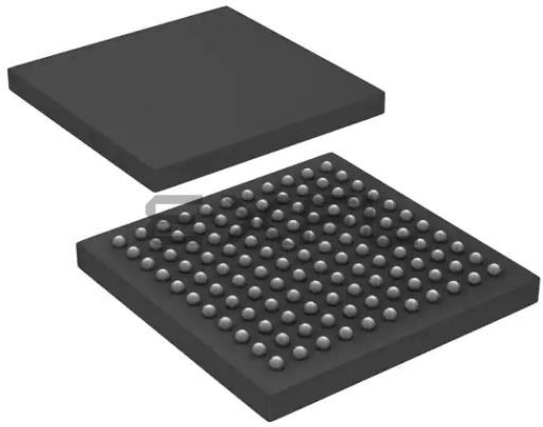
Microchip Technology - PIC32MX575F512L-80I/BG Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, I²C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	-
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	121-TFBGA
Supplier Device Package	121-TFBGA (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx575f512l-80i-bg

TABLE 5: PIN NAMES FOR 64-PIN USB AND ETHERNET DEVICES

64-PIN QFN(2) AND TQFP (TOP VIEW)

PIC32MX664F064H
PIC32MX664F128H
PIC32MX675F256H
PIC32MX675F512H
PIC32MX695F512H

64 1

QFN(2)

64 1

TQFP

Pin #	Full Pin Name	Pin #	Full Pin Name
1	ETXEN/PMD5/RE5	33	USBID/RF3
2	ETXD0/PMD6/RE6	34	VBUS
3	ETXD1/PMD7/RE7	35	VUSB3V3
4	SCK2/U6TX/U3RTS/PMA5/CN8/RG6	36	D-/RG3
5	SDA4/SDI2/U3RX/PMA4/CN9/RG7	37	D+/RG2
6	SCL4/SDO2/U3TX/PMA3/CN10/RG8	38	VDD
7	MCLR	39	OSC1/CLKI/RC12
8	SS2/U6RX/U3CTS/PMA2/CN11/RG9	40	OSC2/CLKO/RC15
9	VSS	41	VSS
10	VDD	42	RTCC/AERXD1/ETXD3/IC1/INT1/RD8
11	AN5/C1IN+/VBUSON/CN7/RB5	43	AERXD0/ETXD2/SS3/U4RX/U1CTS/SDA1/IC2/INT2/RD9
12	AN4/C1IN-/CN6/RB4	44	ECOL/AECRSDV/SCL1/IC3/PMCS2/PMA15/INT3/RD10
13	AN3/C2IN+/CN5/RB3	45	ECRS/AEREFCLK/IC4/PMCS1/PMA14/INT4/RD11
14	AN2/C2IN-/CN4/RB2	46	OC1/INT0/RD0
15	PGEC1/AN1/VREF-/CVREF-/CN3/RB1	47	SOSCI/CN1/RC13
16	PGED1/AN0/VREF+/CVREF+/PMA6/CN2/RB0	48	SOSCO/T1CK/CN0/RC14
17	PGEC2/AN6/OCFA/RB6	49	EMDIO/AEMDIO/SCK3/U4TX/U1RTS/OC2/RD1
18	PGED2/AN7/RB7	50	SDA3/SDI3/U1RX/OC3/RD2
19	AVDD	51	SCL3/SDO3/U1TX/OC4/RD3
20	AVSS	52	OC5/IC5/PMWR/CN13/RD4
21	AN8/SS4/U5RX/U2CTS/C1OUT/RB8	53	PMRD/CN14/RD5
22	AN9/C2OUT/PMA7/RB9	54	AETXEN/ETXERR/CN15/RD6
23	TMS/AN10/CVREFOUT/PMA13/RB10	55	ETXCLK/AERXERR/CN16/RD7
24	TDO/AN11/PMA12/RB11	56	VCAP
25	VSS	57	VDD
26	VDD	58	AETXD1/ERXD3/RF0
27	TCK/AN12/PMA11/RB12	59	AETXD0/ERXD2/RF1
28	TDI/AN13/PMA10/RB13	60	ERXD1/PMD0/RE0
29	AN14/SCK4/U5TX/U2RTSU2RTS/PMALH/PMA1/RB14	61	ERXD0/PMD1/RE1
30	AN15/EMDC/AEMDC/OCFB/PMALL/PMA0/CN12/RB15	62	ERXDV/ECRSDV/PMD2/RE2
31	SDA5/SDI4/U2RX/PMA9/CN17/RF4	63	ERXCLK/EREFCLK/PMD3/RE3
32	SCL5/SDO4/U2TX/PMA8/CN18/RF5	64	ERXERR/PMD4/RE4

Note 1: Shaded pins are 5V tolerant.
2: The metal plane at the bottom of the QFN device is not connected to any pins and is recommended to be connected to VSS externally.

Coprocessor 0 also contains the logic for identifying and managing exceptions. Exceptions can be caused by a variety of sources, including alignment errors in data, external events or program errors. Table 3-3 lists the exception types in order of priority.

TABLE 3-3: PIC32MX5XX/6XX/7XX FAMILY CORE EXCEPTION TYPES

Exception	Description
Reset	Assertion $\overline{\text{MCLR}}$ or a Power-on Reset (POR).
DSS	EJTAG debug single step.
DINT	EJTAG debug interrupt. Caused by the assertion of the external *EJ_DINT* input or by setting the EjtagBrk bit in the ECR register.
NMI	Assertion of NMI signal.
Interrupt	Assertion of unmasked hardware or software interrupt signal.
DIB	EJTAG debug hardware instruction break matched.
AdEL	Fetch address alignment error. Fetch reference to protected address.
IBE	Instruction fetch bus error.
DBp	EJTAG breakpoint (execution of SDBBP instruction).
Sys	Execution of SYSCALL instruction.
Bp	Execution of BREAK instruction.
RI	Execution of a reserved instruction.
CpU	Execution of a coprocessor instruction for a coprocessor that is not enabled.
CEU	Execution of a `CorExtend` instruction when `CorExtend` is not enabled.
Ov	Execution of an arithmetic instruction that overflowed.
Tr	Execution of a trap (when trap condition is true).
DDBL/DDBS	EJTAG Data Address Break (address only) or EJTAG data value break on store (address + value).
AdEL	Load address alignment error. Load reference to protected address.
AdES	Store address alignment error. Store to protected address.
DBE	Load or store bus error.
DDBL	EJTAG data hardware breakpoint matched in load data compare.

REGISTER 4-5: BMXDRMSZ: DATA RAM SIZE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R	R	R	R	R	R	R	R
	BMXDRMSZ<31:24>							
23:16	R	R	R	R	R	R	R	R
	BMXDRMSZ<23:16>							
15:8	R	R	R	R	R	R	R	R
	BMXDRMSZ<15:8>							
7:0	R	R	R	R	R	R	R	R
	BMXDRMSZ<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **BMXDRMSZ<31:0>:** Data RAM Memory (DRM) Size bits
Static value that indicates the size of the Data RAM in bytes:
0x00004000 = device has 16 KB RAM
0x00008000 = device has 32 KB RAM
0x00010000 = device has 64 KB RAM

REGISTER 4-6: BMXPUPBA: PROGRAM FLASH (PFM) USER PROGRAM BASE ADDRESS REGISTER(1,2)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	BMXPUPBA<19:16>			
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0	R-0
	BMXPUPBA<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	BMXPUPBA<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-20 **Unimplemented:** Read as '0'

bit 19-11 **BMXPUPBA<19:11>:** Program Flash (PFM) User Program Base Address bits

bit 10-0 **BMXPUPBA<10:0>:** Program Flash (PFM) User Program Base Address Read-Only bits
Value is always '0', which forces 2 KB increments

Note 1: At Reset, the value in this register is forced to zero, which causes all of the RAM to be allocated to Kernal mode data usage.

2: The value in this register must be less than or equal to BMXPFMSZ.

TABLE 7-5: INTERRUPT REGISTER MAP FOR PIC32MX534F064L, PIC32MX564F064L, PIC32MX564F128L PIC32MX575F512L AND PIC32MX575F256L DEVICES (CONTINUED)

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
10D0	IPC4	31:16	—	—	—	INT4IP<2:0>			INT4IS<1:0>		—	—	—	OC4IP<2:0>			OC4IS<1:0>		0000
		15:0	—	—	—	IC4IP<2:0>			IC4IS<1:0>		—	—	—	T4IP<2:0>			T4IS<1:0>		0000
10E0	IPC5	31:16	—	—	—	SPI1IP<2:0>			SPI1IS<1:0>		—	—	—	OC5IP<2:0>			OC5IS<1:0>		0000
		15:0	—	—	—	IC5IP<2:0>			IC5IS<1:0>		—	—	—	T5IP<2:0>			T5IS<1:0>		0000
10F0	IPC6	31:16	—	—	—	AD1IP<2:0>			AD1IS<1:0>		—	—	—	CNIP<2:0>			CNIS<1:0>		0000
		15:0	—	—	—	I2C1IP<2:0>			I2C1IS<1:0>		—	—	—	U1IP<2:0>			U1IS<1:0>		0000
														SPI3IP<2:0>			SPI3IS<1:0>		
														I2C3IP<2:0>			I2C3IS<1:0>		
1100	IPC7	31:16	—	—	—	U3IP<2:0>			U3IS<1:0>		—	—	—	CMP2IP<2:0>			CMP2IS<1:0>		0000
						SPI2IP<2:0>			SPI2IS<1:0>										
						I2C4IP<2:0>			I2C4IS<1:0>										
		15:0	—	—	—	CMP1IP<2:0>			CMP1IS<1:0>		—	—	—	PMPIP<2:0>			PMPIS<1:0>		0000
1110	IPC8	31:16	—	—	—	RTCCIP<2:0>			RTCCIS<1:0>		—	—	—	FSCMIP<2:0>			FSCMIS<1:0>		0000
		15:0	—	—	—	I2C2IP<2:0>			I2C2IS<1:0>		—	—	—	U2IP<2:0>			U2IS<1:0>		0000
														SPI4IP<2:0>			SPI4IS<1:0>		
														I2C5IP<2:0>			I2C5IS<1:0>		
1120	IPC9	31:16	—	—	—	DMA3IP<2:0>			DMA3IS<1:0>		—	—	—	DMA2IP<2:0>			DMA2IS<1:0>		0000
		15:0	—	—	—	DMA1IP<2:0>			DMA1IS<1:0>		—	—	—	DMA0IP<2:0>			DMA0IS<1:0>		0000
1130	IPC10	31:16	—	—	—	DMA7IP<2:0>(2)			DMA7IS<1:0>(2)		—	—	—	DMA6IP<2:0>(2)			DMA6IS<1:0>(2)		0000
		15:0	—	—	—	DMA5IP<2:0>(2)			DMA5IS<1:0>(2)		—	—	—	DMA4IP<2:0>(2)			DMA4IS<1:0>(2)		0000
1140	IPC11	31:16	—	—	—	—	—	—	—	—	—	—	—	CAN1IP<2:0>			CAN1IS<1:0>		0000
		15:0	—	—	—	USBIP<2:0>			USBIS<1:0>		—	—	—	FCEIP<2:0>			FCEIS<1:0>		0000
1150	IPC12	31:16	—	—	—	U5IP<2:0>			U5IS<1:0>		—	—	—	U6IP<2:0>			U6IS<1:0>		0000
		15:0	—	—	—	U4IP<2:0>			U4IS<1:0>		—	—	—	—	—	—	—	—	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Except where noted, all registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

2: These bits are not available on PIC32MX534/564 devices.

3: This register does not have associated CLR, SET, and INV registers.

TABLE 12-11: PORTG REGISTER MAP FOR PIC32MX534F064H, PIC32MX564F064H, PIC32MX564F128H, PIC32MX575F256H, PIC32MX575F512H, PIC32MX664F064H, PIC32MX664F128H, PIC32MX675F256H, PIC32MX675F512H, PIC32MX695F512H, PIC32MX764F128H, PIC32MX775F256H, PIC32MX775F512H AND PIC32MX795F512H DEVICES

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
6180	TRISG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	TRISG9	TRISG8	TRISG7	TRISG6	—	—	TRISG3	TRISG2	—	—	03CC
6190	PORTG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	RG9	RG8	RG7	RG6	—	—	RG3	RG2	—	—	xxxx
61A0	LATG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	LATG9	LATG8	LATG7	LATG6	—	—	LATG3	LATG2	—	—	xxxx
61B0	ODCG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	ODCG9	ODCG8	ODCG7	ODCG6	—	—	ODCG3	ODCG2	—	—	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

TABLE 12-12: PORTG REGISTER MAP FOR PIC32MX534F064L, PIC32MX564F064L, PIC32MX564F128L, PIC32MX575F256L, PIC32MX575F512L, PIC32MX664F064L, PIC32MX664F128L, PIC32MX675F256L, PIC32MX675F512L, PIC32MX695F512L, PIC32MX764F128L, PIC32MX775F256L, PIC32MX775F512L AND PIC32MX795F512L DEVICES

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
6180	TRISG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	TRISG15	TRISG14	TRISG13	TRISG12	—	—	TRISG9	TRISG8	TRISG7	TRISG6	—	—	TRISG3	TRISG2	TRISG1	TRISG0	F3CF
6190	PORTG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RG15	RG14	RG13	RG12	—	—	RG9	RG8	RG7	RG6	—	—	RG3	RG2	RG1	RG0	xxxx
61A0	LATG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	LATG15	LATG14	LATG13	LATG12	—	—	LATG9	LATG8	LATG7	LATG6	—	—	LATG3	LATG2	LATG1	LATG0	xxxx
61B0	ODCG	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ODCG15	ODCG14	ODCG13	ODCG12	—	—	ODCG9	ODCG8	ODCG7	ODCG6	—	—	ODCG3	ODCG2	ODCG1	ODCG0	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

15.1 Control Registers

TABLE 15-1: WATCHDOG TIMER REGISTER MAP

Virtual Address (BF80_#)	Register Name(1)	Bit Range	Bits																All Resets(2)
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
0000	WDTCON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	—	—	—	—	—	—	—	SWDTPS<4:0>					—	WDTCLR	0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 "CLR, SET and INV Registers"** for more information.

2: Reset values are dependent on the DEVCFGx Configuration bits and the type of Reset.

Figure 20-2 and Figure 20-3 illustrate typical receive and transmit timing for the UART module.

FIGURE 20-2: UART RECEPTION

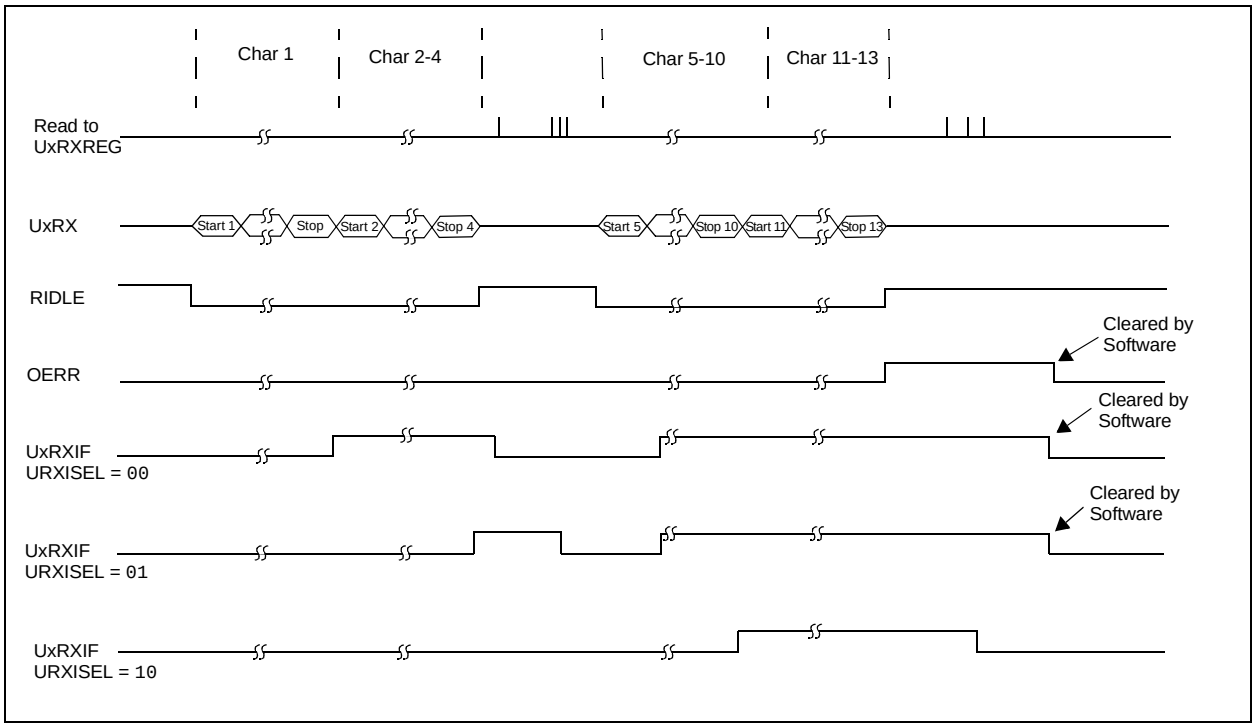
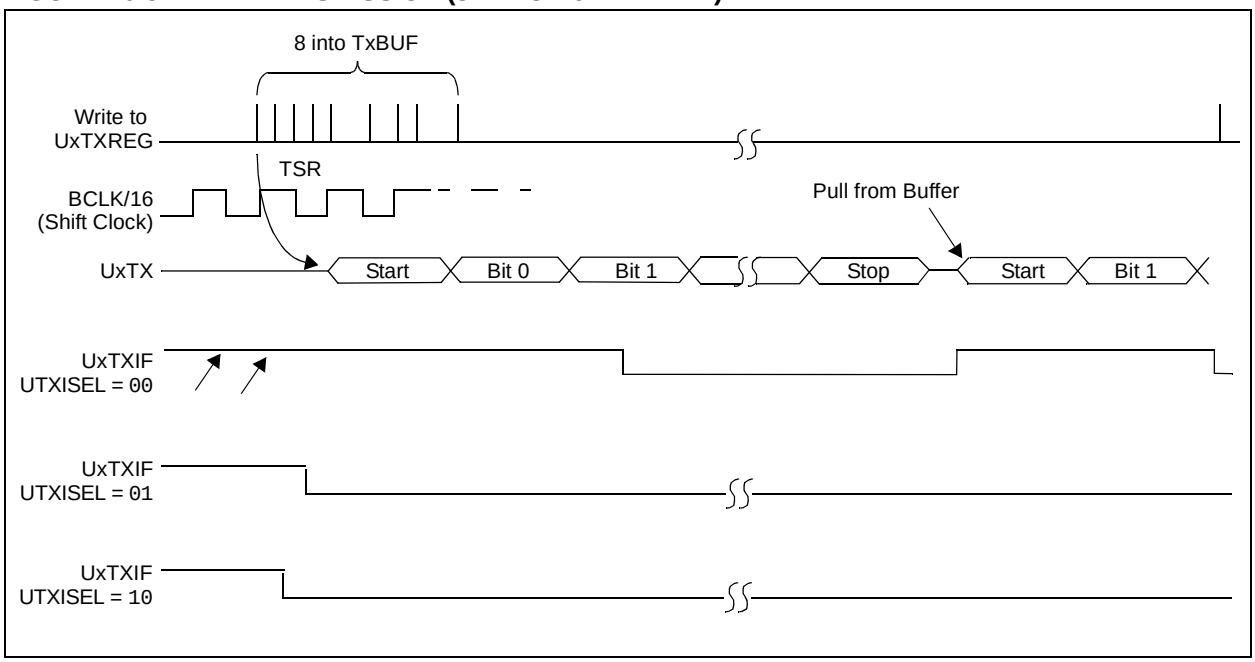


FIGURE 20-3: TRANSMISSION (8-BIT OR 9-BIT DATA)



REGISTER 24-3: CiINT: CAN INTERRUPT REGISTER (CONTINUED)

bit 14 **WAKIF:** CAN Bus Activity Wake-up Interrupt Flag bit
1 = A bus wake-up activity interrupt has occurred
0 = A bus wake-up activity interrupt has not occurred

bit 13 **CERRIF:** CAN Bus Error Interrupt Flag bit
1 = A CAN bus error has occurred
0 = A CAN bus error has not occurred

bit 12 **SERRIF:** System Error Interrupt Flag bit
1 = A system error occurred (typically an illegal address was presented to the system bus)
0 = A system error has not occurred

bit 11 **RBOVIF:** Receive Buffer Overflow Interrupt Flag bit
1 = A receive buffer overflow has occurred
0 = A receive buffer overflow has not occurred

bit 10-4 **Unimplemented:** Read as '0'

bit 3 **MODIF:** CAN Mode Change Interrupt Flag bit
1 = A CAN module mode change has occurred (OPMOD<2:0> has changed to reflect REQOP)
0 = A CAN module mode change has not occurred

bit 2 **CTMRIF:** CAN Timer Overflow Interrupt Flag bit
1 = A CAN timer (CANTMR) overflow has occurred
0 = A CAN timer (CANTMR) overflow has not occurred

bit 1 **RBIF:** Receive Buffer Interrupt Flag bit
1 = A receive buffer interrupt is pending
0 = A receive buffer interrupt is not pending

bit 0 **TBIF:** Transmit Buffer Interrupt Flag bit
1 = A transmit buffer interrupt is pending
0 = A transmit buffer interrupt is not pending

Note 1: This bit can only be cleared by turning the CAN module Off and On by clearing or setting the ON bit (CiCON<15>).

REGISTER 24-12: CiFLTCON2: CAN FILTER CONTROL REGISTER 2 (CONTINUED)

bit 15 **FLTEN9:** Filter 9 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 14-13 **MSEL9<1:0>:** Filter 9 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 12-8 **FSEL9<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 7 **FLTEN8:** Filter 8 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 6-5 **MSEL8<1:0>:** Filter 8 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 4-0 **FSEL8<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 25-24: EMAC1CFG2: ETHERNET CONTROLLER MAC CONFIGURATION 2 REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 25/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
	—	EXCESS DFR	BPNOBK OFF	NOBK OFF	—	—	LONGPRE	PUREPRE
7:0	R/W-1	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-1	R/W-0
	AUTO PAD(1,2)	VLAN PAD(1,2)	PAD ENABLE(1,3)	CRC ENABLE	DELAYCRC	HUGEFRM	LENGTHCK	FULLDPLX

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-15 **Unimplemented:** Read as '0'

bit 14 **EXCESSDER:** Excess Defer bit
- 1 = The MAC will defer to carrier indefinitely as per the Standard
- 0 = The MAC will abort when the excessive deferral limit is reached

bit 13 **BPNOBKOFF:** Backpressure/No Backoff bit
- 1 = The MAC after incidentally causing a collision during backpressure will immediately retransmit without backoff reducing the chance of further collisions and ensuring transmit packets get sent
- 0 = The MAC will not remove the backoff

bit 12 **NOBKOFF:** No Backoff bit
- 1 = Following a collision, the MAC will immediately retransmit rather than using the Binary Exponential Back-off algorithm as specified in the Standard
- 0 = Following a collision, the MAC will use the Binary Exponential Backoff algorithm

bit 11-10 **Unimplemented:** Read as '0'

bit 9 **LONGPRE:** Long Preamble Enforcement bit
- 1 = The MAC only allows receive packets which contain preamble fields less than 12 bytes in length
- 0 = The MAC allows any length preamble as per the Standard

bit 8 **PUREPRE:** Pure Preamble Enforcement bit
- 1 = The MAC will verify the content of the preamble to ensure it contains 0x55 and is error-free. A packet with errors in its preamble is discarded
- 0 = The MAC does not perform any preamble checking

bit 7 **AUTOPAD:** Automatic Detect Pad Enable bit(1,2)
- 1 = The MAC will automatically detect the type of frame, either tagged or untagged, by comparing the two octets following the source address with 0x8100 (VLAN Protocol ID) and pad accordingly
- 0 = The MAC does not perform automatic detection

Note 1: Table 25-6 provides a description of the pad function based on the configuration of this register.
2: This bit is ignored if the PADENABLE bit is cleared.
3: This bit is used in conjunction with the AUTOPAD and VLANPAD bits.

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware

REGISTER 25-24: EMAC1CFG2: ETHERNET CONTROLLER MAC CONFIGURATION 2 REGISTER (CONTINUED)

bit 6 **VLANPAD:** VLAN Pad Enable bit(1,2)
1 = The MAC will pad all short frames to 64 bytes and append a valid CRC
0 = The MAC does not perform padding of short frames

bit 5 **PADENABLE:** Pad/CRC Enable bit(1,3)
1 = The MAC will pad all short frames
0 = The frames presented to the MAC have a valid length

bit 4 **CRCENABLE:** CRC Enable1 bit
1 = The MAC will append a CRC to every frame whether padding was required or not. Must be set if the PADENABLE bit is set.
0 = The frames presented to the MAC have a valid CRC

bit 3 **DELAYCRC:** Delayed CRC bit
This bit determines the number of bytes, if any, of proprietary header information that exist on the front of the IEEE 802.3 frames.
1 = Four bytes of header (ignored by the CRC function)
0 = No proprietary header

bit 2 **HUGEFRM:** Huge Frame enable bit
1 = Frames of any length are transmitted and received
0 = Huge frames are not allowed for receive or transmit

bit 1 **LENGTHCK:** Frame Length checking bit
1 = Both transmit and receive frame lengths are compared to the Length/Type field. If the Length/Type field represents a length then the check is performed. Mismatches are reported on the transmit/receive statistics vector.
0 = Length/Type field check is not performed

bit 0 **FULLDPLX:** Full-Duplex Operation bit
1 = The MAC operates in Full-Duplex mode
0 = The MAC operates in Half-Duplex mode

Note 1: Table 25-6 provides a description of the pad function based on the configuration of this register.
2: This bit is ignored if the PADENABLE bit is cleared.
3: This bit is used in conjunction with the AUTOPAD and VLANPAD bits.

Note:	Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware

TABLE 25-6: PAD OPERATION

Type	AUTOPAD	VLANPAD	PADENABLE	Action
Any	x	x	0	No pad, check CRC
Any	0	0	1	Pad to 60 Bytes, append CRC
Any	x	1	1	Pad to 64 Bytes, append CRC
Any	1	0	1	If untagged: Pad to 60 Bytes, append CRC If VLAN tagged: Pad to 64 Bytes, append CRC

REGISTER 25-33: EMAC1MADR: ETHERNET CONTROLLER MAC MII MANAGEMENT ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
	—	—	—	PHYADDR<4:0>				
7:0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	REGADDR<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-13 **Unimplemented:** Read as '0'

bit 12-8 **PHYADDR<4:0>:** MII Management PHY Address bits

This field represents the 5-bit PHY Address field of Management cycles. Up to 31 PHYs can be addressed (0 is reserved).

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **REGADDR<4:0>:** MII Management Register Address bits

This field represents the 5-bit Register Address field of Management cycles. Up to 32 registers can be accessed.

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

REGISTER 25-34: EMAC1MWTD: ETHERNET CONTROLLER MAC MII MANAGEMENT WRITE DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	MWTD<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	MWTD<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **MWTD<15:0>:** MII Management Write Data bits
When written, a MII Management write cycle is performed using the 16-bit data and the pre-configured PHY and Register addresses from the EMAC1MADR register.

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

REGISTER 25-35: EMAC1MRDD: ETHERNET CONTROLLER MAC MII MANAGEMENT READ DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	MRDD<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	MRDD<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **MRDD<15:0>:** MII Management Read Data bits
Following a MII Management Read Cycle, the 16-bit data can be read from this location.

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

The processor will exit, or 'wake-up', from Sleep mode on one of the following events:

- On any interrupt from an enabled source that is operating in Sleep mode. The interrupt priority must be greater than the current CPU priority.
- On any form of device Reset
- On a WDT time-out

If the interrupt priority is lower than or equal to the current priority, the CPU will remain Halted, but the PBCLK will start running and the device will enter into Idle mode.

28.3.2 IDLE MODE

In Idle mode, the CPU is Halted but the System Clock (SYSCLK) source is still enabled. This allows peripherals to continue operation when the CPU is Halted. Peripherals can be individually configured to Halt when entering Idle by setting their respective SIDL bit. Latency, when exiting Idle mode, is very low due to the CPU oscillator source remaining active.

Note 1: Changing the PBCLK divider ratio requires recalculation of peripheral timing. For example, assume the UART is configured for 9600 baud with a PB clock ratio of 1:1 and a POSC of 8 MHz. When the PB clock divisor of 1:2 is used, the input frequency to the baud clock is cut in half; therefore, the baud rate is reduced to 1/2 its former value. Due to numeric truncation in calculations (such as the baud rate divisor), the actual baud rate may be a tiny percentage different than expected. For this reason, any timing calculation required for a peripheral should be performed with the new PB clock frequency instead of scaling the previous value based on a change in the PB divisor ratio.

2: Oscillator start-up and PLL lock delays are applied when switching to a clock source that was disabled and that uses a crystal and/or the PLL. For example, assume the clock source is switched from POSC to LPRC just prior to entering Sleep in order to save power. No oscillator start-up delay would be applied when exiting Idle. However, when switching back to POSC, the appropriate PLL and/or oscillator start-up/lock delays would be applied.

The device enters Idle mode when the SLPEN bit (OSCCON<4>) is clear and a `WAIT` instruction is executed.

The processor will wake or exit from Idle mode on the following events:

- On any interrupt event for which the interrupt source is enabled. The priority of the interrupt event must be greater than the current priority of the CPU. If the priority of the interrupt event is lower than or equal to current priority of the CPU, the CPU will remain Halted and the device will remain in Idle mode.
- On any form of device Reset
- On a WDT time-out interrupt

28.3.3 PERIPHERAL BUS SCALING METHOD

Most of the peripherals on the device are clocked using the PBCLK. The Peripheral Bus (PB) can be scaled relative to the SYSCLK to minimize the dynamic power consumed by the peripherals. The PBCLK divisor is controlled by PBDIV<1:0> (OSCCON<20:19>), allowing SYSCLK to PBCLK ratios of 1:1, 1:2, 1:4 and 1:8. All peripherals using PBCLK are affected when the divisor is changed. Peripherals such as USB, interrupt controller, DMA, bus matrix and prefetch cache are clocked directly from SYSCLK. As a result, they are not affected by PBCLK divisor changes.

Changing the PBCLK divisor affects:

- The CPU to peripheral access latency. The CPU has to wait for next PBCLK edge for a read to complete. In 1:8 mode, this results in a latency of one to seven SYSCLKs.
- The power consumption of the peripherals. Power consumption is directly proportional to the frequency at which the peripherals are clocked. The greater the divisor, the lower the power consumed by the peripherals.

To minimize dynamic power, the PB divisor should be chosen to run the peripherals at the lowest frequency that provides acceptable system performance. When selecting a PBCLK divider, peripheral clock requirements, such as baud rate accuracy, should be taken into account. For example, the UART peripheral may not be able to achieve all baud rate values at some PBCLK divider depending on the SYSCLK value.

31.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

31.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

31.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

31.9 PICkit 3 In-Circuit Debugger/ Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

31.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at V_{DDMIN} and V_{DDMAX} for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

TABLE 32-6: DC CHARACTERISTICS: IDLE CURRENT (IIDLE) (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp			
Parameter No.	**Typical(2)**	**Max.**	**Units**	**Conditions**		
Idle Current (IIDLE)(1) for PIC32MX534/564/664/764 Family Devices						
DC30a	1.5	5	mA	-40ºC, +25ºC, +85ºC	—	4 MHz
DC30c	3.5	6		+105ºC		
DC31a	7	11		-40ºC, +25ºC, +85ºC	—	25 MHz **(Note 3)**
DC32a	13	20	mA	-40ºC, +25ºC, +85ºC	—	60 MHz **(Note 3)**
DC33a	17	25	mA	-40ºC, +25ºC, +85ºC	—	80 MHz
DC33c	20	27		+105ºC		
DC34c	—	40	µA	-40°C	2.3V	LPRC (31 kHz) **(Note 3)**
DC34d		75		+25°C		
DC34e		800		+85°C		
DC34f		1000		+105ºC		
DC35c	30	—	µA	-40°C	3.3V	
DC35d	55			+25°C		
DC35e	230			+85°C		
DC35f	800			+105ºC		
DC36c	—	43	µA	-40°C	3.6V	
DC36d		106		+25°C		
DC36e		800		+85°C		
DC36f		1000		+105ºC		

Note 1: The test conditions for IIDLE current measurements are as follows:

- Oscillator mode is EC (for 8 MHz and below) and EC+PLL (for above 8 MHz) with OSC1 driven by external square wave from rail-to-rail, (OSC1 input clock input over/undershoot < 100 mV required)
- OSC2/CLKO is configured as an I/O input pin
- USB PLL oscillator is disabled if the USB module is implemented, PBCLK divisor = 1:8
- CPU is in Idle mode, program Flash memory Wait states = 111, Program Cache and Prefetch are disabled and SRAM data memory Wait states = 1
- No peripheral modules are operating, (ON bit = 0)
- WDT, Clock Switching, Fail-Safe Clock Monitor, and Secondary Oscillator are disabled
- All I/O pins are configured as inputs and pulled to VSS
- $\overline{MCLR}$ = VDD
- RTCC and JTAG are disabled

2: Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: This parameter is characterized, but not tested in manufacturing.

4: All parameters are characterized, but only those parameters listed for 4 MHz and 80 MHz are tested at 3.3V in manufacturing.

FIGURE 32-28: EJTAG TIMING CHARACTERISTICS

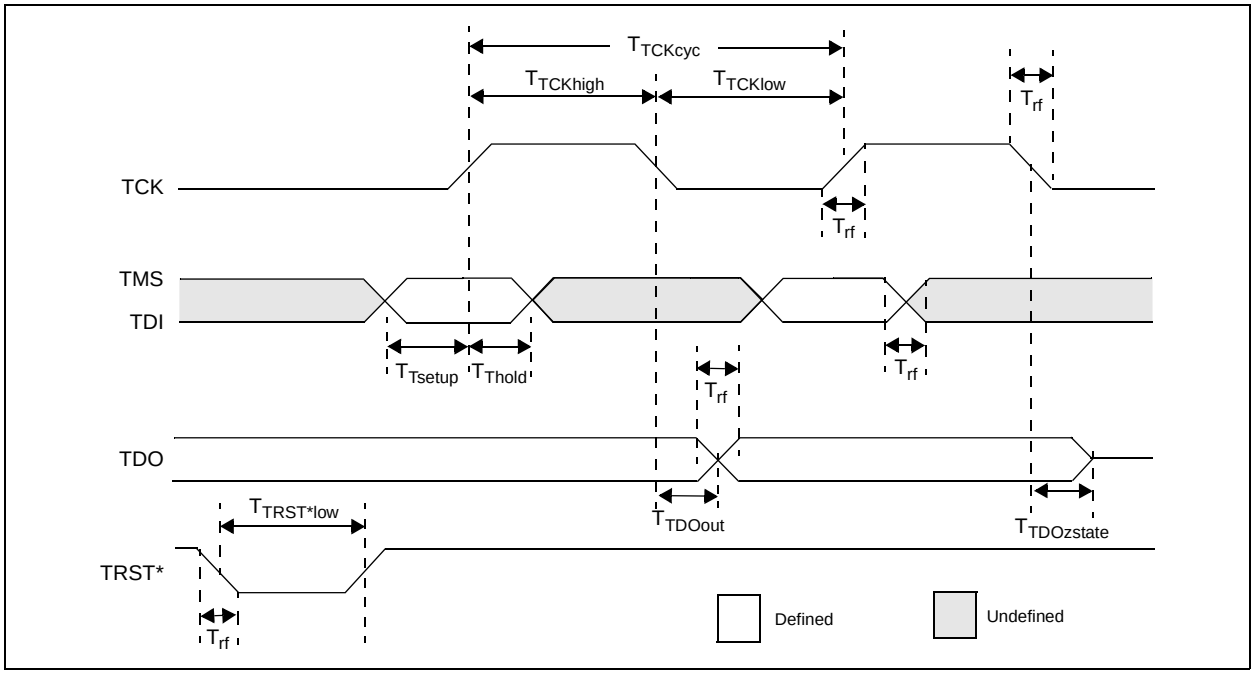


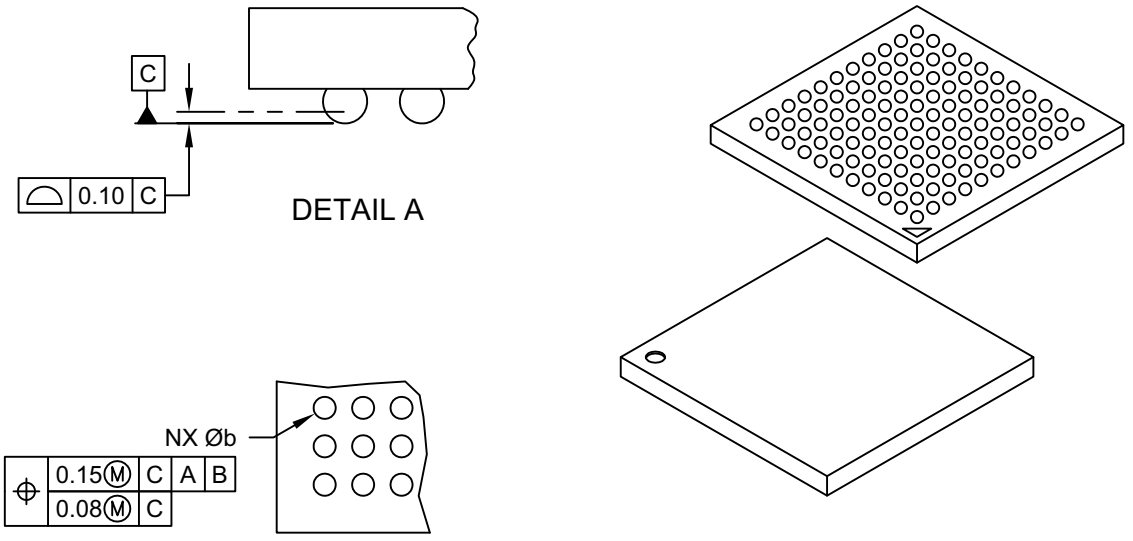
TABLE 32-43: EJTAG TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp			
Param. No.	**Symbol**	**Description(1)**	**Min.**	**Max.**	**Units**	**Conditions**
EJ1	TTCKCYC	TCK Cycle Time	25	—	ns	—
EJ2	TTCKHIGH	TCK High Time	10	—	ns	—
EJ3	TTCKLOW	TCK Low Time	10	—	ns	—
EJ4	TTSETUP	TAP Signals Setup Time Before Rising TCK	5	—	ns	—
EJ5	TTHOLD	TAP Signals Hold Time After Rising TCK	3	—	ns	—
EJ6	TTDOOUT	TDO Output Delay Time from Falling TCK	—	5	ns	—
EJ7	TTDOZSTATE	TDO 3-State Delay Time from Falling TCK	—	5	ns	—
EJ8	TTRSTLOW	TRST Low Time	25	—	ns	—
EJ9	TRF	TAP Signals Rise/Fall Time, All Input and Output	—	—	ns	—

Note 1: These parameters are characterized, but not tested in manufacturing.

121-Ball Plastic Thin Profile Fine Pitch Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Contacts	N		121	
Contact Pitch	e		0.80 BSC	
Overall Height	A	1.00	1.10	1.20
Ball Height	A1	0.25	0.30	0.35
Overall Width	E		10.00 BSC	
Array Width	E1		8.00 BSC	
Overall Length	D		10.00 BSC	
Array Length	D1		8.00 BSC	
Contact Diameter	b	0.35	0.40	0.45

Notes:

1. Ball A1 visual index feature may vary, but must be located within the hatched area.
2. Dimensioning and tolerancing per ASME Y14.5M.
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.
   REF: Reference Dimension, usually without tolerance, for information purposes only.
3. The outer rows and colums of balls are located with respect to datums A and B.
4. Ball interface to package body: 0.37mm nominal diameter.

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TABLE B-4: SECTION UPDATES (CONTINUED)

Section Name	Update Description
7.0 "Interrupt Controller"	• Updated the following Interrupt Sources in Table 7-1: - Changed IC2AM – I2C4 Master Event to: IC4M – I2C4 Master Event - Changed IC3AM – I2C5 Master Event to: IC5M – I2C4 Master Event - Changed U1E – UART1A Error to: U1E – UART1 Error - Changed U4E – UART1B Error to: U4E – UART4 Error - Changed U1RX – UART1A Receiver to: U1RX – UART1 Receiver - Changed U4RX – UART1B Receiver to: U4RX – UART4 Receiver - Changed U1TX – UART1A Transmitter to: U1TX – UART1 Transmitter - Changed U4TX – UART1B Transmitter to: U4TX – UART4 Transmitter - Changed U6E – UART2B Error to: U6E – UART6 Error - Changed U6RX – UART2B Receiver to: U6RX – UART6 Receiver - Changed U6TX – UART2B Transmitter to: U6TX – UART6 Transmitter - Changed U5E – UART3B Error to: U5E – UART5 Error - Changed U5RX – UART3B Receiver to: U5RX – UART5 Receiver - Changed U5TX – UART3B Transmitter to: U5TX – UART5 Transmitter
1.0 "Oscillator Configuration"	Updated Figure 1-1
1.0 "Output Compare"	Updated Figure 1-1
1.0 "Ethernet Controller"	Added a note on using the Ethernet controller pins (see note above Table 1-3)
1.0 "Comparator Voltage Reference (CV_{REF})"	Updated the note in Figure 1-1
1.0 "Special Features"	Updated the bit description for bit 10 in Register 1-2 Added notes 1 and 2 to Register 1-4
1.0 "Electrical Characteristics"	Updated the Absolute Maximum Ratings: • Voltage on any 5V tolerant pin with respect to V_{SS} when V_{DD} < 2.3V - 0.3V to +3.6V was updated • Voltage on V_{BUS} with respect to V_{SS} - 0.3V to +5.5V was added Updated the maximum value of DC16 as 2.1 in Table 1-4 Updated the Typical values for the following parameters: DC20b, DC20c, DC21c, DC22c and DC23c (see Table 1-5) Updated Table 1-11: • Removed the following DC Characteristics: Programming temperature 0°C ≤ TA ≤ +70°C (25°C recommended) • Updated the Minimum value for the Parameter number D131 as 2.3 • Removed the Conditions for the following Parameter numbers: D130, D131, D132, D135, D136 and D137 • Updated the condition for the parameter number D130a and D132a Updated the Minimum, Typical and Maximum values for parameter D305 in Table 1-13 Added note 2 to Table 1-18 Updated the Minimum and Maximum values for parameter F20b (see Table 1-19) Updated the following figures: • Figure 1-4 • Figure 1-9 • Figure 1-22 • Figure 1-23
Appendix A: "Migrating from PIC32MX3XX/4XX to PIC32MX5XX/ 6XX/7XX Devices"	Removed the A.3 Pin Assignments sub-section.

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