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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	MIPS32® M4K™
Core Size	32-Bit Single-Core
Speed	80MHz
Connectivity	Ethernet, I ² C, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 16x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mx664f128lt-v-pt

Referenced Sources

This device data sheet is based on the following individual chapters of the *"PIC32 Family Reference Manual"*. These documents should be considered as the general reference for the operation of a particular module or device feature.

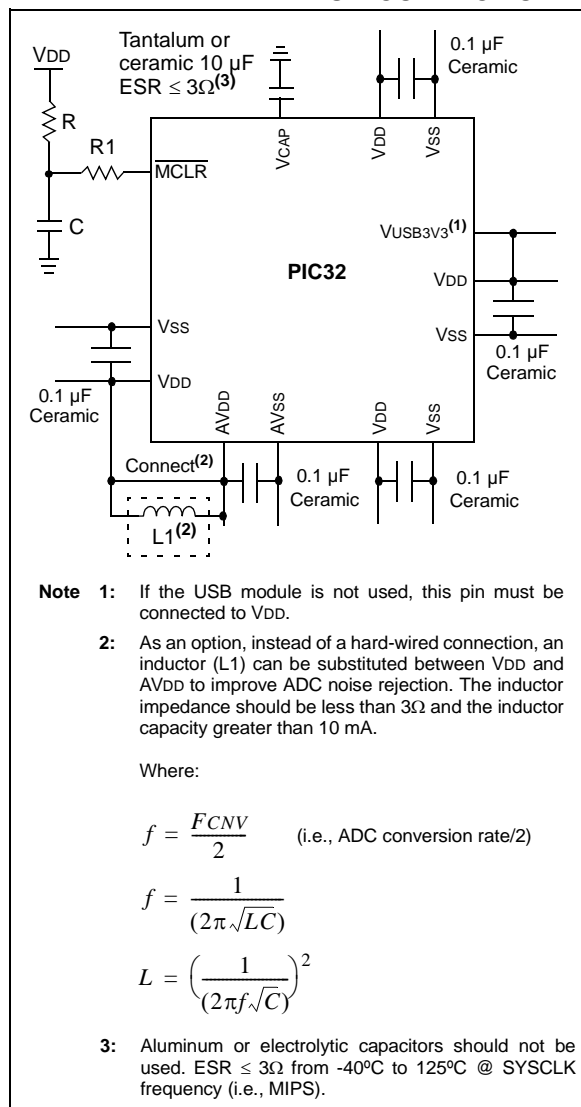
Note 1: To access the documents listed below, browse to the documentation section of the PIC32MX795F512L product page on the Microchip web site (www.microchip.com) or select a family reference manual section from the following list.

In addition to parameters, features, and other documentation, the resulting page provides links to the related family reference manual sections.

- **Section 1. "Introduction"** (DS60001127)
- **Section 2. "CPU"** (DS60001113)
- **Section 4. "Prefetch Cache"** (DS60001119)
- **Section 3. "Memory Organization"** (DS60001115)
- **Section 5. "Flash Program Memory"** (DS60001121)
- **Section 6. "Oscillator Configuration"** (DS60001112)
- **Section 7. "Resets"** (DS60001118)
- **Section 8. "Interrupt Controller"** (DS60001108)
- **Section 9. "Watchdog Timer and Power-up Timer"** (DS60001114)
- **Section 10. "Power-Saving Features"** (DS60001130)
- **Section 12. "I/O Ports"** (DS60001120)
- **Section 13. "Parallel Master Port (PMP)"** (DS60001128)
- **Section 14. "Timers"** (DS60001105)
- **Section 15. "Input Capture"** (DS60001122)
- **Section 16. "Output Capture"** (DS60001111)
- **Section 17. "10-bit Analog-to-Digital Converter (ADC)"** (DS60001104)
- **Section 19. "Comparator"** (DS60001110)
- **Section 20. "Comparator Voltage Reference (CVREF)"** (DS60001109)
- **Section 21. "Universal Asynchronous Receiver Transmitter (UART)"** (DS60001107)
- **Section 23. "Serial Peripheral Interface (SPI)"** (DS60001106)
- **Section 24. "Inter-Integrated Circuit (I2C)"** (DS60001116)
- **Section 27. "USB On-The-Go (OTG)"** (DS60001126)
- **Section 29. "Real-Time Clock and Calendar (RTCC)"** (DS60001125)
- **Section 31. "Direct Memory Access (DMA) Controller"** (DS60001117)
- **Section 32. "Configuration"** (DS60001124)
- **Section 33. "Programming and Diagnostics"** (DS60001129)
- **Section 34. "Controller Area Network (CAN)"** (DS60001154)
- **Section 35. "Ethernet Controller"** (DS60001155)

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FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION



2.2.1 BULK CAPACITORS

The use of a bulk capacitor is recommended to improve power supply stability. Typical values range from 4.7 μF to 47 μF . This capacitor should be located as close to the device as possible.

2.3 Capacitor on Internal Voltage Regulator (VCAP)

2.3.1 INTERNAL REGULATOR MODE

A low-ESR (1 ohm) capacitor is required on the VCAP pin, which is used to stabilize the internal voltage regulator output. The VCAP pin must not be connected to VDD, and must have a CEFC capacitor, with at least a 6V rating, connected to ground. The type can be ceramic or tantalum. Refer to **Section 32.0 "Electrical Characteristics"** for additional information on CEFC specifications.

2.4 Master Clear (MCLR) Pin

The **MCLR** pin provides two specific device functions:

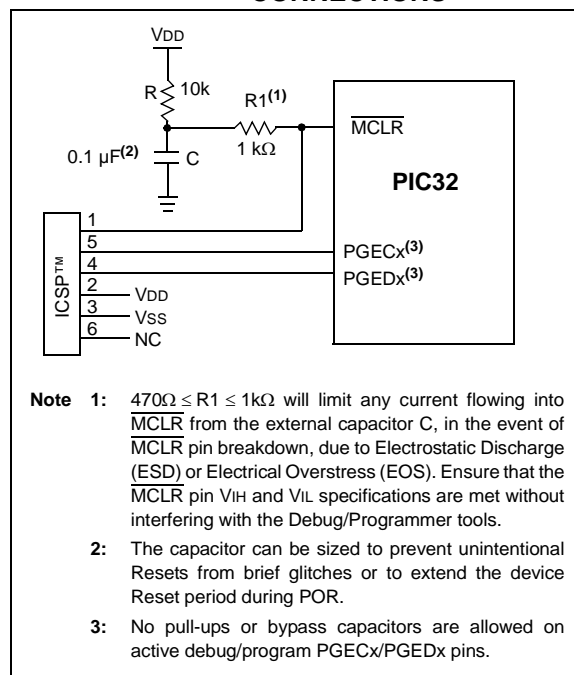
- Device Reset
- Device Programming and Debugging

Pulling The **MCLR** pin low generates a device Reset. Figure 2-2 illustrates a typical **MCLR** circuit. During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the **MCLR** pin. Consequently, specific voltage levels (V_{IH} and V_{IL}) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as illustrated in Figure 2-2, it is recommended that the capacitor C, be isolated from the **MCLR** pin during programming and debugging operations.

Place the components illustrated in Figure 2-2 within one-quarter inch (6 mm) from the **MCLR** pin.

FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS



2.5 ICSP Pins

The PGECx and PGEDx pins are used for In-Circuit Serial Programming™ (ICSP™) and debugging. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (V_{IH}) and input low (V_{IL}) requirements.

Ensure that the “Communication Channel Select” (i.e., PGECx/PGEDx pins) programmed into the device matches the physical connections for the ICSP to MPLAB® ICD 3 or MPLAB® REAL ICE™.

For more information on ICD 3 and REAL ICE connection requirements, refer to the following documents that are available on the Microchip web site.

- “Using MPLAB® ICD 3” (poster) (DS50001765)
- “MPLAB® ICD 3 Design Advisory” (DS50001764)
- “MPLAB® REAL ICE™ In-Circuit Emulator User’s Guide” (DS50001616)
- “Using MPLAB® REAL ICE™ Emulator” (poster) (DS50001749)

2.6 JTAG

The TMS, TDO, TDI and TCK pins are used for testing and debugging according to the Joint Test Action Group (JTAG) standard. It is recommended to keep the trace length between the JTAG connector and the JTAG pins on the device as short as possible. If the JTAG connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes and capacitors on the TMS, TDO, TDI and TCK pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (V_{IH}) and input low (V_{IL}) requirements.

2.7 Trace

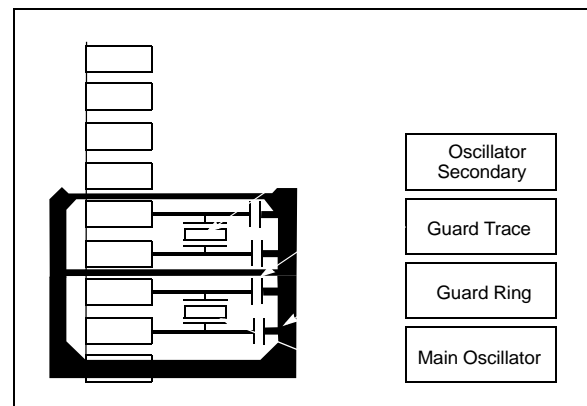
The trace pins can be connected to a hardware-trace-enabled programmer to provide a compress real time instruction trace. When used for trace the TRD3, TRD2, TRD1, TRD0 and TRCLK pins should be dedicated for this use. The trace hardware requires a 22Ω series resistor between the trace pins and the trace connector.

2.8 External Oscillator Pins

Many MCUs have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator. Refer to **Section 8.0 “Oscillator Configuration”** for details.

The oscillator circuit should be placed on the same side of the board as the device. Also, place the oscillator circuit close to the respective oscillator pins, not exceeding one-half inch (12 mm) distance between them. The load capacitors should be placed next to the oscillator itself, on the same side of the board. Use a grounded copper pour around the oscillator circuit to isolate them from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed. A suggested layout is illustrated in Figure 2-3.

FIGURE 2-3: SUGGESTED OSCILLATOR CIRCUIT PLACEMENT



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3.2 Architecture Overview

The MIPS32 M4K processor core contains several logic blocks working together in parallel, providing an efficient high-performance computing engine. The following blocks are included with the core:

- Execution Unit
- Multiply/Divide Unit (MDU)
- System Control Coprocessor (CP0)
- Fixed Mapping Translation (FMT)
- Dual Internal Bus interfaces
- Power Management
- MIPS16e® Support
- Enhanced JTAG (EJTAG) Controller

3.2.1 EXECUTION UNIT

The MIPS32 M4K processor core execution unit implements a load/store architecture with single-cycle ALU operations (logical, shift, add, subtract) and an autonomous multiply/divide unit. The core contains thirty-two 32-bit General Purpose Registers (GPRs) used for integer operations and address calculation. One additional register file shadow set (containing thirty-two registers) is added to minimize context switching overhead during interrupt/exception processing. The register file consists of two read ports and one write port and is fully bypassed to minimize operation latency in the pipeline.

The execution unit includes:

- 32-bit adder used for calculating the data address
- Address unit for calculating the next instruction address
- Logic for branch determination and branch target address calculation
- Load aligner
- Bypass multiplexers used to avoid stalls when executing instruction streams where data producing instructions are followed closely by consumers of their results
- Leading Zero/One detect unit for implementing the CLZ and CLO instructions
- Arithmetic Logic Unit (ALU) for performing bit-wise logical operations
- Shifter and store aligner

3.2.2 MULTIPLY/DIVIDE UNIT (MDU)

MIPS32 M4K processor core includes a Multiply/Divide Unit (MDU) that contains a separate pipeline for multiply and divide operations. This pipeline operates in parallel with the Integer Unit (IU) pipeline and does not stall when the IU pipeline stalls. This allows MDU operations to be partially masked by system stalls and/or other integer unit instructions.

The high-performance MDU consists of a 32x16 booth recoded multiplier, result/accumulation registers (HI and LO), a divide state machine, and the necessary multiplexers and control logic. The first number shown ('32' of 32x16) represents the *rs* operand. The second number ('16' of 32x16) represents the *rt* operand. The PIC32 core only checks the value of the latter (*rt*) operand to determine how many times the operation must pass through the multiplier. The 16x16 and 32x16 operations pass through the multiplier once. A 32x32 operation passes through the multiplier twice.

The MDU supports execution of one 16x16 or 32x16 multiply operation every clock cycle; 32x32 multiply operations can be issued every other clock cycle. Appropriate interlocks are implemented to stall the issuance of back-to-back 32x32 multiply operations. The multiply operand size is automatically determined by logic built into the MDU.

Divide operations are implemented with a simple 1 bit per clock iterative algorithm. An early-in detection checks the sign extension of the dividend (*rs*) operand. If *rs* is 8 bits wide, 23 iterations are skipped. For a 16 bit wide *rs*, 15 iterations are skipped and for a 24 bit wide *rs*, 7 iterations are skipped. Any attempt to issue a subsequent MDU instruction while a divide is still active causes an IU pipeline stall until the divide operation is completed.

Table 3-1 lists the repeat rate (peak issue rate of cycles until the operation can be reissued) and latency (number of cycles until a result is available) for the PIC32 core multiply and divide instructions. The approximate latency and repeat rates are listed in terms of pipeline clocks.

TABLE 3-1: MIPS32® M4K® CORE HIGH-PERFORMANCE INTEGER MULTIPLY/DIVIDE UNIT LATENCIES AND REPEAT RATES

Opcode	Operand Size (mul <i>rt</i>) (div <i>rs</i>)	Latency	Repeat Rate
MULT/MULTU, MADD/MADDU, MSUB/MSUBU	16 bits	1	1
	32 bits	2	2
MUL	16 bits	2	1
	32 bits	3	2
DIV/DIVU	8 bits	12	11
	16 bits	19	18
	24 bits	26	25
	32 bits	33	32

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REGISTER 4-3: BMXDUDBA: DATA RAM USER DATA BASE ADDRESS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0	R-0
	BMXDUDBA<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	BMXDUDBA<7:0>							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-10 **BMXDUDBA<15:10>:** DRM User Data Base Address bits

When non-zero, the value selects the relative base address for User mode data space in RAM, the value must be greater than BMXDKPBA.

bit 9-0 **BMXDUDBA<9:0>:** DRM User Data Base Address Read-Only bits

Value is always '0', which forces 1 KB increments

- Note 1:** At Reset, the value in this register is forced to zero, which causes all of the RAM to be allocated to Kernal mode data usage.
- 2:** The value in this register must be less than or equal to BMXDRMSZ.

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REGISTER 6-2: RSWRST: SOFTWARE RESET REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	W-0, HC
	—	—	—	—	—	—	—	SWRST ⁽¹⁾

Legend:	HC = Cleared by hardware		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-1 **Unimplemented:** Read as '0'

bit 0 **SWRST:** Software Reset Trigger bit⁽¹⁾

1 = Enable software Reset event

0 = No effect

Note 1: The system unlock sequence must be performed before the SWRST bit can be written. Refer to **Section 6. "Oscillator"** (DS60001112) in the *"PIC32 Family Reference Manual"* for details.

REGISTER 7-1: INTCON: INTERRUPT CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —
23:16	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	U-0 —	R/W-0 SS0
15:8	U-0 —	U-0 —	U-0 —	R/W-0 MVEC	U-0 —	R/W-0 TPC<2:0>	R/W-0 TPC<2:0>	R/W-0 TPC<2:0>
7:0	U-0 —	U-0 —	U-0 —	R/W-0 INT4EP	R/W-0 INT3EP	R/W-0 INT2EP	R/W-0 INT1EP	R/W-0 INT0EP

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-17 **Unimplemented:** Read as '0'

bit 16 **SS0:** Single Vector Shadow Register Set bit

1 = Single vector is presented with a shadow register set

0 = Single vector is not presented with a shadow register set

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **MVEC:** Multiple Vector Configuration bit

1 = Interrupt controller configured for Multi-vector mode

0 = Interrupt controller configured for Single-vector mode

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **TPC<2:0>:** Interrupt Proximity Timer Control bits

111 = Interrupts of group priority 7 or lower start the Interrupt Proximity timer

110 = Interrupts of group priority 6 or lower start the Interrupt Proximity timer

101 = Interrupts of group priority 5 or lower start the Interrupt Proximity timer

100 = Interrupts of group priority 4 or lower start the Interrupt Proximity timer

011 = Interrupts of group priority 3 or lower start the Interrupt Proximity timer

010 = Interrupts of group priority 2 or lower start the Interrupt Proximity timer

001 = Interrupts of group priority 1 start the Interrupt Proximity timer

000 = Disables Interrupt Proximity timer

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **INT4EP:** External Interrupt 4 Edge Polarity Control bit

1 = Rising edge

0 = Falling edge

bit 3 **INT3EP:** External Interrupt 3 Edge Polarity Control bit

1 = Rising edge

0 = Falling edge

bit 2 **INT2EP:** External Interrupt 2 Edge Polarity Control bit

1 = Rising edge

0 = Falling edge

bit 1 **INT1EP:** External Interrupt 1 Edge Polarity Control bit

1 = Rising edge

0 = Falling edge

bit 0 **INT0EP:** External Interrupt 0 Edge Polarity Control bit

1 = Rising edge

0 = Falling edge

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REGISTER 7-2: INTSTAT: INTERRUPT STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	—	RIPL<2:0> ⁽¹⁾		
7:0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	VEC<5:0> ⁽¹⁾					

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-11 **Unimplemented:** Read as '0'

bit 10-8 **RIPL<2:0>:** Requested Priority Level bits⁽¹⁾

111-000 = The priority level of the latest interrupt presented to the CPU

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **VEC<5:0>:** Interrupt Vector bits⁽¹⁾

11111-00000 = The interrupt vector that is presented to the CPU

Note 1: This value should only be used when the interrupt controller is configured for Single-vector mode.

REGISTER 7-3: TPTMR: TEMPORAL PROXIMITY TIMER REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TPTMR<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TPTMR<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TPTMR<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	TPTMR<7:0>							

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-0 **TPTMR<31:0>:** Temporal Proximity Timer Reload bits

Used by the Temporal Proximity Timer as a reload value when the Temporal Proximity timer is triggered by an interrupt event.

REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0 —	U-0 —	R/W-y	R/W-y	R/W-y	R/W-0	R/W-0	R/W-1
	PLLODIV<2:0>					FRCDIV<2:0>		
23:16	U-0 —	R-0 SOSCRDY	R-1 PBDIVRDY	R/W-y	R/W-y	R/W-y	R/W-y	R/W-y
	PBDIV<1:0>		PLLMULT<2:0>					
15:8	U-0 —	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
	COSC<2:0>				—	NOSC<2:0>		
7:0	R/W-0 CLKLOCK	R-0 ULOCK	R-0 SLOCK	R/W-0 SLPEN	R/W-0 CF	R/W-0 UFRCCEN	R/W-y SOSCEN	R/W-0 OSWEN

Legend:	y = Value set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-30 **Unimplemented:** Read as '0'

bit 29-27 **PLLODIV<2:0>:** Output Divider for PLL

- 111 = PLL output divided by 256
- 110 = PLL output divided by 64
- 101 = PLL output divided by 32
- 100 = PLL output divided by 16
- 011 = PLL output divided by 8
- 010 = PLL output divided by 4
- 001 = PLL output divided by 2
- 000 = PLL output divided by 1

bit 26-24 **FRCDIV<2:0>:** Internal Fast RC (FRC) Oscillator Clock Divider bits

- 111 = FRC divided by 256
- 110 = FRC divided by 64
- 101 = FRC divided by 32
- 100 = FRC divided by 16
- 011 = FRC divided by 8
- 010 = FRC divided by 4
- 001 = FRC divided by 2 (default setting)
- 000 = FRC divided by 1

bit 23 **Unimplemented:** Read as '0'

bit 22 **SOSCRDY:** Secondary Oscillator (Sosc) Ready Indicator bit

- 1 = Indicates that the Secondary Oscillator is running and is stable
- 0 = Secondary Oscillator is still warming up or is turned off

bit 21 **PBDIVRDY:** Peripheral Bus Clock (PBCLK) Divisor Ready bit

- 1 = PBDIV<1:0> bits can be written
- 0 = PBDIV<1:0> bits cannot be written

bit 20-19 **PBDIV<1:0>:** Peripheral Bus Clock (PBCLK) Divisor bits

- 11 = PBCLK is SYSCLK divided by 8 (default)
- 10 = PBCLK is SYSCLK divided by 4
- 01 = PBCLK is SYSCLK divided by 2
- 00 = PBCLK is SYSCLK divided by 1

Note: Writes to this register require an unlock sequence. Refer to **Section 6. "Oscillator"** (DS60001112) in the *"PIC32 Family Reference Manual"* for details.

10.1 Control Registers

TABLE 10-1: DMA GLOBAL REGISTER MAP

Virtual Address (BF88_#)	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	
3000	DMACON ⁽¹⁾	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	000
		15:0	ON	—	—	SUSPEND	DMABUSY	—	—	—	—	—	—	—	—	—	—	000
3010	DMASTAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	000
		15:0	—	—	—	—	—	—	—	—	—	—	—	RDWR	DMACH<2:0> ⁽²⁾			000
3020	DMAADDR	31:16	DMAADDR<31:0>															000
		15:0																000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: This register has corresponding CLR, SET and INV registers at its virtual address, plus an offset of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

2: DMACH<3> bit is not available on PIC32MX534/564/664/764 devices.

TABLE 10-2: DMA CRC REGISTER MAP⁽¹⁾

Virtual Address (BF88_#)	Register Name ⁽¹⁾	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	
3030	DCRCCON	31:16	—	—	BYTO<1:0>		WBO	—	—	BITO	—	—	—	—	—	—	—	000
		15:0	—	—	—	PLEN<4:0>					CRCEN	CRCAPP	CRCTYP	—	—	CRCCH<2:0>		000
3040	DCRCDATA	31:16	DCRCDATA<31:0>															000
		15:0																000
3050	DCRCXOR	31:16	DCRCXOR<31:0>															000
		15:0																000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.

REGISTER 10-1: DMACON: DMA CONTROLLER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	U-0	R/W-0	R/W-0	U-0	U-0	U-0
	ON ⁽¹⁾	—	—	SUSPEND	DMABUSY	—	—	—
7:0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** DMA On bit⁽¹⁾

1 = DMA module is enabled

0 = DMA module is disabled

bit 14-13 **Unimplemented:** Read as '0'

bit 12 **SUSPEND:** DMA Suspend bit

1 = DMA transfers are suspended to allow CPU uninterrupted access to data bus

0 = DMA operates normally

bit 11 **DMABUSY:** DMA Module Busy bit

1 = DMA module is active

0 = DMA module is disabled and not actively transferring data

bit 10-0 **Unimplemented:** Read as '0'

Note 1: When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral's SFRs in the SYSCLK cycle immediately following the instruction that clears the module's ON bit.

PIC32MX5XX/6XX/7XX

REGISTER 14-1: TXCON: TYPE B TIMER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
	ON ^(1,3)	—	SIDL ⁽⁴⁾	—	—	—	—	—
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
	TGATE ⁽³⁾	TCKPS<2:0> ⁽³⁾			T32 ⁽²⁾	—	TCS ⁽³⁾	—

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ON:** Timer On bit^(1,3)

1 = Module is enabled

0 = Module is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **SIDL:** Stop in Idle Mode bit⁽⁴⁾

1 = Discontinue operation when device enters Idle mode

0 = Continue operation when device is in Idle mode

bit 12-8 **Unimplemented:** Read as '0'

bit 7 **TGATE:** Timer Gated Time Accumulation Enable bit⁽³⁾

When TCS = 1:

This bit is ignored and is read as '0'.

When TCS = 0:

1 = Gated time accumulation is enabled

0 = Gated time accumulation is disabled

bit 6-4 **TCKPS<2:0>:** Timer Input Clock Prescale Select bits⁽³⁾

111 = 1:256 prescale value

110 = 1:64 prescale value

101 = 1:32 prescale value

100 = 1:16 prescale value

011 = 1:8 prescale value

010 = 1:4 prescale value

001 = 1:2 prescale value

000 = 1:1 prescale value

Note 1: When using the 1:1 PBCLK divisor, the user's software should not read/write the peripheral SFRs in the SYSClk cycle immediately following the instruction that clears the module's ON bit.

2: This bit is only available on even numbered timers (Timer2 and Timer4).

3: While operating in 32-bit mode, this bit has no effect for odd numbered timers (Timer1, Timer3, and Timer5). All timer functions are set through the even numbered timers.

4: While operating in 32-bit mode, this bit must be cleared on odd numbered timers to enable the 32-bit timer in Idle mode.

PIC32MX5XX/6XX/7XX

REGISTER 24-11: CiFLTCON1: CAN FILTER CONTROL REGISTER 1

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN7	MSEL7<1:0>		FSEL7<4:0>				
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN6	MSEL6<1:0>		FSEL6<4:0>				
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN5	MSEL5<1:0>		FSEL5<4:0>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN4	MSEL4<1:0>		FSEL4<4:0>				

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31 **FLTEN7**: Filter 7 Enable bit

- 1 = Filter is enabled
- 0 = Filter is disabled

bit 30-29 **MSEL7<1:0>**: Filter 7 Mask Select bits

- 11 = Acceptance Mask 3 selected
- 10 = Acceptance Mask 2 selected
- 01 = Acceptance Mask 1 selected
- 00 = Acceptance Mask 0 selected

bit 28-24 **FSEL7<4:0>**: FIFO Selection bits

- 11111 = Message matching filter is stored in FIFO buffer 31
- 11110 = Message matching filter is stored in FIFO buffer 30
- .
- .
- .
- 00001 = Message matching filter is stored in FIFO buffer 1
- 00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN6**: Filter 6 Enable bit

- 1 = Filter is enabled
- 0 = Filter is disabled

bit 22-21 **MSEL6<1:0>**: Filter 6 Mask Select bits

- 11 = Acceptance Mask 3 selected
- 10 = Acceptance Mask 2 selected
- 01 = Acceptance Mask 1 selected
- 00 = Acceptance Mask 0 selected

bit 20-16 **FSEL6<4:0>**: FIFO Selection bits

- 11111 = Message matching filter is stored in FIFO buffer 31
- 11110 = Message matching filter is stored in FIFO buffer 30
- .
- .
- .
- 00001 = Message matching filter is stored in FIFO buffer 1
- 00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 24-14: CifLTCON4: CAN FILTER CONTROL REGISTER 4 (CONTINUED)

- bit 15 **FLTEN17**: Filter 13 Enable bit
1 = Filter is enabled
0 = Filter is disabled
- bit 14-13 **MSEL17<1:0>**: Filter 17 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected
- bit 12-8 **FSEL17<4:0>**: FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0
- bit 7 **FLTEN16**: Filter 16 Enable bit
1 = Filter is enabled
0 = Filter is disabled
- bit 6-5 **MSEL16<1:0>**: Filter 16 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected
- bit 4-0 **FSEL16<4:0>**: FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

TABLE 25-5: ETHERNET CONTROLLER REGISTER SUMMARY FOR PIC32MX664F064H, PIC32MX664F128H, PIC32MX664F064L, PIC32MX664F128L, PIC32MX675F256H, PIC32MX675F512H, PIC32MX695F512H, PIC32MX775F256H, PIC32MX775F512H, PIC32MX795F512H, PIC32MX695F512L, PIC32MX675F256L, PIC32MX675F512L, PIC32MX764F128H, PIC32MX764F128L, PIC32MX775F256L, PIC32MX775F512L AND PIC32MX795F512L DEVICES (CONTINUED)

Virtual Address (BF88_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
90E0	ETHSTAT	31:16	—	—	—	—	—	—	—	—	BUFCNT<7:0>								0000
		15:0	—	—	—	—	—	—	—	—	BUSY	TXBUSY	RXBUSY	—	—	—	—	—	0000
9100	ETH RXOVFLOW	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RXOVFLWCNT<15:0>																0000
9110	ETH FRMTXOK	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	FRMTXOKCNT<15:0>																0000
9120	ETH SCOLFRM	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	SCOLFRMCNT<15:0>																0000
9130	ETH MCOLFRM	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	MCOLFRMCNT<15:0>																0000
9140	ETH FRMRXOK	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	FRMRXOKCNT<15:0>																0000
9150	ETH FCSERR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	FCSERRCNT<15:0>																0000
9160	ETH ALGNERR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ALGNERRCNT<15:0>																0000
9200	EMAC1 CFG1	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	SOFT RESET	SIM RESET	—	—	RESET RMCS	RESET RFUN	RESET TMCS	RESET TFUN	—	—	—	LOOPBACK	TXPAUSE	RXPAUSE	PASSALL	RXENABLE	800D
9210	EMAC1 CFG2	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	EXCESS DFR	BP NOBKOFF	NOBKOFF	—	—	LONGPRE	PUREPRE	AUTOPAD	VLANPAD	PAD ENABLE	CRC ENABLE	DELAYCRC	HUGEFRM	LENGTHCK	FULLDPLX	4082
9220	EMAC1 IPGT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0012
9230	EMAC1 IPGR	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	NB2BIPKTGP1<6:0>							—	NB2BIPKTGP2<6:0>							0C12
9240	EMAC1 CLRT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	CWINDOW<5:0>							—	—	—	RETX<3:0>				370F
9250	EMAC1 MAXF	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	MACMAXF<15:0>																05EE

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

- Note** 1: All registers in this table (with the exception of ETHSTAT) have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.1.1 “CLR, SET and INV Registers”** for more information.
- 2: Reset values default to the factory programmed value.

PIC32MX5XX/6XX/7XX

REGISTER 25-23: EMAC1CFG1: ETHERNET CONTROLLER MAC CONFIGURATION 1 REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-1	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	SOFT RESET	SIM RESET	—	—	RESET RMCS	RESET RFUN	RESET TMCS	RESET TFUN
7:0	U-0	U-0	U-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-1
	—	—	—	LOOPBACK	TX PAUSE	RX PAUSE	PASSALL	RX ENABLE

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **SOFTRESET:** Soft Reset bit

Setting this bit will put the MACMII in reset. Its default value is '1'.

bit 14 **SIMRESET:** Simulation Reset bit

Setting this bit will cause a reset to the random number generator within the Transmit Function.

bit 13-12 **Unimplemented:** Read as '0'

bit 11 **RESETRMCS:** Reset MCS/RX bit

Setting this bit will put the MAC Control Sub-layer/Receive domain logic in reset.

bit 10 **RESETRFUN:** Reset RX Function bit

Setting this bit will put the MAC Receive function logic in reset.

bit 9 **RESETTMCS:** Reset MCS/TX bit

Setting this bit will put the MAC Control Sub-layer/TX domain logic in reset.

bit 8 **RESETTFUN:** Reset TX Function bit

Setting this bit will put the MAC Transmit function logic in reset.

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **LOOPBACK:** MAC Loopback mode bit

1 = MAC Transmit interface is loop backed to the MAC Receive interface
0 = MAC normal operation

bit 3 **TXPAUSE:** MAC TX Flow Control bit

1 = PAUSE Flow Control frames are allowed to be transmitted
0 = PAUSE Flow Control frames are blocked

bit 2 **RXPAUSE:** MAC RX Flow Control bit

1 = The MAC acts upon received PAUSE Flow Control frames
0 = Received PAUSE Flow Control frames are ignored

bit 1 **PASSALL:** MAC Pass all Receive Frames bit

1 = The MAC will accept all frames regardless of type (Normal vs. Control)
0 = The received Control frames are ignored

bit 0 **RXENABLE:** MAC Receive Enable bit

1 = Enable the MAC receiving of frames
0 = Disable the MAC receiving of frames

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

PIC32MX5XX/6XX/7XX

REGISTER 25-28: EMAC1MAXF: ETHERNET CONTROLLER MAC MAXIMUM FRAME LENGTH REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-0	R/W-1
	MACMAXF<15:8> ⁽¹⁾							
7:0	R/W-1	R/W-1	R/W-1	R/W-0	R/W-1	R/W-1	R/W-1	R/W-0
	MACMAXF<7:0> ⁽¹⁾							

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **MACMAXF<15:0>:** Maximum Frame Length bits⁽¹⁾

These bits reset to 0x05EE, which represents a maximum receive frame of 1518 octets. An untagged maximum size Ethernet frame is 1518 octets. A tagged frame adds four octets for a total of 1522 octets. If a shorter/longer maximum length restriction is desired, program this 16-bit field.

Note 1: If a proprietary header is allowed, this bit should be adjusted accordingly. For example, if 4-byte headers are prepended to frames, MACMAXF could be set to 1527 octets. This would allow the maximum VLAN tagged frame plus the 4-byte header.

Note: Both 16-bit and 32-bit accesses are allowed to these registers (including the SET, CLR and INV registers). 8-bit accesses are not allowed and are ignored by the hardware.

PIC32MX5XX/6XX/7XX

NOTES:

PIC32MX5XX/6XX/7XX

REGISTER 29-2: DEVCFG1: DEVICE CONFIGURATION WORD 1

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	r-1 —	r-1 —	r-1 —	r-1 —	r-1 —	r-1 —	r-1 —	r-1 —
23:16	R/P FWDTEN	r-1 —	r-1 —	R/P	R/P	R/P	R/P	R/P
15:8	R/P FCKSM<1:0>	R/P	R/P	R/P	r-1 —	R/P	R/P	R/P
7:0	R/P IESO	r-1 —	R/P	r-1 —	r-1 —	R/P	R/P	R/P
			FSOSCEN				WDTPS<4:0>	FNOSC<2:0>

Legend:	r = Reserved bit	P = Programmable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

bit 31-24 **Reserved:** Write '1'

bit 23 **FWDTEN:** Watchdog Timer Enable bit

1 = The WDT is enabled and cannot be disabled by software
0 = The WDT is not enabled; it can be enabled in software

bit 22-21 **Reserved:** Write '1'

bit 20-16 **WDTPS<4:0>:** Watchdog Timer Postscale Select bits

10100 = 1:1048576
10011 = 1:524288
10010 = 1:262144
10001 = 1:131072
10000 = 1:65536
01111 = 1:32768
01110 = 1:16384
01101 = 1:8192
01100 = 1:4096
01011 = 1:2048
01010 = 1:1024
01001 = 1:512
01000 = 1:256
00111 = 1:128
00110 = 1:64
00101 = 1:32
00100 = 1:16
00011 = 1:8
00010 = 1:4
00001 = 1:2
00000 = 1:1

All other combinations not shown result in operation = 10100

bit 15-14 **FCKSM<1:0>:** Clock Switching and Monitor Selection Configuration bits

1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled
01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled

Note 1: Do not disable the Posc (POSCMOD = 11) when using this oscillator source.

APPENDIX A: MIGRATING FROM PIC32MX3XX/4XX TO PIC32MX5XX/6XX/7XX DEVICES

This appendix provides an overview of considerations for migrating from PIC32MX3XX/4XX devices to the PIC32MX5XX/6XX/7XX family of devices. The code developed for the PIC32MX3XX/4XX devices can be ported to the PIC32MX5XX/6XX/7XX devices after making the appropriate changes outlined below.

A.1 DMA

PIC32MX5XX/6XX/7XX devices do not support stopping DMA transfers in Idle mode.

A.2 Interrupts

PIC32MX5XX/6XX/7XX devices have persistent interrupts for some of the peripheral modules. This means that the interrupt condition for these peripherals must be cleared before the interrupt flag can be cleared.

For example, to clear a UART receive interrupt, the user application must first read the UART Receive register to clear the interrupt condition and then clear the associated UxIF flag to clear the pending UART interrupt. In other words, the UxIF flag cannot be cleared by software until the UART Receive register is read.

Table A-1 outlines the peripherals and associated interrupts that are implemented differently on PIC32MX5XX/6XX/7XX versus PIC32MX3XX/4XX devices.

In addition, on the SPI module, the IRQ numbers for the receive done interrupts were changed from 25 to 24 and the transfer done interrupts were changed from 24 to 25.

TABLE A-1: PIC32MX3XX/4XX VERSUS PIC32MX5XX/6XX/7XX INTERRUPT IMPLEMENTATION DIFFERENCES

Module	Interrupt Implementation
Input Capture	To clear an interrupt source, read the Buffer Result (ICxBUF) register to obtain the number of capture results in the buffer that are below the interrupt threshold (specified by ICI<1:0> bits).
SPI	Receive and transmit interrupts are controlled by the SRXISEL<1:0> and STXISEL<1:0> bits, respectively. To clear an interrupt source, data must be written to, or read from, the SPIxBUF register to obtain the number of data to receive/transmit below the level specified by the SRXISEL<1:0> and STXISEL<1:0> bits.
UART	TX interrupt will be generated as soon as the UART module is enabled. Receive and transmit interrupts are controlled by the URXISEL<1:0> and UTXISEL<1:0> bits, respectively. To clear an interrupt source, data must be read from, or written to, the UxRXREG or UxTXREG registers to obtain the number of data to receive/transmit below the level specified by the URXISEL<1:0> and UTXISEL<1:0> bits.
ADC	All samples must be read from the result registers (ADC1BUFx) to clear the interrupt source.
PMP	To clear an interrupt source, read the Parallel Master Port Data Input/Output (PMDIN/PMDOUT) register.