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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	CANbus, I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx575f512lt-80v-pf

PIC32MX5XX/6XX/7XX

TABLE 8: PIN NAMES FOR 100-PIN USB AND ETHERNET DEVICES

100-PIN TQFP (TOP VIEW)			
PIC32MX664F064L PIC32MX664F128L PIC32MX675F256L PIC32MX675F512L PIC32MX695F512L		100 1	
Pin #	Full Pin Name	Pin #	Full Pin Name
1	AERXERR/RG15	36	Vss
2	VDD	37	VDD
3	PMD5/RE5	38	TCK/RA1
4	PMD6/RE6	39	SCK4/U5TX/U2RTS/RF13
5	PMD7/RE7	40	SS4/U5RX/U2CTS/RF12
6	T2CK/RC1	41	AN12/ERXD0/AECRS/PMA11/RB12
7	T3CK/RC2	42	AN13/ERXD1/AECOL/PMA10/RB13
8	T4CK/RC3	43	AN14/ERXD2/AETXD3/PMALH/PMA1/RB14
9	T5CK/SDI1/RC4	44	AN15/ERXD3/AETXD2/OCFB/PMALL/PMA0/CN12/RB15
10	ECOL/SCK2/U6TX/U3RTS/PMA5/CN8/RG6	45	Vss
11	ECRS/SDA4/SDI2/U3RX/PMA4/CN9/RG7	46	VDD
12	ERXD0/AERXDV/ECRSDV/AECRSDV/SCL4/SDO2/U3TX/PMA3/CN10/RG8	47	AETXD0/SS3/U4RX/U1CTS/CN20/RD14
13	MCLR	48	AETXD1/SCK3/U4TX/U1RTS/CN21/RD15
14	ERXCLK/AERXCLK/EREFCLK/AEREFCLK/SS2/U6RX/U3CTS/PMA2/CN11/RG9	49	SDA5/SDI4/U2RX/PMA9/CN17/RF4
15	Vss	50	SCL5/SDO4/U2TX/PMA8/CN18/RF5
16	VDD	51	USBID/RF3
17	TMS/RA0	52	SDA3/SDI3/U1RX/RF2
18	AERXD0/INT1/RE8	53	SCL3/SDO3/U1TX/RF8
19	AERXD1/INT2/RE9	54	VBUS
20	AN5/C1IN+/VBUSN/CN7/RB5	55	VUSB3V3
21	AN4/C1IN-/CN6/RB4	56	D-/RG3
22	AN3/C2IN+/CN5/RB3	57	D+/RG2
23	AN2/C2IN-/CN4/RB2	58	SCL2/RA2
24	PGEC1/AN1/CN3/RB1	59	SDA2/RA3
25	PGED1/AN0/CN2/RB0	60	TDI/RA4
26	PGEC2/AN6/OCFA/RB6	61	TDO/RA5
27	PGED2/AN7/RB7	62	VDD
28	VREF-/CVREF-/AERXD2/PMA7/RA9	63	OSC1/CLKI/RC12
29	VREF+/CVREF+/AERXD3/PMA6/RA10	64	OSC2/CLKO/RC15
30	AVDD	65	Vss
31	AVss	66	AETXCLK/SCL1/INT3/RA14
32	AN8/C1OUT/RB8	67	AETXEN/SDA1/INT4/RA15
33	AN9/C2OUT/RB9	68	RTCC/EMDIO/AEMDIO/IC1/RD8
34	AN10/CVREFOUT/PMA13/RB10	69	SS1/IC2/RD9
35	AN11/ERXERR/AETXERR/PMA12/RB11	70	SCK1/IC3/PMCS2/PMA15/RD10

Note 1: Shaded pins are 5V tolerant.

PIC32MX5XX/6XX/7XX

TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)

Pin Name	Pin Number ⁽¹⁾				Pin Type	Buffer Type	Description
	64-Pin QFN/TQFP	100-Pin TQFP	121-Pin TFBGA	124-pin VTLA			
RG0	—	90	A5	A61	I/O	ST	PORTG is a bidirectional I/O port
RG1	—	89	E6	B50	I/O	ST	
RG6	4	10	E3	A7	I/O	ST	
RG7	5	11	F4	B6	I/O	ST	
RG8	6	12	F2	A8	I/O	ST	
RG9	8	14	F3	A9	I/O	ST	
RG12	—	96	C3	A65	I/O	ST	
RG13	—	97	A3	B55	I/O	ST	
RG14	—	95	C4	B54	I/O	ST	
RG15	—	1	B2	A2	I/O	ST	
RG2	37	57	H10	B31	I	ST	PORTG input pins
RG3	36	56	J11	A38	I	ST	
T1CK	48	74	B11	B40	I	ST	Timer1 external clock input
T2CK	—	6	D1	A5	I	ST	Timer2 external clock input
T3CK	—	7	E4	B4	I	ST	Timer3 external clock input
T4CK	—	8	E2	A6	I	ST	Timer4 external clock input
T5CK	—	9	E1	B5	I	ST	Timer5 external clock input
U1CTS	43	47	L9	B26	I	ST	UART1 clear to send
U1RTS	49	48	K9	A31	O	—	UART1 ready to send
U1RX	50	52	K11	A36	I	ST	UART1 receive
U1TX	51	53	J10	B29	O	—	UART1 transmit
U3CTS	8	14	F3	A9	I	ST	UART3 clear to send
U3RTS	4	10	E3	A7	O	—	UART3 ready to send
U3RX	5	11	F4	B6	I	ST	UART3 receive
U3TX	6	12	F2	A8	O	—	UART3 transmit
U2CTS	21	40	K6	A27	I	ST	UART2 clear to send
U2RTS	29	39	L6	B22	O	—	UART2 ready to send
U2RX	31	49	L10	B27	I	ST	UART2 receive
U2TX	32	50	L11	A32	O	—	UART2 transmit
U4RX	43	47	L9	B26	I	ST	UART4 receive
U4TX	49	48	K9	A31	O	—	UART4 transmit
U6RX	8	14	F3	A9	I	ST	UART6 receive
U6TX	4	10	E3	A7	O	—	UART6 transmit
U5RX	21	40	K6	A27	I	ST	UART5 receive
U5TX	29	39	L6	B22	O	—	UART5 transmit
SCK1	—	70	D11	B38	I/O	ST	Synchronous serial clock input/output for SPI1

Legend: CMOS = CMOS compatible input or output
ST = Schmitt Trigger input with CMOS levels
TTL = TTL input buffer

Analog = Analog input
O = Output
P = Power
I = Input

Note 1: Pin numbers are only provided for reference. See the “**Device Pin Tables**” section for device pin availability.

2: See **25.0 “Ethernet Controller”** for more information.

The MIPS architecture defines that the result of a multiply or divide operation be placed in the HI and LO registers. Using the Move-From-HI (MFHI) and Move-From-LO (MFLO) instructions, these values can be transferred to the General Purpose Register file.

In addition to the HI/LO targeted operations, the MIPS32 architecture also defines a multiply instruction, MUL, which places the least significant results in the primary register file instead of the HI/LO register pair. By avoiding the explicit MFLO instruction required when using the LO register, and by supporting multiple destination registers, the throughput of multiply-intensive operations is increased.

Two other instructions, Multiply-Add (MADD) and Multiply-Subtract (MSUB), are used to perform the multiply-accumulate and multiply-subtract operations. The MADD instruction multiplies two numbers and then adds the product to the current contents of the HI and LO registers. Similarly, the MSUB instruction multiplies two operands and then subtracts the product from the HI and LO registers. The MADD and MSUB operations are commonly used in DSP algorithms.

3.2.3 SYSTEM CONTROL COPROCESSOR (CP0)

In the MIPS architecture, CP0 is responsible for the virtual-to-physical address translation, the exception control system, the processor's diagnostics capability, the operating modes (Kernel, User and Debug) and whether interrupts are enabled or disabled. Configuration information, such as presence of options like MIPS16e, is also available by accessing the CP0 registers, listed in Table 3-2.

TABLE 3-2: COPROCESSOR 0 REGISTERS

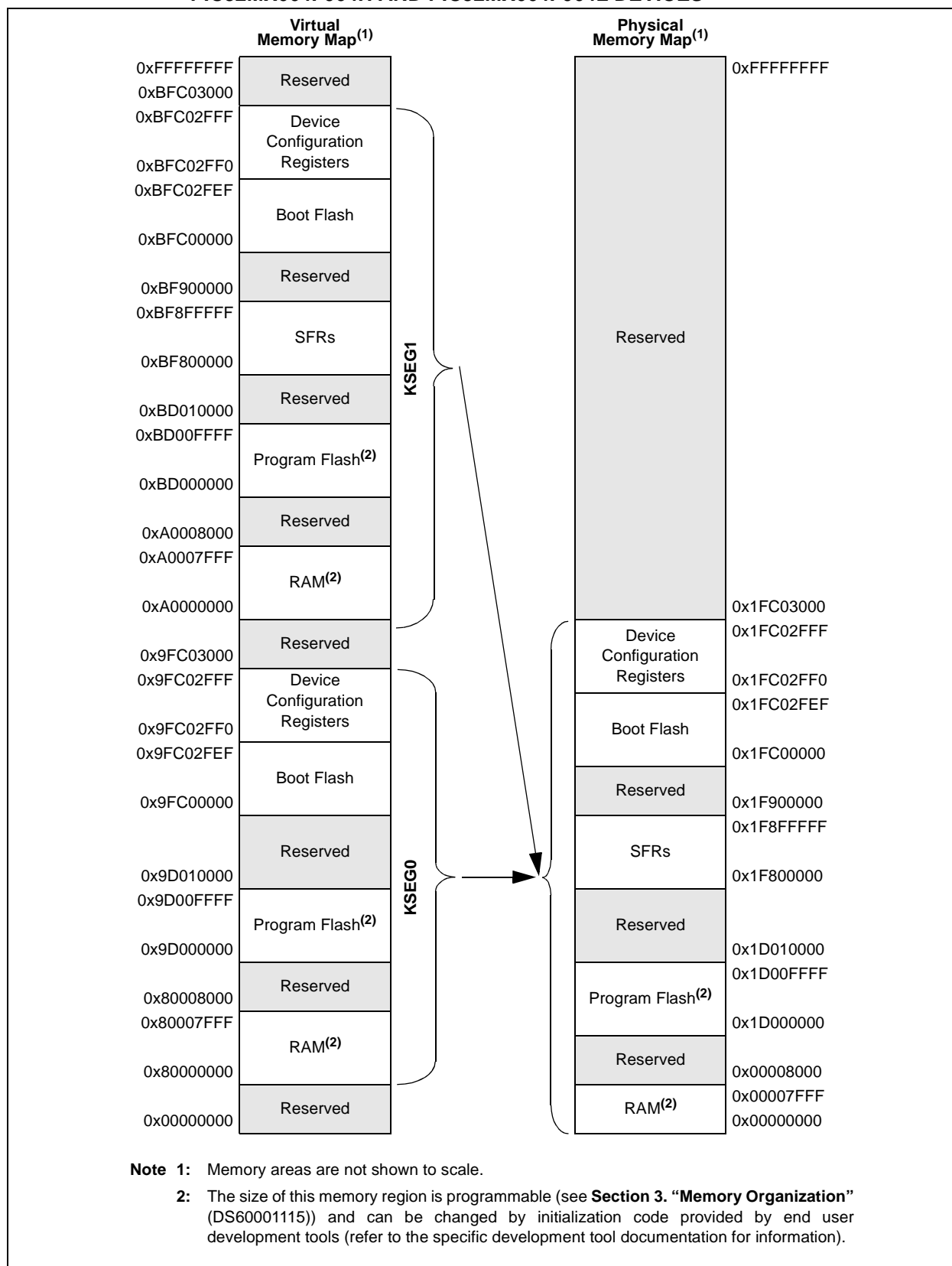
Register Number	Register Name	Function
0-6	Reserved	Reserved.
7	HWREna	Enables access via the RDHWR instruction to selected hardware registers.
8	BadVAddr ⁽¹⁾	Reports the address for the most recent address-related exception.
9	Count ⁽¹⁾	Processor cycle count.
10	Reserved	Reserved.
11	Compare ⁽¹⁾	Timer interrupt control.
12	Status ⁽¹⁾	Processor status and control.
12	IntCtl ⁽¹⁾	Interrupt system status and control.
12	SRSCtl ⁽¹⁾	Shadow register set status and control.
12	SRSMap ⁽¹⁾	Provides mapping from vectored interrupt to a shadow set.
13	Cause ⁽¹⁾	Cause of last general exception.
14	EPC ⁽¹⁾	Program counter at last exception.
15	PRId	Processor identification and revision.
15	Ebase	Exception vector base register.
16	Config	Configuration register.
16	Config1	Configuration Register 1.
16	Config2	Configuration Register 2.
16	Config3	Configuration Register 3.
17-22	Reserved	Reserved.
23	Debug ⁽²⁾	Debug control and exception status.
24	DEPC ⁽²⁾	Program counter at last debug exception.
25-29	Reserved	Reserved.
30	ErrorEPC ⁽¹⁾	Program counter at last error.
31	DESAVE ⁽²⁾	Debug handler scratchpad register.

Note 1: Registers used in exception processing.

2: Registers used during debug.

PIC32MX5XX/6XX/7XX

FIGURE 4-1: MEMORY MAP ON RESET FOR PIC32MX564F064H, PIC32MX564F064L, PIC32MX664F064H AND PIC32MX664F064L DEVICES



PIC32MX5XX/6XX/7XX

REGISTER 5-4: NVMDATA: FLASH PROGRAM DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMDATA<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMDATA<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMDATA<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMDATA<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-0 **NVMDATA<31:0>**: Flash Programming Data bits

Note: The bits in this register are only reset by a Power-on Reset (POR).

REGISTER 5-5: NVMSRCADDR: SOURCE DATA ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMSRCADDR<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMSRCADDR<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMSRCADDR<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	NVMSRCADDR<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-0 **NVMSRCADDR<31:0>**: Source Data Address bits

The system physical address of the data to be programmed into the Flash when the NVMOP<3:0> bits (NVMCON<3:0>) are set to perform row programming.

7.0 INTERRUPT CONTROLLER

Note: This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 8. “Interrupts”** (DS60001108) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site (www.microchip.com/PIC32).

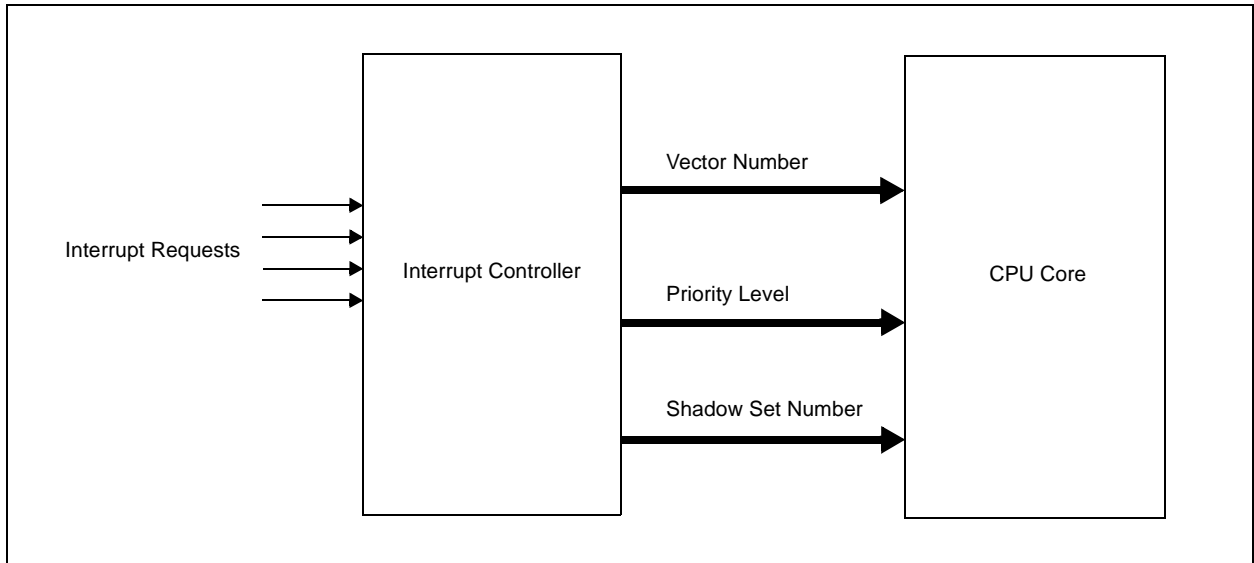
PIC32MX5XX/6XX/7XX devices generate interrupt requests in response to interrupt events from peripheral modules. The interrupt control module exists externally to the CPU logic and prioritizes the interrupt events before presenting them to the CPU.

The Interrupt Controller module includes the following features:

- Up to 96 interrupt sources
- Up to 64 interrupt vectors
- Single and multi-vector mode operations
- Five external interrupts with edge polarity control
- Interrupt proximity timer
- Seven user-selectable priority levels for each vector
- Four user-selectable sub-priority levels within each priority
- Dedicated shadow set for user-selectable priority level
- Software can generate any interrupt
- User-configurable interrupt vector table location
- User-configurable interrupt vector spacing

A simplified block diagram of the Interrupt Controller module is illustrated in Figure 7-1.

FIGURE 7-1: INTERRUPT CONTROLLER MODULE



PIC32MX5XX/6XX/7XX

TABLE 7-1: INTERRUPT IRQ, VECTOR AND BIT LOCATION

Interrupt Source ⁽¹⁾	IRQ Number	Vector Number	Interrupt Bit Location			
			Flag	Enable	Priority	Sub-Priority
Highest Natural Order Priority						
CT – Core Timer Interrupt	0	0	IFS0<0>	IEC0<0>	IPC0<4:2>	IPC0<1:0>
CS0 – Core Software Interrupt 0	1	1	IFS0<1>	IEC0<1>	IPC0<12:10>	IPC0<9:8>
CS1 – Core Software Interrupt 1	2	2	IFS0<2>	IEC0<2>	IPC0<20:18>	IPC0<17:16>
INT0 – External Interrupt 0	3	3	IFS0<3>	IEC0<3>	IPC0<28:26>	IPC0<25:24>
T1 – Timer1	4	4	IFS0<4>	IEC0<4>	IPC1<4:2>	IPC1<1:0>
IC1 – Input Capture 1	5	5	IFS0<5>	IEC0<5>	IPC1<12:10>	IPC1<9:8>
OC1 – Output Compare 1	6	6	IFS0<6>	IEC0<6>	IPC1<20:18>	IPC1<17:16>
INT1 – External Interrupt 1	7	7	IFS0<7>	IEC0<7>	IPC1<28:26>	IPC1<25:24>
T2 – Timer2	8	8	IFS0<8>	IEC0<8>	IPC2<4:2>	IPC2<1:0>
IC2 – Input Capture 2	9	9	IFS0<9>	IEC0<9>	IPC2<12:10>	IPC2<9:8>
OC2 – Output Compare 2	10	10	IFS0<10>	IEC0<10>	IPC2<20:18>	IPC2<17:16>
INT2 – External Interrupt 2	11	11	IFS0<11>	IEC0<11>	IPC2<28:26>	IPC2<25:24>
T3 – Timer3	12	12	IFS0<12>	IEC0<12>	IPC3<4:2>	IPC3<1:0>
IC3 – Input Capture 3	13	13	IFS0<13>	IEC0<13>	IPC3<12:10>	IPC3<9:8>
OC3 – Output Compare 3	14	14	IFS0<14>	IEC0<14>	IPC3<20:18>	IPC3<17:16>
INT3 – External Interrupt 3	15	15	IFS0<15>	IEC0<15>	IPC3<28:26>	IPC3<25:24>
T4 – Timer4	16	16	IFS0<16>	IEC0<16>	IPC4<4:2>	IPC4<1:0>
IC4 – Input Capture 4	17	17	IFS0<17>	IEC0<17>	IPC4<12:10>	IPC4<9:8>
OC4 – Output Compare 4	18	18	IFS0<18>	IEC0<18>	IPC4<20:18>	IPC4<17:16>
INT4 – External Interrupt 4	19	19	IFS0<19>	IEC0<19>	IPC4<28:26>	IPC4<25:24>
T5 – Timer5	20	20	IFS0<20>	IEC0<20>	IPC5<4:2>	IPC5<1:0>
IC5 – Input Capture 5	21	21	IFS0<21>	IEC0<21>	IPC5<12:10>	IPC5<9:8>
OC5 – Output Compare 5	22	22	IFS0<22>	IEC0<22>	IPC5<20:18>	IPC5<17:16>
SPI1E – SPI1 Fault	23	23	IFS0<23>	IEC0<23>	IPC5<28:26>	IPC5<25:24>
SPI1RX – SPI1 Receive Done	24	23	IFS0<24>	IEC0<24>	IPC5<28:26>	IPC5<25:24>
SPI1TX – SPI1 Transfer Done	25	23	IFS0<25>	IEC0<25>	IPC5<28:26>	IPC5<25:24>
U1E – UART1 Error	26	24	IFS0<26>	IEC0<26>	IPC6<4:2>	IPC6<1:0>
SPI3E – SPI3 Fault						
I2C3B – I2C3 Bus Collision Event						
U1RX – UART1 Receiver	27	24	IFS0<27>	IEC0<27>	IPC6<4:2>	IPC6<1:0>
SPI3RX – SPI3 Receive Done						
I2C3S – I2C3 Slave Event						
U1TX – UART1 Transmitter	28	24	IFS0<28>	IEC0<28>	IPC6<4:2>	IPC6<1:0>
SPI3TX – SPI3 Transfer Done						
I2C3M – I2C3 Master Event						
I2C1B – I2C1 Bus Collision Event	29	25	IFS0<29>	IEC0<29>	IPC6<12:10>	IPC6<9:8>
I2C1S – I2C1 Slave Event	30	25	IFS0<30>	IEC0<30>	IPC6<12:10>	IPC6<9:8>
I2C1M – I2C1 Master Event	31	25	IFS0<31>	IEC0<31>	IPC6<12:10>	IPC6<9:8>
CN – Input Change Interrupt	32	26	IFS1<0>	IEC1<0>	IPC6<20:18>	IPC6<17:16>

Note 1: Not all interrupt sources are available on all devices. See **TABLE 1: “PIC32MX5XX USB and CAN Features”**, **TABLE 2: “PIC32MX6XX USB and Ethernet Features”** and **TABLE 3: “PIC32MX7XX USB, Ethernet, and CAN Features”** for the list of available peripherals.

8.0 OSCILLATOR CONFIGURATION

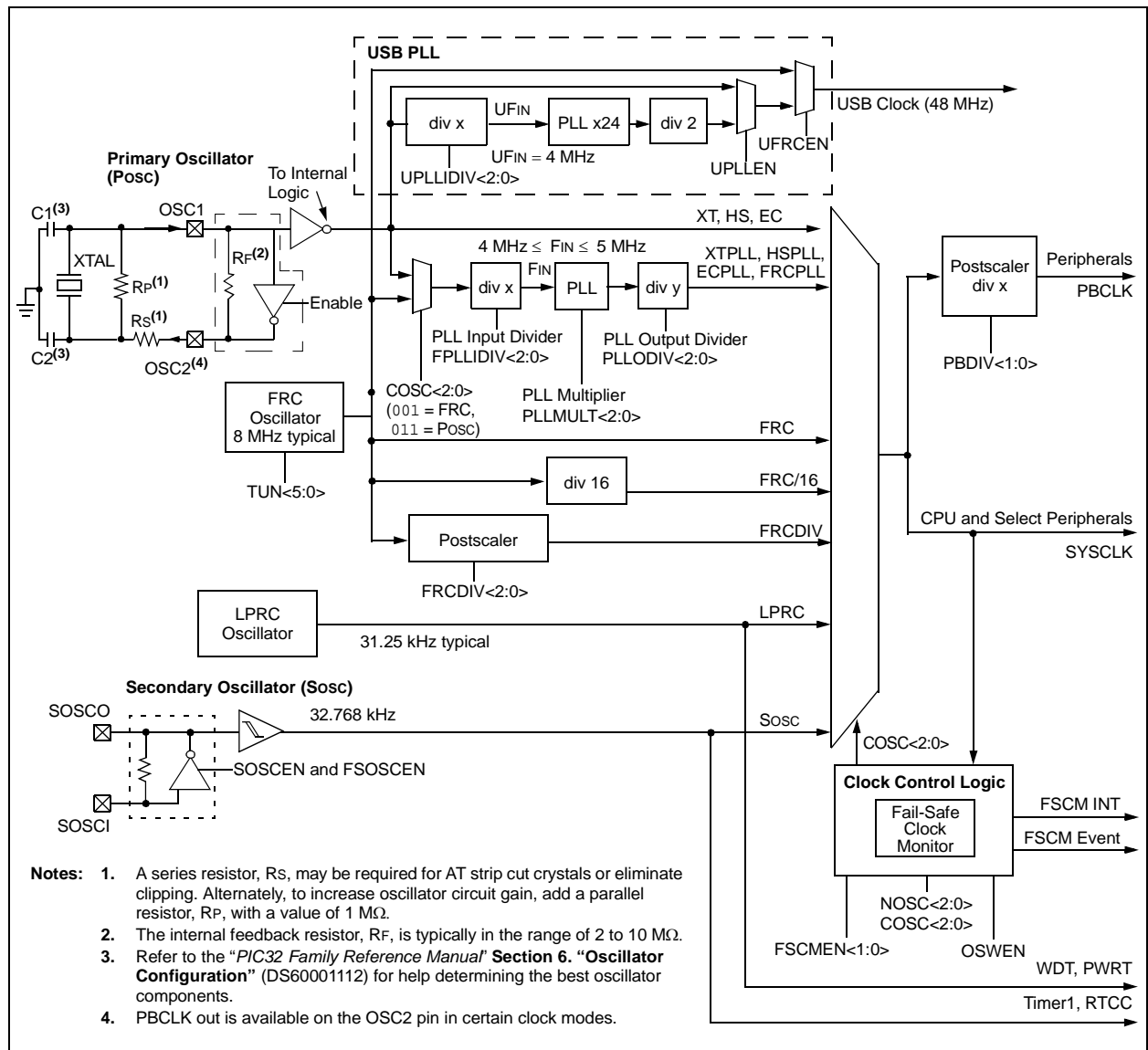
Note: This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 6. "Oscillator"** (DS60001112) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

The Oscillator module has the following features:

- A total of four external and internal oscillator options as clock sources
- On-chip PLL with user-selectable input divider, multiplier and output divider to boost operating frequency on select internal and external oscillator sources
- On-chip user-selectable divisor postscaler on select oscillator sources
- Software-controllable switching between various clock sources
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and permits safe application recovery or shutdown
- Dedicated On-Chip PLL for USB peripheral

Figure 8-1 shows the Oscillator module block diagram.

FIGURE 8-1: OSCILLATOR BLOCK DIAGRAM



REGISTER 9-3: CHETAG: CACHE TAG REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	LTAGBOOT	—	—	—	—	—	—	—
23:16	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	LTAG<19:12>							
15:8	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
	LTAG<11:4>							
7:0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-0	R/W-0	R/W-1	U-0
	LTAG<3:0>				LVALID	LLOCK	LTYPE	—

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31 **LTAGBOOT:** Line Tag Address Boot bit

1 = The line is in the 0x1D000000 (physical) area of memory

0 = The line is in the 0x1FC00000 (physical) area of memory

bit 30-24 **Unimplemented:** Write '0'; ignore read

bit 23-4 **LTAG<19:0>:** Line Tag Address bits

LTAG<19:0> bits are compared against physical address to determine a hit. Because its address range and position of PFM in kernel space and user space, the LTAG PFM address is identical for virtual addresses, (system) physical addresses, and PFM physical addresses.

bit 3 **LVALID:** Line Valid bit

1 = The line is valid and is compared to the physical address for hit detection

0 = The line is not valid and is not compared to the physical address for hit detection

bit 2 **LLOCK:** Line Lock bit

1 = The line is locked and will not be replaced

0 = The line is not locked and can be replaced

bit 1 **LTYPE:** Line Type bit

1 = The line caches instruction words

0 = The line caches data words

bit 0 **Unimplemented:** Write '0'; ignore read

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REGISTER 11-14: U1FRMH: USB FRAME NUMBER HIGH REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	R-0	R-0	R-0
	—	—	—	—	—	FRMH<2:0>		

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-3 **Unimplemented:** Read as '0'

bit 2-0 **FRMH<2:0>:** Upper 3 bits of the Frame Numbers bits

These register bits are updated with the current frame number whenever a SOF TOKEN is received.

REGISTER 11-15: U1TOK: USB TOKEN REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PID<3:0>				EP<3:0>			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-8 **Unimplemented:** Read as '0'

bit 7-4 **PID<3:0>:** Token Type Indicator bits⁽¹⁾

1101 = SETUP (TX) token type transaction

1001 = IN (RX) token type transaction

0001 = OUT (TX) token type transaction

Note: All other values not listed, are Reserved and must not be used.

bit 3-0 **EP<3:0>:** Token Command Endpoint Address bits

The four bit value must specify a valid endpoint.

18.0 SERIAL PERIPHERAL INTERFACE (SPI)

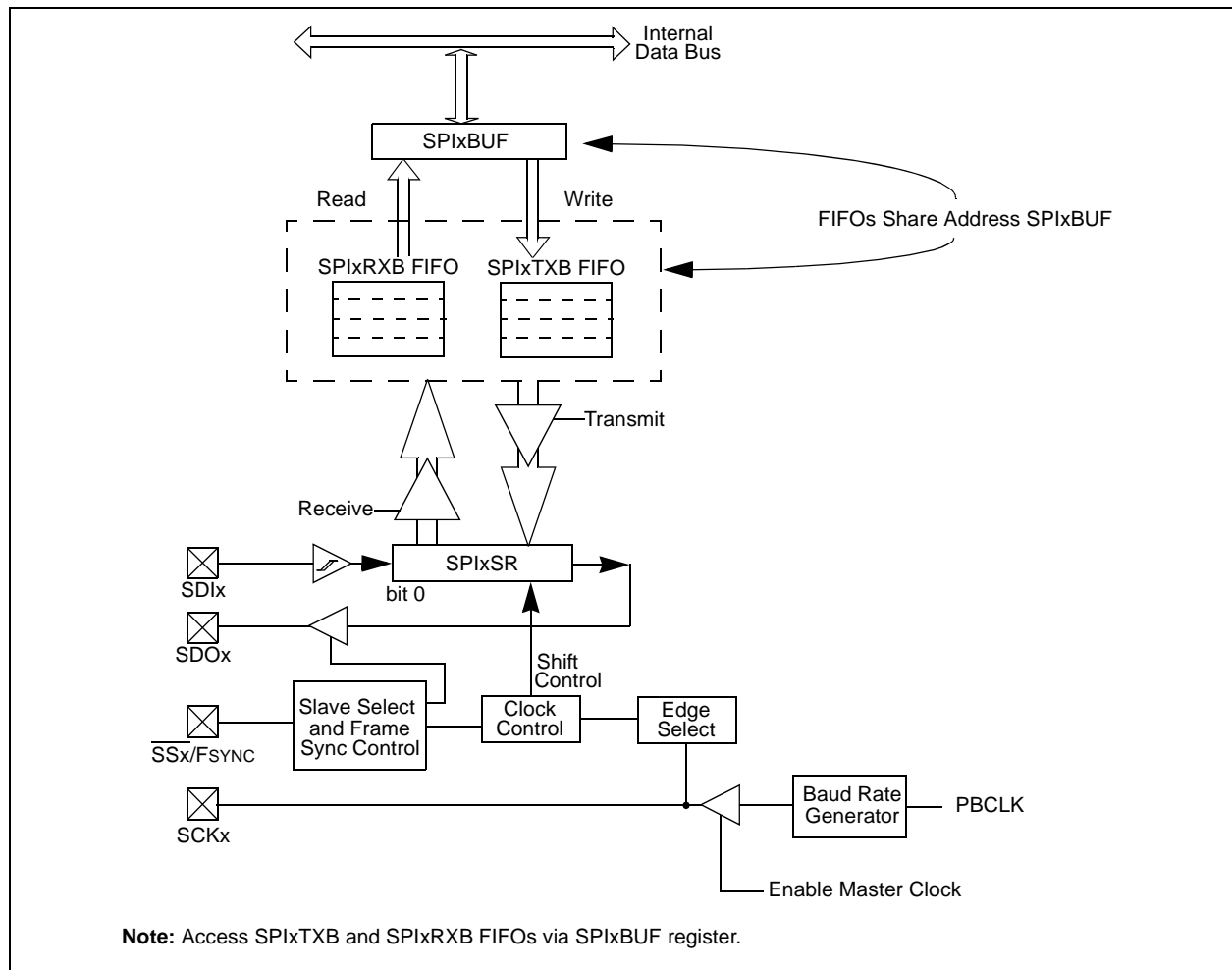
Note: This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 23. “Serial Peripheral Interface (SPI)”** (DS60001106) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site (www.microchip.com/PIC32).

The SPI module is a synchronous serial interface that is useful for communicating with external peripherals and other microcontroller devices. These peripheral devices may be Serial EEPROMs, Shift registers, display drivers, Analog-to-Digital Converters, etc. The PIC32 SPI module is compatible with Motorola® SPI and SIOP interfaces.

The following are some of the key features of the SPI module:

- Master mode and Slave mode support
- Four different clock formats
- Enhanced Framed SPI protocol support
- User-configurable 8-bit, 16-bit and 32-bit data width
- Separate SPI FIFO buffers for receive and transmit
 - FIFO buffers act as 4/8/16-level deep FIFOs based on 32/16/8-bit data width
- Programmable interrupt event on every 8-bit, 16-bit and 32-bit data transfer
- Operation during Sleep and Idle modes
- Fast bit manipulation using CLR, SET and INV registers

FIGURE 18-1: SPI MODULE BLOCK DIAGRAM



22.1 Control Registers

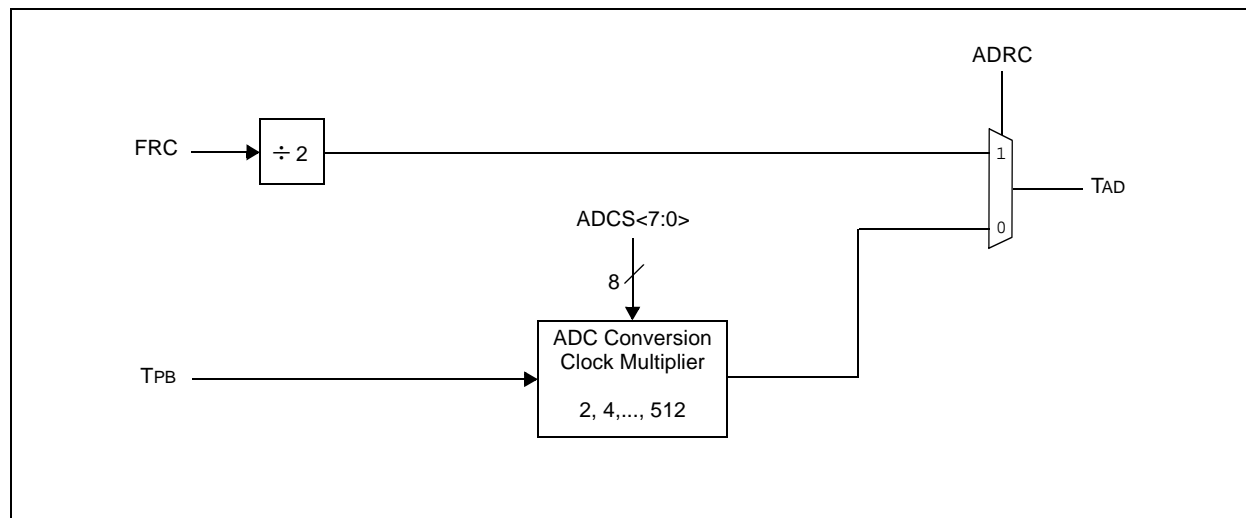
TABLE 22-1: RTCC REGISTER MAP

Virtual Address (BF80_#)	Register Name ⁽¹⁾	Bit Range	Bits															All Resets		
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1		16/0	
0200	RTCCON	31:16	—	—	—	—	—	—	CAL<9:0>										000	
		15:0	ON	—	SIDL	—	—	—	—	—	RTSECSEL	RTCCLKON	—	—	RTCWREN	RTCSYNC	HALFSEC	RTCOE	000	
0210	RTCALRM	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	000		
		15:0	ALRMEN	CHIME	PIV	ALRMSYNC	AMASK<3:0>					ARPT<7:0>							000	
0220	RTCTIME	31:16	HR10<3:0>					HR01<3:0>				MIN10<3:0>				MIN01<3:0>				xxxx
		15:0	SEC10<3:0>					SEC01<3:0>				—	—	—	—	—	—	—	xx0	
0230	RTCDATE	31:16	YEAR10<3:0>					YEAR01<3:0>				MONTH10<3:0>				MONTH01<3:0>				xxxx
		15:0	DAY10<3:0>					DAY01<3:0>				—	—	—	—	WDAY01<3:0>				xx0
0240	ALRMTIME	31:16	HR10<3:0>					HR01<3:0>				MIN10<3:0>				MIN01<3:0>				xxxx
		15:0	SEC10<3:0>					SEC01<3:0>				—	—	—	—	—	—	—	xx0	
0250	ALRMDATE	31:16	—	—	—	—	—	—	—	—	MONTH10<3:0>				MONTH01<3:0>				00xx	
		15:0	DAY10<3:0>					DAY01<3:0>				—	—	—	—	WDAY01<3:0>				xx0

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at its virtual address, plus an offset of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

FIGURE 23-2: ADC CONVERSION CLOCK PERIOD BLOCK DIAGRAM



REGISTER 24-2: CiCFG: CAN BAUD RATE CONFIGURATION REGISTER (CONTINUED)

bit 10-8 **PRSEG<2:0>**: Propagation Time Segment bits⁽⁴⁾

111 = Length is 8 x T_Q

•
•
•

000 = Length is 1 x T_Q

bit 7-6 **SJW<1:0>**: Synchronization Jump Width bits⁽³⁾

11 = Length is 4 x T_Q

10 = Length is 3 x T_Q

01 = Length is 2 x T_Q

00 = Length is 1 x T_Q

bit 5-0 **BRP<5:0>**: Baud Rate Prescaler bits

111111 = T_Q = (2 x 64)/F_{SYS}

111110 = T_Q = (2 x 63)/F_{SYS}

•
•
•

000001 = T_Q = (2 x 2)/F_{SYS}

000000 = T_Q = (2 x 1)/F_{SYS}

Note 1: SEG2PH ≤ SEG1PH. If SEG2PHTS is clear, SEG2PH will be set automatically.

2: 3 Time bit sampling is not allowed for BRP < 2.

3: SJW ≤ SEG2PH.

4: The Time Quanta per bit must be greater than 7 (that is, T_{QBIT} > 7).

Note: This register can only be modified when the CAN module is in Configuration mode (OPMOD<2:0> (CiCON<23:21>) = 100).

REGISTER 24-21: C*i*FIFOINT*n*: CAN FIFO INTERRUPT REGISTER 'n' (n = 0 THROUGH 31)

- bit 9 **TXHALFIF**: FIFO Transmit FIFO Half Empty Interrupt Flag bit⁽¹⁾
 TXEN = 1: (FIFO configured as a transmit buffer)
 1 = FIFO is \leq half full
 0 = FIFO is $>$ half full
 TXEN = 0: (FIFO configured as a receive buffer)
 Unused, reads '0'
- bit 8 **TXEMPTYIF**: Transmit FIFO Empty Interrupt Flag bit⁽¹⁾
 TXEN = 1: (FIFO configured as a transmit buffer)
 1 = FIFO is empty
 0 = FIFO is not empty, at least 1 message queued to be transmitted
 TXEN = 0: (FIFO configured as a receive buffer)
 Unused, reads '0'
- bit 7-4 **Unimplemented**: Read as '0'
- bit 3 **RXOVFLIF**: Receive FIFO Overflow Interrupt Flag bit
 TXEN = 1: (FIFO configured as a transmit buffer)
 Unused, reads '0'
 TXEN = 0: (FIFO configured as a receive buffer)
 1 = Overflow event has occurred
 0 = No overflow event occurred
- bit 2 **RXFULLIF**: Receive FIFO Full Interrupt Flag bit⁽¹⁾
 TXEN = 1: (FIFO configured as a transmit buffer)
 Unused, reads '0'
 TXEN = 0: (FIFO configured as a receive buffer)
 1 = FIFO is full
 0 = FIFO is not full
- bit 1 **RXHALFIF**: Receive FIFO Half Full Interrupt Flag bit⁽¹⁾
 TXEN = 1: (FIFO configured as a transmit buffer)
 Unused, reads '0'
 TXEN = 0: (FIFO configured as a receive buffer)
 1 = FIFO is \geq half full
 0 = FIFO is $<$ half full
- bit 0 **RXEMPTYIF**: Receive Buffer Not Empty Interrupt Flag bit⁽¹⁾
 TXEN = 1: (FIFO configured as a transmit buffer)
 Unused, reads '0'
 TXEN = 0: (FIFO configured as a receive buffer)
 1 = FIFO is not empty, has at least 1 message
 0 = FIFO is empty

Note 1: This bit is read-only and reflects the status of the FIFO.

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The processor will exit, or 'wake-up', from Sleep mode on one of the following events:

- On any interrupt from an enabled source that is operating in Sleep mode. The interrupt priority must be greater than the current CPU priority.
- On any form of device Reset
- On a WDT time-out

If the interrupt priority is lower than or equal to the current priority, the CPU will remain Halted, but the PBCLK will start running and the device will enter into Idle mode.

28.3.2 IDLE MODE

In Idle mode, the CPU is Halted but the System Clock (SYSCLK) source is still enabled. This allows peripherals to continue operation when the CPU is Halted. Peripherals can be individually configured to Halt when entering Idle by setting their respective SIDL bit. Latency, when exiting Idle mode, is very low due to the CPU oscillator source remaining active.

Note 1: Changing the PBCLK divider ratio requires recalculation of peripheral timing. For example, assume the UART is configured for 9600 baud with a PB clock ratio of 1:1 and a POSC of 8 MHz. When the PB clock divisor of 1:2 is used, the input frequency to the baud clock is cut in half; therefore, the baud rate is reduced to 1/2 its former value. Due to numeric truncation in calculations (such as the baud rate divisor), the actual baud rate may be a tiny percentage different than expected. For this reason, any timing calculation required for a peripheral should be performed with the new PB clock frequency instead of scaling the previous value based on a change in the PB divisor ratio.

- 2: Oscillator start-up and PLL lock delays are applied when switching to a clock source that was disabled and that uses a crystal and/or the PLL. For example, assume the clock source is switched from POSC to LPRC just prior to entering Sleep in order to save power. No oscillator start-up delay would be applied when exiting Idle. However, when switching back to POSC, the appropriate PLL and/or oscillator start-up/lock delays would be applied.

The device enters Idle mode when the SLPEN bit (OSCCON<4>) is clear and a WAIT instruction is executed.

The processor will wake or exit from Idle mode on the following events:

- On any interrupt event for which the interrupt source is enabled. The priority of the interrupt event must be greater than the current priority of the CPU. If the priority of the interrupt event is lower than or equal to current priority of the CPU, the CPU will remain Halted and the device will remain in Idle mode.
- On any form of device Reset
- On a WDT time-out interrupt

28.3.3 PERIPHERAL BUS SCALING METHOD

Most of the peripherals on the device are clocked using the PBCLK. The Peripheral Bus (PB) can be scaled relative to the SYSCLK to minimize the dynamic power consumed by the peripherals. The PBCLK divisor is controlled by PBDIV<1:0> (OSCCON<20:19>), allowing SYSCLK to PBCLK ratios of 1:1, 1:2, 1:4 and 1:8. All peripherals using PBCLK are affected when the divisor is changed. Peripherals such as USB, interrupt controller, DMA, bus matrix and prefetch cache are clocked directly from SYSCLK. As a result, they are not affected by PBCLK divisor changes.

Changing the PBCLK divisor affects:

- The CPU to peripheral access latency. The CPU has to wait for next PBCLK edge for a read to complete. In 1:8 mode, this results in a latency of one to seven SYSCLKs.
- The power consumption of the peripherals. Power consumption is directly proportional to the frequency at which the peripherals are clocked. The greater the divisor, the lower the power consumed by the peripherals.

To minimize dynamic power, the PB divisor should be chosen to run the peripherals at the lowest frequency that provides acceptable system performance. When selecting a PBCLK divider, peripheral clock requirements, such as baud rate accuracy, should be taken into account. For example, the UART peripheral may not be able to achieve all baud rate values at some PBCLK divider depending on the SYSCLK value.

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TABLE 32-13: COMPARATOR SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions (see Note 3): 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp				
Param. No.	Symbol	Characteristics	Min.	Typical	Max.	Units	Comments
D300	VIOFF	Input Offset Voltage	—	±7.5	±25	mV	AVDD = VDD, AVSS = VSS
D301	VICM	Input Common Mode Voltage	0	—	VDD	V	AVDD = VDD, AVSS = VSS (Note 2)
D302	CMRR	Common Mode Rejection Ratio	55	—	—	dB	Max VICM = (VDD - 1)V (Note 2)
D303	TRESP	Response Time	—	150	400	ns	AVDD = VDD, AVSS = VSS (Notes 1, 2)
D304	ON2OV	Comparator Enabled to Output Valid	—	—	10	μs	Comparator module is configured before setting the comparator ON bit (Note 2)
D305	IVREF	Internal Voltage Reference	0.57	0.6	0.63	V	For devices without BGSEL<1:0>
			1.14	1.2	1.26	V	BGSEL<1:0> = 00
			0.57	0.6	0.63	V	BGSEL<1:0> = 01

Note 1: Response time measured with one comparator input at $(VDD - 1.5)/2$, while the other input transitions from VSS to VDD.

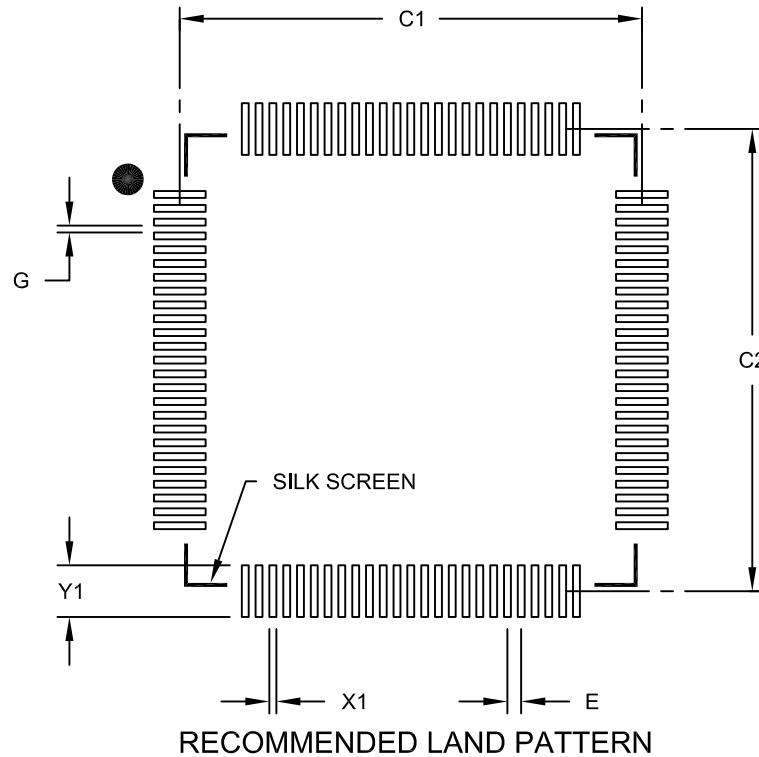
2: These parameters are characterized but not tested.

3: The Comparator module is functional at $VBORMIN < VDD < VDDMIN$, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

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100-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

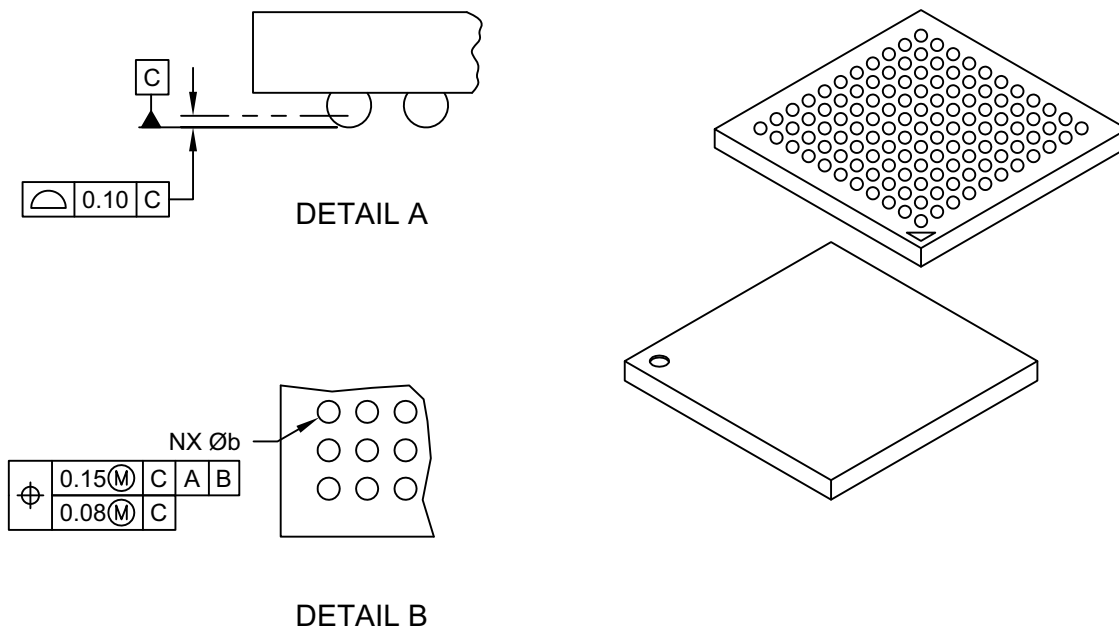
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2100B

PIC32MX5XX/6XX/7XX

121-Ball Plastic Thin Profile Fine Pitch Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Contacts	N	121		
Contact Pitch	e	0.80 BSC		
Overall Height	A	1.00	1.10	1.20
Ball Height	A1	0.25	0.30	0.35
Overall Width	E	10.00 BSC		
Array Width	E1	8.00 BSC		
Overall Length	D	10.00 BSC		
Array Length	D1	8.00 BSC		
Contact Diameter	b	0.35	0.40	0.45

Notes:

1. Ball A1 visual index feature may vary, but must be located within the hatched area.
2. Dimensioning and tolerancing per ASME Y14.5M.
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.
3. The outer rows and columns of balls are located with respect to datums A and B.
4. Ball interface to package body: 0.37mm nominal diameter.

Microchip Technology Drawing C04-148 Rev F Sheet 2 of 2

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TABLE B-7: MAJOR SECTION UPDATES (CONTINUED)

Section Name	Update Description
32.0 “Electrical Characteristics”	Note 4 in the Operating Current specification was updated (see Table 32-5). Note 3 in the Idle Current specification was updated (see Table 32-6). Note 6 references in the Power-Down Current specification were updated (see Table 32-7). The Program Memory parameters, D135, D136, and D137, and Note 4 were updated (see Table 32-11). The Voltage Reference Specifications were updated (see Table 32-14). Parameter DO50 (Cosco) was added to the Capacitive Loading Requirements on Output Pins (see Table 32-16). The EJTAG Timing Characteristics were updated (see Figure 32-28). The maximum value for parameters ET13 and ET14 were updated in the Ethernet Module Specifications (see Table 32-35). Parameter PM7 (TDHOLD) was updated (see Table 32-40).
34.0 “Packaging Information”	Packaging diagrams were updated.
Product Identification System	The Speed and Program Memory Size were updated and Note 1 was added.