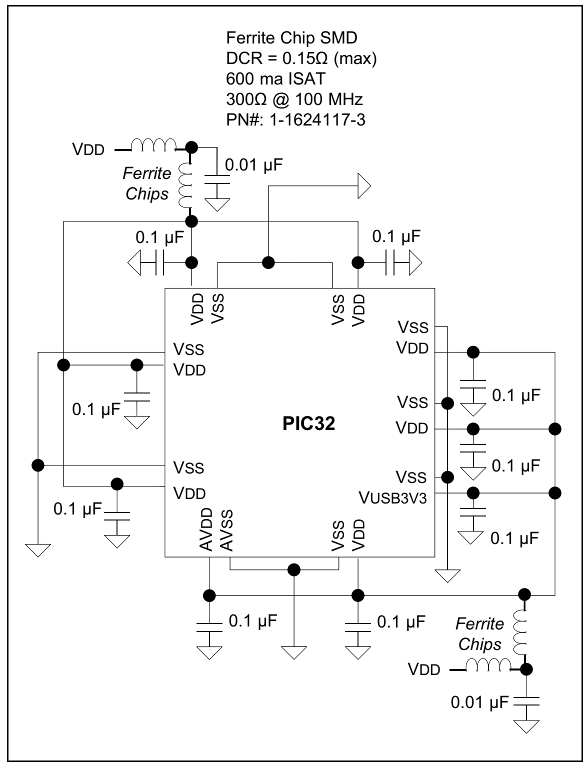


TABLE 7-4: INTERRUPT REGISTER MAP FOR PIC32MX764F128H, PIC32MX775F256H, PIC32MX775F512H AND PIC32MX795F512H DEVICES (CONTINUED)

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
10D0	IPC4	31:16	—	—	—	INT4IP<2:0>			INT4IS<1:0>		—	—	—	OC4IP<2:0>			OC4IS<1:0>		0000
		15:0	—	—	—	IC4IP<2:0>			IC4IS<1:0>		—	—	—	T4IP<2:0>			T4IS<1:0>		0000
10E0	IPC5	31:16	—	—	—	—	—	—	—	—	—	—	—	OC5IP<2:0>			OC5IS<1:0>		0000
		15:0	—	—	—	IC5IP<2:0>			IC5IS<1:0>		—	—	—	T5IP<2:0>			T5IS<1:0>		0000
10F0	IPC6	31:16	—	—	—	AD1IP<2:0>			AD1IS<1:0>		—	—	—	CNIP<2:0>			CNIS<1:0>		0000
		15:0	—	—	—	I2C1IP<2:0>			I2C1IS<1:0>		—	—	—	U1IP<2:0> SPI3IP<2:0> I2C3IP<2:0>			U1IS<1:0> SPI3IS<1:0> I2C3IS<1:0>		0000
1100	IPC7	31:16	—	—	—	U3IP<2:0> SPI2IP<2:0> I2C4IP<2:0>			U3IS<1:0> SPI2IS<1:0> I2C4IS<1:0>		—	—	—	CMP2IP<2:0>			CMP2IS<1:0>		0000
		15:0	—	—	—	CMP1IP<2:0>			CMP1IS<1:0>		—	—	—	PMPIP<2:0>			PMPIS<1:0>		0000
1110	IPC8	31:16	—	—	—	RTCCIP<2:0>			RTCCIS<1:0>		—	—	—	FSCMIP<2:0>			FSCMIS<1:0>		0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	U2IP<2:0> SPI4IP<2:0> I2C5IP<2:0>			U2IS<1:0> SPI4IS<1:0> I2C5IS<1:0>		0000
1120	IPC9	31:16	—	—	—	DMA3IP<2:0>			DMA3IS<1:0>		—	—	—	DMA2IP<2:0>			DMA2IS<1:0>		0000
		15:0	—	—	—	DMA1IP<2:0>			DMA1IS<1:0>		—	—	—	DMA0IP<2:0>			DMA0IS<1:0>		0000
1130	IPC10	31:16	—	—	—	DMA7IP<2:0>(2)			DMA7IS<1:0>(2)		—	—	—	DMA6IP<2:0>(2)			DMA6IS<1:0>(2)		0000
		15:0	—	—	—	DMA5IP<2:0>(2)			DMA5IS<1:0>(2)		—	—	—	DMA4IP<2:0>(2)			DMA4IS<1:0>(2)		0000
1140	IPC11	31:16	—	—	—	CAN2IP<2:0>(2)			CAN2IS<1:0>(2)		—	—	—	CAN1IP<2:0>			CAN1IS<1:0>		0000
		15:0	—	—	—	USBIP<2:0>			USBIS<1:0>		—	—	—	FCEIP<2:0>			FCEIS<1:0>		0000
1150	IPC12	31:16	—	—	—	U5IP<2:0>			U5IS<1:0>		—	—	—	U6IP<2:0>			U6IS<1:0>		0000
		15:0	—	—	—	U4IP<2:0>			U4IS<1:0>		—	—	—	ETHIP<2:0>			ETHIS<1:0>		0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Except where noted, all registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

2: This bit is unimplemented on PIC32MX764F128H device.

3: This register does not have associated CLR, SET, and INV registers.

TABLE 7-6: INTERRUPT REGISTER MAP FOR PIC32MX664F064L, PIC32MX664F128L, PIC32MX675F256L, PIC32MX675F512L AND PIC32MX695F512L DEVICES (CONTINUED)

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
10D0	IPC4	31:16	—	—	—	INT4IP<2:0>			INT4IS<1:0>		—	—	—	OC4IP<2:0>			OC4IS<1:0>		0000
		15:0	—	—	—	IC4IP<2:0>			IC4IS<1:0>		—	—	—	T4IP<2:0>			T4IS<1:0>		0000
10E0	IPC5	31:16	—	—	—	SPI1IP<2:0>			SPI1IS<1:0>		—	—	—	OC5IP<2:0>			OC5IS<1:0>		0000
		15:0	—	—	—	IC5IP<2:0>			IC5IS<1:0>		—	—	—	T5IP<2:0>			T5IS<1:0>		0000
10F0	IPC6	31:16	—	—	—	AD1IP<2:0>			AD1IS<1:0>		—	—	—	CNIP<2:0>			CNIS<1:0>		0000
		15:0	—	—	—	I2C1IP<2:0>			I2C1IS<1:0>		—	—	—	U1IP<2:0>			U1IS<1:0>		0000
														SPI3IP<2:0>			SPI3IS<1:0>		
														I2C3IP<2:0>			I2C3IS<1:0>		
1100	IPC7	31:16	—	—	—	U3IP<2:0>			U3IS<1:0>		—	—	—	CMP2IP<2:0>			CMP2IS<1:0>		0000
						SPI2IP<2:0>			SPI2IS<1:0>										
						I2C4IP<2:0>			I2C4IS<1:0>										
		15:0	—	—	—	CMP1IP<2:0>			CMP1IS<1:0>		—	—	—	PMPIP<2:0>			PMPIS<1:0>		0000
1110	IPC8	31:16	—	—	—	RTCCIP<2:0>			RTCCIS<1:0>		—	—	—	FSCMIP<2:0>			FSCMIS<1:0>		0000
		15:0	—	—	—	I2C2IP<2:0>			I2C2IS<1:0>		—	—	—	U2IP<2:0>			U2IS<1:0>		0000
														SPI4IP<2:0>			SPI4IS<1:0>		
														I2C5IP<2:0>			I2C5IS<1:0>		
1120	IPC9	31:16	—	—	—	DMA3IP<2:0>			DMA3IS<1:0>		—	—	—	DMA2IP<2:0>			DMA2IS<1:0>		0000
		15:0	—	—	—	DMA1IP<2:0>			DMA1IS<1:0>		—	—	—	DMA0IP<2:0>			DMA0IS<1:0>		0000
1130	IPC10	31:16	—	—	—	DMA7IP<2:0>(2)			DMA7IS<1:0>(2)		—	—	—	DMA6IP<2:0>(2)			DMA6IS<1:0>(2)		0000
		15:0	—	—	—	DMA5IP<2:0>(2)			DMA5IS<1:0>(2)		—	—	—	DMA4IP<2:0>(2)			DMA4IS<1:0>(2)		0000
1140	IPC11	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	USBIP<2:0>			USBIS<1:0>		—	—	—	FCEIP<2:0>			FCEIS<1:0>		0000
1150	IPC12	31:16	—	—	—	U5IP<2:0>			U5IS<1:0>		—	—	—	U6IP<2:0>			U6IS<1:0>		0000
		15:0	—	—	—	U4IP<2:0>			U4IS<1:0>		—	—	—	ETHIP<2:0>			ETHIS<1:0>		0000

Legend: x = unknown value on Reset; — = unimplemented, read as ‘0’. Reset values are shown in hexadecimal.

Note 1: Except where noted, all registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

2: These bits are not available on PIC32MX664 devices.

3: This register does note have associated CLR, SET, and INV registers.

REGISTER 7-6: IPCx: INTERRUPT PRIORITY CONTROL REGISTER (CONTINUED)

bit 12-10 **IP01<2:0>:** Interrupt Priority bits

111 = Interrupt priority is 7
•
•
•
010 = Interrupt priority is 2
001 = Interrupt priority is 1
000 = Interrupt is disabled

bit 9-8 **IS01<1:0>:** Interrupt Sub-priority bits

11 = Interrupt sub-priority is 3
10 = Interrupt sub-priority is 2
01 = Interrupt sub-priority is 1
00 = Interrupt sub-priority is 0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-2 **IP00<2:0>:** Interrupt Priority bits

111 = Interrupt priority is 7
•
•
•
010 = Interrupt priority is 2
001 = Interrupt priority is 1
000 = Interrupt is disabled

bit 1-0 **IS00<1:0>:** Interrupt Sub-priority bits

11 = Interrupt sub-priority is 3
10 = Interrupt sub-priority is 2
01 = Interrupt sub-priority is 1
00 = Interrupt sub-priority is 0

Note: This register represents a generic definition of the IPCx register. Refer to Table 7-1 for the exact bit definitions.

8.1 Control Registers

TABLE 8-1: OSCILLATOR REGISTER MAP

Virtual Address (BF80_#)	Register Name(1)	Bit Range	Bits																All Resets(2)
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
F000	OSCCON	31:16	—	—	PLLODIV<2:0>			FRCDIV<2:0>			—	SOSCRDY	—	PBDIV<1:0>		PLLMULT<2:0>			0000
		15:0	—	COSC<2:0>			—	NOSC<2:0>			CLKLOCK	ULOCK	SLOCK	SLPEN	CF	UFRCEN	SOSCEN	OSWEN	0000
F010	OSCTUN	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	TUN<5:0>						0000

Legend: x = unknown value on Reset; — = unimplemented, read as ‘0’. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

2: Reset values are dependent on the DEVCFGx Configuration bits and the type of Reset.

TABLE 10-3: DMA CHANNELS 0-7 REGISTER MAP (CONTINUED)

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
3290	DCH2DAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	CHPDAT<7:0>								0000
32A0	DCH3CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHBUSY	—	—	—	—	—	—	CHCHNS	CHEN	CHAED	CHCHN	CHAEN	—	CHEDET	CHPRI<1:0>		0000
32B0	DCH3ECON	31:16	—	—	—	—	—	—	—	—	CHAIRQ<7:0>								00FF
		15:0	CHSIRQ<7:0>								CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	—	—	—	FF00
32C0	DCH3INT	31:16	—	—	—	—	—	—	—	—	CHSDIE	CHSHIE	CHDDIE	CHDHIE	CHBCIE	CHCCIE	CHTAIE	CHERIE	0000
		15:0	—	—	—	—	—	—	—	—	CHSDIF	CHSHIF	CHDDIF	CHDHIF	CHBCIF	CHCCIF	CHTAIF	CHERIF	0000
32D0	DCH3SSA	31:16	CHSSA<31:0>																0000
		15:0																	0000
32E0	DCH3DSA	31:16	CHDSA<31:0>																0000
		15:0																	0000
32F0	DCH3SSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHSSIZ<15:0>																0000
3300	DCH3DSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHDSIZ<15:0>																0000
3310	DCH3SPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHSPTR<15:0>																0000
3320	DCH3DPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHDPTR<15:0>																0000
3330	DCH3CSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHCSIZ<15:0>																0000
3340	DCH3CPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHCPTR<15:0>																0000
3350	DCH3DAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	CHPDAT<7:0>								0000
3360	DCH4CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	CHBUSY	—	—	—	—	—	—	CHCHNS	CHEN	CHAED	CHCHN	CHAEN	—	CHEDET	CHPRI<1:0>		0000
3370	DCH4ECON	31:16	—	—	—	—	—	—	—	—	CHAIRQ<7:0>								00FF
		15:0	CHSIRQ<7:0>								CFORCE	CABORT	PATEN	SIRQEN	AIRQEN	—	—	—	FF00
3380	DCH4INT	31:16	—	—	—	—	—	—	—	—	CHSDIE	CHSHIE	CHDDIE	CHDHIE	CHBCIE	CHCCIE	CHTAIE	CHERIE	0000
		15:0	—	—	—	—	—	—	—	—	CHSDIF	CHSHIF	CHDDIF	CHDHIF	CHBCIF	CHCCIF	CHTAIF	CHERIF	0000
3390	DCH4SSA	31:16	CHSSA<31:0>																0000
		15:0																	0000
33A0	DCH4DSA	31:16	CHDSA<31:0>																0000
		15:0																	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

2: DMA channels 4-7 are not available on PIC32MX534/564/664/764 devices.

18.0 SERIAL PERIPHERAL INTERFACE (SPI)

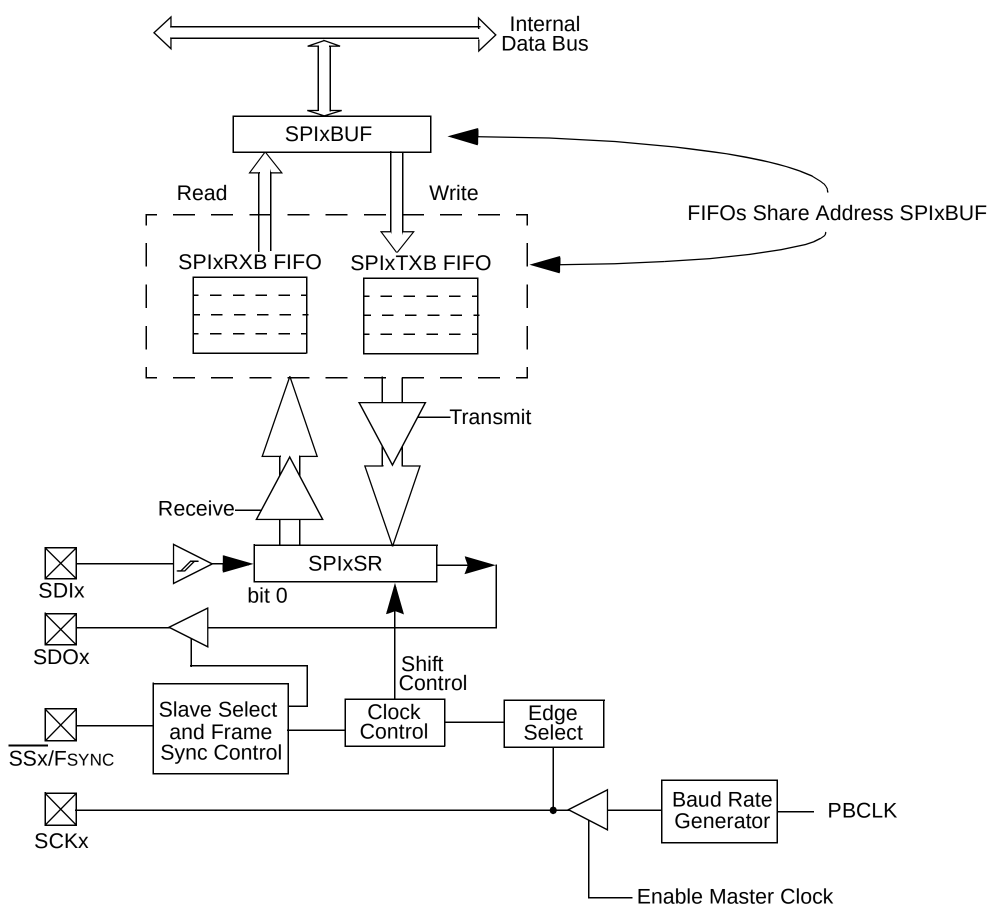
> **Note:** This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 23. “Serial Peripheral Interface (SPI)”** (DS60001106) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site (www.microchip.com/PIC32).

The SPI module is a synchronous serial interface that is useful for communicating with external peripherals and other microcontroller devices. These peripheral devices may be Serial EEPROMs, Shift registers, display drivers, Analog-to-Digital Converters, etc. The PIC32 SPI module is compatible with Motorola® SPI and SIOP interfaces.

The following are some of the key features of the SPI module:

- Master mode and Slave mode support
- Four different clock formats
- Enhanced Framed SPI protocol support
- User-configurable 8-bit, 16-bit and 32-bit data width
- Separate SPI FIFO buffers for receive and transmit
  - FIFO buffers act as 4/8/16-level deep FIFOs based on 32/16/8-bit data width
- Programmable interrupt event on every 8-bit, 16-bit and 32-bit data transfer
- Operation during Sleep and Idle modes
- Fast bit manipulation using CLR, SET and INV registers

FIGURE 18-1: SPI MODULE BLOCK DIAGRAM



Note: Access SPIxTXB and SPIxRXB FIFOs via SPIxBUF register.

REGISTER 19-2: I2CxSTAT: I²C STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R-0, HSC	R-0, HSC	U-0	U-0	U-0	R/C-0, HS	R-0, HSC	R-0, HSC
	ACKSTAT	TRSTAT	—	—	—	BCL	GCSTAT	ADD10
7:0	R/C-0, HS	R/C-0, HS	R-0, HSC	R/C-0, HSC	R/C-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
	IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF

Legend:	HS = Set by hardware	HSC = Hardware set/cleared	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	C = Clearable bit

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ACKSTAT:** Acknowledge Status bit (when operating as I²C master, applicable to master transmit operation)
This bit is set or cleared by hardware at the end of a slave Acknowledge.
1 = NACK received from slave
0 = ACK received from slave

bit 14 **TRSTAT:** Transmit Status bit (when operating as I²C master, applicable to master transmit operation)
This bit is set by hardware at the beginning of a master transmission, and is cleared by hardware at the end of a slave Acknowledge.
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress

bit 13-11 **Unimplemented:** Read as '0'

bit 10 **BCL:** Master Bus Collision Detect bit
This bit is set by hardware at the detection of a bus collision.
1 = A bus collision has been detected during a master operation
0 = No collision

bit 9 **GCSTAT:** General Call Status bit
This bit is set by hardware when the address matches the general call address, and is cleared by hardware clear at a Stop detection.
1 = General call address was received
0 = General call address was not received

bit 8 **ADD10:** 10-bit Address Status bit
This bit is set by hardware upon a match of the 2nd byte of the matched 10-bit address, and is cleared by hardware at a Stop detection.
1 = 10-bit address was matched
0 = 10-bit address was not matched

bit 7 **IWCOL:** Write Collision Detect bit
This bit is set by hardware at the occurrence of a write to I2CxTRN while busy (cleared by software).
1 = An attempt to write the I2CxTRN register failed because the I²C module is busy
0 = No collision

bit 6 **I2COV:** Receive Overflow Flag bit
This bit is set by hardware at an attempt to transfer I2CxRSR to I2CxRCV (cleared by software).
1 = A byte was received while the I2CxRCV register is still holding the previous byte
0 = No overflow

REGISTER 20-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)

bit 8	**TRMT:** Transmit Shift Register is Empty bit (read-only) 1 = Transmit shift register is empty and transmit buffer is empty (the last transmission has completed) 0 = Transmit shift register is not empty, a transmission is in progress or queued in the transmit buffer
bit 7-6	**URXISEL<1:0>:** Receive Interrupt Mode Selection bit 11 = Reserved 10 = Interrupt flag bit is asserted while receive buffer is 3/4 or more full (has 6 or more data characters) 01 = Interrupt flag bit is asserted while receive buffer is 1/2 or more full (has 4 or more data characters) 00 = Interrupt flag bit is asserted while receive buffer is not empty (has at least 1 data character)
bit 5	**ADDEN:** Address Character Detect bit (bit 8 of received data = 1) 1 = Address Detect mode is enabled. If 9-bit mode is not selected, this control bit has no effect. 0 = Address Detect mode is disabled
bit 4	**RIDLE:** Receiver Idle bit (read-only) 1 = Receiver is idle 0 = Data is being received
bit 3	**PERR:** Parity Error Status bit (read-only) 1 = Parity error has been detected for the current character 0 = Parity error has not been detected
bit 2	**FERR:** Framing Error Status bit (read-only) 1 = Framing error has been detected for the current character 0 = Framing error has not been detected
bit 1	**OERR:** Receive Buffer Overrun Error Status bit. This bit is set in hardware and can only be cleared (= 0) in software. Clearing a previously set OERR bit resets the receiver buffer and RSR to an empty state. 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed
bit 0	**URXDA:** Receive Buffer Data Available bit (read-only) 1 = Receive buffer has data, at least one more character can be read 0 = Receive buffer is empty

REGISTER 23-1: AD1CON1: ADC CONTROL REGISTER 1 (CONTINUED)

bit 4 **CLRASAM:** Stop Conversion Sequence bit (when the first ADC interrupt is generated)
1 = Stop conversions when the first ADC interrupt is generated. Hardware clears the ASAM bit when the ADC interrupt is generated.
0 = Normal operation, buffer contents will be overwritten by the next conversion sequence

bit 3 **Unimplemented:** Read as '0'

bit 2 **ASAM:** ADC Sample Auto-Start bit
1 = Sampling begins immediately after last conversion completes; SAMP bit is automatically set
0 = Sampling begins when SAMP bit is set

bit 1 **SAMP:** ADC Sample Enable bit(2)
1 = The ADC S&H circuit is sampling
0 = The ADC S&H circuit is holding
When ASAM = 0, writing '1' to this bit starts sampling.
When SSRC<2:0> = 000, writing '0' to this bit will end sampling and start conversion.

bit 0 **DONE:** Analog-to-Digital Conversion Status bit(3)
Clearing this bit will not affect any operation in progress.
1 = Analog-to-digital conversion is done
0 = Analog-to-digital conversion is not done or has not started

Note 1: When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

2: If ASAM = 0, software can write a '1' to start sampling. This bit is automatically set by hardware if ASAM = 1. If SSRC<2:0> = 000, software can write a '0' to end sampling and start conversion. If SSRC<2:0> ≠ '000', this bit is automatically cleared by hardware to end sampling and start conversion.

3: This bit is automatically set by hardware when analog-to-digital conversion is complete. Software can write a '0' to clear this bit (a write of '1' is not allowed). Clearing this bit does not affect any operation already in progress. This bit is automatically cleared by hardware at the start of a new conversion.

REGISTER 24-3: CiINT: CAN INTERRUPT REGISTER (CONTINUED)

bit 14 **WAKIF:** CAN Bus Activity Wake-up Interrupt Flag bit
1 = A bus wake-up activity interrupt has occurred
0 = A bus wake-up activity interrupt has not occurred

bit 13 **CERRIF:** CAN Bus Error Interrupt Flag bit
1 = A CAN bus error has occurred
0 = A CAN bus error has not occurred

bit 12 **SERRIF:** System Error Interrupt Flag bit
1 = A system error occurred (typically an illegal address was presented to the system bus)
0 = A system error has not occurred

bit 11 **RBOVIF:** Receive Buffer Overflow Interrupt Flag bit
1 = A receive buffer overflow has occurred
0 = A receive buffer overflow has not occurred

bit 10-4 **Unimplemented:** Read as '0'

bit 3 **MODIF:** CAN Mode Change Interrupt Flag bit
1 = A CAN module mode change has occurred (OPMOD<2:0> has changed to reflect REQOP)
0 = A CAN module mode change has not occurred

bit 2 **CTMRIF:** CAN Timer Overflow Interrupt Flag bit
1 = A CAN timer (CANTMR) overflow has occurred
0 = A CAN timer (CANTMR) overflow has not occurred

bit 1 **RBIF:** Receive Buffer Interrupt Flag bit
1 = A receive buffer interrupt is pending
0 = A receive buffer interrupt is not pending

bit 0 **TBIF:** Transmit Buffer Interrupt Flag bit
1 = A transmit buffer interrupt is pending
0 = A transmit buffer interrupt is not pending

Note 1: This bit can only be cleared by turning the CAN module Off and On by clearing or setting the ON bit (CiCON<15>).

REGISTER 24-17: CiFLTCON7: CAN FILTER CONTROL REGISTER 7

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN31	MSEL31<1:0>		FSEL31<4:0>				
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN30	MSEL30<1:0>		FSEL30<4:0>				
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN29	MSEL29<1:0>		FSEL29<4:0>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN28	MSEL28<1:0>		FSEL28<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 31 **FLTEN31:** Filter 31 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 30-29 **MSEL31<1:0>:** Filter 31 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 28-24 **FSEL31<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN30:** Filter 30Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 22-21 **MSEL30<1:0>:** Filter 30Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 20-16 **FSEL30<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is ‘0’.

32.1 DC Characteristics

TABLE 32-1: OPERATING MIPS VS. VOLTAGE

Characteristic	V_{DD} Range (in Volts)[1]	Temp. Range (in °C)	Max. Frequency
			PIC32MX5XX/6XX/7XX
DC5	2.3-3.6V	-40°C to +85°C	80 MHz
DC5b	2.3-3.6V	-40°C to +105°C	80 MHz

Note 1: Overall functional device operation at $V_{BORMIN} < V_{DD} < V_{DDMIN}$ is tested, but not characterized. All device Analog modules, such as ADC, etc., will function, but with degraded performance below V_{DDMIN}. Refer to parameter BO10 in Table 32-10 for BOR values.

TABLE 32-2: THERMAL OPERATING CONDITIONS

Rating	Symbol	Min.	Typical	Max.	Unit
Industrial Temperature Devices					
Operating Junction Temperature Range	T_J	-40	—	+125	°C
Operating Ambient Temperature Range	T_A	-40	—	+85	°C
V-Temp Temperature Devices					
Operating Junction Temperature Range	T_J	-40	—	+140	°C
Operating Ambient Temperature Range	T_A	-40	—	+105	°C
Power Dissipation: Internal Chip Power Dissipation: $P_{INT} = V_{DD} \times (I_{DD} - S\ I_{OH})$ I/O Pin Power Dissipation: $I/O = S\ ((\{V_{DD} - V_{OH}\} \times I_{OH}) + S\ (V_{OL} \times I_{OL}))$	P_D	$P_{INT} + P_{I/O}$			W
Maximum Allowed Power Dissipation	P_{DMAX}	$(T_J - T_A)/\theta_{JA}$			W

TABLE 32-3: THERMAL PACKAGING CHARACTERISTICS

Characteristics	Symbol	Typical	Max.	Unit	See Note
Package Thermal Resistance, 121-Pin TFBGA (10x10x1.1 mm)	θ_{JA}	40	—	°C/W	**1**
Package Thermal Resistance, 100-Pin TQFP (14x14x1 mm)	θ_{JA}	43	—	°C/W	**1**
Package Thermal Resistance, 100-Pin TQFP (12x12x1 mm)	θ_{JA}	43	—	°C/W	**1**
Package Thermal Resistance, 64-Pin TQFP (10x10x1 mm)	θ_{JA}	47	—	°C/W	**1**
Package Thermal Resistance, 64-Pin QFN (9x9x0.9 mm)	θ_{JA}	28	—	°C/W	**1**
Package Thermal Resistance, 124-Pin VTLA (9x9x0.9 mm)	θ_{JA}	21	—	°C/W	**1**

Note 1: Junction to ambient thermal resistance, Theta-JA (θ_{JA}) numbers are achieved by package simulations.

TABLE 32-6: DC CHARACTERISTICS: IDLE CURRENT (IIDLE) (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp			
Parameter No.	**Typical[(2)]**	**Max.**	**Units**	**Conditions**		
Idle Current (IIDLE)[(1)] for PIC32MX534/564/664/764 Family Devices						
DC30a	1.5	5	mA	-40ºC, +25ºC, +85ºC	—	4 MHz
DC30c	3.5	6		+105ºC		
DC31a	7	11		-40ºC, +25ºC, +85ºC	—	25 MHz **(Note 3)**
DC32a	13	20	mA	-40ºC, +25ºC, +85ºC	—	60 MHz **(Note 3)**
DC33a	17	25	mA	-40ºC, +25ºC, +85ºC	—	80 MHz
DC33c	20	27		+105ºC		
DC34c	—	40	µA	-40°C	2.3V	LPRC (31 kHz) **(Note 3)**
DC34d		75		+25°C		
DC34e		800		+85°C		
DC34f		1000		+105ºC		
DC35c	30	—	µA	-40°C	3.3V	
DC35d	55			+25°C		
DC35e	230			+85°C		
DC35f	800			+105ºC		
DC36c	—	43	µA	-40°C	3.6V	
DC36d		106		+25°C		
DC36e		800		+85°C		
DC36f		1000		+105ºC		

Note 1: The test conditions for IIDLE current measurements are as follows:

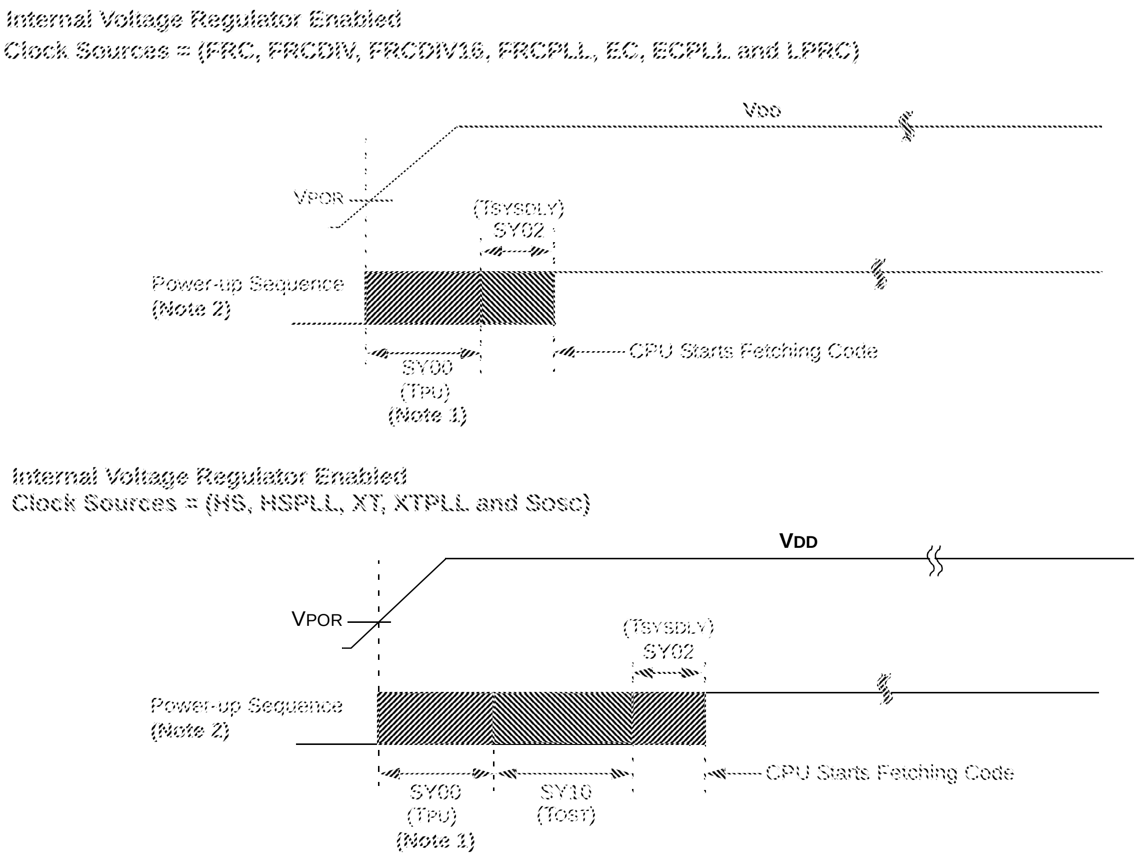
- Oscillator mode is EC (for 8 MHz and below) and EC+PLL (for above 8 MHz) with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)
- OSC2/CLKO is configured as an I/O input pin
- USB PLL oscillator is disabled if the USB module is implemented, PBCLK divisor = 1:8
- CPU is in Idle mode, program Flash memory Wait states = 111, Program Cache and Prefetch are disabled and SRAM data memory Wait states = 1
- No peripheral modules are operating, (ON bit = 0)
- WDT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- All I/O pins are configured as inputs and pulled to VSS
- $\overline{\text{MCLR}}$ = VDD
- RTCC and JTAG are disabled

2: Data in “Typical” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: This parameter is characterized, but not tested in manufacturing.

4: All parameters are characterized, but only those parameters listed for 4 MHz and 80 MHz are tested at 3.3V in manufacturing.

FIGURE 32-4: POWER-ON RESET TIMING CHARACTERISTICS



Note 1: The power-up period will be extended if the power-up sequence completes before the device exits from BOR (VDD < VDDMIN).

2: Includes interval voltage regulator stabilization delay.

FIGURE 32-5: EXTERNAL RESET TIMING CHARACTERISTICS

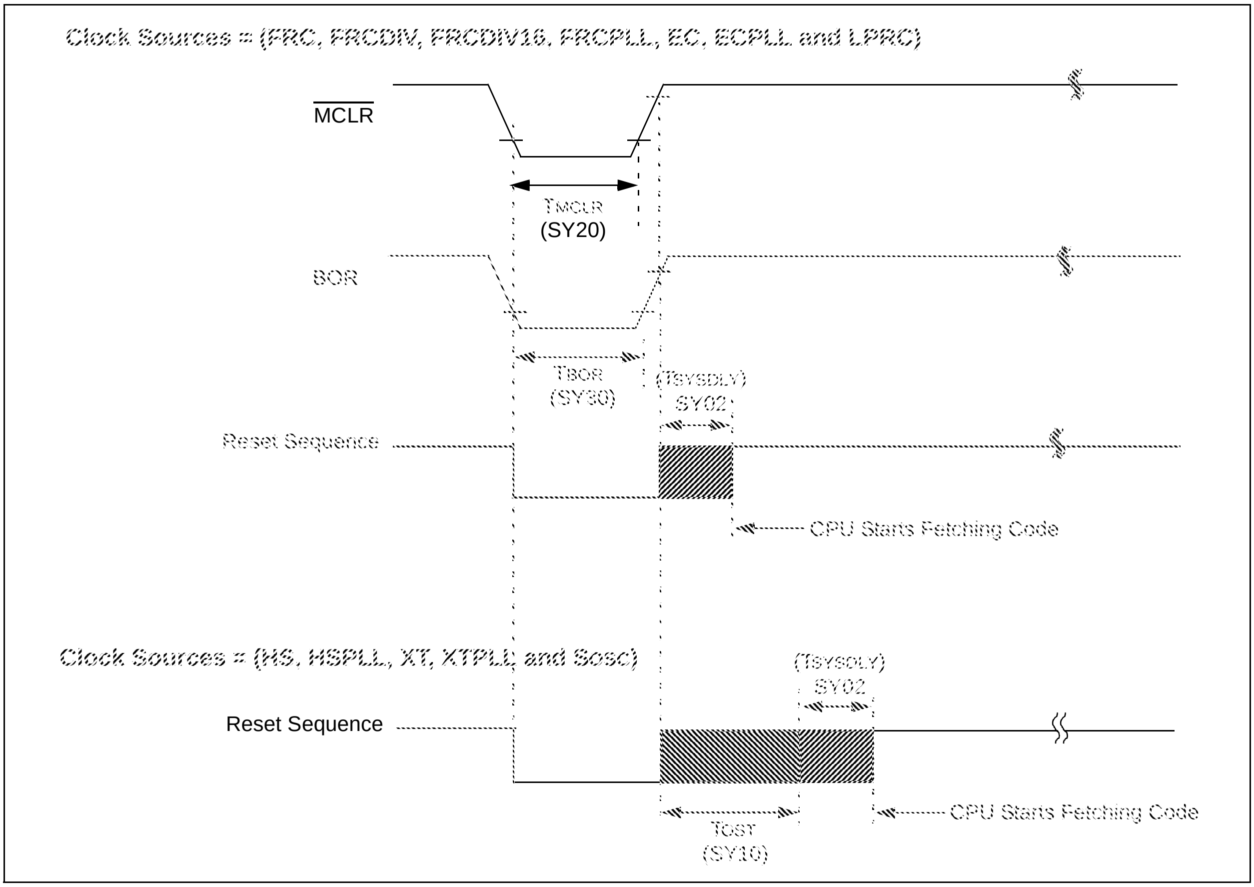


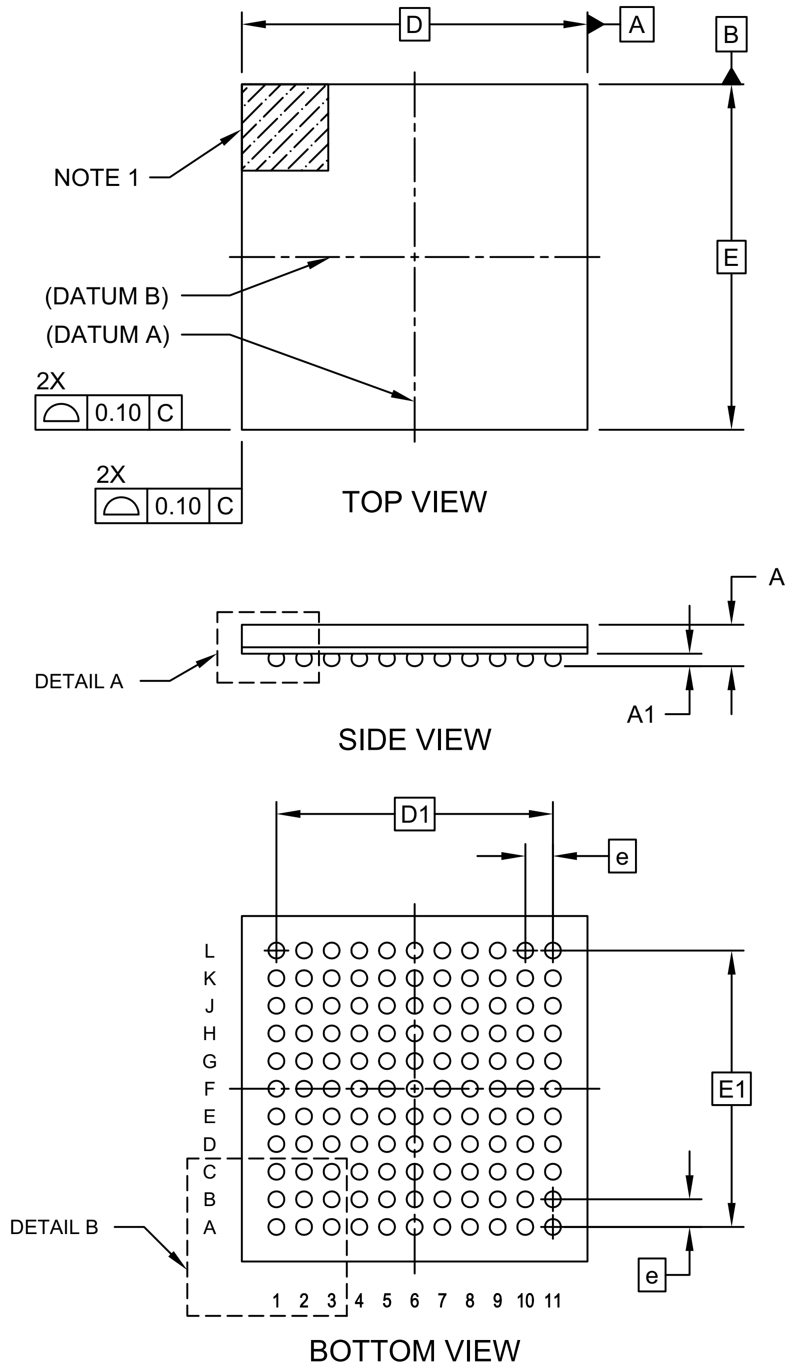
TABLE 32-22: RESETS TIMING

AC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp				
Param. No.	Symbol	Characteristics(1)	Min.	Typical(2)	Max.	Units	Conditions
SY00	TPU	Power-up Period Internal Voltage Regulator Enabled	—	400	600	µs	-40°C to +85°C
SY02	TSYSDLY	System Delay Period: Time Required to Reload Device Configuration Fuses plus SYSCLK Delay before First instruction is Fetched.	—	1 µs + 8 SYSCLK cycles	—	—	-40°C to +85°C
SY20	TMCLR	MCLR Pulse Width (low)	—	2	—	µs	-40°C to +85°C
SY30	TBOR	BOR Pulse Width (low)	—	1	—	µs	-40°C to +85°C

Note 1: These parameters are characterized, but not tested in manufacturing.
2: Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Characterized by design but not tested.

121-Ball Plastic Thin Profile Fine Pitch Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA]

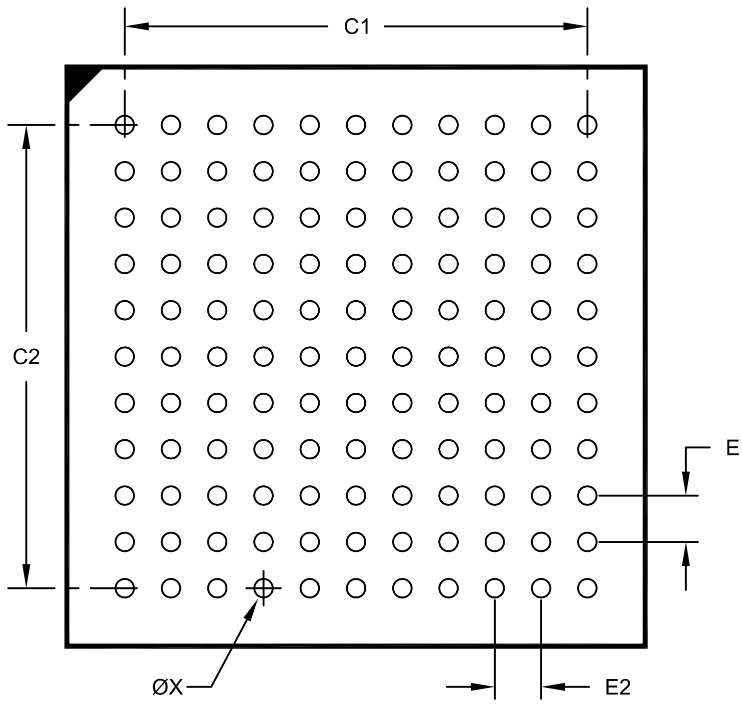
Note:	For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-148 Rev F Sheet 1 of 2

121-Lead Plastic Thin Profile Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA--Formerly XBGA]

Note:	For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E1		0.80 BSC	
Contact Pitch	E2		0.80 BSC	
Contact Pad Spacing	C1		8.00	
Contact Pad Spacing	C2		8.00	
Contact Pad Diameter (X121)	X			0.32

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2148 Rev D