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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	Ethernet, I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	53
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-VQFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx664f064ht-v-mr

PIC32MX5XX/6XX/7XX

TABLE 7: PIN NAMES FOR 100-PIN USB AND CAN DEVICES

100-PIN TQFP (TOP VIEW)			
PIC32MX534F064L PIC32MX564F064L PIC32MX564F128L PIC32MX575F512L PIC32MX575F256L		100	1
Pin #	Full Pin Name	Pin #	Full Pin Name
1	RG15	36	Vss
2	VDD	37	VDD
3	PMD5/RE5	38	TCK/RA1
4	PMD6/RE6	39	AC1TX/SCK4/U5TX/U2RTS/RF13
5	PMD7/RE7	40	AC1RX/SS4/U5RX/U2CTS/RF12
6	T2CK/RC1	41	AN12/PMA11/RB12
7	T3CK/RC2	42	AN13/PMA10/RB13
8	T4CK/RC3	43	AN14/PMALH/PMA1/RB14
9	T5CK/SDI1/RC4	44	AN15/OCFB/PMALL/PMA0/CN12/RB15
10	SCK2/U6TX/U3RTS/PMA5/CN8/RG6	45	Vss
11	SDA4/SDI2/U3RX/PMA4/CN9/RG7	46	VDD
12	SCL4/SDO2/U3TX/PMA3/CN10/RG8	47	SS3/U4RX/U1CTS/CN20/RD14
13	MCLR	48	SCK3/U4TX/U1RTS/CN21/RD15
14	SS2/U6RX/U3CTS/PMA2/CN11/RG9	49	SDA5/SDI4/U2RX/PMA9/CN17/RF4
15	Vss	50	SCL5/SDO4/U2TX/PMA8/CN18/RF5
16	VDD	51	USBID/RF3
17	TMS/RA0	52	SDA3/SDI3/U1RX/RF2
18	INT1/RE8	53	SCL3/SDO3/U1TX/RF8
19	INT2/RE9	54	VBUS
20	AN5/C1IN+/VBUSON/CN7/RB5	55	VUSB3V3
21	AN4/C1IN-/CN6/RB4	56	D-/RG3
22	AN3/C2IN+/CN5/RB3	57	D+/RG2
23	AN2/C2IN-/CN4/RB2	58	SCL2/RA2
24	PGEC1/AN1/CN3/RB1	59	SDA2/RA3
25	PGED1/AN0/CN2/RB0	60	TDI/RA4
26	PGEC2/AN6/OCFA/RB6	61	TDO/RA5
27	PGED2/AN7/RB7	62	VDD
28	VREF-/CVREF-/PMA7/RA9	63	OSC1/CLKI/RC12
29	VREF+/CVREF+/PMA6/RA10	64	OSC2/CLKO/RC15
30	AVDD	65	Vss
31	AVSS	66	SCL1/INT3/RA14
32	AN8/C1OUT/RB8	67	SDA1/INT4/RA15
33	AN9/C2OUT/RB9	68	RTCC/IC1/RD8
34	AN10/CVREFOUT/PMA13/RB10	69	SS1/IC2/RD9
35	AN11/PMA12/RB11	70	SCK1/IC3/PMCS2/PMA15/RD10

Note 1: Shaded pins are 5V tolerant.

PIC32MX5XX/6XX/7XX

TABLE 8: PIN NAMES FOR 100-PIN USB AND ETHERNET DEVICES (CONTINUED)

100-PIN TQFP (TOP VIEW)

PIC32MX664F064L
 PIC32MX664F128L
 PIC32MX675F256L
 PIC32MX675F512L
 PIC32MX695F512L

100

1

Pin #	Full Pin Name	Pin #	Full Pin Name
71	EMDC/AEMDC/IC4/PMCS1/PMA14/RD11	86	VDD
72	SDO1/OC1/INT0/RD0	87	ETXD1/PMD11/RF0
73	SOSCI/CN1/RC13	88	ETXD0/PMD10/RF1
74	SOSCO/T1CK/CN0/RC14	89	ETXERR/PMD9/RG1
75	Vss	90	PMD8/RG0
76	OC2/RD1	91	TRCLK/RA6
77	OC3/RD2	92	TRD3/RA7
78	OC4/RD3	93	PMD0/RE0
79	ETXD2/IC5/PMD12/RD12	94	PMD1/RE1
80	ETXD3/PMD13/CN19/RD13	95	TRD2/RG14
81	OC5/PMWR/CN13/RD4	96	TRD1/RG12
82	PMRD/CN14/RD5	97	TRD0/RG13
83	ETXEN/PMD14/CN15/RD6	98	PMD2/RE2
84	ETXCLK/PMD15/CN16/RD7	99	PMD3/RE3
85	VCAP/VDDCORE	100	PMD4/RE4

Note 1: Shaded pins are 5V tolerant.

PIC32MX5XX/6XX/7XX

NOTES:

PIC32MX5XX/6XX/7XX

NOTES:

TABLE 10-3: DMA CHANNELS 0-7 REGISTER MAP (CONTINUED)

Virtual Address (BF88_#)	Register Name ⁽¹⁾	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
35F0	DCH7SSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHSSIZ<15:0>																0000
3600	DCH7DSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHDSIZ<15:0>																0000
3610	DCH7SPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHSPTR<15:0>																0000
3620	DCH7DPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHDPTR<15:0>																0000
3630	DCH7CSIZ	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHCSIZ<15:0>																0000
3640	DCH7CPTR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	CHCPTR<15:0>																0000
3650	DCH7DAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000	
		15:0	—	—	—	—	—	—	—	CHPDAT<7:0>									

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

2: DMA channels 4-7 are not available on PIC32MX534/564/664/764 devices.

11.0 USB ON-THE-GO (OTG)

Note: This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 27. “USB On-The-Go (OTG)”** (DS60001126) in the *“PIC32 Family Reference Manual”*, which is available from the Microchip web site (www.microchip.com/PIC32).

The Universal Serial Bus (USB) module contains analog and digital components to provide a USB 2.0 full-speed and low-speed embedded Host, full-speed Device or OTG implementation with a minimum of external components. This module in Host mode is intended for use as an embedded host and therefore does not implement a UHCI or OHCI controller.

The USB module consists of the clock generator, the USB voltage comparators, the transceiver, the Serial Interface Engine (SIE), a dedicated USB DMA controller, pull-up and pull-down resistors, and the register interface. A block diagram of the PIC32 USB OTG module is presented in Figure 11-1.

The clock generator provides the 48 MHz clock required for USB full-speed and low-speed communication. The voltage comparators monitor the voltage on the VBUS pin to determine the state of the bus. The transceiver provides the analog translation between the USB bus and the digital logic. The SIE is a state machine that transfers data to and from the endpoint buffers and generates the hardware protocol for data transfers. The USB DMA controller transfers data between the data buffers in RAM and the SIE. The integrated pull-up and pull-down resistors eliminate the need for external signaling components. The register interface allows the CPU to configure and communicate with the module.

The USB module includes the following features:

- USB Full-speed support for host and device
- Low-speed host support
- USB OTG support
- Integrated signaling resistors
- Integrated analog comparators for VBUS monitoring
- Integrated USB transceiver
- Transaction handshaking performed by hardware
- Endpoint buffering anywhere in system RAM
- Integrated DMA to access system RAM and Flash

Note: The implementation and use of the USB specifications, as well as other third party specifications or technologies, may require licensing; including, but not limited to, USB Implementers Forum, Inc. (also referred to as USB-IF). The user is fully responsible for investigating and satisfying any applicable licensing obligations.

REGISTER 11-11: U1CON: USB CONTROL REGISTER (CONTINUED)

- bit 1 **PPBRST:** Ping-Pong Buffers Reset bit
 1 = Reset all Even/Odd buffer pointers to the Even buffer descriptor banks
 0 = Even/Odd buffer pointers are not reset
- bit 0 **USBEN:** USB Module Enable bit⁽⁴⁾
 1 = USB module and supporting circuitry is enabled
 0 = USB module and supporting circuitry is disabled
- SOFEN:** SOF Enable bit⁽⁵⁾
 1 = SOF token is sent every 1 ms
 0 = SOF token is disabled

- Note 1:** Software is required to check this bit before issuing another token command to the U1TOK register (see Register 11-15).
- 2:** All host control logic is reset any time that the value of this bit is toggled.
- 3:** Software must set RESUME for 10 ms in Device mode, or for 25 ms in Host mode, and then clear it to enable remote wake-up. In Host mode, the USB module will append a low-speed EOP to the RESUME signaling when this bit is cleared.
- 4:** Device mode.
- 5:** Host mode.

REGISTER 13-1: T1CON: TYPE A TIMER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	R/W-0	R/W-0	R-0	U-0	U-0	U-0
	ON ⁽¹⁾	—	SIDL	TWDIS	TWIP	—	—	—
7:0	R/W-0	U-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
	TGATE	—	TCKPS<1:0>		—	TSYNC	TCS	—

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Timer On bit⁽¹⁾

1 = Timer is enabled

0 = Timer is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **SIDL:** Stop in Idle Mode bit

1 = Discontinue operation when device enters Idle mode

0 = Continue operation when device is in Idle mode

bit 12 **TWDIS:** Asynchronous Timer Write Disable bit

1 = Writes to TMR1 are ignored until pending write operation completes

0 = Back-to-back writes are enabled (Legacy Asynchronous Timer functionality)

bit 11 **TWIP:** Asynchronous Timer Write in Progress bit

In Asynchronous Timer mode:

1 = Asynchronous write to TMR1 register in progress

0 = Asynchronous write to TMR1 register complete

In Synchronous Timer mode:

This bit is read as '0'.

bit 10-8 **Unimplemented:** Read as '0'

bit 7 **TGATE:** Timer Gated Time Accumulation Enable bit

When TCS = 1:

This bit is ignored.

When TCS = 0:

1 = Gated time accumulation is enabled

0 = Gated time accumulation is disabled

bit 6 **Unimplemented:** Read as '0'

bit 5-4 **TCKPS<1:0>:** Timer Input Clock Prescale Select bits

11 = 1:256 prescale value

10 = 1:64 prescale value

01 = 1:8 prescale value

00 = 1:1 prescale value

Note 1: When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral SFRs in the SYSClk cycle immediately following the instruction that clears the module's ON bit.

15.0 WATCHDOG TIMER (WDT)

Note: This data sheet summarizes the features of the PIC32MX5XX/6XX/7XX family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 8. “Watchdog Timer and Power-up Timer”** (DS60001114) in the “PIC32 Family Reference Manual”, which is available from the Microchip web site (www.microchip.com/PIC32).

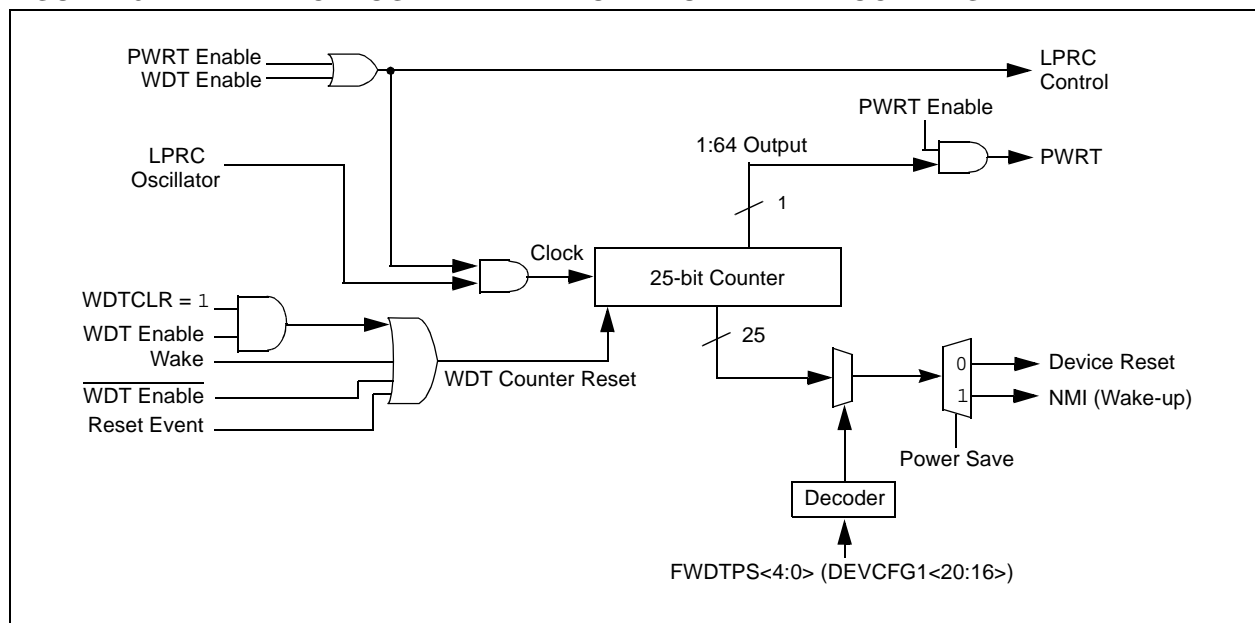
This section describes the operation of the WDT and Power-up Timer of the PIC32MX5XX/6XX/7XX.

The WDT, when enabled, operates from the internal Low-Power Oscillator (LPRC) clock source and can be used to detect system software malfunctions by resetting the device if the WDT is not cleared periodically in software. Various WDT time-out periods can be selected using the WDT postscaler. The WDT can also be used to wake the device from Sleep or Idle mode.

The following are key features of the WDT module:

- Configuration or software controlled
- User-configurable time-out period
- Can wake the device from Sleep or Idle mode

FIGURE 15-1: WATCHDOG TIMER AND POWER-UP TIMER BLOCK DIAGRAM



PIC32MX5XX/6XX/7XX

NOTES:

PIC32MX5XX/6XX/7XX

REGISTER 21-4: PMAEN: PARALLEL PORT PIN ENABLE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	PTEN14	—	—	—	PTEN<10:8>		
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PTEN<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-15 **Unimplemented:** Read as '0'

bit 15-14 **PTEN14:** PMCS1 Strobe Enable bits

1 = PMA14 functions as either PMA14 or PMCS1⁽¹⁾

0 = PMA14 functions as port I/O

bit 13-11 **Unimplemented:** Read as '0'

bit 10-2 **PTEN<10:2>:** PMP Address Port Enable bits

1 = PMA<10:2> function as PMP address lines

0 = PMA<10:2> function as port I/O

bit 1-0 **PTEN<1:0>:** PMALH/PMALL Strobe Enable bits

1 = PMA1 and PMA0 function as either PMA<1:0> or PMALH and PMALL⁽²⁾

0 = PMA1 and PMA0 pads function as port I/O

Note 1: The use of this pin as PMA14 or CS1 is selected by the CSF<1:0> bits in the PMCON register.

2: The use of these pins as PMA1/PMA0 or PMALH/PMALL depends on the Address/Data Multiplex mode selected by bits ADRMUX<1:0> in the PMCON register.

PIC32MX5XX/6XX/7XX

REGISTER 22-1: RTCCON: RTC CONTROL REGISTER (CONTINUED)

- bit 3 **RTCWREN:** RTC Value Registers Write Enable bit⁽⁴⁾
1 = RTC Value registers can be written to by the user
0 = RTC Value registers are locked out from being written to by the user
- bit 2 **RTCSYNC:** RTCC Value Registers Read Synchronization bit
1 = RTC Value registers can change while reading, due to a rollover ripple that results in an invalid data read. If the register is read twice and results in the same data, the data can be assumed to be valid.
0 = RTC Value registers can be read without concern about a rollover ripple
- bit 1 **HALFSEC:** Half-Second Status bit⁽⁵⁾
1 = Second half period of a second
0 = First half period of a second
- bit 0 **RTCOE:** RTCC Output Enable bit
1 = RTCC clock output is enabled (clock presented onto an I/O)
0 = RTCC clock output is disabled

- Note 1:** The ON bit is only writable when RTCWREN = 1.
- 2:** When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCCLK cycle immediately following the instruction that clears the module's ON bit.
- 3:** Requires RTCOE = 1 (RTCCON<0>) for the output to be active.
- 4:** The RTCWREN bit can only be set when the write sequence is enabled.
- 5:** This bit is read-only. It is cleared to '0' on a write to the seconds bit fields (RTCTIME<14:8>).

Note: This register is only reset on a Power-on Reset (POR).

REGISTER 24-1: CiCON: CAN MODULE CONTROL REGISTER (CONTINUED)

- bit 13 **SIDLE:** CAN Stop in Idle bit
 1 = CAN Stops operation when system enters Idle mode
 0 = CAN continues operation when system enters Idle mode
- bit 12 **Unimplemented:** Read as '0'
- bit 11 **CANBUSY:** CAN Module is Busy bit
 1 = The CAN module is active
 0 = The CAN module is completely disabled
- bit 10-5 **Unimplemented:** Read as '0'
- bit 4-0 **DNCNT<4:0>:** Device Net Filter Bit Number bits
 10011-11111 = Invalid Selection (compare up to 18-bits of data with EID)
 10010 = Compare up to data byte 2 bit 6 with EID17 (CiRXFn<17>)
 •
 •
 •
 00001 = Compare up to data byte 0 bit 7 with EID0 (CiRXFn<0>)
 00000 = Do not compare data bytes

Note 1: If the user application clears this bit, it may take a number of cycles before the CAN module completes the current transaction and responds to this request. The user application should poll the CANBUSY bit to verify that the request has been honored.

REGISTER 25-16: ETHRXOVFLOW: ETHERNET CONTROLLER RECEIVE OVERFLOW STATISTICS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXOVFLWCNT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXOVFLWCNT<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **RXOVFLWCNT<15:0>:** Dropped Receive Frames Count bits

Increment counter for frames accepted by the RX filter and subsequently dropped due to internal receive error (RXFIFO overrun). This event also sets the RXOVFLW bit (ETHIRQ<0>) interrupt flag.

Note 1: This register is only used for RX operations.

2: This register is automatically cleared by hardware after a read operation, unless the byte enables for bytes 0/1 are '0'.

3: It is recommended to use the SET, CLR, or INV registers to set or clear any bit in this register. Setting or clearing any bits in this register should only be done for debug/test purposes.

REGISTER 25-20: ETHFRMRXOK: ETHERNET CONTROLLER FRAMES RECEIVED OK STATISTICS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FRMRXOKCNT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FRMRXOKCNT<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **FRMRXOKCNT<15:0>:** Frames Received OK Count bits

Increment count for frames received successfully by the RX Filter. This count will not be incremented if there is a Frame Check Sequence (FCS) or Alignment error.

Note 1: This register is only used for RX operations.

2: This register is automatically cleared by hardware after a read operation, unless the byte enables for bytes 0/1 are '0'.

3: It is recommended to use the SET, CLR, or INV registers to set or clear any bit in this register. Setting or clearing any bits in this register should only be done for debug/test purposes.

29.2 On-Chip Voltage Regulator

All PIC32MX5XX/6XX/7XX devices' core and digital logic are designed to operate at a nominal 1.8V. To simplify system designs, most devices in the PIC32MX-5XX/6XX/7XX family incorporate an on-chip regulator providing the required core logic voltage from VDD.

A low-ESR capacitor (such as tantalum) must be connected to the VCAP pin (see Figure 29-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in **Section 32.1 "DC Characteristics"**.

Note: It is important that the low-ESR capacitor is placed as close as possible to the VCAP pin.

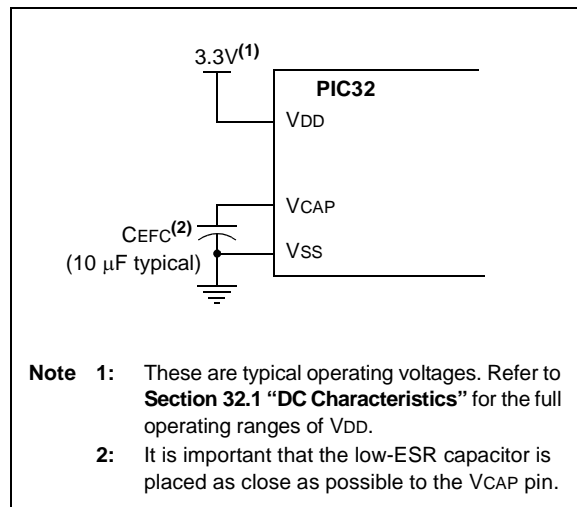
29.2.1 ON-CHIP REGULATOR AND POR

It takes a fixed delay for the on-chip regulator to generate an output. During this time, designated as TPU, code execution is disabled. TPU is applied every time the device resumes operation after any power-down, including Sleep mode.

29.2.2 ON-CHIP REGULATOR AND BOR

PIC32MX5XX/6XX/7XX devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain a regulated level, the regulator Reset circuitry will generate a Brown-out Reset (BOR). This event is captured by the BOR flag bit (RCON<1>). The brown-out voltage levels are specified in **Section 32.1 "DC Characteristics"**.

FIGURE 29-1: CONNECTIONS FOR THE ON-CHIP REGULATOR



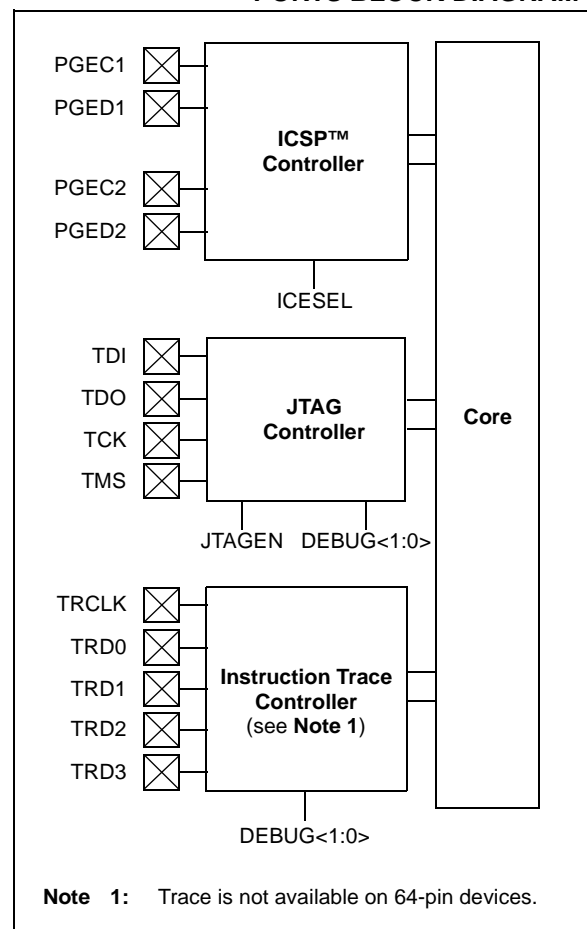
29.3 Programming and Diagnostics

PIC32MX5XX/6XX/7XX devices provide a complete range of programming and diagnostic features that can increase the flexibility of any application using them. These features allow system designers to include:

- Simplified field programmability using two-wire In-Circuit Serial Programming™ (ICSP™) interfaces
- Debugging using ICSP
- Programming and debugging capabilities using the EJTAG extension of JTAG
- JTAG boundary scan testing for device and board diagnostics

PIC32 devices incorporate two programming and diagnostic modules, and a trace controller, that provide a range of functions to the application developer.

FIGURE 29-2: PROGRAMMING, DEBUGGING, AND TRACE PORTS BLOCK DIAGRAM



31.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
 - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB XC Compiler
 - MPASM™ Assembler
 - MPLINK™ Object Linker/
MPLIB™ Object Librarian
 - MPLAB Assembler/Linker/Librarian for
Various Device Families
- Simulators
 - MPLAB X SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
 - MPLAB ICD 3
 - PICKit™ 3
- Device Programmers
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,
Evaluation Kits and Starter Kits
- Third-party development tools

31.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

FIGURE 32-13: SPIx MODULE SLAVE MODE (CKE = 1) TIMING CHARACTERISTICS

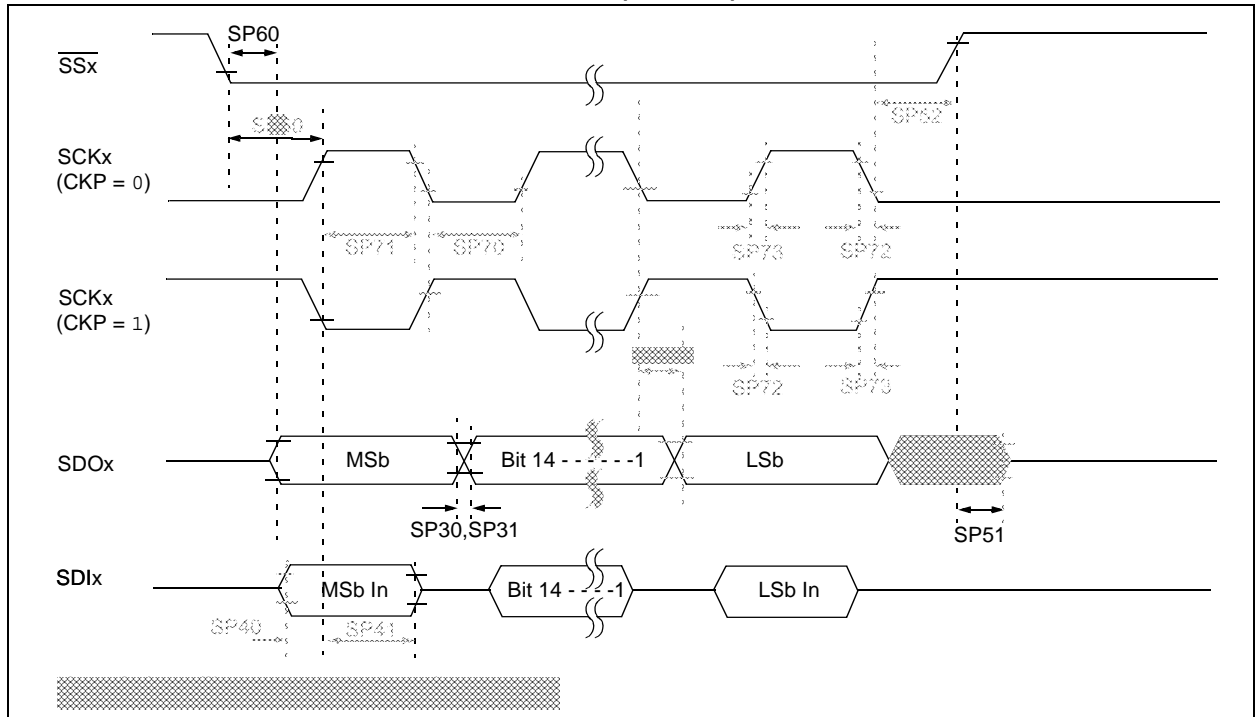


TABLE 32-31: SPIx MODULE SLAVE MODE (CKE = 1) TIMING REQUIREMENTS

AC CHARACTERISTICS				Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp			
Param. No.	Symbol	Characteristics ⁽¹⁾	Min.	Typical ⁽²⁾	Max.	Units	Conditions
SP70	TsCL	SCKx Input Low Time ⁽³⁾	Tsck/2	—	—	ns	—
SP71	TsCH	SCKx Input High Time ⁽³⁾	Tsck/2	—	—	ns	—
SP72	TscF	SCKx Input Fall Time	—	5	10	ns	—
SP73	TscR	SCKx Input Rise Time	—	5	10	ns	—
SP30	TdOF	SDOx Data Output Fall Time ⁽⁴⁾	—	—	—	ns	See parameter DO32
SP31	TdOR	SDOx Data Output Rise Time ⁽⁴⁾	—	—	—	ns	See parameter DO31
SP35	Tsch2dov, TscL2dov	SDOx Data Output Valid after SCKx Edge	—	—	20	ns	VDD > 2.7V
			—	—	30	ns	VDD < 2.7V
SP40	TdIV2sch, TdIV2scl	Setup Time of SDIx Data Input to SCKx Edge	10	—	—	ns	—
SP41	Tsch2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	10	—	—	ns	—
SP50	TssL2sch, TssL2scl	SSx ↓ to SCKx ↓ or SCKx ↑ Input	175	—	—	ns	—

Note 1: These parameters are characterized, but not tested in manufacturing.

2: Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

3: The minimum clock period for SCKx is 40 ns.

4: Assumes 50 pF load on all SPIx pins.

TABLE 32-36: ADC MODULE SPECIFICATIONS (CONTINUED)

AC CHARACTERISTICS			Standard Operating Conditions (see Note 5): 2.5V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +105°C for V-Temp				
Param. No.	Symbol	Characteristics	Min.	Typical	Max.	Units	Conditions
ADC Accuracy – Measurements with Internal VREF+/VREF-							
AD20d	Nr	Resolution	10 data bits			bits	(Note 3)
AD21d	INL	Integral Nonlinearity	> -1	—	< 1	LSb	VINL = AVSS = 0V, AVDD = 2.5V to 3.6V (Note 3)
AD22d	DNL	Differential Nonlinearity	> -1	—	< 1	LSb	VINL = AVSS = 0V, AVDD = 2.5V to 3.6V (Notes 2,3)
AD23d	GERR	Gain Error	> -4	—	< 4	LSb	VINL = AVSS = 0V, AVDD = 2.5V to 3.6V (Note 3)
AD24d	E _{OFF}	Offset Error	> -2	—	< 2	LSb	VINL = AVSS = 0V, AVDD = 2.5V to 3.6V (Note 3)
AD25d	—	Monotonicity	—	—	—	—	Guaranteed
Dynamic Performance							
AD31b	SINAD	Signal to Noise and Distortion	55	58.5	—	dB	(Notes 3,4)
AD34b	ENOB	Effective Number of Bits	9.0	9.5	—	bits	(Notes 3,4)

Note 1: These parameters are not characterized or tested in manufacturing.

2: With no missing codes.

3: These parameters are characterized, but not tested in manufacturing.

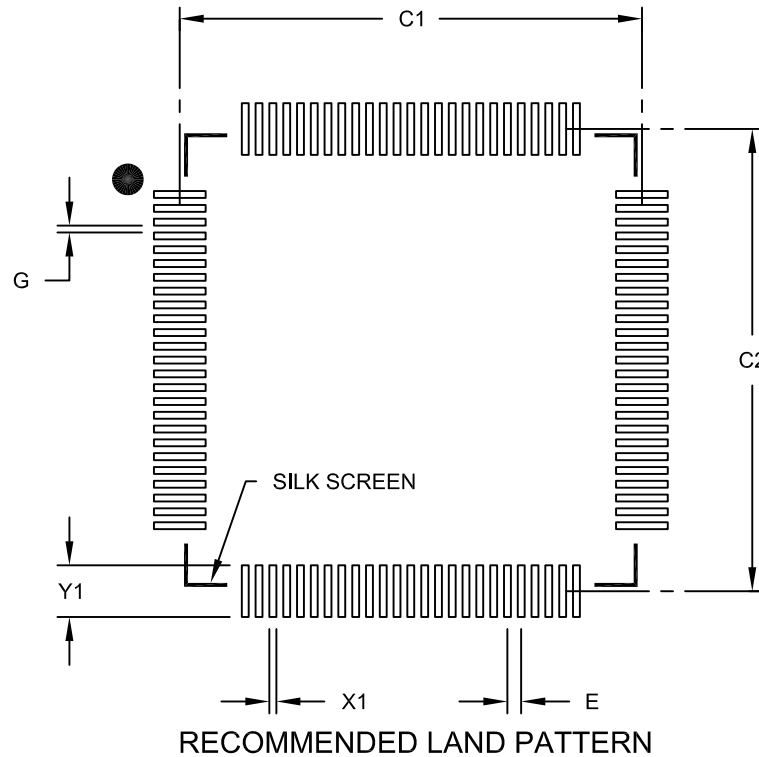
4: Characterized with a 1 kHz sine wave.

5: The ADC module is functional at VB_{ORMIN} < VDD < 2.5V, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

PIC32MX5XX/6XX/7XX

100-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2100B